

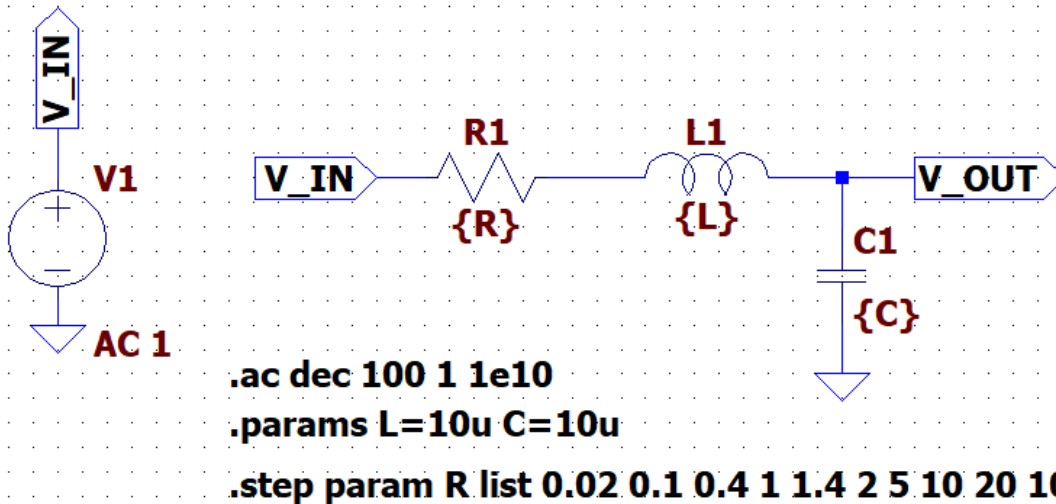
# Understanding 2nd order RLC Low-Pass Filter

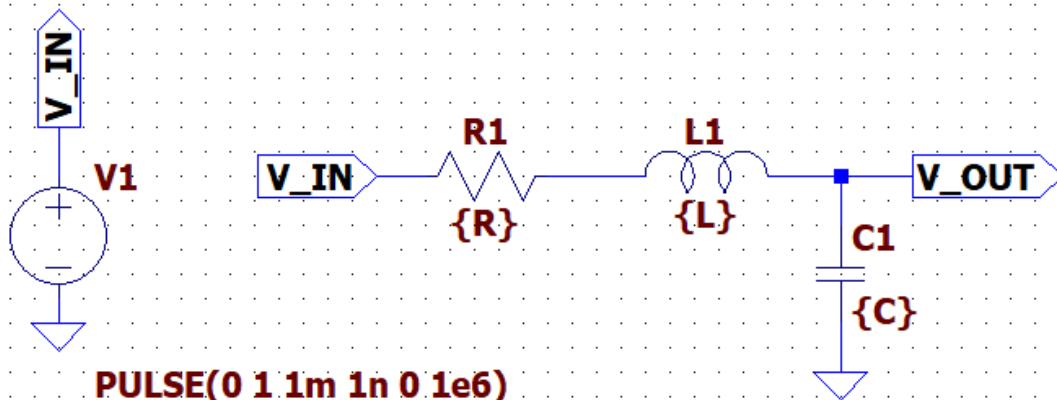
## and Two Stage Opamp

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### 2nd order RLC Low-Pass Filter:

- The following LTSpice schematics detail the circuit diagram for analyzing Transfer Function and Step Response of a standard RLC low-pass filter.





```
PULSE(0 1 1m 1n 0 1e6)
.params L=10u C=10u
.step param R list 0.02 0.1 0.4 1 1.4 2 5 10 20 100
.tran 0 10m 0
```

- We analyze the differences in the plots for different values of R.
- This code is used to tabulate the different parameter results as R varies.

```
def analyze_RLC(R, L, C):
    '''Find damping factor, quality factor, natural frequency and
    poles for given RLC system'''
    from cmath import sqrt
    z = 0.5 * R * sqrt(C / L)
    Q = 1 / (2 * z)
    w = 1 / sqrt(L * C)
    p1 = w * (-z + sqrt(z**2 - 1))
    p2 = w * (-z - sqrt(z**2 - 1))
    return z, Q, w, p1, p2
```

```

from tabulate import tabulate
L = 10 * 10**(-6)
C = 10 * 10**(-6)
R_list = [0.02, 0.1, 0.4, 1, 1.4, 2, 5, 10, 20, 100]
results = []
for R in R_list:
    z, Q, w, p1, p2 = analyze_RLC(R, L, C)
    results.append([R, z, Q, w, p1, p2, p1.imag, p2.imag])
print(tabulate(results, headers = ["R", "z", "Q", "w", "p1", "p2", "wp1",
"wp2"]))

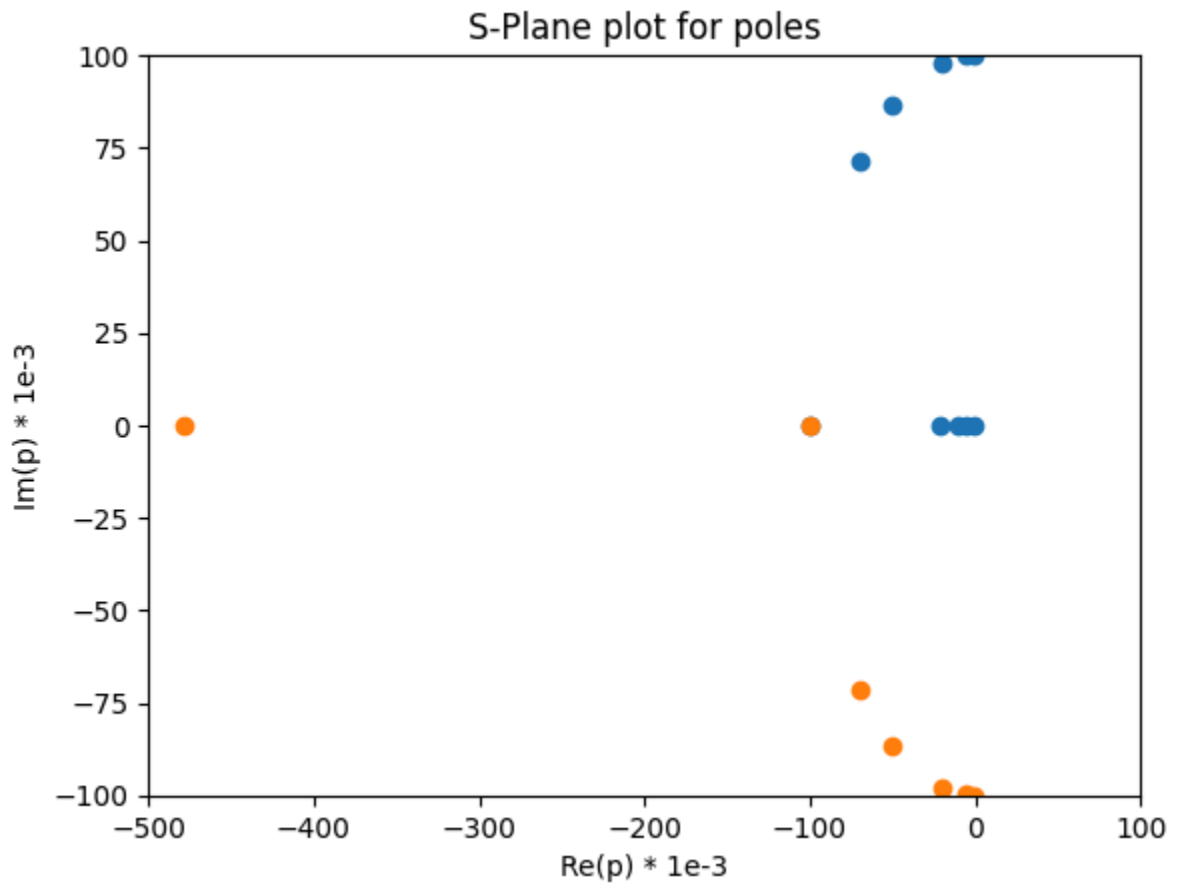
```

