

Linux Software (DM75xx)

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Contents

1	Module Index	1
1.1	Modules	1
2	Data Structure Index	3
2.1	Data Structures	3
3	File Index	5
3.1	File List	5
4	Module Documentation	7
4.1	DM75xx driver header file	7
4.1.1	Detailed Description	7
4.2	DM75xx driver enumerations	8
4.2.1	Detailed Description	8
4.2.2	Enumeration Type Documentation	8
4.2.2.1	dm75xx_pci_region_access_dir	8
4.3	DM75xx driver macros	9
4.3.1	Detailed Description	9
4.3.2	Macro Definition Documentation	9
4.3.2.1	DM75xx_MAX_DMA_BUFFER_SIZE	9
4.4	DM75xx driver structures	10
4.4.1	Detailed Description	10
4.5	DM75xx driver forward declarations	11
4.5.1	Detailed Description	11
4.6	DM75xx driver functions	12
4.6.1	Detailed Description	13
4.6.2	Function Documentation	13
4.6.2.1	dm75xx_access_pci_region	13
4.6.2.2	dm75xx_allocate_irq	14
4.6.2.3	dm75xx_board_reset	14
4.6.2.4	dm75xx_dma_abort	14
4.6.2.5	dm75xx_dma_alloc_buffer	15

4.6.2.6	dm75xx_dma_initialize	15
4.6.2.7	dm75xx_dreq_init	16
4.6.2.8	dm75xx_enable_plx_dma	16
4.6.2.9	dm75xx_enable_plx_interrupts	17
4.6.2.10	dm75xx_free_dma_mappings	17
4.6.2.11	dm75xx_get_fifo_size	17
4.6.2.12	dm75xx_get_interrupt	17
4.6.2.13	dm75xx_get_pci_master_status	18
4.6.2.14	dm75xx_initialize_device_descriptor	18
4.6.2.15	dm75xx_initialize_hardware	18
4.6.2.16	dm75xx_interrupt_control	19
4.6.2.17	dm75xx_interrupt_enable	20
4.6.2.18	dm75xx_interrupt_handler	20
4.6.2.19	dm75xx_ioctl	20
4.6.2.20	dm75xx_load	21
4.6.2.21	dm75xx_modify_pci_region	21
4.6.2.22	dm75xx_open	22
4.6.2.23	dm75xx_poll	22
4.6.2.24	dm75xx_probe_devices	23
4.6.2.25	dm75xx_process_pci_regions	23
4.6.2.26	dm75xx_put_interrupt	24
4.6.2.27	dm75xx_register_char_device	24
4.6.2.28	dm75xx_release	24
4.6.2.29	dm75xx_release_resources	25
4.6.2.30	dm75xx_service_dma_function	25
4.6.2.31	dm75xx_unregister_char_device	25
4.6.2.32	dm75xx_validate_device	26
4.6.2.33	dm75xx_validate_pci_access	26
4.7	DM75xx ioctl header file	28
4.7.1	Detailed Description	28
4.8	DM75xx ioctl enumerations	29
4.8.1	Detailed Description	29
4.8.2	Enumeration Type Documentation	29
4.8.2.1	dm75xx_dma_manage_function	29
4.8.2.2	dm75xx_int_control_function	29
4.9	DM75xx ioctl structures	30
4.9.1	Detailed Description	30
4.9.2	Typedef Documentation	30
4.9.2.1	dm75xx_ioctl_region_readwrite_t	30
4.10	DM75xx ioctl macros	31

4.10.1 Detailed Description	31
4.11 DM75xx kernel compatibility header file	32
4.12 DM75xx kernel compatibility interrupt handler macros	33
4.12.1 Detailed Description	33
4.13 kernel compatibility interrupt handler macros	34
4.13.1 Detailed Description	34
4.14 DM75xx kernel compatibility device I/O memory access macros	35
4.14.1 Detailed Description	35
4.15 DM75xx user library header file	36
4.15.1 Detailed Description	36
4.16 DM75xx user library macros	37
4.16.1 Detailed Description	37
4.16.2 Macro Definition Documentation	37
4.16.2.1 DM75xx_ADC_ANALOG_DATA	37
4.16.2.2 DM75xx_ADC_MARKERS	37
4.16.2.3 DM75xx_DAC_PACK_DATA	38
4.16.2.4 DM75xx_INTERRUPT_ACTIVE	38
4.17 DM75xx user library type definitions	39
4.17.1 Detailed Description	39
4.18 DM75xx user library structures	40
4.18.1 Detailed Description	40
4.18.2 Typedef Documentation	40
4.18.2.1 DM75xx_Board_Descriptor	40
4.19 DM75xx user library functions	41
4.19.1 Detailed Description	44
4.19.2 Function Documentation	44
4.19.2.1 DM75xx_ACNT_Get_Count	44
4.19.2.2 DM75xx_ACNT_Set_Count	45
4.19.2.3 DM75xx_ADC_About_Enable	45
4.19.2.4 DM75xx_ADC_Clear	46
4.19.2.5 DM75xx_ADC_Conv_Signal	47
4.19.2.6 DM75xx_ADC_FIFO_Read	47
4.19.2.7 DM75xx_ADC_SCNT_Load	48
4.19.2.8 DM75xx_ADC_SCNT_Read	48
4.19.2.9 DM75xx_ADC_SCNT_Source	48
4.19.2.10 DM75xx_ADC_Software_Sample	49
4.19.2.11 DM75xx_ALGDIO_Get_Data	49
4.19.2.12 DM75xx_ALGDIO_Get_Direction	49
4.19.2.13 DM75xx_ALGDIO_Get_IRQ_Status	50
4.19.2.14 DM75xx_ALGDIO_Get_Mask	50

4.19.2.15 DM75xx_ALGDIO_Set_Data	50
4.19.2.16 DM75xx_ALGDIO_Set_Direction	50
4.19.2.17 DM75xx_ALGDIO_Set_Mask	51
4.19.2.18 DM75xx_Calibrate	51
4.19.2.19 DM75xx_CLK_Get_Status	51
4.19.2.20 DM75xx_DAC_Clear	52
4.19.2.21 DM75xx_DAC_FIFO_Write	52
4.19.2.22 DM75xx_DAC_Get_Update_Counter	52
4.19.2.23 DM75xx_DAC_Reset	53
4.19.2.24 DM75xx_DAC_Set_CLK_Mode	53
4.19.2.25 DM75xx_DAC_Set_Clock_Start	54
4.19.2.26 DM75xx_DAC_Set_Clock_Stop	54
4.19.2.27 DM75xx_DAC_Set_Count	54
4.19.2.28 DM75xx_DAC_Set_Frequency	55
4.19.2.29 DM75xx_DAC_Set_Mode	55
4.19.2.30 DM75xx_DAC_Set_Range	56
4.19.2.31 DM75xx_DAC_Set_Rate	56
4.19.2.32 DM75xx_DAC_Set_Update_Counter	57
4.19.2.33 DM75xx_DAC_Set_Update_Source	57
4.19.2.34 DM75xx_DAC_Setup	57
4.19.2.35 DM75xx_DAC_Soft_Update	58
4.19.2.36 DM75xx_DAC_Start	58
4.19.2.37 DM75xx_DAC_Stop	58
4.19.2.38 DM75xx_DCNT_Get_Count	59
4.19.2.39 DM75xx_DCNT_Set_Count	59
4.19.2.40 DM75xx_DIO_Clear_IRQ	60
4.19.2.41 DM75xx_DIO_Clock	60
4.19.2.42 DM75xx_DIO_Enable_IRQ	60
4.19.2.43 DM75xx_DIO_Get_Compare	61
4.19.2.44 DM75xx_DIO_Get_Port	62
4.19.2.45 DM75xx_DIO_Get_Status	62
4.19.2.46 DM75xx_DIO_IRQ_Mode	62
4.19.2.47 DM75xx_DIO_Reset	63
4.19.2.48 DM75xx_DIO_Set_Compare	63
4.19.2.49 DM75xx_DIO_Set_Direction	63
4.19.2.50 DM75xx_DIO_Set_Mask	64
4.19.2.51 DM75xx_DIO_Set_Port	64
4.19.2.52 DM75xx_DSP_CMD_Complete	64
4.19.2.53 DM75xx_DSP_CMD_Send	65
4.19.2.54 DM75xx_DSP_CMD_Status	65

4.19.2.55 DM75xx_EINT_Polarity_Select	65
4.19.2.56 DM75xx_ETRIG_Polarity_Select	66
4.19.2.57 DM75xx_FIFO_Get_Status	66
4.19.2.58 DM75xx_Get_Temp	67
4.19.2.59 DM75xx_HSDIN_Clear	68
4.19.2.60 DM75xx_HSDIN_FIFO_Read	68
4.19.2.61 DM75xx_HSDIN_Sample_Signal	68
4.19.2.62 DM75xx_HSDIN_Software_Sample	69
4.19.2.63 DM75xx_McBSP_ADC_FIFO	69
4.19.2.64 DM75xx_McBSP_DAC_FIFO	69
4.19.2.65 DM75xx_SBUS_Enable	70
4.19.2.66 DM75xx_SBUS_Set_Source	70
4.19.2.67 DM75xx_UIO_Read	71
4.19.2.68 DM75xx_UIO_Select	72
4.19.2.69 DM75xx_UIO_Write	72
4.20 DM75xx user library board control functions	73
4.20.1 Detailed Description	73
4.20.2 Function Documentation	73
4.20.2.1 DM75xx_Board_Init	73
4.20.2.2 DM75xx_Board_PCI_Master	73
4.20.2.3 DM75xx_Board_Reset	74
4.20.2.4 DM75xx_Clear_IT_Overrun	74
4.20.2.5 DM75xx_Clear_ITMask	74
4.20.2.6 DM75xx_Exit_On_Error	75
4.20.2.7 DM75xx_Interrupt_Check	75
4.20.2.8 DM75xx_Interrupt_Disable	75
4.20.2.9 DM75xx_Interrupt_Enable	75
4.21 DM75xx user library DMA functions	77
4.21.1 Detailed Description	77
4.21.2 Function Documentation	77
4.21.2.1 DM75xx_DMA_Abort	77
4.21.2.2 DM75xx_DMA_Buffer_Create	78
4.21.2.3 DM75xx_DMA_Buffer_Free	78
4.21.2.4 DM75xx_DMA_Buffer_Read	78
4.21.2.5 DM75xx_DMA_Buffer_Write	79
4.21.2.6 DM75xx_DMA_Enable	79
4.21.2.7 DM75xx_DMA_Init_Arb	80
4.21.2.8 DM75xx_DMA_Initialize	81
4.21.2.9 DM75xx_DMA_Request_Source	81
4.21.2.10 DM75xx_DMA_Start	82

4.22	DM75xx user library general functions	83
4.22.1	Detailed Description	83
4.22.2	Function Documentation	83
4.22.2.1	DM75xx_Board_Close	83
4.22.2.2	DM75xx_Board_Open	84
4.22.2.3	DM75xx_Board_Type	84
4.22.2.4	DM75xx_FIFO_Size	84
4.22.2.5	DM75xx_InstallISR	85
4.22.2.6	DM75xx_RemoveISR	85
4.22.2.7	DM75xx_WaitForInterrupt	86
4.23	DM75xx user library user timer/counter control	88
4.23.1	Detailed Description	88
4.23.2	Function Documentation	88
4.23.2.1	DM75xx_UTC_Get_Count	88
4.23.2.2	DM75xx_UTC_Get_Mode	89
4.23.2.3	DM75xx_UTC_Get_Status	90
4.23.2.4	DM75xx_UTC_Set_Clock_Source	90
4.23.2.5	DM75xx_UTC_Set_Divisor	90
4.23.2.6	DM75xx_UTC_Set_Gate	91
4.23.2.7	DM75xx_UTC_Set_Mode	91
4.23.2.8	DM75xx_UTC_Setup	91
4.24	DM75xx user library burst clock control	93
4.24.1	Detailed Description	93
4.24.2	Function Documentation	93
4.24.2.1	DM75xx_BCLK_Get_Count	93
4.24.2.2	DM75xx_BCLK_Set_Count	93
4.24.2.3	DM75xx_BCLK_Set_Frequency	94
4.24.2.4	DM75xx_BCLK_Set_Rate	94
4.24.2.5	DM75xx_BCLK_Set_Start	94
4.24.2.6	DM75xx_BCLK_Setup	95
4.25	DM75xx user library pacer clock control	97
4.25.1	Detailed Description	97
4.25.2	Function Documentation	97
4.25.2.1	DM75xx_PCLK_Read	97
4.25.2.2	DM75xx_PCLK_Set_Count	98
4.25.2.3	DM75xx_PCLK_Set_Frequency	98
4.25.2.4	DM75xx_PCLK_Set_Rate	98
4.25.2.5	DM75xx_PCLK_Set_Source	99
4.25.2.6	DM75xx_PCLK_Set_Start	100
4.25.2.7	DM75xx_PCLK_Set_Stop	100

4.25.2.8	DM75xx_PCLK_Set_Trigger_Mode	100
4.25.2.9	DM75xx_PCLK_Setup	101
4.25.2.10	DM75xx_PCLK_Start	101
4.25.2.11	DM75xx_PCLK_Stop	101
4.26	DM75xx user library channel gain table	103
4.26.1	Detailed Description	103
4.26.2	Function Documentation	103
4.26.2.1	DM75xx_CGT_Clear	103
4.26.2.2	DM75xx_CGT_Create_Entry	103
4.26.2.3	DM75xx_CGT_Enable	104
4.26.2.4	DM75xx_CGT_Latch	104
4.26.2.5	DM75xx_CGT_Pause	104
4.26.2.6	DM75xx_CGT_Reset	105
4.26.2.7	DM75xx_CGT_Write	105
4.26.2.8	DM75xx_DT_Enable	106
4.26.2.9	DM75xx_DT_Write_Entry	106
4.27	DM75xx type definition header file	107
4.27.1	Detailed Description	107
4.28	DM75xx type enumerations	108
4.28.1	Detailed Description	108
4.29	DM75xx type PCI enumerations	109
4.29.1	Detailed Description	109
4.29.2	Enumeration Type Documentation	109
4.29.2.1	_dm75xx_board	109
4.29.2.2	dm75xx_pci_region_access_size	109
4.29.2.3	dm75xx_pci_region_num	110
4.30	DM75xx type DSP enumerations	111
4.30.1	Detailed Description	111
4.30.2	Enumeration Type Documentation	111
4.30.2.1	_dm75xx_dsp_command	111
4.31	DM75xx type DMA	112
4.31.1	Detailed Description	112
4.31.2	Enumeration Type Documentation	112
4.31.2.1	_dm75xx_dma_channel	112
4.31.2.2	_dm75xx_dma_flag	113
4.31.2.3	_dm75xx_dma_request	113
4.31.2.4	_dm75xx_dma_reset	113
4.31.2.5	_dm75xx_dma_source	113
4.32	DM75xx type Interrupt	114
4.32.1	Detailed Description	114

4.32.2	Enumeration Type Documentation	114
4.32.2.1	<code>_dm75xx_int_source</code>	114
4.33	DM75xx type Analog DIO	116
4.33.1	Detailed Description	116
4.33.2	Enumeration Type Documentation	116
4.33.2.1	<code>_dm75xx_algdio_direction</code>	116
4.33.2.2	<code>_dm75xx_algdio_mask</code>	116
4.33.2.3	<code>_dm75xx_algdio_pin</code>	117
4.34	DM75xx type User Output	118
4.34.1	Detailed Description	118
4.34.2	Enumeration Type Documentation	118
4.34.2.1	<code>_dm75xx_uio_channel</code>	118
4.34.2.2	<code>_dm75xx_uio_source</code>	118
4.35	DM75xx type Digital Input/Output	119
4.35.1	Detailed Description	119
4.35.2	Enumeration Type Documentation	119
4.35.2.1	<code>_dm75xx_dio_clk</code>	119
4.35.2.2	<code>_dm75xx_dio_mode</code>	119
4.35.2.3	<code>_dm75xx_dio_port</code>	120
4.36	DM75xx type External Trigger/Interrupt	121
4.36.1	Detailed Description	121
4.36.2	Enumeration Type Documentation	121
4.36.2.1	<code>_dm75xx_ext_polarity</code>	121
4.37	DM75xx type SyncBus enumerations	122
4.37.1	Detailed Description	122
4.37.2	Enumeration Type Documentation	122
4.37.2.1	<code>_dm75xx_sbus</code>	122
4.37.2.2	<code>_dm75xx_sbus_src</code>	122
4.38	DM75xx type HighSpeed Digital enumerations	124
4.38.1	Detailed Description	124
4.38.2	Enumeration Type Documentation	124
4.38.2.1	<code>_dm75xx_hsdin_signal</code>	124
4.39	DM75xx type Digital to Analog enumerations	125
4.39.1	Detailed Description	126
4.39.2	Typedef Documentation	126
4.39.2.1	<code>dm75xx_dac_channel_t</code>	126
4.39.3	Enumeration Type Documentation	126
4.39.3.1	<code>_dm75xx_dac_channel</code>	126
4.39.3.2	<code>_dm75xx_dac_clk_mode</code>	126
4.39.3.3	<code>_dm75xx_dac_clk_start</code>	126

4.39.3.4	_dm75xx_dac_clk_stop	127
4.39.3.5	_dm75xx_dac_freq	127
4.39.3.6	_dm75xx_dac_mode	127
4.39.3.7	_dm75xx_dac_range	127
4.39.3.8	_dm75xx_dac_update_src	128
4.40	DM75xx type Analog to Digital enumerations	129
4.40.1	Detailed Description	129
4.40.2	Enumeration Type Documentation	129
4.40.2.1	_dm75xx_adc_conv_signal	129
4.40.2.2	_dm75xx_adc_scnt_src	129
4.41	DM75xx type Burst Clock enumerations	131
4.41.1	Detailed Description	131
4.41.2	Enumeration Type Documentation	131
4.41.2.1	_dm75xx_bclk_freq	131
4.41.2.2	_dm75xx_bclk_start	131
4.42	DM75xx type Pacer Clock enumerations	132
4.42.1	Detailed Description	132
4.42.2	Enumeration Type Documentation	132
4.42.2.1	_dm75xx_pclk_freq	132
4.42.2.2	_dm75xx_pclk_mode	133
4.42.2.3	_dm75xx_pclk_select	133
4.42.2.4	_dm75xx_pclk_start	133
4.42.2.5	_dm75xx_pclk_stop	134
4.43	DM75xx type timer/counter enumerations	135
4.43.1	Detailed Description	135
4.43.2	Enumeration Type Documentation	135
4.43.2.1	_dm75xx_utc_clk	135
4.43.2.2	_dm75xx_utc_gate	136
4.43.2.3	_dm75xx_utc_mode	136
4.43.2.4	_dm75xx_utc_timer	136
4.44	DM75xx type definition structures	137
4.44.1	Detailed Description	137
4.44.2	Enumeration Type Documentation	137
4.44.2.1	_dm75xx_fifo_status	137
5	Data Structure Documentation	139
5.1	_dm75xx_cgt_entry Struct Reference	139
5.1.1	Detailed Description	139
5.1.2	Field Documentation	139
5.1.2.1	channel	139

5.1.2.2	dac1	139
5.1.2.3	dac2	140
5.1.2.4	gain	140
5.1.2.5	ground	140
5.1.2.6	nrse	140
5.1.2.7	pause	140
5.1.2.8	range	140
5.1.2.9	reserved	140
5.1.2.10	skip	140
5.2	<code>_dm75xx_int_status</code> Struct Reference	141
5.2.1	Detailed Description	141
5.2.2	Field Documentation	141
5.2.2.1	<code>int_missed</code>	141
5.2.2.2	<code>int_remaining</code>	141
5.2.2.3	<code>status</code>	141
5.3	<code>DM75xx_Board_Descriptor</code> Struct Reference	141
5.3.1	Detailed Description	142
5.3.2	Field Documentation	142
5.3.2.1	<code>file_descriptor</code>	142
5.3.2.2	<code>isr</code>	142
5.3.2.3	<code>k_buf</code>	142
5.3.2.4	<code>k_buf_siz</code>	142
5.3.2.5	<code>pid</code>	142
5.3.2.6	<code>thread_status</code>	142
5.3.2.7	<code>u_buf</code>	143
5.3.2.8	<code>u_buf_siz</code>	143
5.4	<code>dm75xx_device_descriptor</code> Struct Reference	143
5.4.1	Detailed Description	143
5.4.2	Field Documentation	143
5.4.2.1	<code>board_type</code>	143
5.4.2.2	<code>dma_buffers</code>	144
5.4.2.3	<code>dma_chain</code>	144
5.4.2.4	<code>dma_flag</code>	144
5.4.2.5	<code>dma_size</code>	144
5.4.2.6	<code>fifo_size</code>	144
5.4.2.7	<code>int_control</code>	144
5.4.2.8	<code>int_count</code>	144
5.4.2.9	<code>int_queue_in</code>	144
5.4.2.10	<code>int_queue_missed</code>	144
5.4.2.11	<code>int_queue_out</code>	145

5.4.2.12	int_status	145
5.4.2.13	int_wait_queue	145
5.4.2.14	irq_number	145
5.4.2.15	lock	145
5.4.2.16	name	145
5.4.2.17	pci	145
5.4.2.18	reference_count	145
5.4.2.19	remove_isr_flag	145
5.5	dm75xx_dma_chain_descriptor Struct Reference	146
5.5.1	Detailed Description	146
5.5.2	Field Documentation	146
5.5.2.1	descriptor_pointer	146
5.5.2.2	local_address	146
5.5.2.3	pci_address	146
5.5.2.4	transfer_size	146
5.6	dm75xx_dma_descriptor Struct Reference	146
5.6.1	Detailed Description	147
5.6.2	Field Documentation	147
5.6.2.1	bus_address	147
5.6.2.2	size	147
5.6.2.3	virtual_address	147
5.7	dm75xx_ioctl_argument Union Reference	147
5.7.1	Detailed Description	147
5.7.2	Field Documentation	148
5.7.2.1	dma_function	148
5.7.2.2	int_control	148
5.7.2.3	modify	148
5.7.2.4	readwrite	148
5.8	dm75xx_ioctl_dma_function Struct Reference	148
5.8.1	Detailed Description	148
5.8.2	Field Documentation	149
5.8.2.1	arb	149
5.8.2.2	channel	149
5.8.2.3	function	149
5.8.2.4	pci_address	149
5.8.2.5	request	149
5.8.2.6	size	149
5.8.2.7	source	149
5.9	dm75xx_ioctl_int_control Struct Reference	149
5.9.1	Detailed Description	150

5.9.2	Field Documentation	150
5.9.2.1	function	150
5.9.2.2	source	150
5.10	dm75xx_ioctl_region_modify Struct Reference	150
5.10.1	Detailed Description	150
5.10.2	Field Documentation	151
5.10.2.1	access	151
5.10.2.2	mask	151
5.10.2.3	mask16	151
5.10.2.4	mask32	151
5.10.2.5	mask8	151
5.11	dm75xx_ioctl_region_readwrite Struct Reference	151
5.11.1	Detailed Description	151
5.11.2	Field Documentation	152
5.11.2.1	access	152
5.12	dm75xx_pci_access_request Struct Reference	152
5.12.1	Detailed Description	152
5.12.2	Field Documentation	152
5.12.2.1	data	152
5.12.2.2	data16	152
5.12.2.3	data32	152
5.12.2.4	data8	153
5.12.2.5	offset	153
5.12.2.6	region	153
5.12.2.7	size	153
5.13	dm75xx_pci_region Struct Reference	153
5.13.1	Detailed Description	153
5.13.2	Field Documentation	153
5.13.2.1	allocated	153
5.13.2.2	io_addr	154
5.13.2.3	length	154
5.13.2.4	phys_addr	154
5.13.2.5	virt_addr	154
6	File Documentation	155
6.1	examples/about_intrpt.c File Reference	155
6.1.1	Detailed Description	156
6.1.2	Macro Definition Documentation	156
6.1.2.1	ADC_RATE	156
6.1.2.2	UTC2_RATE	156

6.1.3	Variable Documentation	156
6.1.3.1	interrupts	156
6.1.3.2	program_name	156
6.2	examples/adc_abrst.c File Reference	157
6.2.1	Detailed Description	157
6.2.2	Macro Definition Documentation	158
6.2.2.1	BURST_RATE	158
6.2.2.2	NUM_CHANNELS	158
6.2.2.3	PACER_RATE	158
6.2.2.4	UTC2_RATE	158
6.2.3	Variable Documentation	158
6.2.3.1	program_name	158
6.3	examples/adc_dac_simul.c File Reference	158
6.3.1	Detailed Description	159
6.3.2	Macro Definition Documentation	160
6.3.2.1	ADC_FIFO	160
6.3.2.2	ADC_RATE	160
6.3.2.3	DAC_FIFO	160
6.3.2.4	DAC_RATE	160
6.3.2.5	DAT_FILE	160
6.3.3	Variable Documentation	160
6.3.3.1	adc_ints	161
6.3.3.2	dac_ints	161
6.3.3.3	exit_program	161
6.3.3.4	program_name	161
6.4	examples/adc_dma.c File Reference	161
6.4.1	Detailed Description	162
6.4.2	Macro Definition Documentation	162
6.4.2.1	ADC_RATE	162
6.4.2.2	FIFO	162
6.4.2.3	NUM_DATA	163
6.4.2.4	NUM_INTS	163
6.4.3	Function Documentation	163
6.4.3.1	setup_ctrlc_handler	163
6.4.4	Variable Documentation	163
6.4.4.1	board	163
6.4.4.2	interrupts	163
6.4.4.3	program_name	163
6.5	examples/adc_dma_continuous.c File Reference	164
6.5.1	Detailed Description	164

6.5.2	Macro Definition Documentation	165
6.5.2.1	ADC_RATE	165
6.5.2.2	DAT_FILE	165
6.5.2.3	FIFO	165
6.5.2.4	NUM_DATA	165
6.5.2.5	NUM_INTS	165
6.5.3	Variable Documentation	165
6.5.3.1	exit_program	165
6.5.3.2	interrupts	166
6.5.3.3	program_name	166
6.6	examples/adc_hd_simul.c File Reference	166
6.6.1	Detailed Description	167
6.6.2	Macro Definition Documentation	167
6.6.2.1	ADC_FIFO	167
6.6.2.2	ADC_NUM_DATA	167
6.6.2.3	ADC_NUM_INTS	167
6.6.2.4	ADC_RATE	168
6.6.2.5	HD_FIFO	168
6.6.2.6	HD_NUM_DATA	168
6.6.2.7	HD_NUM_INTS	168
6.6.2.8	HSDIN_RATE	168
6.6.3	Variable Documentation	168
6.6.3.1	board	168
6.6.3.2	dma_0_ints	168
6.6.3.3	dma_1_ints	168
6.6.3.4	program_name	169
6.7	examples/adc_multi.c File Reference	169
6.7.1	Detailed Description	169
6.7.2	Macro Definition Documentation	170
6.7.2.1	BURST_RATE	170
6.7.2.2	NUM_CHANNELS	170
6.7.2.3	PACER_RATE	170
6.7.3	Variable Documentation	170
6.7.3.1	program_name	170
6.8	examples/adc_single.c File Reference	170
6.8.1	Detailed Description	171
6.8.2	Macro Definition Documentation	172
6.8.2.1	ADC_RATE	172
6.8.3	Variable Documentation	172
6.8.3.1	program_name	172

6.9	examples/adc_soft_trig.c File Reference	172
6.9.1	Detailed Description	172
6.9.2	Variable Documentation	173
6.9.2.1	exit_program	173
6.9.2.2	program_name	173
6.10	examples/adc_trig_ext.c File Reference	173
6.10.1	Detailed Description	174
6.10.2	Macro Definition Documentation	175
6.10.2.1	ADC_RATE	175
6.10.2.2	FIFO	175
6.10.2.3	NUM_DATA	175
6.10.2.4	NUM_INTS	175
6.10.3	Variable Documentation	175
6.10.3.1	board	175
6.10.3.2	interrupts	175
6.10.3.3	program_name	175
6.11	examples/adio_event.c File Reference	176
6.11.1	Detailed Description	176
6.11.2	Variable Documentation	177
6.11.2.1	board	177
6.11.2.2	interrupts	177
6.11.2.3	program_name	177
6.12	examples/adio_match.c File Reference	177
6.12.1	Detailed Description	178
6.12.2	Variable Documentation	178
6.12.2.1	board	178
6.12.2.2	interrupts	178
6.12.2.3	program_name	178
6.13	examples/analog_dio.c File Reference	178
6.13.1	Detailed Description	179
6.13.2	Variable Documentation	179
6.13.2.1	interrupts	179
6.13.2.2	program_name	180
6.14	examples/calibrate.c File Reference	180
6.14.1	Detailed Description	180
6.14.2	Variable Documentation	181
6.14.2.1	program_name	181
6.15	examples/cgt_reset_intrpt.c File Reference	181
6.15.1	Detailed Description	182
6.15.2	Macro Definition Documentation	182

6.15.2.1	ADC_RATE	182
6.15.2.2	NUM_CHANNELS	182
6.15.3	Variable Documentation	182
6.15.3.1	interrupts	182
6.15.3.2	program_name	182
6.16	examples/dac.c File Reference	183
6.16.1	Detailed Description	183
6.16.2	Macro Definition Documentation	184
6.16.2.1	DAC_RATE	184
6.16.3	Variable Documentation	184
6.16.3.1	program_name	184
6.17	examples/dac_dma.c File Reference	184
6.17.1	Detailed Description	185
6.17.2	Macro Definition Documentation	185
6.17.2.1	DAC_RATE	185
6.17.2.2	FIFO	185
6.17.3	Variable Documentation	185
6.17.3.1	exit_program	185
6.17.3.2	interrupts	186
6.17.3.3	program_name	186
6.18	examples/delay_intrpt.c File Reference	186
6.18.1	Detailed Description	187
6.18.2	Macro Definition Documentation	187
6.18.2.1	ADC_RATE	187
6.18.3	Variable Documentation	187
6.18.3.1	interrupts	187
6.18.3.2	program_name	187
6.19	examples/dma_pci_arb.c File Reference	187
6.19.1	Detailed Description	188
6.19.2	Macro Definition Documentation	189
6.19.2.1	ADC_RATE	189
6.19.2.2	FIFO	189
6.19.2.3	NUM_DATA	189
6.19.2.4	NUM_INTS	189
6.19.3	Variable Documentation	189
6.19.3.1	board	189
6.19.3.2	interrupts	189
6.19.3.3	program_name	189
6.20	examples/etrig_intrpt.c File Reference	190
6.20.1	Detailed Description	190

6.20.2	Macro Definition Documentation	191
6.20.2.1	FALLING_EDGE	191
6.20.2.2	RISING_EDGE	191
6.20.3	Variable Documentation	191
6.20.3.1	board	191
6.20.3.2	edge_val	191
6.20.3.3	interrupts	191
6.20.3.4	program_name	191
6.21	examples/hd.c File Reference	191
6.21.1	Detailed Description	192
6.21.2	Macro Definition Documentation	192
6.21.2.1	TIMER_RATE	192
6.21.3	Variable Documentation	193
6.21.3.1	program_name	193
6.22	examples/hd_dma.c File Reference	193
6.22.1	Detailed Description	194
6.22.2	Macro Definition Documentation	194
6.22.2.1	FIFO	194
6.22.2.2	NUM_DATA	194
6.22.2.3	NUM_INTS	194
6.22.2.4	RATE	194
6.22.3	Variable Documentation	194
6.22.3.1	board	194
6.22.3.2	interrupts	195
6.22.3.3	program_name	195
6.23	examples/library_test.c File Reference	195
6.23.1	Detailed Description	196
6.23.2	Variable Documentation	196
6.23.2.1	program_name	196
6.24	examples/temperature.c File Reference	196
6.24.1	Detailed Description	197
6.24.2	Variable Documentation	197
6.24.2.1	program_name	197
6.25	examples/timer.c File Reference	197
6.25.1	Detailed Description	198
6.25.2	Macro Definition Documentation	198
6.25.2.1	TIMER_RATE	198
6.25.3	Variable Documentation	198
6.25.3.1	exit_program	198
6.25.3.2	program_name	199

6.26	examples/timer_intrpt.c File Reference	199
6.26.1	Detailed Description	200
6.26.2	Macro Definition Documentation	200
6.26.2.1	UTC0	200
6.26.2.2	UTC1	200
6.26.3	Variable Documentation	200
6.26.3.1	board	200
6.26.3.2	program_name	200
6.26.3.3	utc1_int	201
6.26.3.4	utc1_int_inverted	201
6.27	include/dm75xx_driver.h File Reference	201
6.27.1	Detailed Description	204
6.28	include/dm75xx_ioctl.h File Reference	204
6.28.1	Detailed Description	206
6.29	include/dm75xx_kernel.h File Reference	206
6.29.1	Detailed Description	207
6.30	include/dm75xx_library.h File Reference	207
6.30.1	Detailed Description	214
6.31	include/dm75xx_registers.h File Reference	215
6.31.1	Detailed Description	222
6.32	include/dm75xx_types.h File Reference	222
6.32.1	Detailed Description	227

Chapter 1

Module Index

1.1 Modules

Here is a list of all modules:

DM75xx driver header file	7
DM75xx driver enumerations	8
DM75xx driver macros	9
DM75xx driver structures	10
DM75xx driver forward declarations	11
DM75xx driver functions	12
DM75xx ioctl header file	28
DM75xx ioctl enumerations	29
DM75xx ioctl structures	30
DM75xx ioctl macros	31
DM75xx kernel compatibility header file	32
DM75xx kernel compatibility interrupt handler macros	33
kernel compatibility interrupt handler macros	34
DM75xx kernel compatibility device I/O memory access macros	35
DM75xx user library header file	36
DM75xx user library macros	37
DM75xx user library type definitions	39
DM75xx user library structures	40
DM75xx user library functions	41
DM75xx user library board control functions	73
DM75xx user library DMA functions	77
DM75xx user library general functions	83
DM75xx user library user timer/counter control	88
DM75xx user library burst clock control	93
DM75xx user library pacer clock control	97
DM75xx user library channel gain table	103
DM75xx type definition header file	107
DM75xx type enumerations	108
DM75xx type PCI enumerations	109
DM75xx type DSP enumerations	111
DM75xx type DMA	112
DM75xx type Interrupt	114
DM75xx type Analog DIO	116
DM75xx type User Output	118
DM75xx type Digital Input/Output	119
DM75xx type External Trigger/Interrupt	121
DM75xx type SyncBus enumerations	122

DM75xx type HighSpeed Digital enumerations	124
DM75xx type Digital to Analog enumerations	125
DM75xx type Analog to Digital enumerations	129
DM75xx type Burst Clock enumerations	131
DM75xx type Pacer Clock enumerations	132
DM75xx type timer/counter enumerations	135
DM75xx type definition structures	137

Chapter 2

Data Structure Index

2.1 Data Structures

Here are the data structures with brief descriptions:

_dm75xx_cgt_entry	Channel gain table entry	139
_dm75xx_int_status	Interrupts status	141
DM75xx_Board_Descriptor	DM75xx board descriptor. This structure holds information about a device needed by the library	141
dm75xx_device_descriptor	DM75xx device descriptor. This structure holds information about a device needed by the kernel	143
dm75xx_dma_chain_descriptor	Dm75xx DMA chaining descriptor	146
dm75xx_dma_descriptor	DM75xx DMA buffer descriptor. This structure holds allocation information for a single DMA buffer	146
dm75xx_ioctl_argument	ioctl() request structure encapsulating all possible requests. This is what gets passed into the kernel from user space on the ioctl() call	147
dm75xx_ioctl_dma_function	ioctl() request structure for performing a DMA function	148
dm75xx_ioctl_int_control	ioctl() request structure for interrupt control	149
dm75xx_ioctl_region_modify	ioctl() request structure for PCI region read/modify/write	150
dm75xx_ioctl_region_readwrite	ioctl() request structure for read from or write to PCI region	151
dm75xx_pci_access_request	PCI region access request descriptor. This structure holds information about a request to read data from or write data to one of a device's PCI regions	152
dm75xx_pci_region	DM75xx PCI region descriptor. This structure holds information about one of a device's PCI memory regions	153

Chapter 3

File Index

3.1 File List

Here is a list of all documented files with brief descriptions:

examples/ about_intrpt.c	
This example program demonstrates the use of the About Counter Interrupt	155
examples/ adc_abrst.c	
This example program demonstrates the use of the About Counter	157
examples/ adc_dac_simul.c	
Demonstrates simultaneous Analog and Digital sampling	158
examples/ adc_dma.c	
Demonstrates the use of Analog to Digital sampling with DMA	161
examples/ adc_dma_continuous.c	
Demonstrates the use of Digital to Analog sampling via DMA	164
examples/ adc_hd_simul.c	
Demonstrates Analog to Digital and High Speed Digital simultaneously	166
examples/ adc_multi.c	
Demonstrates the use of Analog to Digital Burst sampling	169
examples/ adc_single.c	
Demonstrates the use of Analog to Digital Conversion	170
examples/ adc_soft_trig.c	
Demonstrates the use of the Software Trigger	172
examples/ adc_trig_ext.c	
Demonstrates the use of Analog to Digital sampling via external trigger	173
examples/ adio_event.c	
Demonstrates the use of the Digital I/O Event Mode to generate interrupts	176
examples/ adio_match.c	
Demonstrates the use of the Digital I/O Match Mode to generate interrupts	177
examples/ analog_dio.c	
Demonstrates the use of Analog DIO Connector on the SDM7540	178
examples/ calibrate.c	
Demonstrates auto-calibration of SDM7540/8540	180
examples/ cgt_reset_intrpt.c	
Demonstrates the use of the Channge Gain Reset Interrupt	181
examples/ dac.c	
Demonstrates the use of Digital to Analog conversion	183
examples/ dac_dma.c	
Demonstrates the use of Digital to Analog conversion with DMA	184
examples/ delay_intrpt.c	
This example program demonstrates the use of the Delay Counter Interrupt	186
examples/ dma_pci_arb.c	
Demonstrates the ability to DMA to an arbitrary PCI address	187

examples/ etrig_intrpt.c	
Demonstrates the use of the External Trigger rising/falling interrupts	190
examples/ hd.c	
Demonstrates the use of high speed digital data acquisition	191
examples/ hd_dma.c	
Demonstrates the use of High Speed Digital acquisition via DMA	193
examples/ library_test.c	
Program which tests the basic functionality of the library	195
examples/ temperature.c	
Demonstrates the use of the SDM7540's on board temp sensor	196
examples/ timer.c	
Demonstrates the use of the User Timer/Counters for keeping time	197
examples/ timer_intrpt.c	
Demonstrates the use of the User Timer/Counter Out Interrupts	199
include/ dm75xx_driver.h	
Definitions for the DM75xx driver	201
include/ dm75xx_ioctl.h	
Low level ioctl() request descriptor structure and request code definitions	204
include/ dm75xx_kernel.h	
Kernel compatibility issues between 2.6.0 and 3.x kernels	206
include/ dm75xx_library.h	
DM75xx user library definitions	207
include/ dm75xx_registers.h	
Register definitions for DM75xx devices	215
include/ dm75xx_types.h	
Type definitions used both in kernel and user space	222
include/ dm75xx_version.h	??

Chapter 4

Module Documentation

4.1 DM75xx driver header file

Modules

- [DM75xx driver enumerations](#)
- [DM75xx driver macros](#)
- [DM75xx driver structures](#)
- [DM75xx driver forward declarations](#)
- [DM75xx driver functions](#)

4.1.1 Detailed Description

4.2 DM75xx driver enumerations

Typedefs

- typedef enum
[dm75xx_pci_region_access_dir](#) [dm75xx_pci_region_access_dir_t](#)
Standard PCI region access direction type.

Enumerations

- enum [dm75xx_pci_region_access_dir](#) { [DM75xx_PCI_REGION_ACCESS_READ](#) = 0, [DM75xx_PCI_REGION_ACCESS_WRITE](#) }
Direction of access to standard PCI region.

4.2.1 Detailed Description

4.2.2 Enumeration Type Documentation

4.2.2.1 enum [dm75xx_pci_region_access_dir](#)

Direction of access to standard PCI region.

Enumerator

[DM75xx_PCI_REGION_ACCESS_READ](#) Read from the region
[DM75xx_PCI_REGION_ACCESS_WRITE](#) Write to the region

Definition at line 54 of file [dm75xx_driver.h](#).

4.3 DM75xx driver macros

Macros

- `#define DM75xx_DEVICE_NAME_LENGTH 22`
Maximum number of characters in device's name.
- `#define DM7520_PCI_DEVICE_ID 0x7520`
DM7520 PCI device ID.
- `#define DM7540_PCI_DEVICE_ID 0x7540`
DM7540 PCI device ID.
- `#define RTD_PCI_VENDOR_ID 0x1435`
RTD Embedded Technologies PCI vendor ID.
- `#define DM75xx_PCI_REGIONS PCI_ROM_RESOURCE`
Number of standard PCI regions.
- `#define DM75xx_DMA_CHANNELS 2`
Number of FIFO channels per device.
- `#define DM75xx_MAX_DMA_BUFFER_SIZE 0x20000`
Maximum size in bytes of any DMA buffer.
- `#define DM75xx_INT_QUEUE_SIZE 0x10`
Maximum size in entries of the interrupt status queue.

4.3.1 Detailed Description

DM75xx_Driver_Enumerations

4.3.2 Macro Definition Documentation

4.3.2.1 `#define DM75xx_MAX_DMA_BUFFER_SIZE 0x20000`

Maximum size in bytes of any DMA buffer.

Note

Be aware that the probability of DMA buffer allocation failure increases as the buffer size increases. If this default value does not suit your needs, you can change it and then recompile the driver. The max buffer size is set to 128k to remain architecture independent. it is more than likely that much more than this can be allocated on an x86 system at one time.

Definition at line 149 of file dm75xx_driver.h.

4.4 DM75xx driver structures

Data Structures

- struct [dm75xx_pci_region](#)
DM75xx PCI region descriptor. This structure holds information about one of a device's PCI memory regions.
- struct [dm75xx_dma_chain_descriptor](#)
Dm75xx DMA chaining descriptor.
- struct [dm75xx_dma_descriptor](#)
DM75xx DMA buffer descriptor. This structure holds allocation information for a single DMA buffer.
- struct [dm75xx_device_descriptor](#)
DM75xx device descriptor. This structure holds information about a device needed by the kernel.

Typedefs

- typedef struct [dm75xx_pci_region](#) [dm75xx_pci_region_t](#)
DM75xx PCI region descriptor type.
- typedef struct [dm75xx_dma_chain_descriptor](#) [dm75xx_dma_chain_descriptor_t](#)
DM75xx DMA Chaining descriptor type.
- typedef struct [dm75xx_dma_descriptor](#) [dm75xx_dma_descriptor_t](#)
DM75xx DMA buffer descriptor type.
- typedef struct [dm75xx_device_descriptor](#) [dm75xx_device_descriptor_t](#)
DM75xx device descriptor type.

4.4.1 Detailed Description

DM75xx_Driver_Macros

4.5 DM75xx driver forward declarations

Variables

- static struct file_operations [dm75xx_file_ops](#)
File operations supported by driver.

4.5.1 Detailed Description

DM75xx_Driver_Structures

4.6 DM75xx driver functions

Functions

- static void [dm75xx_access_pci_region](#) (const [dm75xx_device_descriptor_t](#) *dm75xx, [dm75xx_pci_access_request_t](#) *pci_request, [dm75xx_pci_region_access_dir_t](#) direction)
Read from or write to one of the standard PCI regions.
- static int [dm75xx_allocate_irq](#) ([dm75xx_device_descriptor_t](#) *dm75xx, const struct pci_dev *pci_device)
Allocate an interrupt line for a DM75xx device.
- static void [dm75xx_enable_plx_interrupts](#) (const [dm75xx_device_descriptor_t](#) *dm75xx, uint8_t enable)
Enable PLX interrupts for the specified DM75xx Device.
- static void [dm75xx_enable_plx_dma](#) (const [dm75xx_device_descriptor_t](#) *dm75xx, [dm75xx_dma_channel_t](#) channel)
Configure PLX Mode register for the specified DMA Channel.
- static void [dm75xx_get_pci_master_status](#) ([dm75xx_device_descriptor_t](#) *dm75xx, uint8_t *pci_master)
Determine whether or not a device is PCI master capable.
- static void [dm75xx_initialize_device_descriptor](#) ([dm75xx_device_descriptor_t](#) *dm75xx)
Initialize the device descriptor for the specified DM75xx device.
- static void [dm75xx_initialize_hardware](#) (const [dm75xx_device_descriptor_t](#) *dm75xx)
Initialize the specified DM75xx device.
- [INTERRUPT_HANDLER_TYPE dm75xx_interrupt_handler](#) (int irq_number, void *device_id)
DM75xx device interrupt handler.
- static long [dm75xx_ioctl](#) (struct file *file, unsigned int request_code, unsigned long ioctl_param)
Process ioctl(2) system calls directed toward a DM75xx device file.
- static void [dm75xx_board_reset](#) ([dm75xx_device_descriptor_t](#) *dm75xx)
Performs a reset of the board and device descriptor.
- static void [dm75xx_interrupt_enable](#) ([dm75xx_device_descriptor_t](#) *dm75xx, [dm75xx_int_source_t](#) source, uint8_t enable)
Performs the actual enable/disable of the interrupt sources.
- static int [dm75xx_interrupt_control](#) ([dm75xx_device_descriptor_t](#) *dm75xx, unsigned long ioctl_param)
Control the interrupts on the boards. This includes enabling, disabling and checking the enable/disable status of the interrupts.
- static int [dm75xx_get_interrupt](#) ([dm75xx_device_descriptor_t](#) *dm75xx, unsigned long ioctl_param)
Returns the top entry from the interrupt status queue.
- static void [dm75xx_put_interrupt](#) ([dm75xx_device_descriptor_t](#) *dm75xx, uint32_t interrupt)
Adds an interrupt to the interrupt status queue.
- static int [dm75xx_service_dma_function](#) ([dm75xx_device_descriptor_t](#) *dm75xx, unsigned long ioctl_param)
Process user space DMA function requests.
- static int [dm75xx_dma_abort](#) ([dm75xx_device_descriptor_t](#) *dm75xx, [dm75xx_dma_channel_t](#) channel)
Aborts any DMA transfers on the given channel.
- static int [dm75xx_dma_alloc_buffer](#) ([dm75xx_device_descriptor_t](#) *dm75xx, [dm75xx_dma_channel_t](#) channel)
Allocates a coherent and consistent buffer for our DMA operations.
- static int [dm75xx_dreq_init](#) ([dm75xx_device_descriptor_t](#) *dm75xx, [dm75xx_dma_channel_t](#) channel, [dm75xx_dma_request_t](#) dreq)
Performs some DMA initialization work based on the DREQ source.
- static int [dm75xx_dma_initialize](#) ([dm75xx_device_descriptor_t](#) *dm75xx, [dm75xx_ioctl_argument_t](#) *ioctl_argument)
Initialize DMA for the specified channel and source for the DM75xx device.
- static void [dm75xx_free_dma_mappings](#) ([dm75xx_device_descriptor_t](#) *dm75xx, [dm75xx_dma_channel_t](#) channel)
Free all coherent/consistent DMA mappings for the given DMA channel on the specified DM75xx device.

- int `dm75xx_load` (void)
Perform all actions necessary to initialize the DM75xx driver and devices.
- static int `dm75xx_modify_pci_region` (`dm75xx_device_descriptor_t` *dm75xx, unsigned long ioctl_param)
Read an unsigned value from one of a device's PCI regions, modify certain bits in the value, and then write it back to the region.
- static int `dm75xx_open` (struct inode *inode, struct file *file)
Prepare a DM75xx device file to be opened and used.
- static unsigned int `dm75xx_poll` (struct file *file, struct poll_table_struct *poll_table)
Determine whether or not a DM75xx device is readable. This function supports the poll(2) and select(2) system calls.
- static int `dm75xx_probe_devices` (uint32_t *device_count, `dm75xx_device_descriptor_t` **device_descriptors)
Probe and set up all DM75xx devices.
- static int `dm75xx_process_pci_regions` (`dm75xx_device_descriptor_t` *dm75xx, const struct pci_dev *pci_device)
For each of the standard PCI regions, get the region's base address and length from kernel PCI resource information set up at boot. Also, remap any memory-mapped region into the kernel's virtual address space.
- static int `dm75xx_register_char_device` (int *major)
Register the DM75xx character device and request dynamic allocation of a character device major number.
- static int `dm75xx_release` (struct inode *inode, struct file *file)
Do all processing necessary after the last reference to a DM75xx device file is released elsewhere in the kernel.
- static void `dm75xx_release_resources` (void)
Release any resources allocated by the driver.
- void `dm75xx_unload` (void)
Perform all actions necessary to deinitialize the DM75xx driver and devices.
- static int `dm75xx_unregister_char_device` (void)
Unregister the DM75xx character device and free the character device major number.
- static int `dm75xx_validate_device` (const `dm75xx_device_descriptor_t` *dm75xx)
Given what is assumed to be the address of a DM75xx device descriptor, make sure it corresponds to a valid DM75xx device descriptor.
- static int `dm75xx_validate_pci_access` (const `dm75xx_device_descriptor_t` *dm75xx, const `dm75xx_pci_access_request_t` *pci_request)
Validate a user-space access to one of the device's PCI regions.
- static int `dm75xx_get_fifo_size` (`dm75xx_device_descriptor_t` *dm75xx, unsigned int *size)
Measure the size of the fifo by filling it until it is half-full then doubling that value to get the size of the fifo.

4.6.1 Detailed Description

DM75xx_Driver_Forward_Declarations

4.6.2 Function Documentation

4.6.2.1 static void `dm75xx_access_pci_region` (const `dm75xx_device_descriptor_t` * dm75xx,
`dm75xx_pci_access_request_t` * pci_request, `dm75xx_pci_region_access_dir_t` direction)
[static]

Read from or write to one of the standard PCI regions.

Parameters

<i>dm75xx</i>	Address of device's DM75xx device descriptor.
<i>pci_request</i>	Address of access' PCI request descriptor.
<i>direction</i>	Direction of access to PCI region (read from or write to).

Warning

This function performs no validation on its arguments. All arguments are assumed correct.

4.6.2.2 `static int dm75xx_allocate_irq (dm75xx_device_descriptor_t * dm75xx, const struct pci_dev * pci_device)`
`[static]`

Allocate an interrupt line for a DM75xx device.

Parameters

<i>dm75xx</i>	Address of device's DM75xx device descriptor.
<i>pci_device</i>	Address of kernel's PCI device structure for the current DM75xx device.

Return values

<i>0</i>	Success.
<i><</i>	0

Failure.

The following values may be returned:

- `-EBUSY` The interrupt line is allocated to another device which requested it as unsharable; returned by `request_irq()`.
- `-EINVAL` The interrupt line is not valid; returned by `request_irq()`.
- `-EINVAL` No interrupt handler is to be associated with the requested interrupt line; returned by `request_irq()`.
- `-ENOMEM` Memory for interrupt action descriptor could not be allocated; returned by `request_irq()`.

Note

On failure, this function will clean up by releasing any resources allocated by the driver to this point.

4.6.2.3 `static void dm75xx_board_reset (dm75xx_device_descriptor_t * dm75xx)` `[static]`

Performs a reset of the board and device descriptor.

Parameters

<i>dm75xx</i>	Address of the device's DM75xx device descriptor
---------------	--

4.6.2.4 `static int dm75xx_dma_abort (dm75xx_device_descriptor_t * dm75xx, dm75xx_dma_channel_t channel)`
`[static]`

Aborts any DMA transfers on the given channel.

Parameters

<i>dm75xx</i>	Address of the device's DM75xx device descriptor.
<i>channel</i>	The DMA channel on which to cancel any transfers.

Return values

0	Success
<	0

Failure.

The following values may be returned:

- `-EINVAL` The channel entered is invalid

4.6.2.5 `static int dm75xx_dma_alloc_buffer (dm75xx_device_descriptor_t * dm75xx, dm75xx_dma_channel_t channel) [static]`

Allocates a coherent and consistent buffer for our DMA operations.

Parameters

<i>dm75xx</i>	Address of the device's DM75xx device descriptor.
<i>channel</i>	The DMA channel for which to allocate a buffer.

Return values

0	Success
<	0

Failure.

The following values may be returned:

- `-ENOMEM` Failed to allocate DMA buffer

Note

The buffer allocated by this function will be mapped to user space.
The pages allocated by this function will be reserved in 2.4 kernel. This is done to allow successful userspace mapping.

