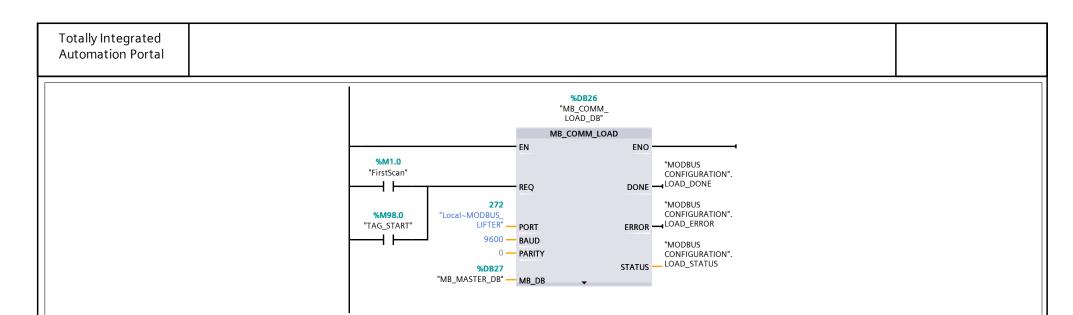
Totally Integ Automation							
ACD NEW 11122024 / AMD V 2 [CDU 1214C DC/DC/DC] / Drogram blocks							
ACR_NEW_11122024 / AMR V 3 [CPU 1214C DC/DC/DC] / Program blocks							
LIFTER MOTOR [FC35]							
LIFTER MOTOR Properties							
General	rioperaes						
Name	LIFTER MOTOR	Number	35	Туре	FC	Language	LAD
Numbering	Automatic		:				

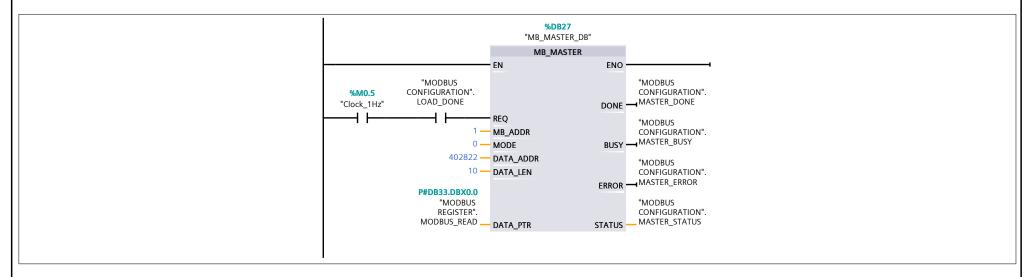
LIFTER MOTOR Properties							
General							
Name	LIFTER MOTOR	Number	35	Type	FC	Language	LAD
Numbering	Automatic						
Information							
Title		Author		Comment		Family	
Version	0.1	User-defined ID					

LIFTER MOTOR						
Name	Data type	Default value	Comment			
Input						
Output						
InOut						
Temp						
Constant						
<b>▼</b> Return						
LIFTER MOTOR	Void					

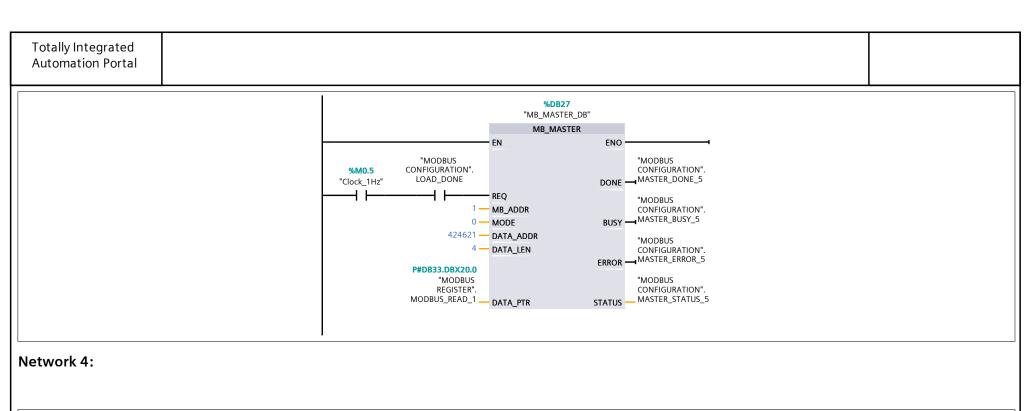
# Network 1:

