Weekly report

1 My *Objectives* this week: Optimal Solution for the algorithm for two robots positioning using friction

- Write down the code of optimal solution.

2 My *Accomplishments* this week

- If it is reachable in one move is written and it is debugged and errors has been corrected. It works.

- If it is reachable in 3 moves, the algorithm chooses the right move for the first two moves. I corrected the errors for this part as well.

- The rotations are NOT correct.

3 My *Plan* for next week

- make the rotations work correctly.

- complete the algorithm so that it also considers the not achievable sets.

3.1 Meeting with Dr. Becker

- Nothing to mention. I will give my progress report in my next meeting.