4.6.2.6 `static int dm75xx_dma_initialize (dm75xx_device_descriptor_t * dm75xx, dm75xx_ioctl_argument_t * ioctl_argument) [static]`

Initialize DMA for the specified channel and source for the DM75xx device.

Parameters

<i>dm75xx</i>	Address of the device's DM75xx device descriptor.
<i>ioctl_argument</i>	Address of the kernel's ioctl() request structure.

Return values

0	Success
<	0

Failure.

The following values may be returned:

- `-EAGAIN` DMA has already been initialized.

- `-ENOMEM` Failed to allocate page for DMA chain descriptors.
- `-EOPNOTSUPP` The device is not PCI master capable.
- `-EINVAL` Invalid buffer size requested.
- `-EINVAL` Invalid DMA channel.
- `-EINVAL` Invalid DREQ source.

Please see the descriptions of [dm75xx_dreq_init\(\)](#), and [dm75xx_dma_alloc_buffer\(\)](#) for information on other possible values returned in this case.

Note

When initializing DMA, this function: 1) allocates coherent/consistent DMA mappings, 2) allocates memory to store DMA buffer allocation information, 3) allocates memory to link DMA buffers into device's DMA buffer list, 4) links all DMA buffers into the device's DMA buffer list, 5) allocates memory to link DMA buffers in device's free DMA buffer list, and 6) links all DMA buffers into the device's free DMA buffer list.

Factors beyond the number and size of DMA buffers affect the probability of DMA buffer allocation failure. These factors include the number of processes on the system, how much system memory is already in use, and the presence of processes (such as the X server) which use a lot of memory.

System memory can be a scarce resource Every system entity needs some amount of memory. Memory is being allocated and released all the time.

4.6.2.7 `static int dm75xx_dreq_init (dm75xx_device_descriptor_t * dm75xx, dm75xx_dma_channel_t channel, dm75xx_dma_request_t dreq) [static]`

Performs some DMA initialization work based on the DREQ source.

Parameters

<i>dm75xx</i>	Address of the device's DM75xx device descriptor.
<i>channel</i>	The DMA Channel to perform the initialization for.
<i>dreq</i>	The selected DREQ source.

Return values

<i>0</i>	Success
<i><</i>	0

Failure.

The following values may be returned:

- `-EINVAL` Invalid DREQ source

4.6.2.8 `static void dm75xx_enable_plx_dma (const dm75xx_device_descriptor_t * dm75xx, dm75xx_dma_channel_t channel) [static]`

Configure PLX Mode register for the specified DMA Channel.

Parameters

<i>dm75xx</i>	Address of the devices' DM75xx Device Descriptor.
<i>channel</i>	The DMA Channel to configure.

4.6.2.9 `static void dm75xx_enable_plx_interrupts (const dm75xx_device_descriptor_t * dm75xx, uint8_t enable)`
`[static]`

Enable PLX interrupts for the specified DM75xx Device.

Parameters

<i>dm75xx</i>	Address of the devices' DM75xx Device Descriptor.
<i>enable</i>	Flag indicating whether or not PLX interrupts should be enabled. A value of zero indicates disable and any other value indicates enable.

4.6.2.10 `static void dm75xx_free_dma_mappings (dm75xx_device_descriptor_t * dm75xx, dm75xx_dma_channel_t channel)` `[static]`

Free all coherent/consistent DMA mappings for the given DMA channel on the specified DM75xx device.

Parameters

<i>dm75xx</i>	Address of the device's DM75xx device descriptor.
<i>channel</i>	The DMA channel for which to free the DMA mappings.

Note

This function also frees the memory allocated to manage the DMA buffer allocation information and the DMA buffer lists.

4.6.2.11 `static int dm75xx_get_fifo_size (dm75xx_device_descriptor_t * dm75xx, unsigned int * size)` `[static]`

Measure the size of the fifo by filling it until it is half-full then doubling that value to get the size of the fifo.

Parameters

<i>dm75xx</i>	Address of the device descriptor.
<i>size</i>	Address of the variable to store the size once it is found

Return values

<i>0</i>	Success.
<i>< 0</i>	

Failure

4.6.2.12 `static int dm75xx_get_interrupt (dm75xx_device_descriptor_t * dm75xx, unsigned long ioctl_param)`
`[static]`

Returns the top entry from the interrupt status queue.

Parameters

<i>dm75xx</i>	Address of the device's DM75xx device descriptor.
<i>ioctl_param</i>	Third parameter given on ioctl() call. This is the user space address of the structure used to pass in the arguments.

Return values

0	Success
< 0	

Failure.

The following values may be returned:

```
@arg \c
      -EFAULT      Copy to user failed
```

4.6.2.13 `static void dm75xx_get_pci_master_status (dm75xx_device_descriptor_t * dm75xx, uint8_t * pci_master)` `[static]`

Determine whether or not a device is PCI master capable.

Parameters

<i>dm75xx</i>	Address of device's DM75xx device descriptor.
<i>pci_master</i>	Address where pci master capable flag should be stored. Zero will be stored if the device is not PCI master capable. A non-zero value will be stored here if the device is PCI master capable.

Note

PCI Master capability is required for DMA operations.

4.6.2.14 `static void dm75xx_initialize_device_descriptor (dm75xx_device_descriptor_t * dm75xx)` `[static]`

Initialize the device descriptor for the specified DM75xx device.

Parameters

<i>dm75xx</i>	Address of device's DM75xx device descriptor.
---------------	---

Note

When initializing the device descriptor, the driver will perform the following: 1) Reset interrupt tracking and status variables 2) Initialize wait queue 3) Reset DMA information

4.6.2.15 `static void dm75xx_initialize_hardware (const dm75xx_device_descriptor_t * dm75xx)` `[static]`

Initialize the specified DM75xx device.

Parameters

<i>dm75xx</i>	Address of device's DM75xx device descriptor.
---------------	---

Note

When initializing a device, the driver will perform the following: 1) Hardware reset of the board 2) disables PLX PCI interrupts 3) disables PLX local interrupt input 4) disables PLX DMA channel 0/1 interrupts

4.6.2.16 `static int dm75xx_interrupt_control (dm75xx_device_descriptor_t * dm75xx, unsigned long ioctl_param)`
`[static]`

Control the interrupts on the boards. This includes enabling, disabling and checking the enable/disable status of the interrupts.

Parameters

<i>dm75xx</i>	Address of the device's DM75xx device descriptor.
<i>ioctl_param</i>	Third parameter given on ioctl() call. This is the user space address of the structure used to pass in the arguments.

Return values

0	Success
< 0	

Failure.

The following may be returned:

```
@arg \c
-EFAULT      Copy from user failed
-ENOSYS      Interrupt control function requested does not exist
```

4.6.2.17 static void dm75xx_interrupt_enable(dm75xx_device_descriptor_t * dm75xx, dm75xx_int_source_t source, uint8_t enable) [static]

Performs the actual enable/disable of the interrupt sources.

Parameters

<i>dm75xx</i>	Address of the device's DM75xx device descriptor
<i>source</i>	A bit mask indicating which interrupt sources to enable/disable
<i>enable</i>	flag indicating if we are performing an enable or a disable

4.6.2.18 INTERRUPT_HANDLER_TYPE dm75xx_interrupt_handler(int irq_number, void * device_id)

DM75xx device interrupt handler.

Parameters

<i>irq_number</i>	Interrupt line number.
<i>device_id</i>	Address of device's DM75xx device descriptor. This is set on request_irq() call.

Return values

<i>IRQ_HANDLED</i>	Interrupt successfully processed;
<i>IRQ_NONE</i>	Interrupt could not be processed;

4.6.2.19 static long dm75xx_ioctl(struct file * file, unsigned int request_code, unsigned long ioctl_param) [static]

Process ioctl(2) system calls directed toward a DM75xx device file.

Parameters

<i>file</i>	Address of kernel's file descriptor for the device file.
<i>request_code</i>	The service being requested.
<i>ioctl_param</i>	Third parameter given on ioctl() call. Depending upon request_code, ioctl_param may or may not be used. Also based upon request_code, ioctl_param may be an actual value or may be an address. If the third parameter is not given on the ioctl() call, then ioctl_param has some undefined value.

Return values

0	Success.
< 0	

Failure.

The following values may be returned:

- `-EINVAL` request_code is not valid.

Please see the descriptions of [dm75xx_validate_device\(\)](#), [dm75xx_read_pci_region\(\)](#), [dm75xx_write_pci_region\(\)](#), [dm75xx_modify_pci_region\(\)](#), [dm75xx_service_dma_function\(\)](#), [dm75xx_get_interrupt\(\)](#), [dm75xx_interrupt_control\(\)](#), and [dm75xx_board_reset\(\)](#) for information on other possible values returned in this case.

4.6.2.20 `int dm75xx_load (void)`

Perform all actions necessary to initialize the DM75xx driver and devices.

Return values

0	Success.
< 0	

Failure.

The following values may be returned:

- `-ENOMEM` /proc entry creation failed.

Please see the descriptions of [dm75xx_probe_devices\(\)](#) and [dm75xx_register_char_device\(\)](#) for information on other possible values returned in this case.

Note

On failure, this function will clean up by releasing any resources allocated by the driver. When loaded, the driver performs a board reset, disables PLX PCI interrupts, disables PLX local interrupt input, and disables PLX DMA channel 0/1 interrupts.

4.6.2.21 `static int dm75xx_modify_pci_region (dm75xx_device_descriptor_t * dm75xx, unsigned long ioctl_param)`
[static]

Read an unsigned value from one of a device's PCI regions, modify certain bits in the value, and then write it back to the region.

Parameters

<i>dm75xx</i>	Address of device's DM75xx device descriptor.
<i>iocctl_param</i>	Third parameter given on <code>iocctl()</code> call. This is the user space address of the structure used to pass in the arguments.

Return values

0	Success.
< 0	

Failure.

The following values may be returned:

- `-EFAULT` iocctl_param is not a valid user address.

Please see the description of [dm75xx_validate_pci_access\(\)](#) for information on other possible values returned in this case.

4.6.2.22 `static int dm75xx_open (struct inode * inode, struct file * file)` `[static]`

Prepare a DM75xx device file to be opened and used.

Parameters

<i>inode</i>	Address of kernel's inode descriptor for the device file.
<i>file</i>	Address of kernel's file descriptor for the device file.

Return values

0	Success.
<	0

Failure.

The following values may be returned:

- `-EBUSY` The device file is already open.
- `-ENODEV` The device's inode does not refer to a valid DM75xx device; 2.4 kernel only.

Note

When a device is opened, the driver disables & clears all device interrupts, enables PLX PCI interrupts, enables PLX local interrupt input, and enables PLX DMA channel 0/1 interrupts.

4.6.2.23 `static unsigned int dm75xx_poll (struct file * file, struct poll_table_struct * poll_table)` `[static]`

Determine whether or not a DM75xx device is readable. This function supports the `poll(2)` and `select(2)` system calls.

Parameters

<i>file</i>	Address of kernel's file descriptor for the device file.
<i>poll_table</i>	Address of kernel's poll table descriptor. This keeps track of all event queues on which the process can wait.

Return values

<i>status</i>	mask
---------------	------

Bit mask describing the status of the device.

The following bits may be set in the mask:

- `POLLPRI` will be set if the file descriptor contains an invalid device descriptor.
- `POLLIN` will be set if an interrupt occurred since the last time the interrupt status was read.
- `POLLRDNORM` will be set if an interrupt occurred since the last time the interrupt status was read.

Note

A DM75xx device is readable if and only if an interrupt just occurred on the device and a process has not yet obtained the interrupt status from it.

This function is used in the process of waiting until an interrupt occurs on a device.

This function can be executed before an interrupt occurs, which happens if something sends a signal to the process.

4.6.2.24 `static int dm75xx_probe_devices (uint32_t * device_count, dm75xx_device_descriptor_t ** device_descriptors) [static]`

Probe and set up all DM75xx devices.

Parameters

<i>device_count</i>	Address where DM75xx device count should be stored. The content of this this memory is undefined if the function fails.
<i>device_↔ descriptors</i>	Address where address of device descriptor memory should be stored. The content of this memory is undefined if the function fails.

Return values

0	Success.
< 0	

Failure.

The following values may be returned:

- `-ENAMETOOLONG` Device name creation failed.
- `-ENODEV` No DM75xx devices found.
- `-ENOMEM` Device descriptor memory allocation failed.

Please see the descriptions of [dm75xx_process_pci_regions\(\)](#), [dm75xx_allocate_irq\(\)](#) ... for information on other possible values returned in this case.

Note

If set up of any device fails, then all device set up fails.

This function allocates memory for the DM75xx device descriptors based upon the number of devices found.

On failure, this function will clean up by releasing any resources allocated by the driver to this point.

4.6.2.25 `static int dm75xx_process_pci_regions (dm75xx_device_descriptor_t * dm75xx, const struct pci_dev * pci_device) [static]`

For each of the standard PCI regions, get the region's base address and length from kernel PCI resource information set up at boot. Also, remap any memory-mapped region into the kernel's virtual address space.

Parameters

<i>dm75xx</i>	Address of device's DM75xx device descriptor.
<i>pci_device</i>	Address of kernel's PCI device structure for the current DM75xx device.

Return values

0	Success.
< 0	

Failure.

The following values may be returned:

- `-EBUSY` I/O port or I/O memory range allocation failed.
- `-EIO` A region's resource flags are not valid.
- `-ENOMEM` Remapping a memory-mapped region into the kernel's virtual address space failed.

Note

Currently, only BAR0 through BAR2 are used. BAR0 is the memory-mapped PLX DMA register region. BAR1 is the I/O-mapped PLX DMA register region. BAR2 is the memory-mapped FPGA register region. On failure, this function will clean up by releasing any resources allocated by the driver to this point.

4.6.2.26 `static void dm75xx_put_interrupt (dm75xx_device_descriptor_t * dm75xx, uint32_t interrupt) [static]`

Adds an interrupt to the interrupt status queue.

Parameters

<i>dm75xx</i>	Address of the device's DM75xx device descriptor.
<i>interrupt</i>	Interrupt to add to the queue.

Return values

0	Success
<	0

Failure.

The following values may be returned:

```
@arg \c
      -EFAULT      Copy to user failed
```

4.6.2.27 `static int dm75xx_register_char_device (int * major) [static]`

Register the DM75xx character device and request dynamic allocation of a character device major number.

Parameters

<i>major</i>	Address where character device major number should be stored.
--------------	---

Return values

0	Success.
<	0

Failure.

The following values may be returned:

- `-EBUSY` A character device major number could not be allocated; returned by `alloc_chrdev_region()`.
- `-EBUSY` All character device major numbers are in use; returned by `register_chrdev()`.
- `-ENOMEM` Memory allocation failed; returned by `alloc_chrdev_region()`.

Note

This function hides the character device interface differences between 2.4 and 2.6 kernels.

4.6.2.28 `static int dm75xx_release (struct inode * inode, struct file * file) [static]`

Do all processing necessary after the last reference to a DM75xx device file is released elsewhere in the kernel.

Parameters

<i>inode</i>	Address of kernel's inode descriptor for the device file. Unused.
<i>file</i>	Address of kernel's file descriptor for the device file.

Return values

0	Success.
< 0	

Failure. Please see the description of [dm75xx_validate_device\(\)](#) for information on possible values returned in this case.

Note

When a device is released, the driver disables PLX PCI interrupts, disables PLX local interrupt input, and disables PLX DMA channel 0/1 interrupts.

4.6.2.29 static void dm75xx_release_resources (void) [static]

Release any resources allocated by the driver.

Note

This function is called both at module unload time and when the driver is cleaning up after some error occurred.

4.6.2.30 static int dm75xx_service_dma_function (dm75xx_device_descriptor_t * dm75xx, unsigned long ioctl_param) [static]

Process user space DMA function requests.

Parameters

<i>dm75xx</i>	Address of the device's DM75xx device descriptor.
<i>ioctl_param</i>	Third parameters given on ioctl() call. This is the user space address of the structure used to pass in the arguments.

Return values

0	Success
< 0	

Failure.

The following values may be returned:

- -EFAULT ioctl_param is not a valid user address
- -EFAULT DMA channel or source used to operate upon is not valid.
- -ENOSYS DMA function request is not valid

Please see the descriptions of [dm75xx_dma_initialize\(\)](#), and [dm75xx_dma_abort\(\)](#) for information on other possible values returned in this case.

4.6.2.31 static int dm75xx_unregister_char_device (void) [static]

Unregister the DM75xx character device and free the character device major number.

Return values

0	Success.
<	0

Failure.

The following values may be returned:

- `-EINVAL` Character major number is not valid; returned by `unregister_chrdev()`; 2.4 kernel only.

`-EINVAL` Character major number has no file operations registered for it; returned by `unregister_chrdev()`; 2.4 kernel only.

`-EINVAL` Device name specified when character major number was registered does not match the name being unregistered; returned by `unregister_chrdev()`; 2.4 kernel only.

Note

This function hides the character device interface differences between 2.4 and 2.6 kernels.
This function does not fail on 2.6 kernels.

4.6.2.32 `static int dm75xx_validate_device (const dm75xx_device_descriptor_t * dm75xx) [static]`

Given what is assumed to be the address of a DM75xx device descriptor, make sure it corresponds to a valid DM75xx device descriptor.

Parameters

<i>dm75xx</i>	Address of device descriptor to be verified.
---------------	--

Return values

0	Success.
<	0

Failure.

The following values may be returned:

- `-EBADFD` *dm75xx* is not a valid DM75xx device descriptor address.

4.6.2.33 `static int dm75xx_validate_pci_access (const dm75xx_device_descriptor_t * dm75xx, const dm75xx_pci_access_request_t * pci_request) [static]`

Validate a user-space access to one of the device's PCI regions.

Parameters

<i>dm75xx</i>	Address of the device's DM75xx device descriptor.
<i>pci_request</i>	Address of PCI region access request descriptor.

Return values

0	Success
<	0

Failure.

The following values may be returned:

- `-EINVAL` The PCI region is not valid.

- `-EMSGSIZE` The access size is not valid.
- `-EOPNOTSUPP` The PCI region offset is valid but is not suitably aligned for the number of bytes to be accessed.
- `-ERANGE` The PCI region offset is not valid.

Note

This function accesses information in the device descriptor. Therefore, the device descriptor spin lock should be held when this function is called.

4.7 DM75xx ioctl header file

Modules

- [DM75xx ioctl enumerations](#)
- [DM75xx ioctl structures](#)
- [DM75xx ioctl macros](#)

4.7.1 Detailed Description

4.8 DM75xx ioctl enumerations

Typedefs

- typedef enum
[dm75xx_dma_manage_function](#) [dm75xx_dma_manage_function_t](#)
Functions supported by driver DMA management system.
- typedef enum
[dm75xx_int_control_function](#) [dm75xx_int_control_function_t](#)
Functions supported by driver interrupt control system.

Enumerations

- enum [dm75xx_dma_manage_function](#) { [DM75xx_DMA_FUNCTION_INITIALIZE](#) = 0, [DM75xx_DMA_FUNCTION_ABORT](#) }
Functions supported by driver DMA management system.
- enum [dm75xx_int_control_function](#) { [DM75xx_INT_CONTROL_ENABLE](#) = 0, [DM75xx_INT_CONTROL_DISABLE](#), [DM75xx_INT_CONTROL_CHECK](#) }
Functions supported by driver interrupt control system.

4.8.1 Detailed Description

4.8.2 Enumeration Type Documentation

4.8.2.1 enum [dm75xx_dma_manage_function](#)

Functions supported by driver DMA management system.

Enumerator

[DM75xx_DMA_FUNCTION_INITIALIZE](#) DMA initialization

[DM75xx_DMA_FUNCTION_ABORT](#) DMA abort

Definition at line 48 of file [dm75xx_ioctl.h](#).

4.8.2.2 enum [dm75xx_int_control_function](#)

Functions supported by driver interrupt control system.

Enumerator

[DM75xx_INT_CONTROL_ENABLE](#) Enable Interrupts

[DM75xx_INT_CONTROL_DISABLE](#) Disable Interrupts

[DM75xx_INT_CONTROL_CHECK](#) Returns with a value indicating which interrupts are currently enabled.
 This value should then be checked with [DM75xx_INTERRUPT_ACTIVE\(\)](#).

Definition at line 63 of file [dm75xx_ioctl.h](#).

4.9 DM75xx ioctl structures

Data Structures

- struct [dm75xx_ioctl_region_readwrite](#)
ioctl() request structure for read from or write to PCI region
- struct [dm75xx_ioctl_region_modify](#)
ioctl() request structure for PCI region read/modify/write
- struct [dm75xx_ioctl_dma_function](#)
ioctl() request structure for performing a DMA function
- struct [dm75xx_ioctl_int_control](#)
ioctl() request structure for interrupt control.
- union [dm75xx_ioctl_argument](#)
ioctl() request structure encapsulating all possible requests. This is what gets passed into the kernel from user space on the *ioctl()* call.

Typedefs

- typedef struct
[dm75xx_ioctl_region_readwrite](#) [dm75xx_ioctl_region_readwrite_t](#)
- typedef struct
[dm75xx_ioctl_region_modify](#) [dm75xx_ioctl_region_modify_t](#)
ioctl() PCI region read/modify/write request descriptor type
- typedef struct
[dm75xx_ioctl_dma_function](#) [dm75xx_ioctl_dma_function_t](#)
ioctl() request structure for performing a DMA function type.
- typedef struct
[dm75xx_ioctl_int_control](#) [dm75xx_ioctl_int_control_t](#)
ioctl() request structure for interrupt control.
- typedef union [dm75xx_ioctl_argument](#) [dm75xx_ioctl_argument_t](#)
ioctl() request descriptor type

4.9.1 Detailed Description

DM75xx_Ioctl_Enumerations

4.9.2 Typedef Documentation

4.9.2.1 typedef struct [dm75xx_ioctl_region_readwrite](#) [dm75xx_ioctl_region_readwrite_t](#)

typedef for the PCI region access request type

Definition at line 108 of file [dm75xx_ioctl.h](#).

4.10 DM75xx ioctl macros

Macros

- #define `DM75xx_IOCTL_MAGIC` 'D'
Unique 8-bit value used to generate unique ioctl() request codes.
- #define `DM75xx_IOCTL_REQUEST_BASE` 0x00
First ioctl() request number.
- #define `DM75xx_IOCTL_REGION_READ`
ioctl() request code for reading from a PCI region
- #define `DM75xx_IOCTL_REGION_WRITE`
ioctl() request code for writing to a PCI region
- #define `DM75xx_IOCTL_REGION_MODIFY`
ioctl() request code for PCI region read/modify/write
- #define `DM75xx_IOCTL_DMA_FUNCTION`
ioctl() request code for DMA function
- #define `DM75xx_IOCTL_WAKEUP`
ioctl() request code to wake up a sleeping driver function
- #define `DM75xx_IOCTL_INT_STATUS`
ioctl() request code to get the interrupt status queue
- #define `DM75xx_IOCTL_GET_FIFO_SIZE`
ioctl() request code to get the fifo size
- #define `DM75xx_IOCTL_GET_BOARD_TYPE`
ioctl() request code to get the board type
- #define `DM75xx_IOCTL_INT_CONTROL`
ioctl() request code to control interrupts
- #define `DM75xx_IOCTL_RESET`
ioctl() request code to reset the board
- #define `DM75xx_IOCTL_RESET_DMA_STATUS`
ioctl() request code to control DMA buffer status

4.10.1 Detailed Description

DM75xx_ioctl_Structures

4.11 DM75xx kernel compatibility header file

4.12 DM75xx kernel compatibility interrupt handler macros

Macros

- `#define INTERRUPT_HANDLER_TYPE static irqreturn_t`
Type returned by interrupt handler.

Typedefs

- `typedef irqreturn_t(* dm75xx_handler_t)(int, void *)`
Type definition for interrupt handling function.

4.12.1 Detailed Description

DM75xx_Kernel_Module_Major_Minor_Number_Macros

4.13 kernel compatibility interrupt handler macros

Macros

- `#define DM75XX_IOCTL .unlocked_ioctl`
In Kernel 2.6.35, `.ioctl` was replaced with `.unlocked_ioctl`.

4.13.1 Detailed Description

DM75xx_Kernel_Interrupt_Handler_Macros

4.14 DM75xx kernel compatibility device I/O memory access macros

Macros

- `#define IO_MEMORY_READ8 ioread8`
Entity which reads an 8-bit value from device I/O memory.
- `#define IO_MEMORY_READ16 ioread16`
Entity which reads a 16-bit value from device I/O memory.
- `#define IO_MEMORY_READ32 ioread32`
Entity which reads a 32-bit value from device I/O memory.
- `#define IO_MEMORY_WRITE8 iowrite8`
Entity which writes an 8-bit value to device I/O memory.
- `#define IO_MEMORY_WRITE16 iowrite16`
Entity which writes a 16-bit value to device I/O memory.
- `#define IO_MEMORY_WRITE32 iowrite32`
Entity which writes a 32-bit value to device I/O memory.

4.14.1 Detailed Description

DM75xx_Kernel_File_Ops_Struct_Macros

4.15 DM75xx user library header file

Modules

- [DM75xx user library macros](#)
- [DM75xx user library type definitions](#)
- [DM75xx user library structures](#)
- [DM75xx user library functions](#)

4.15.1 Detailed Description

4.16 DM75xx user library macros

Macros

- `#define DM75xx_INTERRUPT_ACTIVE(status, source) (((status) & (source)) ? 0xFF : 0x00)`
Determine whether or not the specified interrupt source has occurred in your the user space ISR.
- `#define DM75xx_ADC_ANALOG_DATA(data) (((int16_t) (data)) >> 3)`
This macro will return the sample portion of raw analog data.
- `#define DM75xx_ADC_MARKERS(data) ((data) & 0x07)`
This macro will turn the data marker portion of raw analog data.
- `#define DM75xx_DAC_PACK_DATA(data, mcbasp_bit, data_markers)`
This macro will assemble a package to be sent to the Digital to Analog FIFO.

4.16.1 Detailed Description

4.16.2 Macro Definition Documentation

4.16.2.1 `#define DM75xx_ADC_ANALOG_DATA(data) (((int16_t) (data)) >> 3)`

This macro will return the sample portion of raw analog data.

Parameters

<i>data</i>	The raw analog data
-------------	---------------------

Returns

The 12 bit signed analog sample

Note

The value returned by this macro should be stored in an `int16_t`

Definition at line 94 of file `dm75xx_library.h`.

Referenced by `main()`.

4.16.2.2 `#define DM75xx_ADC_MARKERS(data) ((data) & 0x07)`

This macro will turn the data marker portion of raw analog data.

Parameters

<i>data</i>	The raw analog data
-------------	---------------------

Returns

The 3 marker bits

Note

The value returned by this macro should be stored in a `uint8_t`

Definition at line 112 of file `dm75xx_library.h`.

4.16.2.3 `#define DM75xx_DAC_PACK_DATA(data, mcbssp_bit, data_markers)`

Value:

```
((int16_t)((int16_t)(data) << 3) | \
(mcbssp_bit & 0x0004) | \
(data_markers & 0x0003))
```

This macro will assemble a package to be sent to the Digital to Analog FIFO.

Parameters

<i>data</i>	The 12 bit signed data to write to the Digital to Analog channel
<i>mcbssp_bit</i>	A bit designating which Digital to Analog channel will receive McBSP data
<i>data_markers</i>	The 2 data marker bits

Returns

The combined DAC Data in an `int16_t`

Definition at line 139 of file `dm75xx_library.h`.

Referenced by `main()`.

4.16.2.4 `#define DM75xx_INTERRUPT_ACTIVE(status, source) (((status) & (source)) ? 0xFF : 0x00)`

Determine whether or not the specified interrupt source has occurred in your the user space ISR.

Parameters

<i>status</i>	Interrupt status to examine.
<i>source</i>	Interrupt source to determine state of.

Return values

<i>0x00</i>	The specified interrupt source is not pending.
<i>0xFF</i>	The specified interrupt source is pending.

Definition at line 75 of file `dm75xx_library.h`.

Referenced by `ISR()`.

4.17 DM75xx user library type definitions

Typedefs

- typedef int [DM75xx_Error](#)
DM75xx user library error code type.

4.17.1 Detailed Description

DM75xx_Library_Macros

4.18 DM75xx user library structures

Data Structures

- struct [DM75xx_Board_Descriptor](#)

DM75xx board descriptor. This structure holds information about a device needed by the library.

Typedefs

- typedef struct
[DM75xx_Board_Descriptor](#) [DM75xx_Board_Descriptor](#)

4.18.1 Detailed Description

DM75xx_Library_Types

4.18.2 Typedef Documentation

4.18.2.1 typedef struct [DM75xx_Board_Descriptor](#) [DM75xx_Board_Descriptor](#)

DM75xx board descriptor type

Definition at line 224 of file dm75xx_library.h.

4.19 DM75xx user library functions

Modules

- [DM75xx user library board control functions](#)
- [DM75xx user library DMA functions](#)
- [DM75xx user library general functions](#)
- [DM75xx user library user timer/counter control](#)
- [DM75xx user library burst clock control](#)
- [DM75xx user library pacer clock control](#)
- [DM75xx user library channel gain table](#)

- [DM75xx_Error DM75xx_ADC_FIFO_Read](#) (DM75xx_Board_Descriptor *handle, uint16_t *value)
DM75xx_Library_ADC_Functions DM75xx user library analog to digital.
- [DM75xx_Error DM75xx_ADC_Software_Sample](#) (DM75xx_Board_Descriptor *handle)
Analog to Digital Software Sample.
- [DM75xx_Error DM75xx_ADC_Conv_Signal](#) (DM75xx_Board_Descriptor *handle, dm75xx_adc_conv_↔
signal_t adc_conv_signal)
Select the A/D Conversion Signal.
- [DM75xx_Error DM75xx_ADC_SCNT_Source](#) (DM75xx_Board_Descriptor *handle, dm75xx_adc_scnt_src_↔
_t src)
Select the A/D Sample Counter Source.
- [DM75xx_Error DM75xx_ADC_About_Enable](#) (DM75xx_Board_Descriptor *handle, uint16_t enable)
Enable/Disable About Counter stop.
- [DM75xx_Error DM75xx_ADC_Clear](#) (DM75xx_Board_Descriptor *handle)
Clear Analog to Digital FIFO.
- [DM75xx_Error DM75xx_ADC_SCNT_Read](#) (DM75xx_Board_Descriptor *handle, uint16_t *data)
Read the value in the A/D Sample Counter.
- [DM75xx_Error DM75xx_ADC_SCNT_Load](#) (DM75xx_Board_Descriptor *handle, uint16_t data)
Load a value into the A/D Sample Counter.

- [DM75xx_Error DM75xx_DAC_Soft_Update](#) (DM75xx_Board_Descriptor *handle, uint8_t dac)
DM75xx_Library_DAC_Functions DM75xx user library digital to analog.
- [DM75xx_Error DM75xx_DAC_Get_Update_Counter](#) (DM75xx_Board_Descriptor *handle, dm75xx_dac_↔
channel_t dac, uint16_t *data)
Get DAC update counter for a specified channel.
- [DM75xx_Error DM75xx_DAC_Set_Update_Counter](#) (DM75xx_Board_Descriptor *handle, dm75xx_dac_↔
channel_t dac, uint16_t data)
Set the DAC update counter for a specified channel.
- [DM75xx_Error DM75xx_DAC_Set_Range](#) (DM75xx_Board_Descriptor *handle, dm75xx_dac_channel_↔
t dac, dm75xx_dac_range_t range)
Set the DAC output range for a specified channel.
- [DM75xx_Error DM75xx_DAC_Set_Update_Source](#) (DM75xx_Board_Descriptor *handle, dm75xx_dac_↔
channel_t dac, dm75xx_dac_update_src_t src)
Set the DAC Update Source for the specified channel.
- [DM75xx_Error DM75xx_DAC_Set_Mode](#) (DM75xx_Board_Descriptor *handle, dm75xx_dac_channel_t dac,
dm75xx_dac_mode_t mode)
Set the DAC mode for a specified channel.
- [DM75xx_Error DM75xx_DAC_FIFO_Write](#) (DM75xx_Board_Descriptor *handle, dm75xx_dac_channel_↔
t dac, uint16_t data)
Write a value to the DAC FIFO of a specified channel.
- [DM75xx_Error DM75xx_DAC_Set_Frequency](#) (DM75xx_Board_Descriptor *handle, dm75xx_dac_freq_↔
t freq)

- Set the primary slock frequency for DAC conversion.*

 - [DM75xx_Error DM75xx_DAC_Set_Count](#) ([DM75xx_Board_Descriptor](#) *handle, uint32_t count)

Set the DAC Clock Count.

 - [DM75xx_Error DM75xx_DAC_Set_Rate](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dac_freq_t](#) freq, uint32_t rate, float *actualRate)

Set the DAC conversion rate.

 - [DM75xx_Error DM75xx_DAC_Set_Clock_Stop](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dac_clk_t](#) stop_t stop)

Set the DAC Clock Stop Value.

 - [DM75xx_Error DM75xx_DAC_Set_Clock_Start](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dac_clk_t](#) start_t start)

Set the DAC Clock Start Value.

 - [DM75xx_Error DM75xx_DAC_Start](#) ([DM75xx_Board_Descriptor](#) *handle)

Causes a DAC Software Start.

 - [DM75xx_Error DM75xx_DAC_Stop](#) ([DM75xx_Board_Descriptor](#) *handle)

Causes a DAC Software Stop.

 - [DM75xx_Error DM75xx_DAC_Setup](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dac_channel_t](#) dac, [dm75xx_dac_range_t](#) range, [dm75xx_dac_update_src_t](#) src, [dm75xx_dac_mode_t](#) mode)

Setup a DAC channel.

 - [DM75xx_Error DM75xx_DAC_Reset](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dac_channel_t](#) dac)

Reset a DAC Fifo.

 - [DM75xx_Error DM75xx_DAC_Clear](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dac_channel_t](#) dac)

Clear a DAC Fifo.

 - [DM75xx_Error DM75xx_DAC_Set_CLK_Mode](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dac_clk_t](#) mode_t clk_mode)

Set DAC Clock Mode.
- [DM75xx_Error DM75xx_HSDIN_Software_Sample](#) ([DM75xx_Board_Descriptor](#) *handle)
- DM75xx_Library_HSDIN_Functions DM75xx user library high speed digital.*

 - [DM75xx_Error DM75xx_HSDIN_Sample_Signal](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_hsdin_t](#) signal_t signal)

Set HighSpeed digital sampling signal.

 - [DM75xx_Error DM75xx_HSDIN_Clear](#) ([DM75xx_Board_Descriptor](#) *handle)

Clear High Speed Digital FIFO.

 - [DM75xx_Error DM75xx_HSDIN_FIFO_Read](#) ([DM75xx_Board_Descriptor](#) *handle, uint16_t *data)

Read value from High Speed Digital FIFO.
- [DM75xx_Error DM75xx_SBUS_Set_Source](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_sbus_t](#) sbus, [dm75xx_sbus_src_t](#) src)
- DM75xx_Library_SBUS_Functions DM75xx user library synbus.*

 - [DM75xx_Error DM75xx_SBUS_Enable](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_sbus_t](#) sbus, uint16_t enable)

Enable/Disable Synbus.
- [DM75xx_Error DM75xx_ACNT_Get_Count](#) ([DM75xx_Board_Descriptor](#) *handle, uint16_t *data)
- DM75xx_Library_ACNT_Functions DM75xx user library about counter.*

 - [DM75xx_Error DM75xx_ACNT_Set_Count](#) ([DM75xx_Board_Descriptor](#) *handle, uint16_t data)

Set the About Counter value.
- [DM75xx_Error DM75xx_DCNT_Get_Count](#) ([DM75xx_Board_Descriptor](#) *handle, uint16_t *data)
- DM75xx_Library_DCNT_Functions DM75xx user library delay counter.*

 - [DM75xx_Error DM75xx_DCNT_Set_Count](#) ([DM75xx_Board_Descriptor](#) *handle, uint16_t data)

Set the Delay Counter value.

- [DM75xx_Error DM75xx_DIO_Set_Port](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dio_port_t](#) port, [uint8_t](#) data)
DM75xx_Library_DIO_Functions DM75xx user library digital input/output.
- [DM75xx_Error DM75xx_DIO_Get_Port](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dio_port_t](#) port, [uint8_t](#) *data)
Get the value from the specified Digital I/O Port.
- [DM75xx_Error DM75xx_DIO_Get_Status](#) ([DM75xx_Board_Descriptor](#) *handle, [uint8_t](#) *data)
Get the Digital I/O Status byte.
- [DM75xx_Error DM75xx_DIO_Clear_IRQ](#) ([DM75xx_Board_Descriptor](#) *handle)
Clear Digital I/O IRQ Status.
- [DM75xx_Error DM75xx_DIO_Reset](#) ([DM75xx_Board_Descriptor](#) *handle)
Clear Digital I/O Chip.
- [DM75xx_Error DM75xx_DIO_Set_Direction](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dio_port_t](#) port, [uint8_t](#) direction)
Set the direction of the specified Digital I/O Port.
- [DM75xx_Error DM75xx_DIO_Set_Mask](#) ([DM75xx_Board_Descriptor](#) *handle, [uint8_t](#) mask)
Set Digital I/O Port 0 Mask.
- [DM75xx_Error DM75xx_DIO_Set_Compare](#) ([DM75xx_Board_Descriptor](#) *handle, [uint8_t](#) compare)
Set the compare register for Digital I/O Port 0.
- [DM75xx_Error DM75xx_DIO_Get_Compare](#) ([DM75xx_Board_Descriptor](#) *handle, [uint8_t](#) *compare)
Get the compare register for Digital I/O Port 0.
- [DM75xx_Error DM75xx_DIO_IRQ_Mode](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dio_mode_t](#) mode)
Set the IRQ Mode for Digital I/O.
- [DM75xx_Error DM75xx_DIO_Clock](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dio_clk_t](#) clock)
Set the Digital I/O Sample Clock.
- [DM75xx_Error DM75xx_DIO_Enable_IRQ](#) ([DM75xx_Board_Descriptor](#) *handle, [uint8_t](#) enable)
Enable/Disable Digital I/O Interrupts.
- [DM75xx_Error DM75xx_UIO_Select](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_uio_channel_t](#) channel, [dm75xx_uio_source_t](#) source)
DM75xx_Library_UIO_Functions DM75xx user library user I/O.
- [DM75xx_Error DM75xx_UIO_Read](#) ([DM75xx_Board_Descriptor](#) *handle, [uint32_t](#) *data)
Read the current status of the user I/O.
- [DM75xx_Error DM75xx_UIO_Write](#) ([DM75xx_Board_Descriptor](#) *handle, [uint32_t](#) data)
Write the value of the user I/O.
- [DM75xx_Error DM75xx_McBSP_ADC_FIFO](#) ([DM75xx_Board_Descriptor](#) *handle, [uint8_t](#) enable)
DM75xx_Library_McBSP_Functions DM75xx user library mcbbsp.
- [DM75xx_Error DM75xx_McBSP_DAC_FIFO](#) ([DM75xx_Board_Descriptor](#) *handle, [uint8_t](#) enable)
Enable/Disable D/A FIFO to DSP.
- [DM75xx_Error DM75xx_ETRIG_Polarity_Select](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_ext_ext_polarity_t](#) polarity)
DM75xx_Library_EXT_Functions DM75xx user library external trigger/interrupt.
- [DM75xx_Error DM75xx_EINT_Polarity_Select](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_ext_ext_polarity_t](#) polarity)
Set the External Interrupt polarity.
- [DM75xx_Error DM75xx_FIFO_Get_Status](#) ([DM75xx_Board_Descriptor](#) *handle, [uint16_t](#) *fifo_status)

DM75xx_Library_STATUS_Funcions DM75xx user library status.

- [DM75xx_Error DM75xx_CLK_Get_Status](#) ([DM75xx_Board_Descriptor](#) *handle, uint16_t *status)

Get status of pacer/burst clocks.

- [DM75xx_Error DM75xx_Calibrate](#) ([DM75xx_Board_Descriptor](#) *handle, uint16_t dac1_value, uint16_t dac2_value, [dm75xx_dac_range_t](#) dac1_range, [dm75xx_dac_range_t](#) dac2_range)

DM75xx_Library_SDM7540_Funcions DM75xx user library SDM7540 functions.

- [DM75xx_Error DM75xx_DSP_CMD_Send](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dsp_command_t](#) command)

Issue a command to the 7540 onboard DSP.

- [DM75xx_Error DM75xx_DSP_CMD_Complete](#) ([DM75xx_Board_Descriptor](#) *handle, uint8_t *data)

Checks if the last command given to the DSP is finished.

- [DM75xx_Error DM75xx_DSP_CMD_Status](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dsp_command_t](#) command)

Checks whether or not a command successfully completed on the DSP.

- [DM75xx_Error DM75xx_ALGDIO_Get_Mask](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_algdio_mask_t](#) *pin1, [dm75xx_algdio_mask_t](#) *pin2)

Get the the mask of the Analog DIO.

- [DM75xx_Error DM75xx_ALGDIO_Set_Mask](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_algdio_mask_t](#) pin1, [dm75xx_algdio_mask_t](#) pin2)

Set the Analog DIO Mask.

- [DM75xx_Error DM75xx_ALGDIO_Get_Direction](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_algdio_direction_t](#) *pin1, [dm75xx_algdio_direction_t](#) *pin2)

Get the Analog DIO Direction.

- [DM75xx_Error DM75xx_ALGDIO_Set_Direction](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_algdio_direction_t](#) pin1, [dm75xx_algdio_direction_t](#) pin2)

Set the Analog DIO Direction.

- [DM75xx_Error DM75xx_ALGDIO_Set_Data](#) ([DM75xx_Board_Descriptor](#) *handle, uint8_t pin1, uint8_t pin2)

Set the Analog DIO pin values.

- [DM75xx_Error DM75xx_ALGDIO_Get_Data](#) ([DM75xx_Board_Descriptor](#) *handle, uint8_t *pin1, uint8_t *pin2)

Get the Analog DIO pin values.

- [DM75xx_Error DM75xx_ALGDIO_Get_IRQ_Status](#) ([DM75xx_Board_Descriptor](#) *handle, uint8_t *status)

Get Analog DIO IRQ Status.

- [DM75xx_Error DM75xx_Get_Temp](#) ([DM75xx_Board_Descriptor](#) *handle, uint8_t *temp)

Get the temperature from the board.

4.19.1 Detailed Description

DM75xx_Library_Structures

4.19.2 Function Documentation

4.19.2.1 [DM75xx_Error DM75xx_ACNT_Get_Count](#) ([DM75xx_Board_Descriptor](#) * handle, uint16_t * data)

DM75xx_Library_ACNT_Funcions DM75xx user library about counter.

DM75xx_Library_SBUS_Funcions

Get About Counter value

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>data</i>	Address of the variable to store the value.

Return values

0	Success.
-1	Failure. Please see the ioctl(2) man page for information on possible values <code>errno</code> may have in this case.

4.19.2.2 DM75xx_Error DM75xx_ACNT_Set_Count (DM75xx_Board_Descriptor * *handle*, uint16_t *data*)

Set the About Counter value.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>data</i>	Value at which to set the About Counter.

Return values

0	Success.
-1	Failure. Please see the ioctl(2) man page for information on possible values <code>errno</code> may have in this case.

Referenced by main().

4.19.2.3 DM75xx_Error DM75xx_ADC_About_Enable (DM75xx_Board_Descriptor * *handle*, uint16_t *enable*)

Enable/Disable About Counter stop.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>enable</i>	Enable/Disable.

Return values

0	Success.
-1	Failure. Please see the ioctl(2) man page for information on possible values <code>errno</code> may have in this case.

Referenced by main().

4.19.2.4 `DM75xx_Error DM75xx_ADC_Clear (DM75xx_Board_Descriptor * handle)`

Clear Analag to Digital FIFO.

Parameters

<i>handle</i>	Address of device's library board descriptor.
---------------	---

Return values

0	Success.
-1	Failure.

Please see the `ioctl(2)` man page for information on possible values `errno` may have in this case.

Referenced by `main()`.

4.19.2.5 DM75xx_Error DM75xx_ADC_Conv_Signal (DM75xx_Board_Descriptor * *handle*, dm75xx_adc_conv_signal_t *adc_conv_signal*)

Select the A/D Conversion Signal.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>adc_conv_signal</i>	The A/D conversion signal to select.

Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

Referenced by `main()`.

4.19.2.6 DM75xx_Error DM75xx_ADC_FIFO_Read (DM75xx_Board_Descriptor * *handle*, uint16_t * *value*)

DM75xx_Library_ADC_Functions DM75xx user library analog to digital.

DM75xx_Library_CGT_Functions

Read a value from the A/D FIFO

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>value</i>	Address of the variable to store the value read.

Returns

0

Success

Returns

-1

Failure.

errno may be set as follows:

- `EINVAL` pointer was NULL.

Please see the `close(2)` man page for information on other possible values `errno` may have in this case.

Referenced by `main()`.

4.19.2.7 **DM75xx_Error DM75xx_ADC_SCNT_Load** (**DM75xx_Board_Descriptor** * *handle*, **uint16_t** *data*)

Load a value into the A/D Sample Counter.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>data</i>	Value to load into the sample counter.

Return values

0	Success.
-1	Failure.

Please see the `ioctl(2)` man page for information on possible values `errno` may have in this case.

4.19.2.8 **DM75xx_Error DM75xx_ADC_SCNT_Read** (**DM75xx_Board_Descriptor** * *handle*, **uint16_t** * *data*)

Read the value in the A/D Sample Counter.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>data</i>	Address of the variable to store the data.

Return values

0	Success.
-1	Failure.

Please see the `ioctl(2)` man page for information on possible values `errno` may have in this case.

4.19.2.9 **DM75xx_Error DM75xx_ADC_SCNT_Source** (**DM75xx_Board_Descriptor** * *handle*, **dm75xx_adc_scnt_src_t** *src*)

Select the A/D Sample Counter Source.

Parameters

<i>handle</i>	Address of device's library board descriptor.
---------------	---

<i>src</i>	The selected sample counter source.
------------	-------------------------------------

Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

4.19.2.10 **DM75xx_Error DM75xx_ADC_Software_Sample (DM75xx_Board_Descriptor * *handle*)**

Analog to Digital Software Sample.

Parameters

<i>handle</i>	Address of device's library board descriptor.
---------------	---

Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

Referenced by `main()`.

4.19.2.11 **DM75xx_Error DM75xx_ALGDIO_Get_Data (DM75xx_Board_Descriptor * *handle*, uint8_t * *pin1*, uint8_t * *pin2*)**

Get the Analog DIO pin values.

Parameters

<i>handle</i>	Address of the device's library board descriptor.
<i>pin1</i>	Value at logic high (0xFF) or logic low (0x00).
<i>pin2</i>	Value at logic high (0xFF) or logic low (0x00).

Return values

0	Success.
-1	Failure.

4.19.2.12 **DM75xx_Error DM75xx_ALGDIO_Get_Direction (DM75xx_Board_Descriptor * *handle*, dm75xx_algdio_direction_t * *pin1*, dm75xx_algdio_direction_t * *pin2*)**

Get the Analog DIO Direction.

Parameters

<i>handle</i>	Address of the device's library board descriptor.
<i>pin1</i>	Pin1 Direction 0 = Input, Positive vals = Output.
<i>pin2</i>	Pin2 Direction 0 = Input, Positive vals = Output.

Return values

0	Success.
-1	Failure.

4.19.2.13 DM75xx_Error DM75xx_ALGDIO_Get_IRQ_Status (DM75xx_Board_Descriptor * handle, uint8_t * status)

Get Analog DIO IRQ Status.

Parameters

<i>handle</i>	Address of the device's library board descriptor.
<i>status</i>	The IRQ status.

Return values

0	Success.
-1	Failure.

4.19.2.14 DM75xx_Error DM75xx_ALGDIO_Get_Mask (DM75xx_Board_Descriptor * handle, dm75xx_algdiio_mask_t * pin1, dm75xx_algdiio_mask_t * pin2)

Get the the mask of the Analog DIO.

Parameters

<i>handle</i>	Address of the device's library board descriptor.
<i>pin1</i>	Pin1 mask enabled/disabled.
<i>pin2</i>	Pin2 mask enabled/disabled.

Return values

0	Success.
-1	Failure.

4.19.2.15 DM75xx_Error DM75xx_ALGDIO_Set_Data (DM75xx_Board_Descriptor * handle, uint8_t pin1, uint8_t pin2)

Set the Analog DIO pin values.

Parameters

<i>handle</i>	Address of the device's library board descriptor.
<i>pin1</i>	Value at logic high (0xFF) or logic low (0x00).
<i>pin2</i>	Value at logic high (0xFF) or logic low (0x00).

Return values

0	Success.
-1	Failure.

Referenced by main().

4.19.2.16 DM75xx_Error DM75xx_ALGDIO_Set_Direction (DM75xx_Board_Descriptor * handle, dm75xx_algdiio_direction_t pin1, dm75xx_algdiio_direction_t pin2)

Set the Analog DIO Direction.

Parameters

<i>handle</i>	Address of the device's library board descriptor.
<i>pin1</i>	Pin1 Direction 0 = Input, Positive vals = Output.
<i>pin2</i>	Pin2 Direction 0 = Input, Positive vals = Output.

Return values

0	Success.
-1	Failure.

Referenced by main().

4.19.2.17 DM75xx_Error DM75xx_ALGDIO_Set_Mask (DM75xx_Board_Descriptor * *handle*, dm75xx_algdio_mask_t *pin1*, dm75xx_algdio_mask_t *pin2*)

Set the Analog DIO Mask.

Parameters

<i>handle</i>	Address of the device's library board descriptor.
<i>pin1</i>	Pin1 mask enabled/disabled.
<i>pin2</i>	Pin2 mask enabled/disabled.

Return values

0	Success.
-1	Failure.

Referenced by main().

4.19.2.18 DM75xx_Error DM75xx_Calibrate (DM75xx_Board_Descriptor * *handle*, uint16_t *dac1_value*, uint16_t *dac2_value*, dm75xx_dac_range_t *dac1_range*, dm75xx_dac_range_t *dac2_range*)

DM75xx_Library_SDM7540_Functions DM75xx user library SDM7540 functions.

DM75xx_Library_STATUS_Functions

Calibrate an SDM7540/SDM8540.

Parameters

<i>handle</i>	Address of the device's library board descriptor.
<i>dac1_value</i>	Value to set on DAC1 after calibration.
<i>dac2_value</i>	Value to set on DAC2 after calibration.
<i>dac1_range</i>	The voltage range by which to calibrate dac1.
<i>dac2_range</i>	The voltage range by which to calibrate dac2.

Return values

0	Success.
-1	Failure.

Referenced by main().

4.19.2.19 DM75xx_Error DM75xx_CLK_Get_Status (DM75xx_Board_Descriptor * *handle*, uint16_t * *status*)

Get status of pacer/burst clocks.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>status</i>	Variable in which to store the current status.

Return values

0	Success.
-1	Failure.

Please see the `ioctl(2)` man page for information on possible values `errno` may have in this case.

4.19.2.20 **DM75xx_Error DM75xx_DAC_Clear** (**DM75xx_Board_Descriptor** * *handle*, **dm75xx_dac_channel_t** *dac*)

Clear a DAC Fifo.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>dac</i>	The specified DAC channel.

Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

4.19.2.21 **DM75xx_Error DM75xx_DAC_FIFO_Write** (**DM75xx_Board_Descriptor** * *handle*, **dm75xx_dac_channel_t** *dac*, **uint16_t** * *data*)

Write a value to the DAC FIFO of a specified channel.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>dac</i>	The specified DAC channel.
<i>data</i>	Value to write to the DAC FIFO.

Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

Referenced by `main()`.

4.19.2.22 **DM75xx_Error DM75xx_DAC_Get_Update_Counter** (**DM75xx_Board_Descriptor** * *handle*, **dm75xx_dac_channel_t** *dac*, **uint16_t** * *data*)

Get DAC update counter for a specified channel.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>dac</i>	The specific DAC channel.
<i>data</i>	Address of the variable to store the data.

Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

Referenced by `main()`.

4.19.2.23 DM75xx_Error DM75xx_DAC_Reset (DM75xx_Board_Descriptor * *handle*, dm75xx_dac_channel_t *dac*)

Reset a DAC Fifo.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>dac</i>	The specified DAC channel.

Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

4.19.2.24 DM75xx_Error DM75xx_DAC_Set_CLK_Mode (DM75xx_Board_Descriptor * *handle*, dm75xx_dac_clk_mode_t *clk_mode*)

Set DAC Clock Mode.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>clk_mode</i>	The mode set the DAC Clock (Free Run or Start/Stop).

Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

Referenced by `main()`.

