

# Mathematical Finance

## Probability Review

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# Outline

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# Sample Space

- We collect the possible states of the world and denote the set by  $\Omega$ . The states are called **samples** or **elementary events**.
- The sample space  $\Omega$  is either **countable** or **uncountable**.
  - ▶ A toss of a coin:  $\Omega = \{Head, Tail\} = \{H, T\}$ .
  - ▶ The number of successes in a sequence of  $n$  identical and independent trials:  $\Omega = \{0, 1, \dots, n\}$ .
  - ▶ The moment of occurrence of the first success in an infinite sequence of identical and independent trials:  $\Omega = \{1, 2, \dots\}$ .
  - ▶ The lifetime of a light bulb:  $\Omega = \{x \in \mathbb{R} \mid x \geq 0\}$ .
- The choice of a sample space is arbitrary and thus any set can be taken as a sample space. However, practical considerations justify the choice of the most convenient sample space for the problem at hand. **Discrete** (finite or infinite, but countable) sample spaces are easier to handle than general sample spaces.



# Discrete Random Variables

- Examples of random variables:
  - ▶ Prices of stocks.
  - ▶ Exchange rates.
  - ▶ Payoffs corresponding to portfolios.

## Definition (Discrete Random Variable)

A real-valued function  $X : \Omega \rightarrow \mathbb{R}$  on a discrete sample space  $\Omega = (\omega_k)_{k \in I}$ , where the set  $I$  is countable, is called a **discrete random variable**.

## Definition (Probability)

A map  $\mathbb{P} : \Omega \mapsto [0, 1]$  is called a **probability** on a discrete sample space  $\Omega$  if

- P.1.  $\mathbb{P}(\omega_k) \geq 0$  for all  $k \in I$ ,
- P.2.  $\sum_{k \in I} \mathbb{P}(\omega_k) = 1$ .



# Probability Measure

- Let  $\mathcal{F} = 2^\Omega$  stand for the class of all subsets of the sample space  $\Omega$ . The set  $2^\Omega$  is called the **power set** of  $\Omega$ .
- Note that the **empty set**  $\emptyset$  also belongs to any power set.

## Definition (Probability Measure)

A map  $\mathbb{P} : \mathcal{F} \mapsto [0, 1]$  is called a **probability measure** on  $(\Omega, \mathcal{F})$  if

- M.1. For any sequence  $A_i \subset \mathcal{F}$ ,  $i = 1, 2, \dots$  of events such that  $A_i \cap A_j = \emptyset$  for all  $i \neq j$  we have

$$\mathbb{P}(\cup_{i=1}^{\infty} A_i) = \sum_{i=1}^{\infty} \mathbb{P}(A_i).$$

- M.2.  $\mathbb{P}(\Omega) = 1$ .

- Any set  $A \in \mathcal{F}$  is called an **event**.
- For any  $A \in \mathcal{F}$  the equality  $\mathbb{P}(\Omega \setminus A) = 1 - \mathbb{P}(A)$  holds.



# Probability Measure on a Discrete Sample Space

- Note a probability  $\mathbb{P} : \Omega \mapsto [0, 1]$  on a discrete sample space  $\Omega$  uniquely specifies probabilities of all events  $A_k = \{\omega_k\}$ .
- It is common to write  $\mathbb{P}(\{\omega_k\}) = \mathbb{P}(\omega_k) = p_k$ .
- The theorem shows that any probability on a discrete sample space  $\Omega$  generates a unique probability measure on  $(\Omega, \mathcal{F})$ .

## Theorem

*Let  $\mathbb{P} : \Omega \mapsto [0, 1]$  be a probability on a discrete sample space  $\Omega$ . Then the unique probability measure on  $(\Omega, \mathcal{F})$  generated by  $\mathbb{P}$  satisfies, for all  $A \in \mathcal{F}$ ,*

$$\mathbb{P}(A) = \sum_{\omega_k \in A} \mathbb{P}(\omega_k).$$

- The proof of the theorem presents no difficulties, since  $\Omega$  is assumed to be discrete.



## Example: Coin Flipping

- Let  $X$  be the number of “heads” appearing when a **fair** coin is tossed twice. We choose the sample space  $\Omega$  to be

$$\Omega = \{0, 1, 2\}$$

where a number  $k \in \Omega$  represents the number of times “head” has occurred.

- The probability measure  $\mathbb{P}$  on  $\Omega$  is defined as

$$\mathbb{P}(k) = \begin{cases} \frac{1}{4}, & \text{if } k = 0, 2, \\ \frac{1}{2}, & \text{otherwise.} \end{cases}$$

- We recognise here the binomial distribution with  $n = 2$  and  $p = \frac{1}{2}$ . A single flip of a coin is a **Bernoulli trial**.



## Example: Coin Flipping

- We now suppose that the coin is not a fair one.
- Let the probability of “head” be  $p$  for some  $p \neq \frac{1}{2}$ .
- Then the probability measure  $\mathbb{P}$  is given by

$$\mathbb{P}(k) = \begin{cases} q^2, & \text{if } k = 0, \\ 2pq, & \text{if } k = 1, \\ p^2, & \text{if } k = 2, \end{cases}$$

where  $q := 1 - p$  is the probability of “tail” appearing.