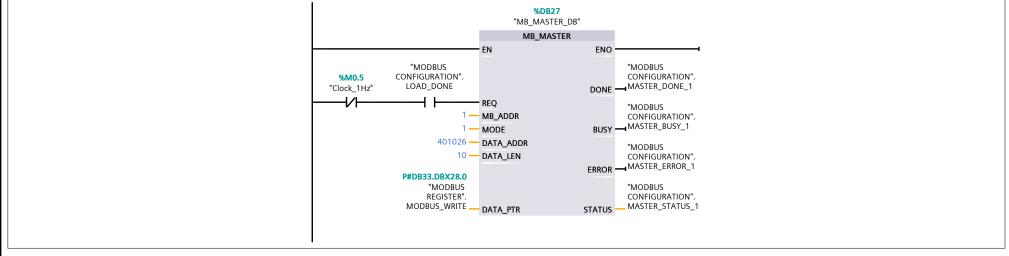


#### Network 2:

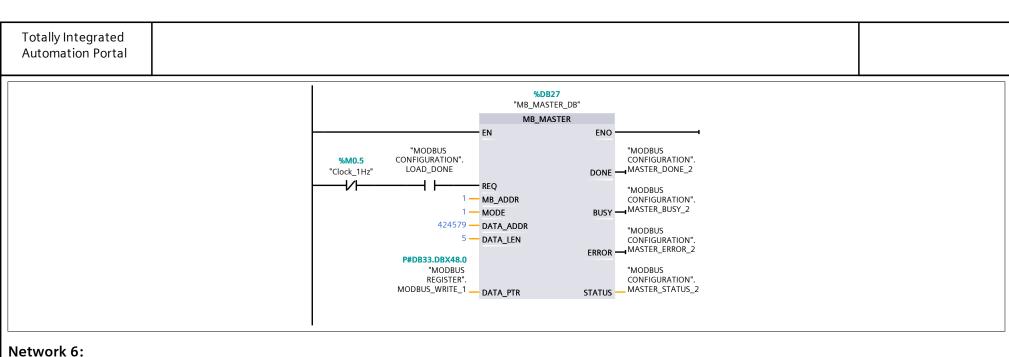


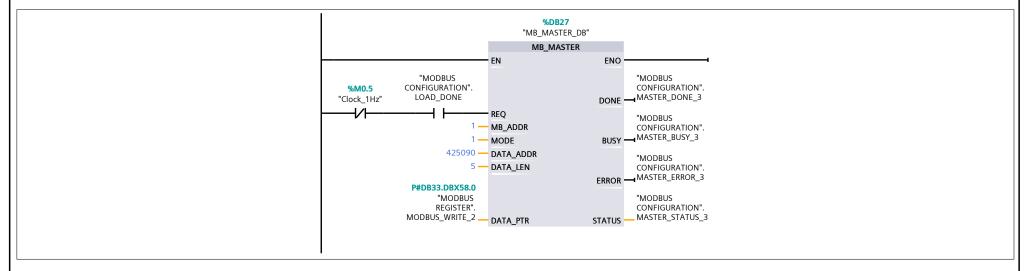
# Network 3:



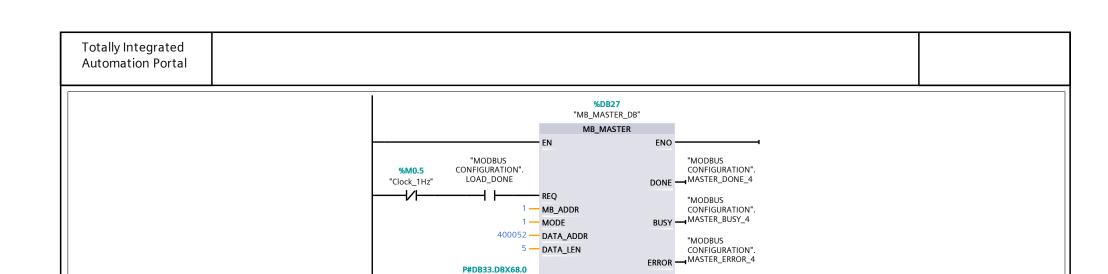


### Network 5:





## Network 7:



"MODBUS CONFIGURATION".

