

Mechanics - 7 -

Boundary Value Problem

L7 - ① a

$$\frac{d^2y}{dx^2} = f(x) \quad \text{with } y(a) = \gamma_1 \text{ and } y(b) = \gamma_2$$

As we saw, one can use shooting method to change it into IVPs and solve.

a) Superposition [only linear]

$$y(b) = \lambda y(b; \alpha) + (1-\lambda) y(b; \beta)$$

$$\bar{y}(a) = \alpha \rightarrow y(b; \alpha)$$

$$y'(a) = \beta \rightarrow y(b; \beta)$$

$$\boxed{\lambda = \frac{\gamma_2 - y(b; \beta)}{y(b; \alpha) - y(b; \beta)}}$$

b) Iterative 

Secant method

$$\alpha_{n+1} = \alpha_n - \frac{(\alpha_n - \alpha_{n-1})}{[\phi(\alpha_n) - \phi(\alpha_{n-1})]} \cdot \phi(\alpha_n)$$

$$\phi(\alpha) = y(b; \alpha) - \gamma_2$$

Need two α guess & then keep modifying the α to get the proper soln.

Simple and effective.

One can also do →

$$\text{Differential} \xrightarrow[\text{into}]{} \text{Converg}^* \rightarrow \text{Difference} = n$$

Consider Taylor series

$$y(x+h) = y(x) + h y'(x) + \frac{h^2}{2!} y''(x) + \dots \quad -①$$

$$y'(x) = \frac{y(x+h) - y(x)}{h} - \frac{h}{2} y''(\xi)$$

Forward

Approximation for 1st derivative.

$$x < \xi < x+h$$

Now consider

$$y(x-h) = y(x) - h y'(x) + \frac{h^2}{2!} y''(x) - \dots \quad -②$$

$$y'(x) = \frac{y(x) - y(x-h)}{h} + \frac{h}{2} y''(\xi) \quad \boxed{\text{Backward}}$$

$$x-h < \xi < x$$

Another approximation

Any grid point, one get

$$y'(x_i) = y'_i \simeq \frac{y(x_{i+1}) - y(x_i)}{h} = \frac{y_{i+1} - y_i}{h} + O(h)$$

Forward

$$y'_i \simeq \frac{y_i - y_{i-1}}{h} + O(h)$$

Backward

$$y(x+h) = y(x) + hy'(x) + \frac{h^2}{2!} y''(x) + \frac{h^3}{3!} y'''(\xi) \quad \dots \quad (1)$$

$$y(x-h) = y(x) - hy'(x) + \frac{h^2}{2!} y''(x) - \frac{h^3}{3!} y'''(\xi) \quad \dots \quad (2)$$

$$(1) - (2)$$

$$y(x+h) - y(x-h) = 2hy'(x) + \frac{h^3}{3} y'''(\xi)$$

$x-h < \xi < x+h$

$$\Rightarrow y'(x) \approx \frac{y(x+h) - y(x-h)}{2h} - \frac{h^2}{6} y'''(\xi)$$

$$y'(x_i) \approx y'_i \approx \frac{y_{i+1} - y_{i-1}}{2h} + O(h^2) \quad \dots \quad (3)$$

This approximation use second order

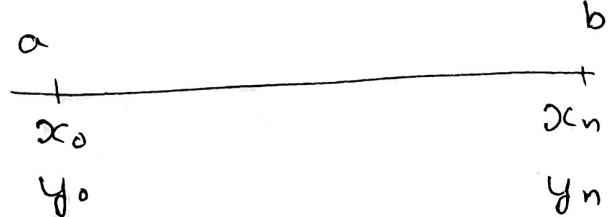
Similarly (1) + (2)

$$y(x+h) + y(x-h) = 2y(x) + h^2 y''(x) + \frac{h^4}{12} y''''(\xi)$$

$$y''(x) = \frac{y(x+h) + y(x-h) - 2y(x)}{h^2} - \frac{h^2}{12} y''''(\xi)$$

$$y''_i = \frac{y_{i+1} - 2y_i + y_{i-1}}{h^2} + O(h^2) \quad \dots \quad (4)$$

lets domain for $x \in [a, b]$



lets proceed to solve the simple BVP

Simple two point BVP

$$y''(x) = f(x)$$

$$a < x < b$$

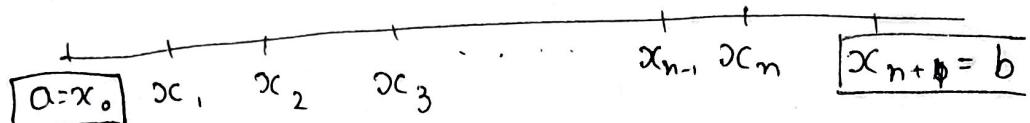
$$0 < x < 1$$

$$\text{--- (1)}$$

$$y(0) = \alpha \quad y(1) = \beta$$

$$y_i'' = \frac{y_{i-1} - 2y_i + y_{i+1}}{h^2} + O(h^2)$$

$$\text{--- (1)} \Rightarrow \frac{y_{i-1} - 2y_i + y_{i+1}}{h^2} = f(x_i) = f^i \quad i = 1, 2, \dots, n$$



i=1 involves y_0 (which is α)

$$y_1'' = \frac{\cancel{y_0} - 2y_1 + y_2}{h^2} = f_1 \Rightarrow \frac{1}{h^2} [-2y_1 + y_2] = f_1 - \frac{\alpha}{h}$$

i=n involves y_{n+1} (which is β)

$$y_n'' = \frac{y_{n-1} - 2y_n + \cancel{y_{n+1}}}{h^2} = f_n$$

$$\Rightarrow \frac{1}{h^2} [y_{n-1} - 2y_n] = f_n - \frac{\beta}{h^2}$$

rest $i = 2, \dots, n-1$

i=2

$$\frac{1}{h^2} [y_1 - 2y_2 + y_3] = f_2$$

$$i=n-1 \quad \frac{1}{h^2} [y_{n-2} - 2y_{n-1} + y_n] = f_{n-2}$$

$$\frac{1}{h^2} \left[-2y_1 + y_2 \right] = f_1 - \frac{\alpha}{h^2}$$

$$\frac{1}{h^2} \left[y_1 - 2y_2 + y_3 \right] = f_2$$

$$\frac{1}{h^2} \left[y_2 - 2y_3 + y_4 \right] = f_3$$

$$\frac{1}{h^2} \left[y_{n-2} - 2y_{n-1} + y_n \right] = f_{n-2}$$

$$\frac{1}{h^2} \left[y_{n-1} - 2y_n \right] = f_n - \frac{\beta}{h^2}$$

One can write in \bar{Y} form

$$A \bar{Y} = \bar{F}$$

$$A = \frac{1}{h^2} \begin{pmatrix} -2 & 1 & 0 & 0 \\ 1 & -2 & 1 & 0 \\ 0 & 1 & -2 & 1 \\ \vdots & & & \ddots \end{pmatrix}$$