- We deal here with the binomial distribution with  $n = 2$  and  $0 < p < 1$ .



# Expectation of a Random Variable

## Definition (Expectation)

Let  $X$  be a random variable on a discrete sample space  $\Omega$  endowed with a probability measure  $\mathbb{P}$ . The **expectation (expected value or mean value)** of  $X$  is defined to be

$$\mathbb{E}_{\mathbb{P}}(X) = \mu := \sum_{k \in I} X(\omega_k) \mathbb{P}(\omega_k) = \sum_{k \in I} x_k p_k.$$

$\mathbb{E}_{\mathbb{P}}(\cdot)$  is called the **expectation operator** over the probability  $\mathbb{P}$ .

- Note that the expectation of a random variable can be seen as the weighted average.
- Since it is impossible to know the exact event in the future, expectation could help one to make decisions.



# Expectation Operator

- Any random variable defined on a finite set  $\Omega$  admits the expectation.
- When the set  $\Omega$  is countable (but infinite), we say that  $X$  is  **$\mathbb{P}$ -integrable** whenever  $\mathbb{E}_{\mathbb{P}}(|X|) = \sum_{\omega \in \Omega} |X(\omega)| \mathbb{P}(\omega) < \infty$ . Then the expectation  $\mathbb{E}_{\mathbb{P}}(X)$  is well defined (and finite).

## Theorem (1.1)

*Let  $X$  and  $Y$  be two  $\mathbb{P}$ -integrable random variables and  $\mathbb{P}$  be a probability measure on a discrete sample space  $\Omega$ . Then for all  $\alpha, \beta \in \mathbb{R}$*

$$\mathbb{E}_{\mathbb{P}}(\alpha X + \beta Y) = \alpha \mathbb{E}_{\mathbb{P}}(X) + \beta \mathbb{E}_{\mathbb{P}}(Y).$$

*Hence  $\mathbb{E}_{\mathbb{P}}(\cdot) : \mathcal{X} \rightarrow \mathbb{R}$  is a linear operator on the space  $\mathcal{X}$  of  $\mathbb{P}$ -integrable random variables.*



# Expectation Operator

## Proof.

[Proof of Theorem 1.1] We note that

$$\mathbb{E}_{\mathbb{P}} (|\alpha X + \beta Y|) \leq |\alpha| \mathbb{E}_{\mathbb{P}} (|X|) + |\beta| \mathbb{E}_{\mathbb{P}} (|Y|) < \infty$$

so that the random variable  $\alpha X + \beta Y$  belongs to  $\mathcal{X}$ . The linearity of expectation can be easily deduced from the definition:

$$\begin{aligned} \mathbb{E}_{\mathbb{P}} (\alpha X + \beta Y) &= \sum_{\omega \in \Omega} (\alpha X(\omega) + \beta Y(\omega)) \mathbb{P}(\omega) \\ &= \sum_{\omega \in \Omega} \alpha X(\omega) \mathbb{P}(\omega) + \sum_{\omega \in \Omega} \beta Y(\omega) \mathbb{P}(\omega) \\ &= \alpha \sum_{\omega \in \Omega} X(\omega) \mathbb{P}(\omega) + \beta \sum_{\omega \in \Omega} Y(\omega) \mathbb{P}(\omega) \\ &= \alpha \mathbb{E}_{\mathbb{P}} (X) + \beta \mathbb{E}_{\mathbb{P}} (Y) \end{aligned}$$

where  $\alpha$  and  $\beta$  are arbitrary real numbers. □



## Expectation: Coin Flipping

- A fair coin is tossed three times. The player receives one dollar each time “head” appears and loses one dollar when “tail” occurs.
- Let the random variable  $X$  represent the player's payoff.
- The sample space  $\Omega$  is defined as  $\Omega = \{0, 1, 2, 3\}$  where  $k \in \Omega$  represents the number of times “head” occurs.
- The probability measure is given by

$$\mathbb{P}(k) = \begin{cases} \frac{1}{8}, & \text{if } k = 0, 3, \\ \frac{3}{8}, & \text{if } k = 1, 2. \end{cases}$$

- This is the binomial distribution with  $n = 3$  and  $p = \frac{1}{2}$ .



# Expectation: Coin Flipping

- The random variable  $X$  is defined as

$$X(k) = \begin{cases} -3, & \text{if } k = 0, \\ -1, & \text{if } k = 1, \\ 1, & \text{if } k = 2, \\ 3, & \text{if } k = 3. \end{cases}$$

- Hence the player's expected payoff equals

$$\begin{aligned} \mathbb{E}_{\mathbb{P}}(X) &= \sum_{k=0}^3 X(k)\mathbb{P}(k) \\ &= \frac{-3}{8} + \left(\frac{-3}{8}\right) + \frac{3}{8} + \frac{3}{8} \\ &= 0. \end{aligned}$$



# Expectation of a Function of a Random Variable

- Let  $X$  be a random variable and  $\mathbb{P}$  be a probability measure on a discrete sample space  $\Omega$ . We define  $Y = f(X)$  where  $f : \mathbb{R} \rightarrow \mathbb{R}$  is an arbitrary function.
- Then  $Y$  is also a random variable on the sample space  $\Omega$  endowed with the same probability measure  $\mathbb{P}$ . Moreover,

$$\mathbb{E}_{\mathbb{P}}(Y) = \mathbb{E}_{\mathbb{P}}(f(X)) = \sum_{\omega \in \Omega} f(X(\omega))\mathbb{P}(\omega).$$

- If a random variable  $X$  is deterministic then  $\mathbb{E}_{\mathbb{P}}(X) = X$  and  $\mathbb{E}_{\mathbb{P}}(f(X)) = f(X)$ .



