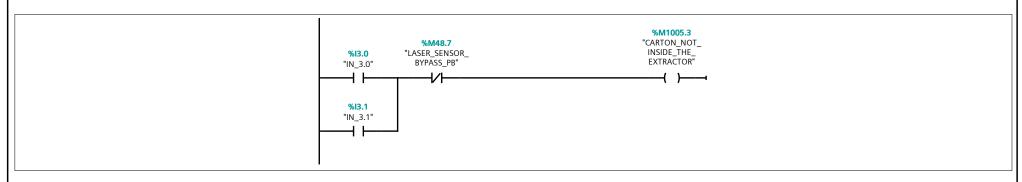
Totally Integrated Automation Portal	
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SWING ARM MOTOR [FC3]

SWING ARM MOTOR Properties							
General							
Name	SWING ARM MOTOR	Number	3	Туре	FC	Language	LAD
Numbering	Automatic						
Information							
Title		Author		Comment		Family	
Version	0.1	User-defined ID					

Name	Data type	Default value	Comment
Input			
Output			
InOut			
Temp			
Constant			
▼ Return			
SWING ARM MOTOR	Void		

Network 1: LASER_SENSOR_FOR_CARTON_CONFIRMATION:

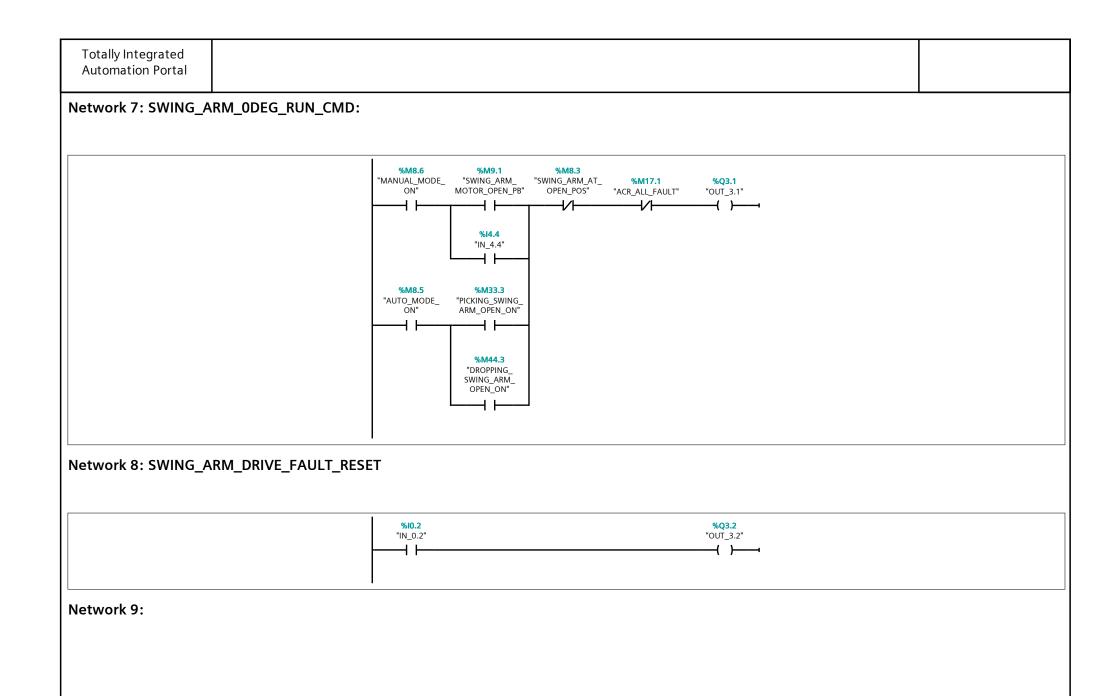


Network 2: SWING_ARM_AT_OPEN_POSITION:

```
Totally Integrated
  Automation Portal
                                                                                                                         %M8.3
                                                               %13.2
                                                                              %I3.4
                                                                                                                     "SWING_ARM_AT_
OPEN_POS"
                                                              "IN_3.2"
                                                                             "IN_3.4"
Network 3: SWING_ARM_AT_OPEN_POSITION:
                                                              %M27.4
                                                                                                                         %M8.3
                                                           "PICKING_SWING_
                                                                             %M1.2
                                                                                                                     "SWING_ARM_AT_
                                                                                                                        OPEN_POS"
                                                           ARM_CLOSE_ON"
                                                                           "AlwaysTRUE"
                                                                                                                          _( R )____
                                                              %M43.5
                                                            "DROPPING
                                                            SWING_ARM_
CLOSE_ON"
                                                              %M8.4
                                                          "SWING_ARM_AT_
CLOSE_POS"
Network 4: SWING_ARM_AT_CLOSE_POSITION:
                                                                                                                         %M8.4
                                                                                                                     "SWING_ARM_AT_
CLOSE_POS"
                                                                              %I3.5
                                                               %13.3
                                                              "IN_3.3"
                                                                             "IN_3.5"
Network 5: SWING_ARM_AT_OPEN_POSITION:
```

Totally Integrated **Automation Portal** %M33.3 %M8.4 "PICKING_SWING_ ARM_OPEN_ON" %M1.2 "SWING_ARM_AT_ CLOSE_POS" "AlwaysTRUE" _(R)____ %M44.3 "DROPPING_ SWING_ARM_ OPEN_ON" %M8.3 "SWING_ARM_AT_ OPEN_POS" Network 6: SWING_ARM_90DEG_RUN_CMD: %M9.0 %M8.6 "SWING_ARM_ MOTOR_CLOSE_ %M8.4 **%Q3.0** "OUT_3.0" "MANUAL_MODE_ "SWING_ARM_AT_ %M17.1 ON" PB" CLOSE_POS" "ACR_ALL_FAULT" %14.4 "IN_4.4" %M8.5 %M27.4 "PICKING_SWING_ ARM_CLOSE_ON" "AUTO_MODE_ %M43.5

"DROPPING_ SWING_ARM_ CLOSE_ON"



Totally Integrated Automation Portal				
			1	