

Totally Integrated Automation Portal		
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TT MOTOR [FC1]

TT MOTOR Properties

General

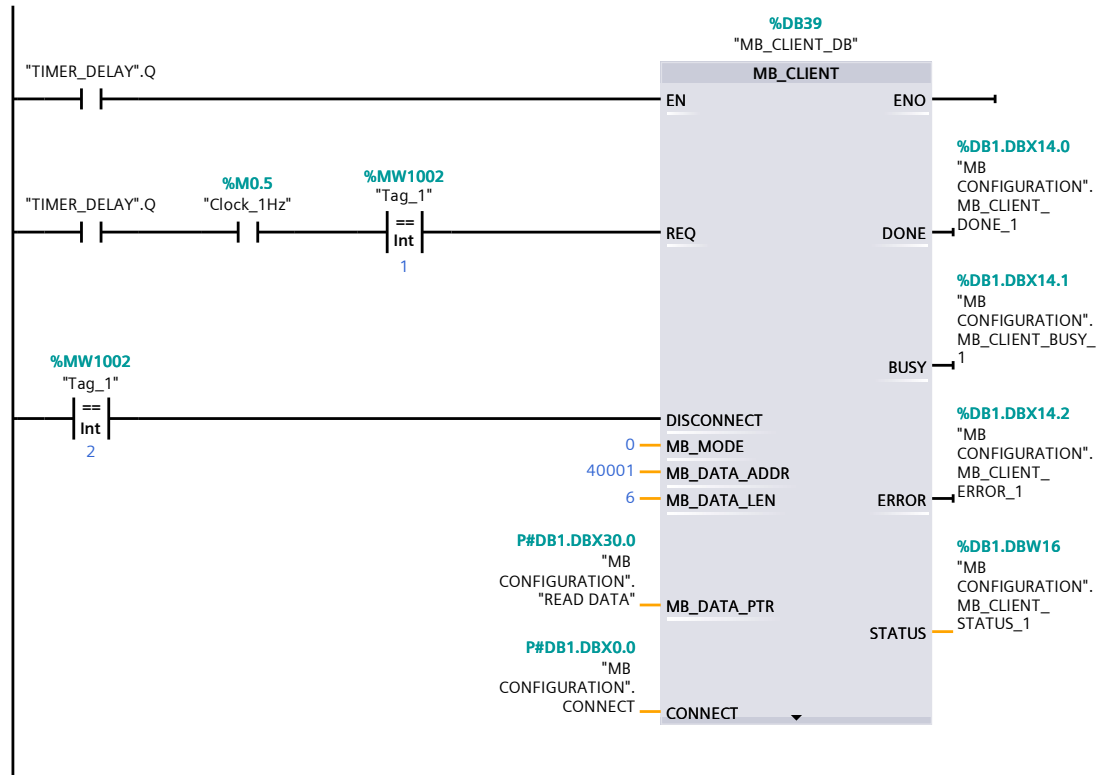
Name	TT MOTOR	Number	1	Type	FC	Language	LAD
Numbering	Automatic						

Information

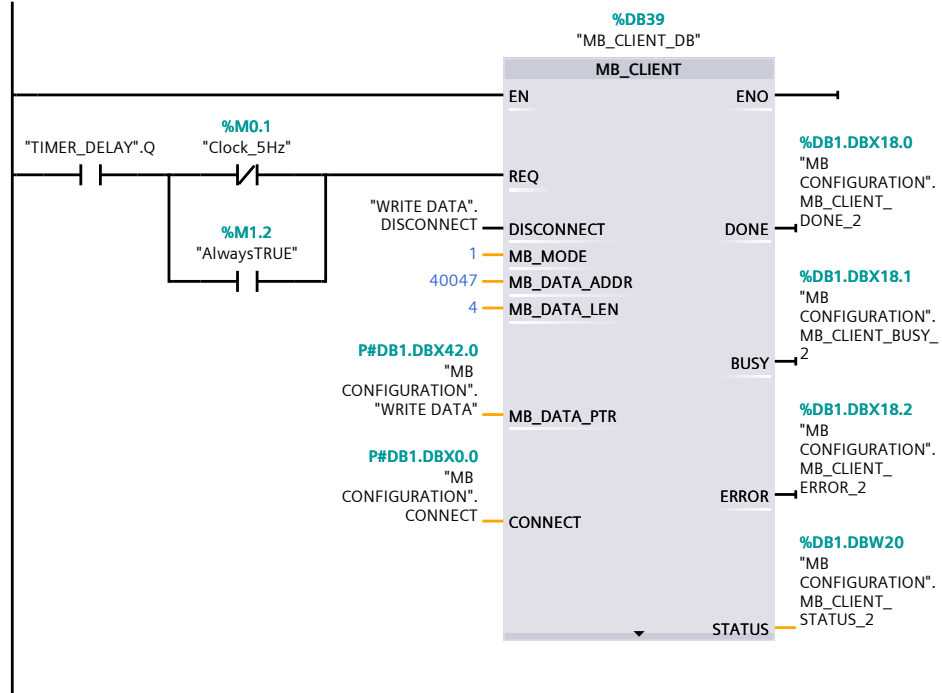
Title		Author		Comment		Family	
Version	0.1	User-defined ID					

Name	Data type	Default value	Comment
Input			
Output			
InOut			
Temp			
Constant			
▼ Return			
TT MOTOR	Void		