# Equivalence of Probability Measures

Let  $\mathbb{P}$  and  $\mathbb{Q}$  be two probability measures on a discrete sample space  $\Omega$ .

## Definition (Equivalence of Probability Measures)

We say that the probability measures  $\mathbb{P}$  and  $\mathbb{Q}$  are **equivalent** and we denote  $\mathbb{P} \sim \mathbb{Q}$  whenever for all  $\omega \in \Omega$

$$\mathbb{P}(\omega) > 0 \quad \Leftrightarrow \quad \mathbb{Q}(\omega) > 0.$$

The random variable  $L : \Omega \rightarrow \mathbb{R}_+$  given as

$$L(\omega) = \frac{\mathbb{Q}(\omega)}{\mathbb{P}(\omega)}$$

is called the **Radon-Nikodym** density of  $\mathbb{Q}$  with respect to  $\mathbb{P}$ . Note that

$$\mathbb{E}_{\mathbb{Q}}(X) = \sum_{\omega \in \Omega} X(\omega) \mathbb{Q}(\omega) = \sum_{\omega \in \Omega} X(\omega) L(\omega) \mathbb{P}(\omega) = \mathbb{E}_{\mathbb{P}}(LX).$$



## Example: Equivalent Probability Measures

- The sample space  $\Omega$  is defined as  $\Omega = \{1, 2, 3, 4\}$ .
- Let the two probability measures  $\mathbb{P}$  and  $\mathbb{Q}$  be given by

$$\left(\frac{1}{8}, \frac{3}{8}, \frac{2}{8}, \frac{2}{8}\right) \quad \text{and} \quad \left(\frac{4}{8}, \frac{1}{8}, \frac{2}{8}, \frac{1}{8}\right).$$

- It is clear that  $\mathbb{P}$  and  $\mathbb{Q}$  are equivalent, that is,  $\mathbb{P} \sim \mathbb{Q}$ .
- Moreover, the Radon-Nikodym density  $L$  of  $\mathbb{Q}$  with respect to  $\mathbb{P}$  can be represented as follows

$$\left(4, \frac{1}{3}, 1, \frac{1}{2}\right).$$

- Check that for any random variable  $X$ :  $\mathbb{E}_{\mathbb{Q}}(X) = \mathbb{E}_{\mathbb{P}}(LX)$ .



# Risky Investments

When deciding whether to invest in a given portfolio, an agent may be concerned with the “risk” of his investment.

## Example

Consider an investor who is given an opportunity to choose between the following two options:

The investor either receives or loses 1,000 dollars with equal probabilities. This random payoff is denoted by  $X_1$ .

The investor either receives or loses 1,000,000 dollars with equal probabilities. We denote this random payoff as  $X_2$ .

Hence in both scenarios the expected value of the payoff equals 0

$$\mathbb{E}_{\mathbb{P}}(X_1) = \mathbb{E}_{\mathbb{P}}(X_2) = 0.$$

The following question arises: which option is preferred?



# Variance of a Random Variable

## Definition (Variance)

The **variance** of a random variable  $X$  on a discrete sample set  $\Omega$  is defined as

$$\text{Var}(X) = \sigma^2 := \mathbb{E}_{\mathbb{P}} \left\{ (X - \mu)^2 \right\},$$

where  $\mathbb{P}$  is a probability measure on  $\Omega$ .

- Variance is a measure of the spread of a random variable about its mean and also a measure of uncertainty.
- In financial applications, it is common to identify variance of the price of a security with its degree of “risk”.
- Note that  $\text{Var}(X) = \sigma^2 \geq 0$ . It equals 0 if and only if  $X$  is deterministic.



# Variance of a Random Variable

## Example

- The variance of option 1 equals

$$\text{Var}(X_1) = \frac{(1000 - 0)^2}{2} + \frac{(-1000 - 0)^2}{2} = 10^6.$$

- The variance of option 2 equals

$$\text{Var}(X_2) = \frac{(10^6 - 0)^2}{2} + \frac{(-10^6 - 0)^2}{2} = 10^{12}.$$

- Therefore, the option represented by  $X_2$  is more risky than the option represented by  $X_1$ .
- A **risk-averse agent** would prefer the first option over the second. However, a **risk-loving agent** would prefer the second option over the first.