- The results are as follows:

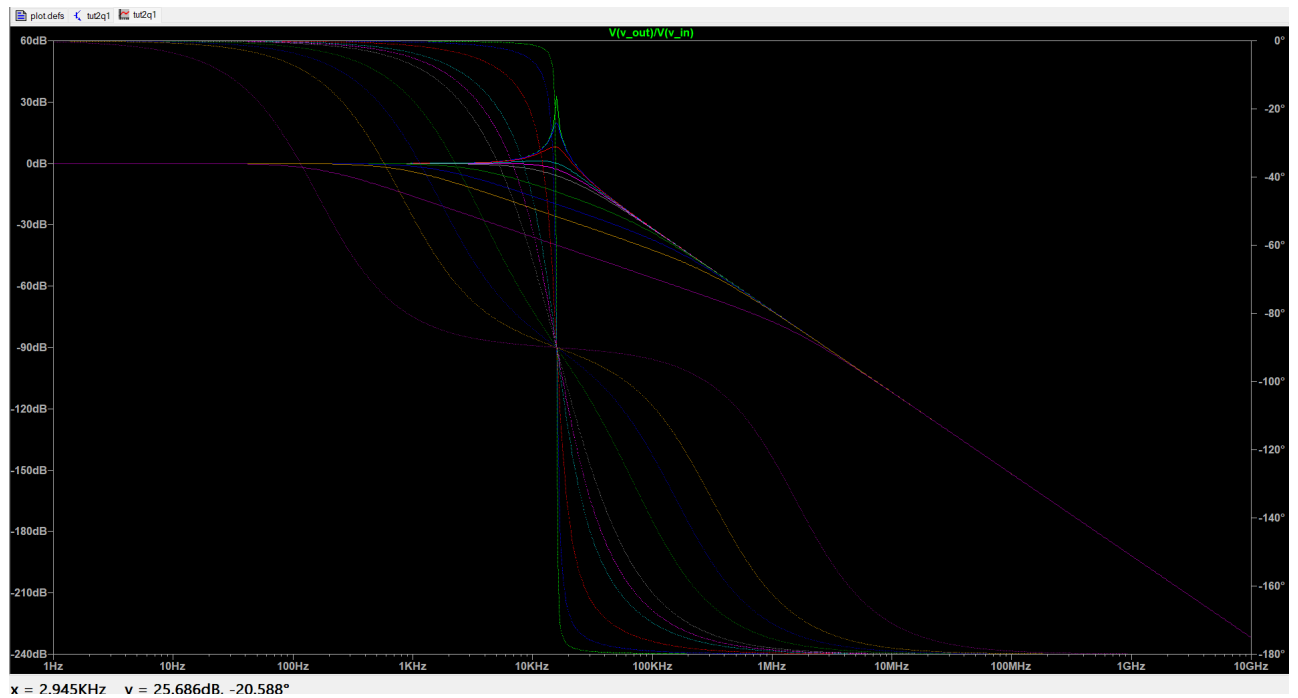
R	z	Q	w	p1	p2	wp1	wp2
0.02	(0.01+0j)	(50+0j)	(100000.000000000001+0j)	(-1000.0000000000001+99994.99987499377j)	(-1000.0000000000001-99994.99987499377j)	99995	-99995
0.1	(0.05+0j)	(10+0j)	(100000.000000000001+0j)	(-5000.000000000001+99874.9217771909j)	(-5000.000000000001-99874.9217771909j)	99874.9	-99874.9
0.4	(0.2+0j)	(2.5+0j)	(100000.000000000001+0j)	(-20000.000000000004+97979.58971132713j)	(-20000.000000000004-97979.58971132713j)	97979.6	-97979.6
1	(0.5+0j)	(1+0j)	(100000.000000000001+0j)	(-50000.000000000001+86602.54037844387j)	(-50000.000000000001-86602.54037844387j)	86602.5	-86602.5
1.4	(0.7+0j)	(0.7142857142857143+0j)	(100000.000000000001+0j)	(-70000+71414.28428542851j)	(-70000-71414.28428542851j)	71414.3	-71414.3
2	(1+0j)	(0.5+0j)	(100000.000000000001+0j)	(-100000.000000000001+0j)	(-100000.000000000001-0j)	0	-0
5	(2.5+0j)	(0.2+0j)	(100000.000000000001+0j)	(-20871.21525220801+0j)	(-479128.784747792-0j)	0	-0
10	(5+0j)	(0.1+0j)	(100000.000000000001+0j)	(-10102.051443364426+0j)	(-989897.9485566358-0j)	0	-0
20	(10+0j)	(0.05+0j)	(100000.000000000001+0j)	(-5012.562893380058+0j)	(-1994987.4371066205-0j)	0	-0
100	(50+0j)	(0.01+0j)	(100000.000000000001+0j)	(-1000.1000200048794+0j)	(-9998999.899979997-0j)	0	-0

- As R increases damping increases.
- As damping increases poles go further apart.
- For damping factor < 1, complex conjugate poles exist. Causes ringing.
- System is unconditionally stable- real part of pole is always in left-half plane (<=0).

