

Artificial Intelligence Practical File

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DFS Algorithm

```
def dfs(graph, start, visited=None):

    if visited is None:

        visited = set()

    visited.add(start)

    print(start, end=' ')

    for neighbor in graph[start]:

        if neighbor not in visited:

            dfs(graph, neighbor, visited)

graph = {

    'A': ['B', 'C'],

    'B': ['D', 'E'],

    'C': ['F'],

    'D': [],

    'E': ['F'],

    'F': []

}

print("DFS Traversal:")

dfs(graph, 'A')
```

BFS Algorithm

```
from collections import deque
```

```
def bfs(graph, start):
```

```
    visited = set()
```

```
    queue = deque([start])
```

```
    while queue:
```

```
        vertex = queue.popleft()
```

```
        if vertex not in visited:
```

```
            print(vertex, end=' ')
```

```
            visited.add(vertex)
```

```
            queue.extend(graph[vertex])
```

```
graph = {
```

```
    'A': ['B', 'C'],
```

```
    'B': ['D', 'E'],
```

```
    'C': ['F'],
```

```
    'D': [],
```

```
    'E': ['F'],
```

```
    'F': []
```

```
}
```

```
print("\nBFS Traversal:")
```

```
bfs(graph, 'A')
```

A* Algorithm

```
from queue import PriorityQueue
```

```
def heuristic(a, b):
```

```
    return abs(a[0] - b[0]) + abs(a[1] - b[1])
```

```
def a_star(start, goal):
```

```
    frontier = PriorityQueue()
```

```
    frontier.put((0, start))
```

```
    came_from = {}
```

```
    cost_so_far = {start: 0}
```

```
    while not frontier.empty():
```

```
        _, current = frontier.get()
```

```
        if current == goal:
```

```
            break
```

```
        for dx, dy in [(1,0), (0,1), (-1,0), (0,-1)]:
```

```
            neighbor = (current[0] + dx, current[1] + dy)
```

```
            if 0 <= neighbor[0] < 5 and 0 <= neighbor[1] < 5:
```

```
                new_cost = cost_so_far[current] + 1
```

```
                if neighbor not in cost_so_far or new_cost < cost_so_far[neighbor]:
```

```
                    cost_so_far[neighbor] = new_cost
```

```
                    priority = new_cost + heuristic(goal, neighbor)
```

```
                    frontier.put((priority, neighbor))
```

```
came_from[neighbor] = current
```

```
return came_from
```

```
start = (0, 0)
```

```
goal = (4, 4)
```

```
path = a_star(start, goal)
```

```
print("\nPath traced using A* (some output):", path)
```

Selection Sort Algorithm

```
def selection_sort(arr):  
    for i in range(len(arr)):  
        min_idx = i  
        for j in range(i+1, len(arr)):  
            if arr[min_idx] > arr[j]:  
                min_idx = j  
        arr[i], arr[min_idx] = arr[min_idx], arr[i]  
  
arr = [64, 25, 12, 22, 11]  
  
selection_sort(arr)  
  
print("\nSorted array:", arr)
```

Prim's MST Algorithm

```
import sys

def prim(graph):

    selected = [False] * len(graph)

    no_edge = 0

    selected[0] = True

    print("Edge : Weight")

    while no_edge < len(graph) - 1:

        minimum = sys.maxsize

        x = 0

        y = 0

        for i in range(len(graph)):

            if selected[i]:

                for j in range(len(graph)):

                    if (not selected[j]) and graph[i][j]:

                        if minimum > graph[i][j]:

                            minimum = graph[i][j]

                            x = i

                            y = j

        print(f"{x} - {y}: {graph[x][y]}")

        selected[y] = True

        no_edge += 1

graph = [
```

```
[0, 2, 0, 6, 0],  
[2, 0, 3, 8, 5],  
[0, 3, 0, 0, 7],  
[6, 8, 0, 0, 9],  
[0, 5, 7, 9, 0]  
]
```

```
prim(graph)
```


Kruskal's MST Algorithm

```
class DisjointSet:

    def __init__(self, n):

        self.parent = list(range(n))

        self.rank = [0] * n

    def find(self, u):

        if self.parent[u] != u:

            self.parent[u] = self.find(self.parent[u])

        return self.parent[u]

    def union(self, u, v):

        root_u = self.find(u)

        root_v = self.find(v)

        if root_u != root_v:

            if self.rank[root_u] > self.rank[root_v]:

                self.parent[root_v] = root_u

            else:

                self.parent[root_u] = root_v

                if self.rank[root_u] == self.rank[root_v]:

                    self.rank[root_v] += 1

    def kruskal(n, edges):

        ds = DisjointSet(n)

        mst = []

        edges.sort(key=lambda edge: edge[2])
```

```

for u, v, w in edges:

    if ds.find(u) != ds.find(v):

        ds.union(u, v)

        mst.append((u, v, w))

return mst

edges = [

    (0, 1, 10),

    (0, 2, 6),

    (0, 3, 5),

    (1, 3, 15),

    (2, 3, 4)

]

mst = kruskal(4, edges)

print("\nKruskal's MST:")

for u, v, w in mst:

    print(f"{u} - {v}: {w}")

```

Dijkstra's Algorithm Algorithm

```
import heapq

def dijkstra(graph, start):

    queue = [(0, start)]

    dist = {start: 0}

    while queue:

        (cost, node) = heapq.heappop(queue)

        if node in dist and dist[node] < cost:

            continue

        for neighbor, weight in graph[node]:

            new_cost = cost + weight

            if neighbor not in dist or new_cost < dist[neighbor]:

                dist[neighbor] = new_cost

                heapq.heappush(queue, (new_cost, neighbor))

    return dist

graph = {

    'A': [('B', 1), ('C', 4)],

    'B': [('A', 1), ('C', 2), ('D', 5)],

    'C': [('A', 4), ('B', 2), ('D', 1)],

    'D': [('B', 5), ('C', 1)]

}
```

```
print("\nShortest path from A:", dijkstra(graph, 'A'))
```

