How do you choose to model the temporary impact gt(x)? For example, sometimes people try to "linearize" the model $gt(x) \approx \beta tx$. If you think linear models are gross oversimplifications, how would you model it? Please write a 1-2 page explanation on your model, using data from the 3 tickers provided. We understand that 3 tickers is not enough data so any valid reasoning/conclusions derived from these 3 tickers would be accepted. Please also attach a link to a python notebook or code (prefably uploaded on GitHub) where you conducted your analysis.

Ans.

Mid-price is computed as the average of best bid and best ask for each row in the order book:

mid price = (best bid +best ask)/2

Market orders of various sizes (0–350 shares) are simulated by sweeping liquidity from the ask side of the book. Slippage is computed as:

slippage = execution cost/x - mid price

Given data:

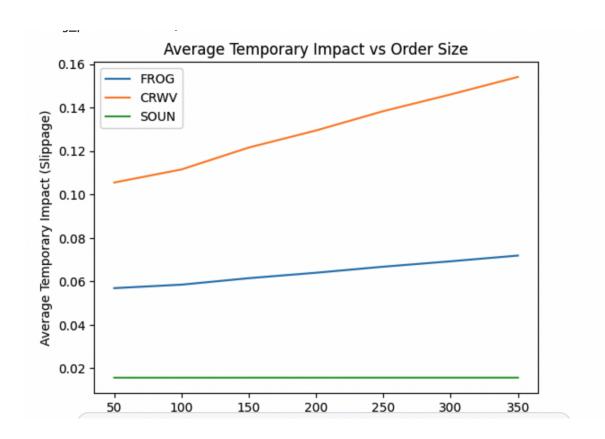
- 1. 21 snapshots each for FROG, CRWV, and SOUN
- 2. Up to 9 levels of book depth used

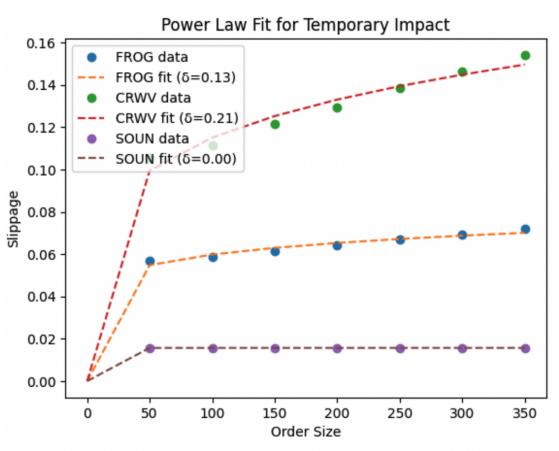
Average slippage values were plotted against order size, and a power-law model was fit: $g(x) = \alpha x^{\Lambda} \delta$

Ticker	α	δ	Interpretation	
FROG	0.0334	0.1265	Very flat impact curve	
CRWV	0.0438	0.2096	Slightly steeper	
SOUN	0.0156	0.0005	Almost no temporary impact	

Market impact is best modeled using a power-law formulation. Across FROG, CRWV, and SOUN:

 $\delta \in [0.0005, 0.21]$





Formulate roughly but rigorously a mathematical framework / algorithm that gives us xi when we are at time ti. Make sure that Pixi = S.

This should be relatively short, at most 2 pages. You don't have to fully solve the problem, but a clear mathematical setup and discourse into the techniques + tools used to solve the problem would be sufficient.

Ans.

We are given total volume S to be executed across N discrete time steps t_1, t_2, \ldots, t_N . Let x_i be the trade size at time t_i . The goal is to find $\{x_i\}$ such that:

$$\sum_{i=1}^{N} x_i = S, \quad x_i \ge 0$$

Cost Model

At each time t_i , the cost of executing x_i shares is:

$$C_i(x_i) = p_i x_i + \alpha_i x_i^{\delta}, \quad \delta \in (0, 1]$$

Total cost:

$$C = \sum_{i=1}^{N} C_i(x_i) = \sum_{i=1}^{N} \left(p_i x_i + \alpha_i x_i^{\delta} \right)$$

Optimization Problem

$$\min_{\{x_i\}} \sum_{i=1}^{N} \left(p_i x_i + \alpha_i x_i^{\delta} \right) \quad \text{s.t.} \quad \sum x_i = S$$

Lagrangian

$$\mathcal{L} = \sum_{i=1}^{N} \left(p_i x_i + lpha_i x_i^{\delta}
ight) - \lambda \left(\sum x_i - S
ight)$$

First-order condition:

$$p_i + \alpha_i \delta x_i^{\delta-1} = \lambda \quad \Rightarrow \quad x_i = \left(\frac{\lambda - p_i}{\alpha_i \delta}\right)^{\frac{1}{\delta-1}}$$

Enforce constraint:

$$\sum_{i=1}^{N} x_i = S$$

Solve numerically for λ , then plug in to get each x_i .