# Variance of a Random Variable

## Theorem (1.2)

*Let  $X$  be a random variable and  $\mathbb{P}$  be a probability measure on a discrete sample space  $\Omega$ . Then the following equality holds*

$$\text{Var}(X) = \mathbb{E}_{\mathbb{P}}(X^2) - \mu^2.$$

## Proof.

[Proof of Theorem 1.2]

$$\begin{aligned}\text{Var}(X) &= \mathbb{E}_{\mathbb{P}}\{(X - \mu)^2\} = \mathbb{E}_{\mathbb{P}}(X^2 - 2\mu X + \mu^2) \quad (\text{linearity}) \\ &= \mathbb{E}_{\mathbb{P}}(X^2) - 2\mu \mathbb{E}_{\mathbb{P}}(X) + \mu^2 = \mathbb{E}_{\mathbb{P}}(X^2) - \mu^2.\end{aligned}$$





# Independence of a Random Variable

## Definition (Independence)

Two discrete random variables  $X$  and  $Y$  are called **independent** if and only if for all  $x, y \in \mathbb{R}$

$$\mathbb{P}(X = x, Y = y) = \mathbb{P}(X = x) \mathbb{P}(Y = y)$$

where  $\mathbb{P}(X = x)$  is the probability of the event  $\{X = x\}$ .

A useful property of independent random variables  $X$  and  $Y$  is

$$\mathbb{E}_{\mathbb{P}}(XY) = \mathbb{E}_{\mathbb{P}}(X) \mathbb{E}_{\mathbb{P}}(Y).$$

## Theorem (1.3)

*Let  $X$  and  $Y$  be two independent discrete random variables. Then we have, for arbitrary  $\alpha, \beta \in \mathbb{R}$ ,*

$$\text{Var}(\alpha X + \beta Y) = \alpha^2 \text{Var}(X) + \beta^2 \text{Var}(Y).$$



# Independence of a Random Variable

## Proof.

[Proof of Theorem 1.3] Let  $\mathbb{E}_{\mathbb{P}}(X) = \mu_X$  and  $\mathbb{E}_{\mathbb{P}}(Y) = \mu_Y$ . Theorem 1.1 yields

$$\mathbb{E}_{\mathbb{P}}(\alpha X + \beta Y) = \alpha \mu_X + \beta \mu_Y.$$

Using Theorem 1.2, we obtain

$$\begin{aligned} \text{Var}(\alpha X + \beta Y) &= \mathbb{E}_{\mathbb{P}}\{(\alpha X + \beta Y)^2\} - (\alpha \mu_X + \beta \mu_Y)^2 \\ &= \alpha^2 \mathbb{E}_{\mathbb{P}}(X^2) + 2\alpha\beta \mathbb{E}_{\mathbb{P}}(XY) + \beta^2 \mathbb{E}_{\mathbb{P}}(Y^2) \\ &\quad - (\alpha \mu_X + \beta \mu_Y)^2 \\ &= \alpha^2 (\mathbb{E}_{\mathbb{P}}(X^2) - \mu_X^2) + \beta^2 (\mathbb{E}_{\mathbb{P}}(Y^2) - \mu_Y^2) \\ &\quad + 2\alpha\beta (\mathbb{E}_{\mathbb{P}}(X) \mathbb{E}_{\mathbb{P}}(Y) - \mu_X \mu_Y) \\ &= \alpha^2 \text{Var}(X) + \beta^2 \text{Var}(Y). \end{aligned}$$





# Continuous Random Variables

## Definitions (Continuous Random Variable)

A random variable  $X$  on the sample space  $\Omega$  is said to have a **continuous distribution** if there exists a real-valued function  $f$  such that

$$\begin{aligned} f(x) &\geq 0, \\ \int_{-\infty}^{\infty} f(x) dx &= 1, \end{aligned}$$

and for all real numbers  $a < b$

$$\mathbb{P}(a \leq X \leq b) = \int_a^b f(x) dx.$$

Then  $f : \mathbb{R} \rightarrow \mathbb{R}_+$  is called the **probability density function (pdf)** of a continuous random variable  $X$ .



# Continuous Random Variables

Assume that  $X$  is a continuous random variable.

- Note that a probability density function need not satisfy the constraint  $f(x) \leq 1$ .
- A function  $F(x)$  is called a **cumulative distribution function (cdf)** of a continuous random variable  $X$  if for all  $x \in \mathbb{R}$

$$F(x) = \mathbb{P}(X \leq x) = \int_{-\infty}^x f(y) dy.$$

- The relationship between the pdf  $f$  and cdf  $F$

$$F(x) = \int_{-\infty}^x f(y) dy \quad \Leftrightarrow \quad f(x) = \frac{d}{dx} F(x).$$



# Continuous Random Variables

- The expectation and variance of a continuous random variable  $X$  are defined as follows:

$$\mathbb{E}_{\mathbb{P}}(X) = \mu := \int_{-\infty}^{\infty} x f(x) dx,$$

$$\text{Var}(X) = \sigma^2 := \int_{-\infty}^{\infty} (x - \mu)^2 f(x) dx,$$

or, equivalently,

$$\text{Var}(X) = \int_{-\infty}^{\infty} x^2 f(x) dx - \mu^2 = \mathbb{E}_{\mathbb{P}}(X^2) - (\mathbb{E}_{\mathbb{P}}(X))^2$$

- The properties of expectations of discrete random variables carry over to continuous random variables, with probability measures being replaced by pdfs and sums by integrals.