N-Queens Backtracking Algorithm

```
def is_safe(board, row, col, n):  
  
    for i in range(col):  
  
        if board[row][i] == 1:  
  
            return False  
  
    for i, j in zip(range(row, -1, -1), range(col, -1, -1)):  
  
        if board[i][j] == 1:  
  
            return False  
  
    for i, j in zip(range(row, n, 1), range(col, -1, -1)):  
  
        if board[i][j] == 1:  
  
            return False  
  
    return True
```

```
def solve(board, col, n):  
  
    if col >= n:  
  
        return True  
  
    for i in range(n):  
  
        if is_safe(board, i, col, n):  
  
            board[i][col] = 1  
  
            if solve(board, col + 1, n):  
  
                return True  
  
            board[i][col] = 0  
  
    return False
```

```
def print_solution(board):  
  
    for row in board:
```

```
print(' '.join(['Q' if x else '.' for x in row]))
```

```
n = 4
```

```
board = [[0] * n for _ in range(n)]
```

```
if solve(board, 0, n):
```

```
    print("\nSolution for N-Queens:")
```

```
    print_solution(board)
```

```
else:
```

```
    print("\nSolution does not exist")
```

Graph Coloring Backtracking Algorithm

```
def is_safe(graph, color, c, v):
```

```
    for i in graph[v]:
```

```
        if color[i] == c:
```

```
            return False
```

```
    return True
```

```
def graph_coloring(graph, m, color, v):
```

```
    if v == len(graph):
```

```
        return True
```

```
    for c in range(1, m + 1):
```

```
        if is_safe(graph, color, c, v):
```

```
            color[v] = c
```

```
            if graph_coloring(graph, m, color, v + 1):
```

```
                return True
```

```
            color[v] = 0
```

```
    return False
```

```
def print_solution(color):
```

```
    print("Graph coloring solution:", color)
```

```
graph = [
```

```
    [1, 2, 3],
```

```
    [0, 2],
```

```
    [0, 1],
```

```
    [0]
```

```
]
```

```
m = 3
```

```
color = [0] * len(graph)
```

```
if graph_coloring(graph, m, color, 0):
```

```
    print_solution(color)
```

```
else:
```

```
    print("Solution does not exist")
```


Chatbot Algorithm

```
import random
```

```
def chatbot_response(user_input):
```

```
    responses = {
```

```
        'hello': 'Hi there! How can I assist you today?',
```

```
        'bye': 'Goodbye! Have a great day!',
```

```
        'help': 'Sure, what can I help you with?',
```

```
        'default': 'Sorry, I did not understand that.'
```

```
    }
```

```
    return responses.get(user_input.lower(), responses['default'])
```

```
while True:
```

```
    user_input = input("You: ")
```

```
    if user_input.lower() == 'bye':
```

```
        print("Chatbot:", chatbot_response(user_input))
```

```
        break
```

```
    print("Chatbot:", chatbot_response(user_input))
```

Salesforce Application (Apex) Algorithm

```
// Example Apex Class in Salesforce

public class HelloWorld {

    public static String greet(String name) {

        return 'Hello, ' + name + '!';

    }

}

// Call the method from Apex class

String result = HelloWorld.greet('V');

System.debug(result);
```

Salesforce Cloud App Algorithm

```
// Simple Salesforce Cloud Application (Mini Project) Example
```

```
public class AccountManager {  
  
    public void createAccount(String name, String type) {  
  
        Account acc = new Account();  
  
        acc.Name = name;  
  
        acc.Type = type;  
  
        insert acc;  
  
    }  
  
}
```

```
// Instantiate the class and create an account
```

```
AccountManager manager = new AccountManager();  
  
manager.createAccount('Acme Corp', 'Customer');
```

Reflex Agent Algorithm

```
# Simple Reflex Agent (AI)

def reflex_agent(state):

    if state == 'hungry':

        return 'eat'

    elif state == 'tired':

        return 'sleep'

    else:

        return 'do nothing'

state = 'hungry'

action = reflex_agent(state)

print("Reflex Agent action:", action)
```

Alpha-Beta Pruning Algorithm

```
# Simple Alpha-Beta Pruning Example
```

```
def alpha_beta_pruning(node, depth, alpha, beta, maximizing_player):

    if depth == 0 or not node:

        return node

    if maximizing_player:

        max_eval = -float('inf')

        for child in node:

            eval = alpha_beta_pruning(child, depth-1, alpha, beta, False)

            max_eval = max(max_eval, eval)

            alpha = max(alpha, eval)

            if beta <= alpha:

                break

        return max_eval

    else:

        min_eval = float('inf')

        for child in node:

            eval = alpha_beta_pruning(child, depth-1, alpha, beta, True)

            min_eval = min(min_eval, eval)

            beta = min(beta, eval)

            if beta <= alpha:

                break

        return min_eval
```

```
# Example of alpha-beta pruning on a tree
```

```
node_tree = [3, 12, 8, 2]

result = alpha_beta_pruning(node_tree, 3, -float('inf'), float('inf'), True)

print("\nAlpha-Beta Pruning Result:", result)
```

Forward Chaining Algorithm

```
# Forward Chaining Example

knowledge_base = {'A': True, 'B': False, 'C': None}

def forward_chaining(kb):

    if kb['A'] and kb['B'] is False:

        kb['C'] = True

    return kb

result = forward_chaining(knowledge_base)

print("\nForward Chaining Result:", result)
```