a) 
$$y' - \frac{1}{\sqrt{1-x^2}} \cdot y = 4x^3 \cdot e^{-\alpha r c \sin x}$$

I det sel ec omagene

$$y' - \frac{1}{\sqrt{1-x^2}} \cdot y = 0 \iff y' = \frac{1}{\sqrt{1-x^2}} \implies \frac{dy}{y} = \frac{dx}{\sqrt{1-x^2}} \implies \frac{dx}{\sqrt{1-x^2}} \implies \frac{dy}{\sqrt{1-x^2}} \implies \frac{dx}{\sqrt{1-x^2}} \implies \frac{dx$$

$$y_p^2 = c'(x) e^{\operatorname{arcsim} x} + c(x) \cdot \frac{1}{\sqrt{1-x^2}} \cdot e^{\operatorname{arcsim} x}$$

imbouism sus => 
$$e'(x)e^{arcsimx} + c(x) \frac{1}{\sqrt{1-x^2}}e^{arcsimx}$$

$$e^{3}(x) = 4x^{3}/\int \Rightarrow c(x) = 4\frac{x^{4}}{4} \Rightarrow c(x) = x^{4}$$

=> 
$$y = y + y_p = ce^{arcsim x} + x^r e^{arcsim x}$$

I resployed et amagena 
$$y'' + 6y' + 9y = 0$$
 $x'' + 6x' + 9 = 0 \Rightarrow \Delta = 0 \Rightarrow x_{1,2} = 3$ 
 $y''_{1} = e^{-3x} y_{2} = x \cdot e^{-3x} \Rightarrow y_{2} = e_{1}e^{-3x} + cos_{2} \times e^{-3x}$ 
 $y''_{1} = e^{-3x} y_{2} = x \cdot e^{-3x} \Rightarrow y_{3} = e_{1}e^{-3x} + cos_{2} \times e^{-3x}$ 

in det o not particularia avem 
$$e^{-x}(x+1) = e^{+x}(ax+b)$$

$$y_p = e^{-x}(ax+b) \Rightarrow y_p' = -e^{-x}(ax+b) + e^{-x} \cdot a$$

$$y_p^2 = +e^{-x}(a-b-ax)$$
 $y_p^2 = -e^{-x}(a-b-ax) + e^{-x}(-a) = e^{-x}(-ax+b+ax-a) = e^{-x}(ax-2a+b)^2$ 

Imbaulum rus:

$$e^{-x}(ax-2a+b)+6\cdot e^{-x}(a-b-ax)+3e^{-x}(ax+b)=(x+1)e^{-x}$$
 $e^{-x}(ax-2a+b+6a-6b-6ax+3ax+9b)=e^{-x}(x+1)$ 

$$\int 4ax=x\Rightarrow 4a=1\Rightarrow a=\frac{1}{4}$$

$$\int 4ax+4b=1\Rightarrow 1+4b=1\Rightarrow b=0$$

=> 
$$y = y_0 + y_p = c_1 e^{3x} + c_2 \cdot x \cdot e^{-3x} + e^{-x} \cdot \frac{1}{4}x$$

$$\begin{cases} y'' + tg(x) \cdot y' = cos(x) & \text{mot } 2 = y' >> 2! + tg(x) \cdot 2 = cos(x) \\ y(0) = 1 & \text{y'}(0) = 0 \end{cases}$$

$$\frac{2'+2}{2'} + \frac{1}{2} +$$

$$2p = c(x) \cdot cos x$$

$$2p' = c'(x) \cdot cos x - c(x) \cdot sim x$$

$$2p' = c'(x) \cdot cos x - c(x) \cdot sim x$$

$$2p' = c'(x) = 1 \quad |S| \Rightarrow c(x) = x$$

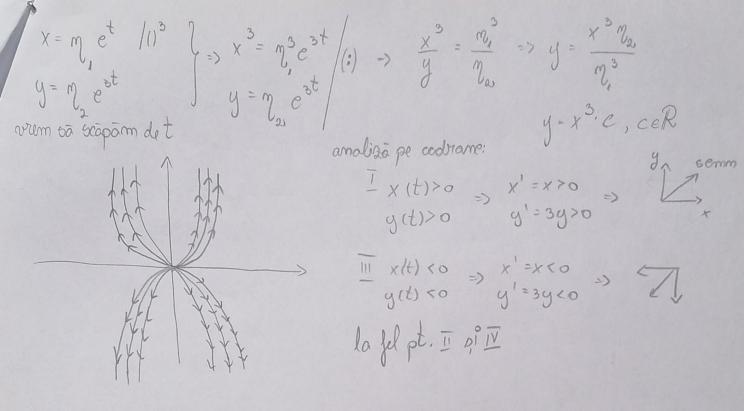
imbouin => 
$$2p = x \cos x \Rightarrow 2 = x \cos x + c \cos x$$
  
imbouin imapoi  $y \Rightarrow y' = x \cos x + c \cos x / \Rightarrow y = (\sin x + x \sin x + \cos x + c \cos x)$   
 $T_1 = \int x \cos x = x \cdot \sin x - \int \sin x = x \sin x + \cos x = c$ 