Tridiagonal system

$$\begin{matrix} 1 & -2 & 1 & & \\ 0 & 1 & -2 & 1 & \\ 0 & 0 & 1 & -2 & \end{matrix}$$

$$\bar{Y} = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ \vdots \\ y_n \end{pmatrix}$$

$$\bar{F} = \begin{pmatrix} f_1 - \frac{\alpha}{h^2} \\ f_2 \\ f_3 \\ \vdots \\ f_n - \frac{\beta}{h^2} \end{pmatrix}$$

Can be solved for a given $f(x)$

How well does $\bar{y} = (y_1, y_2, \dots, y_n)^T$ approximate $y(x)$?
 $y'' \sim O(h^2)$. So approx of the h^2 order.

However, the reality is a bit more complicated!

Local truncation error

$$T_i = \frac{1}{h^2} [y_{i+1} - 2y_i + y_{i-1}] - f(x_i)$$

$$y''(x_i) - \frac{h^2}{12} y^{(4)}(\xi) + O(h^4) = f(x_i)$$

By virtue of $y'' = f(x)$

$$T_i = -\frac{h^2}{12} y^{(4)}(\xi) + O(h^4)$$

We don't know $y^{(4)}(\xi)$; but believe to be independent of h .

and fixed

$$\therefore T_i \sim O(h^2) \text{ as } h \rightarrow 0.$$

Let \bar{T} -vector containing T_i :

$$\begin{aligned}\bar{T} &= A \hat{\bar{y}} - \bar{F} \\ \Rightarrow A \hat{\bar{y}} &= \bar{F} + \bar{T}\end{aligned}$$

Global error: $A \bar{y} = F \quad \text{--- (a)}$

global error $\bar{E} = \bar{y} - \hat{\bar{y}}$

$$A(\bar{y} - \hat{\bar{y}}) = -\bar{T} \Rightarrow A \bar{E} = -\bar{T}$$

$L + - \text{W} a$

$$\Rightarrow \frac{1}{h^2} (E_{i-1} - 2E_i + E_{i+1}) = -T(x_i) \quad i=1, 2, \dots$$

(E)

with b.c.

$$E_0 = 0, E_{n+1} = 0$$

→ Same as difference = n for y_i , except $f(x_i)$ is replaced by T

$$\Rightarrow e''(x) = -\Delta(x)$$

Δ as some function

$$e(a) = 0, e(b) = 0$$

$$\Delta(x) = \frac{1}{12} h^2 y^{(4)}(x)$$

Integrating twice

$$e(x) \approx -\frac{1}{12} h^2 y''(x) + \frac{h^2}{12} \left[y''(0) + x(y''(1) - y''(0)) \right]$$

$$\approx O(h^2)$$

Global error $O(h^2)$

Linear Finite Difference Method

General form

$$y'' = p(x) y' + q(x) y + r(x) \text{ for } a \leq x \leq b$$

where $y(a) = \gamma_1$ and $y(b) = \gamma_2$

Divide $[a, b]$ into $N+1$

$$h = \frac{(b-a)}{N+1}$$

$i = \overbrace{0, 1, 2, \dots, \dots, \dots, N-1, N}^a, \underbrace{N+1}_b$

interior mesh point x_i for $i=1, 2, \dots, N$

$$y''(x_i) = p(x_i) y'(x_i) + q(x_i) y(x_i) + r(x_i)$$

Using central difference formulae

$$y''(x_i) = \frac{1}{h^2} [y(x_{i+1}) - 2y(x_i) + y(x_{i-1})] - \frac{h^2}{12} y^{(4)}(\xi)$$

$x_{i-1} < \xi < x_{i+1}$

$$y'(x_i) = \frac{1}{2h} [y(x_{i+1}) - y(x_{i-1})] - \frac{h^2}{6} y'''(\xi)$$

$x_{i-1} < \xi < x_{i+1}$

This leads to

$$\frac{y(x_{i+1}) - 2y(x_i) + y(x_{i-1})}{h^2} = p(x_i) \left[\frac{y(x_{i+1}) - y(x_{i-1})}{2h} \right] -$$

$$+ q(x_i) y(x_i) + r(x_i) - \frac{1}{12} h^2 [2p(x_i) y'''(\xi) - y^{(4)}(\xi)]$$

\downarrow

Truncation Error

$$\rightarrow \frac{y_{i+1} - 2y_i + y_{i-1} + p(x_i) \left[\frac{y_{i+1} - y_{i-1}}{2h} \right] + q(x_i) y_i}{h^2} = r_i \\ i = 1, 2, \dots, N$$

Have conveniently chosen $p(x)$ to be $p(x)$. Absorb the negative in the constant ($p(x)$)

$$\rightarrow y_0 = \gamma_1 \quad \text{and} \quad y_{N+1} = \gamma_2$$

$$i = 1, 2, \dots, N$$

$$y_{i+1} - 2y_i + y_{i-1} + \frac{h}{2} p(x_i) y_{i+1} - \frac{h}{2} p(x_i) y_{i-1} + h^2 q(x_i) y_i = h^2 r_i$$

$$\left[1 - \frac{h}{2} p(x_i) \right] y_{i-1} + \left[-2 + h^2 q(x_i) \right] y_i + \left[1 + \frac{h}{2} p(x_i) \right] y_{i+1} = h^2 r_i$$

$$y_0 = \gamma_1$$

$$i=1 \quad \left[1 - \frac{h}{2} p(x_1) \right] y_0 + \left[-2 + h^2 q(x_1) \right] y_1 + \left[1 + \frac{h}{2} p(x_1) \right] y_2 = h^2 r_1$$