4.19.2.25 **DM75xx_Error DM75xx_DAC_Set_Clock_Start** (**DM75xx_Board_Descriptor** * *handle*, **dm75xx_dac_clk_start_t** *start*)

Set the DAC Clock Start Value.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>start</i>	The selected clock start value to be written.

Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

Note

This function calls `DM75xx_DAC_Set_Clock()`

Referenced by `main()`.

4.19.2.26 **DM75xx_Error DM75xx_DAC_Set_Clock_Stop** (**DM75xx_Board_Descriptor** * *handle*, **dm75xx_dac_clk_stop_t** *stop*)

Set the DAC Clock Stop Value.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>stop</i>	The selected clock stop value to be written.

Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

Note

This function calls `DM75xx_DAC_Set_Clock()`

Referenced by `main()`.

4.19.2.27 **DM75xx_Error DM75xx_DAC_Set_Count** (**DM75xx_Board_Descriptor** * *handle*, **uint32_t** *count*)

Set the DAC Clock Count.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>count</i>	The value to which to set the DAC Clock Count

Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

Note

This function calls `DM75xx_DAC_Set_Clock()`

4.19.2.28 **DM75xx_Error** `DM75xx_DAC_Set_Frequency (DM75xx_Board_Descriptor * handle, dm75xx_dac_freq_t freq)`

Set the primary slock frequency for DAC conversion.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>freq</i>	The specified primary clock frequency.

Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

Referenced by `main()`.

4.19.2.29 **DM75xx_Error** `DM75xx_DAC_Set_Mode (DM75xx_Board_Descriptor * handle, dm75xx_dac_channel_t dac, dm75xx_dac_mode_t mode)`

Set the DAC mode for a specified channel.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>dac</i>	The specified DAC channel.
<i>mode</i>	The specified mode.

Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

Referenced by `main()`.

4.19.2.30 **DM75xx_Error DM75xx_DAC_Set_Range** (**DM75xx_Board_Descriptor** * *handle*, **dm75xx_dac_channel_t** *dac*, **dm75xx_dac_range_t** *range*)

Set the DAC output range for a specified channel.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>dac</i>	The specified DAC channel.
<i>range</i>	The specified output range.

Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

Referenced by `main()`.

4.19.2.31 **DM75xx_Error DM75xx_DAC_Set_Rate** (**DM75xx_Board_Descriptor** * *handle*, **dm75xx_dac_freq_t** *freq*, **uint32_t** *rate*, **float** * *actualRate*)

Set the DAC conversion rate.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>freq</i>	The specified primary frequency.
<i>rate</i>	The chosen rate for conversion (in Hz).
<i>actualRate</i>	Address of the variable to store the precise rate the clock was set to.

Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

Note

This function calls `DM75xx_DAC_Set_Clock()`

Referenced by `main()`.

4.19.2.32 DM75xx_Error DM75xx_DAC_Set_Update_Counter (DM75xx_Board_Descriptor * *handle*, dm75xx_dac_channel_t *dac*, uint16_t *data*)

Set the DAC update counter for a specified channel.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>dac</i>	The specific DAC channel.
<i>data</i>	The value to write to the DAC update counter

Return values

0	Success.
-1	Failure. Please see the ioctl(2) man page for information on possible values <code>errno</code> may have in this case.

Referenced by main().

4.19.2.33 DM75xx_Error DM75xx_DAC_Set_Update_Source (DM75xx_Board_Descriptor * *handle*, dm75xx_dac_channel_t *dac*, dm75xx_dac_update_src_t *src*)

Set the DAC Update Source for the specified channel.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>dac</i>	The specified DAC channel.
<i>src</i>	The specified update source.

Return values

0	Success.
-1	Failure. Please see the ioctl(2) man page for information on possible values <code>errno</code> may have in this case.

Referenced by main().

4.19.2.34 DM75xx_Error DM75xx_DAC_Setup (DM75xx_Board_Descriptor * *handle*, dm75xx_dac_channel_t *dac*, dm75xx_dac_range_t *range*, dm75xx_dac_update_src_t *src*, dm75xx_dac_mode_t *mode*)

Setup a DAC channel.

Parameters

<i>handle</i>	Address of device's library board descriptor.
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<i>dac</i>	The specified DAC channel.
<i>range</i>	The specified DAC range.
<i>src</i>	The specified DAC update source.
<i>mode</i>	The specified DAC mode.

Return values

<i>0</i>	Success.
<i>-1</i>	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

Referenced by `main()`.

4.19.2.35 **DM75xx_Error DM75xx_DAC_Soft_Update (DM75xx_Board_Descriptor * *handle*, uint8_t *dac*)**

DM75xx_Library_DAC_Functions DM75xx user library digital to analog.

DM75xx_Library_ADC_Functions

Cause a DAC software update on the specified channel.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>dac</i>	The specific DAC channel(s).

Return values

<i>0</i>	Success.
<i>-1</i>	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

4.19.2.36 **DM75xx_Error DM75xx_DAC_Start (DM75xx_Board_Descriptor * *handle*)**

Causes a DAC Software Start.

Parameters

<i>handle</i>	Address of device's library board descriptor.
---------------	---

Return values

<i>0</i>	Success.
<i>-1</i>	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

Note

This function calls `DM75xx_DAC_Set_Clock()`

4.19.2.37 DM75xx_Error DM75xx_DAC_Stop (DM75xx_Board_Descriptor * *handle*)

Causes a DAC Software Stop.

Parameters

<i>handle</i>	Address of device's library board descriptor.
---------------	---

Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

Note

This function calls `DM75xx_DAC_Set_Clock()`

4.19.2.38 DM75xx_Error DM75xx_DCNT_Get_Count (DM75xx_Board_Descriptor * *handle*, uint16_t * *data*)

DM75xx_Library_DCNT_Functions DM75xx user library delay counter.

DM75xx_Library_ACNT_Functions

Get the Delay Counter value.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>data</i>	Address of the variable to store the value.

Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

4.19.2.39 DM75xx_Error DM75xx_DCNT_Set_Count (DM75xx_Board_Descriptor * *handle*, uint16_t *data*)

Set the Delay Counter value.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>data</i>	Value at which to set the Delay Counter.

Return values

0	Success.
-1	Failure. Please see the ioctl(2) man page for information on possible values errno may have in this case.

Referenced by main().

4.19.2.40 DM75xx_Error DM75xx_DIO_Clear_IRQ (DM75xx_Board_Descriptor * *handle*)

Clear Digital I/O IRQ Status.

Parameters

<i>handle</i>	Address of device's library board descriptor.
---------------	---

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

Referenced by ISR().

4.19.2.41 DM75xx_Error DM75xx_DIO_Clock (DM75xx_Board_Descriptor * *handle*, dm75xx_dio_clk_t *clock*)

Set the Digital I/O Sample Clock.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>clock</i>	The clock

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

Referenced by main().

4.19.2.42 DM75xx_Error DM75xx_DIO_Enable_IRQ (DM75xx_Board_Descriptor * *handle*, uint8_t *enable*)

Enable/Disable Digital I/O Interrupts.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>enable</i>	0 for Disable anything else for Enable

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

Referenced by main().

4.19.2.43 DM75xx_Error DM75xx_DIO_Get_Compare (DM75xx_Board_Descriptor * *handle*, uint8_t * *compare*)

Get the compare register for Digital I/O Port 0.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>compare</i>	Address of the variable to store the value in the compare register.

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

Note

This register is used as a latch when in event mode. The value that caused the event will be latched to this register and can subsequently be read.

4.19.2.44 DM75xx_Error DM75xx_DIO_Get_Port (DM75xx_Board_Descriptor * *handle*, dm75xx_dio_port_t *port*, uint8_t * *data*)

Get the value from the specified Digital I/O Port.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>port</i>	The specified Digital I/O Port.
<i>data</i>	The address of the variable to store the Digital I/O Port's value.

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

Referenced by main().

4.19.2.45 DM75xx_Error DM75xx_DIO_Get_Status (DM75xx_Board_Descriptor * *handle*, uint8_t * *data*)

Get the Digital I/O Status byte.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>data</i>	Address of the variable to store the status byte.

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

4.19.2.46 DM75xx_Error DM75xx_DIO_IRQ_Mode (DM75xx_Board_Descriptor * handle, dm75xx_dio_mode_t mode)

Set the IRQ Mode for Digital I/O.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>mode</i>	Set event or match mode IRQ.

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

Referenced by main().

4.19.2.47 DM75xx_Error DM75xx_DIO_Reset (DM75xx_Board_Descriptor * handle)

Clear Digital I/O Chip.

Parameters

<i>handle</i>	Address of device's library board descriptor.
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Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

4.19.2.48 DM75xx_Error DM75xx_DIO_Set_Compare (DM75xx_Board_Descriptor * handle, uint8_t compare)

Set the compare register for Digital I/O Port 0.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>compare</i>	The value to compare for Match Mode.

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

Note

A compare value can only be set for Digital I/O Port 0.

Referenced by ISR(), and main().

4.19.2.49 **DM75xx_Error** DM75xx_DIO_Set_Direction (DM75xx_Board_Descriptor * *handle*, dm75xx_dio_port_t *port*, uint8_t *direction*)

Set the direction of the specified Digital I/O Port.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>port</i>	The specified Digital I/O Port.
<i>direction</i>	The direction to set for the specified Digital I/O Port.

Return values

0	Success.
-1	Failure.

Please see the `ioctl(2)` man page for information on possible values `errno` may have in this case.

Note

Port 0 is bit directional and Port 1 is byte directional.

Referenced by `main()`.

4.19.2.50 **DM75xx_Error DM75xx_DIO_Set_Mask (DM75xx_Board_Descriptor * *handle*, `uint8_t mask`)**

Set Digital I/O Port 0 Mask.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>mask</i>	The mask to set for Digital I/O Port 0.

Return values

0	Success.
-1	Failure.

Please see the `ioctl(2)` man page for information on possible values `errno` may have in this case.

Note

A mask value can only be set for Digital I/O Port 0.

Referenced by `main()`.

4.19.2.51 **DM75xx_Error DM75xx_DIO_Set_Port (DM75xx_Board_Descriptor * *handle*, `dm75xx_dio_port_t port`, `uint8_t data`)**

DM75xx_Library_DIO_Functions DM75xx user library digital input/output.

DM75xx_Library_DCNT_Functions

Set a specified Digital I/O Port to the given value.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>port</i>	The specified Digital I/O Port.
<i>data</i>	The value to set on the Digital I/O Port.

Return values

0	Success.
-1	Failure.

Please see the `ioctl(2)` man page for information on possible values `errno` may have in this case.

Referenced by `main()`.

4.19.2.52 **DM75xx_Error DM75xx_DSP_CMD_Complete** (**DM75xx_Board_Descriptor** * *handle*, **uint8_t** * *data*)

Checks if the last command given to the DSP is finished.

Parameters

<i>handle</i>	Address of the device's library board descriptor.
<i>data</i>	This value will be zero if the DSP has completed the instruction and greater than zero if an instruction is still being executed.

Return values

0	Success.
-1	Failure.

Referenced by main().

4.19.2.53 **DM75xx_Error DM75xx_DSP_CMD_Send (DM75xx_Board_Descriptor * *handle*, dm75xx_dsp_command_t *command*)**

Issue a command to the 7540 onboard DSP.

Parameters

<i>handle</i>	Address of the device's library board descriptor.
<i>command</i>	The DSP Command to issue.

Return values

0	Success.
-1	Failure.

4.19.2.54 **DM75xx_Error DM75xx_DSP_CMD_Status (DM75xx_Board_Descriptor * *handle*, dm75xx_dsp_command_t *command*)**

Checks whether or not a command successfully completed on the DSP.

Parameters

<i>handle</i>	Address of the device's library board descriptor.
<i>command</i>	The DSP command status that is being checked.

Return values

0	Success.
-1	Failure.

Referenced by main().

4.19.2.55 **DM75xx_Error DM75xx_EINT_Polarity_Select (DM75xx_Board_Descriptor * *handle*, dm75xx_ext_polarity_t *polarity*)**

Set the External Interrupt polarity.

Parameters

<i>handle</i>	Address of device's library board descriptor.
---------------	---

<i>polarity</i>	Positive/Negative polarity select.
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Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

Referenced by `main()`.

4.19.2.56 DM75xx_Error DM75xx_ETRIG_Polarity_Select (DM75xx_Board_Descriptor * *handle*, dm75xx_ext_polarity_t *polarity*)

DM75xx_Library_EXT_Functions DM75xx user library external trigger/interrupt.

DM75xx_Library_McBSP_Functions

Set the External Trigger polarity

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>polarity</i>	Positive/Negative polarity select.

Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

Referenced by `main()`.

4.19.2.57 DM75xx_Error DM75xx_FIFO_Get_Status (DM75xx_Board_Descriptor * *handle*, uint16_t * *fifo_status*)

DM75xx_Library_STATUS_Functions DM75xx user library status.

DM75xx_Library_EXT_Functions

Get current FIFO Status

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>fifo_status</i>	Variable in which to store the current status.

Return values

0	Success.
-1	Failure.

Please see the `ioctl(2)` man page for information on possible values `errno` may have in this case.

Referenced by `main()`.

4.19.2.58 **DM75xx_Error DM75xx_Get_Temp** (**DM75xx_Board_Descriptor** * *handle*, **uint8_t** * *temp*)

Get the temperature from the board.

Parameters

<i>handle</i>	Address of the device's library board descriptor.
<i>temp</i>	The temperature returned from the board.

Return values

0	Success
-1	Failure

Referenced by main().

4.19.2.59 DM75xx_Error DM75xx_HSDIN_Clear (DM75xx_Board_Descriptor * *handle*)

Clear High Speed Digital FIFO.

Parameters

<i>handle</i>	Address of device's library board descriptor.
---------------	---

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

Referenced by main().

4.19.2.60 DM75xx_Error DM75xx_HSDIN_FIFO_Read (DM75xx_Board_Descriptor * *handle*, uint16_t * *data*)

Read value from High Speed Digital FIFO.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>data</i>	Address of the variable to store the data.

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

Referenced by main().

4.19.2.61 DM75xx_Error DM75xx_HSDIN_Sample_Signal (DM75xx_Board_Descriptor * *handle*, dm75xx_hsdin_signal_t *signal*)

Set HighSpeed digital sampling signal.

Parameters

<i>handle</i>	Address of device's library board descriptor.
---------------	---

<i>signal</i>	Sampling signal to select.
---------------	----------------------------

Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

Referenced by `main()`.

4.19.2.62 **DM75xx_Error DM75xx_HSDIN_Software_Sample (DM75xx_Board_Descriptor * *handle*)**

DM75xx_Library_HSDIN_Functions DM75xx user library high speed digital.

DM75xx_Library_DAC_Functions

Software high speed digital input sample command

Parameters

<i>handle</i>	Address of device's library board descriptor.
---------------	---

Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

Note

This function calls `DM75xx_DAC_Set_Clock()`

4.19.2.63 **DM75xx_Error DM75xx_McBSP_ADC_FIFO (DM75xx_Board_Descriptor * *handle*, uint8_t *enable*)**

DM75xx_Library_McBSP_Functions DM75xx user library mcbasp.

DM75xx_Library_UIO_Functions

Enable/Disable A/D FIFO to DSP

Parameters

<i>handle</i>	Address of device's library board descriptor
<i>enable</i>	0x00 disables, 0xFF enables

Return values

0	Success
-1	Failure

Please see the `ioctl(2)` man page for information on possible values `errno` may have in this case.

4.19.2.64 **DM75xx_Error DM75xx_McBSP_DAC_FIFO** (**DM75xx_Board_Descriptor** * *handle*, **uint8_t** *enable*)

Enable/Disable D/A FIFO to DSP.

Parameters

<i>handle</i>	Address of device's library board descriptor
<i>enable</i>	0x00 disables, 0xFF enables

Return values

0	Success
-1	Failure

Please see the `ioctl(2)` man page for information on possible values `errno` may have in this case.

4.19.2.65 `DM75xx_Error DM75xx_SBUS_Enable (DM75xx_Board_Descriptor * handle, dm75xx_sbust_t sbus, uint16_t enable)`

Enable/Disable Syncbus.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>sbust</i>	The specified SyncBus.
<i>enable</i>	Value determining whether to enable/disable the syncbus.

Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

4.19.2.66 `DM75xx_Error DM75xx_SBUS_Set_Source (DM75xx_Board_Descriptor * handle, dm75xx_sbust_t sbus, dm75xx_sbust_src_t src)`

DM75xx_Library_SBUS_Functions DM75xx user library syncbus.

DM75xx_Library_HSDIN_Functions

Set SyncBus Source

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>sbust</i>	The specified SyncBus.
<i>src</i>	Source to set for the specified SyncBus.

Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

Referenced by `main()`.

4.19.2.67 **DM75xx_Error** DM75xx_UIO_Read (DM75xx_Board_Descriptor * *handle*, uint32_t * *data*)

Read the current status of the user I/O.

Parameters

<i>handle</i>	Address of device's library board descriptor
<i>data</i>	Address of the variable to store the read value.

Return values

0	Success
-1	Failure

Please see the ioctl(2) man page for information on possible values errno may have in this case.

4.19.2.68 DM75xx_Error DM75xx_UIO_Select (DM75xx_Board_Descriptor * *handle*, dm75xx_uio_channel_t *channel*, dm75xx_uio_source_t *source*)

DM75xx_Library_UIO_Functions DM75xx user library user I/O.

DM75xx_Library_DIO_Functions

Selects the source of a user I/O signal

Parameters

<i>handle</i>	Address of device's library board descriptor
<i>channel</i>	The user output channel on which the signal will be sent
<i>source</i>	The source for the signal

Return values

0	Success
-1	Failure

Please see the ioctl(2) man page for information on possible values errno may have in this case.

Referenced by main().

4.19.2.69 DM75xx_Error DM75xx_UIO_Write (DM75xx_Board_Descriptor * *handle*, uint32_t *data*)

Write the value of the user I/O.

Parameters

<i>handle</i>	Address of device's library board descriptor
<i>data</i>	Value to write to the user I/O

Return values

0	Success
-1	Failure

Please see the ioctl(2) man page for information on possible values errno may have in this case.

4.20 DM75xx user library board control functions

Functions

- **DM75xx_Error DM75xx_Board_PCI_Master** (**DM75xx_Board_Descriptor** *handle, uint8_t *pci_master)
Determine whether or not a device is PCI master capable.
- **DM75xx_Error DM75xx_Board_Reset** (**DM75xx_Board_Descriptor** *handle)
Reset a DM75xx device.
- **DM75xx_Error DM75xx_Clear_ITMask** (**DM75xx_Board_Descriptor** *handle, uint16_t mask)
Clear Interrupts via Mask.
- **DM75xx_Error DM75xx_Clear_IT_Overrun** (**DM75xx_Board_Descriptor** *handle)
Clear Interrupt Overrun Register.
- void **DM75xx_Exit_On_Error** (**DM75xx_Board_Descriptor** *handle, **DM75xx_Error** status, char *str)
Tests the return status of a library function, and if it's an error we clean up the board and exit.
- **DM75xx_Error DM75xx_Board_Init** (**DM75xx_Board_Descriptor** *handle)
Initialize a Board. This function performs the following to attempt to get the device into a known state:
- **DM75xx_Error DM75xx_Interrupt_Enable** (**DM75xx_Board_Descriptor** *handle, dm75xx_int_source_t int_↵ source)
Enable one or more DM75xx interrupt source(s).
- **DM75xx_Error DM75xx_Interrupt_Disable** (**DM75xx_Board_Descriptor** *handle, dm75xx_int_source_t int_↵ source)
Disable one or more DM75xx interrupt source(s).
- **DM75xx_Error DM75xx_Interrupt_Check** (**DM75xx_Board_Descriptor** *handle, dm75xx_int_source_t *int_↵ source)
Returns the value of current active/enabled interrupts on the device.

4.20.1 Detailed Description

4.20.2 Function Documentation

4.20.2.1 DM75xx_Error DM75xx_Board_Init (DM75xx_Board_Descriptor * handle)

Initialize a Board. This function performs the following to attempt to get the device into a known state:

Board Reset Clear A/D FIFO Clear D/A 1 FIFO Clear D/A 2 FIFO Clear High Speed Digital FIFO Clear Channel Gain Table Reset Digital I/O Chip Clear Digital Interrupts Clear Interrupts Clear Interrupt Overrun register

Parameters

<i>handle</i>	Address of device's library board descriptor.
---------------	---

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

Referenced by main().

4.20.2.2 DM75xx_Error DM75xx_Board_PCI_Master (DM75xx_Board_Descriptor * handle, uint8_t * pci_master)

Determine whether or not a device is PCI master capable.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>pci_master</i>	Address where PCI master capable flag should be stored. Zero will be stored here if the device is not PCI master capable. A non-zero value will be stored here if the device is PCI master capable.

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

Referenced by main().

4.20.2.3 DM75xx_Error DM75xx_Board_Reset (DM75xx_Board_Descriptor * handle)

Reset a DM75xx device.

Parameters

<i>handle</i>	Address of device's library board descriptor.
---------------	---

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

Note

This function does not reset the PLX chip or 8254 chips.

Referenced by main().

4.20.2.4 DM75xx_Error DM75xx_Clear_IT_Ovrrun (DM75xx_Board_Descriptor * handle)

Clear Interrupt Overrun Register.

Parameters

<i>handle</i>	Address of device's library board descriptor.
---------------	---

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

4.20.2.5 DM75xx_Error DM75xx_Clear_ITMask (DM75xx_Board_Descriptor * handle, uint16_t mask)

Clear Interrupts via Mask.

Parameters

<i>handle</i>	Address of device's library board descriptor.
---------------	---

<i>mask</i>	Mask of the interrupt bits to clear.
-------------	--------------------------------------

Return values

0	Success.
-1	Failure.

Please see the `ioctl(2)` man page for information on possible values `errno` may have in this case.

4.20.2.6 void DM75xx_Exit_On_Error (DM75xx_Board_Descriptor * *handle*, DM75xx_Error *status*, char * *str*)

Tests the return status of a library function, and if it's an error we clean up the board and exit.

Parameters

<i>handle</i>	Address of the device's library board descriptor.
<i>status</i>	The return status we are testing.
<i>str</i>	The string to print in the case of failure.

Referenced by `ISR()`, `main()`, and `sigint_handler()`.

4.20.2.7 DM75xx_Error DM75xx_Interrupt_Check (DM75xx_Board_Descriptor * *handle*, dm75xx_int_source_t * *int_source*)

Returns the value of current active/enabled interrupts on the device.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>int_source</i>	Address of variable to store the returned interrupt enable status

Return values

0	Success.
-1	Failure.

Please see the `ioctl(2)` man page for information on possible values `errno` may have in this case.

4.20.2.8 DM75xx_Error DM75xx_Interrupt_Disable (DM75xx_Board_Descriptor * *handle*, dm75xx_int_source_t * *int_source*)

Disable one or more DM75xx interrupt source(s).

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>int_source</i>	Interrupt source to disable.

Return values

0	Success.
-1	Failure.

Please see the `ioctl(2)` man page for information on possible values `errno` may have in this case.

Referenced by `main()`.

4.20.2.9 DM75xx_Error DM75xx_Interrupt_Enable (DM75xx_Board_Descriptor * *handle*, dm75xx_int_source_t * *int_source*)

Enable one or more DM75xx interrupt source(s).

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>int_source</i>	Interrupt source to enable.

Return values

<i>0</i>	Success.
<i>-1</i>	Failure.

Please see the `ioctl(2)` man page for information on possible values `errno` may have in this case.

Referenced by `main()`.

4.21 DM75xx user library DMA functions

Functions

- [DM75xx_Error DM75xx_DMA_Buffer_Write](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dma_channel_t](#) channel, unsigned long num_ints)
Copy the User Space buffers data incrementally into our Kernel Space buffer.
- [DM75xx_Error DM75xx_DMA_Buffer_Read](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dma_channel_t](#) channel, unsigned long num_ints)
Copy the Kernel Space buffers data incrementally into our User Space buffer.
- [DM75xx_Error DM75xx_DMA_Buffer_Create](#) ([DM75xx_Board_Descriptor](#) *handle, uint16_t **buffer, [dm75xx_dma_channel_t](#) channel, uint32_t samples)
Create a buffer in which the user should place data from the device's DMA buffers.
- [DM75xx_Error DM75xx_DMA_Buffer_Free](#) ([DM75xx_Board_Descriptor](#) *handle, uint16_t **buffer, [dm75xx_dma_channel_t](#) channel)
Free a buffer previously allocated with [DM75xx_DMA_Buffer_Create\(\)](#).
- [DM75xx_Error DM75xx_DMA_Init_Arb](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dma_channel_t](#) channel, [dm75xx_dma_source_t](#) source, [dm75xx_dma_request_t](#) request, uint32_t samples, uint32_t pci_address)
Set up direct memory access (DMA) for the given DMA/FIFO channel to/from an arbitrary PCI address.
- [DM75xx_Error DM75xx_DMA_Initialize](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dma_channel_t](#) channel, [dm75xx_dma_source_t](#) source, [dm75xx_dma_request_t](#) request, uint32_t samples, uint16_t **buf)
Set up direct memory access (DMA) for the given DMA/FIFO channel.
- [DM75xx_Error DM75xx_DMA_Abort](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dma_channel_t](#) channel)
Abort any active transfer on the specified DMA channel.
- [DM75xx_Error DM75xx_DMA_Enable](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dma_channel_t](#) channel, uint8_t enable)
Set the enable bit for a particular DMA channel. To start DMA after this, call [DM75xx_DMA_Start\(\)](#).
- [DM75xx_Error DM75xx_DMA_Request_Source](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dma_channel_t](#) channel, [dm75xx_dma_request_t](#) request)
Set the demand mode request source for a specified DMA channel.
- [DM75xx_Error DM75xx_DMA_Start](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dma_channel_t](#) channel)
Sets the start bit for a particular DMA Channel. DMA will start if the enable bit has been set by [DM75xx_DMA_Enable\(\)](#).

4.21.1 Detailed Description

DM75xx_Library_BrdCtl_Functions

4.21.2 Function Documentation

4.21.2.1 [DM75xx_Error DM75xx_DMA_Abort](#) ([DM75xx_Board_Descriptor](#) * handle, [dm75xx_dma_channel_t](#) channel)

Abort any active transfer on the specified DMA channel.

Parameters

<i>handle</i>	Address of device's library board descriptor.
---------------	---

<i>channel</i>	The channel on which to abort DMA transfer.
----------------	---

Return values

0	Success
-1	Failure

Referenced by main().

4.21.2.2 **DM75xx_Error DM75xx_DMA_Buffer_Create** (**DM75xx_Board_Descriptor** * *handle*, uint16_t ** *buffer*, **dm75xx_dma_channel_t** *channel*, uint32_t *samples*)

Create a buffer in which the user should place data from the device's DMA buffers.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>buffer</i>	Address of the pointer which create for the user.
<i>channel</i>	The DMA channel for which to create a user-space buffer.
<i>samples</i>	The size of the buffer required in samples.

Return values

0	Success.
-1	Failure.

Note

This function MUST be called if you are planning on use the `DMA_Buffer_Read()` or `DMA_Buffer_Write()` function calls to manage your DMA data.

Referenced by main().

4.21.2.3 **DM75xx_Error DM75xx_DMA_Buffer_Free** (**DM75xx_Board_Descriptor** * *handle*, uint16_t ** *buffer*, **dm75xx_dma_channel_t** *channel*)

Free a buffer previously allocated with `DM75xx_DMA_Buffer_Create()`.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>buffer</i>	Address of the pointer which to free.
<i>channel</i>	The DMA Channel's buffer we want to free.

Return values

0	Success.
-1	Failure.

Note

This function MUST be called if you are planning on use the `DMA_Buffer_Read()` or `DMA_Buffer_Write()` function calls to manage your DMA data.

Referenced by main().

4.21.2.4 **DM75xx_Error DM75xx_DMA_Buffer_Read** (**DM75xx_Board_Descriptor** * *handle*, **dm75xx_dma_channel_t** *channel*, unsigned long *num_ints*)

Copy the Kernel Space buffers data incrementally into our User Space buffer.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>channel</i>	The DMA Channel on which to perform the operation.
<i>num_ints</i>	Number of DMA interrupt received, this helps us keep track of our place in the buffer.

Return values

0	Success
-1	Failure

Note

Use this function if you would like the library to handle your DMA buffer reads. This function effectively copies from the buffer mapped to the kernel dma buffer by `DMA_Initialize()` into the buffer allocated by `DMA_Buffer_Create()`.

This function must be used in conjunction with `DMA_Buffer_Create()` and `DMA_Buffer_Free()`.

The user is more than welcome to manage the buffers via `memcpy()`.

Referenced by `main()`.

4.21.2.5 DM75xx_Error DM75xx_DMA_Buffer_Write (DM75xx_Board_Descriptor * handle, dm75xx_dma_channel_t channel, unsigned long num_ints)

Copy the User Space buffers data incrementally into our Kernel Space buffer.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>channel</i>	The DMA Channel on which to perform the operation.
<i>num_ints</i>	Number of DMA interrupt received, this helps us keep track of our place in the buffer

Return values

0	Success
-1	

Note

Use this function if you would like the library to handle your DMA buffer writes. This function effectively copies to the buffer mapped to the kernel dma buffer by `DMA_Initialize()` into the buffer allocated by `DMA_Buffer_Create()`.

This function must be used in conjunction with `DMA_Buffer_Create()` and `DMA_Buffer_Free()`.

The user is more than welcome to manage the buffers via `memcpy()`.

Referenced by `main()`.

4.21.2.6 DM75xx_Error DM75xx_DMA_Enable (DM75xx_Board_Descriptor * handle, dm75xx_dma_channel_t channel, uint8_t enable)

Set the enable bit for a particular DMA channel. To start DMA after this, call [DM75xx_DMA_Start\(\)](#).

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>channel</i>	The DMA channel to enable on the specified device.
<i>enable</i>	0 for disable, > 0 for enable

Returns

0

Success.

Returns

-1

Failure.

Referenced by main().

4.21.2.7 DM75xx_Error DM75xx_DMA_Init_Arb (DM75xx_Board_Descriptor * *handle*, dm75xx_dma_channel_t *channel*, dm75xx_dma_source_t *source*, dm75xx_dma_request_t *request*, uint32_t *samples*, uint32_t *pci_address*)

Set up direct memory access (DMA) for the given DMA/FIFO channel to/from an arbitrary PCI address.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>channel</i>	The DMA channel to use.
<i>source</i>	The FIFO to/from which DMA will be used.
<i>request</i>	The DREQ line source.
<i>samples</i>	The number of samples desired from the FIFO via DMA. For HD DMA, this value is required to be a multiple of half the FIFO size of the board. This is a limitation of the UTC1 DREQ source used for HD DMA.
<i>pci_address</i>	The PCI Address to transfer to/from.

Return values

0	Success.
-1	Failure. errno may be set as follows: <ul style="list-style-type: none"> • EAGAIN DMA has already been initialized for fifo. • EINVAL fifo is not valid. • ENOMEM Kernel memory allocation failed. • EOPNOTSUPP The device is not PCI master capable. Please see the ioctl(2) man page for information on other possible values errno may have in this case.

Note

When using DMA to/from arbitrary PCI addresses, no kernel buffer is allocated for DMA. DMA to arbitrary PCI addresses can cause unknown behavior if you are not careful about what you are doing. As the application designer, you have some flexibility to configure DMA as as your purpose suits. However, if this function fails with errno ENOMEM, you need to allocate smaller buffers.

Referenced by main().

4.21.2.8 DM75xx_Error DM75xx_DMA_Initialize (DM75xx_Board_Descriptor * *handle*, dm75xx_dma_channel_t *channel*, dm75xx_dma_source_t *source*, dm75xx_dma_request_t *request*, uint32_t *samples*, uint16_t ** *buf*)

Set up direct memory access (DMA) for the given DMA/FIFO channel.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>channel</i>	The DMA channel to use.
<i>source</i>	The FIFO to/from which DMA will be used.
<i>request</i>	The DREQ line source.
<i>samples</i>	The number of samples desired from the FIFO via DMA. For HD DMA, this value is required to be a multiple of half the FIFO size of the board. This is a limitation of the UTC1 DREQ source used for HD DMA.
<i>buf</i>	The user space buffer which will be mapped to the kernel space DMA buffer

Return values

0	Success.
-1	Failure. errno may be set as follows: <ul style="list-style-type: none"> • EAGAIN DMA has already been initialized for fifo. • EINVAL fifo is not valid. • ENOMEM Kernel memory allocation failed. • EOPNOTSUPP The device is not PCI master capable. Please see the ioctl(2) man page for information on other possible values errno may have in this case.

Note

Since a single DMA buffer must exist in physically contiguous memory, the probability of DMA buffer allocation failure increases as both the number of buffers to allocate and the size of each buffer increase.

Factors beyond the number and size of DMA buffers affect the probability of DMA buffer allocation failure. These factors include the number of processes on the system, how much system memory is already in use, and the presence of processes (such as the X server) which use a lot of memory.

System memory can be a scarce resource. Every system entity needs some amount of memory. Memory is being allocated and released all the time.

The default value for DM75xx_MAX_DMA_BUFFER_SIZE is 131,072 bytes (128 kilobytes or 65k samples). If you need to change this, edit [include/dm75xx_driver.h](#), save the changes, recompile the driver, and reload the driver.

As the application designer, you have some flexibility to configure DMA as as your purpose suits. However, if this function fails with errno ENOMEM, you need to allocate smaller buffers.

This function also maps a user space buffer to the kernel memory buffer allocated for DMA. This was done to prevent successive calls to copy_to_user() or copy_from_user() as both of these functions will sleep if the user space buffer was paged out.

Referenced by main().

4.21.2.9 DM75xx_Error DM75xx_DMA_Request_Source (DM75xx_Board_Descriptor * *handle*, dm75xx_dma_channel_t *channel*, dm75xx_dma_request_t *request*)

Set the demand mode request source for a specified DMA channel.

Parameters

<i>handle</i>	Address of the device's library board descriptor.
<i>channel</i>	The specified channel for which to set the request source.
<i>request</i>	The demand mode request source to set.

Returns

0

Success

Returns

-1

Failure

4.21.2.10 **DM75xx_Error DM75xx_DMA_Start (DM75xx_Board_Descriptor * *handle*, dm75xx_dma_channel_t *channel*)**

Sets the start bit for a particular DMA Channel. DMA will start if the enable bit has been set by [DM75xx_DMA_↔Enable\(\)](#).

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>channel</i>	The DMA channel to start on the specified device.

Returns

0

Success.

Returns

-1

Failure.

Referenced by main().

4.22 DM75xx user library general functions

Functions

- [DM75xx_Error DM75xx_Board_Close](#) ([DM75xx_Board_Descriptor](#) *handle)
Close a DM75xx device file.
- [DM75xx_Error DM75xx_Board_Open](#) (uint8_t dev_num, [DM75xx_Board_Descriptor](#) **handle)
Open a DM75xx device file.
- [DM75xx_Error DM75xx_FIFO_Size](#) ([DM75xx_Board_Descriptor](#) *handle, unsigned int *data)
Retrieve the FIFO size of the board from the kernel space device descriptor.
- [DM75xx_Error DM75xx_Board_Type](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_board_t](#) *data)
Determine the family of the board (DM7520 or SDM7540/8540).
- [DM75xx_Error DM75xx_InstallISR](#) ([DM75xx_Board_Descriptor](#) *handle, void(*isr_fnct)(unsigned int status))
Install userspace ISR.
- [DM75xx_Error DM75xx_RemoveISR](#) ([DM75xx_Board_Descriptor](#) *handle)
Uninstall userspace ISR.
- void * [DM75xx_WaitForInterrupt](#) (void *ptr)
Function that will have its own thread and wait for interrupts to occur. Once an interrupt is received this function will call our callback ISR and pass it the interrupt status.

4.22.1 Detailed Description

DM75xx_Library_DMA_Functions

4.22.2 Function Documentation

4.22.2.1 [DM75xx_Error DM75xx_Board_Close](#) ([DM75xx_Board_Descriptor](#) * handle)

Close a DM75xx device file.

Parameters

<i>handle</i>	Address of device's library board descriptor.
---------------	---

Return values

0	Success.
-1	Failure. errno may be set as follows: <ul style="list-style-type: none"> • ENODATA handle is NULL. Please see the close(2) man page for information on other possible values errno may have in this case.

Note

This function frees the memory allocated for the library board descriptor.
When processing the close request, the driver disables PLX PCI interrupts, disables PLX local interrupt input, and disables PLX DMA channel 0/1 interrupts.

Warning

Whether or not this function succeeds, the library board descriptor must not be referenced in any way after the function returns.

Referenced by main().

4.22.2.2 DM75xx_Error DM75xx_Board_Open (uint8_t dev_num, DM75xx_Board_Descriptor ** handle)

Open a DM75xx device file.

Parameters

<i>dev_num</i>	Minor number of DM75xx device file.
<i>handle</i>	Address where address of memory allocated for library device descriptor should be stored. If the first open of a device file fails, then NULL will be stored here.

Return values

0	Success.
-1	Failure. errno may be set as follows: <ul style="list-style-type: none"> • EBUSY The DM75xx device file with minor number dev_num is already open. • ENODEV dev_num is not a valid DM75xx minor number; 2.4 kernel only. • ENOMEM Library device descriptor memory allocation failed. • ENXIO dev_num is not a valid DM75xx minor number; 2.6 kernel only. Please see the open(2) man page for information on other possible values errno may have in this case.

Note

Once a device file is open, it cannot be opened again until it is closed.

When processing the open request, the driver disables & clears all device interrupts, enables PLX PC↔I interrupts, enables PLX local interrupt input, and enables PLX DMA channel 0/1 interrupts.

Referenced by main().

4.22.2.3 DM75xx_Error DM75xx_Board_Type (DM75xx_Board_Descriptor * handle, dm75xx_board_t * data)

Determine the family of the board (DM7520 or SDM7540/8540).

Parameters

<i>handle</i>	Address of the device's library board descriptor.
<i>data</i>	This value will be returned as 0 if the board is a DM7520 or a positive value if the board is an SDM7540/8540.

Return values

0	Success
-1	Failure

4.22.2.4 DM75xx_Error DM75xx_FIFO_Size (DM75xx_Board_Descriptor * handle, unsigned int * data)

Retrieve the FIFO size of the board from the kernel space device descriptor.

Parameters

<i>handle</i>	Address of the device's library board descriptor.
<i>data</i>	Address of the variable in which to store the fifo size.

Return values

0	Success
-1	Failure

Note

This function does not calculate the value of the FIFO upon each call. The FIFO size is determined at 'insmod' time and is stored in the drivers device descriptor.

Referenced by main().

4.22.2.5 DM75xx_Error DM75xx_InstallISR (DM75xx_Board_Descriptor * *handle*, void(*) (unsigned int status) *isr_fnc*)

Install userspace ISR.

Parameters

<i>handle</i>	Address of the device's library board descriptor.
<i>isr_fnc</i>	Function pointer to the user ISR that will be called in the event of an interrupt

Return values

0	Success
-1	Failure

Note

Any previously installed ISR will be removed before installing a new ISR
 This function creates another thread that runs [DM75xx_WaitForInterrupt\(\)](#). This thread is removed by a call to [DM75xx_RemoveISR\(\)](#).

Referenced by main().

4.22.2.6 DM75xx_Error DM75xx_RemoveISR (DM75xx_Board_Descriptor * *handle*)

Uninstall userspace ISR.

Parameters

<i>handle</i>	Address of the device's library board descriptor.
---------------	---

Return values

0	Success
-1	Failure

Note

This function makes an ioctl call into the kernel which makes a call to wake the thread from the select() call.

Referenced by main().

4.22.2.7 void* DM75xx_WaitForInterrupt (void * *ptr*)

Function that will have its own thread and wait for interrupts to occur. Once an interrupt is received this function will call our callback ISR and pass it the interrupt status.

Parameters

<i>ptr</i>	Pointer to be typecasted to the device handle.
------------	--

Return values

0	Success
-1	Failure

Note

This function should not be called directly by the user.

4.23 DM75xx user library user timer/counter control

Functions

- [DM75xx_Error DM75xx_UTC_Set_Clock_Source](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_utc_timer_t](#) utc, [dm75xx_utc_clk_t](#) source)
Set a User Timer/Counter Clock Source.
- [DM75xx_Error DM75xx_UTC_Set_Gate](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_utc_timer_t](#) utc, [dm75xx_utc_gate](#) gate)
Set a User Timer/Counter Gate.
- [DM75xx_Error DM75xx_UTC_Set_Mode](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_utc_timer_t](#) utc, [dm75xx_utc_mode](#) mode)
Set a User Timer/Counter Mode.
- [DM75xx_Error DM75xx_UTC_Get_Mode](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_utc_timer_t](#) utc, [uint16_t](#) *mode)
Set a User Timer/Counter Mode.
- [DM75xx_Error DM75xx_UTC_Set_Divisor](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_utc_timer_t](#) utc, [uint16_t](#) rate)
Set a User Timer/Counter Divisor.
- [DM75xx_Error DM75xx_UTC_Get_Count](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_utc_timer_t](#) utc, [uint16_t](#) *count)
Return current value of a User Timer/Counter.
- [DM75xx_Error DM75xx_UTC_Get_Status](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_utc_timer_t](#) utc, [select](#), [uint8_t](#) *utc_status)
Return current status of a User Timer/Counter.
- [DM75xx_Error DM75xx_UTC_Setup](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_utc_timer_t](#) utc, [dm75xx_utc_clk_t](#) source, [dm75xx_utc_gate](#) gate, [dm75xx_utc_mode](#) mode, [uint16_t](#) divisor)
Setup a User Timer/Counter.

4.23.1 Detailed Description

DM75xx_Library_General_Functions

4.23.2 Function Documentation

4.23.2.1 [DM75xx_Error DM75xx_UTC_Get_Count](#) ([DM75xx_Board_Descriptor](#) * handle, [dm75xx_utc_timer_t](#) utc, [uint16_t](#) * count)

Return current value of a User Timer/Counter.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>utc</i>	User Timer/Counter we are configuring.
<i>count</i>	Variable to store the current count in.

Return values

0	Success.
-1	Failure.

Please see the `ioctl(2)` man page for information on possible values `errno` may have in this case.

Referenced by `main()`.

4.23.2.2 **DM75xx_Error** DM75xx_UTC_Get_Mode (DM75xx_Board_Descriptor * *handle*, dm75xx_utc_timer_t *utc*,
uint16_t * *mode*)

Set a User Timer/Counter Mode.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>utc</i>	Which user timer/counter's mode to read.
<i>mode</i>	Variable to store the retrieved mode value.

Return values

0	Success.
-1	Failure.

Please see the `ioctl(2)` man page for information on possible values `errno` may have in this case.

Referenced by `main()`.

4.23.2.3 **DM75xx_Error** DM75xx_UTC_Get_Status (DM75xx_Board_Descriptor * *handle*, dm75xx_utc_timer_t *utc_select*, uint8_t * *utc_status*)

Return current status of a User Timer/Counter.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>utc_select</i>	User Timer/Counter we are configuring.
<i>utc_status</i>	Variable to store the current status in.

Return values

0	Success.
-1	Failure.

Please see the `ioctl(2)` man page for information on possible values `errno` may have in this case.

Referenced by `main()`.

4.23.2.4 **DM75xx_Error** DM75xx_UTC_Set_Clock_Source (DM75xx_Board_Descriptor * *handle*, dm75xx_utc_timer_t *utc*, dm75xx_utc_clk_t *source*)

Set a User Timer/Counter Clock Source.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>utc</i>	User Timer/Counter we are configuring.
<i>source</i>	The User Timer/Counter source to be set.

Return values

0	Success.
-1	Failure.

Please see the `ioctl(2)` man page for information on possible values `errno` may have in this case.

Referenced by `main()`.

4.23.2.5 **DM75xx_Error** DM75xx_UTC_Set_Divisor (DM75xx_Board_Descriptor * *handle*, dm75xx_utc_timer_t *utc*, uint16_t *rate*)

Set a User Timer/Counter Divisor.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>utc</i>	User Timer/Counter we are configuring.
<i>rate</i>	The rate to set for this User Timer/Counter

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

Referenced by main().

4.23.2.6 DM75xx_Error DM75xx_UTC_Set_Gate (DM75xx_Board_Descriptor * *handle*, dm75xx_utc_timer_t *utc*, dm75xx_utc_gate *gate*)

Set a User Timer/Counter Gate.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>utc</i>	User Timer/Counter we are configuring.
<i>gate</i>	The User Timer/Counter gate option.

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

Referenced by main().

4.23.2.7 DM75xx_Error DM75xx_UTC_Set_Mode (DM75xx_Board_Descriptor * *handle*, dm75xx_utc_timer_t *utc*, dm75xx_utc_mode *mode*)

Set a User Timer/Counter Mode.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>utc</i>	User Timer/Counter we are configuring.
<i>mode</i>	The User Timer/Counter mode to be set.

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

Referenced by main().

4.23.2.8 DM75xx_Error DM75xx_UTC_Setup (DM75xx_Board_Descriptor * *handle*, dm75xx_utc_timer_t *utc*, dm75xx_utc_clk_t *source*, dm75xx_utc_gate *gate*, dm75xx_utc_mode *mode*, uint16_t *divisor*)

Setup a User Timer/Counter.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>utc</i>	User Timer/Counter we are configuring.
<i>source</i>	The User Timer/Counter source to be set.
<i>gate</i>	The User Timer/Counter gate option to set.
<i>mode</i>	The User Timer/Counter mode option to set.
<i>divisor</i>	The divisor to set the User Timer/Counter with.

Return values

<i>0</i>	Success.
<i>-1</i>	Failure.

Please see the `ioctl(2)` man page for information on possible values `errno` may have in this case.

Referenced by `main()`.

4.24 DM75xx user library burst clock control

Functions

- `DM75xx_Error DM75xx_BCLK_Get_Count (DM75xx_Board_Descriptor *handle, uint16_t *data)`
Get the current Burst Clock count.
- `DM75xx_Error DM75xx_BCLK_Set_Count (DM75xx_Board_Descriptor *handle, uint16_t data)`
Set the current Burst Clock count.
- `DM75xx_Error DM75xx_BCLK_Set_Rate (DM75xx_Board_Descriptor *handle, dm75xx_bclk_freq_t freq, float rate, float *actualRate)`
Set the Burst Clock rate.
- `DM75xx_Error DM75xx_BCLK_Set_Start (DM75xx_Board_Descriptor *handle, dm75xx_bclk_start_t start)`
Set Burst Clock start trigger.
- `DM75xx_Error DM75xx_BCLK_Set_Frequency (DM75xx_Board_Descriptor *handle, dm75xx_bclk_freq_t freq)`
Set the Burst Clock primary frequency.
- `DM75xx_Error DM75xx_BCLK_Setup (DM75xx_Board_Descriptor *handle, dm75xx_bclk_start_t start, dm75xx_bclk_freq_t freq, float rate, float *actualRate)`
Setup Burst Clock.

4.24.1 Detailed Description

DM75xx_Library_UTC_Funtions

4.24.2 Function Documentation

4.24.2.1 DM75xx_Error DM75xx_BCLK_Get_Count (DM75xx_Board_Descriptor * handle, uint16_t * data)

Get the current Burst Clock count.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>data</i>	Address of the variable to store the value.

Return values

0	Success.
-1	Failure.

Please see the `ioctl(2)` man page for information on possible values `errno` may have in this case.

4.24.2.2 DM75xx_Error DM75xx_BCLK_Set_Count (DM75xx_Board_Descriptor * handle, uint16_t data)

Set the current Burst Clock count.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>data</i>	Value to write to the Burst Clock count.

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

4.24.2.3 DM75xx_Error DM75xx_BCLK_Set_Frequency (DM75xx_Board_Descriptor * *handle*, dm75xx_bclk_freq_t *freq*)

Set the Burst Clock primary frequency.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>freq</i>	Frequency to select.

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

4.24.2.4 DM75xx_Error DM75xx_BCLK_Set_Rate (DM75xx_Board_Descriptor * *handle*, dm75xx_bclk_freq_t *freq*, float *rate*, float * *actualRate*)

Set the Burst Clock rate.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>freq</i>	Set the Burst Clock primary frequency.
<i>rate</i>	The desired Burst Clock rate.
<i>actualRate</i>	The actual rate set.

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

Referenced by main().

4.24.2.5 DM75xx_Error DM75xx_BCLK_Set_Start (DM75xx_Board_Descriptor * *handle*, dm75xx_bclk_start_t *start*)

Set Burst Clock start trigger.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>start</i>	Start trigger to set.

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

Referenced by main().

4.24.2.6 `DM75xx_Error DM75xx_BCLK_Setup (DM75xx_Board_Descriptor * handle, dm75xx_bclk_start_t start, dm75xx_bclk_freq_t freq, float rate, float * actualRate)`

Setup Burst Clock.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>start</i>	Burst Clock start trigger.
<i>freq</i>	Burst Clock primary frequency.
<i>rate</i>	Rate at which to set the clock.
<i>actualRate</i>	Rate at which the clock is actually set.

Return values

<i>0</i>	Success.
<i>-1</i>	Failure.

Please see the `ioctl(2)` man page for information on possible values `errno` may have in this case.

Referenced by `main()`.

4.25 DM75xx user library pacer clock control

Functions

- [DM75xx_Error DM75xx_PCLK_Set_Frequency](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_pclk_freq_t](#) pclk_freq)
Set the Pacer Clock frequency.
- [DM75xx_Error DM75xx_PCLK_Set_Source](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_pclk_select_t](#) pclk_select)
Set the Pacer Clock source.
- [DM75xx_Error DM75xx_PCLK_Set_Start](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_pclk_start_t](#) pclk_start)
Set the Pacer Clock start trigger.
- [DM75xx_Error DM75xx_PCLK_Set_Stop](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_pclk_stop_t](#) pclk_stop)
Set the Pacer Clock stop trigger.
- [DM75xx_Error DM75xx_PCLK_Read](#) ([DM75xx_Board_Descriptor](#) *handle, [uint32_t](#) *pacer_value)
Read the current pacer clock value.
- [DM75xx_Error DM75xx_PCLK_Set_Trigger_Mode](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_pclk_mode_t](#) pclk_mode)
Set the Pacer Clock trigger mode.
- [DM75xx_Error DM75xx_PCLK_Set_Count](#) ([DM75xx_Board_Descriptor](#) *handle, [uint32_t](#) count)
Set the Pacer Clock Count.
- [DM75xx_Error DM75xx_PCLK_Set_Rate](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_pclk_freq_t](#) freq, float rate, float *actualRate)
Set the Pacer Clock Rate.
- [DM75xx_Error DM75xx_PCLK_Setup](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_pclk_select_t](#) pclk_select, [dm75xx_pclk_freq_t](#) pclk_freq, [dm75xx_pclk_mode_t](#) pclk_mode, [dm75xx_pclk_start_t](#) pclk_start, [dm75xx_pclk_stop_t](#) pclk_stop, float rate, float *actualRate)
Setup the Pacer Clock.
- [DM75xx_Error DM75xx_PCLK_Start](#) ([DM75xx_Board_Descriptor](#) *handle)
Software Pacer Clock Start.
- [DM75xx_Error DM75xx_PCLK_Stop](#) ([DM75xx_Board_Descriptor](#) *handle)
Software Pacer Clock Stop.

4.25.1 Detailed Description

DM75xx_Library_BCLK_Funtions

4.25.2 Function Documentation

4.25.2.1 DM75xx_Error DM75xx_PCLK_Read ([DM75xx_Board_Descriptor](#) * handle, [uint32_t](#) * pacer_value)

Read the current pacer clock value.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>pacer_value</i>	Address of the variable to store the value of the pacer

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

4.25.2.2 DM75xx_Error DM75xx_PCLK_Set_Count (DM75xx_Board_Descriptor * *handle*, uint32_t *count*)

Set the Pacer Clock Count.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>count</i>	Pacer Clock count

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

4.25.2.3 DM75xx_Error DM75xx_PCLK_Set_Frequency (DM75xx_Board_Descriptor * *handle*, dm75xx_pclk_freq_t *pclk_freq*)

Set the Pacer Clock frequency.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>pclk_freq</i>	Frequency to set for the pacer clock.

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

Referenced by main().

4.25.2.4 DM75xx_Error DM75xx_PCLK_Set_Rate (DM75xx_Board_Descriptor * *handle*, dm75xx_pclk_freq_t *freq*, float *rate*, float * *actualRate*)

Set the Pacer Clock Rate.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>freq</i>	Pacer Clock primary frequency.
<i>rate</i>	Rate desired or the Pacer Clock.
<i>actualRate</i>	Address to store the actual rate value.

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

Referenced by main().

