

DESIGN AND ANALYSIS OF ALGORITHMS – CSCI 612

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1. (5 points) Give an $O(n^2)$ time algorithm to find the longest monotonically increasing sub-sequence of a sequence of n integers.

Answer.)

Step 1:

Consider the input sequence be $Se[1], Se[2], Se[3], Se[4], \dots, Se[n]$. Let us assume that there is a value $Le[j]$ (such that the values of j is 1 to n) to be the longest monotonically increasing sub-sequence of the first j letters $Se[1], Se[2], Se[3], Se[4], \dots, Se[j]$.

It is assumed that the last letter of the sub-sequence is $Se[j]$.

Assume that the position of the last letter before $Se[j]$ in the longest sub-sequence of the first j letters be $Po[j]$ such that $Se[j]$ is the last letter.

R is the resulting sub-sequence.

Step 2:

The recurrence function for computing $Le[j]$ is provided as below:

$Le[j] =$

The algorithm provided is as follows:

// This loop will run for n times:

for $j = 1$ to n do

$Le[j] = 1;$

$Po[j] = 0;$

// This inner loop will execute for $O(n^2)$ times.

for $k = 1$ to $j - 1$ do

if $Se[k] < Se[j]$ && $Le[k] \geq Le[j]$ then

$Le[j] = Le[k] + 1;$

$Po[j] = k;$

end if

end for ; end for

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// The largest value of $Le[m]$ in $Le[1] \dots Le[n]$ should be found.

// Backtracking we get the following

$j = 1; k = m$ do

$R[j] = Se[k];$

$j++;$

$k = Po[k];$

Until $k = 0$

Output $Le[m]$ and the reverse of R .

Hence, it is evident that the time complexity is $O(n^2)$

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2. (5 points) Describe an efficient algorithm that, given a set $\{x_1, x_2, \dots, x_n\}$ of points on the real line, determines the smallest set of unit-length closed intervals that contains all of the given points. Argue that your algorithm is correct.

Answer.)

The array of n points on the real line is $A[1..n]$: Points $A[1] < A[2] < \dots < A[n]$

The array of intervals $B[1 \dots m]$: Intervals $[B[j], B[j] + 1]$

Algorithm smallest-set (n)

Step1: $m = 1;$

Step 2: $B[1] = A[1];$

Step 3: for $j = 1$ to n do

Step 4: if $(A[j] > B[m] + 1)$

Step 5: $m = m + 1;$ // Adds a new interval

Step 6: $B[m] = A[j];$
else

Step 7: $A[j]$ is in $[B[m], B[m] + 1]$

Step 8: return $m;$

Proof of the algorithm:

Theorem:

smallest-set returns the minimal number of unit intervals that cover $A[1], A[2], \dots, A[n]$.

Lemma: None of the intervals obtained by smallest-set can move right by any distance, otherwise some points won't be covered.

Proof: Induction on m

Base case: $m = 1$ and $B[1] = A[1]$. If $[B[1], B[1]+1]$ moves right, then $A[1]$ cannot be covered.

Inductive hypothesis: Suppose none of the first m intervals can move right. When $A[j] > B[m] + 1$, the last interval $[B[m], B[m]+1]$ cannot cover $A[j]$ (and it cannot move right). So need a new interval and let it be $[A[j], A[j] + 1]$, which cannot move right; otherwise $A[j]$ cannot be covered.

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3.) Suppose you want to drive from San Francisco to New York on I-80. Your car holds C gallons of gas and gets m miles to the gallon. You are handed a list of the n gas stations that are on I-80 and the price that they sell gas. Let d_i be the distance of the i -th gas station from SF, and c_i be the cost of gasoline at the i -th gas station. Furthermore, you can assume that for any two stations i and j , the distance $d_i - d_j$ between these two stations is a multiple of m . You start out with an empty tank at station 1. Your final destination is gas station n . You need to end at station n with at least 0 gallons of gas.

Find a polynomial-time dynamic programming algorithm to output the minimum gas bill to cross the country. Analyze the running time of your algorithm in terms of n and C . You do not need to find the most efficient algorithm as long as your solution's running time is polynomial in n and C .

Remember that your car cannot run if your tank ever holds less than 0 gallons of gas. Also, if you decide to get gasoline at a particular station, you needn't fill up the tank; for example, you might decide to purchase only 7 gallons of gas at one station.

Answer.)

Let $M_i(g)$ be the minimum gas bill to reach gas station i with g gallons of gas in the tank (after potentially purchasing gas at station i). The range of the indices is $1 \leq i \leq n$ and $0 \leq g \leq C$.

The recursive equation will be written in terms of the number of gallons of gas in the car when leaving station $i - 1$. Call this number h . Clearly $(d_i - d_{i-1})/m \leq h \leq C$ otherwise the car cannot reach station i . Also $h \leq (d_i - d_{i-1})/m + g$ because we cannot purchase a negative number of gallons at station i .

The recursive equation is

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$$M^i(g) = \min_h [M^{i-1}(h) + (g + (d_i - d_{i-1})/m - h)c_i]$$

where, h runs from $(d_i - d_{i-1})/m$ to $\min(C, (d_i - d_{i-1})/m + g)$.

The base case is $M^1(g) = c_1g$ where $0 \leq g \leq C$.

The answer will be given by $\min_{g=0}^C(M^n(g))$. One can argue that the cheapest solution will involve arriving at gas station n with 0 gallons in the tank, so the answer is also simply the entry $M^n(0)$.

We choose to evaluate the matrix in increasing order of i . Note that to compute M^i we only need M^{i-1} , so the space can be reused. This is demonstrated in the pseudo-code, which uses only two arrays M and N .

GasolineRefilling($n, d[], c[]$)

```
{
    for g from 0 to C M[g] = c[1]*g
    // base case for i from 2 to n
    {
        for g from 0 to C
        {
            N[g] = infinity // N is a temporary array
            for h from (d[i] - d[i-1])/m to min(C, (d[i] - d[i-1])/m + g)
            {
                cost = M[h] + (g + (d[i] - d[i-1])/m - h)*c[i]
                if (cost < N[g]) N[g] = cost;
            }
        }
        for g from 0 to C
            M[g] = N[g] // copy entries from the temporary array
    }
    return M[0]
}
```