$$i=2 \quad \left[1 - \frac{h}{2} p(x_2) \right] y_1 + \left[-2 + h^2 q(x_2) \right] y_2 + \left[1 + \frac{h}{2} p(x_3) \right] y_3 = h^2 r_2$$

$$i=3 \quad \left[1 - \frac{h}{2} p(x_3) \right] y_2 + \left[-2 + h^2 q(x_3) \right] y_3 + \left[1 + \frac{h}{2} p(x_3) \right] y_4 = h^2 r_3$$

$$i=N-1 \quad \left[1 - \frac{h}{2} p(x_{N-1}) \right] y_{N-2} + \left[-2 + h^2 q(x_{N-1}) \right] y_{N-1} + \left[1 + \frac{h}{2} p(x_{N-1}) \right] y_N = h^2 r_{N-1}$$

$$i=N \quad \left[1 - \frac{h}{2} p(x_N) \right] y_{N-1} + \left[-2 + h^2 q(x_N) \right] y_N + \left[1 + \frac{h}{2} p(x_N) \right] y_{N+1} = h^2 r_N$$

One can take these B.V. to R.M.S.

One can generalize and write in form of
a matrix = n

$$A_i y_{i-1} + B_i y_i + C_i y_{i+1} = h^2 q_i \quad i=1, 2, \dots, N$$

$$A_i = \left(1 - \frac{h}{2} p_i\right)$$

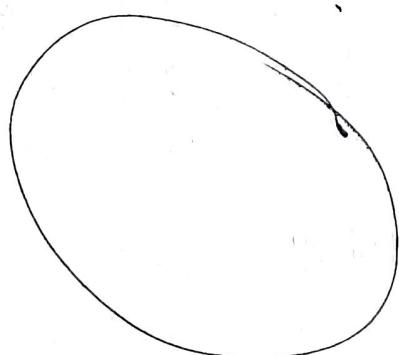
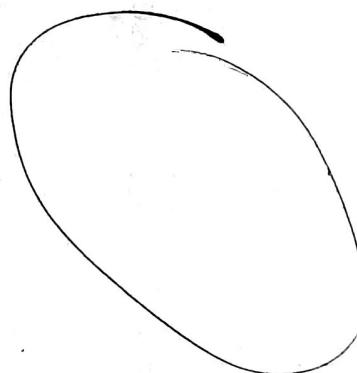
$$B_i = \left(-2 + h^2 q_i\right)$$

$$C_i = \left(1 + \frac{h}{2} p_i\right)$$

From the $\textcircled{*}$, we see that one get A as a tri diagonal system

$$A \bar{y} = \bar{b}$$

$$A = \begin{pmatrix} B_1 & C_1 & 0 & 0 & 0 \\ A_2 & B_2 & C_2 & 0 & 0 \\ 0 & A_3 & B_3 & C_3 & 0 \\ 0 & 0 & A_4 & B_4 & C_4 \end{pmatrix}$$



$$\begin{matrix} A_{N-2} & B_{N-2} & C_{N-2} & 0 \\ 0 & A_{N-1} & B_{N-1} & C_N \\ 0 & 0 & A_N & B \end{matrix}$$

as A_1 and C_N goes to the RHS.

L + - (6) a

$$\bar{y} = (y_1, y_2, y_3, \dots, y_{N-1}, y_N)^T$$

$$\bar{b} = (h^2 r_1 - A_1 \gamma_1, h^2 r_2, h^2 r_3, \dots, h^2 r_{N-1}, h^2 r_N - C_N \gamma_2)^T$$

This system has unique soln. provided that p , q and r are continuous on $[a, b]$, that $q(x) \geq 0$ on $[a, b]$ and that $h < 2/L$ where $L = \max_{a \leq x \leq b} |b(x)|$.

One can use Gauss elimination to solve the eqn,

A brief review

x or y doesn't matter here

somethings to solve

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \dots & a_{2n} \\ a_{31} & a_{32} & a_{33} & \dots & a_{3n} \\ \vdots & & & \ddots & \vdots \\ a_{n1} & a_{n2} & a_{n3} & \dots & a_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ \vdots \\ b_n \end{bmatrix}$$

Use first row to multiply by $\frac{a_{21}}{a_{11}}$ second row & subtract

Assume
 a_{21}, a_{31}, \dots
 not zero

sec.

to multiply by $\frac{a_{31}}{a_{21}}$ third row & subtract

—do— multiply by $\frac{a_{n1}}{a_{(n-1)1}}$ last row & subtract $\left(\frac{a_{n1}}{a_{11}}\right)$

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1n} \\ 0 & a'_{22} & \dots & \dots & a'_{2n} \\ 0 & a'_{32} & \dots & \dots & \vdots \\ \vdots & & & \ddots & \vdots \\ 0 & a'_{n2} & \dots & \dots & a'_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b'_2 \\ b'_3 \\ \vdots \\ b'_n \end{bmatrix}$$

Now
do same with 2nd row and so on.

One ends up with

$$\left[\begin{array}{ccccccc} a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \dots + a_{1n}x_n & = & b_1 \\ a_{21}'x_1 + a_{22}'x_2 + a_{23}'x_3 + \dots + a_{2n}'x_n & = & b_2' \\ a_{31}'x_1 + a_{32}'x_2 + a_{33}'x_3 + \dots + a_{3n}'x_n & = & b_3' \\ & & & a_{n-1,n-1}'x_{n-1} + a_{n-1,n}x_n & = & b_{n-1}' \\ & & & a_{nn}x_n & = & b_n \end{array} \right]$$

One gets $x_n = \frac{b_n}{a_{nn}}$

Then use it to get $x_{n-1} = \frac{1}{a_{n-1,n-1}'} (b_{n-1} - a_{n-1,n}x_n)$

and so on :

Some limitations of Gauss elimination (maine one)
but, not going into ~~pick~~ the detail here.

Do that yourself as already done.