4.25.2.5 **DM75xx_Error** DM75xx_PCLK_Set_Source (DM75xx_Board_Descriptor * *handle*, dm75xx_pclk_select_t *pclk_select*)

Set the Pacer Clock source.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>pclk_select</i>	Source for the Pacer Clock

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

Referenced by main().

4.25.2.6 **DM75xx_Error DM75xx_PCLK_Set_Start** (**DM75xx_Board_Descriptor** * *handle*, **dm75xx_pclk_start_t** *pclk_start*)

Set the Pacer Clock start trigger.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>pclk_start</i>	Start trigger for the Pacer Clock

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

Referenced by main().

4.25.2.7 **DM75xx_Error DM75xx_PCLK_Set_Stop** (**DM75xx_Board_Descriptor** * *handle*, **dm75xx_pclk_stop_t** *pclk_stop*)

Set the Pacer Clock stop trigger.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>pclk_stop</i>	Stop trigger for the Pacer Clock

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

Referenced by main().

4.25.2.8 **DM75xx_Error DM75xx_PCLK_Set_Trigger_Mode** (**DM75xx_Board_Descriptor** * *handle*, **dm75xx_pclk_mode_t** *pclk_mode*)

Set the Pacer Clock trigger mode.

Parameters

<i>handle</i>	Address of device's library board descriptor.
---------------	---

<i>pclk_mode</i>	Mode in which to set the pacer clock.
------------------	---------------------------------------

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

Referenced by main().

4.25.2.9 DM75xx_Error DM75xx_PCLK_Setup (DM75xx_Board_Descriptor * handle, dm75xx_pclk_select_t pclk_select, dm75xx_pclk_freq_t pclk_freq, dm75xx_pclk_mode_t pclk_mode, dm75xx_pclk_start_t pclk_start, dm75xx_pclk_stop_t pclk_stop, float rate, float * actualRate)

Setup the Pacer Clock.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>pclk_select</i>	Select Internal/External Pacer Clock.
<i>pclk_freq</i>	Select the primary clock frequency.
<i>pclk_mode</i>	Select the trigger mode.
<i>pclk_start</i>	Select the start trigger.
<i>pclk_stop</i>	Select the stop trigger.
<i>rate</i>	Desired rate for the Pacer Clock.
<i>actualRate</i>	Rate actually set.

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

Referenced by main().

4.25.2.10 DM75xx_Error DM75xx_PCLK_Start (DM75xx_Board_Descriptor * handle)

Software Pacer Clock Start.

Parameters

<i>handle</i>	Address of device's library board descriptor.
---------------	---

Return values

0	Success.
-1	Failure.

Please see the ioctl(2) man page for information on possible values errno may have in this case.

Referenced by main().

4.25.2.11 DM75xx_Error DM75xx_PCLK_Stop (DM75xx_Board_Descriptor * handle)

Software Pacer Clock Stop.

Parameters

<i>handle</i>	Address of device's library board descriptor.
---------------	---

Return values

0	Success.
-1	Failure.

Please see the `ioctl(2)` man page for information on possible values `errno` may have in this case.

Referenced by `main()`.

4.26 DM75xx user library channel gain table

Functions

- [DM75xx_Error DM75xx_CGT_Reset](#) ([DM75xx_Board_Descriptor](#) *handle)
Reset Channel Gain Table.
- [DM75xx_Error DM75xx_CGT_Clear](#) ([DM75xx_Board_Descriptor](#) *handle)
Clear Channel Gain Table.
- [DM75xx_Error DM75xx_CGT_Create_Entry](#) ([dm75xx_cgt_entry_t](#) *cgt, [uint16_t](#) *cgt_entry)
Create a channel gain table entry.
- [DM75xx_Error DM75xx_CGT_Write](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_cgt_entry_t](#) cgt)
Write a channel gain table entry. This function utilizes [DM75xx_CGT_Create_Entry\(\)](#) to create the 16 bit entry.
- [DM75xx_Error DM75xx_CGT_Latch](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_cgt_entry_t](#) cgt)
Write ADC channel gain table latch for single channel sampling.
- [DM75xx_Error DM75xx_CGT_Enable](#) ([DM75xx_Board_Descriptor](#) *handle, [uint16_t](#) enable)
Enable/disable A/D channel gain table.
- [DM75xx_Error DM75xx_DT_Enable](#) ([DM75xx_Board_Descriptor](#) *handle, [uint16_t](#) enable)
Enable/disable Digital Table.
- [DM75xx_Error DM75xx_DT_Write_Entry](#) ([DM75xx_Board_Descriptor](#) *handle, [uint8_t](#) data)
Write Digital Table entry.
- [DM75xx_Error DM75xx_CGT_Pause](#) ([DM75xx_Board_Descriptor](#) *handle, [uint16_t](#) pause)
Pause the Channel Gain Table.

4.26.1 Detailed Description

DM75xx_Library_PCLK_Functions

4.26.2 Function Documentation

4.26.2.1 [DM75xx_Error DM75xx_CGT_Clear](#) ([DM75xx_Board_Descriptor](#) * handle)

Clear Channel Gain Table.

Parameters

<i>handle</i>	Address of device's library board descriptor.
---------------	---

Return values

0	Success.
-1	Failure.

Please see the `ioctl(2)` man page for information on possible values `errno` may have in this case.

4.26.2.2 [DM75xx_Error DM75xx_CGT_Create_Entry](#) ([dm75xx_cgt_entry_t](#) * cgt, [uint16_t](#) * cgt_entry)

Create a channel gain table entry.

Parameters

<i>cgt</i>	Struct that holds the values for the channel gain table.
------------	--

<i>cgt_entry</i>	The channel gain table converted to a uint16_t for register entry.
------------------	--

Return values

0	Success.
-1	Failure.

Note

This function should not be called by the user.

4.26.2.3 DM75xx_Error DM75xx_CGT_Enable (DM75xx_Board_Descriptor * handle, uint16_t enable)

Enable/disable A/D channel gain table.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>enable</i>	A 0 denotes CGT Disable and CG Latch Enable, a 1 denotes CGT Enable and CG Latch Disable.

Return values

0	Success.
-1	Failure. Please see the ioctl(2) man page for information on possible values errno may have in this case.

Referenced by main().

4.26.2.4 DM75xx_Error DM75xx_CGT_Latch (DM75xx_Board_Descriptor * handle, dm75xx_cgt_entry_t cgt)

Write ADC channel gain table latch for single channel sampling.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>cgt</i>	Channel gain table entry to write to the latch.

Return values

0	Success.
-1	Failure. Please see the ioctl(2) man page for information on possible values errno may have in this case.

Referenced by main().

4.26.2.5 DM75xx_Error DM75xx_CGT_Pause (DM75xx_Board_Descriptor * handle, uint16_t pause)

Pause the Channel Gain Table.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>pause</i>	Enable/Disable CGT Pause.

Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

Note

Pause is ignored in burst mode.

4.26.2.6 DM75xx_Error DM75xx_CGT_Reset (DM75xx_Board_Descriptor * *handle*)

Reset Channel Gain Table.

Parameters

<i>handle</i>	Address of device's library board descriptor.
---------------	---

Return values

0	Success.
-1	Failure.

Please see the `ioctl(2)` man page for information on possible values `errno` may have in this case.

4.26.2.7 DM75xx_Error DM75xx_CGT_Write (DM75xx_Board_Descriptor * *handle*, `dm75xx_cgt_entry_t` *cgt*)

Write a channel gain table entry. This function utilizes [DM75xx_CGT_Create_Entry\(\)](#) to create the 16 bit entry.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>cgt</i>	The channel gain table entry to write.

Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

Referenced by `main()`.

4.26.2.8 DM75xx_Error DM75xx_DT_Enable (DM75xx_Board_Descriptor * *handle*, `uint16_t` *enable*)

Enable/disable Digital Table.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>enable</i>	Enable/Disable the Digital Table and Digital I/O Port 1.

Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

4.26.2.9 DM75xx_Error DM75xx_DT_Write_Entry (DM75xx_Board_Descriptor * *handle*, uint8_t *data*)

Write Digital Table entry.

Parameters

<i>handle</i>	Address of device's library board descriptor.
<i>data</i>	Entry to add to the digital table.

Return values

0	Success.
-1	Failure. Please see the <code>ioctl(2)</code> man page for information on possible values <code>errno</code> may have in this case.

4.27 DM75xx type definition header file

Modules

- [DM75xx type enumerations](#)
- [DM75xx type definition structures](#)

4.27.1 Detailed Description

4.28 DM75xx type enumerations

Modules

- [DM75xx type PCI enumerations](#)
- [DM75xx type DSP enumerations](#)
- [DM75xx type DMA](#)
- [DM75xx type Interrupt](#)
- [DM75xx type Analog DIO](#)
- [DM75xx type User Output](#)
- [DM75xx type Digital Input/Output](#)
- [DM75xx type External Trigger/Interrupt](#)
- [DM75xx type SyncBus enumerations](#)
- [DM75xx type HighSpeed Digital enumerations](#)
- [DM75xx type Digital to Analog enumerations](#)
- [DM75xx type Analog to Digital enumerations](#)
- [DM75xx type Burst Clock enumerations](#)
- [DM75xx type Pacer Clock enumerations](#)
- [DM75xx type timer/counter enumerations](#)

4.28.1 Detailed Description

4.29 DM75xx type PCI enumerations

Typedefs

- typedef enum `dm75xx_pci_region_num` `dm75xx_pci_region_num_t`
Standard PCI region number type.
- typedef enum `dm75xx_pci_region_access_size` `dm75xx_pci_region_access_size_t`
Standard PCI region access size type.
- typedef enum `_dm75xx_board` `dm75xx_board_t`
DM75xx Board Type.

Enumerations

- enum `dm75xx_pci_region_num` { `DM75xx_PLX_MEM` = 0, `DM75xx_PLX_IO`, `DM75xx_LAS0`, `DM75xx_LAS1` }
Standard PCI region number.
- enum `dm75xx_pci_region_access_size` { `DM75xx_PCI_REGION_ACCESS_8` = 0, `DM75xx_PCI_REGION_ACCESS_16`, `DM75xx_PCI_REGION_ACCESS_32` }
Desired size in bits of access to standard PCI region.
- enum `_dm75xx_board` { `DM75xx_BOARD_DM7520` = 0, `DM75xx_BOARD_SDM7540` }
DM75xx Board.

4.29.1 Detailed Description

4.29.2 Enumeration Type Documentation

4.29.2.1 enum `_dm75xx_board`

DM75xx Board.

Enumerator

`DM75xx_BOARD_DM7520` DM7520
`DM75xx_BOARD_SDM7540` SDM7540

Definition at line 125 of file `dm75xx_types.h`.

4.29.2.2 enum `dm75xx_pci_region_access_size`

Desired size in bits of access to standard PCI region.

Enumerator

`DM75xx_PCI_REGION_ACCESS_8` 8-bit access
`DM75xx_PCI_REGION_ACCESS_16` 16-bit access
`DM75xx_PCI_REGION_ACCESS_32` 32-bit access

Definition at line 92 of file `dm75xx_types.h`.

4.29.2.3 enum dm75xx_pci_region_num

Standard PCI region number.

Enumerator

DM75xx_PLX_MEM Memory-mapped PLX registers

DM75xx_PLX_IO I/O-mapped PLX registers

DM75xx_LAS0 Memory-mapped LAS 0 registers

DM75xx_LAS1 Memory-mapped LAS 1 registers

Definition at line 53 of file dm75xx_types.h.

4.30 DM75xx type DSP enumerations

Typedefs

- typedef enum [_dm75xx_dsp_command](#) [dm75xx_dsp_command_t](#)
DSP Command Type.

Enumerations

- enum [_dm75xx_dsp_command](#) {
[DM75xx_DSP_CAL_AUTO](#) = 1, [DM75xx_DSP_FLASH_DOWNLOAD](#) = 2, [DM75xx_DSP_USER_RUN](#) = 3,
[DM75xx_DSP_USER_UPGRADE](#) = 4,
[DM75xx_DSP_INT_FLASH_ERASE](#) = 5, [DM75xx_DSP_EXT_FLASH_ERASE](#) = 6, [DM75xx_DSP_ATTENTION](#) = 7, [DM75xx_DSP_CAL_DEFAULT](#) = 8,
[DM75xx_DSP_CAL_VERSION](#) = 10, [DM75xx_DSP_BOOT_VERSION](#) = 11 }
DSP Command.

4.30.1 Detailed Description

DM75xx_Types_PCI_Enumerations

4.30.2 Enumeration Type Documentation

4.30.2.1 enum [_dm75xx_dsp_command](#)

DSP Command.

Enumerator

[DM75xx_DSP_CAL_AUTO](#) Auto Calibration of SDM7540
[DM75xx_DSP_FLASH_DOWNLOAD](#) Internal Flash Download
[DM75xx_DSP_USER_RUN](#) Run User Program
[DM75xx_DSP_USER_UPGRADE](#) Upgrade User Program
[DM75xx_DSP_INT_FLASH_ERASE](#) Erase Internal Flash
[DM75xx_DSP_EXT_FLASH_ERASE](#) Erase External Flash
[DM75xx_DSP_ATTENTION](#) Check if DSP still alive
[DM75xx_DSP_CAL_DEFAULT](#) Load Default Calibration
[DM75xx_DSP_CAL_VERSION](#) Get Calibration Algorithm Version
[DM75xx_DSP_BOOT_VERSION](#) Get Boot Loader Version

Definition at line 151 of file [dm75xx_types.h](#).

4.31 DM75xx type DMA

Typedefs

- typedef enum [_dm75xx_dma_flag](#) dm75xx_dma_flag_t
DMA Control Flag Type.
- typedef enum [_dm75xx_dma_reset](#) dm75xx_dma_reset_t
DMA Status Reset Flag Type.
- typedef enum [_dm75xx_dma_request](#) dm75xx_dma_request_t
DMA Demand Mode Source Type.
- typedef enum [_dm75xx_dma_source](#) dm75xx_dma_source_t
DMA Source Type.
- typedef enum [_dm75xx_dma_channel](#) dm75xx_dma_channel_t
DMA Channel Type.

Enumerations

- enum [_dm75xx_dma_flag](#) {
[DM75xx_DMA_FLAG_INIT](#) = 0x01, [DM75xx_DMA_FLAG_MMAP](#) = 0x02, [DM75xx_DMA_FLAG_RESET](#) = 0x04, [DM75xx_DMA_FLAG_NONDEMAND](#) = 0x08,
[DM75xx_DMA_FLAG_STATUS](#) = 0x10, [DM75xx_DMA_FLAG_ARB](#) = 0x20 }
DMA Control Flag.
- enum [_dm75xx_dma_reset](#) { [DM75xx_DMA_RESET_SEL](#) = 0x01, [DM75xx_DMA_RESET_VAL](#) = 0x10 }
DMA Status Reset Flag.
- enum [_dm75xx_dma_request](#) {
[DM75xx_DMA_DEMAND_DISABLE](#) = 0, [DM75xx_DMA_DEMAND_SCNT_ADC](#) = 1, [DM75xx_DMA_DEMAND_SCNT_DAC1](#) = 2, [DM75xx_DMA_DEMAND_SCNT_DAC2](#) = 3,
[DM75xx_DMA_DEMAND_UTC1](#) = 4, [DM75xx_DMA_DEMAND_FIFO_ADC](#) = 8, [DM75xx_DMA_DEMAND_FIFO_DAC1](#) = 9, [DM75xx_DMA_DEMAND_FIFO_DAC2](#) = 10 }
DMA Demand Mode Source.
- enum [_dm75xx_dma_source](#) { [DM75xx_DMA_FIFO_ADC](#) = 0, [DM75xx_DMA_FIFO_DAC1](#), [DM75xx_DMA_FIFO_DAC2](#), [DM75xx_DMA_FIFO_HSDIN](#) }
DMA Local Source.
- enum [_dm75xx_dma_channel](#) { [DM75xx_DMA_CHANNEL_0](#) = 0, [DM75xx_DMA_CHANNEL_1](#) }
DMA Channel.

4.31.1 Detailed Description

DM75xx_Types_DSP_Enumerations

4.31.2 Enumeration Type Documentation

4.31.2.1 enum [_dm75xx_dma_channel](#)

DMA Channel.

Enumerator

- [DM75xx_DMA_CHANNEL_0](#)** DMA Channel 0
[DM75xx_DMA_CHANNEL_1](#) DMA Channel 1

Definition at line 337 of file dm75xx_types.h.

4.31.2.2 enum _dm75xx_dma_flag

DMA Control Flag.

Enumerator

DM75xx_DMA_FLAG_INIT DMA Initialized
DM75xx_DMA_FLAG_MMAP DMA Memory Map
DM75xx_DMA_FLAG_RESET DMA Reset DREQ
DM75xx_DMA_FLAG_NONDEMAND DMA Non Demand Mode
DM75xx_DMA_FLAG_STATUS DMA Channel Status
DM75xx_DMA_FLAG_ARB DMA Arbitrary

Definition at line 213 of file dm75xx_types.h.

4.31.2.3 enum _dm75xx_dma_request

DMA Demand Mode Source.

Enumerator

DM75xx_DMA_DEMAND_DISABLE Request Disable
DM75xx_DMA_DEMAND_SCNT_ADC A/D Sample Counter
DM75xx_DMA_DEMAND_SCNT_DAC1 D/A 1 Sample Counter
DM75xx_DMA_DEMAND_SCNT_DAC2 D/A 2 Sample Counter
DM75xx_DMA_DEMAND_UTC1 User Timer/Counter 1
DM75xx_DMA_DEMAND_FIFO_ADC A/D FIFO Half Full
DM75xx_DMA_DEMAND_FIFO_DAC1 D/A 1 FIFO Half Empty
DM75xx_DMA_DEMAND_FIFO_DAC2 D/A 2 FIFO Half Empty

Definition at line 267 of file dm75xx_types.h.

4.31.2.4 enum _dm75xx_dma_reset

DMA Status Reset Flag.

Enumerator

DM75xx_DMA_RESET_SEL DMA 0
DM75xx_DMA_RESET_VAL DMA Channel Reset Value

Definition at line 248 of file dm75xx_types.h.

4.31.2.5 enum _dm75xx_dma_source

DMA Local Source.

Enumerator

DM75xx_DMA_FIFO_ADC DMA A/D FIFO
DM75xx_DMA_FIFO_DAC1 DMA D/A 1 FIFO
DM75xx_DMA_FIFO_DAC2 DMA D/A 2 FIFO
DM75xx_DMA_FIFO_HSDIN DMA HSDIN FIFO

Definition at line 310 of file dm75xx_types.h.

4.32 DM75xx type Interrupt

Typedefs

- typedef enum [_dm75xx_int_source](#) dm75xx_int_source_t
Interrupt Source Type.

Enumerations

- enum [_dm75xx_int_source](#) {
[DM75xx_INT_FIFO_WRITE](#) = 0x0001, [DM75xx_INT_CGT_RESET](#) = 0x0002, [DM75xx_INT_RESERVED](#) = 0x0004, [DM75xx_INT_CGT_PAUSE](#) = 0x0008,
[DM75xx_INT_ABOUT](#) = 0x0010, [DM75xx_INT_DELAY](#) = 0x0020, [DM75xx_INT_SCNT_ADC](#) = 0x0040, [DM75xx_INT_SCNT_DAC1](#) = 0x0080,
[DM75xx_INT_SCNT_DAC2](#) = 0x0100, [DM75xx_INT_UTC1](#) = 0x0200, [DM75xx_INT_UTC1_INV](#) = 0x0400, [DM75xx_INT_UTC2](#) = 0x0800,
[DM75xx_INT_DIO](#) = 0x1000, [DM75xx_INT_EXTERNAL](#) = 0x2000, [DM75xx_INT_ETRIG_RISING](#) = 0x4000, [DM75xx_INT_ETRIG_FALLING](#) = 0x8000,
[DM75xx_INT_DMA_0](#) = 0x00200000, [DM75xx_INT_DMA_1](#) = 0x00400000, [DM75xx_INT_ALGDIO_POS_PIN1](#) = 0x04000000, [DM75xx_INT_ALGDIO_POS_PIN2](#) = 0x08000000,
[DM75xx_INT_ALGDIO_NEG_PIN1](#) = 0x10000000, [DM75xx_INT_ALGDIO_NEG_PIN2](#) = 0x20000000 }
Interrupt Source.

4.32.1 Detailed Description

DM75xx_Types_DMA_Enumerations

4.32.2 Enumeration Type Documentation

4.32.2.1 enum [_dm75xx_int_source](#)

Interrupt Source.

Enumerator

[DM75xx_INT_FIFO_WRITE](#) FIFO Write
[DM75xx_INT_CGT_RESET](#) Reset CGT
[DM75xx_INT_RESERVED](#) Reserved
[DM75xx_INT_CGT_PAUSE](#) Pause CGT
[DM75xx_INT_ABOUT](#) About Counter Out
[DM75xx_INT_DELAY](#) Delay Counter Out
[DM75xx_INT_SCNT_ADC](#) A/D Sample Counter
[DM75xx_INT_SCNT_DAC1](#) D/A 1 Update Counter
[DM75xx_INT_SCNT_DAC2](#) D/A 2 Update Counter
[DM75xx_INT_UTC1](#) User Timer/Counter 1 Out
[DM75xx_INT_UTC1_INV](#) Inverted User Timer/Counter 1 Out
[DM75xx_INT_UTC2](#) User Timer/Counter 2 Out
[DM75xx_INT_DIO](#) Digital Interrupt
[DM75xx_INT_EXTERNAL](#) External Interrupt
[DM75xx_INT_ETRIG_RISING](#) External Trigger Rising Edge

DM75xx_INT_ETRIG_FALLING External Trigger Falling Edge
DM75xx_INT_DMA_0 DMA Channel 0 – ENABLED BY DEFAULT
DM75xx_INT_DMA_1 DMA Channel 1 – ENABLED BY DEFAULT
DM75xx_INT_ALGDIO_POS_PIN1 Analog DIO Pin 1 Pos Edge
DM75xx_INT_ALGDIO_POS_PIN2 Analog DIO Pin 2 Pos Edge
DM75xx_INT_ALGDIO_NEG_PIN1 Analog DIO Pin 1 Neg Edge
DM75xx_INT_ALGDIO_NEG_PIN2 Analog DIO Pin 2 Neg Edge

Definition at line 366 of file dm75xx_types.h.

4.33 DM75xx type Analog DIO

Typedefs

- typedef enum [_dm75xx_algdio_mask](#) [dm75xx_algdio_mask_t](#)
Analog DIO Mask Type.
- typedef enum [_dm75xx_algdio_pin](#) [dm75xx_algdio_pin_t](#)
Analog DIO Pin Type.
- typedef enum [_dm75xx_algdio_direction](#) [dm75xx_algdio_direction_t](#)
Analog DIO Direction Type.

Enumerations

- enum [_dm75xx_algdio_mask](#) { [DM75xx_ALGDIO_MASKED](#) = 0, [DM75xx_ALGDIO_UNMASKED](#) }
Analog DIO Mask.
- enum [_dm75xx_algdio_pin](#) { [DM75xx_ALGDIO_PIN1](#) = 0, [DM75xx_ALGDIO_PIN2](#) }
Analog DIO Pins.
- enum [_dm75xx_algdio_direction](#) { [DM75xx_ALGDIO_INPUT](#) = 0, [DM75xx_ALGDIO_OUTPUT](#) }
Analog DIO Direction.

4.33.1 Detailed Description

DM75xx_Types_INT_Enumerations

4.33.2 Enumeration Type Documentation

4.33.2.1 enum [_dm75xx_algdio_direction](#)

Analog DIO Direction.

Enumerator

[DM75xx_ALGDIO_INPUT](#) Input

[DM75xx_ALGDIO_OUTPUT](#) Output

Definition at line 513 of file [dm75xx_types.h](#).

4.33.2.2 enum [_dm75xx_algdio_mask](#)

Analog DIO Mask.

Enumerator

[DM75xx_ALGDIO_MASKED](#) Masked

[DM75xx_ALGDIO_UNMASKED](#) Unmasked

Definition at line 475 of file [dm75xx_types.h](#).

4.33.2.3 enum _dm75xx_algdio_pin

Analog DIO Pins.

Enumerator

DM75xx_ALGDIO_PIN1 Pin 1

DM75xx_ALGDIO_PIN2 Pin 2

Definition at line 494 of file dm75xx_types.h.

4.34 DM75xx type User Output

Typedefs

- typedef enum [_dm75xx_uio_channel](#) dm75xx_uio_channel_t
User I/O Channel Type.
- typedef enum [_dm75xx_uio_source](#) dm75xx_uio_source_t
User I/O Source Type.

Enumerations

- enum [_dm75xx_uio_channel](#) { [DM75xx_UIO0](#) = 0, [DM75xx_UIO1](#) }
User I/O Channel.
- enum [_dm75xx_uio_source](#) { [DM75xx_UIO_ADC](#) = 0, [DM75xx_UIO_DAC1](#), [DM75xx_UIO_DAC2](#), [DM75xx_UIO_PRG](#) }
User I/O Source.

4.34.1 Detailed Description

DM75xx_Types_ALGDIO_Enumerations

4.34.2 Enumeration Type Documentation

4.34.2.1 enum [_dm75xx_uio_channel](#)

User I/O Channel.

Enumerator

- [DM75xx_UIO0](#)** User I/O Channel 0
[DM75xx_UIO1](#) User I/O Channel 1

Definition at line 542 of file dm75xx_types.h.

4.34.2.2 enum [_dm75xx_uio_source](#)

User I/O Source.

Enumerator

- [DM75xx_UIO_ADC](#)** A/D Conversion Signal
[DM75xx_UIO_DAC1](#) D/A 1 Update
[DM75xx_UIO_DAC2](#) D/A 2 Update
[DM75xx_UIO_PRG](#) Software Programmable

Definition at line 561 of file dm75xx_types.h.

4.35 DM75xx type Digital Input/Output

Typedefs

- typedef enum `_dm75xx_dio_clk` `dm75xx_dio_clk_t`
Digital I/O Clock Type.
- typedef enum `_dm75xx_dio_mode` `dm75xx_dio_mode_t`
Digital I/O IRQ Mode Type.
- typedef enum `_dm75xx_dio_port` `dm75xx_dio_port_t`
Digital I/O Port Type.

Enumerations

- enum `_dm75xx_dio_clk` { `DM75xx_DIO_CLK_8MHZ` = 0, `DM75xx_DIO_CLK_UTC1` }
Digital I/O Clock.
- enum `_dm75xx_dio_mode` { `DM75xx_DIO_MODE_EVENT` = 0, `DM75xx_DIO_MODE_MATCH` }
Digital I/O IRQ Mode.
- enum `_dm75xx_dio_port` { `DM75xx_DIO_PORT0` = 0, `DM75xx_DIO_PORT1` }
Digital I/O Port.

4.35.1 Detailed Description

DM75xx_Types_UIO_Enumerations

4.35.2 Enumeration Type Documentation

4.35.2.1 enum `_dm75xx_dio_clk`

Digital I/O Clock.

Enumerator

`DM75xx_DIO_CLK_8MHZ` 8MHZ Clock
`DM75xx_DIO_CLK_UTC1` Programmable Clock

Definition at line 598 of file `dm75xx_types.h`.

4.35.2.2 enum `_dm75xx_dio_mode`

Digital I/O IRQ Mode.

Enumerator

`DM75xx_DIO_MODE_EVENT` Event Mode
`DM75xx_DIO_MODE_MATCH` Match Mode

Definition at line 617 of file `dm75xx_types.h`.

4.35.2.3 enum _dm75xx_dio_port

Digital I/O Port.

Enumerator

DM75xx_DIO_PORT0 Port 0

DM75xx_DIO_PORT1 Port 1

Definition at line 636 of file dm75xx_types.h.

4.36 DM75xx type External Trigger/Interrupt

Typedefs

- typedef enum `_dm75xx_ext_polarity` `dm75xx_ext_polarity_t`
Polarity Type.

Enumerations

- enum `_dm75xx_ext_polarity` { `DM75xx_EXT_POLARITY_POS` = 0, `DM75xx_EXT_POLARITY_NEG` }
Polarity.

4.36.1 Detailed Description

DM75xx_Types_DIO_Enumerations

4.36.2 Enumeration Type Documentation

4.36.2.1 enum `_dm75xx_ext_polarity`

Polarity.

Enumerator

- `DM75xx_EXT_POLARITY_POS`** Positive Edge
`DM75xx_EXT_POLARITY_NEG` Negative Edge

Definition at line 665 of file `dm75xx_types.h`.

4.37 DM75xx type SyncBus enumerations

Typedefs

- typedef enum `_dm75xx_sbus` `dm75xx_sbus_t`
SyncBus Enumeration Type.
- typedef enum `_dm75xx_sbus_src` `dm75xx_sbus_src_t`
SyncBus Source Select Type.

Enumerations

- enum `_dm75xx_sbus` { `DM75xx_SBUS0` = 0, `DM75xx_SBUS1`, `DM75xx_SBUS2` }
SyncBus Enumerations.
- enum `_dm75xx_sbus_src` {
`DM75xx_SBUS_SRC_SOFT_ADC` = 0, `DM75xx_SBUS_SRC_PCLK` = 1, `DM75xx_SBUS_SRC_PCLK_START` = 1, `DM75xx_SBUS_SRC_BCLK` = 2,
`DM75xx_SBUS_SRC_PCLK_STOP` = 2, `DM75xx_SBUS_SRC_DIG_IT` = 3, `DM75xx_SBUS_SRC_DAC1` = 3, `DM75xx_SBUS_SRC_ETRIG` = 4,
`DM75xx_SBUS_SRC_DAC2` = 4, `DM75xx_SBUS_SRC_DAC_UPDATE` = 5, `DM75xx_SBUS_SRC_EPCLK` = 5, `DM75xx_SBUS_SRC_DAC_CLK` = 6,
`DM75xx_SBUS_SRC_ETRIG2` = 6, `DM75xx_SBUS_SRC_UTC2` = 7 }
SyncBus Source Select.

4.37.1 Detailed Description

DM75xx_Types_EXT_Enumerations

4.37.2 Enumeration Type Documentation

4.37.2.1 enum `_dm75xx_sbus`

SyncBus Enumerations.

Enumerator

`DM75xx_SBUS0` SyncBus 0
`DM75xx_SBUS1` SyncBus 1
`DM75xx_SBUS2` SyncBus 2

Definition at line 694 of file `dm75xx_types.h`.

4.37.2.2 enum `_dm75xx_sbus_src`

SyncBus Source Select.

Enumerator

`DM75xx_SBUS_SRC_SOFT_ADC` Software A/D Start
`DM75xx_SBUS_SRC_PCLK` Pacer Clock
`DM75xx_SBUS_SRC_PCLK_START` Software Pacer Start
`DM75xx_SBUS_SRC_BCLK` Burst Clock
`DM75xx_SBUS_SRC_PCLK_STOP` Software Pacer Stop

DM75xx_SBUS_SRC_DIG_IT Digital Interrupt
DM75xx_SBUS_SRC_DAC1 Software D/A1 Update
DM75xx_SBUS_SRC_ETRIG External Trigger
DM75xx_SBUS_SRC_DAC2 Software D/A2 Update
DM75xx_SBUS_SRC_DAC_UPDATE Simultaneous D/A Update
DM75xx_SBUS_SRC_EPCLK External Pacer Clock
DM75xx_SBUS_SRC_DAC_CLK D/A Clock
DM75xx_SBUS_SRC_ETRIG2 External Trigger
DM75xx_SBUS_SRC_UTC2 User Timer/Counter 2 Out

Definition at line 717 of file dm75xx_types.h.

4.38 DM75xx type HighSpeed Digital enumerations

Typedefs

- typedef enum [_dm75xx_hsdin_signal](#) [dm75xx_hsdin_signal_t](#)
HSDIN Sampling Signal Type.

Enumerations

- enum [_dm75xx_hsdin_signal](#) {
[DM75xx_HSDIN_SIGNAL_SOFTWARE](#) = 0, [DM75xx_HSDIN_SIGNAL_ADC](#), [DM75xx_HSDIN_SIGNAL_UTC0](#), [DM75xx_HSDIN_SIGNAL_UTC1](#),
[DM75xx_HSDIN_SIGNAL_UTC2](#), [DM75xx_HSDIN_SIGNAL_EPCLK](#), [DM75xx_HSDIN_SIGNAL_ETRIG](#) }
HSDIN Sampling Signal.

4.38.1 Detailed Description

DM75xx_Types_SBUS_Enumerations

4.38.2 Enumeration Type Documentation

4.38.2.1 enum [_dm75xx_hsdin_signal](#)

HSDIN Sampling Signal.

Enumerator

DM75xx_HSDIN_SIGNAL_SOFTWARE Software
DM75xx_HSDIN_SIGNAL_ADC A/D Conversion Signal
DM75xx_HSDIN_SIGNAL_UTC0 User Timer/Counter 0 Out
DM75xx_HSDIN_SIGNAL_UTC1 User Timer/Counter 1 Out
DM75xx_HSDIN_SIGNAL_UTC2 User Timer/Counter 2 Out
DM75xx_HSDIN_SIGNAL_EPCLK External Pacer Clock
DM75xx_HSDIN_SIGNAL_ETRIG External Trigger

Definition at line 794 of file dm75xx_types.h.

4.39 DM75xx type Digital to Analog enumerations

Typedefs

- typedef enum `_dm75xx_dac_freq` `dm75xx_dac_freq_t`
DAC primary clock source type.
- typedef enum `_dm75xx_dac_clk_stop` `dm75xx_dac_clk_stop_t`
DAC clock stop source type.
- typedef enum `_dm75xx_dac_clk_start` `dm75xx_dac_clk_start_t`
DAC clock start source type.
- typedef enum `_dm75xx_dac_mode` `dm75xx_dac_mode_t`
DAC Cycle Mode Type.
- typedef enum `_dm75xx_dac_update_src` `dm75xx_dac_update_src_t`
DAC Update Source Type.
- typedef enum `_dm75xx_dac_range` `dm75xx_dac_range_t`
DAC Output Range Type.
- typedef enum `_dm75xx_dac_channel` `dm75xx_dac_channel_t`
- typedef enum `_dm75xx_dac_clk_mode` `dm75xx_dac_clk_mode_t`
DAC Clock Mode Type.

Enumerations

- enum `_dm75xx_dac_freq` { `DM75xx_DAC_FREQ_8_MHZ` = 0, `DM75xx_DAC_FREQ_20_MHZ` }
DAC primary clock source.
- enum `_dm75xx_dac_clk_stop` {
`DM75xx_DAC_CLK_STOP_SOFTWARE_PACER` = 0, `DM75xx_DAC_CLK_STOP_ETRIG`, `DM75xx_DAC_CLK_STOP_DIG_IT`, `DM75xx_DAC_CLK_STOP_UTC2`,
`DM75xx_DAC_CLK_STOP_SBUS0`, `DM75xx_DAC_CLK_STOP_SBUS1`, `DM75xx_DAC_CLK_STOP_SBUS2`, `DM75xx_DAC_CLK_STOP_SOFTWARE`,
`DM75xx_DAC_CLK_STOP_DAC1_UCNT`, `DM75xx_DAC_CLK_STOP_DAC2_UCNT` }
DAC clock stop source.
- enum `_dm75xx_dac_clk_start` {
`DM75xx_DAC_CLK_START_SOFTWARE_PACER` = 0, `DM75xx_DAC_CLK_START_ETRIG`, `DM75xx_DAC_CLK_START_DIG_IT`, `DM75xx_DAC_CLK_START_UTC2`,
`DM75xx_DAC_CLK_START_SBUS0`, `DM75xx_DAC_CLK_START_SBUS1`, `DM75xx_DAC_CLK_START_SBUS2`, `DM75xx_DAC_CLK_START_SOFTWARE` }
DAC clock start source.
- enum `_dm75xx_dac_mode` { `DM75xx_DAC_MODE_NOT_CYCLE` = 0, `DM75xx_DAC_MODE_CYCLE` }
DAC Cycle Mode.
- enum `_dm75xx_dac_update_src` {
`DM75xx_DAC_UPDATE_SOFTWARE` = 0, `DM75xx_DAC_UPDATE_CGT`, `DM75xx_DAC_UPDATE_CLOCK`, `DM75xx_DAC_UPDATE_EPCLK`,
`DM75xx_DAC_UPDATE_SBUS0`, `DM75xx_DAC_UPDATE_SBUS1`, `DM75xx_DAC_UPDATE_SBUS2` }
DAC Update Source.
- enum `_dm75xx_dac_range` { `DM75xx_DAC_RANGE_UNIPOLAR_5` = 0, `DM75xx_DAC_RANGE_UNIPOLAR_10`, `DM75xx_DAC_RANGE_BIPOLAR_5`, `DM75xx_DAC_RANGE_BIPOLAR_10` }
DAC Output Range.
- enum `_dm75xx_dac_channel` { `DM75xx_DAC1` = 1, `DM75xx_DAC2` }
DAC channels.
- enum `_dm75xx_dac_clk_mode` { `DM75xx_DAC_CLK_FREE_RUN` = 0, `DM75xx_DAC_CLK_START_STOP` }
DAC Clock Mode.

4.39.1 Detailed Description

DM75xx_Types_HSDIN_Enumerations

4.39.2 Typedef Documentation

4.39.2.1 typedef enum _dm75xx_dac_channel dm75xx_dac_channel_t

DAC channel type

Definition at line 1057 of file dm75xx_types.h.

4.39.3 Enumeration Type Documentation

4.39.3.1 enum _dm75xx_dac_channel

DAC channels.

Note: These are given these values specifically so they can be bitwise combined and compared.

Enumerator

DM75xx_DAC1 Digital to Analog channel 1

DM75xx_DAC2 Digital to Analog channel 2

Definition at line 1044 of file dm75xx_types.h.

4.39.3.2 enum _dm75xx_dac_clk_mode

DAC Clock Mode.

Enumerator

DM75xx_DAC_CLK_FREE_RUN Free Run Mode

DM75xx_DAC_CLK_START_STOP Start/Stop Mode

Definition at line 1062 of file dm75xx_types.h.

4.39.3.3 enum _dm75xx_dac_clk_start

DAC clock start source.

Enumerator

DM75xx_DAC_CLK_START_SOFTWARE_PACER Software pacer start

DM75xx_DAC_CLK_START_ETRIG External trigger

DM75xx_DAC_CLK_START_DIG_IT Digital Interrupt

DM75xx_DAC_CLK_START_UTC2 User Timer/Counter 2 out

DM75xx_DAC_CLK_START_SBUS0 SyncBus 0

DM75xx_DAC_CLK_START_SBUS1 SyncBus 1

DM75xx_DAC_CLK_START_SBUS2 SyncBus 2

DM75xx_DAC_CLK_START_SOFTWARE Software DAC clock start

Definition at line 913 of file dm75xx_types.h.

4.39.3.4 enum _dm75xx_dac_clk_stop

DAC clock stop source.

Enumerator

DM75xx_DAC_CLK_STOP_SOFTWARE_PACER Software Pacer Stop
DM75xx_DAC_CLK_STOP_ETRIG External trigger
DM75xx_DAC_CLK_STOP_DIG_IT Digital Interrupt
DM75xx_DAC_CLK_STOP_UTC2 User Timer/Counter 2 out
DM75xx_DAC_CLK_STOP_SBUS0 Syncbus 0
DM75xx_DAC_CLK_STOP_SBUS1 Syncbus 1
DM75xx_DAC_CLK_STOP_SBUS2 Syncbus 2
DM75xx_DAC_CLK_STOP_SOFTWARE Software DAC clock stop
DM75xx_DAC_CLK_STOP_DAC1_UCNT DAC1 Update Counter
DM75xx_DAC_CLK_STOP_DAC2_UCNT DAC2 Update Counter

Definition at line 862 of file dm75xx_types.h.

4.39.3.5 enum _dm75xx_dac_freq

DAC primary clock source.

Enumerator

DM75xx_DAC_FREQ_8_MHZ 8 MHz Clock
DM75xx_DAC_FREQ_20_MHZ 20 MHz Clock

Definition at line 843 of file dm75xx_types.h.

4.39.3.6 enum _dm75xx_dac_mode

DAC Cycle Mode.

Enumerator

DM75xx_DAC_MODE_NOT_CYCLE Not cycle
DM75xx_DAC_MODE_CYCLE Cycle

Definition at line 956 of file dm75xx_types.h.

4.39.3.7 enum _dm75xx_dac_range

DAC Output Range.

Enumerator

DM75xx_DAC_RANGE_UNIPOLAR_5 Unipolar 0V to 5V
DM75xx_DAC_RANGE_UNIPOLAR_10 Unipolar 0V to 10V
DM75xx_DAC_RANGE_BIPOLAR_5 Bipolar -5V to 5V
DM75xx_DAC_RANGE_BIPOLAR_10 Bipolar -10V to 10V

Definition at line 1014 of file dm75xx_types.h.

4.39.3.8 enum _dm75xx_dac_update_src

DAC Update Source.

Enumerator

DM75xx_DAC_UPDATE_SOFTWARE Software DAC Update

DM75xx_DAC_UPDATE_CGT CGT Controlled Update

DM75xx_DAC_UPDATE_CLOCK DAC Clock

DM75xx_DAC_UPDATE_EPCLK External pacer clock

DM75xx_DAC_UPDATE_SBUS0 Syncbus 0

DM75xx_DAC_UPDATE_SBUS1 Syncbus 1

DM75xx_DAC_UPDATE_SBUS2 Syncbus 2

Definition at line 975 of file dm75xx_types.h.

4.40 DM75xx type Analog to Digital enumerations

Typedefs

- typedef enum [_dm75xx_adc_scnt_src](#) [dm75xx_adc_scnt_src_t](#)
ADC Sample Counter Source Type.
- typedef enum [_dm75xx_adc_conv_signal](#) [dm75xx_adc_conv_signal_t](#)
ADC Conversion Signal Select type.

Enumerations

- enum [_dm75xx_adc_scnt_src](#) { [DM75xx_ADC_SCNT_SRC_CGT](#) = 0, [DM75xx_ADC_SCNT_SRC_FIFO](#) }
ADC Sample Counter Source.
- enum [_dm75xx_adc_conv_signal](#) {
[DM75xx_ADC_CONV_SIGNAL_SOFTWARE](#) = 0, [DM75xx_ADC_CONV_SIGNAL_PCLK](#), [DM75xx_ADC_CONV_SIGNAL_BCLK](#), [DM75xx_ADC_CONV_SIGNAL_DIG_IT](#),
[DM75xx_ADC_CONV_SIGNAL_DAC1_MRKR1](#), [DM75xx_ADC_CONV_SIGNAL_DAC2_MRKR1](#), [DM75xx_ADC_CONV_SIGNAL_SBUS0](#), [DM75xx_ADC_CONV_SIGNAL_SBUS1](#),
[DM75xx_ADC_CONV_SIGNAL_SBUS2](#) }
ADC Conversion Signal Select.

4.40.1 Detailed Description

DM75xx_Types_DAC_Enumerations

4.40.2 Enumeration Type Documentation

4.40.2.1 enum [_dm75xx_adc_conv_signal](#)

ADC Conversion Signal Select.

Enumerator

[DM75xx_ADC_CONV_SIGNAL_SOFTWARE](#) Software
[DM75xx_ADC_CONV_SIGNAL_PCLK](#) Pacer Clock
[DM75xx_ADC_CONV_SIGNAL_BCLK](#) Burst Clock
[DM75xx_ADC_CONV_SIGNAL_DIG_IT](#) Digital Interrupt
[DM75xx_ADC_CONV_SIGNAL_DAC1_MRKR1](#) DAC1 Marker Bit 1
[DM75xx_ADC_CONV_SIGNAL_DAC2_MRKR1](#) DAC2 Marker Bit 2
[DM75xx_ADC_CONV_SIGNAL_SBUS0](#) SyncBus 0
[DM75xx_ADC_CONV_SIGNAL_SBUS1](#) SyncBus 1
[DM75xx_ADC_CONV_SIGNAL_SBUS2](#) SyncBus 2

Definition at line 1110 of file [dm75xx_types.h](#).

4.40.2.2 enum [_dm75xx_adc_scnt_src](#)

ADC Sample Counter Source.

Enumerator

DM75xx_ADC_SCNT_SRC_CGT Reset Channel Gain Table

DM75xx_ADC_SCNT_SRC_FIFO A/D FIFO Write

Definition at line 1091 of file dm75xx_types.h.

4.41 DM75xx type Burst Clock enumerations

Typedefs

- typedef enum `_dm75xx_bclk_freq` `dm75xx_bclk_freq_t`
Burst Clock primary frequency type.
- typedef enum `_dm75xx_bclk_start` `dm75xx_bclk_start_t`
Burst Clock Start Trigger Type.

Enumerations

- enum `_dm75xx_bclk_freq` { `DM75xx_BCLK_FREQ_8_MHZ` = 0, `DM75xx_BCLK_FREQ_20_MHZ` }
Burst Clock primary frequency.
- enum `_dm75xx_bclk_start` { `DM75xx_BCLK_START_SOFTWARE` = 0, `DM75xx_BCLK_START_PACER`, `DM75xx_BCLK_START_ETRIG`, `DM75xx_BCLK_START_DIG_IT`, `DM75xx_BCLK_START_SBUS0`, `DM75xx_BCLK_START_SBUS1`, `DM75xx_BCLK_START_SBUS2` }
Burst Clock Start Trigger.

4.41.1 Detailed Description

DM75xx_Types_ADC_Enumerations

4.41.2 Enumeration Type Documentation

4.41.2.1 enum `_dm75xx_bclk_freq`

Burst Clock primary frequency.

Enumerator

`DM75xx_BCLK_FREQ_8_MHZ` 8 MHz Clock
`DM75xx_BCLK_FREQ_20_MHZ` 20 MHz Clock

Definition at line 1168 of file `dm75xx_types.h`.

4.41.2.2 enum `_dm75xx_bclk_start`

Burst Clock Start Trigger.

Enumerator

`DM75xx_BCLK_START_SOFTWARE` Software A/D
`DM75xx_BCLK_START_PACER` Pacer Clock
`DM75xx_BCLK_START_ETRIG` External Trigger
`DM75xx_BCLK_START_DIG_IT` Digital Interrupt
`DM75xx_BCLK_START_SBUS0` SyncBus 0
`DM75xx_BCLK_START_SBUS1` SyncBus 1
`DM75xx_BCLK_START_SBUS2` SyncBus 2

Definition at line 1188 of file `dm75xx_types.h`.

4.42 DM75xx type Pacer Clock enumerations

Typedefs

- typedef enum [_dm75xx_pclk_mode](#) [dm75xx_pclk_mode_t](#)
Pacer Clock Trigger Mode Type.
- typedef enum [_dm75xx_pclk_stop](#) [dm75xx_pclk_stop_t](#)
Pacer Clock Stop Type.
- typedef enum [_dm75xx_pclk_start](#) [dm75xx_pclk_start_t](#)
Pacer Clock Start Type.
- typedef enum [_dm75xx_pclk_select](#) [dm75xx_pclk_select_t](#)
Pacer Clock Select Type.
- typedef enum [_dm75xx_pclk_freq](#) [dm75xx_pclk_freq_t](#)
Pacer Clock Frequency type.

Enumerations

- enum [_dm75xx_pclk_mode](#) { [DM75xx_PCLK_NO_REPEAT](#) = 0, [DM75xx_PCLK_REPEAT](#) }
Pacer Clock Trigger Mode.
- enum [_dm75xx_pclk_stop](#) {
[DM75xx_PCLK_STOP_SOFTWARE](#) = 0, [DM75xx_PCLK_STOP_ETRIG](#), [DM75xx_PCLK_STOP_DIGITAL_IT](#), [DM75xx_PCLK_STOP_ACNT](#),
[DM75xx_PCLK_STOP_UTC2](#), [DM75xx_PCLK_STOP_SBUS0](#), [DM75xx_PCLK_STOP_SBUS1](#), [DM75xx_PCLK_STOP_SBUS2](#),
[DM75xx_PCLK_STOP_ASOFTWARE](#), [DM75xx_PCLK_STOP_AETRIG](#), [DM75xx_PCLK_STOP_ADIGITAL_IT](#), [DM75xx_PCLK_STOP_RES](#),
[DM75xx_PCLK_STOP_AUTC2](#), [DM75xx_PCLK_STOP_ASBUS0](#), [DM75xx_PCLK_STOP_ASBUS1](#), [DM75xx_PCLK_STOP_ASBUS2](#) }
Pacer Clock Stop.
- enum [_dm75xx_pclk_start](#) {
[DM75xx_PCLK_START_SOFTWARE](#) = 0, [DM75xx_PCLK_START_ETRIG](#), [DM75xx_PCLK_START_DIGITAL_IT](#), [DM75xx_PCLK_START_UTC2](#),
[DM75xx_PCLK_START_SBUS0](#), [DM75xx_PCLK_START_SBUS1](#), [DM75xx_PCLK_START_SBUS2](#), [DM75xx_PCLK_START_RES](#),
[DM75xx_PCLK_START_DSOFTWARE](#), [DM75xx_PCLK_START_DETRIG](#), [DM75xx_PCLK_START_DIGITAL_IT](#), [DM75xx_PCLK_START_DUTC2](#),
[DM75xx_PCLK_START_DSBUS0](#), [DM75xx_PCLK_START_DSBUS1](#), [DM75xx_PCLK_START_DSBUS2](#), [DM75xx_PCLK_START_ETRIG_GATE](#) }
Pacer Clock Start.
- enum [_dm75xx_pclk_select](#) { [DM75xx_PCLK_EXTERNAL](#) = 0, [DM75xx_PCLK_INTERNAL](#) }
Pacer Clock Select.
- enum [_dm75xx_pclk_freq](#) { [DM75xx_PCLK_FREQ_8_MHZ](#) = 0, [DM75xx_PCLK_FREQ_20_MHZ](#) }
Pacer Clock Frequency Select.

4.42.1 Detailed Description

DM75xx_Types_BCLK_Enumerations

4.42.2 Enumeration Type Documentation

4.42.2.1 enum [_dm75xx_pclk_freq](#)

Pacer Clock Frequency Select.

Enumerator

DM75xx_PCLK_FREQ_8_MHZ 8Mhz Frequency
DM75xx_PCLK_FREQ_20_MHZ 20Mhz Frequency

Definition at line 1436 of file dm75xx_types.h.

4.42.2.2 enum_dm75xx_pclk_mode

Pacer Clock Trigger Mode.

Enumerator

DM75xx_PCLK_NO_REPEAT Single Cycle Mode
DM75xx_PCLK_REPEAT Repeat Mode

Definition at line 1239 of file dm75xx_types.h.

4.42.2.3 enum_dm75xx_pclk_select

Pacer Clock Select.

Enumerator

DM75xx_PCLK_EXTERNAL External Pacer Clock
DM75xx_PCLK_INTERNAL Internal Pacer Clock

Definition at line 1414 of file dm75xx_types.h.

4.42.2.4 enum_dm75xx_pclk_start

Pacer Clock Start.

Enumerator

DM75xx_PCLK_START_SOFTWARE Software
DM75xx_PCLK_START_ETRIG External Trigger
DM75xx_PCLK_START_DIGITAL_IT Digital Interrupt
DM75xx_PCLK_START_UTC2 User Timer/Counter 2 Out
DM75xx_PCLK_START_SBUS0 SyncBus 0
DM75xx_PCLK_START_SBUS1 SyncBus 1
DM75xx_PCLK_START_SBUS2 SyncBus 2
DM75xx_PCLK_START_RES Reserved
DM75xx_PCLK_START_DS SOFTWARE Delayed Software
DM75xx_PCLK_START_DETRIG Delayed External Trigger
DM75xx_PCLK_START_DDIGITAL_IT Delayed Digital Interrupt
DM75xx_PCLK_START_DUTC2 Delayed User Timer/Counter 2 Out
DM75xx_PCLK_START_DSBUS0 Delayed SyncBus 0
DM75xx_PCLK_START_DSBUS1 Delayed SyncBus 1
DM75xx_PCLK_START_DSBUS2 Delayed SyncBus 2
DM75xx_PCLK_START_ETRIG_GATE External Trigger Gated

Definition at line 1339 of file dm75xx_types.h.

4.42.2.5 enum_dm75xx_pclk_stop

Pacer Clock Stop.