STATUS -

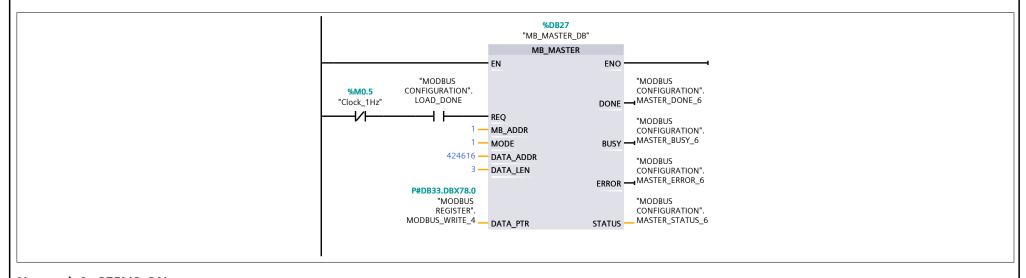
\_MASTER\_STATUS\_4

"MODBUS

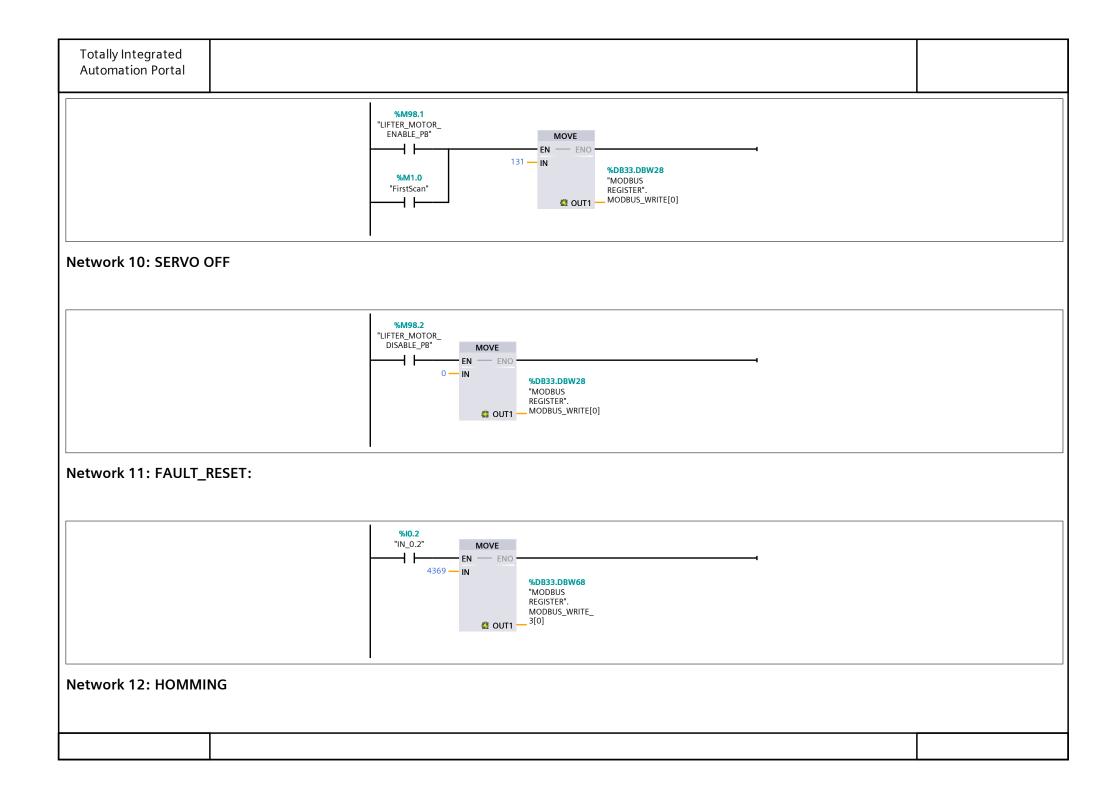
REGISTER".