# Discrete Probability Distributions

## Example

- Let  $\Omega = \{0, 1, 2, \dots, n\}$  be the sample space and let  $X$  be the number of successes in  $n$  independent trials where  $p$  is the probability of success in a single Bernoulli trial.
- The probability measure  $\mathbb{P}$  is called the **binomial distribution** if

$$\mathbb{P}(k) = \binom{n}{k} p^k (1-p)^{n-k} \quad \text{for } k = 0, \dots, n$$

where

$$\binom{n}{k} = \frac{n!}{k!(n-k)!}.$$

- Then

$$\mathbb{E}_{\mathbb{P}}(X) = np \quad \text{and} \quad \text{Var}(X) = np(1-p).$$



# Discrete Probability Distributions

## Example

- Let the sample space be  $\Omega = \{0, 1, 2, \dots\}$ .
- We take an arbitrary number  $\lambda > 0$ .
- The probability measure  $\mathbb{P}$  is called the **Poisson distribution** if

$$\mathbb{P}(k) = \frac{\lambda^k e^{-\lambda}}{k!} \quad \text{for } k = 0, 1, 2, \dots$$

- Then

$$\mathbb{E}_{\mathbb{P}}(X) = \lambda = \text{Var}(X).$$

- It is known that the Poisson distribution can be obtained as the limit of the binomial distribution when  $n$  tends to infinity and the sequence  $np_n$  tends to  $\lambda > 0$ .



# Discrete Probability Distributions

## Example

- Let  $\Omega = \{1, 2, 3, \dots\}$  be the sample space and  $X$  be the number of independent trials to achieve the first success.
- Let  $p$  stand for the probability of a success in a single trial.
- The probability measure  $\mathbb{P}$  is called the **geometric distribution** if

$$\mathbb{P}(k) = (1 - p)^{k-1}p \quad \text{for } k = 1, 2, 3, \dots$$

- Then

$$\mathbb{E}_{\mathbb{P}}(X) = \frac{1}{p} \quad \text{and} \quad \text{Var}(X) = \frac{1 - p}{p^2}.$$



# Continuous Probability Distributions

## Example

- We say that  $X$  has the **uniform distribution** on an interval  $(a, b)$  if its pdf equals

$$f(x) = \begin{cases} \frac{1}{b-a}, & \text{if } x \in (a, b), \\ 0, & \text{otherwise.} \end{cases}$$

- It is clear that

$$\int_{-\infty}^{\infty} f(x) dx = \int_a^b \frac{1}{b-a} dx = 1.$$

- We have

$$\mathbb{E}_{\mathbb{P}}(X) = \frac{a+b}{2} \quad \text{and} \quad \text{Var}(X) = \frac{(b-a)^2}{12}.$$



# Continuous Probability Distributions

## Example

- We say that  $X$  has the **exponential distribution** on  $(0, \infty)$  with the parameter  $\lambda > 0$  if its pdf equals

$$f(x) = \begin{cases} \lambda e^{-\lambda x}, & \text{if } x > 0, \\ 0, & \text{otherwise.} \end{cases}$$

- It is easy to check that

$$\int_{-\infty}^{\infty} f(x) dx = \int_0^{\infty} \lambda e^{-\lambda x} dx = 1.$$

- We have

$$\mathbb{E}_{\mathbb{P}}(X) = \frac{1}{\lambda} \quad \text{and} \quad \text{Var}(X) = \frac{1}{\lambda^2}.$$



# Continuous Probability Distributions

## Example

- We say that  $X$  has the **Gaussian (normal) distribution** with mean  $\mu \in \mathbb{R}$  and variance  $\sigma^2 > 0$  if its pdf equals

$$f(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}} \quad \text{for } x \in \mathbb{R}.$$

We write  $X \sim N(\mu, \sigma^2)$ .

- One can show that

$$\int_{-\infty}^{\infty} f(x) dx = \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}} dx = 1.$$

- We have

$$\mathbb{E}_{\mathbb{P}}(X) = \mu \quad \text{and} \quad \text{Var}(X) = \sigma^2.$$



# Continuous Probability Distributions

## Example

- If we set  $\mu = 0$  and  $\sigma^2 = 1$  then we obtain the **standard normal distribution**  $N(0, 1)$  with the following pdf

$$n(x) = \frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} \quad \text{for } x \in \mathbb{R}.$$

- The cdf of the probability distribution  $N(0, 1)$  equals

$$N(x) = \int_{-\infty}^x n(u) du = \int_{-\infty}^x \frac{1}{\sqrt{2\pi}} e^{-\frac{u^2}{2}} du \quad \text{for } x \in \mathbb{R}.$$

- The values of  $N(x)$  can be found in the **cumulative standard normal table** (also known as the **Z table**).
- If  $X \sim N(\mu, \sigma^2)$  then  $Z := \frac{X - \mu}{\sigma} \sim N(0, 1)$ .



