# **Architecture Document**

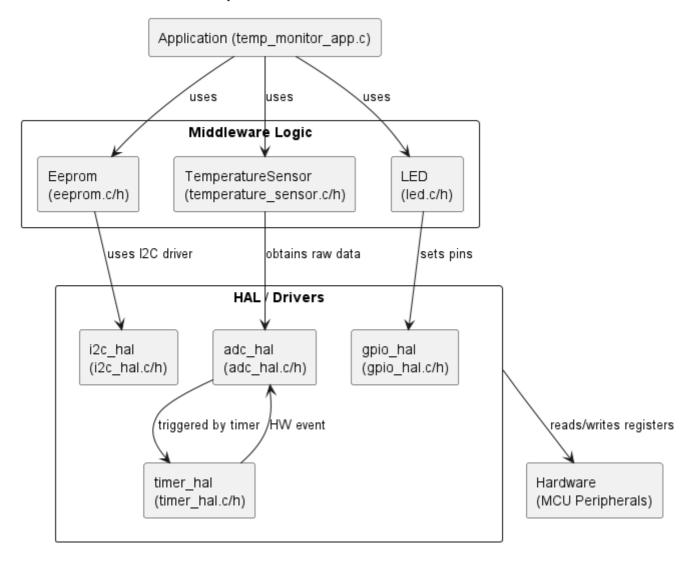
# 1. Introduction

This document describes the software architecture of the **TemperatureMonitor** project—a demonstration of a scalable embedded system for temperature monitoring. The design is organized in layers that separate low-level hardware access (I<sup>2</sup>C, GPIO, Timer, ADC) from higher-level domain logic (EEPROM, LED, Temperature Sensor) and the application layer. This architecture is designed to be maintainable, testable, and scalable.

# 2. Static Architecture

# 2.1 Overall Layered Structure

### TemperatureMonitor - Static Architecture



# 2.2 Module Responsibilities

### main

A minimal entry point that calls temp monitor app init() and temp monitor app run().

### temp\_monitor\_app

 Orchestrates system initialization (calls init functions for EEPROM, Temperature Sensor, LED, Timer, ADC, etc.) and manages the main application loop.

### eeprom

• Uses the **i2c\_hal** module to read and write configuration data (hardware revision and serial number) from an external EEPROM.

## temperature\_sensor

 Retrieves the most recent ADC reading (via adc\_hal\_get\_value()) and converts it to a temperature (°C) using scaling factors based on the hardware revision (Rev-A vs. Rev-B).

### led

- Determines which LED should be activated (green, yellow, or red) based on the current temperature and pre-defined thresholds.
- Uses **gpio\_hal** to actually set the pin states.

## • i2c\_hal

- Real Hardware: Initializes I<sup>2</sup>C registers, sets up pins, configures bus speed, and handles actual I<sup>2</sup>C transactions.
- Simulation: Prints debug messages and returns dummy data.

## gpio\_hal

- Real Hardware: Enables GPIO clocks, configures pin modes (e.g., output, push-pull), and writes directly to registers.
- Simulation: Simply prints the intended pin state changes.

### • timer

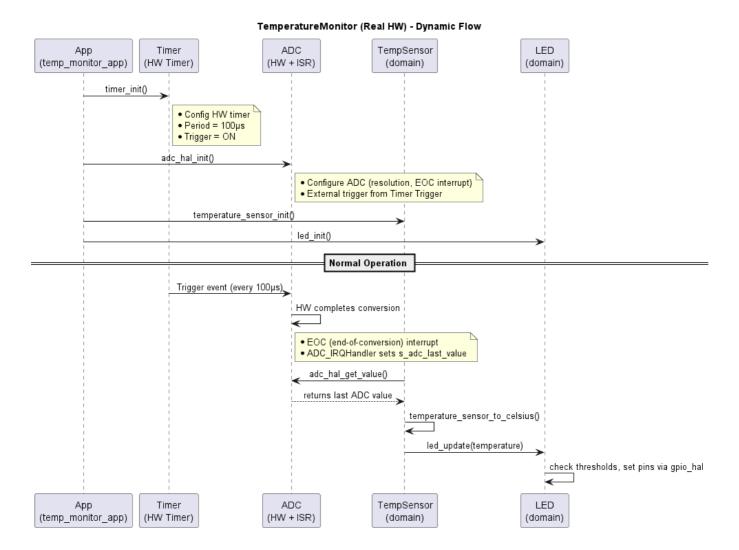
- Real Hardware: Configures a timer with prescaler values for a precise 100 μs period, and sets up a trigger output to start ADC conversions automatically.
- Simulation: Emulates a timer event by calling a function (e.g., timer\_emulate\_period\_event())
  that triggers the ADC conversion.

## adc\_hal

- Real Hardware: Configures the ADC (resolution, sampling time, external trigger via timer trigger)
  and uses an ADC conversion-complete interrupt (e.g., ADC\_IRQHandler) to update a global
  value.
- Simulation: Increments a mock ADC value and stores it in a global variable, mimicking an ISR behavior.

# 3. Dynamic Architecture

## 3.1 Sequence Diagram



### 3.2 Detailed Flow

### 1. Initialization:

The application layer (temp\_monitor\_app\_init()) initializes all modules. In real hardware, each module configures its peripheral only once.

# 2. ADC Triggering:

- $\circ$  In real hardware, a timer configured for 100  $\mu$ s automatically generates a trigger signal that triggers the ADC.
- In simulation mode, the timer module emulates this event by calling adc\_hal\_trigger\_conversion().

## 3. ADC Conversion and ISR:

- The ADC begins conversion upon receiving the trigger and, once complete, raises an interrupt.
- The official ISR (ADC\_IRQHandler) is called and updates a global variable (s\_adc\_last\_value).

### 4. Data Flow to Temperature Sensor:

The temperature sensor module retrieves the ADC value via <a href="adc\_hal\_get\_value">adc\_hal\_get\_value</a>(), converts it to Celsius (using hardware revision scaling), and passes this value to the LED module.

## 5. LED Update:

The LED module uses temperature thresholds (configured in cfg.h) to determine which LED to activate,

calling gpio\_write\_pin() from the GPIO HAL.

# 4. Real Hardware Considerations

### • EEPROM:

In a real system, the EEPROM module would use I<sup>2</sup>C communication (handled by the i2c\_hal module) to read/write non-volatile configuration data.

• Example: Using HAL\_I2C\_Mem\_Read() on an STM32.

### • GPIO:

The GPIO HAL would set up the GPIO ports and pins by enabling clocks and configuring pin modes.

### • ADC:

The ADC module would be configured for the required resolution and sampling time. It would be set to start conversion via an external trigger, and its end-of-conversion interrupt (ADC\_IRQHandler) would be used to update the latest reading.

### Timer:

The timer module configures a hardware timer to operate at a 100 µs interval, outputting a trigger signal for the ADC.

## 5. Conclusion

This architecture provides:

- A **static, layered structure** with well-defined modules (low-level drivers, middleware, and application layer).
- A **dynamic data flow** where the timer triggers the ADC, the ADC interrupt updates a global variable, the temperature sensor converts the value, and the LED module updates outputs accordingly.
- Clear separation of concerns that facilitates maintainability, testability, and scalability in a complex embedded system.

This document and accompanying diagrams illustrate both the **static architecture** (module structure and dependencies) and the **dynamic behavior** (runtime data flow), making it a comprehensive reference for understanding the TemperatureMonitor project's design.

End of Architecture Document