Enumerator

DM75xx_PCLK_STOP_SOFTWARE Software
DM75xx_PCLK_STOP_ETRIG External Trigger
DM75xx_PCLK_STOP_DIGITAL_IT Digital Interrupt
DM75xx_PCLK_STOP_ACNT About Counter
DM75xx_PCLK_STOP_UTC2 User Timer/Counter 2 Out
DM75xx_PCLK_STOP_SBUS0 SyncBus 0
DM75xx_PCLK_STOP_SBUS1 SyncBus 1
DM75xx_PCLK_STOP_SBUS2 SyncBus 2
DM75xx_PCLK_STOP_AS SOFTWARE About Software
DM75xx_PCLK_STOP_AETRIG About External Trigger
DM75xx_PCLK_STOP_ADIGITAL_IT About Digital Interrupt
DM75xx_PCLK_STOP_RES Reserved
DM75xx_PCLK_STOP_AUTC2 About User Timer/Counter 2 Out
DM75xx_PCLK_STOP_AS BUS0 About SyncBus 0
DM75xx_PCLK_STOP_AS BUS1 About SyncBus 1
DM75xx_PCLK_STOP_AS BUS2 About SyncBus 2

Definition at line 1263 of file dm75xx_types.h.

4.43 DM75xx type timer/counter enumerations

Typedefs

- typedef enum [_dm75xx_utc_timer](#) [dm75xx_utc_timer_t](#)
8254 timer/counter type
- typedef enum [_dm75xx_utc_clk](#) [dm75xx_utc_clk_t](#)
8254 timer/counter clock selector type
- typedef enum [_dm75xx_utc_gate](#) [dm75xx_utc_gate](#)
8254 timer/counter gate selector type
- typedef enum [_dm75xx_utc_mode](#) [dm75xx_utc_mode](#)
8254 timer/counter waveform mode selector type

Enumerations

- enum [_dm75xx_utc_timer](#) { [DM75xx_UTC_0](#) = 0, [DM75xx_UTC_1](#), [DM75xx_UTC_2](#) }
8254 timers/counters
- enum [_dm75xx_utc_clk](#) {
[DM75xx_CUTC_8_MHZ](#) = 0, [DM75xx_CUTC_EXT_TC_CLOCK_1](#) = 1, [DM75xx_CUTC_EXT_TC_CLOCK_2](#) = 2, [DM75xx_CUTC_EXT_PCLK](#) = 3,
[DM75xx_CUTC_UTC_0_OUT](#) = 4, [DM75xx_CUTC_UTC_1_OUT](#) = 4, [DM75xx_CUTC_HSDIN_SIGNAL](#) = 5
}
8254 timer/counter clock selectors
- enum [_dm75xx_utc_gate](#) {
[DM75xx_GUTC_NOT_GATED](#) = 0, [DM75xx_GUTC_GATED](#) = 1, [DM75xx_GUTC_EXT_TC_CLK_1](#) = 2, [DM75xx_GUTC_EXT_TC_CLK_2](#) = 3,
[DM75xx_GUTC_UTC_0_OUT](#) = 4, [DM75xx_GUTC_UTC_1_OUT](#) = 4 }
8254 timer/counter gate selectors
- enum [_dm75xx_utc_mode](#) {
[DM75xx_UTC_MODE_EVENT_COUNTER](#) = 0, [DM75xx_UTC_MODE_PROG_ONE_SHOT](#), [DM75xx_UTC_MODE_RATE_GENERATOR](#), [DM75xx_UTC_MODE_SQUARE_WAVE](#),
[DM75xx_UTC_MODE_SOFTWARE_STROBE](#), [DM75xx_UTC_MODE_HARDWARE_STROBE](#) }
8254 timer/counter waveform mode selectors

4.43.1 Detailed Description

DM75xx_Types_PCLK_Enumerations

4.43.2 Enumeration Type Documentation

4.43.2.1 enum [_dm75xx_utc_clk](#)

8254 timer/counter clock selectors

Enumerator

- [DM75xx_CUTC_8_MHZ](#)** 8 MHz clock
- [DM75xx_CUTC_EXT_TC_CLOCK_1](#)** External Timer Counter Clock 1
- [DM75xx_CUTC_EXT_TC_CLOCK_2](#)** External Timer Counter Clock 2
- [DM75xx_CUTC_EXT_PCLK](#)** External Pacer Clock
- [DM75xx_CUTC_UTC_0_OUT](#)** User Timer/Counter 0 Out
- [DM75xx_CUTC_UTC_1_OUT](#)** User Timer/Counter 1 Out

DM75xx_CUTC_HSDIN_SIGNAL High Speed Digital Input Sample Signal

Definition at line 1504 of file dm75xx_types.h.

4.43.2.2 enum _dm75xx_utc_gate

8254 timer/counter gate selectors

Enumerator

DM75xx_GUTC_NOT_GATED Logic 0
DM75xx_GUTC_GATED Logic 1
DM75xx_GUTC_EXT_TC_CLK_1 8254 timer/counter
DM75xx_GUTC_EXT_TC_CLK_2 8254 timer/counter
DM75xx_GUTC.UTC_0_OUT 8254 timer/counter
DM75xx_GUTC.UTC_1_OUT 8254 timer/counter

Definition at line 1561 of file dm75xx_types.h.

4.43.2.3 enum _dm75xx_utc_mode

8254 timer/counter waveform mode selectors

Enumerator

DM75xx.UTC_MODE_EVENT_COUNTER Event counter
DM75xx.UTC_MODE_PROG_ONE_SHOT Programmable one shot
DM75xx.UTC_MODE_RATE_GENERATOR Rate generator
DM75xx.UTC_MODE_SQUARE_WAVE Square wave generator
DM75xx.UTC_MODE_SOFTWARE_STROBE Software triggered strobe
DM75xx.UTC_MODE_HARDWARE_STROBE Hardware triggered strobe

Definition at line 1613 of file dm75xx_types.h.

4.43.2.4 enum _dm75xx_utc_timer

8254 timers/counters

Enumerator

DM75xx.UTC_0 Timer 0 on 8254 chip
DM75xx.UTC_1 Timer 1 on 8254 chip
DM75xx.UTC_2 Timer 2 on 8254 chip

Definition at line 1471 of file dm75xx_types.h.

4.44 DM75xx type definition structures

Data Structures

- struct [_dm75xx_int_status](#)
Interrupts status.
- struct [_dm75xx_cgt_entry](#)
Channel gain table entry.
- struct [dm75xx_pci_access_request](#)
PCI region access request descriptor. This structure holds information about a request to read data from or write data to one of a device's PCI regions.

Typedefs

- typedef enum [_dm75xx_fifo_status](#) [dm75xx_fifo_status_t](#)
FIFO Status Type.
- typedef struct [_dm75xx_int_status](#) [dm75xx_int_status_t](#)
Interrupt status type.
- typedef struct [_dm75xx_cgt_entry](#) [dm75xx_cgt_entry_t](#)
Channel gain table entry type.
- typedef struct [dm75xx_pci_access_request](#) [dm75xx_pci_access_request_t](#)
PCI region access request descriptor type.

Enumerations

- enum [_dm75xx_fifo_status](#) {
[DM75xx_FIFO_DAC1_NOT_EMPTY](#) = 0x0001, [DM75xx_FIFO_DAC1_HALF_EMPTY](#) = 0x0002, [DM75xx_FIFO_DAC1_NOT_FULL](#) = 0x0004, [DM75xx_FIFO_DAC2_NOT_EMPTY](#) = 0x0010,
[DM75xx_FIFO_DAC2_HALF_EMPTY](#) = 0x0020, [DM75xx_FIFO_DAC2_NOT_FULL](#) = 0x0040, [DM75xx_FIFO_ADC_NOT_EMPTY](#) = 0x0100, [DM75xx_FIFO_ADC_HALF_EMPTY](#) = 0x0200,
[DM75xx_FIFO_ADC_NOT_FULL](#) = 0x0400, [DM75xx_FIFO_HSDIN_NOT_EMPTY](#) = 0x1000, [DM75xx_FIFO_HSDIN_HALF_EMPTY](#) = 0x2000, [DM75xx_FIFO_HSDIN_NOT_FULL](#) = 0x4000 }
FIFO status.

4.44.1 Detailed Description

DM75xx_Types_Enumerations

4.44.2 Enumeration Type Documentation

4.44.2.1 enum [_dm75xx_fifo_status](#)

FIFO status.

Enumerator

[DM75xx_FIFO_DAC1_NOT_EMPTY](#) DAC1 FIFO Not Empty
[DM75xx_FIFO_DAC1_HALF_EMPTY](#) DAC1 FIFO Half Empty
[DM75xx_FIFO_DAC1_NOT_FULL](#) DAC1 FIFO Not Full
[DM75xx_FIFO_DAC2_NOT_EMPTY](#) DAC2 FIFO Not Empty

DM75xx_FIFO_DAC2_HALF_EMPTY DAC2 FIFO Half Empty
DM75xx_FIFO_DAC2_NOT_FULL DAC2 FIFO Not Full
DM75xx_FIFO_ADC_NOT_EMPTY ADC FIFO Not Empty
DM75xx_FIFO_ADC_HALF_EMPTY ADC FIFO Half Empty
DM75xx_FIFO_ADC_NOT_FULL ADC FIFO Not Full
DM75xx_FIFO_HSDIN_NOT_EMPTY HSDIN FIFO Not Empty
DM75xx_FIFO_HSDIN_HALF_EMPTY HSDIN FIFO Half Empty
DM75xx_FIFO_HSDIN_NOT_FULL HSDIN FIFO Not Full

Definition at line 1679 of file dm75xx_types.h.

Chapter 5

Data Structure Documentation

5.1 `_dm75xx_cgt_entry` Struct Reference

Channel gain table entry.

```
#include <dm75xx_types.h>
```

Data Fields

- `uint8_t channel`:4
- `uint8_t gain`:3
- `uint8_t nrse`:1
- `uint8_t range`:2
- `uint8_t ground`:1
- `uint8_t pause`:1
- `uint8_t dac1`:1
- `uint8_t dac2`:1
- `uint8_t skip`:1
- `uint8_t reserved`:1

5.1.1 Detailed Description

Channel gain table entry.

Definition at line 1768 of file `dm75xx_types.h`.

5.1.2 Field Documentation

5.1.2.1 `uint8_t channel`

Analog input channel

Definition at line 1772 of file `dm75xx_types.h`.

Referenced by `main()`.

5.1.2.2 `uint8_t dac1`

DAC1 Update

Definition at line 1796 of file `dm75xx_types.h`.

Referenced by main().

5.1.2.3 uint8_t dac2

DAC2 Update

Definition at line 1800 of file dm75xx_types.h.

Referenced by main().

5.1.2.4 uint8_t gain

Gain

Definition at line 1776 of file dm75xx_types.h.

Referenced by main().

5.1.2.5 uint8_t ground

Single/Differential

Definition at line 1788 of file dm75xx_types.h.

Referenced by main().

5.1.2.6 uint8_t nrse

AGND/AINSENSE

Definition at line 1780 of file dm75xx_types.h.

Referenced by main().

5.1.2.7 uint8_t pause

Pause

Definition at line 1792 of file dm75xx_types.h.

Referenced by main().

5.1.2.8 uint8_t range

Output Range

Definition at line 1784 of file dm75xx_types.h.

Referenced by main().

5.1.2.9 uint8_t reserved

Reserved

Definition at line 1808 of file dm75xx_types.h.

5.1.2.10 uint8_t skip

Skip

Definition at line 1804 of file dm75xx_types.h.

Referenced by main().

The documentation for this struct was generated from the following file:

- include/dm75xx_types.h

5.2 _dm75xx_int_status Struct Reference

Interrupts status.

```
#include <dm75xx_types.h>
```

Data Fields

- int [int_remaining](#)
- unsigned int [int_missed](#)
- uint32_t [status](#)

5.2.1 Detailed Description

Interrupts status.

Definition at line 1738 of file dm75xx_types.h.

5.2.2 Field Documentation

5.2.2.1 unsigned int int_missed

Number of interrupts missed

Definition at line 1750 of file dm75xx_types.h.

5.2.2.2 int int_remaining

Number of interrupts remaining in the interrupt status queue

Definition at line 1744 of file dm75xx_types.h.

5.2.2.3 uint32_t status

Interrupt Status

Definition at line 1756 of file dm75xx_types.h.

The documentation for this struct was generated from the following file:

- include/dm75xx_types.h

5.3 DM75xx_Board_Descriptor Struct Reference

DM75xx board descriptor. This structure holds information about a device needed by the library.

```
#include <dm75xx_library.h>
```

Data Fields

- int [file_descriptor](#)
- void(* [isr](#))(unsigned int status)
- pthread_t [pid](#)
- int [thread_status](#)
- uint16_t * [k_buf](#) [2]
- uint16_t * [u_buf](#) [2]
- unsigned long [k_buf_siz](#) [2]
- unsigned long [u_buf_siz](#) [2]

5.3.1 Detailed Description

DM75xx board descriptor. This structure holds information about a device needed by the library.

Definition at line 183 of file dm75xx_library.h.

5.3.2 Field Documentation

5.3.2.1 int file_descriptor

File descriptor for device returned from open()

Definition at line 189 of file dm75xx_library.h.

5.3.2.2 void(* isr)(unsigned int status)

The currently installed user-space ISR for this device.

Definition at line 193 of file dm75xx_library.h.

5.3.2.3 uint16_t* k_buf[2]

Pointer to Kernel Space Buffers

Definition at line 205 of file dm75xx_library.h.

5.3.2.4 unsigned long k_buf_siz[2]

Kernel Buffer Sizes

Definition at line 213 of file dm75xx_library.h.

5.3.2.5 pthread_t pid

The parent ID of the thread watching for interrupts.

Definition at line 197 of file dm75xx_library.h.

5.3.2.6 int thread_status

Status of thread after execution

Definition at line 201 of file dm75xx_library.h.

5.3.2.7 uint16_t* u_buf[2]

Pointer to User Space DMA Buffers

Definition at line 209 of file dm75xx_library.h.

5.3.2.8 unsigned long u_buf_siz[2]

User Space Buffer Sizes

Definition at line 217 of file dm75xx_library.h.

The documentation for this struct was generated from the following file:

- [include/dm75xx_library.h](#)

5.4 dm75xx_device_descriptor Struct Reference

DM75xx device descriptor. This structure holds information about a device needed by the kernel.

```
#include <dm75xx_driver.h>
```

Data Fields

- [char name \[DM75xx_DEVICE_NAME_LENGTH\]](#)
- [dm75xx_board_t board_type](#)
- [dm75xx_pci_region_t pci \[PCI_ROM_RESOURCE\]](#)
- [dm75xx_int_source_t int_control](#)
- [uint32_t int_status \[DM75xx_INT_QUEUE_SIZE\]](#)
- [unsigned int int_queue_in](#)
- [unsigned int int_queue_out](#)
- [unsigned int int_queue_missed](#)
- [unsigned int int_count](#)
- [unsigned int fifo_size](#)
- [spinlock_t lock](#)
- [uint8_t reference_count](#)
- [unsigned int irq_number](#)
- [uint8_t remove_isr_flag](#)
- [wait_queue_head_t int_wait_queue](#)
- [uint32_t dma_size \[DM75xx_DMA_CHANNELS\]](#)
- [dm75xx_dma_descriptor_t dma_buffers \[DM75xx_DMA_CHANNELS\]](#)
- [dm75xx_dma_chain_descriptor_t * dma_chain \[DM75xx_DMA_CHANNELS\]](#)
- [dm75xx_dma_flag_t dma_flag \[DM75xx_DMA_CHANNELS\]](#)

5.4.1 Detailed Description

DM75xx device descriptor. This structure holds information about a device needed by the kernel.

Definition at line 289 of file dm75xx_driver.h.

5.4.2 Field Documentation

5.4.2.1 dm75xx_board_t board_type

Flag which indicates if the board has SDM7540/8540 functionality

Definition at line 302 of file dm75xx_driver.h.

5.4.2.2 `dm75xx_dma_descriptor_t dma_buffers[DM75xx_DMA_CHANNELS]`

Per DMA channel buffer information

Definition at line 393 of file `dm75xx_driver.h`.

5.4.2.3 `dm75xx_dma_chain_descriptor_t* dma_chain[DM75xx_DMA_CHANNELS]`

Per DMA channel chaining descriptors

Definition at line 399 of file `dm75xx_driver.h`.

5.4.2.4 `dm75xx_dma_flag_t dma_flag[DM75xx_DMA_CHANNELS]`

Flag used for DMA control

Definition at line 405 of file `dm75xx_driver.h`.

5.4.2.5 `uint32_t dma_size[DM75xx_DMA_CHANNELS]`

Per-FIFO channel DMA transfer size in bytes

Definition at line 387 of file `dm75xx_driver.h`.

5.4.2.6 `unsigned int fifo_size`

The board's FIFO capacity.

Definition at line 350 of file `dm75xx_driver.h`.

5.4.2.7 `dm75xx_int_source_t int_control`

Interrupt Control

Definition at line 314 of file `dm75xx_driver.h`.

5.4.2.8 `unsigned int int_count`

Number of interrupts in the queue

Definition at line 344 of file `dm75xx_driver.h`.

5.4.2.9 `unsigned int int_queue_in`

Number of entries in the interrupt status queue

Definition at line 326 of file `dm75xx_driver.h`.

5.4.2.10 `unsigned int int_queue_missed`

Number of interrupts missed because of a full queue

Definition at line 338 of file `dm75xx_driver.h`.

5.4.2.11 unsigned int int_queue_out

Number of entries read from the interrupt status queue

Definition at line 332 of file dm75xx_driver.h.

5.4.2.12 uint32_t int_status[DM75xx_INT_QUEUE_SIZE]

Interrupt status queue

Definition at line 320 of file dm75xx_driver.h.

5.4.2.13 wait_queue_head_t int_wait_queue

Queue of processes waiting to be woken up when an interrupt occurs

Definition at line 381 of file dm75xx_driver.h.

5.4.2.14 unsigned int irq_number

IRQ line number

Definition at line 369 of file dm75xx_driver.h.

5.4.2.15 spinlock_t lock

Concurrency control

Definition at line 356 of file dm75xx_driver.h.

5.4.2.16 char name[DM75xx_DEVICE_NAME_LENGTH]

Device name used when requesting resources; a NUL terminated string of the form rtd-dm75xx-x where x is the device minor number.

Definition at line 296 of file dm75xx_driver.h.

5.4.2.17 dm75xx_pci_region_t pci[PCI_ROM_RESOURCE]

Information about each of the standard PCI regions

Definition at line 308 of file dm75xx_driver.h.

5.4.2.18 uint8_t reference_count

Number of entities which have the device file open. Used to enforce single open semantics.

Definition at line 363 of file dm75xx_driver.h.

5.4.2.19 uint8_t remove_isr_flag

Used to assist in shutting down the thread waiting for interrupts

Definition at line 375 of file dm75xx_driver.h.

The documentation for this struct was generated from the following file:

- [include/dm75xx_driver.h](#)

5.5 dm75xx_dma_chain_descriptor Struct Reference

Dm75xx DMA chaining descriptor.

```
#include <dm75xx_driver.h>
```

Data Fields

- uint32_t [pci_address](#)
- uint32_t [local_address](#)
- uint32_t [transfer_size](#)
- uint32_t [descriptor_pointer](#)

5.5.1 Detailed Description

Dm75xx DMA chaining descriptor.

Definition at line 225 of file dm75xx_driver.h.

5.5.2 Field Documentation

5.5.2.1 uint32_t descriptor_pointer

Descriptor Pointer

Definition at line 241 of file dm75xx_driver.h.

5.5.2.2 uint32_t local_address

Local Address

Definition at line 233 of file dm75xx_driver.h.

5.5.2.3 uint32_t pci_address

PCI Address

Definition at line 229 of file dm75xx_driver.h.

5.5.2.4 uint32_t transfer_size

Transfer Size

Definition at line 237 of file dm75xx_driver.h.

The documentation for this struct was generated from the following file:

- [include/dm75xx_driver.h](#)

5.6 dm75xx_dma_descriptor Struct Reference

DM75xx DMA buffer descriptor. This structure holds allocation information for a single DMA buffer.

```
#include <dm75xx_driver.h>
```


Data Fields

- dma_addr_t [bus_address](#)
- void * [virtual_address](#)
- unsigned long [size](#)

5.6.1 Detailed Description

DM75xx DMA buffer descriptor. This structure holds allocation information for a single DMA buffer.

Definition at line 257 of file dm75xx_driver.h.

5.6.2 Field Documentation

5.6.2.1 dma_addr_t bus_address

Bus/physical address

Definition at line 263 of file dm75xx_driver.h.

5.6.2.2 unsigned long size

Buffer size

Definition at line 275 of file dm75xx_driver.h.

5.6.2.3 void* virtual_address

Virtual address

Definition at line 269 of file dm75xx_driver.h.

The documentation for this struct was generated from the following file:

- include/[dm75xx_driver.h](#)

5.7 dm75xx_ioctl_argument Union Reference

ioctl() request structure encapsulating all possible requests. This is what gets passed into the kernel from user space on the ioctl() call.

```
#include <dm75xx_ioctl.h>
```

Data Fields

- [dm75xx_ioctl_region_readwrite_t](#) readwrite
- [dm75xx_ioctl_region_modify_t](#) modify
- [dm75xx_ioctl_dma_function_t](#) dma_function
- [dm75xx_ioctl_int_control_t](#) int_control

5.7.1 Detailed Description

ioctl() request structure encapsulating all possible requests. This is what gets passed into the kernel from user space on the ioctl() call.

Definition at line 254 of file dm75xx_ioctl.h.

5.7.2 Field Documentation

5.7.2.1 `dm75xx_ioctl_dma_function_t` dma_function

DMA management function

Definition at line 272 of file `dm75xx_ioctl.h`.

5.7.2.2 `dm75xx_ioctl_int_control_t` int_control

Interrupt control function

Definition at line 278 of file `dm75xx_ioctl.h`.

5.7.2.3 `dm75xx_ioctl_region_modify_t` modify

PCI region read/modify/write

Definition at line 266 of file `dm75xx_ioctl.h`.

5.7.2.4 `dm75xx_ioctl_region_readwrite_t` readwrite

PCI region read and write

Definition at line 260 of file `dm75xx_ioctl.h`.

The documentation for this union was generated from the following file:

- [include/dm75xx_ioctl.h](#)

5.8 `dm75xx_ioctl_dma_function` Struct Reference

`ioctl()` request structure for performing a DMA function

```
#include <dm75xx_ioctl.h>
```

Data Fields

- [dm75xx_dma_source_t](#) source
- [dm75xx_dma_channel_t](#) channel
- [dm75xx_dma_request_t](#) request
- [uint32_t](#) size
- [uint32_t](#) pci_address
- [uint8_t](#) arb
- [dm75xx_dma_manage_function_t](#) function

5.8.1 Detailed Description

`ioctl()` request structure for performing a DMA function

Definition at line 169 of file `dm75xx_ioctl.h`.

5.8.2 Field Documentation

5.8.2.1 uint8_t arb

Flag indicating whether or not this transfer is to an arbitrary address

Definition at line 204 of file dm75xx_ioctl.h.

5.8.2.2 dm75xx_dma_channel_t channel

The DMA Channel on which to perform the specified operation

Definition at line 181 of file dm75xx_ioctl.h.

5.8.2.3 dm75xx_dma_manage_function_t function

DMA function to perform

Definition at line 210 of file dm75xx_ioctl.h.

5.8.2.4 uint32_t pci_address

PCI Address

Definition at line 199 of file dm75xx_ioctl.h.

5.8.2.5 dm75xx_dma_request_t request

Demand mode request source (DREQ)

Definition at line 187 of file dm75xx_ioctl.h.

5.8.2.6 uint32_t size

Contains the transfer size for the DMA channel

Definition at line 193 of file dm75xx_ioctl.h.

5.8.2.7 dm75xx_dma_source_t source

DMA Local FIFO Source

Definition at line 175 of file dm75xx_ioctl.h.

The documentation for this struct was generated from the following file:

- [include/dm75xx_ioctl.h](#)

5.9 dm75xx_ioctl_int_control Struct Reference

ioctl() request structure for interrupt control.

```
#include <dm75xx_ioctl.h>
```

Data Fields

- [dm75xx_int_source_t source](#)
- [dm75xx_int_control_function_t function](#)

5.9.1 Detailed Description

ioctl() request structure for interrupt control.

Definition at line 226 of file dm75xx_ioctl.h.

5.9.2 Field Documentation

5.9.2.1 dm75xx_int_control_function_t function

Interrupt function to perofmr

Definition at line 238 of file dm75xx_ioctl.h.

5.9.2.2 dm75xx_int_source_t source

Interrupt Sources

Definition at line 232 of file dm75xx_ioctl.h.

The documentation for this struct was generated from the following file:

- include/[dm75xx_ioctl.h](#)

5.10 dm75xx_ioctl_region_modify Struct Reference

ioctl() request structure for PCI region read/modify/write

```
#include <dm75xx_ioctl.h>
```

Data Fields

- [dm75xx_pci_access_request_t access](#)
- union {
 - uint8_t [mask8](#)
 - uint16_t [mask16](#)
 - uint32_t [mask32](#)
- } [mask](#)

5.10.1 Detailed Description

ioctl() request structure for PCI region read/modify/write

Definition at line 115 of file dm75xx_ioctl.h.

5.10.2 Field Documentation

5.10.2.1 dm75xx_pci_access_request_t access

PCI region access request

Definition at line 121 of file dm75xx_ioctl.h.

5.10.2.2 union { ... } mask

Bit mask that controls which bits can be modified. A zero in a bit position means that the corresponding register bit should not be modified. A one in a bit position means that the corresponding register bit should be modified.

Note that it's possible to set bits outside of the mask depending upon the register value before modification. When processing the associated request code, the driver will silently prevent this from happening but will not return an indication that the mask or new value was incorrect.

5.10.2.3 uint16_t mask16

Mask for 16-bit operations

Definition at line 147 of file dm75xx_ioctl.h.

5.10.2.4 uint32_t mask32

Mask for 32-bit operations

Definition at line 153 of file dm75xx_ioctl.h.

5.10.2.5 uint8_t mask8

Mask for 8-bit operations

Definition at line 141 of file dm75xx_ioctl.h.

The documentation for this struct was generated from the following file:

- [include/dm75xx_ioctl.h](#)

5.11 dm75xx_ioctl_region_readwrite Struct Reference

ioctl() request structure for read from or write to PCI region

```
#include <dm75xx_ioctl.h>
```

Data Fields

- [dm75xx_pci_access_request_t access](#)

5.11.1 Detailed Description

ioctl() request structure for read from or write to PCI region

Definition at line 96 of file dm75xx_ioctl.h.

5.11.2 Field Documentation

5.11.2.1 dm75xx_pci_access_request_t access

PCI region access request

Definition at line 102 of file dm75xx_ioctl.h.

The documentation for this struct was generated from the following file:

- [include/dm75xx_ioctl.h](#)

5.12 dm75xx_pci_access_request Struct Reference

PCI region access request descriptor. This structure holds information about a request to read data from or write data to one of a device's PCI regions.

```
#include <dm75xx_types.h>
```

Data Fields

- [dm75xx_pci_region_access_size_t size](#)
- [dm75xx_pci_region_num_t region](#)
- [uint16_t offset](#)
- [union {
 \[uint8_t data8\]\(#\)
 \[uint16_t data16\]\(#\)
 \[uint32_t data32\]\(#\)
} data](#)

5.12.1 Detailed Description

PCI region access request descriptor. This structure holds information about a request to read data from or write data to one of a device's PCI regions.

Definition at line 1824 of file dm75xx_types.h.

5.12.2 Field Documentation

5.12.2.1 union { ... } data

Data to write or the data read

5.12.2.2 uint16_t data16

16-bit value

Definition at line 1860 of file dm75xx_types.h.

5.12.2.3 uint32_t data32

32-bit value

Definition at line 1866 of file dm75xx_types.h.

5.12.2.4 uint8_t data8

8-bit value

Definition at line 1854 of file dm75xx_types.h.

5.12.2.5 uint16_t offset

Offset within region to access

Definition at line 1842 of file dm75xx_types.h.

5.12.2.6 dm75xx_pci_region_num_t region

The PCI region to access

Definition at line 1836 of file dm75xx_types.h.

5.12.2.7 dm75xx_pci_region_access_size_t size

Size of access in bits

Definition at line 1830 of file dm75xx_types.h.

The documentation for this struct was generated from the following file:

- [include/dm75xx_types.h](#)

5.13 dm75xx_pci_region Struct Reference

DM75xx PCI region descriptor. This structure holds information about one of a device's PCI memory regions.

```
#include <dm75xx_driver.h>
```

Data Fields

- unsigned long [io_addr](#)
- unsigned long [length](#)
- unsigned int [phys_addr](#)
- void * [virt_addr](#)
- uint8_t [allocated](#)

5.13.1 Detailed Description

DM75xx PCI region descriptor. This structure holds information about one of a device's PCI memory regions.

Definition at line 177 of file dm75xx_driver.h.

5.13.2 Field Documentation

5.13.2.1 uint8_t allocated

Flag indicating whether or not the I/O-mapped memory ranged was allocated. A value of zero means the memory range was not allocated. Any other value means the memory range was allocated.

Definition at line 211 of file dm75xx_driver.h.

5.13.2.2 unsigned long io_addr

I/O port number if I/O mapped

Definition at line 183 of file dm75xx_driver.h.

5.13.2.3 unsigned long length

Length of region in bytes

Definition at line 189 of file dm75xx_driver.h.

5.13.2.4 unsigned int phys_addr

Region's physical address if memory mapped or I/O port number if I/O mapped

Definition at line 196 of file dm75xx_driver.h.

5.13.2.5 void* virt_addr

Address at which region is mapped in kernel virtual address space if memory mapped

Definition at line 203 of file dm75xx_driver.h.

The documentation for this struct was generated from the following file:

- include/[dm75xx_driver.h](#)

Chapter 6

File Documentation

6.1 examples/about_intrpt.c File Reference

This example program demonstrates the use of the About Counter Interrupt.

```
#include <errno.h>
#include <error.h>
#include <fcntl.h>
#include <getopt.h>
#include <limits.h>
#include <signal.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include "dm75xx_library.h"
```

Macros

- `#define UTC2_RATE 400`
- `#define ADC_RATE 1000`

Functions

- static void `usage` (void)
Print information on stderr about how the program is to be used. After doing so, the program is exited.
- void `ISR` (uint32_t status)
User-Space ISR.
- int `main` (int argument_count, char **arguments)
Main program code.

Variables

- static char * `program_name`
- static int `interrupts`

6.1.1 Detailed Description

This example program demonstrates the use of the About Counter Interrupt.

Samples are gathered via the Pacer Clock which is triggered by User Timer/Counter 2. The About Counter is loaded to trigger an interrupt every 100 samples.

```
-----
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```

```
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(which should be included with this software) or contact RTD Embedded
Technologies, Inc.
-----
```

```
$Id: about_intrpt.c 99065 2016-04-26 18:03:23Z rgroner $
```

Definition in file [about_intrpt.c](#).

6.1.2 Macro Definition Documentation

6.1.2.1 `#define ADC_RATE 1000`

Sampling rate

Definition at line 58 of file `about_intrpt.c`.

Referenced by `main()`.

6.1.2.2 `#define UTC2_RATE 400`

Rate for User Timer/Counter 2

Definition at line 54 of file `about_intrpt.c`.

Referenced by `main()`.

6.1.3 Variable Documentation

6.1.3.1 `int interrupts [static]`

Variable used to count how many interrupts occurred

Definition at line 50 of file `about_intrpt.c`.

Referenced by `ISR()`, and `main()`.

6.1.3.2 `char* program_name [static]`

Name of the program as invoked on the command line.

Definition at line 46 of file `about_intrpt.c`.

Referenced by `main()`, and `usage()`.

6.2 examples/adc_abrst.c File Reference

This example program demonstrates the use of the About Counter.

```
#include <errno.h>
#include <error.h>
#include <fcntl.h>
#include <getopt.h>
#include <limits.h>
#include <signal.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include "dm75xx_library.h"
```

Macros

- `#define NUM_CHANNELS 8`
- `#define PACER_RATE 125000`
- `#define BURST_RATE 1250000`
- `#define UTC2_RATE 400`

Functions

- static void `usage` (void)
Print information on stderr about how the program is to be used. After doing so, the program is exited.
- int `main` (int argument_count, char **arguments)
Main program code.

Variables

- static char * `program_name`

6.2.1 Detailed Description

This example program demonstrates the use of the About Counter.

This example program utilizes the About Counter to demonstrate 'Multi-Burst' sampling.

The board is configured to sample 8 channels 3 times for each 8254 User Timer/Counter 2 Out trigger received.

Samples are gathered in this way until the FIFO is filled at which point the program will print the samples to the screen.

```
-----
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```

```
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Agreement. For a copy of this agreement, refer to the file LICENSE.TXT
(which should be included with this software) or contact RTD Embedded
Technologies, Inc.
-----
```

```
$Id: adc_abrst.c 99065 2016-04-26 18:03:23Z rgroner $
```

Definition in file [adc_abrst.c](#).

6.2.2 Macro Definition Documentation

6.2.2.1 `#define BURST_RATE 1250000`

Burst Clock Rate

Definition at line 62 of file `adc_abrst.c`.

Referenced by `main()`.

6.2.2.2 `#define NUM_CHANNELS 8`

The number of channels to sample

Definition at line 54 of file `adc_abrst.c`.

Referenced by `main()`.

6.2.2.3 `#define PACER_RATE 125000`

Pacer Clock Rate

Definition at line 58 of file `adc_abrst.c`.

Referenced by `main()`.

6.2.2.4 `#define UTC2_RATE 400`

User Timer/Counter 2 Rate

Definition at line 66 of file `adc_abrst.c`.

Referenced by `main()`.

6.2.3 Variable Documentation

6.2.3.1 `char* program_name` `[static]`

Name of the program as invoked on the command line.

Definition at line 50 of file `adc_abrst.c`.

Referenced by `main()`, and `usage()`.

6.3 examples/adc_dac_simul.c File Reference

Demonstrates simultaneous Analog and Digital sampling.

```
#include <errno.h>
#include <error.h>
#include <fcntl.h>
#include <getopt.h>
#include <limits.h>
#include <math.h>
#include <signal.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include "dm75xx_library.h"
```

Macros

- #define `DAC_FIFO` 0x10000
- #define `ADC_FIFO` 0x8000
- #define `DAC_RATE` 40000
- #define `ADC_RATE` 25000
- #define `DAT_FILE` "/test.dat"

Functions

- static void `usage` (void)
Print information on stderr about how the program is to be used. After doing so, the program is exited.
- static void `sigint_handler` (int sig_num)
Exit gracefully if the user enters CTRL-C.
- void `ISR` (uint32_t status)
User-Space ISR.
- int `main` (int argument_count, char **arguments)
Main program code.

Variables

- static char * `program_name`
- static volatile int `adc_ints`
- static volatile int `dac_ints`
- volatile uint8_t `exit_program`

6.3.1 Detailed Description

Demonstrates simultaneous Analog and Digital sampling.

Program samples out the DAC and in the ADC simultaneously via DMA. Different driver FIFO sizes are emulated to show the diversity of the DMA engine. Also, the DAC and ADC are sampled at different rates to show that each interrupt source can be handled at various times. The data captured during this example program is saved to a file named 'test.txt'.

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(which should be included with this software) or contact RTD Embedded
Technologies, Inc.

\$Id: adc_dac_simul.c 99065 2016-04-26 18:03:23Z rgroner \$

Definition in file [adc_dac_simul.c](#).

6.3.2 Macro Definition Documentation

6.3.2.1 #define ADC_FIFO 0x8000

Size of the ADC FIFO to emulate in the driver

Definition at line 66 of file [adc_dac_simul.c](#).

Referenced by [main\(\)](#).

6.3.2.2 #define ADC_RATE 25000

ADC Sample rate

Definition at line 74 of file [adc_dac_simul.c](#).

Referenced by [main\(\)](#).

6.3.2.3 #define DAC_FIFO 0x10000

Size of the DAC FIFO to emulate in the driver

Definition at line 62 of file [adc_dac_simul.c](#).

Referenced by [main\(\)](#).

6.3.2.4 #define DAC_RATE 40000

DAC Sample rate

Definition at line 70 of file [adc_dac_simul.c](#).

Referenced by [main\(\)](#).

6.3.2.5 #define DAT_FILE "/test.dat"

Filename to dump the data

Definition at line 82 of file [adc_dac_simul.c](#).

Referenced by [main\(\)](#).

6.3.3 Variable Documentation

6.3.3.1 `volatile int adc_ints` `[static]`

Variable used to count how many interrupts occurred

Definition at line 54 of file `adc_dac_simul.c`.

Referenced by `ISR()`, and `main()`.

6.3.3.2 `volatile int dac_ints` `[static]`

Variable used to count how many interrupts occurred

Definition at line 58 of file `adc_dac_simul.c`.

Referenced by `ISR()`, and `main()`.

6.3.3.3 `volatile uint8_t exit_program`

Variable to allow graceful exit from Ctrl-C

Definition at line 78 of file `adc_dac_simul.c`.

Referenced by `main()`, and `sigint_handler()`.

6.3.3.4 `char* program_name` `[static]`

Program name as invoked on the command line

Definition at line 50 of file `adc_dac_simul.c`.

Referenced by `main()`, and `usage()`.

6.4 examples/adc_dma.c File Reference

Demonstrates the use of Analog to Digital sampling with DMA.

```
#include <errno.h>
#include <error.h>
#include <fcntl.h>
#include <getopt.h>
#include <limits.h>
#include <signal.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include "dm75xx_library.h"
```

Macros

- `#define FIFO 0x10000`
- `#define NUM_DATA (FIFO * 10)`
- `#define NUM_INTS (NUM_DATA/(FIFO/2))`
- `#define ADC_RATE 1250000`

Functions

- static void [usage](#) (void)
Print information on stderr about how the program is to be used. After doing so, the program is exited.
- static void [sigint_handler](#) (int sig_num)
Exit gracefully if the user enters CTRL-C.
- void [ISR](#) (uint32_t status)
User-Space ISR.
- void [setup_ctrlc_handler](#) ()
Handler to detect when user hits Ctrl-C.
- int [main](#) (int argument_count, char **arguments)
Main program code.

Variables

- static char * [program_name](#)
- static volatile int [interrupts](#)
- [DM75xx_Board_Descriptor](#) * [board](#)

6.4.1 Detailed Description

Demonstrates the use of Analog to Digital sampling with DMA.

This program captures about 1 Million samples at maximum speed (1.25MHz) and displays the samples to the screen.

This example is meant to show that full speed acquisition is now available in the driver.

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-----
```

```
$Id: adc_dma.c 99108 2016-04-27 21:12:59Z rgroner $
```

Definition in file [adc_dma.c](#).

6.4.2 Macro Definition Documentation

6.4.2.1 #define ADC_RATE 1250000

Sampling rate

Definition at line 68 of file [adc_dma.c](#).

Referenced by [main\(\)](#).

6.4.2.2 #define FIFO 0x10000

Size of the FIFO, in samples, to emulate in the driver

Definition at line 56 of file [adc_dma.c](#).

Referenced by [main\(\)](#).

6.4.2.3 #define NUM_DATA (FIFO * 10)

Amount of data, in samples, we want from the board

Definition at line 60 of file adc_dma.c.

Referenced by main().

6.4.2.4 #define NUM_INTS (NUM_DATA/(FIFO/2))

Number of user ISR interrupts until we have the amount of data we want.

Definition at line 64 of file adc_dma.c.

Referenced by main().

6.4.3 Function Documentation**6.4.3.1 void setup_ctrlc_handler ()**

Handler to detect when user hits Ctrl-C.

Return values

<i>None.</i>	
--------------	--

Definition at line 141 of file adc_dma.c.

References sigint_handler().

Referenced by main().

6.4.4 Variable Documentation**6.4.4.1 DM75xx_Board_Descriptor* board**

Board descriptor

Definition at line 72 of file adc_dma.c.

Referenced by main().

6.4.4.2 volatile int interrupts [static]

Variable used to count how many interrupts occurred

Definition at line 52 of file adc_dma.c.

Referenced by ISR(), and main().

6.4.4.3 char* program_name [static]

Name of the program as invoked on the command line.

Definition at line 48 of file adc_dma.c.

Referenced by main(), and usage().

6.5 examples/adc_dma_continuous.c File Reference

Demonstrates the use of Digital to Analog sampling via DMA.

```
#include <errno.h>
#include <error.h>
#include <fcntl.h>
#include <getopt.h>
#include <limits.h>
#include <signal.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include "dm75xx_library.h"
```

Macros

- #define `NUM_DATA` 0x80000
- #define `FIFO` 0x10000
- #define `NUM_INTS` (`NUM_DATA/(FIFO/2)`)
- #define `DAT_FILE` "./test.dat"
- #define `ADC_RATE` 50000

Functions

- static void `usage` (void)
Print information on stderr about how the program is to be used. After doing so, the program is exited.
- void `ISR` (uint32_t status)
User-Space ISR.
- void `sigint_handler` (int sig_num, siginfo_t *info, void *ptr)
Exit gracefully if the user enters CTRL-C.
- int `main` (int argument_count, char **arguments)
Main program code.

Variables

- static char * `program_name`
- static volatile int `interrupts`
- volatile uint8_t `exit_program`

6.5.1 Detailed Description

Demonstrates the use of Digital to Analog sampling via DMA.

This example program is similar to `adc_dma` except data is sampled at a slower rate and instead of logging to a buffer, the data is dumped to disk. This program will continually gather A/D samples until you ask it to quit.

This program will run until the user presses Ctrl+C to quit.

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-----
```

```
$Id: adc_dma_continuous.c 99065 2016-04-26 18:03:23Z rgroner $
```

Definition in file [adc_dma_continuous.c](#).

6.5.2 Macro Definition Documentation

6.5.2.1 #define ADC_RATE 50000

Sampling rate

Definition at line 76 of file `adc_dma_continuous.c`.

Referenced by `main()`.

6.5.2.2 #define DAT_FILE "/test.dat"

Filename to dump the data

Definition at line 68 of file `adc_dma_continuous.c`.

Referenced by `main()`.

6.5.2.3 #define FIFO 0x10000

Size of the FIFO to emulate in the driver

Definition at line 60 of file `adc_dma_continuous.c`.

Referenced by `main()`.

6.5.2.4 #define NUM_DATA 0x80000

Amount of data we want from the board

Definition at line 56 of file `adc_dma_continuous.c`.

6.5.2.5 #define NUM_INTS (NUM_DATA/(FIFO/2))

Number of user ISR interrupts until we have that much data

Definition at line 64 of file `adc_dma_continuous.c`.

6.5.3 Variable Documentation

6.5.3.1 volatile uint8_t exit_program

Variable to allow graceful exit from Ctrl-C

Definition at line 72 of file `adc_dma_continuous.c`.

Referenced by `main()`, and `sigint_handler()`.

6.5.3.2 volatile int interrupts [static]

Variable used to count how many interrupts occurred

Definition at line 52 of file `adc_dma_continuous.c`.

Referenced by `ISR()`, and `main()`.

6.5.3.3 char* program_name [static]

Name of the program as invoked on the command line.

Definition at line 48 of file `adc_dma_continuous.c`.

Referenced by `main()`, and `usage()`.

6.6 examples/adc_hd_simul.c File Reference

Demonstrates Analog to Digital and High Speed Digital simultaneously.

```
#include <errno.h>
#include <error.h>
#include <fcntl.h>
#include <getopt.h>
#include <limits.h>
#include <signal.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include "dm75xx_library.h"
```

Macros

- #define `ADC_NUM_DATA` 0x80000
- #define `ADC_FIFO` 0x10000
- #define `HD_NUM_DATA` 0x80000
- #define `HD_FIFO` 0x8000
- #define `ADC_NUM_INTS` (`ADC_NUM_DATA/(ADC_FIFO/2)`)
- #define `HD_NUM_INTS` (`HD_NUM_DATA/(HD_FIFO/2)`)
- #define `ADC_RATE` 50000
- #define `HSDIN_RATE` 30000

Functions

- static void `usage` (void)
Print information on stderr about how the program is to be used. After doing so, the program is exited.
- static void `sigint_handler` (int sig_num)
Exit gracefully if the user enters CTRL-C.
- void `ISR` (uint32_t status)
User-Space ISR.
- int `main` (int argument_count, char **arguments)
Main program code.

Variables

- static char * [program_name](#)
- static volatile int [dma_0_ints](#)
- static volatile int [dma_1_ints](#)
- [DM75xx_Board_Descriptor](#) * [board](#)

6.6.1 Detailed Description

Demonstrates Analog to Digital and High Speed Digital simultaneously.

This program simultaneously samples Analog and High Speed Digital data acquisition via DMA.

About 500,000 samples are gathered on each source at various speeds and driver FIFO sizes. This is done to show the versatility of the driver's DMA engine.

The samples are printed to the screen at the end of the program.

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-----
```

```
$Id: adc_hd_simul.c 99065 2016-04-26 18:03:23Z rgroner $
```

Definition in file [adc_hd_simul.c](#).

6.6.2 Macro Definition Documentation

6.6.2.1 #define ADC_FIFO 0x10000

Size of the FIFO to emulate in the driver

Definition at line 64 of file [adc_hd_simul.c](#).

Referenced by [main\(\)](#).

6.6.2.2 #define ADC_NUM_DATA 0x80000

Amount of data we want from the board

Definition at line 60 of file [adc_hd_simul.c](#).

Referenced by [main\(\)](#).

6.6.2.3 #define ADC_NUM_INTS (ADC_NUM_DATA/(ADC_FIFO/2))

Number of user ISR interrupts until we have the amount of data we want.

Definition at line 76 of file [adc_hd_simul.c](#).

Referenced by [main\(\)](#).

6.6.2.4 `#define ADC_RATE 50000`

A/D Sampling rate

Definition at line 84 of file `adc_hd_simul.c`.

Referenced by `main()`.

6.6.2.5 `#define HD_FIFO 0x8000`

Size of the FIFO to emulate in the driver

Definition at line 72 of file `adc_hd_simul.c`.

Referenced by `main()`.

6.6.2.6 `#define HD_NUM_DATA 0x80000`

Amount of data we want from the board

Definition at line 68 of file `adc_hd_simul.c`.

Referenced by `main()`.

6.6.2.7 `#define HD_NUM_INTS (HD_NUM_DATA/(HD_FIFO/2))`

Number of user ISR interrupts until we have the amount of data we want.

Definition at line 80 of file `adc_hd_simul.c`.

Referenced by `main()`.

6.6.2.8 `#define HSDIN_RATE 30000`

HD Sampling rate

Definition at line 88 of file `adc_hd_simul.c`.

Referenced by `main()`.

6.6.3 Variable Documentation

6.6.3.1 `DM75xx_Board_Descriptor* board`

Board descriptor

Definition at line 92 of file `adc_hd_simul.c`.

6.6.3.2 `volatile int dma_0_ints [static]`

Variable used to count how many interrupts occurred

Definition at line 52 of file `adc_hd_simul.c`.

Referenced by `ISR()`, and `main()`.

6.6.3.3 `volatile int dma_1_ints [static]`

Variable used to count how many interrupts occurred

Definition at line 56 of file `adc_hd_simul.c`.

Referenced by `ISR()`, and `main()`.

6.6.3.4 `char* program_name` `[static]`

Name of the program as invoked on the command line.

Definition at line 48 of file `adc_hd_simul.c`.

Referenced by `main()`, and `usage()`.

6.7 examples/adc_multi.c File Reference

Demonstrates the use of Analog to Digital Burst sampling.

```
#include <errno.h>
#include <error.h>
#include <fcntl.h>
#include <getopt.h>
#include <limits.h>
#include <signal.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include "dm75xx_library.h"
```

Macros

- `#define NUM_CHANNELS` 16
- `#define BURST_RATE` 1000000
- `#define PACER_RATE` 100000

Functions

- static void `usage` (void)
Print information on stderr about how the program is to be used. After doing so, the program is exited.
- int `main` (int argument_count, char **arguments)
Main program code.

Variables

- static char * `program_name`

6.7.1 Detailed Description

Demonstrates the use of Analog to Digital Burst sampling.

This example program using the Pacer Clock and Burst Clock to perform Burst sampling. Burst sampling is near simultaneous sampling of a given number of channels as configured per the channel gain table. In this

example we sample from all 16 channels on each Pacer Clock conversion signal. Samples are acquired until the FIFO is filled then they are printed to the screen.

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-----
```

```
$Id: adc_multi.c 99065 2016-04-26 18:03:23Z rgroner $
```

Definition in file [adc_multi.c](#).

6.7.2 Macro Definition Documentation

6.7.2.1 #define BURST_RATE 1000000

Burst Clock Rate

Definition at line 57 of file [adc_multi.c](#).

Referenced by [main\(\)](#).

6.7.2.2 #define NUM_CHANNELS 16

The number of channels to sample

Definition at line 53 of file [adc_multi.c](#).

Referenced by [main\(\)](#).

6.7.2.3 #define PACER_RATE 100000

Pacer Clock Rate

Definition at line 61 of file [adc_multi.c](#).

Referenced by [main\(\)](#).

6.7.3 Variable Documentation

6.7.3.1 char* program_name [static]

Name of the program as invoked on the command line.

Definition at line 49 of file [adc_multi.c](#).

Referenced by [main\(\)](#), and [usage\(\)](#).

6.8 examples/adc_single.c File Reference

Demonstrates the use of Analog to Digital Conversion.


```
#include <errno.h>
#include <error.h>
#include <fcntl.h>
#include <getopt.h>
#include <limits.h>
#include <signal.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include "dm75xx_library.h"
```

Macros

- `#define ADC_RATE 10000`

Functions

- static void `usage` (void)
Print information on stderr about how the program is to be used. After doing so, the program is exited.
- int `main` (int argument_count, char **arguments)
Main program code.

Variables

- static char * `program_name`

6.8.1 Detailed Description

Demonstrates the use of Analog to Digital Conversion.

This example program demonstrates simple Analog sampling on a single channel. When sampling on a signal channel the channel gain table latch must be set as shown in this example program. Samples are gathered until the FIFO is filled, then they are printed to the screen.

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-----
```

```
$Id: adc_single.c 99107 2016-04-27 21:09:01Z rgroner $
```

Definition in file `adc_single.c`.

6.8.2 Macro Definition Documentation

6.8.2.1 `#define ADC_RATE 10000`

Sample rate

Definition at line 51 of file `adc_single.c`.

Referenced by `main()`.

6.8.3 Variable Documentation

6.8.3.1 `char* program_name [static]`

Name of the program as invoked on the command line.

Definition at line 47 of file `adc_single.c`.

Referenced by `main()`, and `usage()`.

6.9 examples/adc_soft_trig.c File Reference

Demonstrates the use of the Software Trigger.

```
#include <errno.h>
#include <error.h>
#include <fcntl.h>
#include <getopt.h>
#include <limits.h>
#include <signal.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include "dm75xx_library.h"
```

Functions

- static void `usage` (void)
Print information on stderr about how the program is to be used. After doing so, the program is exited.
- static void `sigint_handler` (int sig_num)
Exit gracefully if the user enters CTRL-C.
- int `main` (int argument_count, char **arguments)
Main program code.

Variables

- static char * `program_name`
- int `exit_program` = 0

6.9.1 Detailed Description

Demonstrates the use of the Software Trigger.

This example program demonstrates simple Analog sampling on a single channel using software triggering.

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-----
```

```
$Id: adc_soft_trig.c 99065 2016-04-26 18:03:23Z rgroner $
```

Definition in file [adc_soft_trig.c](#).

6.9.2 Variable Documentation

6.9.2.1 int exit_program = 0

Flag indicating the user wants to exit.

Definition at line 50 of file [adc_soft_trig.c](#).

Referenced by [main\(\)](#), and [sigint_handler\(\)](#).

6.9.2.2 char* program_name [static]

Name of the program as invoked on the command line.

Definition at line 45 of file [adc_soft_trig.c](#).

Referenced by [main\(\)](#), and [usage\(\)](#).

6.10 examples/adc_trig_ext.c File Reference

Demonstrates the use of Analog to Digital sampling via external trigger.

```
#include <errno.h>
#include <error.h>
#include <fcntl.h>
#include <getopt.h>
#include <limits.h>
#include <signal.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <sys/select.h>
#include <unistd.h>
#include "dm75xx_library.h"
```

Macros

- `#define FIFO 0x1000`
- `#define NUM_DATA (FIFO * 4)`

- `#define NUM_INTS (NUM_DATA/(FIFO/2))`
- `#define ADC_RATE 1000`

Functions

- static void `usage` (void)
Print information on stderr about how the program is to be used. After doing so, the program is exited.
- static void `sigint_handler` (int sig_num)
Exit gracefully if the user enters CTRL-C.
- void `ISR` (uint32_t status)
User-Space ISR.
- int `kbhit` (void)
Implementation of `kbhit()`
- int `main` (int argument_count, char **arguments)
Main program code.