(0)=1=> C1+11=1=> C1=0 => y = x simx + cos x 1 (0)=0=) C·1=0 > C=0 5. Se considera problema Cauchy  $\int y' = x^2 - y^2$ . Scrieti ecuatia întegrala Voltais echinalenta cu problema Cauchy  $\int y(0) = 1$ echinalenta cu problema Cauchy  $\int y(0) = 1$ pt. Junctia de start y(x) = 1 calculati primele 2 aproximatii succesine. y=1+ \$(62-y(5)2) d5 ec. Volterora X0=0 y0=1  $y_{m+1} = y_0 + \int_{\infty} \int_{\infty} (5) d5$  $y_1 = y_0 + \int_0^x \int_0^$ y\_ = y\_ + \[ \( \) = 14 \$ 52-(1+52+ 56-25-25)= = 1+ \( \left( 8^2 - 1 - 8^2 - \frac{5^6}{9} + 25 + \frac{2}{3} 5^7 - \frac{2}{3} 5^3 \right) = = 1+ M - 5 +25+ 3 59 - 253) = 1+ X - 2 X + X +

b) Sã re det, portretul fasic q'étà se pracisese stabilitatea n'étipul panetului de ech (0,0).

a) 
$$\begin{cases} x' = x \\ y' = 3y \\ x(0) = m, \end{cases}$$
 $\begin{cases} y' = 3y \\ x(0) = m, \end{cases}$ 
 $\begin{cases} y' = 3y \\ y' = 3y \\ y' = dy \end{cases} \Rightarrow \begin{cases} \frac{dy}{3y} = dt/f \Rightarrow lm|y| = 3t + e \Rightarrow y = e_3 \cdot e^{3t} \end{cases}$ 

$$\begin{cases} x = e_1 e^t \\ y = e_2 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^t \\ y = e_3 e^{3t} \end{cases} \Rightarrow \begin{cases} x = e_1 e^{3t} \end{cases}$$



vedem cum e punctul (9,0)

$$A = \begin{pmatrix} 1 & 0 \\ 0 & 3 \end{pmatrix} det (\lambda I_2 - A) = 0 \Rightarrow \begin{vmatrix} \lambda - 1 & 0 \\ 0 & \lambda - 3 \end{vmatrix} = 0$$

$$(\lambda - 1) (\lambda - 3) = 0$$

$$\begin{cases} \lambda_1 = 1 \\ \lambda_2 = 0 \end{cases} \Rightarrow x^* (0,0) \text{ pot de ech.}$$
imstabil de tip mod

7. Sa re determine punctele de ech. q'é sa se studiere stabilitatea acestora:

$$\int x^{3}(t) = y^{3}+1$$

$$y^{3}(t) = x^{20}+y$$

$$\int y^{3}=1 \Rightarrow y^{2}=1 \quad | \Rightarrow x^{2}+1 \Rightarrow x^{2}(1,-1), x^{2}(-1,-1) \quad \text{pot de exhibition}$$

$$| x^{20}+y^{20}| = \begin{vmatrix} \frac{\partial y}{\partial x} & \frac{\partial y}{\partial y} \\ \frac{\partial y}{\partial x} & \frac{\partial y}{\partial y} \end{vmatrix} = \begin{vmatrix} 0 & 3y^{20} \\ 2x & \frac{\partial y}{\partial y} \end{vmatrix}$$

$$| x^{20}+y^{20}| = \begin{vmatrix} \frac{\partial y}{\partial x} & \frac{\partial y}{\partial y} \\ \frac{\partial y}{\partial x} & \frac{\partial y}{\partial y} \end{vmatrix}$$

$$| x^{20}+y^{20}| = \begin{vmatrix} 0 & 3y^{20} \\ 2x & \frac{\partial y}{\partial y} \end{vmatrix}$$

$$-\frac{1}{2}(1,-1)=\frac{1}{2}(+1,-1)=\begin{pmatrix}0&3\\2&1\end{pmatrix}$$

$$\frac{1}{2}(1,-1) = \int_{\mathcal{J}} (+1,-1) = \begin{pmatrix} 0 & 3 \\ 21 & 1 \end{pmatrix} det(2 - 2 - A) = 0$$

$$|2 - 3| = 0 \Rightarrow 2(2-1) - 6 = 0$$

$$|2 - 2 - 1| = 0 \Rightarrow \Delta = 25$$

=> 21=3 >0 pct imstabil, tip sa 2,=-2 <0

$$\frac{1}{2} (-1, -1)$$

$$\int_{a}^{b} (-1, -1) = \begin{pmatrix} 0 & 3 \\ -2 & 1 \end{pmatrix} det(\lambda I_{2} - A) = 0$$

$$|\lambda| = 0$$

$$\det (\lambda I_2 - A) = 0$$

$$\begin{vmatrix} \lambda & -3 \\ 2 & \lambda - 1 \end{vmatrix} = 0 \implies \lambda(\lambda - 1) + 6 = 0$$

$$\lambda_1 = \frac{1+i\sqrt{23}}{2}$$
 imstabil, tip focus 
$$\lambda_2 = \frac{1-i\sqrt{23}}{2}$$