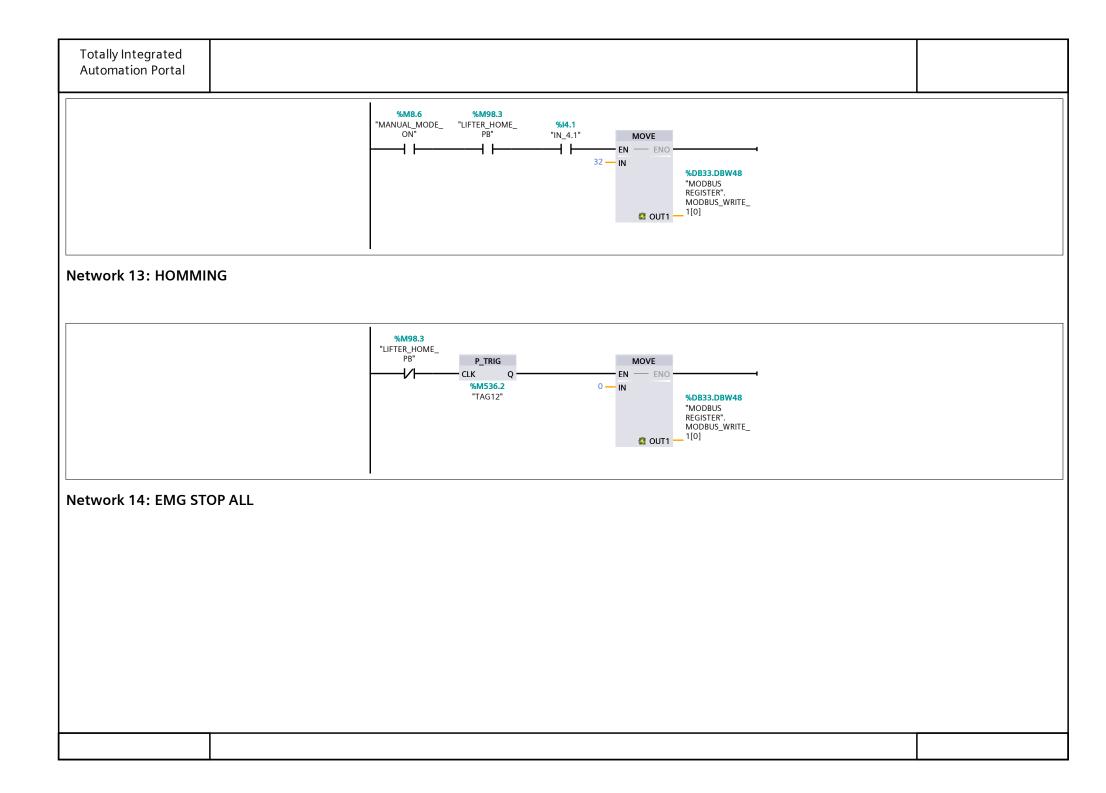
MODBUS\_WRITE\_3 \_\_\_ DATA\_PTR

#### Network 8:

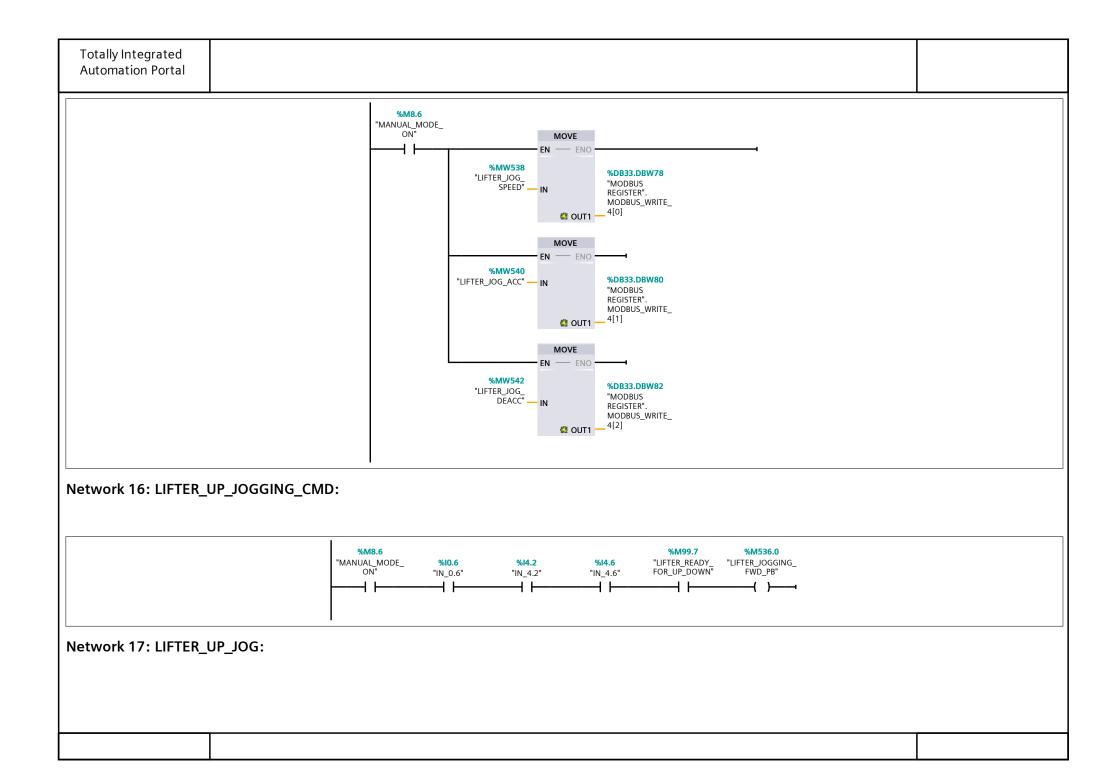


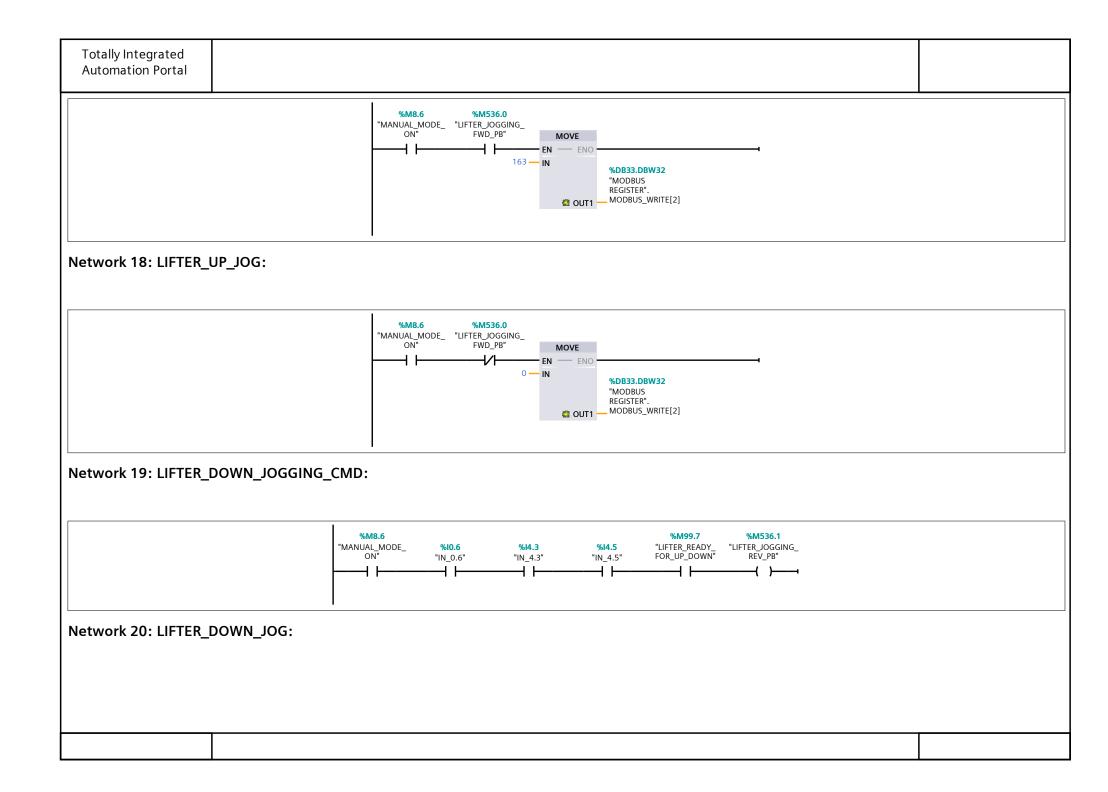