Variables

- static char * `program_name`
- static volatile int `interrupts`
- `DM75xx_Board_Descriptor` * `board`

6.10.1 Detailed Description

Demonstrates the use of Analog to Digital sampling via external trigger.

This example program uses the external trigger to toggle the Pacer Clock. While the External Trigger is high the Pacer Clock will run and while it is low the Pacer Clock will stop. The status of the Pacer Clock will be printed to the screen as External Trigger Edge interrupts are received by the user-space ISR.

Digital I/O Port 1 is used as an input to the external trigger. The value on Port 1 is toggled with the strike of a key on the keyboard. This effectively enables/disables acquisition.

Note: This program uses DMA

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```

```
$Id: adc_trig_ext.c 99065 2016-04-26 18:03:23Z rgroner $
```

Definition in file `adc_trig_ext.c`.

6.10.2 Macro Definition Documentation

6.10.2.1 `#define ADC_RATE 1000`

Sampling rate

Definition at line 75 of file `adc_trig_ext.c`.

Referenced by `main()`.

6.10.2.2 `#define FIFO 0x1000`

Size of the FIFO to emulate in the driver

Definition at line 63 of file `adc_trig_ext.c`.

Referenced by `main()`.

6.10.2.3 `#define NUM_DATA (FIFO * 4)`

Amount of data we want from the board

Definition at line 67 of file `adc_trig_ext.c`.

Referenced by `main()`.

6.10.2.4 `#define NUM_INTS (NUM_DATA/(FIFO/2))`

Number of user ISR interrupts until we have the amount of data we want.

Definition at line 71 of file `adc_trig_ext.c`.

Referenced by `main()`.

6.10.3 Variable Documentation

6.10.3.1 `DM75xx_Board_Descriptor* board`

Board descriptor

Definition at line 79 of file `adc_trig_ext.c`.

6.10.3.2 `volatile int interrupts` `[static]`

Variable used to count how many interrupts occurred

Definition at line 59 of file `adc_trig_ext.c`.

Referenced by `ISR()`, and `main()`.

6.10.3.3 `char* program_name` `[static]`

Name of the program as invoked on the command line.

Definition at line 55 of file `adc_trig_ext.c`.

Referenced by `main()`, and `usage()`.

6.11 examples/adio_event.c File Reference

Demonstrates the use of the Digital I/O Event Mode to generate interrupts.

```
#include <errno.h>
#include <error.h>
#include <fcntl.h>
#include <getopt.h>
#include <limits.h>
#include <signal.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include "dm75xx_library.h"
```

Functions

- static void [usage](#) (void)
Print information on stderr about how the program is to be used. After doing so, the program is exited.
- void [ISR](#) (uint32_t status)
User-Space ISR.
- int [main](#) (int argument_count, char **arguments)
Main program code.

Variables

- static char * [program_name](#)
- [DM75xx_Board_Descriptor](#) * [board](#)
- int [interrupts](#)

6.11.1 Detailed Description

Demonstrates the use of the Digital I/O Event Mode to generate interrupts.

Unlike Match mode where an interrupt only occurs when Port 0 contains a certain value, event mode interrupts are triggered whenever the value at Port 0 changes. The same value array used in the match mode example is iterated through here, and you will see an interrupt triggered each time.

Port0 must be connected to Port1 bit-per-bit (Port0 bit 0 connected to Port1 bit 0 and so on...).

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```

```
$Id: adio_event.c 99065 2016-04-26 18:03:23Z rgroner $
```

Definition in file [adio_event.c](#).

6.11.2 Variable Documentation

6.11.2.1 DM75xx_Board_Descriptor* board

Board's device descriptor

Definition at line 56 of file adio_event.c.

6.11.2.2 int interrupts

Variable to count interrupts

Definition at line 60 of file adio_event.c.

Referenced by ISR(), and main().

6.11.2.3 char* program_name [static]

Program name as invoked on the command line.

Definition at line 52 of file adio_event.c.

Referenced by main(), and usage().

6.12 examples/adio_match.c File Reference

Demonstrates the use of the Digital I/O Match Mode to generate interrupts.

```
#include <errno.h>
#include <error.h>
#include <fcntl.h>
#include <getopt.h>
#include <limits.h>
#include <signal.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include "dm75xx_library.h"
```

Functions

- static void [usage](#) (void)
Print information on stderr about how the program is to be used. After doing so, the program is exited.
- void [ISR](#) (uint32_t status)
User-Space ISR.
- int [main](#) (int argument_count, char **arguments)
Main program code.

Variables

- static char * [program_name](#)
- [DM75xx_Board_Descriptor](#) * [board](#)
- int [interrupts](#)

6.12.1 Detailed Description

Demonstrates the use of the Digital I/O Match Mode to generate interrupts.

The compare register is first set to 0xAB. When this value is written out Port1 and received by Port0 an interrupt is received. In the user-space ISR, the DIO interrupt is cleared and the compare register is changed to 0x3C. When 0x3C is written out Port1 and received by Port0 another interrupt is received.

Port0 must be connected to Port1 bit-per-bit (Port0 bit 0 connected to Port1 bit 0 and so on ...).

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-----
```

```
$Id: adio_match.c 99065 2016-04-26 18:03:23Z rgroner $
```

Definition in file [adio_match.c](#).

6.12.2 Variable Documentation

6.12.2.1 DM75xx_Board_Descriptor* board

Board's device descriptor

Definition at line 56 of file `adio_match.c`.

6.12.2.2 int interrupts

Variable to count the number of interrupts

Definition at line 60 of file `adio_match.c`.

Referenced by `ISR()`, and `main()`.

6.12.2.3 char* program_name [static]

Program name as invoked on the command line.

Definition at line 52 of file `adio_match.c`.

Referenced by `main()`, and `usage()`.

6.13 examples/analog_dio.c File Reference

Demonstrates the use of Analog DIO Connector on the SDM7540.


```
#include <errno.h>
#include <error.h>
#include <fcntl.h>
#include <getopt.h>
#include <limits.h>
#include <signal.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include "dm75xx_library.h"
```

Functions

- static void [usage](#) (void)
Print information on stderr about how the program is to be used. After doing so, the program is exited.
- void [ISR](#) (uint32_t status)
User-Space ISR.
- int [main](#) (int argument_count, char **arguments)
Main program code.

Variables

- static char * [program_name](#)
- unsigned int [interrupts](#)

6.13.1 Detailed Description

Demonstrates the use of Analog DIO Connector on the SDM7540.

This example shows use of the Analog Connector DIO. This consists of pins 1 and 2 on CN9 of the SDM7540. In this particular example, pin 1 is set as an output and pin 2 is set as an input. Pin 2 rising edge interrupt is enabled. Pulses are sent out pin 1 until pin 2 receives 2 interrupts. Pin 1 should be connect to pin 2.

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\$Id: analog_dio.c 99065 2016-04-26 18:03:23Z rgroner \$

Definition in file [analog_dio.c](#).

6.13.2 Variable Documentation

6.13.2.1 unsigned int interrupts

Global used to keep track of the nubmer of interrupts received

Definition at line 52 of file analog_dio.c.

Referenced by ISR().

6.13.2.2 char* program_name [static]

Name of the program as invoked on the command line.

Definition at line 48 of file analog_dio.c.

Referenced by main(), and usage().

6.14 examples/calibrate.c File Reference

Demonstrates auto-calibration of SDM7540/8540.

```
#include <errno.h>
#include <error.h>
#include <fcntl.h>
#include <getopt.h>
#include <limits.h>
#include <signal.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <time.h>
#include <unistd.h>
#include "dm75xx_library.h"
```

Functions

- static void [usage](#) (void)
Print information on stderr about how the program is to be used. After doing so, the program is exited.
- int [main](#) (int argument_count, char **arguments)
Main program code.

Variables

- static char * [program_name](#)

6.14.1 Detailed Description

Demonstrates auto-calibration of SDM7540/8540.

This program utilizes the on-board DSP to auto calibrate the A/D and D/A converters.

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```
$Id: calibrate.c 99065 2016-04-26 18:03:23Z rgroner $
```

Definition in file [calibrate.c](#).

6.14.2 Variable Documentation

6.14.2.1 `char* program_name` [static]

Name of the program as invoked on the command line.

Definition at line 46 of file `calibrate.c`.

Referenced by `main()`, and `usage()`.

6.15 examples/cgt_reset_intrpt.c File Reference

Demonstrates the use of the Channge Gain Reset Interrupt.

```
#include <errno.h>
#include <error.h>
#include <fcntl.h>
#include <getopt.h>
#include <limits.h>
#include <signal.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include "dm75xx_library.h"
```

Macros

- `#define NUM_CHANNELS` 16
- `#define ADC_RATE` 200

Functions

- static void `usage` (void)
Print information on stderr about how the program is to be used. After doing so, the program is exited.
- void `ISR` (uint32_t status)
User-Space ISR.
- int `main` (int argument_count, char **arguments)
Main program code.

Variables

- static char * `program_name`
- int `interrupts`

6.15.1 Detailed Description

Demonstrates the use of the Channge! Gain Reset Interrupt.

This example program will gather samples on each of the 16 channels triggered by the Pacer Clock. Every 16 samples the channel gain table will reset back to the beginning. When this reset occurs a channel gain table reset will be received.

The program will receive 64 CGT reset interrupts before quitting.

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-----
```

```
$Id: cgt_reset_intrpt.c 99065 2016-04-26 18:03:23Z rgroner $
```

Definition in file [cgt_reset_intrpt.c](#).

6.15.2 Macro Definition Documentation

6.15.2.1 `#define ADC_RATE 200`

Sample rate

Definition at line 61 of file `cgt_reset_intrpt.c`.

Referenced by `main()`.

6.15.2.2 `#define NUM_CHANNELS 16`

The number of channels to sample

Definition at line 53 of file `cgt_reset_intrpt.c`.

Referenced by `main()`.

6.15.3 Variable Documentation

6.15.3.1 `int interrupts`

Global used to keep track of the number of interrupts received.

Definition at line 57 of file `cgt_reset_intrpt.c`.

Referenced by `ISR()`, and `main()`.

6.15.3.2 `char* program_name [static]`

Name of the program as invoked on the command line.

Definition at line 49 of file `cgt_reset_intrpt.c`.

Referenced by `main()`, and `usage()`.

6.16 examples/dac.c File Reference

Demonstrates the use of Digital to Analog conversion.

```
#include <errno.h>
#include <error.h>
#include <fcntl.h>
#include <getopt.h>
#include <limits.h>
#include <math.h>
#include <signal.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include "dm75xx_library.h"
```

Macros

- `#define DAC_RATE 10000`

Functions

- static void `usage` (void)
Print information on stderr about how the program is to be used. After doing so, the program is exited.
- int `main` (int argument_count, char **arguments)
Main program code.

Variables

- static char * `program_name`

6.16.1 Detailed Description

Demonstrates the use of Digital to Analog conversion.

This example program produces a Sine Wave on DAC1 and a Saw-Toothed wave on DAC2.

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-----
```

```
$Id: dac.c 99065 2016-04-26 18:03:23Z rgroner $
```

Definition in file [dac.c](#).

6.16.2 Macro Definition Documentation

6.16.2.1 #define DAC_RATE 10000

Sample rate

Definition at line 50 of file dac.c.

Referenced by main().

6.16.3 Variable Documentation

6.16.3.1 char* program_name [static]

Program name as invoked on the command line

Definition at line 46 of file dac.c.

Referenced by main(), and usage().

6.17 examples/dac_dma.c File Reference

Demonstrates the use of Digital to Analog conversion with DMA.

```
#include <errno.h>
#include <error.h>
#include <fcntl.h>
#include <getopt.h>
#include <limits.h>
#include <math.h>
#include <signal.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include "dm75xx_library.h"
```

Macros

- #define [FIFO](#) 0x10000
- #define [DAC_RATE](#) 100000

Functions

- static void [usage](#) (void)
Print information on stderr about how the program is to be used. After doing so, the program is exited.
- static void [sigint_handler](#) (int sig_num)
Exit gracefully if the user enters CTRL-C.
- void [ISR](#) (uint32_t status)
User-Space ISR.
- int [main](#) (int argument_count, char **arguments)
Main program code.

Variables

- static char * [program_name](#)
- static volatile int [interrupts](#)
- volatile uint8_t [exit_program](#)

6.17.1 Detailed Description

Demonstrates the use of Digital to Analog conversion with DMA.

This program displays a Sine Wave out DAC2. This sign wave is repeated via DMA and continued to be displayed until the user presses CTRL+C to end the program.

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-----
```

```
$Id: dac_dma.c 99065 2016-04-26 18:03:23Z rgroner $
```

Definition in file [dac_dma.c](#).

6.17.2 Macro Definition Documentation

6.17.2.1 #define DAC_RATE 100000

Sample rate

Definition at line 59 of file [dac_dma.c](#).

Referenced by [main\(\)](#).

6.17.2.2 #define FIFO 0x10000

Size of the FIFO to emulate in the driver

Definition at line 55 of file [dac_dma.c](#).

Referenced by [main\(\)](#).

6.17.3 Variable Documentation

6.17.3.1 volatile uint8_t exit_program

Variable to allow graceful exit from Ctrl-C

Definition at line 63 of file [dac_dma.c](#).

Referenced by [main\(\)](#), and [sigint_handler\(\)](#).

6.17.3.2 `volatile int interrupts` `[static]`

Variable used to count how many interrupts occurred

Definition at line 51 of file `dac_dma.c`.

Referenced by `ISR()`, and `main()`.

6.17.3.3 `char* program_name` `[static]`

Program name as invoked on the command line

Definition at line 47 of file `dac_dma.c`.

Referenced by `main()`, and `usage()`.

6.18 `examples/delay_intrpt.c` File Reference

This example program demonstrates the use of the Delay Counter Interrupt.

```
#include <errno.h>
#include <error.h>
#include <fcntl.h>
#include <getopt.h>
#include <limits.h>
#include <signal.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include "dm75xx_library.h"
```

Macros

- `#define ADC_RATE 10`

Functions

- static void `usage` (void)
Print information on stderr about how the program is to be used. After doing so, the program is exited.
- void `ISR` (uint32_t status)
User-Space ISR.
- int `main` (int argument_count, char **arguments)
Main program code.

Variables

- static char * `program_name`
- static int `interrupts`

6.18.1 Detailed Description

This example program demonstrates the use of the Delay Counter Interrupt.

Samples are gathered via the Pacer Clock which is triggered by Delay Software Start. It will wait to collect samples until 10 samples have been read then it will collect 10 samples. This process will be repeated via use of the delay and about counters. An interrupt will occur each time the delay counter hits 0 delay counter.

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-----
```

```
$Id: delay_intrpt.c 99065 2016-04-26 18:03:23Z rgroner $
```

Definition in file [delay_intrpt.c](#).

6.18.2 Macro Definition Documentation

6.18.2.1 #define ADC_RATE 10

Sampling rate

Definition at line 56 of file delay_intrpt.c.

Referenced by main().

6.18.3 Variable Documentation

6.18.3.1 int interrupts [static]

Variable used to count how many interrupts occurred

Definition at line 52 of file delay_intrpt.c.

Referenced by ISR(), and main().

6.18.3.2 char* program_name [static]

Name of the program as invoked on the command line.

Definition at line 48 of file delay_intrpt.c.

Referenced by main(), and usage().

6.19 examples/dma_pci_arb.c File Reference

Demonstrates the ability to DMA to an arbitrary PCI address.

```
#include <errno.h>
#include <error.h>
#include <fcntl.h>
#include <getopt.h>
#include <limits.h>
#include <signal.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include "dm75xx_library.h"
```

Macros

- #define `FIFO` 0x10000
- #define `NUM_DATA` (FIFO * 2)
- #define `NUM_INTS` (NUM_DATA/(FIFO/2))
- #define `ADC_RATE` 100000

Functions

- static void `usage` (void)
Print information on stderr about how the program is to be used. After doing so, the program is exited.
- static void `sigint_handler` (int sig_num)
Exit gracefully if the user enters CTRL-C.
- void `ISR` (uint32_t status)
User-Space ISR.
- int `main` (int argument_count, char **arguments)
Main program code.

Variables

- static char * `program_name`
- static int `interrupts`
- `DM75xx_Board_Descriptor` * `board`

6.19.1 Detailed Description

Demonstrates the ability to DMA to an arbitrary PCI address.

This program will perform one 8k DMA transfer to video buffer. This example program is used as a proof of concept that DMA is possible to an arbitrary PCI address. This is useful if you want to DMA data directly to another device, such as a DSP.

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```
$Id: dma_pci_arb.c 99065 2016-04-26 18:03:23Z rgroner $
```

Definition in file [dma_pci_arb.c](#).

6.19.2 Macro Definition Documentation

6.19.2.1 `#define ADC_RATE 100000`

Sampling rate

Definition at line 67 of file [dma_pci_arb.c](#).

Referenced by [main\(\)](#).

6.19.2.2 `#define FIFO 0x10000`

Size of the FIFO, in samples, to emulate in the driver

Definition at line 55 of file [dma_pci_arb.c](#).

Referenced by [main\(\)](#).

6.19.2.3 `#define NUM_DATA (FIFO * 2)`

Amount of data, in samples, we want from the board

Definition at line 59 of file [dma_pci_arb.c](#).

6.19.2.4 `#define NUM_INTS (NUM_DATA/(FIFO/2))`

Number of user ISR interrupts until we have the amount of data we want.

Definition at line 63 of file [dma_pci_arb.c](#).

Referenced by [ISR\(\)](#), and [main\(\)](#).

6.19.3 Variable Documentation

6.19.3.1 `DM75xx_Board_Descriptor* board`

Board descriptor

Definition at line 71 of file [dma_pci_arb.c](#).

6.19.3.2 `int interrupts [static]`

Variable used to count how many interrupts occurred

Definition at line 51 of file [dma_pci_arb.c](#).

Referenced by [ISR\(\)](#), and [main\(\)](#).

6.19.3.3 `char* program_name [static]`

Name of the program as invoked on the command line.

Definition at line 47 of file [dma_pci_arb.c](#).

Referenced by [main\(\)](#), and [usage\(\)](#).

6.20 examples/etrig_intrpt.c File Reference

Demonstrates the use of the External Trigger rising/falling interrupts.

```
#include <errno.h>
#include <error.h>
#include <fcntl.h>
#include <getopt.h>
#include <limits.h>
#include <signal.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include "dm75xx_library.h"
```

Macros

- `#define RISING_EDGE 0`
- `#define FALLING_EDGE 1`

Functions

- static void `usage` (void)
Print information on stderr about how the program is to be used. After doing so, the program is exited.
- void `ISR` (uint32_t status)
User-Space ISR.
- int `main` (int argument_count, char **arguments)
Main program code.

Variables

- static char * `program_name`
- `DM75xx_Board_Descriptor` * `board`
- uint8_t `interrupts`
- uint16_t `edge_val`

6.20.1 Detailed Description

Demonstrates the use of the External Trigger rising/falling interrupts.

This program uses UTC1 out to set off the interrupts. User Timer/Counter 1 Out Pin must be routed to External Trigger Pin. This should cause an interrupt to be received every second.

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-----
```

```
$Id: etrig_intrpt.c 99065 2016-04-26 18:03:23Z rgroner $
```

Definition in file [etrig_intrpt.c](#).

6.20.2 Macro Definition Documentation

6.20.2.1 `#define FALLING_EDGE 1`

Value to denote falling edge interrupts

Definition at line 58 of file [etrig_intrpt.c](#).

Referenced by [main\(\)](#).

6.20.2.2 `#define RISING_EDGE 0`

Value to denote rising edge interrupts

Definition at line 54 of file [etrig_intrpt.c](#).

Referenced by [main\(\)](#).

6.20.3 Variable Documentation

6.20.3.1 `DM75xx_Board_Descriptor* board`

Board's device descriptor

Definition at line 50 of file [etrig_intrpt.c](#).

6.20.3.2 `uint16_t edge_val`

Global used to indicate which edge value we will interrupt on.

Definition at line 66 of file [etrig_intrpt.c](#).

Referenced by [ISR\(\)](#), and [main\(\)](#).

6.20.3.3 `uint8_t interrupts`

Global used to keep track of the number of interrupts received.

Definition at line 62 of file [etrig_intrpt.c](#).

Referenced by [ISR\(\)](#), and [main\(\)](#).

6.20.3.4 `char* program_name [static]`

Program name as invoked on the command line.

Definition at line 46 of file [etrig_intrpt.c](#).

Referenced by [main\(\)](#), and [usage\(\)](#).

6.21 examples/hd.c File Reference

Demonstrates the use of high speed digital data acquisition.

```
#include <errno.h>
#include <error.h>
#include <fcntl.h>
#include <getopt.h>
#include <limits.h>
#include <signal.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include "dm75xx_library.h"
```

Macros

- `#define` [TIMER_RATE](#) 50000

Functions

- static void [usage](#) (void)
Print information on stderr about how the program is to be used. After doing so, the program is exited.
- int [main](#) (int argument_count, char **arguments)
Main program code.

Variables

- static char * [program_name](#)

6.21.1 Detailed Description

Demonstrates the use of high speed digital data acquisition.

This example program simply gathers high speed digital data and displays it to the screen when the FIFO is filled.

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-----
```

```
$Id: hd.c 99065 2016-04-26 18:03:23Z rgroner $
```

Definition in file [hd.c](#).

6.21.2 Macro Definition Documentation

6.21.2.1 `#define` [TIMER_RATE](#) 50000

Rate of high speed acquisition

Definition at line 49 of file hd.c.

Referenced by main().

6.21.3 Variable Documentation

6.21.3.1 char* program_name [static]

Name of the program as invoked on the command line.

Definition at line 45 of file hd.c.

Referenced by main(), and usage().

6.22 examples/hd_dma.c File Reference

Demonstrates the use of High Speed Digital acquisition via DMA.

```
#include <errno.h>
#include <error.h>
#include <fcntl.h>
#include <getopt.h>
#include <limits.h>
#include <signal.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include "dm75xx_library.h"
```

Macros

- `#define NUM_DATA 0x10000`
- `#define FIFO 0x4000`
- `#define NUM_INTS (NUM_DATA/(FIFO/2))`
- `#define RATE 50000`

Functions

- static void `usage` (void)
Print information on stderr about how the program is to be used. After doing so, the program is exited.
- static void `sigint_handler` (int sig_num)
Exit gracefully if the user enters CTRL-C.
- void `ISR` (uint32_t status)
User-Space ISR.
- int `main` (int argument_count, char **arguments)
Main program code.

Variables

- static char * `program_name`
- static int `interrupts`
- `DM75xx_Board_Descriptor` * `board`

6.22.1 Detailed Description

Demonstrates the use of High Speed Digital acquisition via DMA.

This example program uses UTC1 as a demand mode source for HSDIN DMA operations. UTC1 will act as a sample counter and each time FIFO Half is counted it will trigger a demand mode DMA.

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-----
```

```
$Id: hd_dma.c 99065 2016-04-26 18:03:23Z rgroner $
```

Definition in file [hd_dma.c](#).

6.22.2 Macro Definition Documentation

6.22.2.1 #define FIFO 0x4000

Size of the FIFO to emulate in the driver

Definition at line 58 of file `hd_dma.c`.

Referenced by `main()`.

6.22.2.2 #define NUM_DATA 0x10000

Amount of data we want from the board

Definition at line 54 of file `hd_dma.c`.

Referenced by `main()`.

6.22.2.3 #define NUM_INTS (NUM_DATA/(FIFO/2))

Number of user ISR interrupts until we have the amount of data we want.

Definition at line 62 of file `hd_dma.c`.

Referenced by `main()`.

6.22.2.4 #define RATE 50000

Rate at which samples are collected

Definition at line 66 of file `hd_dma.c`.

Referenced by `main()`.

6.22.3 Variable Documentation

6.22.3.1 DM75xx_Board_Descriptor* board

Board descriptor

Definition at line 70 of file `hd_dma.c`.

6.22.3.2 `int interrupts` `[static]`

Variable used to count how many interrupts occurred

Definition at line 50 of file `hd_dma.c`.

Referenced by `ISR()`, and `main()`.

6.22.3.3 `char* program_name` `[static]`

Name of the program as invoked on the command line.

Definition at line 46 of file `hd_dma.c`.

Referenced by `main()`, and `usage()`.

6.23 examples/library_test.c File Reference

Program which tests the basic functionality of the library.

```
#include <errno.h>
#include <error.h>
#include <fcntl.h>
#include <getopt.h>
#include <limits.h>
#include <signal.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include "dm75xx_library.h"
```

Functions

- static void `usage` (void)
Print information on stderr about how the program is to be used. After doing so, the program is exited.
- static void `expect_failure_and_check` (int status, int expected)
Checks to make sure the correct error code was returned.
- static void `expect_success` (int status)
Validates a successful return code.
- int `main` (int argument_count, char **arguments)
Main program code.

Variables

- static char * `program_name`

6.23.1 Detailed Description

Program which tests the basic functionality of the library.

This program is used to test the library API. It passes various valid and invalid parameters to each library function to ensure that only acceptable values are considered valid.

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-----
```

Warning

This program ABSOLUTELY IS NOT INTENDED to be an example of how to program a board. Some of the techniques appearing herein can lead to erratic program or system behavior and are used only to cause specific error conditions.

```
$Id: library_test.c 65468 2012-12-04 19:42:58Z rgroner $
```

Definition in file [library_test.c](#).

6.23.2 Variable Documentation

6.23.2.1 `char* program_name` [static]

Name of the program as invoked on the command line.

Definition at line 52 of file `library_test.c`.

Referenced by `main()`, and `usage()`.

6.24 examples/temperature.c File Reference

Demonstrates the use of the SDM7540's on board temp sensor.

```
#include <errno.h>
#include <error.h>
#include <fcntl.h>
#include <getopt.h>
#include <limits.h>
#include <signal.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include "dm75xx_library.h"
```

Functions

- static void [usage](#) (void)

Print information on stderr about how the program is to be used. After doing so, the program is exited.

- int [main](#) (int argument_count, char **arguments)

Main program code.

Variables

- static char * [program_name](#)

6.24.1 Detailed Description

Demonstrates the use of the SDM7540's on board temp sensor.

This example will show how to use the SDM7540 family on board temperature sensor which is on the I2C bus.

```
-----
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```

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-----
```

```
$Id: temperature.c 99065 2016-04-26 18:03:23Z rgroner $
```

Definition in file [temperature.c](#).

6.24.2 Variable Documentation

6.24.2.1 char* program_name [static]

Name of the program as invoked on the command line.

Definition at line 45 of file [temperature.c](#).

Referenced by [main\(\)](#), and [usage\(\)](#).

6.25 examples/timer.c File Reference

Demonstrates the use of the User Timer/Counters for keeping time.

```
#include <errno.h>
#include <error.h>
#include <fcntl.h>
#include <getopt.h>
#include <limits.h>
#include <signal.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include "dm75xx_library.h"
```

Macros

- `#define` [TIMER_RATE](#) 200

Functions

- static void [usage](#) (void)
Print information on stderr about how the program is to be used. After doing so, the program is exited.
- static void [sigint_handler](#) (int sig_num)
Exit gracefully if the user enters CTRL-C.
- int [main](#) (int argument_count, char **arguments)
Main program code.

Variables

- static char * [program_name](#)
- volatile uint8_t [exit_program](#)

6.25.1 Detailed Description

Demonstrates the use of the User Timer/Counters for keeping time.

This example program demonstrates using the 8254 User Timer/Counters as a simple time keeper.

UTC 1 is being fed by UTC 0

```
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-----

$Id: timer.c 99065 2016-04-26 18:03:23Z rgroner $
```

Definition in file [timer.c](#).

6.25.2 Macro Definition Documentation

6.25.2.1 `#define` [TIMER_RATE](#) 200

Rate of the Timer.

Definition at line 47 of file [timer.c](#).

Referenced by [main\(\)](#).

6.25.3 Variable Documentation

6.25.3.1 volatile uint8_t [exit_program](#)

Variable to allow graceful exit from Ctrl-C

Definition at line 55 of file timer.c.

Referenced by main(), and sigint_handler().

6.25.3.2 char* program_name [static]

Program name as invoked on the command line.

Definition at line 51 of file timer.c.

Referenced by main(), and usage().

6.26 examples/timer_intrpt.c File Reference

Demonstrates the use of the User Timer/Counter Out Interrupts.

```
#include <errno.h>
#include <error.h>
#include <fcntl.h>
#include <getopt.h>
#include <limits.h>
#include <signal.h>
#include <stdint.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include "dm75xx_library.h"
```

Macros

- #define [UTC0](#) 8000
- #define [UTC1](#) 2000

Functions

- static void [usage](#) (void)
Print information on stderr about how the program is to be used. After doing so, the program is exited.
- void [ISR](#) (uint32_t status)
User-Space ISR.
- int [main](#) (int argument_count, char **arguments)
Main program code.

Variables

- static char * [program_name](#)
- [DM75xx_Board_Descriptor](#) * [board](#)
- uint8_t [utc1_int](#)
- uint8_t [utc1_int_inverted](#)

6.26.1 Detailed Description

Demonstrates the use of the User Timer/Counter Out Interrupts.

UTC0 is set to 1kHz and UTC1 is set to 1Hz. An interrupt will occur every UTC1 out and UTC1 Inverted Out. This should end up causing an interrupt. Every second from each source but the interrupts will be shifted half a second apart. The program counts to ten interrupts, on each channel.

```
-----
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```

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-----
```

```
$Id: timer_intrpt.c 99065 2016-04-26 18:03:23Z rgroner $
```

Definition in file [timer_intrpt.c](#).

6.26.2 Macro Definition Documentation

6.26.2.1 #define UTC0 8000

Rate of user timer/counter 0

Definition at line 47 of file timer_intrpt.c.

Referenced by main().

6.26.2.2 #define UTC1 2000

Rate of user timer/counter 1

Definition at line 51 of file timer_intrpt.c.

Referenced by main().

6.26.3 Variable Documentation

6.26.3.1 DM75xx_Board_Descriptor* board

Board's device descriptor

Definition at line 59 of file timer_intrpt.c.

6.26.3.2 char* program_name [static]

Program name as invoked on the command line.

Definition at line 55 of file timer_intrpt.c.

Referenced by main(), and usage().

6.26.3.3 `uint8_t utc1_int`

Global used to keep track of the number of interrupts received.

Definition at line 63 of file `timer_intrpt.c`.

Referenced by `ISR()`, and `main()`.

6.26.3.4 `uint8_t utc1_int_inverted`

Global used to keep track of the number of interrupts received.

Definition at line 67 of file `timer_intrpt.c`.

Referenced by `ISR()`, and `main()`.

6.27 `include/dm75xx_driver.h` File Reference

Definitions for the DM75xx driver.

```
#include <linux/fs.h>
#include <linux/list.h>
#include <linux/pci.h>
#include <linux/spinlock.h>
#include <linux/types.h>
#include "dm75xx_ioctl.h"
#include "dm75xx_types.h"
#include "dm75xx_kernel.h"
```

Data Structures

- struct [dm75xx_pci_region](#)
DM75xx PCI region descriptor. This structure holds information about one of a device's PCI memory regions.
- struct [dm75xx_dma_chain_descriptor](#)
Dm75xx DMA chaining descriptor.
- struct [dm75xx_dma_descriptor](#)
DM75xx DMA buffer descriptor. This structure holds allocation information for a single DMA buffer.
- struct [dm75xx_device_descriptor](#)
DM75xx device descriptor. This structure holds information about a device needed by the kernel.

Macros

- `#define` [DM75xx_DEVICE_NAME_LENGTH](#) 22
Maximum number of characters in device's name.
- `#define` [DM7520_PCI_DEVICE_ID](#) 0x7520
DM7520 PCI device ID.
- `#define` [DM7540_PCI_DEVICE_ID](#) 0x7540
DM7540 PCI device ID.
- `#define` [RTD_PCI_VENDOR_ID](#) 0x1435
RTD Embedded Technologies PCI vendor ID.
- `#define` [DM75xx_PCI_REGIONS](#) PCI_ROM_RESOURCE
Number of standard PCI regions.
- `#define` [DM75xx_DMA_CHANNELS](#) 2

- Number of FIFO channels per device.*
 • #define `DM75xx_MAX_DMA_BUFFER_SIZE` 0x20000
Maximum size in bytes of any DMA buffer.
- #define `DM75xx_INT_QUEUE_SIZE` 0x10
Maximum size in entries of the interrupt status queue.

Typedefs

- typedef enum
`dm75xx_pci_region_access_dir dm75xx_pci_region_access_dir_t`
Standard PCI region access direction type.
- typedef struct `dm75xx_pci_region dm75xx_pci_region_t`
DM75xx PCI region descriptor type.
- typedef struct
`dm75xx_dma_chain_descriptor dm75xx_dma_chain_descriptor_t`
DM75xx DMA Chaining descriptor type.
- typedef struct
`dm75xx_dma_descriptor dm75xx_dma_descriptor_t`
DM75xx DMA buffer descriptor type.
- typedef struct
`dm75xx_device_descriptor dm75xx_device_descriptor_t`
DM75xx device descriptor type.

Enumerations

- enum `dm75xx_pci_region_access_dir` { `DM75xx_PCI_REGION_ACCESS_READ` = 0, `DM75xx_PCI_REGION_ACCESS_WRITE` }
Direction of access to standard PCI region.

Functions

- static void `dm75xx_access_pci_region` (const `dm75xx_device_descriptor_t` *dm75xx, `dm75xx_pci_access_request_t` *pci_request, `dm75xx_pci_region_access_dir_t` direction)
Read from or write to one of the standard PCI regions.
- static int `dm75xx_allocate_irq` (`dm75xx_device_descriptor_t` *dm75xx, const struct pci_dev *pci_device)
Allocate an interrupt line for a DM75xx device.
- static void `dm75xx_enable_plx_interrupts` (const `dm75xx_device_descriptor_t` *dm75xx, uint8_t enable)
Enable PLX interrupts for the specified DM75xx Device.
- static void `dm75xx_enable_plx_dma` (const `dm75xx_device_descriptor_t` *dm75xx, `dm75xx_dma_channel_t` channel)
Configure PLX Mode register for the specified DMA Channel.
- static void `dm75xx_get_pci_master_status` (`dm75xx_device_descriptor_t` *dm75xx, uint8_t *pci_master)
Determine whether or not a device is PCI master capable.
- static void `dm75xx_initialize_device_descriptor` (`dm75xx_device_descriptor_t` *dm75xx)
Initialize the device descriptor for the specified DM75xx device.
- static void `dm75xx_initialize_hardware` (const `dm75xx_device_descriptor_t` *dm75xx)
Initialize the specified DM75xx device.
- `INTERRUPT_HANDLER_TYPE dm75xx_interrupt_handler` (int irq_number, void *device_id)
DM75xx device interrupt handler.
- static long `dm75xx_ioctl` (struct file *file, unsigned int request_code, unsigned long ioctl_param)
Process ioctl(2) system calls directed toward a DM75xx device file.

- static void [dm75xx_board_reset](#) ([dm75xx_device_descriptor_t](#) *dm75xx)
Performs a reset of the board and device descriptor.
- static void [dm75xx_interrupt_enable](#) ([dm75xx_device_descriptor_t](#) *dm75xx, [dm75xx_int_source_t](#) source, [uint8_t](#) enable)
Performs the actual enable/disable of the interrupt sources.
- static int [dm75xx_interrupt_control](#) ([dm75xx_device_descriptor_t](#) *dm75xx, unsigned long ioctl_param)
Control the interrupts on the boards. This includes enabling, disabling and checking the enable/disable status of the interrupts.
- static int [dm75xx_get_interrupt](#) ([dm75xx_device_descriptor_t](#) *dm75xx, unsigned long ioctl_param)
Returns the top entry from the interrupt status queue.
- static void [dm75xx_put_interrupt](#) ([dm75xx_device_descriptor_t](#) *dm75xx, [uint32_t](#) interrupt)
Adds an interrupt to the interrupt status queue.
- static int [dm75xx_service_dma_function](#) ([dm75xx_device_descriptor_t](#) *dm75xx, unsigned long ioctl_param)
Process user space DMA function requests.
- static int [dm75xx_dma_abort](#) ([dm75xx_device_descriptor_t](#) *dm75xx, [dm75xx_dma_channel_t](#) channel)
Aborts any DMA transfers on the given channel.
- static int [dm75xx_dma_alloc_buffer](#) ([dm75xx_device_descriptor_t](#) *dm75xx, [dm75xx_dma_channel_t](#) channel)
Allocates a coherent and consistent buffer for our DMA operations.
- static int [dm75xx_dreq_init](#) ([dm75xx_device_descriptor_t](#) *dm75xx, [dm75xx_dma_channel_t](#) channel, [dm75xx_dma_request_t](#) dreq)
Performs some DMA initialization work based on the DREQ source.
- static int [dm75xx_dma_initialize](#) ([dm75xx_device_descriptor_t](#) *dm75xx, [dm75xx_ioctl_argument_t](#) *ioctl_↵ argument)
Initialize DMA for the specified channel and source for the DM75xx device.
- static void [dm75xx_free_dma_mappings](#) ([dm75xx_device_descriptor_t](#) *dm75xx, [dm75xx_dma_channel_t](#) ↵ channel)
Free all coherent/consistent DMA mappings for the given DMA channel on the specified DM75xx device.
- int [dm75xx_load](#) (void)
Perform all actions necessary to initialize the DM75xx driver and devices.
- static int [dm75xx_modify_pci_region](#) ([dm75xx_device_descriptor_t](#) *dm75xx, unsigned long ioctl_param)
Read an unsigned value from one of a device's PCI regions, modify certain bits in the value, and then write it back to the region.
- static int [dm75xx_open](#) (struct inode *inode, struct file *file)
Prepare a DM75xx device file to be opened and used.
- static unsigned int [dm75xx_poll](#) (struct file *file, struct poll_table_struct *poll_table)
Determine whether or not a DM75xx device is readable. This function supports the poll(2) and select(2) system calls.
- static int [dm75xx_probe_devices](#) ([uint32_t](#) *device_count, [dm75xx_device_descriptor_t](#) **device_↵ descriptors)
Probe and set up all DM75xx devices.
- static int [dm75xx_process_pci_regions](#) ([dm75xx_device_descriptor_t](#) *dm75xx, const struct pci_dev *pci_↵ device)
For each of the standard PCI regions, get the region's base address and length from kernel PCI resource information set up at boot. Also, remap any memory-mapped region into the kernel's virtual address space.
- static int [dm75xx_register_char_device](#) (int *major)
Register the DM75xx character device and request dynamic allocation of a character device major number.
- static int [dm75xx_release](#) (struct inode *inode, struct file *file)
Do all processing necessary after the last reference to a DM75xx device file is released elsewhere in the kernel.
- static void [dm75xx_release_resources](#) (void)
Release any resources allocated by the driver.
- void [dm75xx_unload](#) (void)
Perform all actions necessary to deinitialize the DM75xx driver and devices.

- static int [dm75xx_unregister_char_device](#) (void)
Unregister the DM75xx character device and free the character device major number.
- static int [dm75xx_validate_device](#) (const [dm75xx_device_descriptor_t](#) *dm75xx)
Given what is assumed to be the address of a DM75xx device descriptor, make sure it corresponds to a valid DM75xx device descriptor.
- static int [dm75xx_validate_pci_access](#) (const [dm75xx_device_descriptor_t](#) *dm75xx, const [dm75xx_pci_access_request_t](#) *pci_request)
Validate a user-space access to one of the device's PCI regions.
- static int [dm75xx_get_fifo_size](#) ([dm75xx_device_descriptor_t](#) *dm75xx, unsigned int *size)
Measure the size of the fifo by filling it until it is half-full then doubling that value to get the size of the fifo.

Variables

- static struct file_operations [dm75xx_file_ops](#)
File operations supported by driver.

6.27.1 Detailed Description

Definitions for the DM75xx driver.

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-----
```

Id

[dm75xx_driver.h](#) 99068 2016-04-26 18:25:17Z rgroner

Definition in file [dm75xx_driver.h](#).

6.28 include/dm75xx_ioctl.h File Reference

Low level ioctl() request descriptor structure and request code definitions.

```
#include <linux/ioctl.h>
#include <linux/types.h>
#include "dm75xx_types.h"
```

Data Structures

- struct [dm75xx_ioctl_region_readwrite](#)
ioctl() request structure for read from or write to PCI region
- struct [dm75xx_ioctl_region_modify](#)
ioctl() request structure for PCI region read/modify/write
- struct [dm75xx_ioctl_dma_function](#)
ioctl() request structure for performing a DMA function
- struct [dm75xx_ioctl_int_control](#)

- ioctl()* request structure for interrupt control.
- union [dm75xx_ioctl_argument](#)
ioctl() request structure encapsulating all possible requests. This is what gets passed into the kernel from user space on the *ioctl()* call.

Macros

- #define [DM75xx_IOCTL_MAGIC](#) 'D'
Unique 8-bit value used to generate unique ioctl() request codes.
- #define [DM75xx_IOCTL_REQUEST_BASE](#) 0x00
First ioctl() request number.
- #define [DM75xx_IOCTL_REGION_READ](#)
ioctl() request code for reading from a PCI region
- #define [DM75xx_IOCTL_REGION_WRITE](#)
ioctl() request code for writing to a PCI region
- #define [DM75xx_IOCTL_REGION_MODIFY](#)
ioctl() request code for PCI region read/modify/write
- #define [DM75xx_IOCTL_DMA_FUNCTION](#)
ioctl() request code for DMA function
- #define [DM75xx_IOCTL_WAKEUP](#)
ioctl() request code to wake up a sleeping driver function
- #define [DM75xx_IOCTL_INT_STATUS](#)
ioctl() request code to get the interrupt status queue
- #define [DM75xx_IOCTL_GET_FIFO_SIZE](#)
ioctl() request code to get the fifo size
- #define [DM75xx_IOCTL_GET_BOARD_TYPE](#)
ioctl() request code to get the board type
- #define [DM75xx_IOCTL_INT_CONTROL](#)
ioctl() request code to control interrupts
- #define [DM75xx_IOCTL_RESET](#)
ioctl() request code to reset the board
- #define [DM75xx_IOCTL_RESET_DMA_STATUS](#)
ioctl() request code to control DMA buffer status

Typedefs

- typedef enum
[dm75xx_dma_manage_function](#) [dm75xx_dma_manage_function_t](#)
Functions supported by driver DMA management system.
- typedef enum
[dm75xx_int_control_function](#) [dm75xx_int_control_function_t](#)
Functions supported by driver interrupt control system.
- typedef struct
[dm75xx_ioctl_region_readwrite](#) [dm75xx_ioctl_region_readwrite_t](#)
- typedef struct
[dm75xx_ioctl_region_modify](#) [dm75xx_ioctl_region_modify_t](#)
ioctl() PCI region read/modify/write request descriptor type
- typedef struct
[dm75xx_ioctl_dma_function](#) [dm75xx_ioctl_dma_function_t](#)
ioctl() request structure for performing a DMA function type.

- typedef struct `dm75xx_ioctl_int_control dm75xx_ioctl_int_control_t`
ioctl() request structure for interrupt control.
- typedef union `dm75xx_ioctl_argument dm75xx_ioctl_argument_t`
ioctl() request descriptor type

Enumerations

- enum `dm75xx_dma_manage_function` { `DM75xx_DMA_FUNCTION_INITIALIZE` = 0, `DM75xx_DMA_FUNCTION_ABORT` }
Functions supported by driver DMA management system.
- enum `dm75xx_int_control_function` { `DM75xx_INT_CONTROL_ENABLE` = 0, `DM75xx_INT_CONTROL_DISABLE`, `DM75xx_INT_CONTROL_CHECK` }
Functions supported by driver interrupt control system.

6.28.1 Detailed Description

Low level ioctl() request descriptor structure and request code definitions.

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-----
```

```
$Id: dm75xx_ioctl.h 65466 2012-12-04 19:25:44Z rgroner $
```

Definition in file [dm75xx_ioctl.h](#).

6.29 include/dm75xx_kernel.h File Reference

Kernel compatibility issues between 2.6.0 and 3.x kernels.

```
#include <asm/ptrace.h>
#include <linux/version.h>
#include <linux/interrupt.h>
#include <linux/cdev.h>
#include <linux/dma-mapping.h>
```

Macros

- #define `INTERRUPT_HANDLER_TYPE` static irqreturn_t
Type returned by interrupt handler.
- #define `DM75XX_IOCTL` .unlocked_ioctl
In Kernel 2.6.35, .ioctl was replaced with .unlocked_ioctl.
- #define `IO_MEMORY_READ8` ioread8
Entity which reads an 8-bit value from device I/O memory.
- #define `IO_MEMORY_READ16` ioread16
Entity which reads a 16-bit value from device I/O memory.

- `#define IO_MEMORY_READ32 ioread32`
Entity which reads a 32-bit value from device I/O memory.
- `#define IO_MEMORY_WRITE8 iowrite8`
Entity which writes an 8-bit value to device I/O memory.
- `#define IO_MEMORY_WRITE16 iowrite16`
Entity which writes a 16-bit value to device I/O memory.
- `#define IO_MEMORY_WRITE32 iowrite32`
Entity which writes a 32-bit value to device I/O memory.

Typedefs

- `typedef irqreturn_t(* dm75xx_handler_t)(int, void *)`
Type definition for interrupt handling function.

6.29.1 Detailed Description

Kernel compatibility issues between 2.6.0 and 3.x kernels.

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-----
```

Id

[dm75xx_kernel.h](#) 65703 2012-12-13 17:04:04Z rgroner

Definition in file [dm75xx_kernel.h](#).

6.30 include/dm75xx_library.h File Reference

DM75xx user library definitions.

```
#include <stdint.h>
#include <stdlib.h>
#include <pthread.h>
#include <sys/wait.h>
#include "dm75xx_types.h"
```

Data Structures

- struct [DM75xx_Board_Descriptor](#)
DM75xx board descriptor. This structure holds information about a device needed by the library.

Macros

- `#define DM75xx_INTERRUPT_ACTIVE(status, source) (((status) & (source)) ? 0xFF : 0x00)`
Determine whether or not the specified interrupt source has occurred in your the user space ISR.
- `#define DM75xx_ADC_ANALOG_DATA(data) (((int16_t) (data)) >> 3)`
This macro will return the sample portion of raw analog data.
- `#define DM75xx_ADC_MARKERS(data) ((data) & 0x07)`
This macro will turn the data marker portion of raw analog data.
- `#define DM75xx_DAC_PACK_DATA(data, mcbasp_bit, data_markers)`
This macro will assemble a package to be sent to the Digital to Analog FIFO.