Similarly one can do for Tri-diagonal system ↗

$$\left[\begin{array}{ccc|c} d_1 & c_1 & & y_1 \\ a_2 & d_2 & c_2 & y_2 \\ a_3 & d_3 & c_3 & \vdots \\ a_4 & d_4 & c_4 & \vdots \end{array} \right]$$

$$\begin{matrix} a_{n-2} & d_{n-1} & c_{n-1} & y_{n-1} \\ a_n & d_n & c_n & y_n \end{matrix}$$

Step 1) Let us use same notation

$$\begin{matrix} B_1 & C_1 & 0 & 0 & 0 \\ A_2 & B_2 & C_2 & 0 & 0 \\ 0 & A_3 & B_3 & C_3 & 0 \\ 0 & 0 & A_4 & B_4 & C_4 \end{matrix}$$

$$\left[\begin{matrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{matrix} \right] = \left[\begin{matrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{matrix} \right]$$

$$\begin{matrix} A_{N-2} & B_{N-2} & C_{N-2} & 0 \\ 0 & A_{N-1} & B_{N-1} & C_{N-1} \\ 0 & 0 & A_N & B_N \end{matrix}$$

Step ① Eliminate y_1 from row ② by subtracting row ① $\times \frac{A_2}{B_1}$

$$B_2' = B_2 - C_1 \times \frac{A_2}{B_1}$$

$$b_2' = b_2 - b_1 \times \frac{A_2}{B_1}$$

Step ② Eliminate y_2 from row ③ by subtracting row ①' $\times \frac{A_3}{B_2'}$

$$B_3' = B_3 - C_2 \times \frac{A_3}{B_2'}$$

$$b_3' = b_3 - b_2' \times \frac{A_3}{B_2'}$$

Step N) Eliminate y_{N-1} from row N by subtracting row (N-1)' $\times \frac{A_N}{B_{N-1}'}$

$$B_N' = B_N - C_{N-1} \times \frac{A_N}{B_{N-1}'}$$

$$b_N' = b_N - b_{N-1}' \times \frac{A_N}{B_{N-1}'}$$

Eq 1

(Eq, 1) gives

$$\therefore B_N' y_n = b_n'$$

$$y_n = \frac{b_n'}{B_N'}$$

and then one can get y for $k = N-1, \dots$ and 1.

$$y_k = \frac{b_k' - c_k y_{k+1}}{B_k'}$$

~~Note~~ Original B and b changes here, while C is same!

One can work the algorithm on solve

non-linear system

L + - 10 4

Non linear second order BVP

$$y'' = f(x, y); \quad a < x < b$$

$$y(a) = \gamma_1, \quad y(b) = \gamma_2$$

If one discretize, one can get

$$\frac{y_{i+1} - 2y_i + y_{i-1}}{h^2} = f(x_i, y_i)$$

$$\underbrace{y_{i+1} - 2y_i + y_{i-1}}_{\text{LHS linear}} = \underbrace{h^2 f(x_i, y_i)}_{\text{RHS non linear}} \quad \text{(NL a)}$$

LHS linear

$$y_0 = \gamma_1, \quad y_{N+1} = \gamma_2$$

Let see an example to understand

$$y'' = x y^2 + x; \quad y(-1) = 2$$

$$h = 1$$

$$y(3) = -1$$

Using NLa

$$y_{i-1} - 2y_i + y_{i+1} = (x_i y_i^2 + x_i) h^2$$

$$y_{i-1} - 2y_i + y_{i+1} = x_i y_i^2 + x_i$$

$$\begin{aligned} i=1 \quad y_0 - 2y_1 + 2y_2 &= x_1 y_1^2 + x_1 \\ &= 0 \end{aligned}$$

$$i=2 \quad y_1 - 2y_2 + 2y_3 = y_2^2 + 1$$

$$i=3 \quad y_2 - 2y_3 + 2y_4 = y_3^2 + 2$$

Now y_0 & y_4 are known

$$\Rightarrow -2y_1 + y_2 + 2 = 0$$

$$y_1 - 2y_2 + y_3 - y_2^2 - 1 = 0$$

$$y_2 - 2y_3 - 2y_3^2 - 3 = 0$$

Not easy to put as $Ax = B$ matrix form, due to it non-linear form.

$$F(\bar{y}) = 0$$

$$\begin{pmatrix} F_1(\bar{y}) \\ F_2(\bar{y}) \\ F_3(\bar{y}) \end{pmatrix} = \begin{pmatrix} -2y_1 + y_2 + 2 \\ y_1 - 2y_2 + y_3 - y_2^2 - 1 \\ y_2 - 2y_3 - 2y_3^2 - 3 \end{pmatrix} \quad \textcircled{A}$$

\textcircled{A} is non-linear system of $= 0$ for y_1, y_2, y_3 .

How one can solve the?

Newton Raphson method?

$$\hat{F}(\bar{y}) = 0$$

Suppose we expand in Taylor series about \bar{y}_i

$$\hat{F}(\bar{y}) = \hat{F}(\bar{y}_i) + (\bar{y} - \bar{y}_i) \frac{\partial \hat{F}}{\partial \bar{y}} + \left(\frac{(\bar{y} - \bar{y}_i)^2}{2!} \right) \frac{\partial^2 \hat{F}}{\partial \bar{y}^2} + \dots$$

$$= \hat{F}(\bar{y}_i) + (\bar{y} - \bar{y}_i) \frac{\partial \hat{F}}{\partial \bar{y}} + O(h^2) \approx 0$$

~~$$\bar{y} = \bar{y}_i - \left(\frac{\partial \hat{F}}{\partial \bar{y}} \right)^{-1} \hat{F}(\bar{y}_i)$$~~

$$\bar{y} = \bar{y}_i - \left(\frac{\partial \hat{F}}{\partial \bar{y}} \right)^{-1} \hat{F}(\bar{y}_i) \quad \text{Jacobian}$$

Hence an iterative process

$$\bar{y}^{(k+1)} = \bar{y}^{(k)} - J^{-1}(\bar{y}^{(k)}) \bar{F}(\bar{y}^{(k)})$$

where $J(y_1, \dots, y_p) = \frac{\partial \bar{F}}{\partial \bar{y}}$ Jacobian matrix.

$$J = \begin{pmatrix} \frac{\partial f}{\partial y_1}, & \dots, & \frac{\partial f}{\partial y_p} \\ \vdots & \ddots & \vdots \end{pmatrix}$$