Network 9: SERVO ON



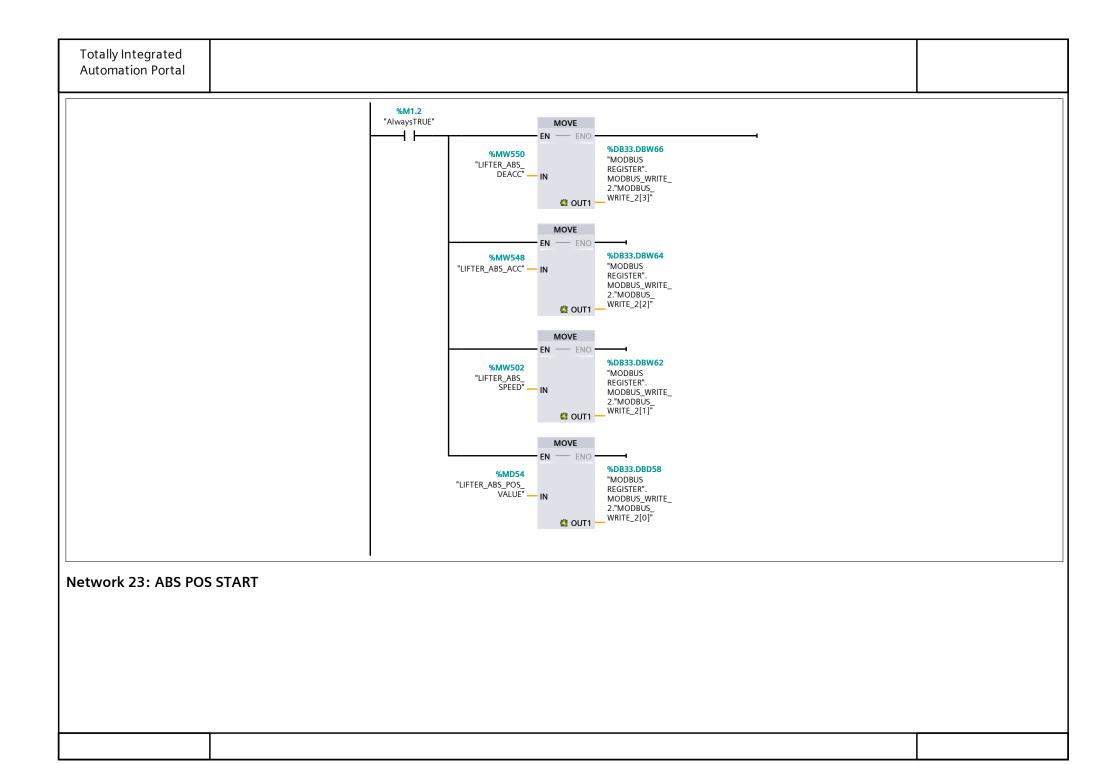


Totally Integrated Automation Portal %M2.7 "EMG\_STOP\_PB" MOVE - EN - ENO %DB33.DBW48 **%I0.0** "IN\_0.0" "MODBUS REGISTER". MODBUS\_WRITE\_ **₫** OUT1 — <sup>1[0]</sup> **%I3.6** "IN\_3.6" <del>-</del>//-**%I4.5** "IN\_4.5" **%I4.6** "IN\_4.6" **Network 15: JOG PARAMETERS:** 