- The behaviour of poles as damping factor varies can be realised from the locus plot :

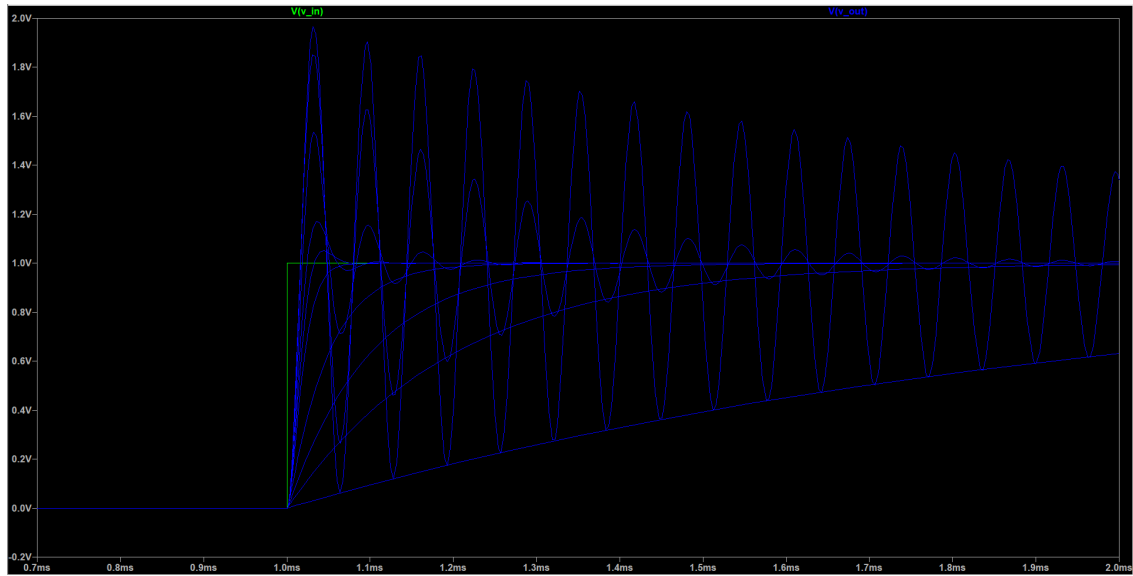


- Variation of AC magnitude and Phase response with damping.



- As damping factor increases the peak is reduced and leads to gradual roll-off. Phase are more abrupt for smaller damping factors.

- The step response for varies damping factor values look as follows:

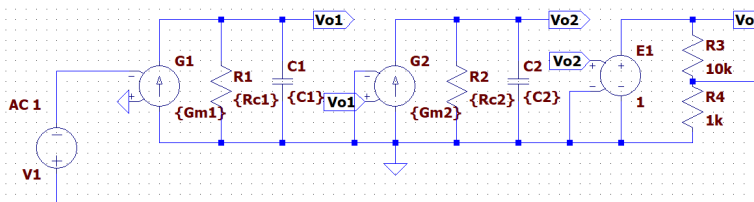


- (For some reason, my LTSpice software doesn't seem to differentiate these with different colours or provide a legend)
- As damping increases, there is less ringing.
- At critical damping (damping factor = 1), the settling time is the fastest.

## 2-stage Opamp

- The LTSpice schematics for loop gain, closed loop gain and step response analysis are detailed below:

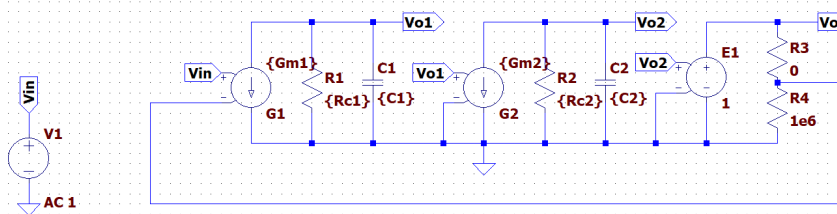
### Loop Gain Analysis of 2-Stage Opamp



```
.tran 0 1000n 0
.params Gm1=0.1m Gm2=0.1m Rc1=1e6 Rc2=1e6
.ac dec 100 1 1e9
.step param idx list 0 1 2 3 4 5 6 7 8 9
.param C1 table(idx, 0, 1e-09, 1, 1e-08, 2, 4e-08, 3, 1e-07, 4, 1.4144271570014145e-07, 5, 2e-07, 6, 5e-07, 7, 1e-06, 8, 2e-06, 9, 1e-05)
.param C2 table(idx, 0, 1e-09, 1, 1e-10, 2, 2.5e-11, 3, 1e-11, 4, 7.092198581560284e-12, 5, 5e-12, 6, 2e-12, 7, 1e-12, 8, 5e-13, 9, 1e-13)
```

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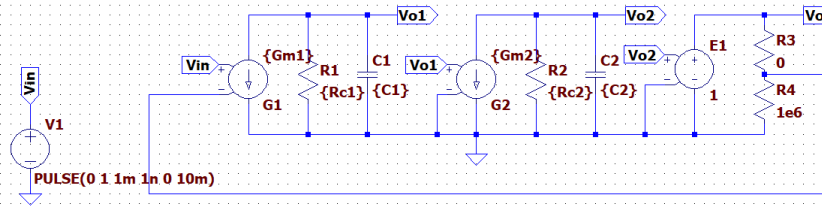
### CLG anlysis of 2-Stage Opamp



```
.tran 0 1000n 0
.params Gm1=0.1m Gm2=0.1m Rc1=1e6 Rc2=1e6
.ac dec 100 1 1G
.step param idx list 0 1 2 3 4 5 6 7 8 9
.param C1 table(idx, 0, 1e-09, 1, 1e-08, 2, 4e-08, 3, 1e-07, 4, 1.4144271570014145e-07, 5, 2e-07, 6, 5e-07, 7, 1e-06, 8, 2e-06, 9, 1e-05)
.param C2 table(idx, 0, 1e-09, 1, 1e-10, 2, 2.5e-11, 3, 1e-11, 4, 7.092198581560284e-12, 5, 5e-12, 6, 2e-12, 7, 1e-12, 8, 5e-13, 9, 1e-13)
```

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### Step Response of 2 Stage Opamp



```
.tran 0 10m 0
.params Gm1=0.1m Gm2=0.1m Rc1=1e6 Rc2=1e6
.step param idx list 0 1 2 3 4 5 6 7 8 9
.param C1 table(idx, 0, 1e-09, 1, 1e-08, 2, 4e-08, 3, 1e-07, 4, 1.4144271570014145e-07, 5, 2e-07, 6, 5e-07, 7, 1e-06, 8, 2e-06, 9, 1e-05)
.param C2 table(idx, 0, 1e-09, 1, 1e-10, 2, 2.5e-11, 3, 1e-11, 4, 7.092198581560284e-12, 5, 5e-12, 6, 2e-12, 7, 1e-12, 8, 5e-13, 9, 1e-13)
```