# LLN and CLT

## Theorem (Law of Large Numbers)

*Assume that  $X_1, X_2, \dots$  are independent and identically distributed random variables with mean  $\mu$ . Then with probability one,*

$$\frac{X_1 + \dots + X_n}{n} \rightarrow \mu \quad \text{as } n \rightarrow \infty$$

## Theorem (Central Limit Theorem)

*Assume that  $X_1, X_2, \dots$  are independent and identically distributed random variables with mean  $\mu$  and variance  $\sigma^2 > 0$ . Then for all real  $x$*

$$\lim_{n \rightarrow \infty} \mathbb{P} \left\{ \frac{X_1 + \dots + X_n - n\mu}{\sigma\sqrt{n}} \leq x \right\} = \int_{-\infty}^x \frac{1}{\sqrt{2\pi}} e^{-u^2/2} du = N(x).$$



# Covariance of Random Variables

- In the real world, agents can invest in several securities and typically would like to benefit from diversification.
- The price of one security may affect the prices of other assets. For example, the stock index falling may lead the price of gold to rise.
- To quantify this effect, it is convenient to introduce the notion of **covariance**.

## Definition (Covariance)

The **covariance** of two random variables  $X_1$  and  $X_2$  is defined as

$$\text{Cov}(X_1, X_2) = \sigma_{12} := \mathbb{E}_{\mathbb{P}} \{(X_1 - \mu_1)(X_2 - \mu_2)\}$$

where  $\mu_i = \mathbb{E}_{\mathbb{P}}(X_i)$  for  $i = 1, 2$ .



# Correlated and Uncorrelated Random Variables

- The covariance of two random variables is a measure of the degree of variation of one variable with respect to the other.
- Unlike the variance of a random variable, covariance of two random variables may take negative values.
  - ▶  $\sigma_{12} > 0$ : An increase in one variable tends to coincide with an increase in the other.
  - ▶  $\sigma_{12} < 0$ : An increase in one variable tends to coincide with a decrease in the other.
  - ▶  $\sigma_{12} = 0$ : Then the random variables  $X_1$  and  $X_2$  are said to be **uncorrelated**. If  $\sigma_{12} \neq 0$  then  $X_1$  and  $X_2$  are **correlated**.

## Definition (Uncorrelated Random Variables)

We say that the random variables  $X_1$  and  $X_2$  are **uncorrelated** whenever

$$\text{Cov}(X_1, X_2) = \sigma_{12} = 0.$$



# Properties of the Covariance

## Theorem (1.4)

*The following properties are valid:*

- $\text{Cov}(X, X) = \text{Var}(X) = \sigma^2$ .
- $\text{Cov}(X_1, X_2) = \mathbb{E}_{\mathbb{P}}(X_1 X_2) - \mu_1 \mu_2$ .
- $\mathbb{E}_{\mathbb{P}}(X_1 X_2) = \mathbb{E}_{\mathbb{P}}(X_1) \mathbb{E}_{\mathbb{P}}(X_2)$  if and only if  $X_1$  and  $X_2$  are uncorrelated, that is,  $\text{Cov}(X_1, X_2) = 0$ .
- $\text{Var}(a_1 X_1 + a_2 X_2) = a_1^2 \sigma_1^2 + a_2^2 \sigma_2^2 + 2a_1 a_2 \sigma_{12}$ .
- $\text{Var}(X_1 + X_2) = \text{Var}(X_1) + \text{Var}(X_2)$  if and only if  $X_1$  and  $X_2$  are uncorrelated.
- If  $X_1$  and  $X_2$  are independent then they are uncorrelated.
- The converse is not true: it may happen that  $X_1$  and  $X_2$  are uncorrelated, but they are not independent.



# Correlation Coefficient

- We can normalise the covariance measure. We obtain in this way the so-called **correlation coefficient**.
- Note that the correlation coefficient is only defined when  $\sigma_1 > 0$  and  $\sigma_2 > 0$ , that is, none of the two random variables is deterministic.

## Definition (Correlation Coefficient)

Let  $X_1$  and  $X_2$  be two random variables with variances  $\sigma_1^2$  and  $\sigma_2^2$  and covariance  $\sigma_{12}$ . Then the **correlation coefficient**

$$\rho = \rho(X_1, X_2) = \text{corr}(X_1, X_2)$$

is defined by

$$\rho := \frac{\sigma_{12}}{\sigma_1 \sigma_2} = \frac{\text{Cov}(X_1, X_2)}{\sqrt{\text{Var}(X_1) \text{Var}(X_2)}}.$$



# Properties of Correlation Coefficient

## Theorem

*The correlation coefficient satisfies  $-1 \leq \rho \leq 1$ . The random variables  $X_1$  and  $X_2$  are uncorrelated whenever  $\rho = 0$ .*

## Proof.

The result follows from an application of the Cauchy-Schwarz inequality:

$$(\sum_{k=1}^n a_k b_k)^2 \leq (\sum_{k=1}^n a_k^2)(\sum_{k=1}^n b_k^2).$$



- $\rho = 1$ : If one variable increases, the other will also increase.
- $0 < \rho < 1$ : If one increases, the other will tend to increase.
- $\rho = 0$ : The two random variables are uncorrelated.
- $-1 < \rho < 0$ : If one increases, the other will tend to decrease.
- $\rho = -1$ : If one increases, the other will decrease.