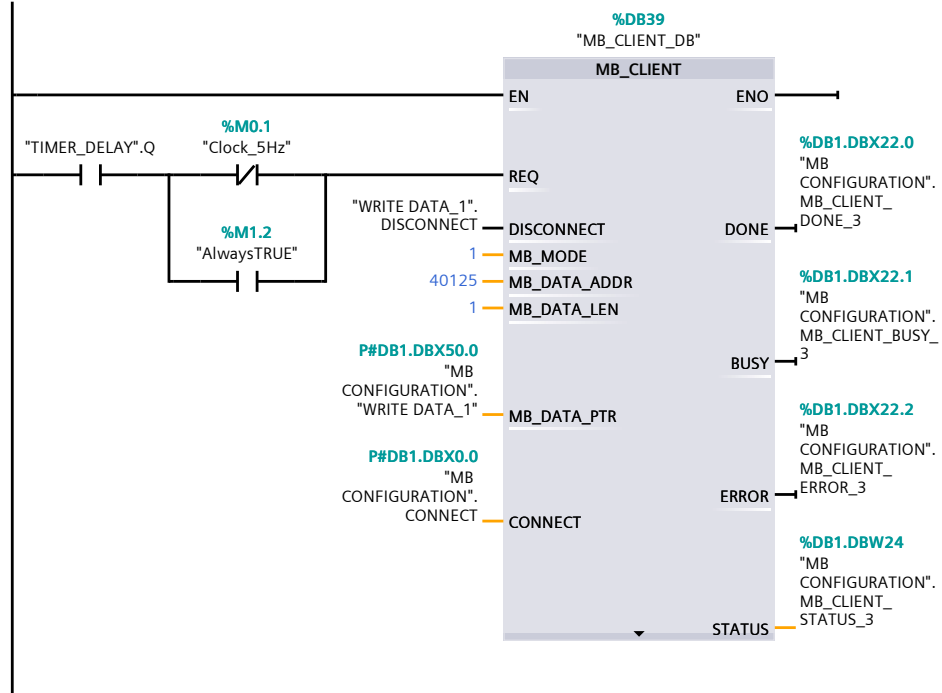
Network 1:



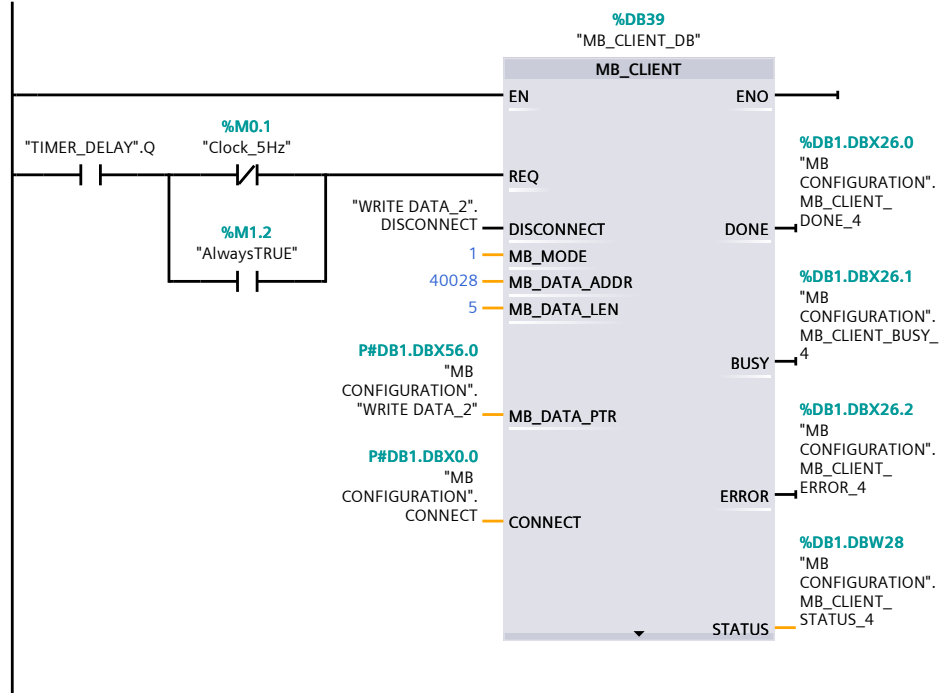
Network 2:



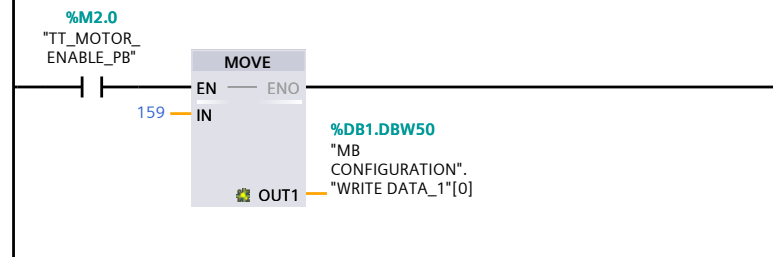
Network 3:



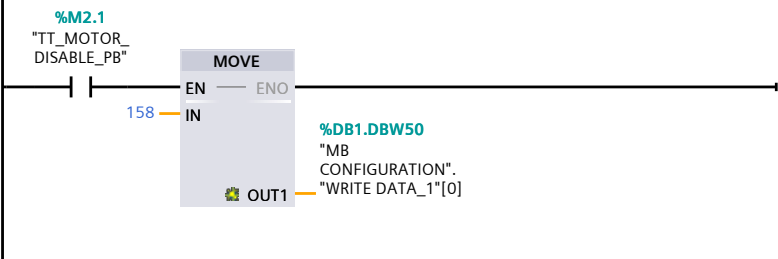
Network 4:



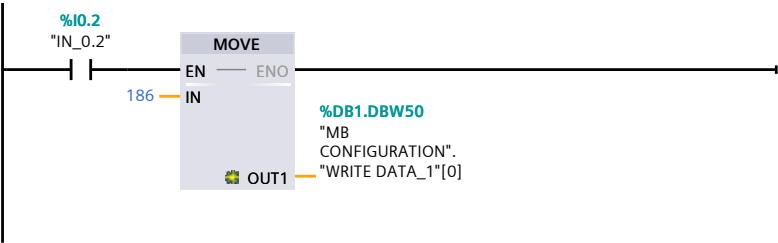
Network 5: SERVO ON



Network 6: SERVO OFF

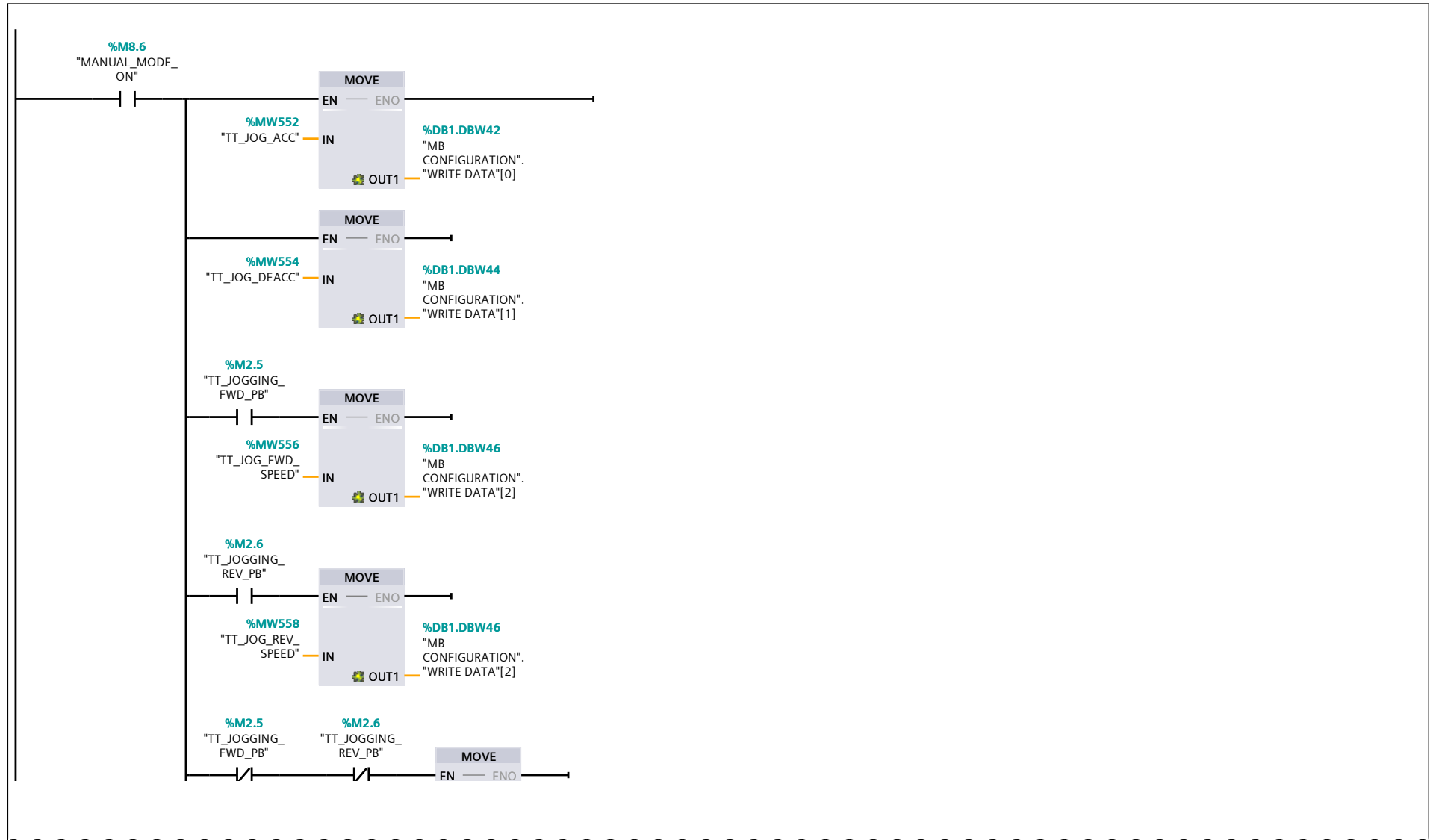


Network 7: ALARM RESET



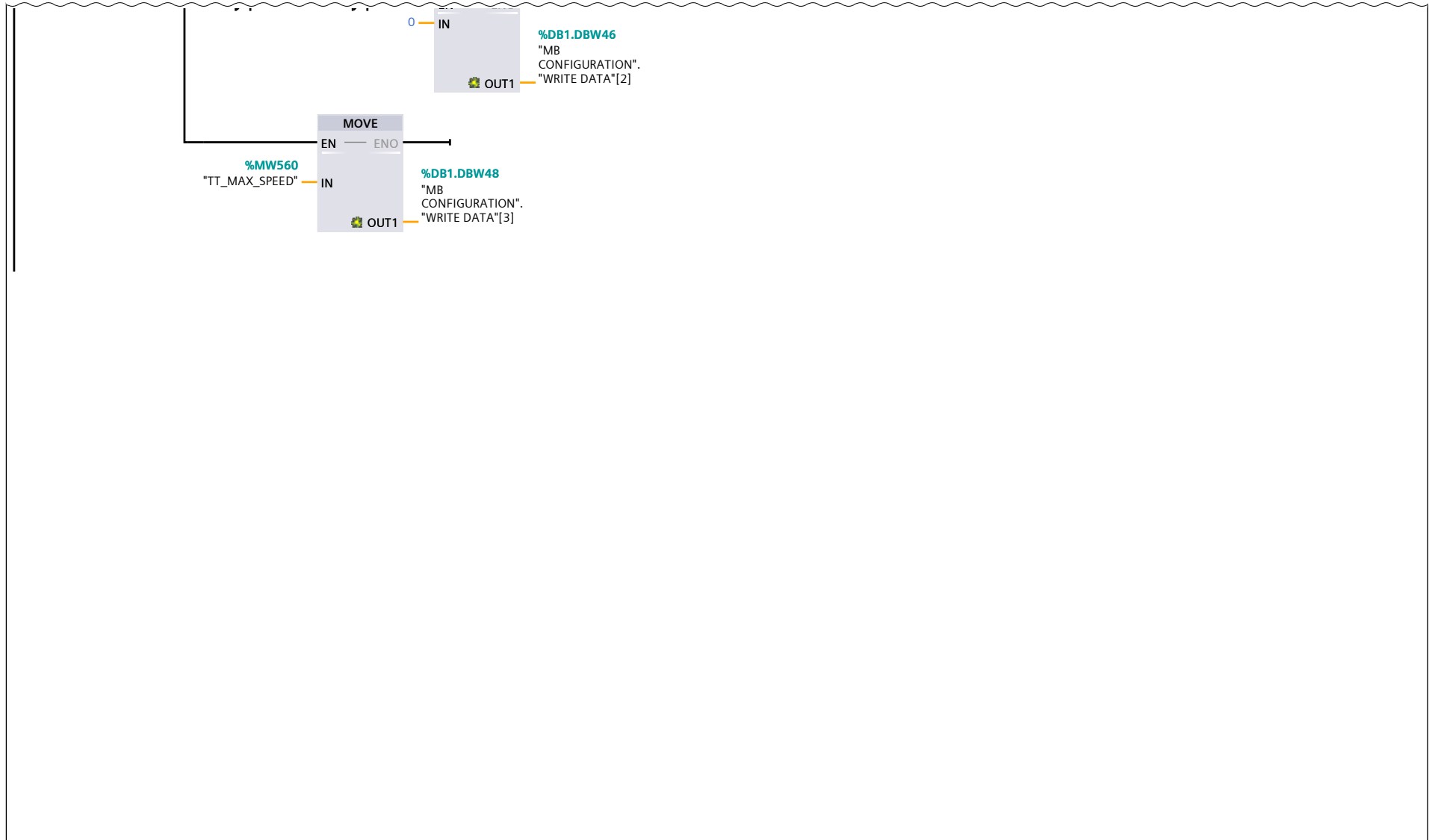
Network 8: JOG DATA

Network 8: JOG DATA (1.1 / 2.1)