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- The following code is used to simulate values of various parameters of the opamp as poles of the gain vary.

```
import cmath

def analyze_opamp(wp1, wp2, A):
    '''Find loop gain and closed loop parameters of opamp'''
    w = cmath.sqrt(A * wp1 * wp2)
    z = (wp1 + wp2) / (2 * cmath.sqrt(A * wp1 * wp2))
    Q = 1 / (2 * z)
    p1 = w * (-z + cmath.sqrt(z**2 - 1))
    p2 = w * (-z - cmath.sqrt(z**2 - 1))
    wp1cl = p1.imag
    wp2cl = p2.imag
    wugf = (0.5 * (-(wp1**2 + wp2**2) + cmath.sqrt((wp1**2 - wp2**2)**2 + 4
    * A**2 * wp1**2 * wp2**2)))**0.5
    pm = (cmath.atan(-wugf * (wp1 + wp2) / ((wp1*wp2) - (wugf**2))) * 180
    / cmath.pi)

    return [wp1, wp2, wugf, pm, z, Q, wp1cl, wp2cl, p1, p2]
```



```

from tabulate import tabulate

wp1_list = [1e3, 1e2, 2.5e1, 1e1, 7.07e0, 5e0, 2e0, 1e0, 5e-1, 1e-1]
wp2_list = [1e3, 1e4, 4e4, 1e5, 1.41e5, 2e5, 5e5, 1e6, 2e6, 1e7]
A = 1e4
results = []

for i in range(len(wp1_list)):
    wp1 = wp1_list[i]
    wp2 = wp2_list[i]
    results.append(analyze_opamp(wp1, wp2, A))
print(tabulate(results, headers = ["wp1", "wp2", "wugf", "PM", "z", "Q",
"wp1cl", "wp2cl", "p1cl", "p2cl"]))

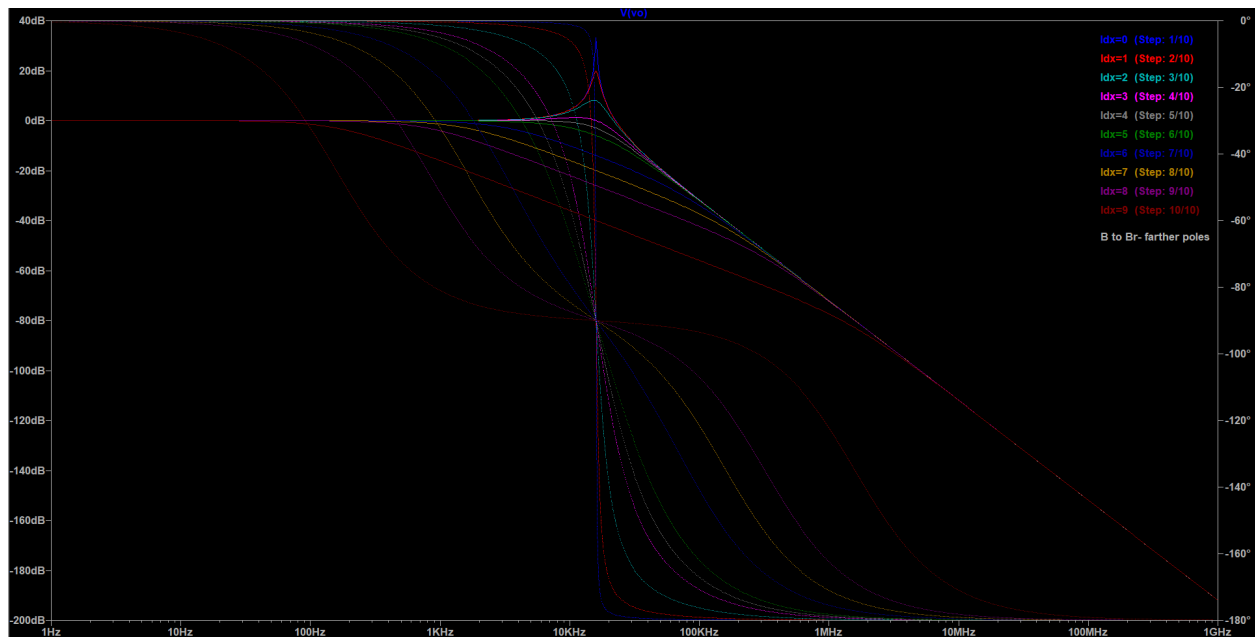
```

- The results are as follows:

wp1	wp2	wugf	PM	z	Q	wp1cl	wp2cl	p1cl	p2cl
1000	1000	(99994.99987499375+0j)	(1.1459346897143052+0j)	(0.01+0j)	(50+0j)	99995	-99995	(-1000+99994.99987499375j)	(-1000-99994.99987499375j)
100	10000	(99750.2880909139+0j)	(5.7822332209242+0j)	(0.0505+0j)	(9.900990099009901+0j)	99872.4	-99872.4	(-5050+99872.40609898212j)	(-5050-99872.40609898212j)
25	40000	(96083.02985318055+0j)	(22.617192368618888+0j)	(0.200125+0j)	(2.4984384759525295+0j)	97977	-97977	(-20012.5+97977.03732890681j)	(-20012.5-97977.03732890681j)
10	100000	(78615.1373159213+0j)	(51.834580671696266+0j)	(0.50005+0j)	(0.9999000099990001+0j)	86599.7	-86599.7	(-50005+86599.65343464141j)	(-50005-86599.65343464141j)
7.07	141000	(64322.96951678045+0j)	(65.48423984049965+0j)	(0.7061413272826799+0j)	(0.708073550828933+0j)	70696.2	-70696.2	(-70503.535+70696.1919236374j)	(-70503.535-70696.1919236374j)
5	200000	(48586.826931973636+0j)	(76.351311545624+0j)	(1.000025+0j)	(0.49998750031249223+0j)	0	-0	(-99295.38879941033+0j)	(-100709.61120058966-0j)
2	500000	(19984.04453184818+0j)	(87.71694955343823+0j)	(2.50001+0j)	(0.19999920000319998+0j)	0	-0	(-20871.124163172495+0j)	(-479130.87583682756-0j)
1	1e+06	(9999.500037483564+0j)	(89.43281980959843+0j)	(5.000005+0j)	(0.0999999000001+0j)	0	-0	(-10102.04113301194+0j)	(-989898.958866881-0j)
0.5	2e+06	(4999.984350170821+0j)	(89.86249089382912+0j)	(10.0000025+0j)	(0.0499998750000312+0j)	0	-0	(-5012.561633926538+0j)	(-1994987.9383660736-0j)
0.1	1e+07	(999.9999882812493+0j)	(-89.9999999986571+0j)	(50.0000005+0j)	(0.009999999+0j)	0	-0	(-1000.1000100018587+0j)	(-9998999.99998998-0j)