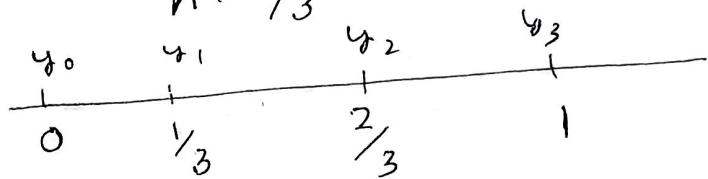
An example

$$y'' = 9y^2 + \frac{1}{x}$$

$$y(0) = 4; \quad y(1) = 1$$

$$h = \frac{1}{3}$$

$$\cancel{y_0 = 0}$$



Discretization

$$y_{i+1} - 2y_i + y_{i-1} = h^2 \left[9y_i^2 + \frac{1}{xi} \right]$$

$$y_0 = 4; \quad y_3 = 1$$

$$i=1 \quad y_0 - 2y_1 + y_2 = \left(\frac{1}{3}\right)^2 \left[9y_1^2 + \frac{1}{(1/3)^2} \right]$$

$$y_0 - 2y_1 + y_2 = y_1^2 + 1 \quad \underbrace{y_0 = 4}_{\cancel{y_0 = 4}}$$

$$i=2 \quad y_1 - 2y_2 + y_3 = \left(\frac{1}{3}\right)^2 \left[9y_2^2 + \frac{1}{(2/3)^2} \right] \quad y_3 = 1$$

$$= y_2^2 + \frac{1}{4}$$

Simplifies to

$$y_1^2 + 2y_1 - y_2 - 3 = 0 \quad (F_1)$$

$$y_2^2 - y_1 + 2y_2 - \frac{3}{4} = 0 \quad (F_2)$$

Compute Jacobian

$$J(y_1, y_2) = \frac{\partial \bar{F}}{\partial r} = \begin{pmatrix} \frac{\partial F_1}{\partial y_1} & \frac{\partial F_1}{\partial y_2} \\ \frac{\partial F_2}{\partial y_1} & \frac{\partial F_2}{\partial y_2} \end{pmatrix}$$

$$= \begin{pmatrix} 2y_1 + 2 & -1 \\ -1 & 2y_2 + 2 \end{pmatrix}$$

Then one need to compute J^{-1}

$$J^{-1} = \frac{1}{D} \begin{pmatrix} 1 & \\ & 2y_1 + 2 \\ & & 1 \\ & & & 2y_2 + 2 \end{pmatrix}$$

$$D = (2y_1 + 2)(2y_2 + 2) - 1$$

$$= 4(1+y_1)(1+y_2) - 1$$

50



$$\therefore \begin{pmatrix} y_1^{(k+1)} \\ y_2^{(k+1)} \end{pmatrix} = \begin{pmatrix} y_1^{(k)} \\ y_2^{(k)} \end{pmatrix} - \frac{1}{4(1+y_1)(1+y_2)-1} \begin{pmatrix} 2y_2^{(k)} + 2 & 1 \\ 1 & 2y_2^{(k)} + 2 \end{pmatrix}$$

One need initial guess to start the iteration

L7-(10) a

Let $y_1^{(0)} = 2$ and $y_2^{(0)} = 1$

one can get $y_1^{(1)}$ and $y_2^{(1)}$ using JD

Then $y_1^{(2)}, y_2^{(2)}$

and soon till one gets the desired accuracy.

BVPs → derivative Boundary condition

General frame work

Consider $y'' + p(x)y' + q(x)y = r(x)$ — (1)
 $a < x < b$

$$\begin{aligned} a_0 y(a) - a_1 y'(a) &= \gamma_1 \\ b_0 y(b) + b_1 y'(b) &= \gamma_2 \end{aligned} \quad \left. \right\} - (2)$$

One can discretize (1) [L7-5 b] — (3)

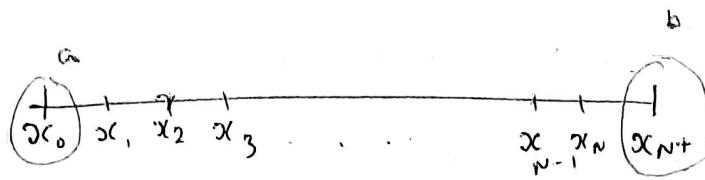
$$A_i y_{i-1} + B_i y_i + C_i y_{i+1} = h^2 r_i \quad i = 1, 2, \dots, N$$

where

$$A_i = \left(1 - \frac{h}{2} p_i\right)$$

$$B_i = \left(-2 + h^2 q_i\right)$$

$$C_i = \left(1 + \frac{h}{2} p_i\right)$$



There is total of $(N+2)$ unknown with N equations

One still has not used L.H. Boundary condition

y_0, y_{N+1}
are not available due
to derivative b.c.

$$\text{As } y_i' \approx \frac{y_{i+1} - y_{i-1}}{2h} + O(h^2)$$

$$\text{at } x_0: \frac{y_1 - y_{-1}}{2h}$$

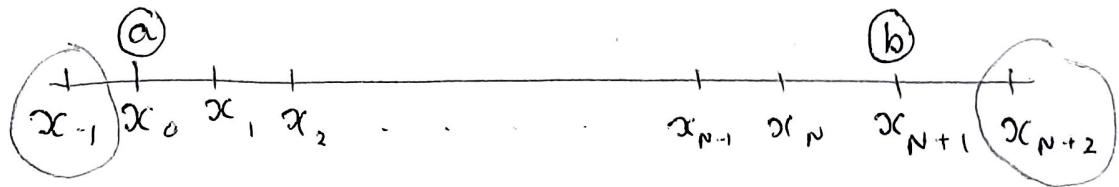
$$\Rightarrow a_0 y(a) - a_1 y'(a) = \gamma_1$$

$$a_0 y_0 - a_1 \left(\frac{y_1 - y_{-1}}{2h} \right) = \gamma_1 \quad \text{--- (4)}$$

$$\text{at } x_N = x_{N+1}, \quad y'_{N+1} = \frac{y_{N+2} - y_N}{2h} + O(h^2)$$

$$b_0 y(b) + b_1 y'(b) = \gamma_2$$

$$b_0 y_{N+1} + b_1 \left(\frac{y_{N+2} - y_N}{2h} \right) = \gamma_2 \quad \text{--- (5)}$$