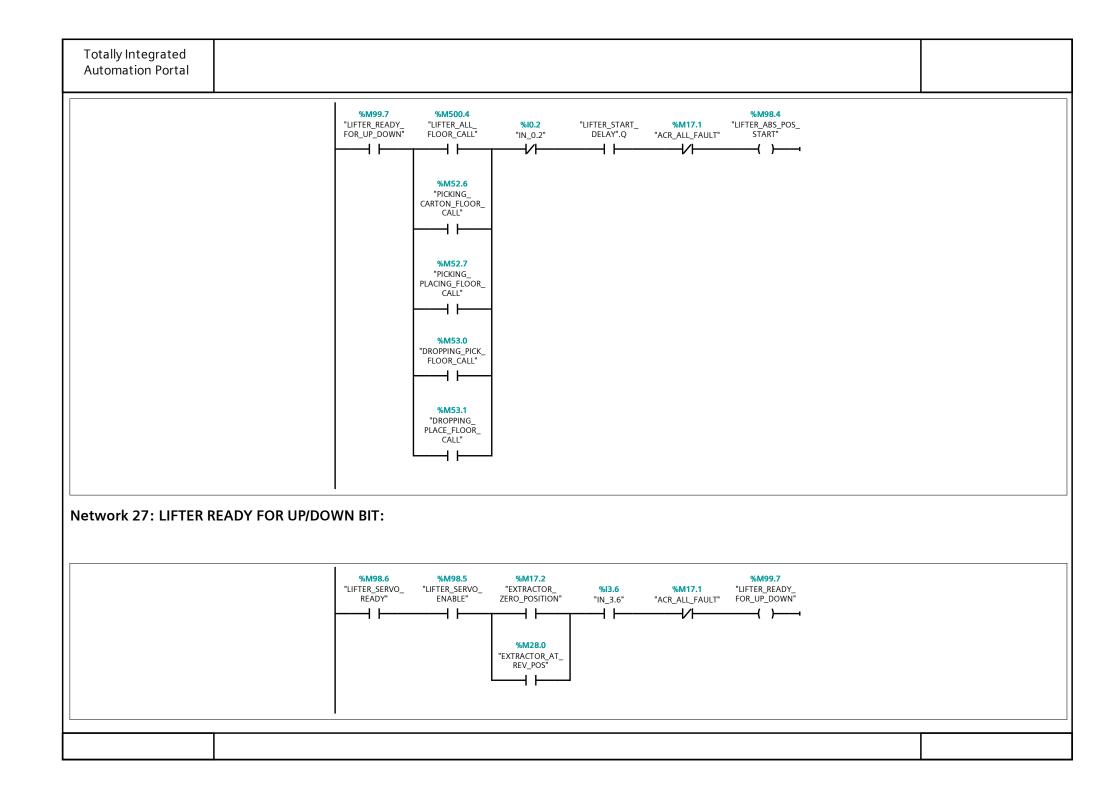


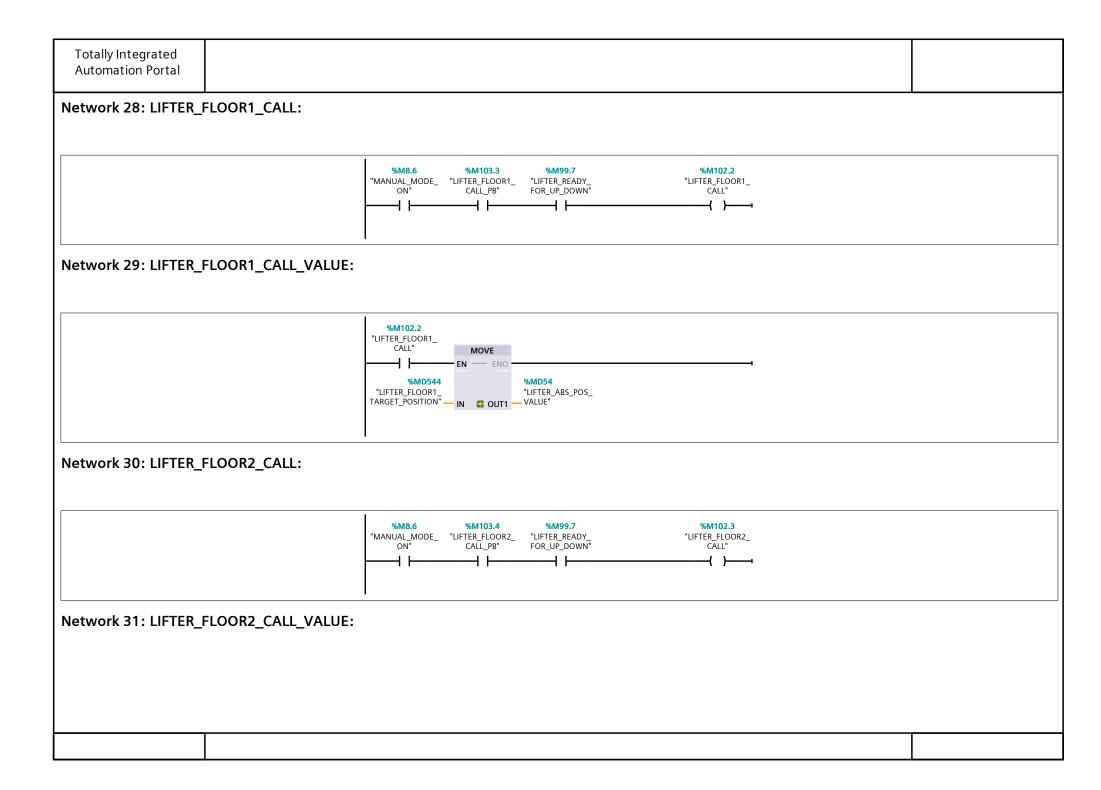
Totally Integrated **Automation Portal** %M8.6 %M536.1 "MANUAL\_MODE\_ "LIFTER\_JOGGING\_ ON" REV\_PB" MOVE 164 — IN %DB33.DBW36 "MODBUS REGISTER". OUT1 — MODBUS\_WRITE[4] Network 21: LIFTER\_DOWN\_JOG: %M8.6 %M536.1 "MANUAL\_MODE\_ "LIFTER\_JOGGING\_ ON" REV\_PB" MOVE - EN 0 — IN %DB33.DBW36 "MODBUS REGISTER". OUT1 — MODBUS\_WRITE[4] **Network 22: ABS POS DATA** 