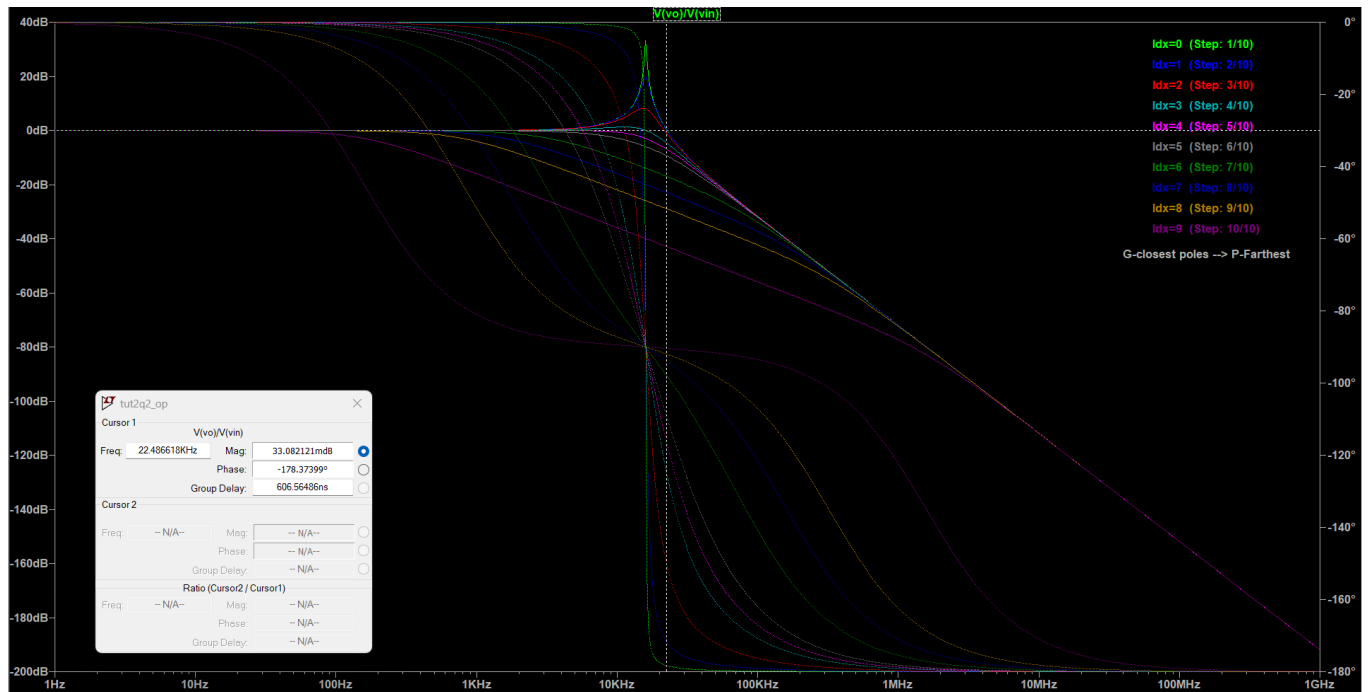
- The characteristics are similar to the previous RLC circuit.
- As poles go further apart, damping factor increases.
- For damping factor < 1, complex conjugate poles exist. Causes ringing.
- System is unconditionally stable- real part of pole is always in left-half plane (<=0).

- Loop gain is analyzed for different damping factors. The following is the AC magnitude and phase plot.



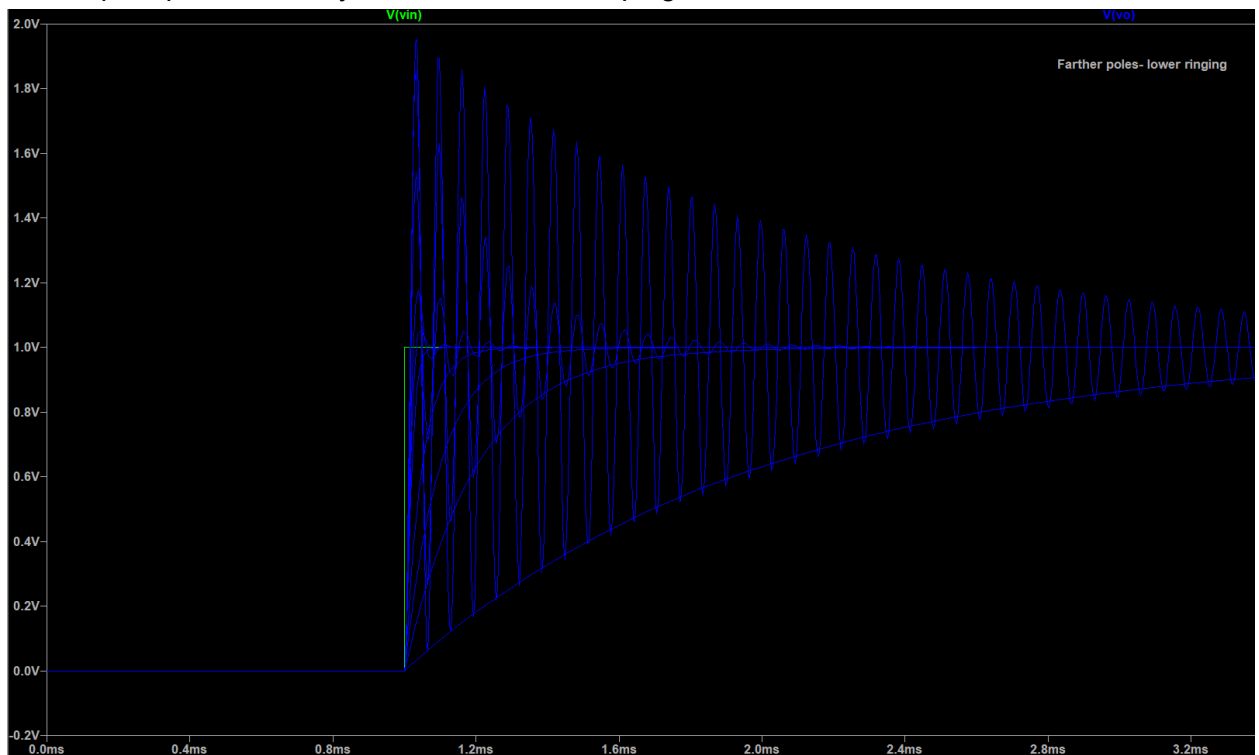
- As poles go farther, the peak is decreased and leads to gradual roll-off. Phase margin increases.