(4) and (5) involve y_{-1} and y_{N+2} terms which corresponds to nodes outside the interval $[a, b]$

y_{-1} and y_{N+2} are called fictitious values

One can express these fictitious values as

$$y_{-1} = \frac{2h}{a_1} \gamma_1 + y_1 - \frac{2h}{a_1} a_0 y_0 \quad \rightarrow \boxed{\text{FVs}}$$

$$y_{N+2} = y_N - \frac{2h}{b_1} b_0 y_{N+1} + \frac{2h}{b_1} \gamma_2$$

Unless one don't get rid of y_{-1} and y_{N+2} , one will not end up with $\boxed{N+2} = \text{rhs}$

Eliminating the fictitious value L7-10a

Assume the discretized = ③ holds for $i=0, N+1$

i.e. at the boundary points x₀ and x_{N+1}

\therefore at $i=0$

$$A_0 y_{-1} + B_0 y_0 + C_0 y_1 = h^2 r_0$$

From FVs

$$A_0 \left[\frac{2h}{a_1} \gamma_1 + y_1 - \frac{2h}{a_1} a_0 y_0 \right] + B_0 y_0 + C_0 y_1 = h^2 r_0.$$

FV-0

$$\left(B_0 - \frac{2h a_0 A_0}{a_1} \right) y_0 + (A_0 + C_0) y_1 = h^2 r_0 - \frac{2h}{a_1} \gamma_1 A_0.$$

for $i=N+1$

$$A_{N+1} y_{N+2} + B_{N+1} y_{N+1} + C_{N+1} y_{N+2} = h^2 r_{N+1}$$

From FVs

$$A_{N+1} y_N + B_{N+1} y_{N+1} + C_{N+1} \left[y_N - 2h \frac{b_0}{b_1} y_{N+1} + \frac{2h}{b_1} \gamma_2 \right] = h^2 r_{N+1}$$

$$(A_{N+1} + C_{N+1}) y_N + \left(B_{N+1} - 2h \frac{b_0}{b_1} C_{N+1} \right) y_{N+1} = h^2 r_{N+1} - \frac{2h}{b_1} \gamma_2 C_{N+1}$$

FV-N+1

Using ③ L7-10a, FV-0 and FV-N+1

one get a tri diagonal system

$$\begin{matrix} B_0 - \frac{2h\alpha_0}{a_1} A_0 & A_0 + C_0 & 0 & 0 & 0 \\ A_1 & B_1 & C_1 & 0 & 0 \\ 0 & A_2 & B_2 & C_2 & 0 \\ 0 & 0 & A_3 & B_3 & C_3 \\ & & & \ddots & \end{matrix}$$

$$\begin{matrix} A_{N-1} & B_{N-1} & C_{N-1} & 0 \\ 0 & A_N & B_N & C_N \\ 0 & 0 & A_{N+1} + C_{N+1} & B_{N+1} - \frac{2h\alpha_0}{b_1} C_{N+1} \end{matrix}$$

One get a bai diagonal system

$$\bar{y} = (y_0, y_1, \dots, y_n, y_{n+1})^T$$

$$\left(h^2 \alpha_0 - \frac{2h\gamma_1}{a_1} A_0, h^2 \alpha_1, h^2 \alpha_2, \dots, h^2 \alpha_n, h^2 \alpha_{n+1} - \frac{2h\gamma_2}{b_1} C_{n+1} \right)^T$$

One can solve it

For the derivative Boundary condition

→ One get also the end point (y_0, y_{n+2}) fictitious value to evaluate

→ One simply eliminated them by discretization

→ Since $N+2 = n.s.$ with $N+2$ unknowns

Example Set up FDM for the BVP

$$y''(x) = -4(y - x) \quad y(0) = 1 \\ y(1) = 2$$

Uniform grid

$$x_i = i h; \quad h = \frac{1}{m}$$

$$\frac{1}{h^2} (y_{i-1} - 2y_i + y_{i+1}) = -4y_i + 4x_i$$

$$i=1 \quad y_0 + (4h^2 - 2)y_1 + y_2 = 4h^2 x_1$$

$$i=1 \quad \begin{matrix} y_0 \\ 1 \end{matrix} + (4h^2 - 2)y_1 + y_2 = 4h^2 x_1$$

$$(4h^2 - 2)y_1 + y_2 = 4h^2 x_1 - 1$$

$$i=2 \quad y_1 + (4h^2 - 2)y_2 + y_3 = 4h^2 x_2$$

$$i=3 \quad y_2 + (4h^2 - 2)y_3 + y_4 = 4h^2 x_3$$

$$i=N-1 \quad y_{n-2} + (4h^2 - 2)y_{n-1} + y_n = 4h^2 x_{n-1}$$

$$i=N \quad y_{n-1} + (4h^2 - 2)y_n + \begin{matrix} 2 \\ y_{n+1} \end{matrix} = 4h^2 x_n$$

$$y_{n-1} + (4h^2 - 2)y_n = 4h^2 x_{n-2}$$

$$\begin{pmatrix} 4h^2 - 2 & 1 & 0 & 0 & 0 \\ 1 & 4h^2 - 2 & 1 & 0 & 0 \\ 0 & 1 & 4h^2 - 2 & 1 & 0 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix} = \begin{pmatrix} 4h^2 x_1 - 1 \\ 4h^2 x_2 \\ 4h^2 x_3 \\ \vdots \\ 4h^2 x_{n-1} \end{pmatrix}$$

