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EDUCATION

Degree/Certificate	${\bf Institute/Board}$	CGPA/Percentage	Year of Passing
B.tech (CE)	Indian Institute of Technology, Jammu	7.34 (Till 4th Semester)	2026
12th Standard	GRM School, Bareilly	94%	2021
10th Standard	GRM School, Bareilly	93.4%	2019

PROJECTS

• See Through Armour (STA), Indian Army

May. 2024

Developed an AI based smart AR glasses system for Indian Army's Tanks.

- Tools & technologies used: Google Colab, Linux, Python, Open CV, PyTorch, RTMP Streaming
- Converted the whole project into Linux bundles for modularity and Compatibility across Linux systems
- Optimized AR glasses to work with Nvidia Jetson Xavier NX GPU reducing the cost of overall project by upwards of 50%.
- Refined Python scripts to reduce lag to 10-20 ms in the RTMP Stream from external 360 camera.

• Flipkart Grid 5.0

Jan. 2024

Built an AI powered robotic arm equiped with Cameras and Sensors to tackle Packaging hurdles of the Industry.

- Tools & technologies used: Raspberry PI, Stepper Motors, Depth Sensors & Cameras, YoloV8, Computer Vision, Python
- Maximized Box and QR Code detection along with pickup and place accuracy of the Arm while managing the arm to move at a fast pace.
- Reached National Finals and placed in the Top 5 teams all from 100+ teams all across India.

• Autonomous EV Jan. 2024

Developed a robust and reliable Self Driving Electric Vehicle based on Deep Learning.

- Tools & technologies used: Image Processing, Deep Learning, Linux, Arduino, Sensors, Stepper Motors
- Trained a Deep Learning model to detect road lanes, used python scripts to send that data to Arduino which would further control Servo motors to Control the EV.
- Developed a Manual Remote Control using FS-iA6 transmitter and receiver as a fail-safe to ensure passenger safety.

• Waste Segregation Robotic Arm

Dec. 2023

Built a Robotic Arm which could be used to segregate different type of waste materials using a gripper.

- Tools & technologies used: Arduino, Robotic Operating System (ROS), Linux, Stepper Motors, Motion Planning,
 CAD, Inverse Kinematics
- Engineered a robotic arm powered by ROS along with Motion Planning and Gazebo Simulation which could be used to segregate different types of waste materials.

• AeroTHON Aug 2023

 $Built\ a\ Drone\ for\ the\ SAE\ AeroTHON\ competition$

- Tools & technologies used: CAD, Performance Optimization, Material Selection, Brushless Motors, Analysis
- Built the CAD model of the Drone and Performed Various Analysis on it to Optimize the design.
- Carefully selected the Parts and Build Material of the Drone to Maximise Flight Time and Stability.

• Line Following Bot March 2023

Engineered a Fast Line following bot based on Ultrasonic Sensors

- Tools & technologies used: CAD, Arduino, Stepper motors, PID controller, Maze Following Algorithms
- Optimized the PID Controller of the bot for the fastest speed while reliably following the line.
- Took the Bot to IIT Kanpur Techfest and World Robotics Championship.

• Robotic Dog Feb 2023

Built a 3D printed Robotic Dog which could perform a few tasks and walk around.

- Tools & technologies used: Arduino, Servo motors, CAD, Inverse Kinematics, 3D Printing
- Worked out the Inverse kinematics needed for proper motion of the Bot.
- Refined and Redesigned the 3D CAD to fit the required components inside.

KEY COURSES TAKEN

• Data Structure and Algorithms, Computer Programming, Mechanics, Calculus, Strength of Materials, Linear Algebra, Structural Analysis.

TECHNICAL SKILLS

- **Programming:** C/C++, Python, Rust, HTML, SQL, Arduino
- Tools & OS: Git, Jupyter Notebook, Google Colab, Linux, Windows, Robotics Operating System (ROS), Docker, Nvidia Jetson
- Libraries/Frameworks: Numpy, Open CV, RosPy, YoloV8, OS, PySerial, etc.

Positions of Responsibility

• Club Coordinator, Robotics Club, IIT Jammu

Present

• Design Head Fintech, IIT Jammu

Present

• Mentor Coding Club, IIT Jammu

Present

• Event Management Outreach Head Tinkering Lab (I2EDC), IIT Jammu

2024

Extracurricular Activities & Workshops

- Won 1st Place in Intra College Football Competition Pahal '24.
- Got 1st Place in Intra College E-sports Tournament Pravaah '24.
- Got 2nd Place in Intra College E-sports Tournament Pravaah '23.
- Attended Boeing's National Aeromodelling Workshop 2023 at IIT Kanpur.
- Attended Canva Workshop for Designing at IIT Jammu.
- Attended Solid Works Workshop held by SAE Club, IIT Jammu.
- Attended Photography Workshop held by Chitraka, IIT Jammu
- Attended Cyber Security Workshop at IIT Jammu.
- Volunteered as Security Head at Udyamitsav '24.
- Volunteered as Harmonic Tech Head at Anhad '24.