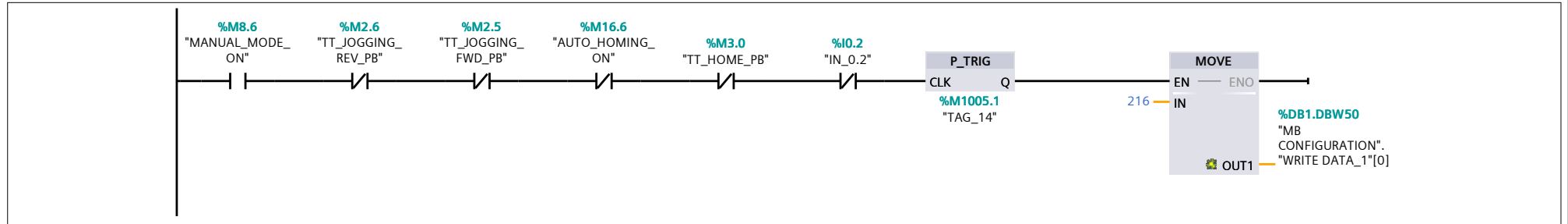


Network 8: JOG DATA (2.1 / 2.1)

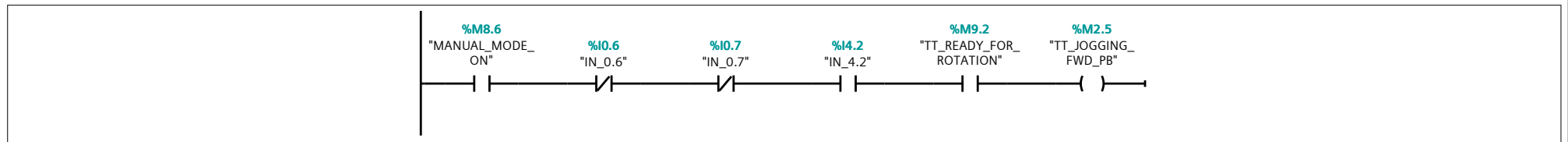
1.1 (Page1 - 7)



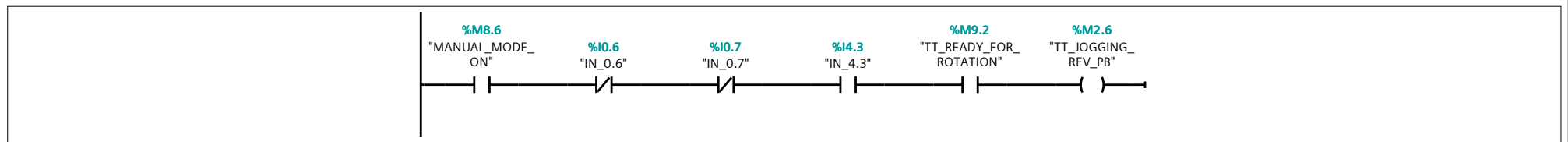
Network 9: JOGGING STOP



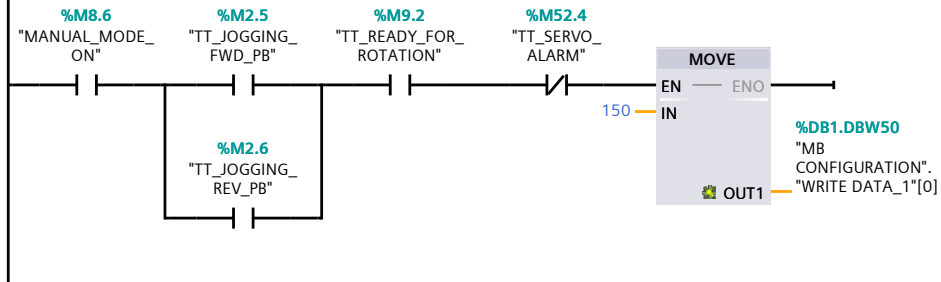
Network 10: TT_FWD_JOGGING_CMD:



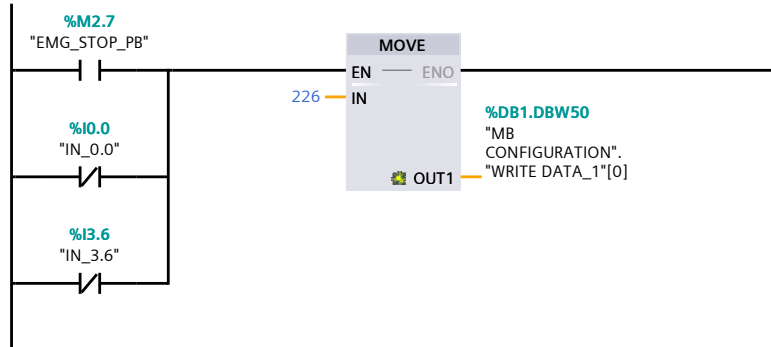
Network 11: TT_REV_JOGGING_CMD:



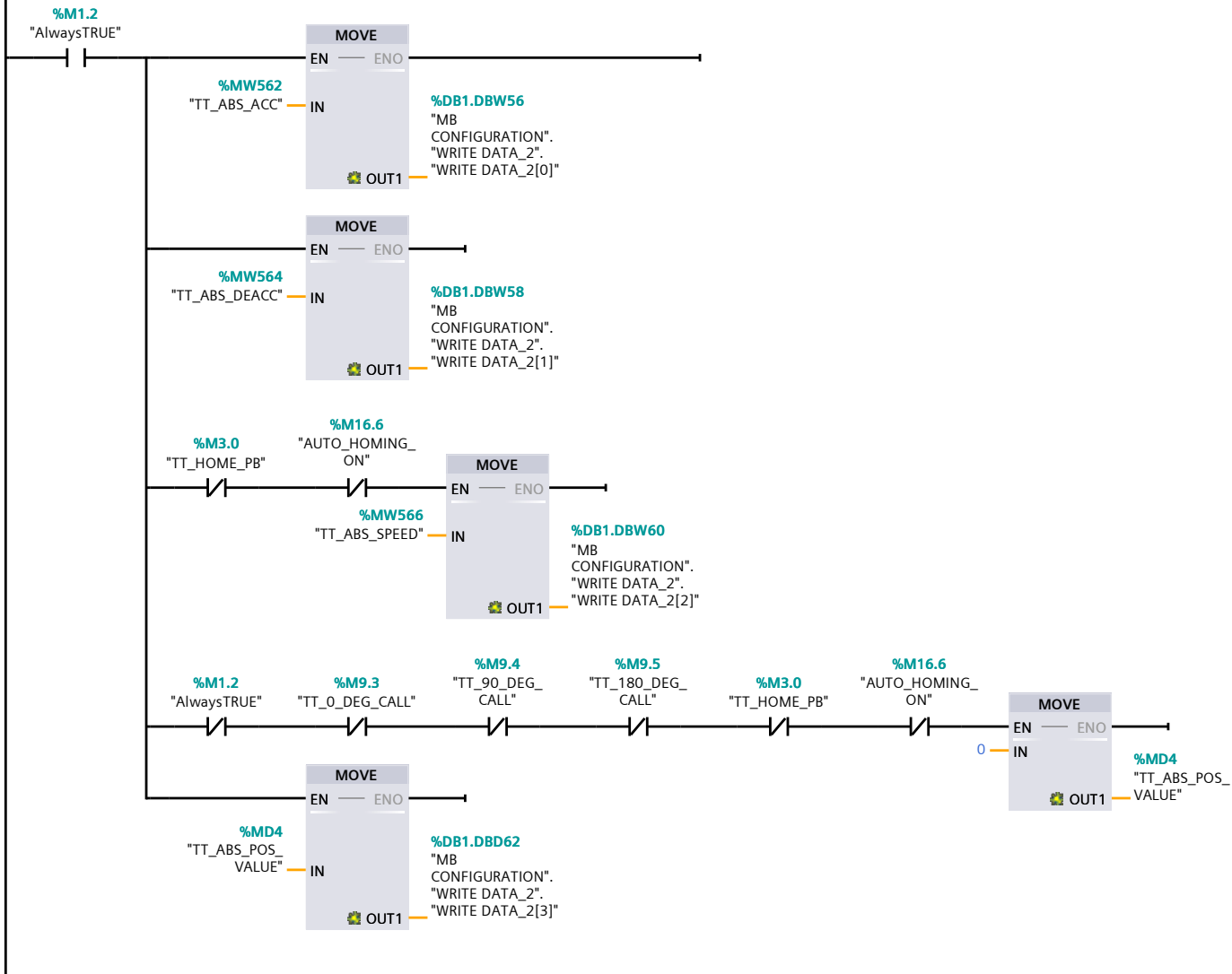
Network 12: JOGGING START



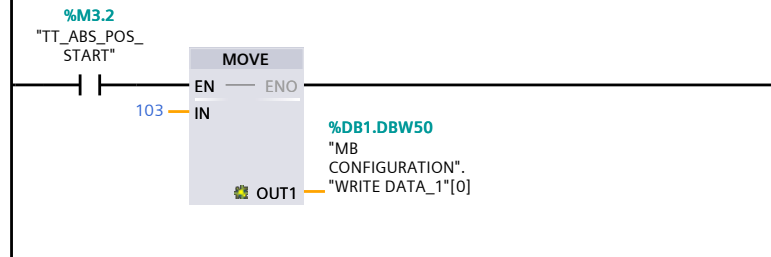
Network 13: EMG STOP ALL



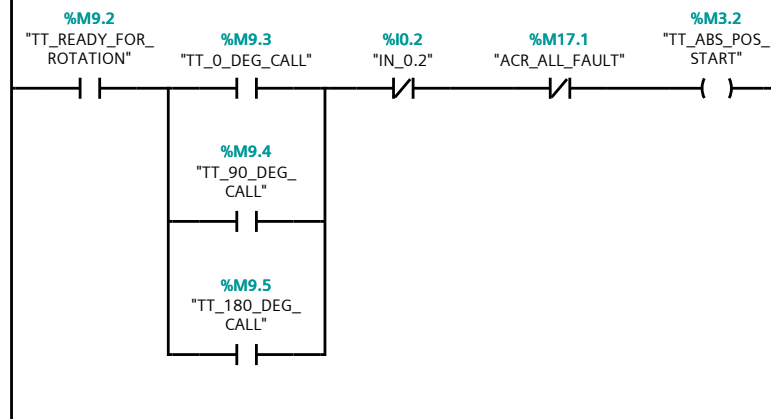
Network 14: ABS POS DATA