Typedefs

- `typedef int DM75xx_Error`
DM75xx user library error code type.
- `typedef struct`
`DM75xx_Board_Descriptor DM75xx_Board_Descriptor`

Functions

- `DM75xx_Error DM75xx_Board_PCI_Master (DM75xx_Board_Descriptor *handle, uint8_t *pci_master)`
Determine whether or not a device is PCI master capable.
- `DM75xx_Error DM75xx_Board_Reset (DM75xx_Board_Descriptor *handle)`
Reset a DM75xx device.
- `DM75xx_Error DM75xx_Clear_ITMask (DM75xx_Board_Descriptor *handle, uint16_t mask)`
Clear Interrupts via Mask.
- `DM75xx_Error DM75xx_Clear_IT_Overrun (DM75xx_Board_Descriptor *handle)`
Clear Interrupt Overrun Register.
- `void DM75xx_Exit_On_Error (DM75xx_Board_Descriptor *handle, DM75xx_Error status, char *str)`
Tests the return status of a library function, and if it's an error we clean up the board and exit.
- `DM75xx_Error DM75xx_Board_Init (DM75xx_Board_Descriptor *handle)`
Initialize a Board. This function performs the following to attempt to get the device into a known state:
- `DM75xx_Error DM75xx_Interrupt_Enable (DM75xx_Board_Descriptor *handle, dm75xx_int_source_t int_↵ source)`
Enable one or more DM75xx interrupt source(s).
- `DM75xx_Error DM75xx_Interrupt_Disable (DM75xx_Board_Descriptor *handle, dm75xx_int_source_t int_↵ source)`
Disable one or more DM75xx interrupt source(s).
- `DM75xx_Error DM75xx_Interrupt_Check (DM75xx_Board_Descriptor *handle, dm75xx_int_source_t *int_↵ source)`
Returns the value of current active/enabled interrupts on the device.
- `DM75xx_Error DM75xx_DMA_Buffer_Write (DM75xx_Board_Descriptor *handle, dm75xx_dma_channel_t channel, unsigned long num_ints)`
Copy the User Space buffers data incrementally into our Kernel Space buffer.
- `DM75xx_Error DM75xx_DMA_Buffer_Read (DM75xx_Board_Descriptor *handle, dm75xx_dma_channel_t channel, unsigned long num_ints)`
Copy the Kernel Space buffers data incrementally into our User Space buffer.
- `DM75xx_Error DM75xx_DMA_Buffer_Create (DM75xx_Board_Descriptor *handle, uint16_t **buffer, dm75xx_dma_channel_t channel, uint32_t samples)`
Create a buffer in which the user should place data from the device's DMA buffers.
- `DM75xx_Error DM75xx_DMA_Buffer_Free (DM75xx_Board_Descriptor *handle, uint16_t **buffer, dm75xx_dma_channel_t channel)`

- Free a buffer previously allocated with `DM75xx_DMA_Buffer_Create()`.*
- `DM75xx_Error DM75xx_DMA_Init_Arb` (`DM75xx_Board_Descriptor *handle`, `dm75xx_dma_channel_t` channel, `dm75xx_dma_source_t` source, `dm75xx_dma_request_t` request, `uint32_t` samples, `uint32_t` pci↵ address)
- Set up direct memory access (DMA) for the given DMA/FIFO channel to/from an arbitrary PCI address.*
- `DM75xx_Error DM75xx_DMA_Initialize` (`DM75xx_Board_Descriptor *handle`, `dm75xx_dma_channel_t` channel, `dm75xx_dma_source_t` source, `dm75xx_dma_request_t` request, `uint32_t` samples, `uint16_t **buf`)
- Set up direct memory access (DMA) for the given DMA/FIFO channel.*
- `DM75xx_Error DM75xx_DMA_Abort` (`DM75xx_Board_Descriptor *handle`, `dm75xx_dma_channel_t` channel)
- Abort any active transfer on the specified DMA channel.*
- `DM75xx_Error DM75xx_DMA_Enable` (`DM75xx_Board_Descriptor *handle`, `dm75xx_dma_channel_t` channel, `uint8_t` enable)
- Set the enable bit for a particular DMA channel. To start DMA after this, call `DM75xx_DMA_Start()`.*
- `DM75xx_Error DM75xx_DMA_Request_Source` (`DM75xx_Board_Descriptor *handle`, `dm75xx_dma_channel_t`↵ channel, `dm75xx_dma_request_t` request)
- Set the demand mode request source for a specified DMA channel.*
- `DM75xx_Error DM75xx_DMA_Start` (`DM75xx_Board_Descriptor *handle`, `dm75xx_dma_channel_t` channel)
- Sets the start bit for a particular DMA Channel. DMA will start if the enable bit has been set by `DM75xx_DMA_↵ Enable()`.*
- `DM75xx_Error DM75xx_Board_Close` (`DM75xx_Board_Descriptor *handle`)
- Close a DM75xx device file.*
- `DM75xx_Error DM75xx_Board_Open` (`uint8_t` dev_num, `DM75xx_Board_Descriptor **handle`)
- Open a DM75xx device file.*
- `DM75xx_Error DM75xx_FIFO_Size` (`DM75xx_Board_Descriptor *handle`, `unsigned int *data`)
- Retrieve the FIFO size of the board from the kernel space device descriptor.*
- `DM75xx_Error DM75xx_Board_Type` (`DM75xx_Board_Descriptor *handle`, `dm75xx_board_t *data`)
- Determine the family of the board (DM7520 or SDM7540/8540).*
- `DM75xx_Error DM75xx_InstallISR` (`DM75xx_Board_Descriptor *handle`, `void(*isr_fnct)(unsigned int status)`)
- Install userspace ISR.*
- `DM75xx_Error DM75xx_RemoveISR` (`DM75xx_Board_Descriptor *handle`)
- Uninstall userspace ISR.*
- `void * DM75xx_WaitForInterrupt` (`void *ptr`)
- Function that will have its own thread and wait for interrupts to occur. Once an interrupt is received this function will call our callback ISR and pass it the interrupt status.*
- `DM75xx_Error DM75xx_UTC_Set_Clock_Source` (`DM75xx_Board_Descriptor *handle`, `dm75xx_utc_timer_t`↵ utc, `dm75xx_utc_clk_t` source)
- Set a User Timer/Counter Clock Source.*
- `DM75xx_Error DM75xx_UTC_Set_Gate` (`DM75xx_Board_Descriptor *handle`, `dm75xx_utc_timer_t` utc, `dm75xx_utc_gate` gate)
- Set a User Timer/Counter Gate.*
- `DM75xx_Error DM75xx_UTC_Set_Mode` (`DM75xx_Board_Descriptor *handle`, `dm75xx_utc_timer_t` utc, `dm75xx_utc_mode` mode)
- Set a User Timer/Counter Mode.*
- `DM75xx_Error DM75xx_UTC_Get_Mode` (`DM75xx_Board_Descriptor *handle`, `dm75xx_utc_timer_t` utc, `uint16_t *mode`)
- Set a User Timer/Counter Mode.*
- `DM75xx_Error DM75xx_UTC_Set_Divisor` (`DM75xx_Board_Descriptor *handle`, `dm75xx_utc_timer_t` utc, `uint16_t` rate)
- Set a User Timer/Counter Divisor.*
- `DM75xx_Error DM75xx_UTC_Get_Count` (`DM75xx_Board_Descriptor *handle`, `dm75xx_utc_timer_t` utc, `uint16_t *count`)
- Return current value of a User Timer/Counter.*

- [DM75xx_Error DM75xx_UTC_Get_Status](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_utc_timer_t](#) utc_↵
select, [uint8_t](#) *utc_status)
Return current status of a User Timer/Counter.
- [DM75xx_Error DM75xx_UTC_Setup](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_utc_timer_t](#) utc,
[dm75xx_utc_clk_t](#) source, [dm75xx_utc_gate](#) gate, [dm75xx_utc_mode](#) mode, [uint16_t](#) divisor)
Setup a User Timer/Counter.
- [DM75xx_Error DM75xx_BCLK_Get_Count](#) ([DM75xx_Board_Descriptor](#) *handle, [uint16_t](#) *data)
Get the current Burst Clock count.
- [DM75xx_Error DM75xx_BCLK_Set_Count](#) ([DM75xx_Board_Descriptor](#) *handle, [uint16_t](#) data)
Set the current Burst Clock count.
- [DM75xx_Error DM75xx_BCLK_Set_Rate](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_bclk_freq_t](#) freq,
float rate, float *actualRate)
Set the Burst Clock rate.
- [DM75xx_Error DM75xx_BCLK_Set_Start](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_bclk_start_t](#) start)
Set Burst Clock start trigger.
- [DM75xx_Error DM75xx_BCLK_Set_Frequency](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_bclk_freq_↵
t](#) freq)
Set the Burst Clock primary frequency.
- [DM75xx_Error DM75xx_BCLK_Setup](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_bclk_start_t](#) start,
[dm75xx_bclk_freq_t](#) freq, float rate, float *actualRate)
Setup Burst Clock.
- [DM75xx_Error DM75xx_PCLK_Set_Frequency](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_pclk_freq_↵
t](#) pclk_freq)
Set the Pacer Clock frequency.
- [DM75xx_Error DM75xx_PCLK_Set_Source](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_pclk_select_↵
t](#) pclk_select)
Set the Pacer Clock source.
- [DM75xx_Error DM75xx_PCLK_Set_Start](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_pclk_start_t](#) pclk_↵
_start)
Set the Pacer Clock start trigger.
- [DM75xx_Error DM75xx_PCLK_Set_Stop](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_pclk_stop_t](#) pclk_↵
stop)
Set the Pacer Clock stop trigger.
- [DM75xx_Error DM75xx_PCLK_Read](#) ([DM75xx_Board_Descriptor](#) *handle, [uint32_t](#) *pacer_value)
Read the current pacer clock value.
- [DM75xx_Error DM75xx_PCLK_Set_Trigger_Mode](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_pclk_↵
mode_t](#) pclk_mode)
Set the Pacer Clock trigger mode.
- [DM75xx_Error DM75xx_PCLK_Set_Count](#) ([DM75xx_Board_Descriptor](#) *handle, [uint32_t](#) count)
Set the Pacer Clock Count.
- [DM75xx_Error DM75xx_PCLK_Set_Rate](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_pclk_freq_t](#) freq,
float rate, float *actualRate)
Set the Pacer Clock Rate.
- [DM75xx_Error DM75xx_PCLK_Setup](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_pclk_select_t](#) pclk_↵
select, [dm75xx_pclk_freq_t](#) pclk_freq, [dm75xx_pclk_mode_t](#) pclk_mode, [dm75xx_pclk_start_t](#) pclk_start,
[dm75xx_pclk_stop_t](#) pclk_stop, float rate, float *actualRate)
Setup the Pacer Clock.
- [DM75xx_Error DM75xx_PCLK_Start](#) ([DM75xx_Board_Descriptor](#) *handle)
Software Pacer Clock Start.
- [DM75xx_Error DM75xx_PCLK_Stop](#) ([DM75xx_Board_Descriptor](#) *handle)
Software Pacer Clock Stop.
- [DM75xx_Error DM75xx_CGT_Reset](#) ([DM75xx_Board_Descriptor](#) *handle)

- Reset Channel Gain Table.*
- [DM75xx_Error DM75xx_CGT_Clear](#) ([DM75xx_Board_Descriptor](#) *handle)
- Clear Channel Gain Table.*
- [DM75xx_Error DM75xx_CGT_Create_Entry](#) ([dm75xx_cgt_entry_t](#) *cgt, [uint16_t](#) *cgt_entry)
- Create a channel gain table entry.*
- [DM75xx_Error DM75xx_CGT_Write](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_cgt_entry_t](#) cgt)
- Write a channel gain table entry. This function utilizes [DM75xx_CGT_Create_Entry\(\)](#) to create the 16 bit entry.*
- [DM75xx_Error DM75xx_CGT_Latch](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_cgt_entry_t](#) cgt)
- Write ADC channel gain table latch for single channel sampling.*
- [DM75xx_Error DM75xx_CGT_Enable](#) ([DM75xx_Board_Descriptor](#) *handle, [uint16_t](#) enable)
- Enable/disable A/D channel gain table.*
- [DM75xx_Error DM75xx_DT_Enable](#) ([DM75xx_Board_Descriptor](#) *handle, [uint16_t](#) enable)
- Enable/disable Digital Table.*
- [DM75xx_Error DM75xx_DT_Write_Entry](#) ([DM75xx_Board_Descriptor](#) *handle, [uint8_t](#) data)
- Write Digital Table entry.*
- [DM75xx_Error DM75xx_CGT_Pause](#) ([DM75xx_Board_Descriptor](#) *handle, [uint16_t](#) pause)
- Pause the Channel Gain Table.*

- [DM75xx_Error DM75xx_ADC_FIFO_Read](#) ([DM75xx_Board_Descriptor](#) *handle, [uint16_t](#) *value)
- DM75xx_Library_ADC_Functions DM75xx user library analog to digital.*
- [DM75xx_Error DM75xx_ADC_Software_Sample](#) ([DM75xx_Board_Descriptor](#) *handle)
- Analog to Digital Software Sample.*
- [DM75xx_Error DM75xx_ADC_Conv_Signal](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_adc_conv_↔signal_t](#) adc_conv_signal)
- Select the A/D Conversion Signal.*
- [DM75xx_Error DM75xx_ADC_SCNT_Source](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_adc_scnt_src_↔_t](#) src)
- Select the A/D Sample Counter Source.*
- [DM75xx_Error DM75xx_ADC_About_Enable](#) ([DM75xx_Board_Descriptor](#) *handle, [uint16_t](#) enable)
- Enable/Disable About Counter stop.*
- [DM75xx_Error DM75xx_ADC_Clear](#) ([DM75xx_Board_Descriptor](#) *handle)
- Clear Analog to Digital FIFO.*
- [DM75xx_Error DM75xx_ADC_SCNT_Read](#) ([DM75xx_Board_Descriptor](#) *handle, [uint16_t](#) *data)
- Read the value in the A/D Sample Counter.*
- [DM75xx_Error DM75xx_ADC_SCNT_Load](#) ([DM75xx_Board_Descriptor](#) *handle, [uint16_t](#) data)
- Load a value into the A/D Sample Counter.*

- [DM75xx_Error DM75xx_DAC_Soft_Update](#) ([DM75xx_Board_Descriptor](#) *handle, [uint8_t](#) dac)
- DM75xx_Library_DAC_Functions DM75xx user library digital to analog.*
- [DM75xx_Error DM75xx_DAC_Get_Update_Counter](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dac_↔channel_t](#) dac, [uint16_t](#) *data)
- Get DAC update counter for a specified channel.*
- [DM75xx_Error DM75xx_DAC_Set_Update_Counter](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dac_↔channel_t](#) dac, [uint16_t](#) data)
- Set the DAC update counter for a specified channel.*
- [DM75xx_Error DM75xx_DAC_Set_Range](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dac_channel_↔t](#) dac, [dm75xx_dac_range_t](#) range)
- Set the DAC output range for a specified channel.*
- [DM75xx_Error DM75xx_DAC_Set_Update_Source](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dac_↔channel_t](#) dac, [dm75xx_dac_update_src_t](#) src)
- Set the DAC Update Source for the specified channel.*

- [DM75xx_Error DM75xx_DAC_Set_Mode](#) (DM75xx_Board_Descriptor *handle, dm75xx_dac_channel_t dac, dm75xx_dac_mode_t mode)
Set the DAC mode for a specified channel.
- [DM75xx_Error DM75xx_DAC_FIFO_Write](#) (DM75xx_Board_Descriptor *handle, dm75xx_dac_channel_t dac, uint16_t data)
Write a value to the DAC FIFO of a specified channel.
- [DM75xx_Error DM75xx_DAC_Set_Frequency](#) (DM75xx_Board_Descriptor *handle, dm75xx_dac_freq_t freq)
Set the primary clock frequency for DAC conversion.
- [DM75xx_Error DM75xx_DAC_Set_Count](#) (DM75xx_Board_Descriptor *handle, uint32_t count)
Set the DAC Clock Count.
- [DM75xx_Error DM75xx_DAC_Set_Rate](#) (DM75xx_Board_Descriptor *handle, dm75xx_dac_freq_t freq, uint32_t rate, float *actualRate)
Set the DAC conversion rate.
- [DM75xx_Error DM75xx_DAC_Set_Clock_Stop](#) (DM75xx_Board_Descriptor *handle, dm75xx_dac_clk_stop_t stop)
Set the DAC Clock Stop Value.
- [DM75xx_Error DM75xx_DAC_Set_Clock_Start](#) (DM75xx_Board_Descriptor *handle, dm75xx_dac_clk_start_t start)
Set the DAC Clock Start Value.
- [DM75xx_Error DM75xx_DAC_Start](#) (DM75xx_Board_Descriptor *handle)
Causes a DAC Software Start.
- [DM75xx_Error DM75xx_DAC_Stop](#) (DM75xx_Board_Descriptor *handle)
Causes a DAC Software Stop.
- [DM75xx_Error DM75xx_DAC_Setup](#) (DM75xx_Board_Descriptor *handle, dm75xx_dac_channel_t dac, dm75xx_dac_range_t range, dm75xx_dac_update_src_t src, dm75xx_dac_mode_t mode)
Setup a DAC channel.
- [DM75xx_Error DM75xx_DAC_Reset](#) (DM75xx_Board_Descriptor *handle, dm75xx_dac_channel_t dac)
Reset a DAC Fifo.
- [DM75xx_Error DM75xx_DAC_Clear](#) (DM75xx_Board_Descriptor *handle, dm75xx_dac_channel_t dac)
Clear a DAC Fifo.
- [DM75xx_Error DM75xx_DAC_Set_CLK_Mode](#) (DM75xx_Board_Descriptor *handle, dm75xx_dac_clk_mode_t clk_mode)
Set DAC Clock Mode.

- [DM75xx_Error DM75xx_HSDIN_Software_Sample](#) (DM75xx_Board_Descriptor *handle)
DM75xx_Library_HSDIN_Functions DM75xx user library high speed digital.
- [DM75xx_Error DM75xx_HSDIN_Sample_Signal](#) (DM75xx_Board_Descriptor *handle, dm75xx_hsdin_signal_t signal)
Set HighSpeed digital sampling signal.
- [DM75xx_Error DM75xx_HSDIN_Clear](#) (DM75xx_Board_Descriptor *handle)
Clear High Speed Digital FIFO.
- [DM75xx_Error DM75xx_HSDIN_FIFO_Read](#) (DM75xx_Board_Descriptor *handle, uint16_t *data)
Read value from High Speed Digital FIFO.

- [DM75xx_Error DM75xx_SBUS_Set_Source](#) (DM75xx_Board_Descriptor *handle, dm75xx_sbus_t sbus, dm75xx_sbus_src_t src)
DM75xx_Library_SBUS_Functions DM75xx user library synbus.
- [DM75xx_Error DM75xx_SBUS_Enable](#) (DM75xx_Board_Descriptor *handle, dm75xx_sbus_t sbus, uint16_t enable)
Enable/Disable Synbus.

- [DM75xx_Error DM75xx_ACNT_Get_Count](#) ([DM75xx_Board_Descriptor](#) *handle, [uint16_t](#) *data)
DM75xx_Library_ACNT_Functions DM75xx user library about counter.
- [DM75xx_Error DM75xx_ACNT_Set_Count](#) ([DM75xx_Board_Descriptor](#) *handle, [uint16_t](#) data)
Set the About Counter value.

- [DM75xx_Error DM75xx_DCNT_Get_Count](#) ([DM75xx_Board_Descriptor](#) *handle, [uint16_t](#) *data)
DM75xx_Library_DCNT_Functions DM75xx user library delay counter.
- [DM75xx_Error DM75xx_DCNT_Set_Count](#) ([DM75xx_Board_Descriptor](#) *handle, [uint16_t](#) data)
Set the Delay Counter value.

- [DM75xx_Error DM75xx_DIO_Set_Port](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dio_port_t](#) port, [uint8_t](#) data)
DM75xx_Library_DIO_Functions DM75xx user library digital input/output.
- [DM75xx_Error DM75xx_DIO_Get_Port](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dio_port_t](#) port, [uint8_t](#) *data)
Get the value from the specified Digital I/O Port.
- [DM75xx_Error DM75xx_DIO_Get_Status](#) ([DM75xx_Board_Descriptor](#) *handle, [uint8_t](#) *data)
Get the Digital I/O Status byte.
- [DM75xx_Error DM75xx_DIO_Clear_IRQ](#) ([DM75xx_Board_Descriptor](#) *handle)
Clear Digital I/O IRQ Status.
- [DM75xx_Error DM75xx_DIO_Reset](#) ([DM75xx_Board_Descriptor](#) *handle)
Clear Digital I/O Chip.
- [DM75xx_Error DM75xx_DIO_Set_Direction](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dio_port_t](#) port, [uint8_t](#) direction)
Set the direction of the specified Digital I/O Port.
- [DM75xx_Error DM75xx_DIO_Set_Mask](#) ([DM75xx_Board_Descriptor](#) *handle, [uint8_t](#) mask)
Set Digital I/O Port 0 Mask.
- [DM75xx_Error DM75xx_DIO_Set_Compare](#) ([DM75xx_Board_Descriptor](#) *handle, [uint8_t](#) compare)
Set the compare register for Digital I/O Port 0.
- [DM75xx_Error DM75xx_DIO_Get_Compare](#) ([DM75xx_Board_Descriptor](#) *handle, [uint8_t](#) *compare)
Get the compare register for Digital I/O Port 0.
- [DM75xx_Error DM75xx_DIO_IRQ_Mode](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dio_mode_t](#) mode)
Set the IRQ Mode for Digital I/O.
- [DM75xx_Error DM75xx_DIO_Clock](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dio_clk_t](#) clock)
Set the Digital I/O Sample Clock.
- [DM75xx_Error DM75xx_DIO_Enable_IRQ](#) ([DM75xx_Board_Descriptor](#) *handle, [uint8_t](#) enable)
Enable/Disable Digital I/O Interrupts.

- [DM75xx_Error DM75xx_UIO_Select](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_uio_channel_t](#) channel, [dm75xx_uio_source_t](#) source)
DM75xx_Library_UIO_Functions DM75xx user library user I/O.
- [DM75xx_Error DM75xx_UIO_Read](#) ([DM75xx_Board_Descriptor](#) *handle, [uint32_t](#) *data)
Read the current status of the user I/O.
- [DM75xx_Error DM75xx_UIO_Write](#) ([DM75xx_Board_Descriptor](#) *handle, [uint32_t](#) data)
Write the value of the user I/O.

- [DM75xx_Error DM75xx_McBSP_ADC_FIFO](#) ([DM75xx_Board_Descriptor](#) *handle, [uint8_t](#) enable)
DM75xx_Library_McBSP_Functions DM75xx user library mcbbsp.
- [DM75xx_Error DM75xx_McBSP_DAC_FIFO](#) ([DM75xx_Board_Descriptor](#) *handle, [uint8_t](#) enable)
Enable/Disable D/A FIFO to DSP.

- [DM75xx_Error DM75xx_ETRIG_Polarity_Select](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_ext_polarity_t](#) polarity)
DM75xx_Library_EXT_Functions DM75xx user library external trigger/interrupt.
- [DM75xx_Error DM75xx_EINT_Polarity_Select](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_ext_polarity_t](#) polarity)
Set the External Interrupt polarity.
- [DM75xx_Error DM75xx_FIFO_Get_Status](#) ([DM75xx_Board_Descriptor](#) *handle, [uint16_t](#) *fifo_status)
DM75xx_Library_STATUS_Functions DM75xx user library status.
- [DM75xx_Error DM75xx_CLK_Get_Status](#) ([DM75xx_Board_Descriptor](#) *handle, [uint16_t](#) *status)
Get status of pacer/burst clocks.
- [DM75xx_Error DM75xx_Calibrate](#) ([DM75xx_Board_Descriptor](#) *handle, [uint16_t](#) dac1_value, [uint16_t](#) dac2_value, [dm75xx_dac_range_t](#) dac1_range, [dm75xx_dac_range_t](#) dac2_range)
DM75xx_Library_SDM7540_Functions DM75xx user library SDM7540 functions.
- [DM75xx_Error DM75xx_DSP_CMD_Send](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dsp_command_t](#) command)
Issue a command to the 7540 onboard DSP.
- [DM75xx_Error DM75xx_DSP_CMD_Complete](#) ([DM75xx_Board_Descriptor](#) *handle, [uint8_t](#) *data)
Checks if the last command given to the DSP is finished.
- [DM75xx_Error DM75xx_DSP_CMD_Status](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_dsp_command_t](#) command)
Checks whether or not a command successfully completed on the DSP.
- [DM75xx_Error DM75xx_ALGDIO_Get_Mask](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_algdio_mask_t](#) *pin1, [dm75xx_algdio_mask_t](#) *pin2)
Get the the mask of the Analog DIO.
- [DM75xx_Error DM75xx_ALGDIO_Set_Mask](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_algdio_mask_t](#) pin1, [dm75xx_algdio_mask_t](#) pin2)
Set the Analog DIO Mask.
- [DM75xx_Error DM75xx_ALGDIO_Get_Direction](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_algdio_direction_t](#) *pin1, [dm75xx_algdio_direction_t](#) *pin2)
Get the Analog DIO Direction.
- [DM75xx_Error DM75xx_ALGDIO_Set_Direction](#) ([DM75xx_Board_Descriptor](#) *handle, [dm75xx_algdio_direction_t](#) pin1, [dm75xx_algdio_direction_t](#) pin2)
Set the Analog DIO Direction.
- [DM75xx_Error DM75xx_ALGDIO_Set_Data](#) ([DM75xx_Board_Descriptor](#) *handle, [uint8_t](#) pin1, [uint8_t](#) pin2)
Set the Analog DIO pin values.
- [DM75xx_Error DM75xx_ALGDIO_Get_Data](#) ([DM75xx_Board_Descriptor](#) *handle, [uint8_t](#) *pin1, [uint8_t](#) *pin2)
Get the Analog DIO pin values.
- [DM75xx_Error DM75xx_ALGDIO_Get_IRQ_Status](#) ([DM75xx_Board_Descriptor](#) *handle, [uint8_t](#) *status)
Get Analog DIO IRQ Status.
- [DM75xx_Error DM75xx_Get_Temp](#) ([DM75xx_Board_Descriptor](#) *handle, [uint8_t](#) *temp)
Get the temperature from the board.

6.30.1 Detailed Description

DM75xx user library definitions.

```
-----
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```

```
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-----
```

```
$Id: dm75xx_library.h 99065 2016-04-26 18:03:23Z rgroner $
```

Definition in file [dm75xx_library.h](#).

6.31 include/dm75xx_registers.h File Reference

Register definitions for DM75xx devices.

Macros

- `#define DM75xx_PLX_ITCSR 0x68`
Interrupt Control/Status.
- `#define DM75xx_PLX_DMA_MODE0 0x80`
DMA Channel 0 Mode.
- `#define DM75xx_PLX_DMA_PADR0 0x84`
DMA Channel 0 PCI Address.
- `#define DM75xx_PLX_DMA_LADR0 0x88`
DMA Channel 0 Local Address.
- `#define DM75xx_PLX_DMA_SIZE0 0x8C`
DMA Channel 0 Transfer Size (Bytes)
- `#define DM75xx_PLX_DMA_DPR0 0x90`
DMA Channel 0 Descriptor Pointer.
- `#define DM75xx_PLX_DMA_MODE1 0x94`
DMA Channel 1 Mode.
- `#define DM75xx_PLX_DMA_PADR1 0x98`
DMA Channel 1 PCI Address.
- `#define DM75xx_PLX_DMA_LADR1 0x9C`
DMA Channel 1 Local Address.
- `#define DM75xx_PLX_DMA_SIZE1 0xA0`
DMA Channel 1 Transfer Size (Bytes)
- `#define DM75xx_PLX_DMA_DPR1 0xA4`
DMA Channel 1 Descriptor Pointer.
- `#define DM75xx_PLX_DMA_CSR0 0xA8`
DMA Command/Status channel 0.
- `#define DM75xx_PLX_DMA_CSR1 0xA9`
DMA Command/Status channel 1.
- `#define DM75xx_PLX_DMA_ARB 0xAC`
DMA Arbitration.
- `#define DM75xx_PLX_DMA_THR 0xB0`
DMA Threshold.
- `#define DM75xx_PLX_SRAM 0xF4`
PLX LAS1 SRAM access space.

- #define [DM75xx_LAS0_MT_MODE](#) 0x00
Read Master/Target Only mode and Firmware version.
- #define [DM75xx_LAS0_SPARE_04](#) 0x04
Spare 0x04.
- #define [DM75xx_LAS0_USER_IO](#) 0x08
Read/Write user inputs.
- #define [DM75xx_LAS0_DAC_CLK_ST](#) 0x0C
Start/Stop software clock.
- #define [DM75xx_LAS0_FIFO_STATUS](#) 0x10
Read FIFO Status.
- #define [DM75xx_LAS0_DAC1](#) 0x14
Software DAC1 Update.
- #define [DM75xx_LAS0_DAC2](#) 0x18
Software DAC2 Update.
- #define [DM75xx_LAS0_SPARE_1C](#) 0x1C
Spare 0x1C.
- #define [DM75xx_LAS0_SPARE_20](#) 0x20
Spare 0x20.
- #define [DM75xx_LAS0_DAC](#) 0x24
Software simultaneous DAC1 and DAC2 Update.
- #define [DM75xx_LAS0_PACER](#) 0x28
Start/Stop software Pacer.
- #define [DM75xx_LAS0_TIMER](#) 0x2C
Read: Read Timer Counter Status Write: Software HSDIN Sample Command.
- #define [DM75xx_LAS0_IT](#) 0x30
Read: Read interrupt status Write: Write IT enable mask.
- #define [DM75xx_LAS0_CLEAR_IT](#) 0x34
Read: Clear ITs via mask Write: Set IT clear mask.
- #define [DM75xx_LAS0_IT_OVERRUN](#) 0x38
Read: Read IT overrun Write: Clear IT overrun.
- #define [DM75xx_LAS0_SPARE_3C](#) 0x3C
Spare 0x3C.
- #define [DM75xx_LAS0_PCLK](#) 0x40
Read/Write Pacer Clock.
- #define [DM75xx_LAS0_BCLK](#) 0x44
Read/Write Burst Clock.
- #define [DM75xx_LAS0_ADC_SCNT](#) 0x48
Read/Write ADC sample counter.
- #define [DM75xx_LAS0_DAC1_UCNT](#) 0x4C
Read/Write DAC1 update counter.
- #define [DM75xx_LAS0_DAC2_UCNT](#) 0x50
Read/Write DAC2 update counter.
- #define [DM75xx_LAS0_DCNT](#) 0x54
Read/Write delay counter.
- #define [DM75xx_LAS0_ACNT](#) 0x58
Read/Write about counter.
- #define [DM75xx_LAS0_DAC_CLK](#) 0x5C
Read/Write DAC clock.
- #define [DM75xx_LAS0_UTC0](#) 0x60
Read/Write UTC0 value.
- #define [DM75xx_LAS0_UTC1](#) 0x64

- Read/Write UTC1 value.*
- #define [DM75xx_LAS0.UTC2](#) 0x68
- Read/Write UTC2 value.*
- #define [DM75xx_LAS0.UTC_CTRL](#) 0x6C
- UTC Control.*
- #define [DM75xx_LAS0.DIO0](#) 0x70
- Read/Program digital input port 0.*
- #define [DM75xx_LAS0.DIO1](#) 0x74
- Read/Program digital input port 1.*
- #define [DM75xx_LAS0.DIO_CTRL](#) 0x78
- Clear digital IRQ status, read/program port 0 direction, mask, or compare register.*
- #define [DM75xx_LAS0.DIO_STATUS](#) 0x7C
- Read DIO Status or Program digital control/interrupts.*
- #define [DM75xx_LAS0.DSP](#) 0xB0
- Read: DSP Command register to be written from the Host side and read from the DSP Write: DSP status written to by the DSP and read from the Host side.*
- #define [DM75xx_LAS0.ALGDIO_MASK](#) 0xE0
- Read/Write analog connection DIO mask.*
- #define [DM75xx_LAS0.ALGDIO_DATA](#) 0xE4
- Read/Write analog connection DIO data.*
- #define [DM75xx_LAS0.ALGDIO_DIR](#) 0xE8
- read/Write analog connection DIO direction*
- #define [DM75xx_LAS0.ALGDIO_IRQ](#) 0xEC
- Read analog connection DIO IRQ status.*
- #define [DM75xx_LAS0.I2C_ADDR](#) 0xC0
- I2C Bus Address.*
- #define [DM75xx_LAS0.I2C_PTR](#) 0xC4
- I2C Bus Pointer.*
- #define [DM75xx_LAS0.I2C_DATA](#) 0xC8
- I2C Bus Data.*
- #define [DM75xx_LAS0.I2C_GO](#) 0xCC
- I2C Bus Go.*
- #define [DM75xx_LAS0.I2C_READ](#) 0xD0
- I2C Bus Read.*
- #define [DM75xx_LAS0.BOARD_RESET](#) 0x100
- Software board reset.*
- #define [DM75xx_LAS0.DMA0_SRC](#) 0x104
- DMA Channel 0 Source.*
- #define [DM75xx_LAS0.DMA1_SRC](#) 0x108
- DMA Channel 1 Source.*
- #define [DM75xx_LAS0.DMA_RSTRQST0](#) 0x1CC
- Reset DMA Channel 0 Request Machine.*
- #define [DM75xx_LAS0.DMA_RSTRQST1](#) 0x1D0
- Reset DMA Channel 1 Request Machine.*
- #define [DM75xx_LAS0.ADC_CONV](#) 0x10C
- Select ADC Conversion Signal.*
- #define [DM75xx_LAS0.BURST_START](#) 0x110
- Select Burst Clock Start Trigger.*
- #define [DM75xx_LAS0.PACER_START](#) 0x114
- Select Pacer Clock Start Trigger.*
- #define [DM75xx_LAS0.PACER_STOP](#) 0x118

- Select Pacer Clock Stop Trigger.*
 - #define [DM75xx_LAS0_ACNT_ENABLE](#) 0x11C
- About Counter Stop Enable.*
 - #define [DM75xx_LAS0_PACER_MODE](#) 0x120
- Pacer Clock Start Trigger Mode.*
 - #define [DM75xx_LAS0_HSDIN_START](#) 0x124
- Select HighSpeed Digital Sampling Signal.*
 - #define [DM75xx_LAS0_HSDIN_FIFO_CLR](#) 0x128
- Clear HighSpeed Digital FIFO.*
 - #define [DM75xx_LAS0_ADC_FIFO_CLR](#) 0x12C
- Clear ADC FIFO.*
 - #define [DM75xx_LAS0_CGT_WRITE](#) 0x130
- Write CGT Multi-Channel.*
 - #define [DM75xx_LAS0_CGT_LATCH](#) 0x134
- Write CGT Latch Single-Channel.*
 - #define [DM75xx_LAS0_DT_WRITE](#) 0x138
- Write Digital Table.*
 - #define [DM75xx_LAS0_CGT_ENABLE](#) 0x13C
- Enable CGT.*
 - #define [DM75xx_LAS0_DT_ENABLE](#) 0x140
- Enable Digital Table.*
 - #define [DM75xx_LAS0_PAUSE_TABLE](#) 0x144
- Table Pause Enable.*
 - #define [DM75xx_LAS0_CGT_RESET](#) 0x148
- Reset CGT.*
 - #define [DM75xx_LAS0_CGT_CLEAR](#) 0x14C
- Clear CGT.*
 - #define [DM75xx_LAS0_DAC1_RANGE](#) 0x150
- Select DAC1 Output Range.*
 - #define [DM75xx_LAS0_DAC1_SRC](#) 0x154
- Select DAC1 Update Source.*
 - #define [DM75xx_LAS0_DAC1_CYCLE](#) 0x158
- Select DAC1 Cycle Mode.*
 - #define [DM75xx_LAS0_DAC1_RESET](#) 0x15C
- Reset DAC1 FIFO.*
 - #define [DM75xx_LAS0_DAC1_CLEAR](#) 0x160
- Clear DAC1 FIFO.*
 - #define [DM75xx_LAS0_DAC2_RANGE](#) 0x164
- Select DAC2 Output Range.*
 - #define [DM75xx_LAS0_DAC2_SRC](#) 0x168
- Select DAC2 Update Source.*
 - #define [DM75xx_LAS0_DAC2_CYCLE](#) 0x16C
- Select DAC2 Cycle Mode.*
 - #define [DM75xx_LAS0_DAC2_RESET](#) 0x170
- Reset DAC2 FIFO.*
 - #define [DM75xx_LAS0_DAC2_CLEAR](#) 0x174
- Clear DAC2 FIFO.*
 - #define [DM75xx_LAS0_SBUS0_SOURCE](#) 0x184
- Select SyncBus 0 Source.*
 - #define [DM75xx_LAS0_SBUS0_ENABLE](#) 0x188
- Syncbus 0 Enable.*

- #define [DM75xx_LAS0_SBUS1_SOURCE](#) 0x18C
Select SyncBus 1 Source.
- #define [DM75xx_LAS0_SBUS1_ENABLE](#) 0x190
SyncBus 1 Enable.
- #define [DM75xx_LAS0_SBUS2_SOURCE](#) 0x198
Select SyncBus 2 Source.
- #define [DM75xx_LAS0_SBUS2_ENABLE](#) 0x19C
SyncBus 2 Enable.
- #define [DM75xx_LAS0_ETRG_POLARITY](#) 0x1A4
Select External Trigger Polarity.
- #define [DM75xx_LAS0_EINT_POLARITY](#) 0x1A8
Select External Interrupt Polarity.
- #define [DM75xx_LAS0_UTC0_CLOCK](#) 0x1AC
Select UTC0 Clock.
- #define [DM75xx_LAS0_UTC0_GATE](#) 0x1B0
Select UTC0 Gate.
- #define [DM75xx_LAS0_UTC1_CLOCK](#) 0x1B4
Select UTC1 Clock.
- #define [DM75xx_LAS0_UTC1_GATE](#) 0x1B8
Select UTC1 Gate.
- #define [DM75xx_LAS0_UTC2_CLOCK](#) 0x1BC
Select UTC2 Clock.
- #define [DM75xx_LAS0_UTC2_GATE](#) 0x1C0
Select UTC2 Gate.
- #define [DM75xx_LAS0_UIO0_SELECT](#) 0x1C4
Select User Output Signal 0.
- #define [DM75xx_LAS0_UIO1_SELECT](#) 0x1C8
Select User Output Signal 1.
- #define [DM75xx_LAS0_ADC_SCNT_SRC](#) 0x178
Select ADC Sample Counter Source.
- #define [DM75xx_LAS0_PACER_SELECT](#) 0x180
Select Pacer Clock.
- #define [DM75xx_LAS0_DAC_CLK_START](#) 0x1D4
Select DAC Clock Start.
- #define [DM75xx_LAS0_DAC_CLK_STOP](#) 0x1D8
Select DAC Clock Stop.
- #define [DM75xx_LAS0_PCLK_FREQ](#) 0x1DC
Select Pacer Clock Frequency.
- #define [DM75xx_LAS0_BCLK_FREQ](#) 0x1E0
Select Burst Clock Frequency.
- #define [DM75xx_LAS0_DAC_CLK_SOURCE](#) 0x1E4
Select DAC Clock Source.
- #define [DM75xx_LAS0_DAC_CLK_MODE](#) 0x1E8
Select DAC Clock Mode.
- #define [DM75xx_LAS0_MCBSP_AD_CTRL](#) 0x1EC
ADC FIFO Data to DSP Enable.
- #define [DM75xx_LAS0_MCBSP_DA_CTRL](#) 0x1F0
DAC FIFO Data from DSP Enable.
- #define [DM75xx_LAS0_FIFO_ADR_MODE](#) 0x1F4
Select FIFO Addressing Mode.
- #define [DM75xx_LAS1_ADC_FIFO](#) 0x00

- *Read ADC FIFO.*
- #define `DM75xx_LAS1_HSDIN_FIFO` 0x04
- *Read HighSpeed Digital FIFO.*
- #define `DM75xx_LAS1_DAC1_FIFO` 0x08
- *Write DAC1 FIFO.*
- #define `DM75xx_LAS1_DAC2_FIFO` 0x0C
- *Write DAC2 FIFO.*
- #define `DMALADDR_ADC` 0x40000000
- *Local Address for ADC FIFO.*
- #define `DMALADDR_HSDIN` 0x40000004
- *Local Address for HSDIN FIFO.*
- #define `DMALADDR_DAC1` 0x40000008
- *Local Address for DAC1 FIFO.*
- #define `DMALADDR_DAC2` 0x4000000C
- *Local Address for DAC2 FIFO.*
- #define `DISABLED` 0x00
- *Generic Disable Logic 0x00.*
- #define `ENABLED` 0x01
- *Generic Enable Logic 0x01.*
- #define `NO_ARG` 0x00
- *Dummy Value.*
- #define `BIT_00` 0x00000001
- *Bit 0.*
- #define `BIT_01` 0x00000002
- *Bit 1.*
- #define `BIT_02` 0x00000004
- *Bit 2.*
- #define `BIT_03` 0x00000008
- *Bit 3.*
- #define `BIT_04` 0x00000010
- *Bit 4.*
- #define `BIT_05` 0x00000020
- *Bit 5.*
- #define `BIT_06` 0x00000040
- *Bit 6.*
- #define `BIT_07` 0x00000080
- *Bit 7.*
- #define `BIT_08` 0x00000100
- *Bit 8.*
- #define `BIT_09` 0x00000200
- *Bit 9.*
- #define `BIT_10` 0x00000400
- *Bit 10.*
- #define `BIT_11` 0x00000800
- *Bit 11.*
- #define `BIT_12` 0x00001000
- *Bit 12.*
- #define `BIT_13` 0x00002000
- *Bit 13.*
- #define `BIT_14` 0x00004000
- *Bit 14.*

- #define [BIT_15](#) 0x00008000
Bit 15.
- #define [BIT_16](#) 0x00010000
Bit 16.
- #define [BIT_17](#) 0x00020000
Bit 17.
- #define [BIT_18](#) 0x00040000
Bit 18.
- #define [BIT_19](#) 0x00080000
Bit 19.
- #define [BIT_20](#) 0x00100000
Bit 20.
- #define [BIT_21](#) 0x00200000
Bit 21.
- #define [BIT_22](#) 0x00400000
Bit 22.
- #define [BIT_23](#) 0x00800000
Bit 23.
- #define [BIT_24](#) 0x01000000
Bit 24.
- #define [BIT_25](#) 0x02000000
Bit 25.
- #define [BIT_26](#) 0x04000000
Bit 26.
- #define [BIT_27](#) 0x08000000
Bit 27.
- #define [BIT_28](#) 0x10000000
Bit 28.
- #define [BIT_29](#) 0x20000000
Bit 29.
- #define [BIT_30](#) 0x40000000
Bit 30.
- #define [BIT_31](#) 0x80000000
Bit 31.
- #define [PLX_DMA_WIDTH_16](#) [BIT_00](#)
PLX DMA Local Bus Width.
- #define [PLX_DMA_READY](#) [BIT_06](#)
PLX DMA Ready.
- #define [PLX_DMA_LOCAL_BURST](#) [BIT_08](#)
PLX DMA Local Burst.
- #define [PLX_DMA_CHAINING](#) [BIT_09](#)
PLX DMA Chaining.
- #define [PLX_DMA_DONE_IT](#) [BIT_10](#)
PLX DMA Done Interrupt.
- #define [PLX_DMA_LA_MODE](#) [BIT_11](#)
PLX DMA Local Addressing Mode.
- #define [PLX_DMA_DEMAND_MODE](#) [BIT_12](#)
PLX DMA Demand Mode.
- #define [PLX_DMA_PCI_IT](#) [BIT_17](#)
PLX DMA PCI Interrupt Enable.
- #define [PLX_DMA_CONFIG](#) [PLX_DMA_WIDTH_16](#)|[PLX_DMA_READY](#)|[PLX_DMA_LOCAL_BURST](#)|[PLX_DMA_DONE_IT](#)|[PLX_DMA_LA_MODE](#)|[PLX_DMA_PCI_IT](#)
Demand Mode DMA Configuration.

6.31.1 Detailed Description

Register definitions for DM75xx devices.