# Linear Regression in Basic Statistics

- If we observe the time series of prices of two securities the following question arises: how are they related to each other?
- Consider two random variables  $X$  and  $Y$  on the sample space  $\Omega = \{\omega_1, \omega_2, \dots, \omega_n\}$ . Denote  $X(\omega_i) = x_i$  and  $Y(\omega_i) = y_i$ .
- A **linear fit** is a relation of the following form, for  $\alpha, \beta \in \mathbb{R}$ ,

$$y_i = \alpha + \beta x_i + \epsilon_i.$$

- The number  $\epsilon_i$  is called the **residual** of the  $i$ th observation.
- In Statistics, the best linear fit to observed data is obtained through the method of least-squares: minimise  $\sum_{i=1}^n \epsilon_i^2$ . The line  $y = \alpha + \beta x$  is called the **least-squares linear regression**.
- We denote by  $\epsilon$  the random variable such that  $\epsilon(\omega_i) = \epsilon_i$ . This means that we set  $\epsilon := Y - \alpha - \beta X$ .



# Linear Regression in Probability Theory

- In Probability Theory, if  $\alpha$  and  $\beta$  are chosen to minimise

$$\mathbb{E}_{\mathbb{P}} \left\{ (Y - \alpha - \beta X)^2 \right\} = \mathbb{E}_{\mathbb{P}} (\epsilon^2) = \sum_{i=1}^n \epsilon^2(\omega_i) \mathbb{P}(\omega_i)$$

then the random variable  $\ell_{Y|X} := \alpha + \beta X$  is called the **linear regression** of  $Y$  on  $X$ .

- The next result is valid for both discrete and continuous random variables.

## Theorem (1.6)

*The minimizers  $\alpha$  and  $\beta$  are*

$$\alpha = \mu_Y - \beta \mu_X \quad \text{and} \quad \beta = \frac{\sigma_{XY}}{\sigma_X^2}.$$

*Hence the linear regression of  $Y$  on  $X$  is given by*

$$\ell_{Y|X} = \frac{\sigma_{XY}}{\sigma_X^2} (X - \mu_X) + \mu_Y.$$



# Covariance Matrix

Recall that the covariance of random variables  $X_i$  and  $X_j$  equals

$$\text{Cov}(X_i, X_j) = \sigma_{ij} := \mathbb{E}_{\mathbb{P}} \left\{ (X_i - \mu_i) (X_j - \mu_j) \right\}$$

where  $\mu_i = \mathbb{E}_{\mathbb{P}}(X_i)$  and  $\mu_j = \mathbb{E}_{\mathbb{P}}(X_j)$ .

## Definition (Covariance Matrix)

We consider random variables  $X_i$  for  $i = 1, 2, \dots, n$  with variances  $\sigma_i^2 = \sigma_{ii}$  and covariances  $\sigma_{ij}$ . The matrix  $S$  given by

$$S := \begin{pmatrix} \sigma_1^2 & \sigma_{12} & \cdots & \sigma_{1n} \\ \sigma_{21} & \sigma_2^2 & \cdots & \sigma_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ \sigma_{n1} & \sigma_{n2} & \cdots & \sigma_n^2 \end{pmatrix}$$

is called the **covariance matrix** of  $(X_1, \dots, X_n)$ .



# Correlation Matrix

## Definition (Correlation Matrix)

We consider random variables  $X_i$  for  $i = 1, 2, \dots, n$  with variances  $\sigma_i^2 = \sigma_{ii}$  and covariances  $\sigma_{ij}$ . The matrix  $P$  given by

$$P := \begin{pmatrix} 1 & \rho_{12} & \cdots & \rho_{1n} \\ \rho_{21} & 1 & \cdots & \rho_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ \rho_{n1} & \rho_{n2} & \cdots & 1 \end{pmatrix}$$

is called the **correlation matrix** of  $(X_1, \dots, X_n)$ .

- $S$  and  $P$  are symmetric and positive-definite matrices.
- $S = DPD$  where  $D^2$  is a diagonal matrix whose main diagonal coincides with the main diagonal in  $S$ .
- If  $X_i$ s are independent (or uncorrelated) random variables then  $S$  is a diagonal matrix and  $P = I$  is the identity matrix.



# Linear Combinations of Random Variables

## Theorem

Assume that the random variables  $Y_1$  and  $Y_2$  are some linear combinations of  $X_i$ , that is, there exists vectors  $a^j \in \mathbb{R}^n$  for  $j = 1, 2$  such that

$$Y_j = \sum_{i=1}^n a_i^j X_i = \begin{pmatrix} a_1^j \\ a_2^j \\ \vdots \\ a_n^j \end{pmatrix}^T \begin{pmatrix} X_1 \\ X_2 \\ \vdots \\ X_n \end{pmatrix} = \langle a^j, X \rangle$$

where  $\langle \cdot, \cdot \rangle$  denotes the inner product in  $\mathbb{R}^n$ . Then

$$\text{Cov}(Y_1, Y_2) = (a^1)^T S a^2 = (a^1)^T D P D a^2.$$



# Conditional Distributions and Expectations

For two random variables  $X_1$  and  $X_2$  and an arbitrary set  $A$  such that  $P(X_2 \in A) \neq 0$ , we define the **conditional probability**

$$\mathbb{P}(X_1 \in A_1 \mid X_2 \in A_2) := \frac{\mathbb{P}(X_1 \in A_1, X_2 \in A_2)}{\mathbb{P}(X_2 \in A_2)}$$