- The closed loop gain is analyzed for different damping factors.

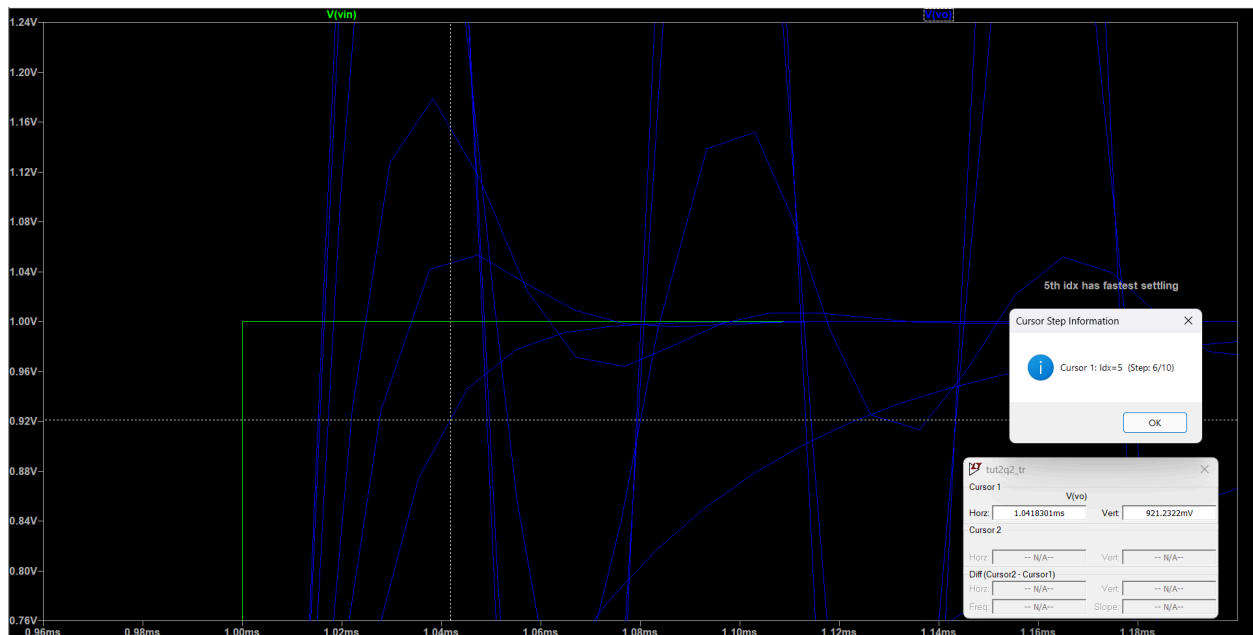


- As poles go farther, peak in magnitude plot decreases. Phase changes gradually.

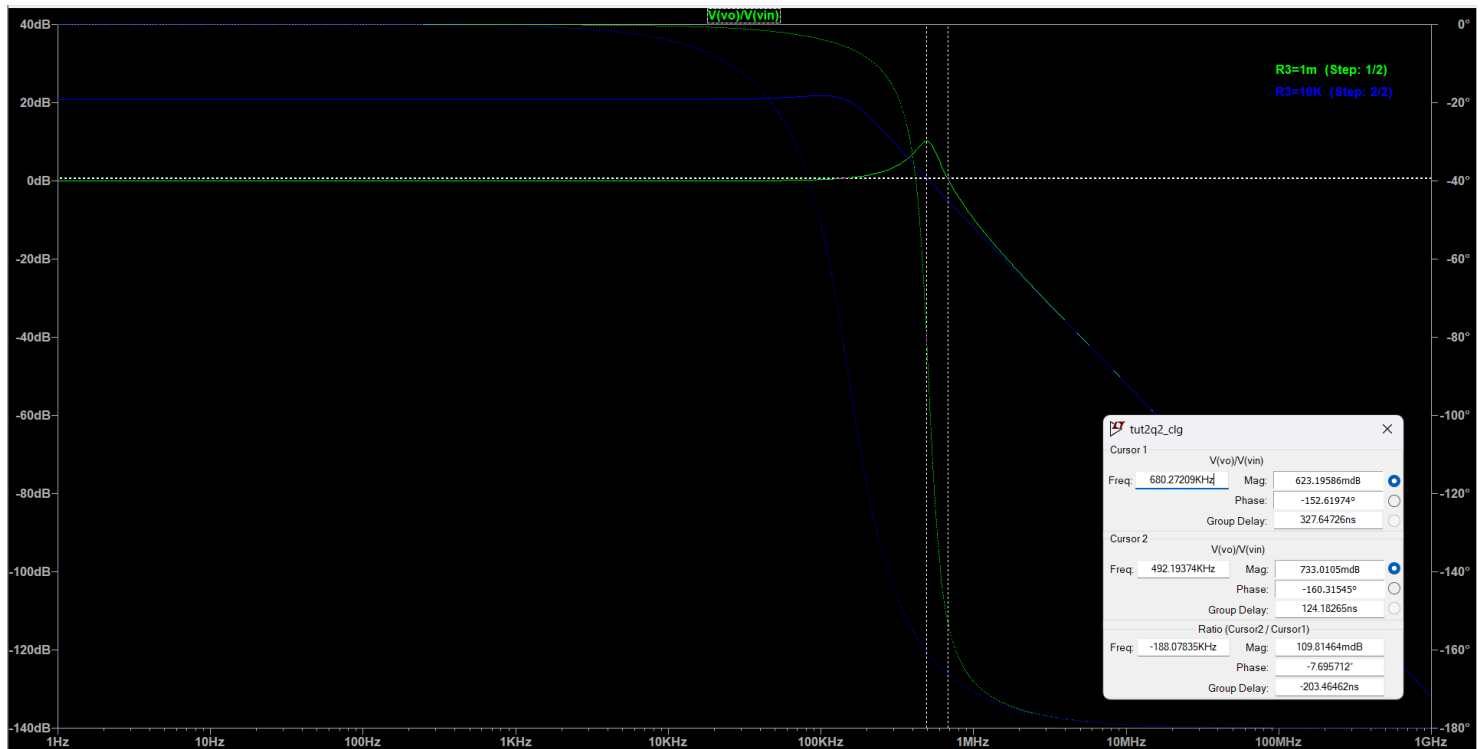
- The step response is analyzed for different damping factors.



