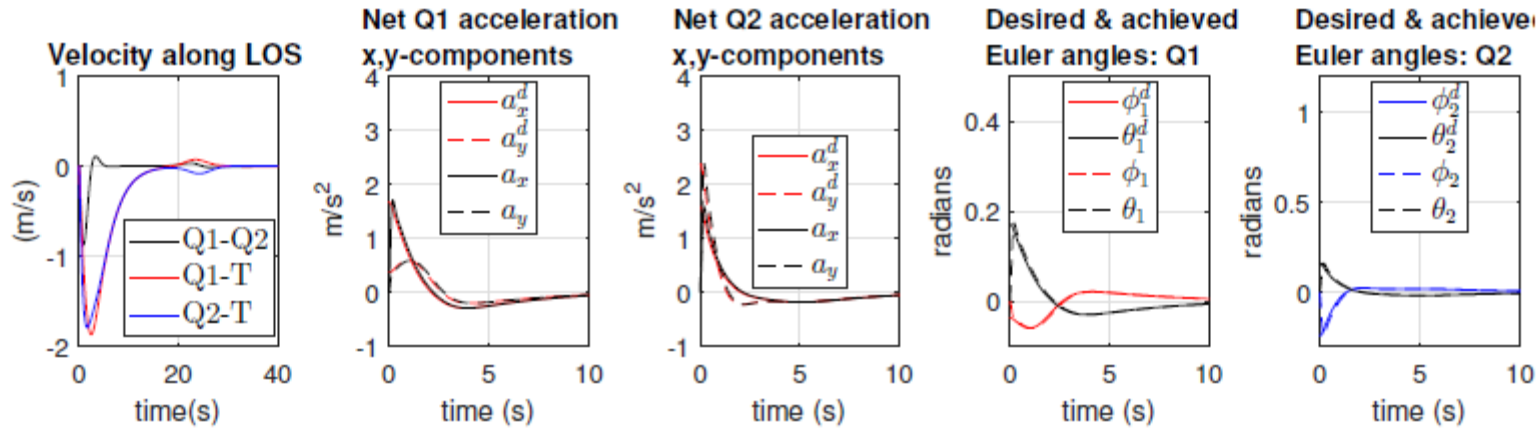


(a)



(b)

Fig. 7 Static target; Linear model, $K_P = 0.2, K_{Pr} = 0.8, K_D = 0.9, K_{Dr} = 0.5$; (a) Quadrotor system performance, (b) Control performance.