Totally Integrated **Automation Portal** %M98.4 "LIFTER\_ABS\_POS\_ START" MOVE - ENO 16 — IN %DB33.DBW48 "MODBUS REGISTER". MODBUS\_WRITE\_ **₫** OUT1 — <sup>1[0]</sup> **Network 24: ABS POS START** %M500.5 "LIFTER\_ POSITIONING\_ COMPLETE" P\_TRIG MOVE %M500.6 0 — IN "TAG\_11" %DB33.DBW48 "MODBUS REGISTER". MODBUS\_WRITE\_ **₫** OUT1 — <sup>1[0]</sup> Network 25: LIFTER\_ABS\_POS\_START\_DELAY:

Totally Integrated **Automation Portal** %DB25 "LIFTER\_START\_ DELAY" %M500.4 "LIFTER\_ALL\_ FLOOR\_CALL" TON Time T#500MS — PT ET — T#0ms %M52.6 "PICKING\_ CARTON\_FLOOR\_ CALL" %M52.7 "PICKING\_ PLACING\_FLOOR\_ CALL" %M53.0 "DROPPING\_PICK\_ FLOOR\_CALL" %M53.1 "DROPPING\_ PLACE\_FLOOR\_ CALL" Network 26: LIFTER\_ABS\_POS\_START:





```
Totally Integrated
  Automation Portal
                                                             %M102.3
                                                           "LIFTER_FLOOR2_
CALL"
                                                                             MOVE
                                                                              - ENO
                                                                 %MD504
                                                                                       %MD54
                                                          "LIFTER_FLOOR2_ IN LOUT1 "LIFTER_ VALUE"
                                                                                       "LIFTER_ABS_POS_
Network 32: LIFTER_FLOOR3_CALL:
                                                       %M8.6
                                                                                                                 %M99.7
                                                                     %M103.5
                                                                                                                               %M102.4
                                                   "MANUAL_MODE_ "LIFTER_FLOOR3_
                                                                                                               "LIFTER_READY_
                                                                                                                             "LIFTER_FLOOR3_
                                                        ON"
                                                                    CALL_PB"
                                                                                                              FOR_UP_DOWN"
                                                                                                                                 CALL"
                                                       %M8.5
                                                                    %M1006.2
                                                                                    %M16.7
                                                                                                   %M36.1
                                                    "AUTO_MODE_
                                                                     "ROBOT_
                                                                                 "PICKING_AUTO_
                                                                                                 "DROPPING_
                                                        ON"
                                                                   RUNNING_FB"
                                                                                   CYCLE_ON"
                                                                                               AUTO_CYCLE_ON"
Network 33: LIFTER_FLOOR3_CALL_VALUE:
                                                             %M102.4
                                                           "LIFTER_FLOOR3_
CALL"
                                                                             MOVE
                                                                          EN - ENO
                                                                 %MD508
                                                                                       %MD54
                                                                                       "LIFTER_ABS_POS_
                                                           "LIFTER_FLOOR3_
                                                           TARGET_POSITION" — IN 🚜 OUT1 — VALUE"
Network 34: LIFTER_FLOOR4_CALL:
```