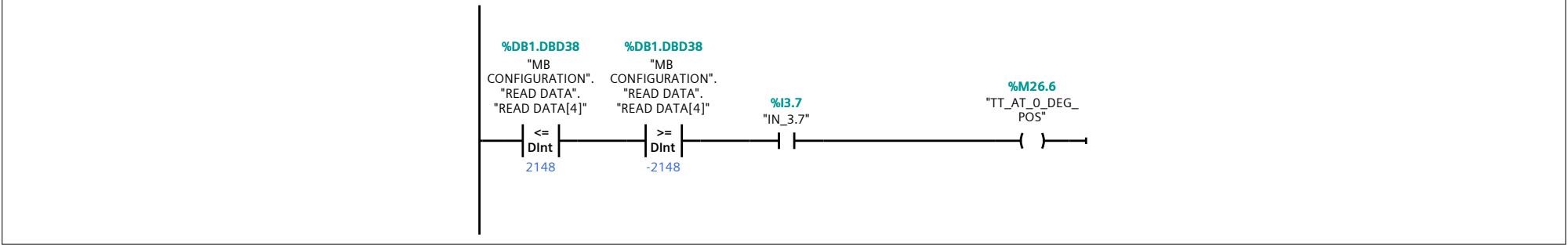
Network 15: ABS POS START



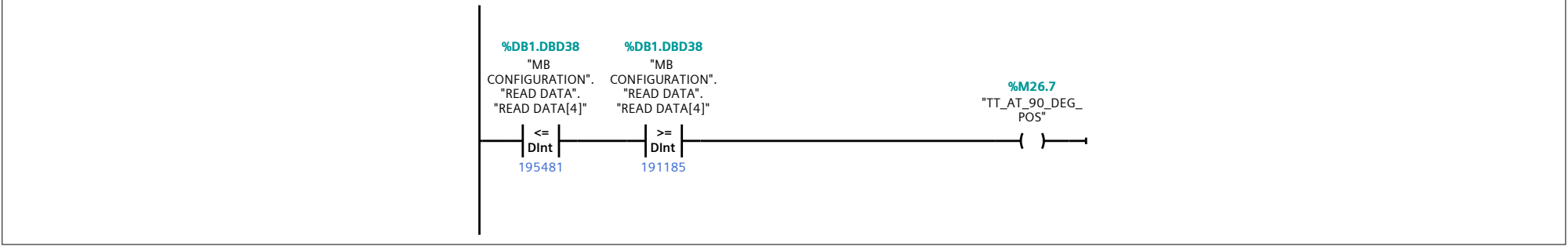
Network 16: TT_ABS_POS_START:



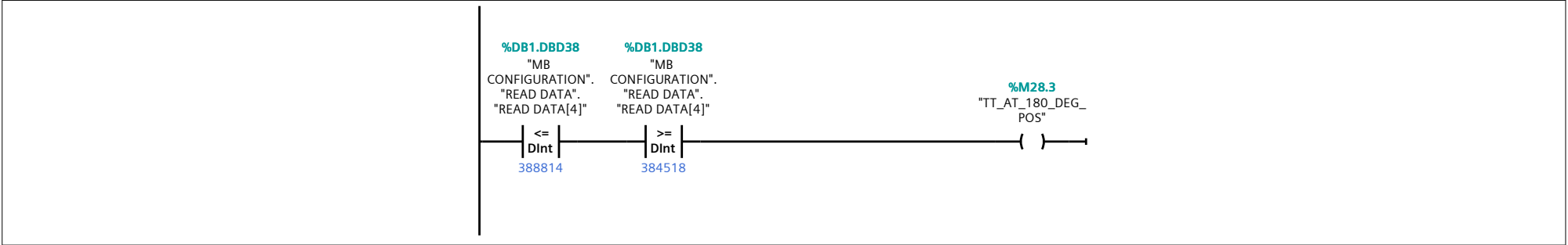
Network 17: TT_AT_0DEG_POSITION:



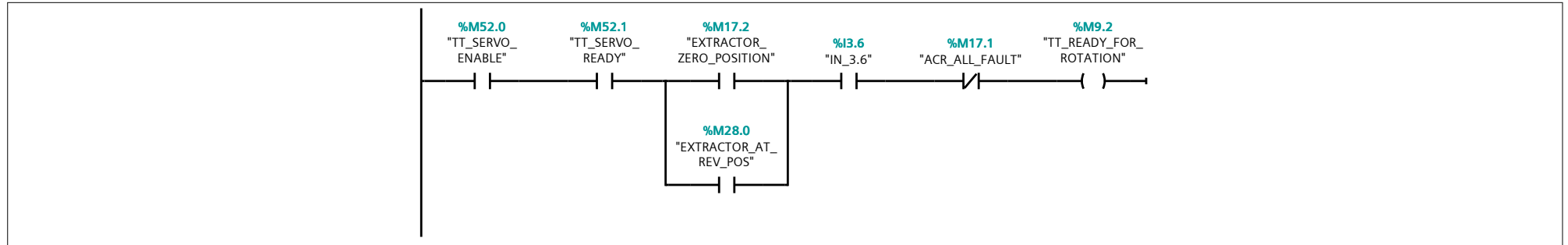
Network 18: TT_AT_90_DEG_POSITION:



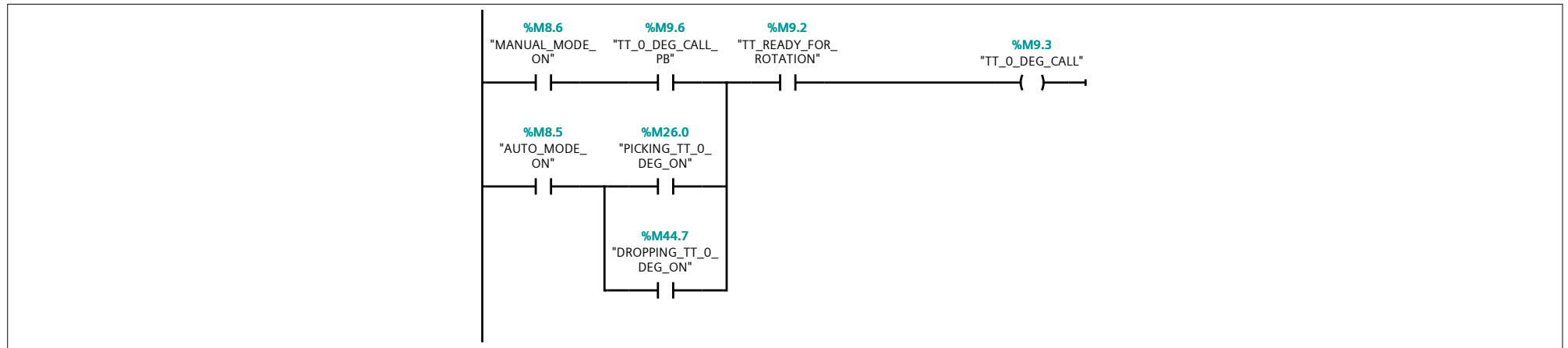
Network 19: TT_AT_180_DEG_POSITION:



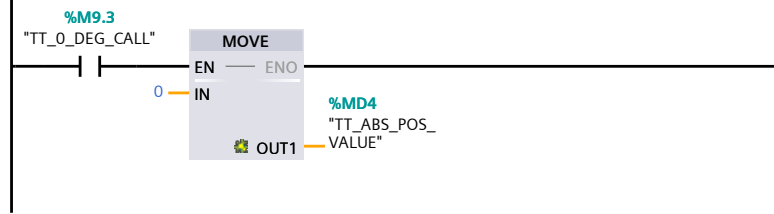
Network 20: TT READY FOR ROTATION BIT:



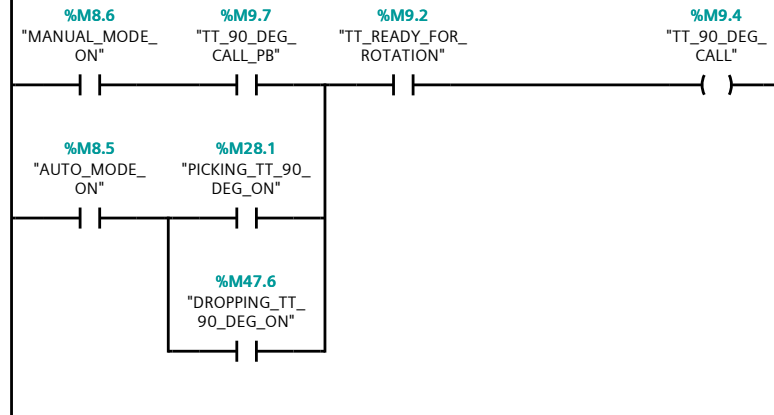
Network 21: TT 0 DEG CALL:



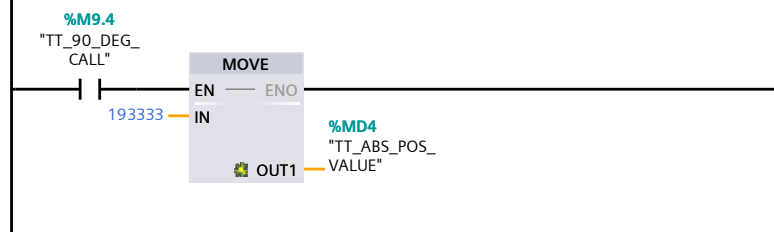
Network 22: TT 0 DEG POSITION VALUE



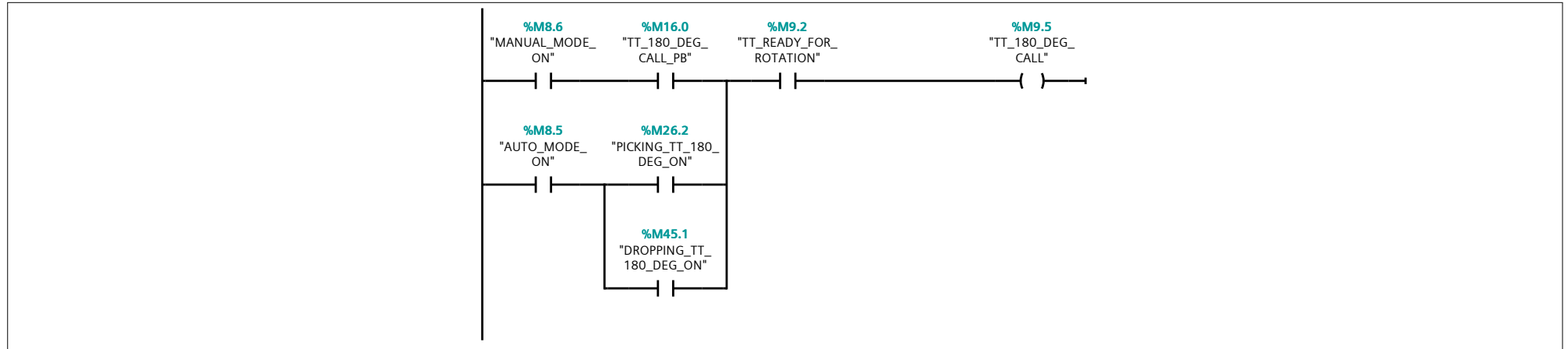
Network 23: TT 90 DEG CALL:



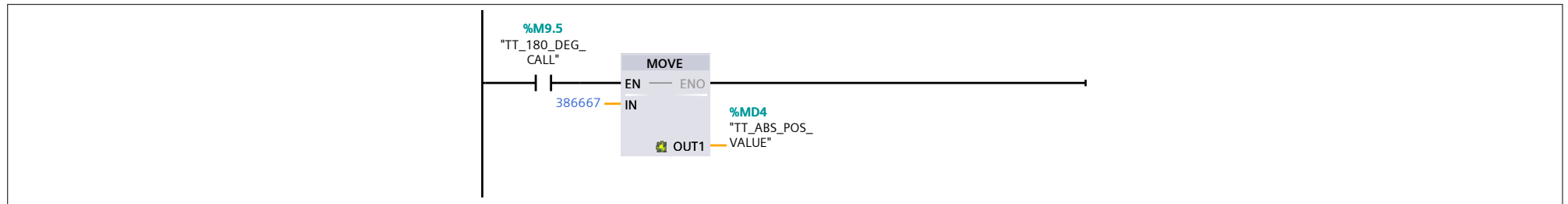
Network 24: TT 90 DEG POSITION VALUE



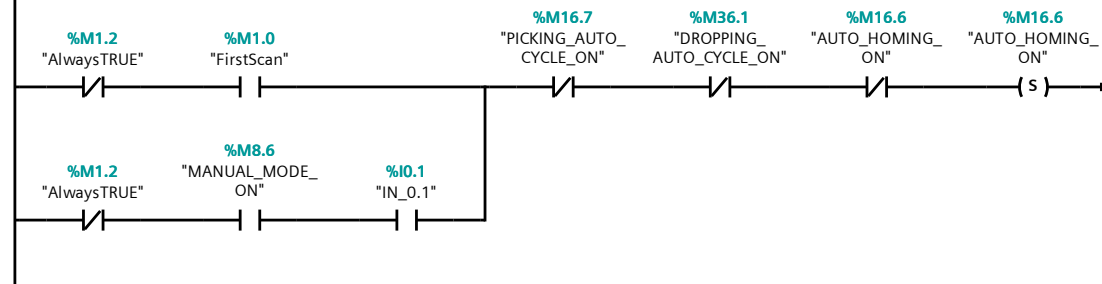
Network 25: TT 180 DEG CALL:



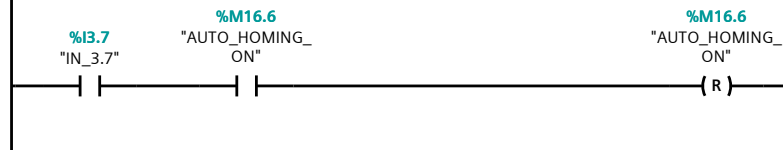
Network 26: TT 180 DEG POSITION VALUE



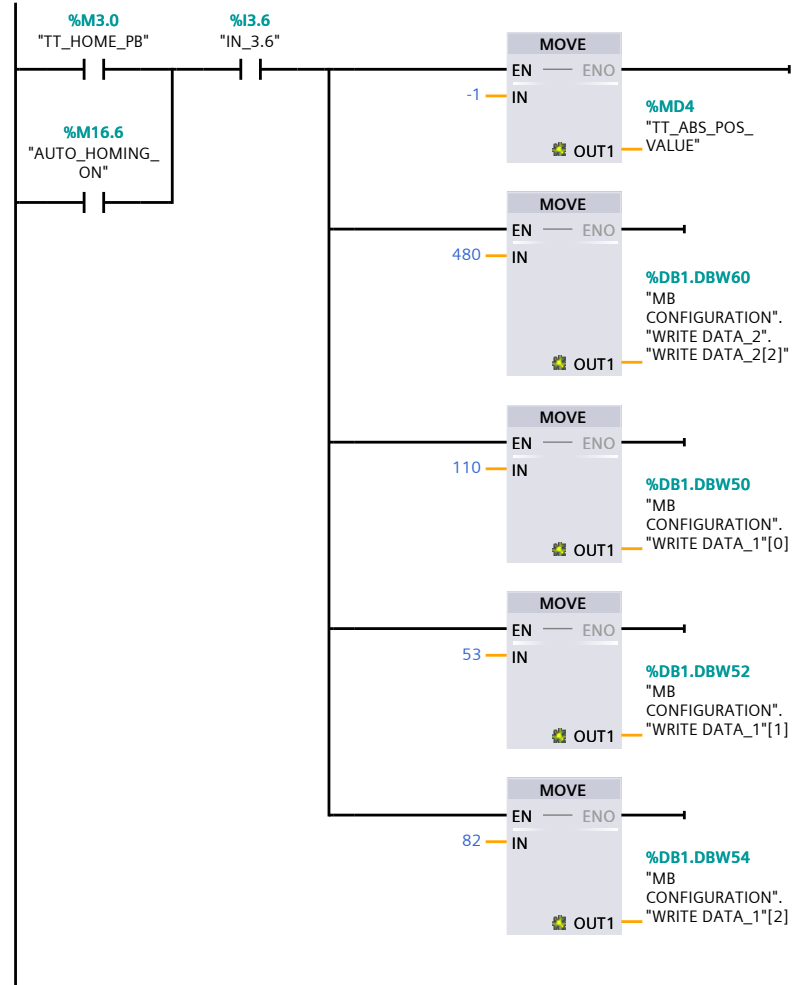
Network 27:



Network 28:



Network 29: HOMMING



Network 30:

%M49.3
"EMG_STOP_
FAULT"

%Q3.3
"OUT_3.3"

%Q3.4
"OUT_3.4"