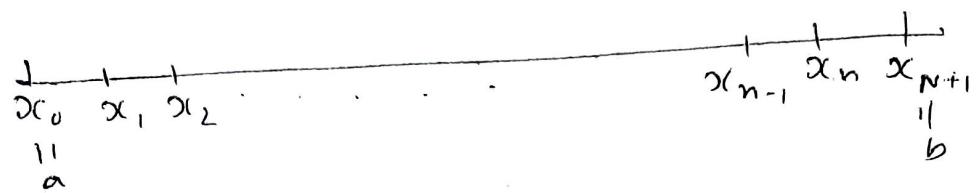
Higher order BVPs

General case

Consider the third order linear $y''' = n$

$$y''' + A(x)y'' + B(x)y' + C(x)y = D(x) \quad (1)$$

$$y(a) = \gamma_1, \quad ; \quad y'(a) = \alpha, \quad y'(b) = \beta \quad (2)$$



Approximate by difference

$$y'_i = \frac{y_{i+1} - y_{i-1}}{2h} \quad ; \quad y''_i = \frac{y_{i+1} - 2y_i + y_{i-1}}{h^2}$$

$$y'''_i = \frac{y_{i+2} - 2y_{i+1} + 2y_{i-1} - y_{i-2}}{2h^3}$$

(1) becomes

$$\frac{y_{i+2} - 2y_{i+1} + 2y_{i-1} - y_{i-2}}{2h^3} + A(x_i) \left[\frac{y_{i+1} - 2y_i + y_{i-1}}{h^2} \right]$$

$$+ B(x_i) \left[\frac{y_{i+1} - y_{i-1}}{2h} \right] + C(x_i)y_i = D(x_i)$$

$$y_{i+2} + \left[2hA(x_i) + h^2B(x_i) - 2 \right] y_{i+1} + \left[2h^3C(x_i) - 24hA(x_i) \right] y_i$$

$$+ \left[2 + 2hA(x_i) - h^2B(x_i) \right] y_{i-1} - y_{i-2} = \frac{2h^3}{3} D(x_i)$$

HBVP

b.c. $y(a) = \gamma_1$, $y'(a) = \alpha$, $y'(b) = \beta$

$$y_0 = \gamma_1, \frac{y_1 - y_0}{2h} = \alpha; \frac{y_{m+1} - y_{n-1}}{2h} = \beta$$

When one write **(HBVP)** at $i=0$

$$y_2 + [2hA_0 + h^2B_0 - 2]y_1 + [2h^3C_0 - 4hA_0]y_0 + \\ [2 + 2hA_0 - h^2B_0](y_{-1}) - (y_{-2}) = 2h^3D_0$$

\downarrow y_{-2}, y_{-1}
2 fictitious values

when $i=N$

$$(y_{N+2}) + [2hA_N + h^2B_N - 2](y_{N+1}) + [2h^3C_N - 4hA_N]y_N + \\ [2 + 2hA_N - h^2B_N]y_{N-1} - y_{N-2} = 2h^3D_N \approx$$

Another 2 fictitious values y_{N+1}, y_{N+2}

We get 4 fictitious values. However we have 3 = no from b.c.

~~Let~~ $y' = p$

$$p'' + A(x)p' + B(x)p + C(x)y = D(x)$$

$$y(a) = \alpha$$

$$p(a) = \beta$$

$$p(b) = \gamma$$

Discretize it

$$y' = p \Rightarrow \underline{y_i - y_{i-1}} \approx \frac{1}{2}(p_i + p_{i-1})$$

Average

AVP

$$\frac{p_{i-1} - 2p_i + p_{i+1}}{h^2} + A_i \left(\frac{p_{i+1} - p_{i-1}}{2h} \right) + B_i p_i + C_i y_i = D_i \quad \text{--- A}$$

Using RVP

$$y_{i-1} + \frac{h}{2} p_{i-1} - y_i + \frac{h}{2} p_i = 0 \quad \text{--- (A)}$$

$$a_i y_i + b_i p_{i-1} + c_i p_i + d_i p_{i+1} = h^2 D_i \quad \text{--- (B)}$$

$$\text{here } a_i = h^2 C_i$$

$$b_i = 1 - \frac{h}{2} A_i$$

$$C_i = h^2 B_i - 2$$

$$d_i = 1 + \frac{h}{2} A_i \quad \begin{matrix} y_0 = \gamma_1 \\ p_0 = \alpha \end{matrix}$$

Write (A) + (B)

$$i=1 \quad y_0 + \frac{h}{2} p_0 - y_1 + \frac{h}{2} p_1 = 0 \quad \text{--- (C)}$$

$$a_1 y_1 + b_1 p_0 + c_1 p_1 + d_1 p_2 = h^2 D_1 \quad \text{--- (D)}$$

$$\Rightarrow -y_1 + \frac{h}{2} p_1 = -\gamma_1 - \frac{h}{2} \alpha \quad \text{--- (E)}$$

$$a_1 y_1 + c_1 p_1 + d_1 p_2 = -b_1 \alpha + h^2 D_1 \quad \text{--- (F)}$$

$$i=2 \quad y_1 + \frac{h}{2} p_1 - y_2 + \frac{h}{2} p_2 = 0$$

$$a_2 y_2 + b_2 p_1 + c_2 p_2 + d_2 p_3 = h^2 D_2$$

Introducing

$$X_i = \begin{pmatrix} y_i \\ p_i \end{pmatrix} \quad ; \quad X_n = \begin{pmatrix} y_n \\ p_n \end{pmatrix}$$

Using (A) + (B)

$$A_i: X_{i-1} + B_i X_i + C_i X_{i+1} = D_i$$

$$X_i = \begin{pmatrix} y_i \\ p_i \end{pmatrix} \quad i = 2, 3, \dots, N-1$$

$$A_i = \begin{pmatrix} 1 & h/2 \\ 0 & b_i \end{pmatrix}$$

$$B_i = \begin{pmatrix} -1 & h/2 \\ a_i & c_i \end{pmatrix}$$

$$C_i = \begin{pmatrix} 0 & 0 \\ 0 & d_i \end{pmatrix}$$

$$D_i = \begin{pmatrix} 0 \\ n^2 D(x_i) \end{pmatrix} \quad D(u) \rightarrow \text{known function}$$

(E) + (F) in matrix form $i=1$

$$B_1 X_1 + C_1 X_2 = D_1$$

$$X_1 = \begin{pmatrix} y_1 \\ p_1 \end{pmatrix} \quad X_2 = \begin{pmatrix} y_2 \\ p_2 \end{pmatrix} \quad X_0 = \begin{pmatrix} y_0 \\ p_0 \end{pmatrix}$$

$$B_1 = \begin{pmatrix} -1 & h/2 \\ a_1 & c_1 \end{pmatrix}$$

$$C_1 = \begin{pmatrix} 0 & 0 \\ 0 & d_1 \end{pmatrix}$$

$$D_1 = \begin{pmatrix} -\alpha - h/2 \beta \\ -b_1 \beta + n^2 D(x_1) \end{pmatrix}$$