and the **conditional expectation**

$$\mathbb{E}_{\mathbb{P}}(X_1 \mid X_2 \in A) := \frac{\mathbb{E}_{\mathbb{P}}(X_1 \mathbb{1}_{\{X_2 \in A\}})}{\mathbb{P}(X_2 \in A)}$$

where  $\mathbb{1}_{\{X_2 \in A\}} : \Omega \rightarrow \{0, 1\}$  is the **indicator function** of  $\{X_2 \in A\}$ , that is,

$$\mathbb{1}_{\{X_2 \in A\}}(\omega) = \begin{cases} 1, & \text{if } X_2(\omega) \in A, \\ 0, & \text{otherwise.} \end{cases}$$



## Discrete Case

- Assume that  $X$  and  $Y$  are discrete random variables

$$p_i = \mathbb{P}(X = x_i) > 0 \quad \text{for } i = 1, 2, \dots \quad \text{and} \quad \sum_{i=1}^{\infty} p_i = 1,$$

$$\hat{p}_j = \mathbb{P}(Y = y_j) > 0 \quad \text{for } j = 1, 2, \dots \quad \text{and} \quad \sum_{j=1}^{\infty} \hat{p}_j = 1.$$

### Definition (Conditional Distribution and Expectation)

Then the **conditional distribution** equals

$$p_{X|Y}(x_i | y_j) = \mathbb{P}(X = x_i | Y = y_j) := \frac{\mathbb{P}(X = x_i, Y = y_j)}{\mathbb{P}(Y = y_j)} = \frac{p_{i,j}}{\hat{p}_j}$$

and the **conditional expectation**  $\mathbb{E}_{\mathbb{P}}(X | Y)$  is given by

$$\mathbb{E}_{\mathbb{P}}(X | Y = y_j) := \sum_{i=1}^{\infty} x_i \mathbb{P}(X = x_i | Y = y_j) = \sum_{i=1}^{\infty} x_i \frac{p_{i,j}}{\hat{p}_j}.$$



## Discrete Case

- It is easy to check that

$$\begin{aligned} p_i &= \mathbb{P}(X = x_i) = \sum_{j=1}^{\infty} \mathbb{P}(X = x_i \mid Y = y_j) \mathbb{P}(Y = y_j) \\ &= \sum_{j=1}^{\infty} p_{X|Y}(x_i \mid y_j) \hat{p}_j. \end{aligned}$$

- The expected value  $E_{\mathbb{P}}(X)$  satisfies

$$\mathbb{E}_{\mathbb{P}}(X) = \sum_{j=1}^{\infty} \mathbb{E}_{\mathbb{P}}(X \mid Y = y_j) \mathbb{P}(Y = y_j).$$

### Definition (Conditional cdf)

The conditional cdf  $F_{X|Y}(\cdot \mid y_j)$  of  $X$  given  $Y$  is defined for all  $y_j$  such that  $\mathbb{P}(Y = y_j) > 0$  by

$$F_{X|Y}(x \mid y_j) := \mathbb{P}(X \leq x \mid Y = y_j) = \sum_{x_i \leq x} p_{X|Y}(x_i \mid y_j).$$

Hence  $\mathbb{E}_{\mathbb{P}}(X \mid Y = y_j)$  is the mean of the conditional distribution.



# Continuous Case

- Assume that the continuous random variables  $X$  and  $Y$  have the joint pdf  $f_{X,Y}(x,y)$ .

## Definition (Conditional pdf and cdf)

The **conditional pdf** of  $Y$  given  $X$  is defined for all  $x$  such that  $f_X(x) > 0$  and equals

$$f_{Y|X}(y|x) := \frac{f_{X,Y}(x,y)}{f_X(x)} \quad \text{for } y \in \mathbb{R}.$$

The **conditional cdf** of  $Y$  given  $X$  equals

$$F_{Y|X}(y|x) := \mathbb{P}(Y \leq y | X = x) = \int_{-\infty}^y \frac{f_{X,Y}(x,u)}{f_X(x)} du.$$



# Continuous Case

## Definition (Conditional Expectation)

The **conditional expectation** of  $Y$  given  $X$  is defined for all  $x$  such that  $f_X(x) > 0$  by

$$\mathbb{E}_{\mathbb{P}}(Y | X = x) := \int_{-\infty}^{\infty} y \, dF_{Y|X}(y | x) = \int_{-\infty}^{\infty} y \frac{f_{X,Y}(x, y)}{f_X(x)} \, dy.$$

- An important property of conditional expectation is that

$$\mathbb{E}_{\mathbb{P}}(Y) = \mathbb{E}_{\mathbb{P}}(\mathbb{E}_{\mathbb{P}}(Y | X)) = \int_{-\infty}^{\infty} \mathbb{E}_{\mathbb{P}}(Y | X = x) f_X(x) \, dx.$$

- Hence the expected value  $\mathbb{E}_{\mathbb{P}}(Y)$  can be determined by first conditioning on  $X$  (in order to compute  $\mathbb{E}_{\mathbb{P}}(Y|X)$ ) and then integrating with respect to the pdf of  $X$ .