- As damping factor increases, less ringing.
- Fastest settling occurs when damping factor is close to 1

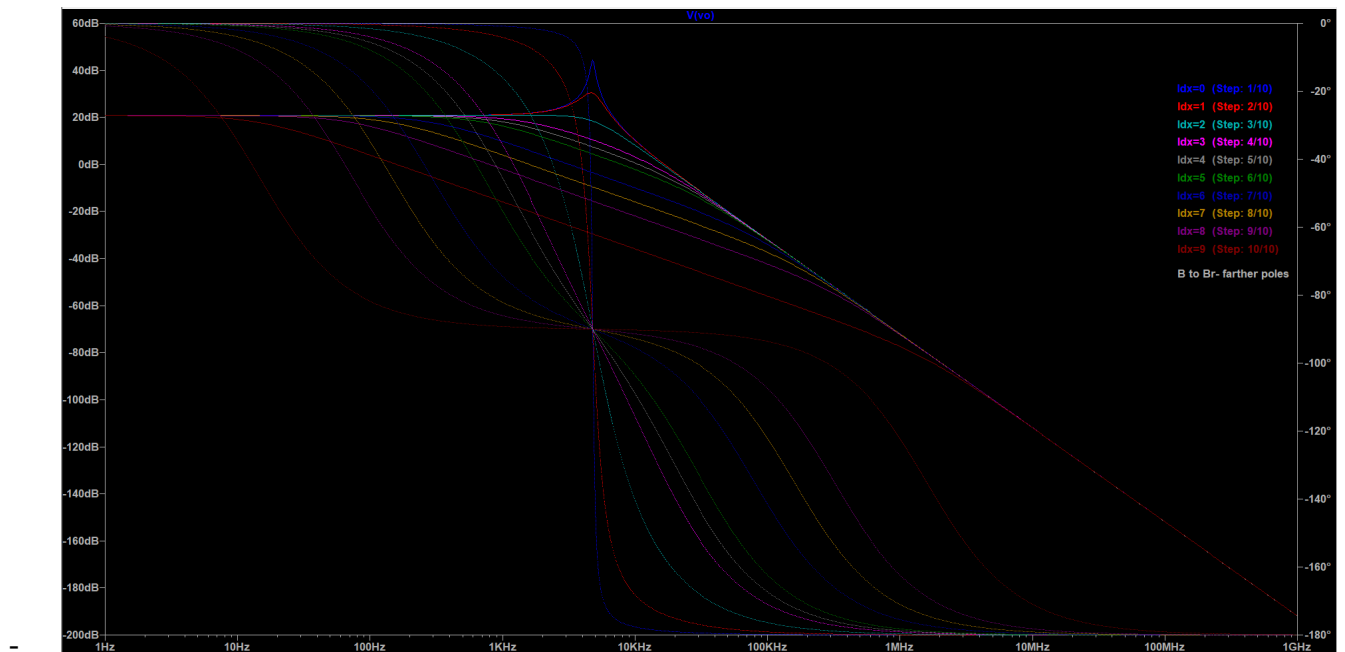


- We also analyze the effect of the gain of opamp on closed loop gain and loop gain.

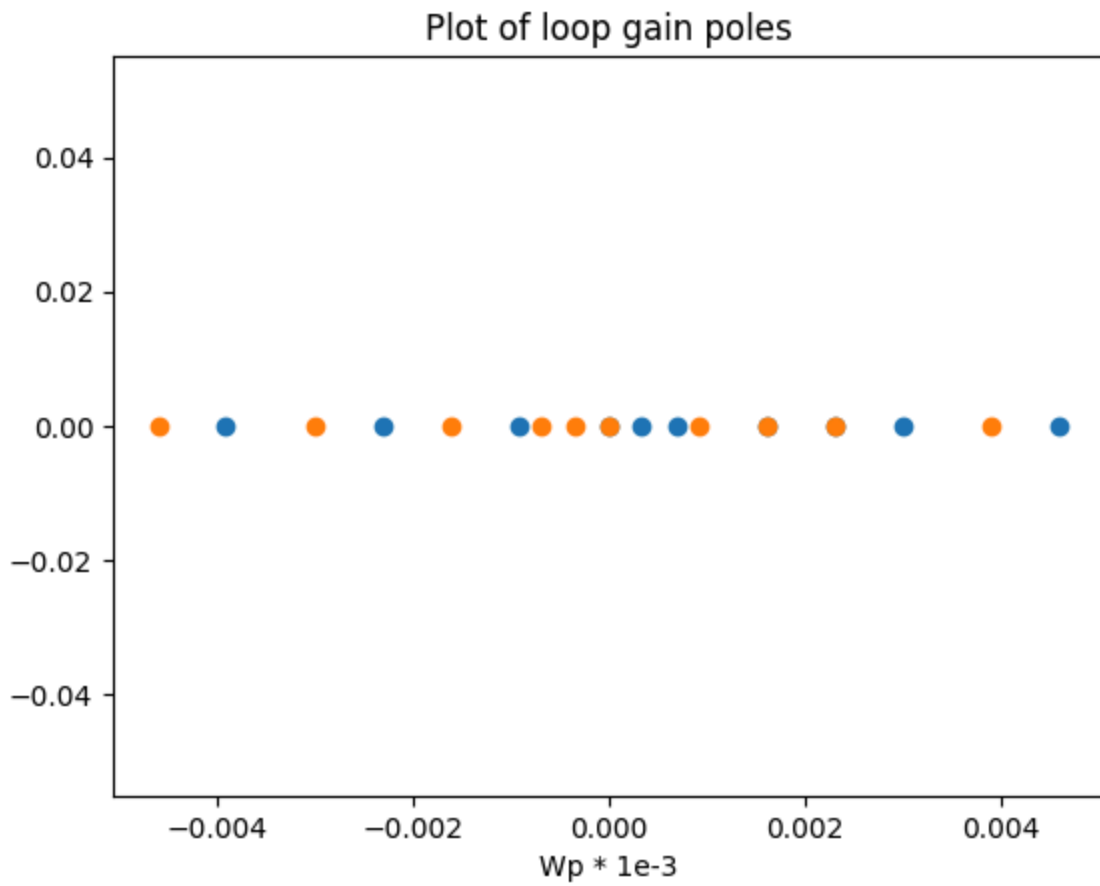


- Increasing beta increases damping factor. Unity gain frequency decreases.