Now we have $i = 1, 2, \dots, N-1$

$(N-1) = n$ left with (1)

$i=1$

$$y_{N-1} + \frac{h}{2} p_{N-1} - y_N + \frac{h}{2} p_N = 0$$

$$a_N y_N + b_N p_{N-1} + c_N p_N + d_N p_{N+1} = h^2 D(x_N)$$

This can be put as

$$\text{as } p_N = \gamma$$

$$A_N X_{N-1} + B_N X_N = D_N$$

$$A_N = \begin{pmatrix} y & \frac{h}{2} p_2 \\ 0 & c_N \end{pmatrix} \quad B_N = \begin{pmatrix} -1 & 0 \\ a_N & d_N \end{pmatrix}$$

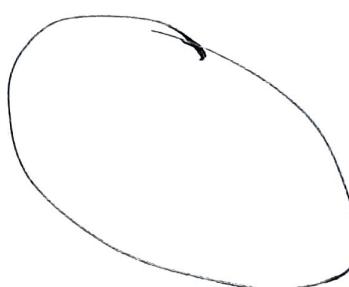
$$D_N = \begin{pmatrix} -\frac{\gamma}{2} h \\ h^2 D(x_N) - c_N \gamma \end{pmatrix}$$

$$X_N = \begin{pmatrix} y_N \\ p_{N+1} \end{pmatrix}$$

Now we have total $n=n$ for n unknown.

$$A X = D$$

$$A = \begin{matrix} & \left. \begin{matrix} B_1 & C_1 & 0 & 0 & 0 \end{matrix} \right. \\ \left. \begin{matrix} A_1 & & & & \end{matrix} \right. & \left. \begin{matrix} A_2 & B_2 & C_2 & 0 & 0 \\ 0 & A_3 & B_3 & C_3 & 0 \end{matrix} \right. \\ & \left. \begin{matrix} & & & & \end{matrix} \right. \end{matrix}$$



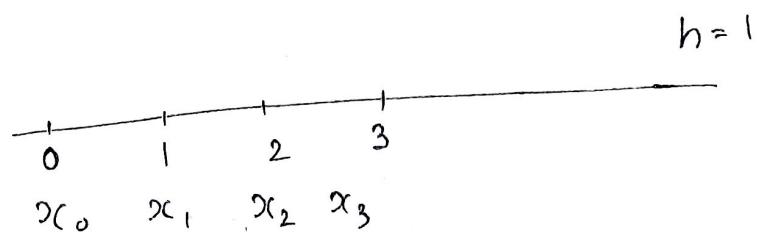
$$\begin{matrix} & & & & x_{n-1} \\ & & & & x_n \\ A_{N-1} & B_{N-1} & C_{N-1} & & \\ 0 & A_N & B_N & & x_n \end{matrix}$$

Block-Tri diagonal system

$$X = \begin{bmatrix} (y_1) \\ b_1 \\ (y_2) \\ b_2 \\ \vdots \\ (y_{N-1}) \\ p_{N-1} \end{bmatrix} \quad D = \begin{pmatrix} D_1 \\ D_2 \\ \vdots \\ \vdots \\ D_{N-1} \\ D_{N+1} \end{pmatrix}$$

Example $y''' + y = x$

B.C. : $y(0) = 1$; $y'(0) = 0$; $y'(3) = 1$



Useful discretization

$$y_{i+2} - 2y_{i+1} + 2y_i + 2y_{i-1} - y_{i-2} = x_i \quad \textcircled{1}$$

b.c. $y_0 = 1$
 $y_1 - y_{-1} = 0$
 $\frac{y_4 - y_2}{2} = 1$

\textcircled{1} at $i=1$

$$\underline{y_3 - 2y_2 + 2y_1 + 2y_0 - y_{-1} = x_1 = 1}$$

$$\stackrel{i=2}{=} y_4 - 2y_3 + 2y_2 + 2y_1 - y_0 = x_2 = 2$$

b.c. $\underline{y_0 = 1}$; $\underline{y_{-1} = y_1}$; $\underline{y_4 = 2 + y_2}$
 given

Given $\rightarrow y_1, y_2, y_3$ as unknowns

$$\begin{aligned} i=0 \quad & y_2 - 2y_1 + 2y_0 + 2y_{-1} - \boxed{y_{-2}} = x_0 = 0 \\ i=3 \quad & \boxed{y_5} - 2y_4 + 2y_3 + 2y_2 - y_1 = x_3 = 3 \end{aligned}$$

$\square \rightarrow$ new fictitious

$y_1, y_2, y_3, y_{-2}, y_5 \rightarrow 5$ unknowns.

and $y = w$

$$y = p, y(0) = 1$$

$$p' + y = x; \quad p(0) = 0 \quad p(1) = 1$$

$$2y_{i-1} + p_{i-1} - 2y_i + p_i = 0 \quad \text{--- (A)}$$

$$y_i + p_{i-1} - 2p_i + p_{i+1} = x_i \quad \text{--- (B)}$$

$$\underline{i=1} \quad \text{(A)} \Rightarrow 2y_1 - p_1 = 2$$

$$\text{(B)} \Rightarrow y_1 - 2p_1 + p_2 = 1$$

(A), (B)

$$\text{for } i=2 \\ A_i x_{i-1} + B_i x_i + C_i x_{i+1} = D_i$$

$$\begin{pmatrix} -2 & 1 \\ 1 & -2 \end{pmatrix} \begin{pmatrix} y_1 \\ p_1 \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} y_2 \\ p_2 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} 2 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} y_2 \\ p_2 \end{pmatrix} + \begin{pmatrix} -2 & 0 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} y_3 \\ p_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 5 \end{pmatrix}$$

Tridiagonal system to solve

$$\left(\begin{array}{cc|c} (-2 & 1) & (0 & 0) & 0 \\ 1 & -2 & 0 & 1 \\ \hline 0 & 0 & (2 & 1) & (-2 & 0) \end{array} \right) \xrightarrow{\text{Row operations}} \left(\begin{array}{cc|c} (1 & 0) & (y_1) \\ (0 & 1) & (y_2) \\ \hline 0 & 0 & (0 & 5) \end{array} \right) \xrightarrow{\text{Solve}} \left(\begin{array}{c} (1) \\ (0) \\ (5) \\ (1) \end{array} \right)$$