## Weekly report

# 1 My *Objectives* this week: Optimal Solution for the algorithm for two robots positioning using friction

- Complete debugging the optimal function A star algorithm.
- Draw the algorithm

### 2 My Accomplishments this week

- The function works.
- now draw the output(Github is updated).
- The main problem now is that sort does not sort correctly. Also, this function is too slow(as we expected) to run normally.

### 3 My Plan for next week

• Write down the algorithm and paper and complete the first draft for IROS 2017

#### 3.1 Meeting with Dr. Becker

• Get opinion about the paper.

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