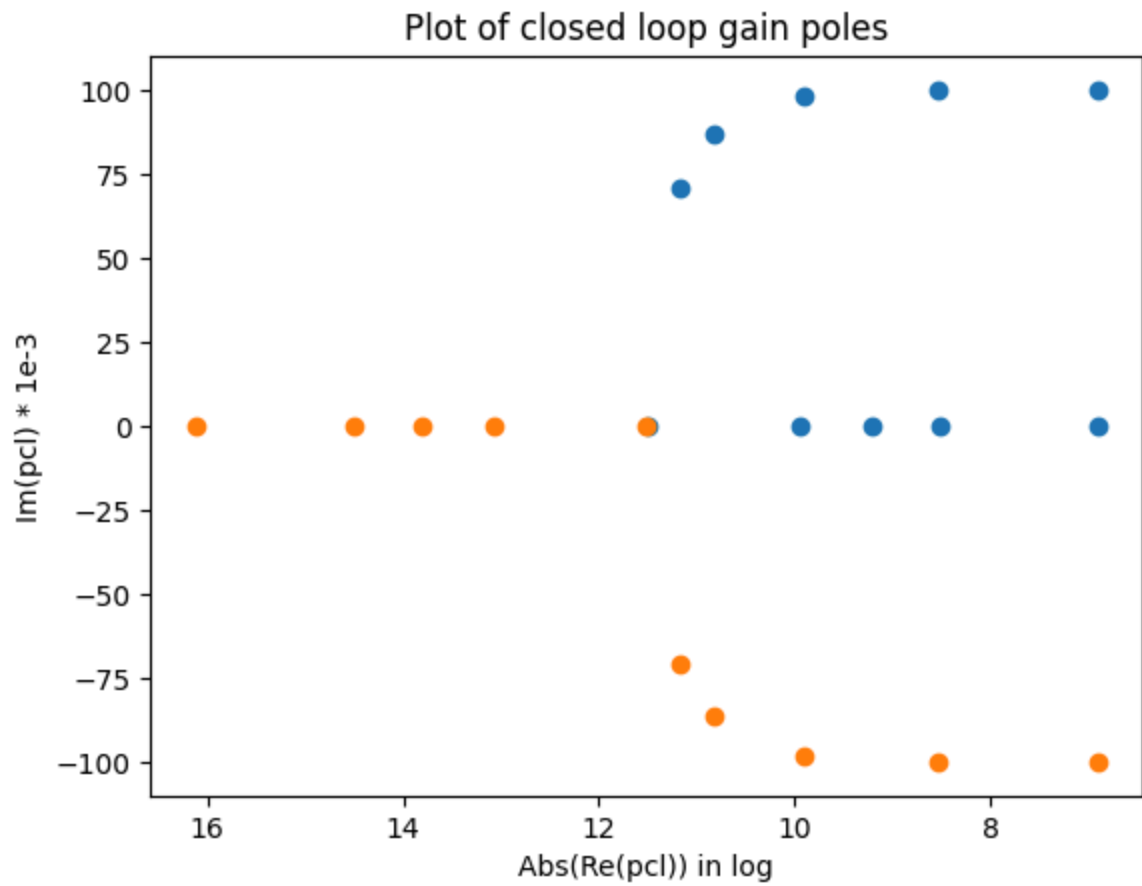
- As the following plot shows, the phase margin increases and unity gain frequency of loop gain also decreases.



- To understand the table better we plot the poles of the loop gain and the closed loop gain.

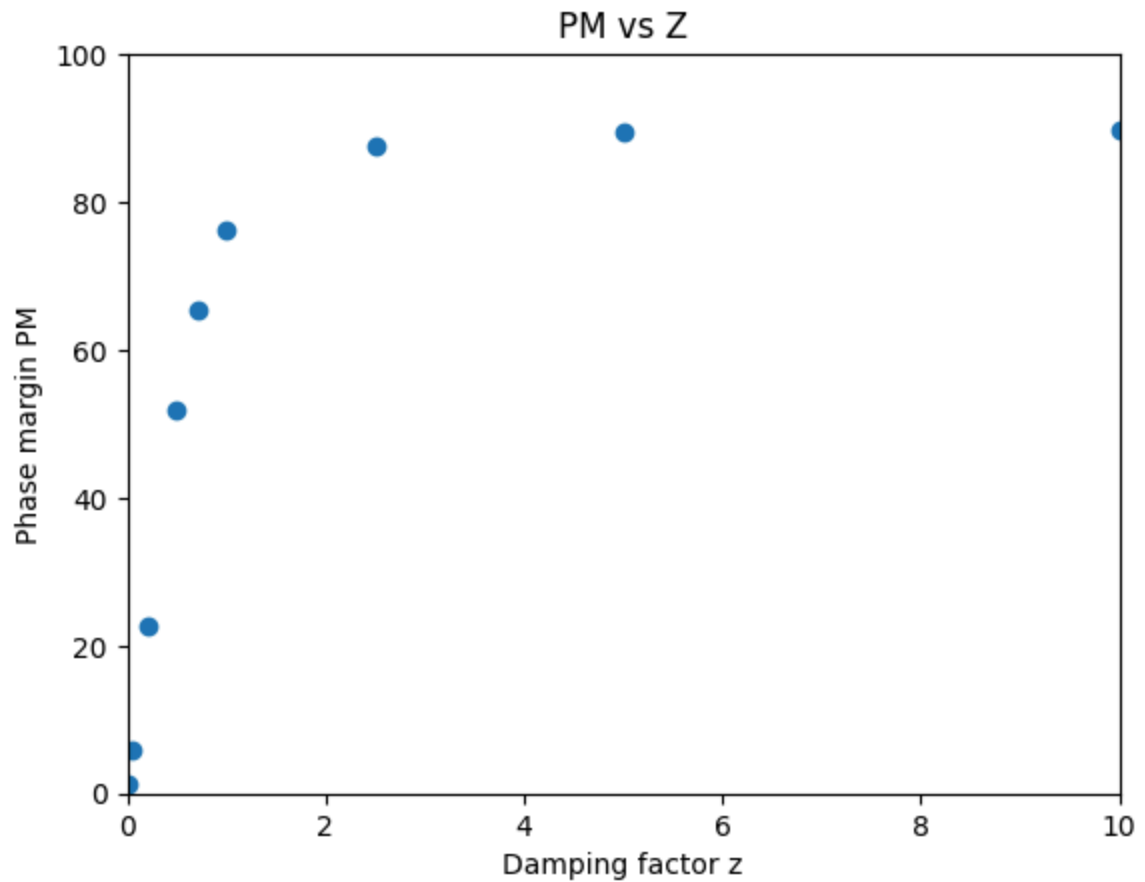


- As damping factor decreases, the loop gain poles go closer together.



- As damping factor increases, loop gain poles go closer and same with closed loop gain poles which later split into complex conjugate pairs.





- The phase margin increases with the damping factor. Note that we can approximate a linear relationship for lower values of damping factor.

## Conclusion

Hopefully, this helps in understanding the characteristics better through plots and simulation. More insights can be gained from these as understanding of the core concepts improve.