```
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```

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-----
```

```
$Id: dm75xx_registers.h 56268 2011-10-25 18:55:35Z rgroner $
```

Definition in file [dm75xx_registers.h](#).

6.32 include/dm75xx_types.h File Reference

Type definitions used both in kernel and user space.

Data Structures

- struct [_dm75xx_int_status](#)
Interrupts status.
- struct [_dm75xx_cgt_entry](#)
Channel gain table entry.
- struct [dm75xx_pci_access_request](#)
PCI region access request descriptor. This structure holds information about a request to read data from or write data to one of a device's PCI regions.

Typedefs

- typedef enum [dm75xx_pci_region_num](#) [dm75xx_pci_region_num_t](#)
Standard PCI region number type.
- typedef enum [dm75xx_pci_region_access_size](#) [dm75xx_pci_region_access_size_t](#)
Standard PCI region access size type.
- typedef enum [_dm75xx_board](#) [dm75xx_board_t](#)
DM75xx Board Type.
- typedef enum [_dm75xx_dsp_command](#) [dm75xx_dsp_command_t](#)
DSP Command Type.
- typedef enum [_dm75xx_dma_flag](#) [dm75xx_dma_flag_t](#)
DMA Control Flag Type.
- typedef enum [_dm75xx_dma_reset](#) [dm75x_dma_reset_t](#)
DMA Status Reset Flag Type.
- typedef enum [_dm75xx_dma_request](#) [dm75xx_dma_request_t](#)
DMA Demand Mode Source Type.
- typedef enum [_dm75xx_dma_source](#) [dm75xx_dma_source_t](#)
DMA Source Type.
- typedef enum [_dm75xx_dma_channel](#) [dm75xx_dma_channel_t](#)
DMA Channel Type.

- typedef enum [_dm75xx_int_source](#) dm75xx_int_source_t
Interrupt Source Type.
- typedef enum [_dm75xx_algdio_mask](#) dm75xx_algdio_mask_t
Analog DIO Mask Type.
- typedef enum [_dm75xx_algdio_pin](#) dm75xx_algdio_pin_t
Analog DIO Pin Type.
- typedef enum [_dm75xx_algdio_direction](#) dm75xx_algdio_direction_t
Analog DIO Direction Type.
- typedef enum [_dm75xx_uio_channel](#) dm75xx_uio_channel_t
User I/O Channel Type.
- typedef enum [_dm75xx_uio_source](#) dm75xx_uio_source_t
User I/O Source Type.
- typedef enum [_dm75xx_dio_clk](#) dm75xx_dio_clk_t
Digital I/O Clock Type.
- typedef enum [_dm75xx_dio_mode](#) dm75xx_dio_mode_t
Digital I/O IRQ Mode Type.
- typedef enum [_dm75xx_dio_port](#) dm75xx_dio_port_t
Digital I/O Port Type.
- typedef enum [_dm75xx_ext_polarity](#) dm75xx_ext_polarity_t
Polarity Type.
- typedef enum [_dm75xx_sbus](#) dm75xx_sbus_t
SyncBus Enumeration Type.
- typedef enum [_dm75xx_sbus_src](#) dm75xx_sbus_src_t
SyncBus Source Select Type.
- typedef enum [_dm75xx_hsdin_signal](#) dm75xx_hsdin_signal_t
HSDIN Sampling Signal Type.
- typedef enum [_dm75xx_dac_freq](#) dm75xx_dac_freq_t
DAC primary clock source type.
- typedef enum [_dm75xx_dac_clk_stop](#) dm75xx_dac_clk_stop_t
DAC clock stop source type.
- typedef enum [_dm75xx_dac_clk_start](#) dm75xx_dac_clk_start_t
DAC clock start source type.
- typedef enum [_dm75xx_dac_mode](#) dm75xx_dac_mode_t
DAC Cycle Mode Type.
- typedef enum [_dm75xx_dac_update_src](#) dm75xx_dac_update_src_t
DAC Update Source Type.
- typedef enum [_dm75xx_dac_range](#) dm75xx_dac_range_t
DAC Output Range Type.
- typedef enum [_dm75xx_dac_channel](#) dm75xx_dac_channel_t
- typedef enum [_dm75xx_dac_clk_mode](#) dm75xx_dac_clk_mode_t
DAC Clock Mode Type.
- typedef enum [_dm75xx_adc_scnt_src](#) dm75xx_adc_scnt_src_t
ADC Sample Counter Source Type.
- typedef enum [_dm75xx_adc_conv_signal](#) dm75xx_adc_conv_signal_t
ADC Conversion Signal Select type.
- typedef enum [_dm75xx_bclk_freq](#) dm75xx_bclk_freq_t
Burst Clock primary frequency type.
- typedef enum [_dm75xx_bclk_start](#) dm75xx_bclk_start_t
Burst Clock Start Trigger Type.

- typedef enum [_dm75xx_pclk_mode](#) [dm75xx_pclk_mode_t](#)
Pacer Clock Trigger Mode Type.
- typedef enum [_dm75xx_pclk_stop](#) [dm75xx_pclk_stop_t](#)
Pacer Clock Stop Type.
- typedef enum [_dm75xx_pclk_start](#) [dm75xx_pclk_start_t](#)
Pacer Clock Start Type.
- typedef enum [_dm75xx_pclk_select](#) [dm75xx_pclk_select_t](#)
Pacer Clock Select Type.
- typedef enum [_dm75xx_pclk_freq](#) [dm75xx_pclk_freq_t](#)
Pacer Clock Frequency type.
- typedef enum [_dm75xx_utc_timer](#) [dm75xx_utc_timer_t](#)
8254 timer/counter type
- typedef enum [_dm75xx_utc_clk](#) [dm75xx_utc_clk_t](#)
8254 timer/counter clock selector type
- typedef enum [_dm75xx_utc_gate](#) [dm75xx_utc_gate](#)
8254 timer/counter gate selector type
- typedef enum [_dm75xx_utc_mode](#) [dm75xx_utc_mode](#)
8254 timer/counter waveform mode selector type
- typedef enum [_dm75xx_fifo_status](#) [dm75xx_fifo_status_t](#)
FIFO Status Type.
- typedef struct [_dm75xx_int_status](#) [dm75xx_int_status_t](#)
Interrupt status type.
- typedef struct [_dm75xx_cgt_entry](#) [dm75xx_cgt_entry_t](#)
Channel gain table entry type.
- typedef struct
[dm75xx_pci_access_request](#) [dm75xx_pci_access_request_t](#)
PCI region access request descriptor type.

Enumerations

- enum [dm75xx_pci_region_num](#) { [DM75xx_PLX_MEM](#) = 0, [DM75xx_PLX_IO](#), [DM75xx_LAS0](#), [DM75xx_LAS1](#) }
Standard PCI region number.
- enum [dm75xx_pci_region_access_size](#) { [DM75xx_PCI_REGION_ACCESS_8](#) = 0, [DM75xx_PCI_REGION_ACCESS_16](#), [DM75xx_PCI_REGION_ACCESS_32](#) }
Desired size in bits of access to standard PCI region.
- enum [_dm75xx_board](#) { [DM75xx_BOARD_DM7520](#) = 0, [DM75xx_BOARD_SDM7540](#) }
DM75xx Board.
- enum [_dm75xx_dsp_command](#) {
[DM75xx_DSP_CAL_AUTO](#) = 1, [DM75xx_DSP_FLASH_DOWNLOAD](#) = 2, [DM75xx_DSP_USER_RUN](#) = 3,
[DM75xx_DSP_USER_UPGRADE](#) = 4,
[DM75xx_DSP_INT_FLASH_ERASE](#) = 5, [DM75xx_DSP_EXT_FLASH_ERASE](#) = 6, [DM75xx_DSP_ATTENTION](#) = 7, [DM75xx_DSP_CAL_DEFAULT](#) = 8,
[DM75xx_DSP_CAL_VERSION](#) = 10, [DM75xx_DSP_BOOT_VERSION](#) = 11 }
DSP Command.
- enum [_dm75xx_dma_flag](#) {
[DM75xx_DMA_FLAG_INIT](#) = 0x01, [DM75xx_DMA_FLAG_MMAP](#) = 0x02, [DM75xx_DMA_FLAG_RESET](#) = 0x04, [DM75xx_DMA_FLAG_NONDEMAND](#) = 0x08,
[DM75xx_DMA_FLAG_STATUS](#) = 0x10, [DM75xx_DMA_FLAG_ARB](#) = 0x20 }
DMA Control Flag.
- enum [_dm75xx_dma_reset](#) { [DM75xx_DMA_RESET_SEL](#) = 0x01, [DM75xx_DMA_RESET_VAL](#) = 0x10 }
DMA Status Reset Flag.

- enum `_dm75xx_dma_request` {
`DM75xx_DMA_DEMAND_DISABLE` = 0, `DM75xx_DMA_DEMAND_SCNT_ADC` = 1, `DM75xx_DMA_DEMAND_SCNT_DAC1` = 2, `DM75xx_DMA_DEMAND_SCNT_DAC2` = 3,
`DM75xx_DMA_DEMAND_UTC1` = 4, `DM75xx_DMA_DEMAND_FIFO_ADC` = 8, `DM75xx_DMA_DEMAND_FIFO_DAC1` = 9, `DM75xx_DMA_DEMAND_FIFO_DAC2` = 10 }
DMA Demand Mode Source.
- enum `_dm75xx_dma_source` { `DM75xx_DMA_FIFO_ADC` = 0, `DM75xx_DMA_FIFO_DAC1`, `DM75xx_DMA_FIFO_DAC2`, `DM75xx_DMA_FIFO_HSDIN` }
DMA Local Source.
- enum `_dm75xx_dma_channel` { `DM75xx_DMA_CHANNEL_0` = 0, `DM75xx_DMA_CHANNEL_1` }
DMA Channel.
- enum `_dm75xx_int_source` {
`DM75xx_INT_FIFO_WRITE` = 0x0001, `DM75xx_INT_CGT_RESET` = 0x0002, `DM75xx_INT_RESERVED` = 0x0004, `DM75xx_INT_CGT_PAUSE` = 0x0008,
`DM75xx_INT_ABOUT` = 0x0010, `DM75xx_INT_DELAY` = 0x0020, `DM75xx_INT_SCNT_ADC` = 0x0040, `DM75xx_INT_SCNT_DAC1` = 0x0080,
`DM75xx_INT_SCNT_DAC2` = 0x0100, `DM75xx_INT_UTC1` = 0x0200, `DM75xx_INT_UTC1_INV` = 0x0400, `DM75xx_INT_UTC2` = 0x0800,
`DM75xx_INT_DIO` = 0x1000, `DM75xx_INT_EXTERNAL` = 0x2000, `DM75xx_INT_ETRIG_RISING` = 0x4000, `DM75xx_INT_ETRIG_FALLING` = 0x8000,
`DM75xx_INT_DMA_0` = 0x00200000, `DM75xx_INT_DMA_1` = 0x00400000, `DM75xx_INT_ALGDIO_POS_PIN1` = 0x04000000, `DM75xx_INT_ALGDIO_POS_PIN2` = 0x08000000,
`DM75xx_INT_ALGDIO_NEG_PIN1` = 0x10000000, `DM75xx_INT_ALGDIO_NEG_PIN2` = 0x20000000 }
Interrupt Source.
- enum `_dm75xx_algdio_mask` { `DM75xx_ALGDIO_MASKED` = 0, `DM75xx_ALGDIO_UNMASKED` }
Analog DIO Mask.
- enum `_dm75xx_algdio_pin` { `DM75xx_ALGDIO_PIN1` = 0, `DM75xx_ALGDIO_PIN2` }
Analog DIO Pins.
- enum `_dm75xx_algdio_direction` { `DM75xx_ALGDIO_INPUT` = 0, `DM75xx_ALGDIO_OUTPUT` }
Analog DIO Direction.
- enum `_dm75xx_uio_channel` { `DM75xx_UIO0` = 0, `DM75xx_UIO1` }
User I/O Channel.
- enum `_dm75xx_uio_source` { `DM75xx_UIO_ADC` = 0, `DM75xx_UIO_DAC1`, `DM75xx_UIO_DAC2`, `DM75xx_UIO_PRG` }
User I/O Source.
- enum `_dm75xx_dio_clk` { `DM75xx_DIO_CLK_8MHZ` = 0, `DM75xx_DIO_CLK_UTC1` }
Digital I/O Clock.
- enum `_dm75xx_dio_mode` { `DM75xx_DIO_MODE_EVENT` = 0, `DM75xx_DIO_MODE_MATCH` }
Digital I/O IRQ Mode.
- enum `_dm75xx_dio_port` { `DM75xx_DIO_PORT0` = 0, `DM75xx_DIO_PORT1` }
Digital I/O Port.
- enum `_dm75xx_ext_polarity` { `DM75xx_EXT_POLARITY_POS` = 0, `DM75xx_EXT_POLARITY_NEG` }
Polarity.
- enum `_dm75xx_sbus` { `DM75xx_SBUS0` = 0, `DM75xx_SBUS1`, `DM75xx_SBUS2` }
SyncBus Enumerations.
- enum `_dm75xx_sbus_src` {
`DM75xx_SBUS_SRC_SOFT_ADC` = 0, `DM75xx_SBUS_SRC_PCLK` = 1, `DM75xx_SBUS_SRC_PCLK_START` = 1, `DM75xx_SBUS_SRC_BCLK` = 2,
`DM75xx_SBUS_SRC_PCLK_STOP` = 2, `DM75xx_SBUS_SRC_DIG_IT` = 3, `DM75xx_SBUS_SRC_DAC1` = 3, `DM75xx_SBUS_SRC_ETRIG` = 4,
`DM75xx_SBUS_SRC_DAC2` = 4, `DM75xx_SBUS_SRC_DAC_UPDATE` = 5, `DM75xx_SBUS_SRC_EPCLK` = 5, `DM75xx_SBUS_SRC_DAC_CLK` = 6,
`DM75xx_SBUS_SRC_ETRIG2` = 6, `DM75xx_SBUS_SRC_UTC2` = 7 }
SyncBus Source Select.

- enum `_dm75xx_hsdin_signal` {
`DM75xx_HSDIN_SIGNAL_SOFTWARE = 0, DM75xx_HSDIN_SIGNAL_ADC, DM75xx_HSDIN_SIGNAL_UTC0, DM75xx_HSDIN_SIGNAL_UTC1, DM75xx_HSDIN_SIGNAL_UTC2, DM75xx_HSDIN_SIGNAL_EPCLK, DM75xx_HSDIN_SIGNAL_ETRIG` }
HSDIN Sampling Signal.
- enum `_dm75xx_dac_freq` { `DM75xx_DAC_FREQ_8_MHZ = 0, DM75xx_DAC_FREQ_20_MHZ` }
DAC primary clock source.
- enum `_dm75xx_dac_clk_stop` {
`DM75xx_DAC_CLK_STOP_SOFTWARE_PACER = 0, DM75xx_DAC_CLK_STOP_ETRIG, DM75xx_DAC_CLK_STOP_DIG_IT, DM75xx_DAC_CLK_STOP_UTC2, DM75xx_DAC_CLK_STOP_SBUS0, DM75xx_DAC_CLK_STOP_SBUS1, DM75xx_DAC_CLK_STOP_SBUS2, DM75xx_DAC_CLK_STOP_SOFTWARE, DM75xx_DAC_CLK_STOP_DAC1_UCNT, DM75xx_DAC_CLK_STOP_DAC2_UCNT` }
DAC clock stop source.
- enum `_dm75xx_dac_clk_start` {
`DM75xx_DAC_CLK_START_SOFTWARE_PACER = 0, DM75xx_DAC_CLK_START_ETRIG, DM75xx_DAC_CLK_START_DIG_IT, DM75xx_DAC_CLK_START_UTC2, DM75xx_DAC_CLK_START_SBUS0, DM75xx_DAC_CLK_START_SBUS1, DM75xx_DAC_CLK_START_SBUS2, DM75xx_DAC_CLK_START_SOFTWARE` }
DAC clock start source.
- enum `_dm75xx_dac_mode` { `DM75xx_DAC_MODE_NOT_CYCLE = 0, DM75xx_DAC_MODE_CYCLE` }
DAC Cycle Mode.
- enum `_dm75xx_dac_update_src` {
`DM75xx_DAC_UPDATE_SOFTWARE = 0, DM75xx_DAC_UPDATE_CGT, DM75xx_DAC_UPDATE_EPCLK, DM75xx_DAC_UPDATE_SBUS0, DM75xx_DAC_UPDATE_SBUS1, DM75xx_DAC_UPDATE_SBUS2` }
DAC Update Source.
- enum `_dm75xx_dac_range` { `DM75xx_DAC_RANGE_UNIPOLAR_5 = 0, DM75xx_DAC_RANGE_UNIPOLAR_10, DM75xx_DAC_RANGE_BIPOLAR_5, DM75xx_DAC_RANGE_BIPOLAR_10` }
DAC Output Range.
- enum `_dm75xx_dac_channel` { `DM75xx_DAC1 = 1, DM75xx_DAC2` }
DAC channels.
- enum `_dm75xx_dac_clk_mode` { `DM75xx_DAC_CLK_FREE_RUN = 0, DM75xx_DAC_CLK_START_STOP` }
DAC Clock Mode.
- enum `_dm75xx_adc_scnt_src` { `DM75xx_ADC_SCNT_SRC_CGT = 0, DM75xx_ADC_SCNT_SRC_FIFO` }
ADC Sample Counter Source.
- enum `_dm75xx_adc_conv_signal` {
`DM75xx_ADC_CONV_SIGNAL_SOFTWARE = 0, DM75xx_ADC_CONV_SIGNAL_PCLK, DM75xx_ADC_CONV_SIGNAL_BCLK, DM75xx_ADC_CONV_SIGNAL_DIG_IT, DM75xx_ADC_CONV_SIGNAL_DAC1_MRKR1, DM75xx_ADC_CONV_SIGNAL_DAC2_MRKR1, DM75xx_ADC_CONV_SIGNAL_SBUS0, DM75xx_ADC_CONV_SIGNAL_SBUS1, DM75xx_ADC_CONV_SIGNAL_SBUS2` }
ADC Conversion Signal Select.
- enum `_dm75xx_bclk_freq` { `DM75xx_BCLK_FREQ_8_MHZ = 0, DM75xx_BCLK_FREQ_20_MHZ` }
Burst Clock primary frequency.
- enum `_dm75xx_bclk_start` {
`DM75xx_BCLK_START_SOFTWARE = 0, DM75xx_BCLK_START_PACER, DM75xx_BCLK_START_ETRIG, DM75xx_BCLK_START_DIG_IT, DM75xx_BCLK_START_SBUS0, DM75xx_BCLK_START_SBUS1, DM75xx_BCLK_START_SBUS2` }
Burst Clock Start Trigger.
- enum `_dm75xx_pclk_mode` { `DM75xx_PCLK_NO_REPEAT = 0, DM75xx_PCLK_REPEAT` }
Pacer Clock Trigger Mode.

- enum `_dm75xx_pclk_stop` {
`DM75xx_PCLK_STOP_SOFTWARE = 0, DM75xx_PCLK_STOP_ETRIG, DM75xx_PCLK_STOP_DIGITAL_IT, DM75xx_PCLK_STOP_ACNT,`
`DM75xx_PCLK_STOP_UTC2, DM75xx_PCLK_STOP_SBUS0, DM75xx_PCLK_STOP_SBUS1, DM75xx_PCLK_STOP_SBUS2,`
`DM75xx_PCLK_STOP_ASOFTWARE, DM75xx_PCLK_STOP_AETRIG, DM75xx_PCLK_STOP_ADIGITAL_IT, DM75xx_PCLK_STOP_RES,`
`DM75xx_PCLK_STOP_AUTC2, DM75xx_PCLK_STOP_ASBUS0, DM75xx_PCLK_STOP_ASBUS1, DM75xx_PCLK_STOP_ASBUS2 }`
Pacer Clock Stop.
- enum `_dm75xx_pclk_start` {
`DM75xx_PCLK_START_SOFTWARE = 0, DM75xx_PCLK_START_ETRIG, DM75xx_PCLK_START_DIGITAL_IT, DM75xx_PCLK_START_UTC2,`
`DM75xx_PCLK_START_SBUS0, DM75xx_PCLK_START_SBUS1, DM75xx_PCLK_START_SBUS2, DM75xx_PCLK_START_RES,`
`DM75xx_PCLK_START_DSOFTWARE, DM75xx_PCLK_START_DETRIG, DM75xx_PCLK_START_DIGITAL_IT, DM75xx_PCLK_START_DUTC2,`
`DM75xx_PCLK_START_DSBUS0, DM75xx_PCLK_START_DSBUS1, DM75xx_PCLK_START_DSBUS2, DM75xx_PCLK_START_ETRIG_GATE }`
Pacer Clock Start.
- enum `_dm75xx_pclk_select` { `DM75xx_PCLK_EXTERNAL = 0, DM75xx_PCLK_INTERNAL }`
Pacer Clock Select.
- enum `_dm75xx_pclk_freq` { `DM75xx_PCLK_FREQ_8_MHZ = 0, DM75xx_PCLK_FREQ_20_MHZ }`
Pacer Clock Frequency Select.
- enum `_dm75xx_utc_timer` { `DM75xx_UTC_0 = 0, DM75xx_UTC_1, DM75xx_UTC_2 }`
8254 timers/counters
- enum `_dm75xx_utc_clk` {
`DM75xx_CUTC_8_MHZ = 0, DM75xx_CUTC_EXT_TC_CLOCK_1 = 1, DM75xx_CUTC_EXT_TC_CLOCK_2 = 2, DM75xx_CUTC_EXT_PCLK = 3,`
`DM75xx_CUTC_UTC_0_OUT = 4, DM75xx_CUTC_UTC_1_OUT = 4, DM75xx_CUTC_HSDIN_SIGNAL = 5 }`
8254 timer/counter clock selectors
- enum `_dm75xx_utc_gate` {
`DM75xx_GUTC_NOT_GATED = 0, DM75xx_GUTC_GATED = 1, DM75xx_GUTC_EXT_TC_CLK_1 = 2, DM75xx_GUTC_EXT_TC_CLK_2 = 3,`
`DM75xx_GUTC_UTC_0_OUT = 4, DM75xx_GUTC_UTC_1_OUT = 4 }`
8254 timer/counter gate selectors
- enum `_dm75xx_utc_mode` {
`DM75xx_UTC_MODE_EVENT_COUNTER = 0, DM75xx_UTC_MODE_PROG_ONE_SHOT, DM75xx_UTC_MODE_RATE_GENERATOR, DM75xx_UTC_MODE_SQUARE_WAVE,`
`DM75xx_UTC_MODE_SOFTWARE_STROBE, DM75xx_UTC_MODE_HARDWARE_STROBE }`
8254 timer/counter waveform mode selectors
- enum `_dm75xx_fifo_status` {
`DM75xx_FIFO_DAC1_NOT_EMPTY = 0x0001, DM75xx_FIFO_DAC1_HALF_EMPTY = 0x0002, DM75xx_FIFO_DAC1_NOT_FULL = 0x0004, DM75xx_FIFO_DAC2_NOT_EMPTY = 0x0010,`
`DM75xx_FIFO_DAC2_HALF_EMPTY = 0x0020, DM75xx_FIFO_DAC2_NOT_FULL = 0x0040, DM75xx_FIFO_ADC_NOT_EMPTY = 0x0100, DM75xx_FIFO_ADC_HALF_EMPTY = 0x0200,`
`DM75xx_FIFO_ADC_NOT_FULL = 0x0400, DM75xx_FIFO_HSDIN_NOT_EMPTY = 0x1000, DM75xx_FIFO_HSDIN_HALF_EMPTY = 0x2000, DM75xx_FIFO_HSDIN_NOT_FULL = 0x4000 }`
FIFO status.

6.32.1 Detailed Description

Type definitions used both in kernel and user space.

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[dm75xx_types.h](#) 79763 2014-06-13 21:01:02Z rgroner

Definition in file [dm75xx_types.h](#).

Index

DM75xx driver enumerations

- DM75xx_PCI_REGION_ACCESS_READ, [8](#)
- DM75xx_PCI_REGION_ACCESS_WRITE, [8](#)

DM75xx ioctl enumerations

- DM75xx_DMA_FUNCTION_ABORT, [29](#)
- DM75xx_DMA_FUNCTION_INITIALIZE, [29](#)
- DM75xx_INT_CONTROL_CHECK, [29](#)
- DM75xx_INT_CONTROL_DISABLE, [29](#)
- DM75xx_INT_CONTROL_ENABLE, [29](#)

DM75xx type Analog DIO

- DM75xx_ALGDIO_INPUT, [116](#)
- DM75xx_ALGDIO_MASKED, [116](#)
- DM75xx_ALGDIO_OUTPUT, [116](#)
- DM75xx_ALGDIO_PIN1, [117](#)
- DM75xx_ALGDIO_PIN2, [117](#)
- DM75xx_ALGDIO_UNMASKED, [116](#)

DM75xx type Analog to Digital enumerations

- DM75xx_ADC_CONV_SIGNAL_BCLK, [129](#)
- DM75xx_ADC_CONV_SIGNAL_DAC1_MRKR1, [129](#)
- DM75xx_ADC_CONV_SIGNAL_DAC2_MRKR1, [129](#)
- DM75xx_ADC_CONV_SIGNAL_DIG_IT, [129](#)
- DM75xx_ADC_CONV_SIGNAL_PCLK, [129](#)
- DM75xx_ADC_CONV_SIGNAL_SBUS0, [129](#)
- DM75xx_ADC_CONV_SIGNAL_SBUS1, [129](#)
- DM75xx_ADC_CONV_SIGNAL_SBUS2, [129](#)
- DM75xx_ADC_CONV_SIGNAL_SOFTWARE, [129](#)
- DM75xx_ADC_SCNT_SRC_CGT, [130](#)
- DM75xx_ADC_SCNT_SRC_FIFO, [130](#)

DM75xx type Burst Clock enumerations

- DM75xx_BCLK_FREQ_20_MHZ, [131](#)
- DM75xx_BCLK_FREQ_8_MHZ, [131](#)
- DM75xx_BCLK_START_DIG_IT, [131](#)
- DM75xx_BCLK_START_ETRIG, [131](#)
- DM75xx_BCLK_START_PACER, [131](#)
- DM75xx_BCLK_START_SBUS0, [131](#)
- DM75xx_BCLK_START_SBUS1, [131](#)
- DM75xx_BCLK_START_SBUS2, [131](#)
- DM75xx_BCLK_START_SOFTWARE, [131](#)

DM75xx type DMA

- DM75xx_DMA_CHANNEL_0, [112](#)
- DM75xx_DMA_CHANNEL_1, [112](#)
- DM75xx_DMA_DEMAND_DISABLE, [113](#)
- DM75xx_DMA_DEMAND_FIFO_ADC, [113](#)
- DM75xx_DMA_DEMAND_FIFO_DAC1, [113](#)
- DM75xx_DMA_DEMAND_FIFO_DAC2, [113](#)
- DM75xx_DMA_DEMAND_SCNT_ADC, [113](#)
- DM75xx_DMA_DEMAND_SCNT_DAC1, [113](#)

- DM75xx_DMA_DEMAND_SCNT_DAC2, [113](#)

- DM75xx_DMA_DEMAND_UTC1, [113](#)
- DM75xx_DMA_FIFO_ADC, [113](#)
- DM75xx_DMA_FIFO_DAC1, [113](#)
- DM75xx_DMA_FIFO_DAC2, [113](#)
- DM75xx_DMA_FIFO_HSDIN, [113](#)
- DM75xx_DMA_FLAG_ARB, [113](#)
- DM75xx_DMA_FLAG_INIT, [113](#)
- DM75xx_DMA_FLAG_MMAP, [113](#)
- DM75xx_DMA_FLAG_NONDEMAND, [113](#)
- DM75xx_DMA_FLAG_RESET, [113](#)
- DM75xx_DMA_FLAG_STATUS, [113](#)
- DM75xx_DMA_RESET_SEL, [113](#)
- DM75xx_DMA_RESET_VAL, [113](#)

DM75xx type DSP enumerations

- DM75xx_DSP_ATTENTION, [111](#)
- DM75xx_DSP_BOOT_VERSION, [111](#)
- DM75xx_DSP_CAL_AUTO, [111](#)
- DM75xx_DSP_CAL_DEFAULT, [111](#)
- DM75xx_DSP_CAL_VERSION, [111](#)
- DM75xx_DSP_EXT_FLASH_ERASE, [111](#)
- DM75xx_DSP_FLASH_DOWNLOAD, [111](#)
- DM75xx_DSP_INT_FLASH_ERASE, [111](#)
- DM75xx_DSP_USER_RUN, [111](#)
- DM75xx_DSP_USER_UPGRADE, [111](#)

DM75xx type definition structures

- DM75xx_FIFO_ADC_HALF_EMPTY, [138](#)
- DM75xx_FIFO_ADC_NOT_EMPTY, [138](#)
- DM75xx_FIFO_ADC_NOT_FULL, [138](#)
- DM75xx_FIFO_DAC1_HALF_EMPTY, [137](#)
- DM75xx_FIFO_DAC1_NOT_EMPTY, [137](#)
- DM75xx_FIFO_DAC1_NOT_FULL, [137](#)
- DM75xx_FIFO_DAC2_HALF_EMPTY, [137](#)
- DM75xx_FIFO_DAC2_NOT_EMPTY, [137](#)
- DM75xx_FIFO_DAC2_NOT_FULL, [138](#)
- DM75xx_FIFO_HSDIN_HALF_EMPTY, [138](#)
- DM75xx_FIFO_HSDIN_NOT_EMPTY, [138](#)
- DM75xx_FIFO_HSDIN_NOT_FULL, [138](#)

DM75xx type Digital Input/Output

- DM75xx_DIO_CLK_8MHZ, [119](#)
- DM75xx_DIO_CLK_UTC1, [119](#)
- DM75xx_DIO_MODE_EVENT, [119](#)
- DM75xx_DIO_MODE_MATCH, [119](#)
- DM75xx_DIO_PORT0, [120](#)
- DM75xx_DIO_PORT1, [120](#)

DM75xx type Digital to Analog enumerations

- DM75xx_DAC1, [126](#)
- DM75xx_DAC2, [126](#)
- DM75xx_DAC_CLK_FREE_RUN, [126](#)

- DM75xx_DAC_CLK_START_DIG_IT, 126
- DM75xx_DAC_CLK_START_ETRIG, 126
- DM75xx_DAC_CLK_START_SBUS0, 126
- DM75xx_DAC_CLK_START_SBUS1, 126
- DM75xx_DAC_CLK_START_SBUS2, 126
- DM75xx_DAC_CLK_START_SOFTWARE, 126
- DM75xx_DAC_CLK_START_SOFTWARE_PAC←
ER, 126
- DM75xx_DAC_CLK_START_STOP, 126
- DM75xx_DAC_CLK_START_UTC2, 126
- DM75xx_DAC_CLK_STOP_DAC1_UCNT, 127
- DM75xx_DAC_CLK_STOP_DAC2_UCNT, 127
- DM75xx_DAC_CLK_STOP_DIG_IT, 127
- DM75xx_DAC_CLK_STOP_ETRIG, 127
- DM75xx_DAC_CLK_STOP_SBUS0, 127
- DM75xx_DAC_CLK_STOP_SBUS1, 127
- DM75xx_DAC_CLK_STOP_SBUS2, 127
- DM75xx_DAC_CLK_STOP_SOFTWARE, 127
- DM75xx_DAC_CLK_STOP_SOFTWARE_PACE←
R, 127
- DM75xx_DAC_CLK_STOP_UTC2, 127
- DM75xx_DAC_FREQ_20_MHZ, 127
- DM75xx_DAC_FREQ_8_MHZ, 127
- DM75xx_DAC_MODE_CYCLE, 127
- DM75xx_DAC_MODE_NOT_CYCLE, 127
- DM75xx_DAC_RANGE_BIPOLAR_10, 127
- DM75xx_DAC_RANGE_BIPOLAR_5, 127
- DM75xx_DAC_RANGE_UNIPOLAR_10, 127
- DM75xx_DAC_RANGE_UNIPOLAR_5, 127
- DM75xx_DAC_UPDATE_CGT, 128
- DM75xx_DAC_UPDATE_CLOCK, 128
- DM75xx_DAC_UPDATE_EPCLK, 128
- DM75xx_DAC_UPDATE_SBUS0, 128
- DM75xx_DAC_UPDATE_SBUS1, 128
- DM75xx_DAC_UPDATE_SBUS2, 128
- DM75xx_DAC_UPDATE_SOFTWARE, 128
- DM75xx type External Trigger/Interrupt
 - DM75xx_EXT_POLARITY_NEG, 121
 - DM75xx_EXT_POLARITY_POS, 121
- DM75xx type HighSpeed Digital enumerations
 - DM75xx_HSDIN_SIGNAL_ADC, 124
 - DM75xx_HSDIN_SIGNAL_EPCLK, 124
 - DM75xx_HSDIN_SIGNAL_ETRIG, 124
 - DM75xx_HSDIN_SIGNAL_SOFTWARE, 124
 - DM75xx_HSDIN_SIGNAL_UTC0, 124
 - DM75xx_HSDIN_SIGNAL_UTC1, 124
 - DM75xx_HSDIN_SIGNAL_UTC2, 124
- DM75xx type Interrupt
 - DM75xx_INT_ABOUT, 114
 - DM75xx_INT_ALGDIO_NEG_PIN1, 115
 - DM75xx_INT_ALGDIO_NEG_PIN2, 115
 - DM75xx_INT_ALGDIO_POS_PIN1, 115
 - DM75xx_INT_ALGDIO_POS_PIN2, 115
 - DM75xx_INT_CGT_PAUSE, 114
 - DM75xx_INT_CGT_RESET, 114
 - DM75xx_INT_DELAY, 114
 - DM75xx_INT_DIO, 114
 - DM75xx_INT_DMA_0, 115
 - DM75xx_INT_DMA_1, 115
 - DM75xx_INT_ETRIG_FALLING, 114
 - DM75xx_INT_ETRIG_RISING, 114
 - DM75xx_INT_EXTERNAL, 114
 - DM75xx_INT_FIFO_WRITE, 114
 - DM75xx_INT_RESERVED, 114
 - DM75xx_INT_SCNT_ADC, 114
 - DM75xx_INT_SCNT_DAC1, 114
 - DM75xx_INT_SCNT_DAC2, 114
 - DM75xx_INT_UTC1, 114
 - DM75xx_INT_UTC1_INV, 114
 - DM75xx_INT_UTC2, 114
- DM75xx type PCI enumerations
 - DM75xx_BOARD_DM7520, 109
 - DM75xx_BOARD_SDM7540, 109
 - DM75xx_LAS0, 110
 - DM75xx_LAS1, 110
 - DM75xx_PCI_REGION_ACCESS_16, 109
 - DM75xx_PCI_REGION_ACCESS_32, 109
 - DM75xx_PCI_REGION_ACCESS_8, 109
 - DM75xx_PLX_IO, 110
 - DM75xx_PLX_MEM, 110
- DM75xx type Pacer Clock enumerations
 - DM75xx_PCLK_EXTERNAL, 133
 - DM75xx_PCLK_FREQ_20_MHZ, 133
 - DM75xx_PCLK_FREQ_8_MHZ, 133
 - DM75xx_PCLK_INTERNAL, 133
 - DM75xx_PCLK_NO_REPEAT, 133
 - DM75xx_PCLK_REPEAT, 133
 - DM75xx_PCLK_START_DDIGITAL_IT, 133
 - DM75xx_PCLK_START_DETRIG, 133
 - DM75xx_PCLK_START_DIGITAL_IT, 133
 - DM75xx_PCLK_START_DSBUS0, 133
 - DM75xx_PCLK_START_DSBUS1, 133
 - DM75xx_PCLK_START_DSBUS2, 133
 - DM75xx_PCLK_START_DSOFTWARE, 133
 - DM75xx_PCLK_START_DUTC2, 133
 - DM75xx_PCLK_START_ETRIG, 133
 - DM75xx_PCLK_START_ETRIG_GATE, 133
 - DM75xx_PCLK_START_RES, 133
 - DM75xx_PCLK_START_SBUS0, 133
 - DM75xx_PCLK_START_SBUS1, 133
 - DM75xx_PCLK_START_SBUS2, 133
 - DM75xx_PCLK_START_SOFTWARE, 133
 - DM75xx_PCLK_START_UTC2, 133
 - DM75xx_PCLK_STOP_ACNT, 134
 - DM75xx_PCLK_STOP_ADIGITAL_IT, 134
 - DM75xx_PCLK_STOP_AETRIG, 134
 - DM75xx_PCLK_STOP_ASBUS0, 134
 - DM75xx_PCLK_STOP_ASBUS1, 134
 - DM75xx_PCLK_STOP_ASBUS2, 134
 - DM75xx_PCLK_STOP_ASOFTWARE, 134
 - DM75xx_PCLK_STOP_AUTC2, 134
 - DM75xx_PCLK_STOP_DIGITAL_IT, 134
 - DM75xx_PCLK_STOP_ETRIG, 134
 - DM75xx_PCLK_STOP_RES, 134
 - DM75xx_PCLK_STOP_SBUS0, 134
 - DM75xx_PCLK_STOP_SBUS1, 134

- DM75xx_PCLK_STOP_SBUS2, [134](#)
- DM75xx_PCLK_STOP_SOFTWARE, [134](#)
- DM75xx_PCLK_STOP_UTC2, [134](#)
- DM75xx type SyncBus enumerations
 - DM75xx_SBUS0, [122](#)
 - DM75xx_SBUS1, [122](#)
 - DM75xx_SBUS2, [122](#)
 - DM75xx_SBUS_SRC_BCLK, [122](#)
 - DM75xx_SBUS_SRC_DAC1, [123](#)
 - DM75xx_SBUS_SRC_DAC2, [123](#)
 - DM75xx_SBUS_SRC_DAC_CLK, [123](#)
 - DM75xx_SBUS_SRC_DAC_UPDATE, [123](#)
 - DM75xx_SBUS_SRC_DIG_IT, [122](#)
 - DM75xx_SBUS_SRC_EPCLK, [123](#)
 - DM75xx_SBUS_SRC_ETRIG, [123](#)
 - DM75xx_SBUS_SRC_ETRIG2, [123](#)
 - DM75xx_SBUS_SRC_PCLK, [122](#)
 - DM75xx_SBUS_SRC_PCLK_START, [122](#)
 - DM75xx_SBUS_SRC_PCLK_STOP, [122](#)
 - DM75xx_SBUS_SRC_SOFT_ADC, [122](#)
 - DM75xx_SBUS_SRC_UTC2, [123](#)
- DM75xx type timer/counter enumerations
 - DM75xx_CUTC_8_MHZ, [135](#)
 - DM75xx_CUTC_EXT_PCLK, [135](#)
 - DM75xx_CUTC_EXT_TC_CLOCK_1, [135](#)
 - DM75xx_CUTC_EXT_TC_CLOCK_2, [135](#)
 - DM75xx_CUTC_HSDIN_SIGNAL, [135](#)
 - DM75xx_CUTC_UTC_0_OUT, [135](#)
 - DM75xx_CUTC_UTC_1_OUT, [135](#)
 - DM75xx_GUTC_EXT_TC_CLK_1, [136](#)
 - DM75xx_GUTC_EXT_TC_CLK_2, [136](#)
 - DM75xx_GUTC_GATED, [136](#)
 - DM75xx_GUTC_NOT_GATED, [136](#)
 - DM75xx_GUTC_UTC_0_OUT, [136](#)
 - DM75xx_GUTC_UTC_1_OUT, [136](#)
 - DM75xx_UTC_0, [136](#)
 - DM75xx_UTC_1, [136](#)
 - DM75xx_UTC_2, [136](#)
 - DM75xx_UTC_MODE_EVENT_COUNTER, [136](#)
 - DM75xx_UTC_MODE_HARDWARE_STROBE, [136](#)
 - DM75xx_UTC_MODE_PROG_ONE_SHOT, [136](#)
 - DM75xx_UTC_MODE_RATE_GENERATOR, [136](#)
 - DM75xx_UTC_MODE_SOFTWARE_STROBE, [136](#)
 - DM75xx_UTC_MODE_SQUARE_WAVE, [136](#)
- DM75xx type User Output
 - DM75xx_UIO0, [118](#)
 - DM75xx_UIO1, [118](#)
 - DM75xx_UIO_ADC, [118](#)
 - DM75xx_UIO_DAC1, [118](#)
 - DM75xx_UIO_DAC2, [118](#)
 - DM75xx_UIO_PRG, [118](#)
- DM75xx_ADC_CONV_SIGNAL_BCLK
 - DM75xx type Analog to Digital enumerations, [129](#)
- DM75xx_ADC_CONV_SIGNAL_DAC1_MRKR1
 - DM75xx type Analog to Digital enumerations, [129](#)
- DM75xx_ADC_CONV_SIGNAL_DAC2_MRKR1
 - DM75xx type Analog to Digital enumerations, [129](#)
- DM75xx_ADC_CONV_SIGNAL_DIG_IT
 - DM75xx type Analog to Digital enumerations, [129](#)
- DM75xx_ADC_CONV_SIGNAL_PCLK
 - DM75xx type Analog to Digital enumerations, [129](#)
- DM75xx_ADC_CONV_SIGNAL_SBUS0
 - DM75xx type Analog to Digital enumerations, [129](#)
- DM75xx_ADC_CONV_SIGNAL_SBUS1
 - DM75xx type Analog to Digital enumerations, [129](#)
- DM75xx_ADC_CONV_SIGNAL_SBUS2
 - DM75xx type Analog to Digital enumerations, [129](#)
- DM75xx_ADC_CONV_SIGNAL_SOFTWARE
 - DM75xx type Analog to Digital enumerations, [129](#)
- DM75xx_ADC_SCNT_SRC_CGT
 - DM75xx type Analog to Digital enumerations, [130](#)
- DM75xx_ADC_SCNT_SRC_FIFO
 - DM75xx type Analog to Digital enumerations, [130](#)
- DM75xx_ALGDIO_INPUT
 - DM75xx type Analog DIO, [116](#)
- DM75xx_ALGDIO_MASKED
 - DM75xx type Analog DIO, [116](#)
- DM75xx_ALGDIO_OUTPUT
 - DM75xx type Analog DIO, [116](#)
- DM75xx_ALGDIO_PIN1
 - DM75xx type Analog DIO, [117](#)
- DM75xx_ALGDIO_PIN2
 - DM75xx type Analog DIO, [117](#)
- DM75xx_ALGDIO_UNMASKED
 - DM75xx type Analog DIO, [116](#)
- DM75xx_BCLK_FREQ_20_MHZ
 - DM75xx type Burst Clock enumerations, [131](#)
- DM75xx_BCLK_FREQ_8_MHZ
 - DM75xx type Burst Clock enumerations, [131](#)
- DM75xx_BCLK_START_DIG_IT
 - DM75xx type Burst Clock enumerations, [131](#)
- DM75xx_BCLK_START_ETRIG
 - DM75xx type Burst Clock enumerations, [131](#)
- DM75xx_BCLK_START_PACER
 - DM75xx type Burst Clock enumerations, [131](#)
- DM75xx_BCLK_START_SBUS0
 - DM75xx type Burst Clock enumerations, [131](#)
- DM75xx_BCLK_START_SBUS1
 - DM75xx type Burst Clock enumerations, [131](#)
- DM75xx_BCLK_START_SBUS2
 - DM75xx type Burst Clock enumerations, [131](#)
- DM75xx_BCLK_START_SOFTWARE
 - DM75xx type Burst Clock enumerations, [131](#)
- DM75xx_BOARD_DM7520
 - DM75xx type PCI enumerations, [109](#)
- DM75xx_BOARD_SDM7540
 - DM75xx type PCI enumerations, [109](#)
- DM75xx_CUTC_8_MHZ
 - DM75xx type timer/counter enumerations, [135](#)
- DM75xx_CUTC_EXT_PCLK
 - DM75xx type timer/counter enumerations, [135](#)
- DM75xx_CUTC_EXT_TC_CLOCK_1
 - DM75xx type timer/counter enumerations, [135](#)
- DM75xx_CUTC_EXT_TC_CLOCK_2

- DM75xx type timer/counter enumerations, [135](#)
- DM75xx_CUTC_HSDIN_SIGNAL
 - DM75xx type timer/counter enumerations, [135](#)
- DM75xx_CUTC_UTC_0_OUT
 - DM75xx type timer/counter enumerations, [135](#)
- DM75xx_CUTC_UTC_1_OUT
 - DM75xx type timer/counter enumerations, [135](#)
- DM75xx_DAC1
 - DM75xx type Digital to Analog enumerations, [126](#)
- DM75xx_DAC2
 - DM75xx type Digital to Analog enumerations, [126](#)
- DM75xx_DAC_CLK_FREE_RUN
 - DM75xx type Digital to Analog enumerations, [126](#)
- DM75xx_DAC_CLK_START_DIG_IT
 - DM75xx type Digital to Analog enumerations, [126](#)
- DM75xx_DAC_CLK_START_ETRIG
 - DM75xx type Digital to Analog enumerations, [126](#)
- DM75xx_DAC_CLK_START_SBUS0
 - DM75xx type Digital to Analog enumerations, [126](#)
- DM75xx_DAC_CLK_START_SBUS1
 - DM75xx type Digital to Analog enumerations, [126](#)
- DM75xx_DAC_CLK_START_SBUS2
 - DM75xx type Digital to Analog enumerations, [126](#)
- DM75xx_DAC_CLK_START_SOFTWARE
 - DM75xx type Digital to Analog enumerations, [126](#)
- DM75xx_DAC_CLK_START_SOFTWARE_PACER
 - DM75xx type Digital to Analog enumerations, [126](#)
- DM75xx_DAC_CLK_START_STOP
 - DM75xx type Digital to Analog enumerations, [126](#)
- DM75xx_DAC_CLK_START_UTC2
 - DM75xx type Digital to Analog enumerations, [126](#)
- DM75xx_DAC_CLK_STOP_DAC1_UCNT
 - DM75xx type Digital to Analog enumerations, [127](#)
- DM75xx_DAC_CLK_STOP_DAC2_UCNT
 - DM75xx type Digital to Analog enumerations, [127](#)
- DM75xx_DAC_CLK_STOP_DIG_IT
 - DM75xx type Digital to Analog enumerations, [127](#)
- DM75xx_DAC_CLK_STOP_ETRIG
 - DM75xx type Digital to Analog enumerations, [127](#)
- DM75xx_DAC_CLK_STOP_SBUS0
 - DM75xx type Digital to Analog enumerations, [127](#)
- DM75xx_DAC_CLK_STOP_SBUS1
 - DM75xx type Digital to Analog enumerations, [127](#)
- DM75xx_DAC_CLK_STOP_SBUS2
 - DM75xx type Digital to Analog enumerations, [127](#)
- DM75xx_DAC_CLK_STOP_SOFTWARE
 - DM75xx type Digital to Analog enumerations, [127](#)
- DM75xx_DAC_CLK_STOP_SOFTWARE_PACER
 - DM75xx type Digital to Analog enumerations, [127](#)
- DM75xx_DAC_CLK_STOP_UTC2
 - DM75xx type Digital to Analog enumerations, [127](#)
- DM75xx_DAC_FREQ_20_MHZ
 - DM75xx type Digital to Analog enumerations, [127](#)
- DM75xx_DAC_FREQ_8_MHZ
 - DM75xx type Digital to Analog enumerations, [127](#)
- DM75xx_DAC_MODE_CYCLE
 - DM75xx type Digital to Analog enumerations, [127](#)
- DM75xx_DAC_MODE_NOT_CYCLE
 - DM75xx type Digital to Analog enumerations, [127](#)
- DM75xx type Digital to Analog enumerations, [127](#)
- DM75xx_DAC_RANGE_BIPOLAR_10
 - DM75xx type Digital to Analog enumerations, [127](#)
- DM75xx_DAC_RANGE_BIPOLAR_5
 - DM75xx type Digital to Analog enumerations, [127](#)
- DM75xx_DAC_RANGE_UNIPOLAR_10
 - DM75xx type Digital to Analog enumerations, [127](#)
- DM75xx_DAC_RANGE_UNIPOLAR_5
 - DM75xx type Digital to Analog enumerations, [127](#)
- DM75xx_DAC_UPDATE_CGT
 - DM75xx type Digital to Analog enumerations, [128](#)
- DM75xx_DAC_UPDATE_CLOCK
 - DM75xx type Digital to Analog enumerations, [128](#)
- DM75xx_DAC_UPDATE_EPCLK
 - DM75xx type Digital to Analog enumerations, [128](#)
- DM75xx_DAC_UPDATE_SBUS0
 - DM75xx type Digital to Analog enumerations, [128](#)
- DM75xx_DAC_UPDATE_SBUS1
 - DM75xx type Digital to Analog enumerations, [128](#)
- DM75xx_DAC_UPDATE_SBUS2
 - DM75xx type Digital to Analog enumerations, [128](#)
- DM75xx_DAC_UPDATE_SOFTWARE
 - DM75xx type Digital to Analog enumerations, [128](#)
- DM75xx_DIO_CLK_8MHZ
 - DM75xx type Digital Input/Output, [119](#)
- DM75xx_DIO_CLK_UTC1
 - DM75xx type Digital Input/Output, [119](#)
- DM75xx_DIO_MODE_EVENT
 - DM75xx type Digital Input/Output, [119](#)
- DM75xx_DIO_MODE_MATCH
 - DM75xx type Digital Input/Output, [119](#)
- DM75xx_DIO_PORT0
 - DM75xx type Digital Input/Output, [120](#)
- DM75xx_DIO_PORT1
 - DM75xx type Digital Input/Output, [120](#)
- DM75xx_DMA_CHANNEL_0
 - DM75xx type DMA, [112](#)
- DM75xx_DMA_CHANNEL_1
 - DM75xx type DMA, [112](#)
- DM75xx_DMA_DEMAND_DISABLE
 - DM75xx type DMA, [113](#)
- DM75xx_DMA_DEMAND_FIFO_ADC
 - DM75xx type DMA, [113](#)
- DM75xx_DMA_DEMAND_FIFO_DAC1
 - DM75xx type DMA, [113](#)
- DM75xx_DMA_DEMAND_FIFO_DAC2
 - DM75xx type DMA, [113](#)
- DM75xx_DMA_DEMAND_SCNT_ADC
 - DM75xx type DMA, [113](#)
- DM75xx_DMA_DEMAND_SCNT_DAC1
 - DM75xx type DMA, [113](#)
- DM75xx_DMA_DEMAND_SCNT_DAC2
 - DM75xx type DMA, [113](#)
- DM75xx_DMA_DEMAND_UTC1
 - DM75xx type DMA, [113](#)
- DM75xx_DMA_FIFO_ADC
 - DM75xx type DMA, [113](#)
- DM75xx_DMA_FIFO_DAC1
 - DM75xx type DMA, [113](#)

- DM75xx type DMA, [113](#)
- DM75xx_DMA_FIFO_DAC2
 - DM75xx type DMA, [113](#)
- DM75xx_DMA_FIFO_HSDIN
 - DM75xx type DMA, [113](#)
- DM75xx_DMA_FLAG_ARB
 - DM75xx type DMA, [113](#)
- DM75xx_DMA_FLAG_INIT
 - DM75xx type DMA, [113](#)
- DM75xx_DMA_FLAG_MMAP
 - DM75xx type DMA, [113](#)
- DM75xx_DMA_FLAG_NONDEMAND
 - DM75xx type DMA, [113](#)
- DM75xx_DMA_FLAG_RESET
 - DM75xx type DMA, [113](#)
- DM75xx_DMA_FLAG_STATUS
 - DM75xx type DMA, [113](#)
- DM75xx_DMA_FUNCTION_ABORT
 - DM75xx ioctl enumerations, [29](#)
- DM75xx_DMA_FUNCTION_INITIALIZE
 - DM75xx ioctl enumerations, [29](#)
- DM75xx_DMA_RESET_SEL
 - DM75xx type DMA, [113](#)
- DM75xx_DMA_RESET_VAL
 - DM75xx type DMA, [113](#)
- DM75xx_DSP_ATTENTION
 - DM75xx type DSP enumerations, [111](#)
- DM75xx_DSP_BOOT_VERSION
 - DM75xx type DSP enumerations, [111](#)
- DM75xx_DSP_CAL_AUTO
 - DM75xx type DSP enumerations, [111](#)
- DM75xx_DSP_CAL_DEFAULT
 - DM75xx type DSP enumerations, [111](#)
- DM75xx_DSP_CAL_VERSION
 - DM75xx type DSP enumerations, [111](#)
- DM75xx_DSP_EXT_FLASH_ERASE
 - DM75xx type DSP enumerations, [111](#)
- DM75xx_DSP_FLASH_DOWNLOAD
 - DM75xx type DSP enumerations, [111](#)
- DM75xx_DSP_INT_FLASH_ERASE
 - DM75xx type DSP enumerations, [111](#)
- DM75xx_DSP_USER_RUN
 - DM75xx type DSP enumerations, [111](#)
- DM75xx_DSP_USER_UPGRADE
 - DM75xx type DSP enumerations, [111](#)
- DM75xx_EXT_POLARITY_NEG
 - DM75xx type External Trigger/Interrupt, [121](#)
- DM75xx_EXT_POLARITY_POS
 - DM75xx type External Trigger/Interrupt, [121](#)
- DM75xx_FIFO_ADC_HALF_EMPTY
 - DM75xx type definition structures, [138](#)
- DM75xx_FIFO_ADC_NOT_EMPTY
 - DM75xx type definition structures, [138](#)
- DM75xx_FIFO_ADC_NOT_FULL
 - DM75xx type definition structures, [138](#)
- DM75xx_FIFO_DAC1_HALF_EMPTY
 - DM75xx type definition structures, [137](#)
- DM75xx_FIFO_DAC1_NOT_EMPTY
 - DM75xx type definition structures, [137](#)
- DM75xx_FIFO_DAC2_HALF_EMPTY
 - DM75xx type definition structures, [137](#)
- DM75xx_FIFO_DAC2_NOT_EMPTY
 - DM75xx type definition structures, [137](#)
- DM75xx_FIFO_DAC2_NOT_FULL
 - DM75xx type definition structures, [138](#)
- DM75xx_FIFO_HSDIN_HALF_EMPTY
 - DM75xx type definition structures, [138](#)
- DM75xx_FIFO_HSDIN_NOT_EMPTY
 - DM75xx type definition structures, [138](#)
- DM75xx_FIFO_HSDIN_NOT_FULL
 - DM75xx type definition structures, [138](#)
- DM75xx_GUTC_EXT_TC_CLK_1
 - DM75xx type timer/counter enumerations, [136](#)
- DM75xx_GUTC_EXT_TC_CLK_2
 - DM75xx type timer/counter enumerations, [136](#)
- DM75xx_GUTC_GATED
 - DM75xx type timer/counter enumerations, [136](#)
- DM75xx_GUTC_NOT_GATED
 - DM75xx type timer/counter enumerations, [136](#)
- DM75xx_GUTC_UTC_0_OUT
 - DM75xx type timer/counter enumerations, [136](#)
- DM75xx_GUTC_UTC_1_OUT
 - DM75xx type timer/counter enumerations, [136](#)
- DM75xx_HSDIN_SIGNAL_ADC
 - DM75xx type HighSpeed Digital enumerations, [124](#)
- DM75xx_HSDIN_SIGNAL_EPCLK
 - DM75xx type HighSpeed Digital enumerations, [124](#)
- DM75xx_HSDIN_SIGNAL_ETRIG
 - DM75xx type HighSpeed Digital enumerations, [124](#)
- DM75xx_HSDIN_SIGNAL_SOFTWARE
 - DM75xx type HighSpeed Digital enumerations, [124](#)
- DM75xx_HSDIN_SIGNAL_UTC0
 - DM75xx type HighSpeed Digital enumerations, [124](#)
- DM75xx_HSDIN_SIGNAL_UTC1
 - DM75xx type HighSpeed Digital enumerations, [124](#)
- DM75xx_HSDIN_SIGNAL_UTC2
 - DM75xx type HighSpeed Digital enumerations, [124](#)
- DM75xx_INT_ABOUT
 - DM75xx type Interrupt, [114](#)
- DM75xx_INT_ALGDIO_NEG_PIN1
 - DM75xx type Interrupt, [115](#)
- DM75xx_INT_ALGDIO_NEG_PIN2
 - DM75xx type Interrupt, [115](#)
- DM75xx_INT_ALGDIO_POS_PIN1
 - DM75xx type Interrupt, [115](#)
- DM75xx_INT_ALGDIO_POS_PIN2
 - DM75xx type Interrupt, [115](#)
- DM75xx_INT_CGT_PAUSE
 - DM75xx type Interrupt, [114](#)
- DM75xx_INT_CGT_RESET
 - DM75xx type Interrupt, [114](#)
- DM75xx_INT_CONTROL_CHECK
 - DM75xx ioctl enumerations, [29](#)
- DM75xx_INT_CONTROL_DISABLE

- DM75xx ioctl enumerations, [29](#)
- DM75xx_INT_CONTROL_ENABLE
 - DM75xx ioctl enumerations, [29](#)
- DM75xx_INT_DELAY
 - DM75xx type Interrupt, [114](#)
- DM75xx_INT_DIO
 - DM75xx type Interrupt, [114](#)
- DM75xx_INT_DMA_0
 - DM75xx type Interrupt, [115](#)
- DM75xx_INT_DMA_1
 - DM75xx type Interrupt, [115](#)
- DM75xx_INT_ETRIG_FALLING
 - DM75xx type Interrupt, [114](#)
- DM75xx_INT_ETRIG_RISING
 - DM75xx type Interrupt, [114](#)
- DM75xx_INT_EXTERNAL
 - DM75xx type Interrupt, [114](#)
- DM75xx_INT_FIFO_WRITE
 - DM75xx type Interrupt, [114](#)
- DM75xx_INT_RESERVED
 - DM75xx type Interrupt, [114](#)
- DM75xx_INT_SCNT_ADC
 - DM75xx type Interrupt, [114](#)
- DM75xx_INT_SCNT_DAC1
 - DM75xx type Interrupt, [114](#)
- DM75xx_INT_SCNT_DAC2
 - DM75xx type Interrupt, [114](#)
- DM75xx_INT_UTC1
 - DM75xx type Interrupt, [114](#)
- DM75xx_INT_UTC1_INV
 - DM75xx type Interrupt, [114](#)
- DM75xx_INT_UTC2
 - DM75xx type Interrupt, [114](#)
- DM75xx_LAS0
 - DM75xx type PCI enumerations, [110](#)
- DM75xx_LAS1
 - DM75xx type PCI enumerations, [110](#)
- DM75xx_PCI_REGION_ACCESS_16
 - DM75xx type PCI enumerations, [109](#)
- DM75xx_PCI_REGION_ACCESS_32
 - DM75xx type PCI enumerations, [109](#)
- DM75xx_PCI_REGION_ACCESS_8
 - DM75xx type PCI enumerations, [109](#)
- DM75xx_PCI_REGION_ACCESS_READ
 - DM75xx driver enumerations, [8](#)
- DM75xx_PCI_REGION_ACCESS_WRITE
 - DM75xx driver enumerations, [8](#)
- DM75xx_PCLK_EXTERNAL
 - DM75xx type Pacer Clock enumerations, [133](#)
- DM75xx_PCLK_FREQ_20_MHZ
 - DM75xx type Pacer Clock enumerations, [133](#)
- DM75xx_PCLK_FREQ_8_MHZ
 - DM75xx type Pacer Clock enumerations, [133](#)
- DM75xx_PCLK_INTERNAL
 - DM75xx type Pacer Clock enumerations, [133](#)
- DM75xx_PCLK_NO_REPEAT
 - DM75xx type Pacer Clock enumerations, [133](#)
- DM75xx_PCLK_REPEAT
 - DM75xx type Pacer Clock enumerations, [133](#)
- DM75xx_PCLK_START_DDIGITAL_IT
 - DM75xx type Pacer Clock enumerations, [133](#)
- DM75xx_PCLK_START_DETRIG
 - DM75xx type Pacer Clock enumerations, [133](#)
- DM75xx_PCLK_START_DIGITAL_IT
 - DM75xx type Pacer Clock enumerations, [133](#)
- DM75xx_PCLK_START_DSBUS0
 - DM75xx type Pacer Clock enumerations, [133](#)
- DM75xx_PCLK_START_DSBUS1
 - DM75xx type Pacer Clock enumerations, [133](#)
- DM75xx_PCLK_START_DSBUS2
 - DM75xx type Pacer Clock enumerations, [133](#)
- DM75xx_PCLK_START_DSOFTWARE
 - DM75xx type Pacer Clock enumerations, [133](#)
- DM75xx_PCLK_START_DUTC2
 - DM75xx type Pacer Clock enumerations, [133](#)
- DM75xx_PCLK_START_ETRIG
 - DM75xx type Pacer Clock enumerations, [133](#)
- DM75xx_PCLK_START_ETRIG_GATE
 - DM75xx type Pacer Clock enumerations, [133](#)
- DM75xx_PCLK_START_RES
 - DM75xx type Pacer Clock enumerations, [133](#)
- DM75xx_PCLK_START_SBUS0
 - DM75xx type Pacer Clock enumerations, [133](#)
- DM75xx_PCLK_START_SBUS1
 - DM75xx type Pacer Clock enumerations, [133](#)
- DM75xx_PCLK_START_SBUS2
 - DM75xx type Pacer Clock enumerations, [133](#)
- DM75xx_PCLK_START_SOFTWARE
 - DM75xx type Pacer Clock enumerations, [133](#)
- DM75xx_PCLK_START_UTC2
 - DM75xx type Pacer Clock enumerations, [133](#)
- DM75xx_PCLK_STOP_ACNT
 - DM75xx type Pacer Clock enumerations, [134](#)
- DM75xx_PCLK_STOP_ADIGITAL_IT
 - DM75xx type Pacer Clock enumerations, [134](#)
- DM75xx_PCLK_STOP_AETRIG
 - DM75xx type Pacer Clock enumerations, [134](#)
- DM75xx_PCLK_STOP_ASBUS0
 - DM75xx type Pacer Clock enumerations, [134](#)
- DM75xx_PCLK_STOP_ASBUS1
 - DM75xx type Pacer Clock enumerations, [134](#)
- DM75xx_PCLK_STOP_ASBUS2
 - DM75xx type Pacer Clock enumerations, [134](#)
- DM75xx_PCLK_STOP_ASOFTWARE
 - DM75xx type Pacer Clock enumerations, [134](#)
- DM75xx_PCLK_STOP_AUTC2
 - DM75xx type Pacer Clock enumerations, [134](#)
- DM75xx_PCLK_STOP_DIGITAL_IT
 - DM75xx type Pacer Clock enumerations, [134](#)
- DM75xx_PCLK_STOP_ETRIG
 - DM75xx type Pacer Clock enumerations, [134](#)
- DM75xx_PCLK_STOP_RES
 - DM75xx type Pacer Clock enumerations, [134](#)
- DM75xx_PCLK_STOP_SBUS0
 - DM75xx type Pacer Clock enumerations, [134](#)
- DM75xx_PCLK_STOP_SBUS1
 - DM75xx type Pacer Clock enumerations, [134](#)

- DM75xx type Pacer Clock enumerations, [134](#)
- DM75xx_PCLK_STOP_SBUS2
 - DM75xx type Pacer Clock enumerations, [134](#)
- DM75xx_PCLK_STOP_SOFTWARE
 - DM75xx type Pacer Clock enumerations, [134](#)
- DM75xx_PCLK_STOP_UTC2
 - DM75xx type Pacer Clock enumerations, [134](#)
- DM75xx_PLX_IO
 - DM75xx type PCI enumerations, [110](#)
- DM75xx_PLX_MEM
 - DM75xx type PCI enumerations, [110](#)
- DM75xx_SBUS0
 - DM75xx type SyncBus enumerations, [122](#)
- DM75xx_SBUS1
 - DM75xx type SyncBus enumerations, [122](#)
- DM75xx_SBUS2
 - DM75xx type SyncBus enumerations, [122](#)
- DM75xx_SBUS_SRC_BCLK
 - DM75xx type SyncBus enumerations, [122](#)
- DM75xx_SBUS_SRC_DAC1
 - DM75xx type SyncBus enumerations, [123](#)
- DM75xx_SBUS_SRC_DAC2
 - DM75xx type SyncBus enumerations, [123](#)
- DM75xx_SBUS_SRC_DAC_CLK
 - DM75xx type SyncBus enumerations, [123](#)
- DM75xx_SBUS_SRC_DAC_UPDATE
 - DM75xx type SyncBus enumerations, [123](#)
- DM75xx_SBUS_SRC_DIG_IT
 - DM75xx type SyncBus enumerations, [122](#)
- DM75xx_SBUS_SRC_EPCLK
 - DM75xx type SyncBus enumerations, [123](#)
- DM75xx_SBUS_SRC_ETRIG
 - DM75xx type SyncBus enumerations, [123](#)
- DM75xx_SBUS_SRC_ETRIG2
 - DM75xx type SyncBus enumerations, [123](#)
- DM75xx_SBUS_SRC_PCLK
 - DM75xx type SyncBus enumerations, [122](#)
- DM75xx_SBUS_SRC_PCLK_START
 - DM75xx type SyncBus enumerations, [122](#)
- DM75xx_SBUS_SRC_PCLK_STOP
 - DM75xx type SyncBus enumerations, [122](#)
- DM75xx_SBUS_SRC_SOFT_ADC
 - DM75xx type SyncBus enumerations, [122](#)
- DM75xx_SBUS_SRC_UTC2
 - DM75xx type SyncBus enumerations, [123](#)
- DM75xx_UIO0
 - DM75xx type User Output, [118](#)
- DM75xx_UIO1
 - DM75xx type User Output, [118](#)
- DM75xx_UIO_ADC
 - DM75xx type User Output, [118](#)
- DM75xx_UIO_DAC1
 - DM75xx type User Output, [118](#)
- DM75xx_UIO_DAC2
 - DM75xx type User Output, [118](#)
- DM75xx_UIO_PRG
 - DM75xx type User Output, [118](#)
- DM75xx_UTC_0
 - DM75xx type timer/counter enumerations, [136](#)
- DM75xx_UTC_1
 - DM75xx type timer/counter enumerations, [136](#)
- DM75xx_UTC_2
 - DM75xx type timer/counter enumerations, [136](#)
- DM75xx_UTC_MODE_EVENT_COUNTER
 - DM75xx type timer/counter enumerations, [136](#)
- DM75xx_UTC_MODE_HARDWARE_STROBE
 - DM75xx type timer/counter enumerations, [136](#)
- DM75xx_UTC_MODE_PROG_ONE_SHOT
 - DM75xx type timer/counter enumerations, [136](#)
- DM75xx_UTC_MODE_RATE_GENERATOR
 - DM75xx type timer/counter enumerations, [136](#)
- DM75xx_UTC_MODE_SOFTWARE_STROBE
 - DM75xx type timer/counter enumerations, [136](#)
- DM75xx_UTC_MODE_SQUARE_WAVE
 - DM75xx type timer/counter enumerations, [136](#)
- kernel compatibility interrupt handler macros, [34](#)