



I²C implementation: Accessing the 24LC01 Serial EEPROM

Introduction

This application note presents programming techniques for reading from and writing to a serial EEPROM using I²C data transfer protocol. This implementation uses the Parallax demo board and takes advantage of their *SX demo* software's UART and user interface features to allow simple access to the EEPROM contents.

Additions to the Parallax SX Demo interface

Three new commands have been added to the SX demo UART interface to access the EEPROM, as follows:

- 1) Sample: (a) **S** - sample the analog to digital converter ADC1 and store it in current memory address
(b) **S xx** - put the hex value **xx** into current memory address
- 2) View: (a) **V** - display all currently stored values
(b) **V xx** - display the value at hex memory address **xx**
(c) **V FF** - display all of the EEPROM contents
- 3) Erase: **E** - write zeroes to the entire EEPROM

How the circuit and program work

Thanks to the basic hardware requirements of the I²C protocol, the circuit is very simple, using only two port pins (PortA pins 0 and 1) of the SX to provide serial access to the 24LC01 EEPROM. PortA.0 functions as the serial data clock *SCL* which provides the timing reference for data transfer to and from the EEPROM, and PortA bit 1 is *SDA*, the actual data bit stream. As on the demo board, a 10K¹ pull-up resistor should be connected from the *SDA*² pin to *V_{dd}* since the EEPROM's data port is open-collector.

The two main functions of the program are to read to and write from the EEPROM. Data transfers to and from the 24LC01 are composed of 8 bit data bytes which can be read/written in a random access format (i.e. one byte at a time) or in a sequential³ format, the latter not being implemented here.

To write to the 24LC01 in random access mode, the SX must initiate the write operation by sending the EEPROM a 'START' signal, followed by a control byte 10100000b (which identifies the 24LC01 as the device to be accessed and signals that the operation to be performed is a write), followed by the address where the byte is to be written to, followed by the data byte to be written, followed by a STOP signal. It should be noted that after each byte of this sequence is sent, the program toggles the I/O status of the *SDA* line to read an acknowledge signal (that a byte has been received) from the EEPROM. Both the write and read sequences, as implemented here, use *acknowledge polling*. This technique sends a repeating control byte query to the EEPROM until a valid

¹A value of 10K is sufficient for the data transfer rate used here. For faster rates, the pull-up may need to be reduced in order to allow successful operation. If speed is not an important issue, the external pull-up may be eliminated entirely by increasing the *t_{all}* bus timing delay and using the SX's internal pull-up resistor feature (see SX data sheet for programming details) on the *SDA* port pin.

²No pull-up is needed for the *SCL* line since it is always driven high or low by the SX

³The maximum number of bytes allowed during a sequential write is 8 for the 24LC01, though sequential reads have no byte count limit.

acknowledge (ACK) signal is received, before sending the address byte and then writing or reading the data byte. This is done because the EEPROM enters into an internal write cycle after each write operation, and cannot be accessed until the preceeding write process is complete, which for the 24LC01 is on the order of 10 msec. Thus by using acknowledge polling, subsequent write or read operations are executed as soon as possible after a preceeding write.

To read from the 24LC01 in random access mode, the procedure is essentially identical to the write process except that after the initial control byte and address byte have been sent and an ACK received, a new START signal is then sent followed by a read control byte (10100001b). The SDA line is then switched to an input, and data is clocked in from the EEPROM instead of sent out. The procedure is signaled as complete, as during a write, by generating a final STOP signal.

A START signal is generated by toggling the SDA line from high to low (creating a falling edge) while the SCL line is held high. A STOP signal is generated in the same manner except that SDA is toggled from low to high, thus creating a rising edge. An ACK signal is received after 8 control, address or data bits have been sent, and is considered valid if the SDA line is held low during the following (i.e. the 9th) SCL toggle cycle.

During all operations, the timing between changes in the SCL and SDA lines is a crucial factor. In this case, a generic delay time has been selected for all required START, STOP, data I/O, and ACK delays. As given, the program is capable of reading the EEPROM at approximately 200kbps⁴ with the SX in turbo mode.

When calling the *I2C_write* and *I2C_read* subroutines, the program register bank must be set to the *I2C* bank. For random access mode, the address of the byte to be written/read must be pre-loaded into the *address*⁵ program register, and the sequential flag *seq_flag* must be set to low. For writes, the byte to be written must be also be pre-loaded into the *data* program register, and for reads, the *data* program register will contain the value received from the EEPROM upon completion of the read procedure.

Modifications and further options

To optimize access speed to the 24LC01, the specific event and signal timings should be taken from the 24LC01 data sheet, and the appropriate reduced delay values inserted into the various bit operation subroutines. The *Bus_delay* subroutine can be accessed to produce a customized delay by loading the W register with the delay value and then calling *Bus_delay:custom*. In turbo mode each custom call will cause the following timing delay: $delay [usec] = 1/xtal[MHz] * (6 + 4 * (W-1))$, where *xtal* is the oscillator frequency in MHz and *W* is the value pre-loaded into the W register. For example, a value in *W*=62 will cause a 5 usec delay at 50 MHz.

Performing sequential writes and reads will also speed up the rate at which the 24LC01 can be accessed, and especially significantly increase the rate at which the 24LC01 can be written (since up to 8 bytes can be written simultaneously, reducing the need for separate internal EEPROM write delays).

To perform a **sequential write**, a specific series of steps must be followed. First the sequential flag *seq_flag* must be set high. The first byte to be written is then written as usual, but the following bytes (up to 7 more) are written by calling the write routine at the *I2C_write:sequential* entry point. Take note that *seq_flag* must be reset to low before the final byte of the group is sent, though the entry point called to write this final byte is still *I2C_write:sequential*. This generates the required stop bit to initiate the EEPROM write sequence.

To perform a **sequential read**, a similar series of steps must be followed. First the sequential flag *seq_flag* must be set high. The first byte to be read is read as usual, but the following bytes (up to the length of

⁴Since this implementation of the I2C access is coupled with a with a program that uses the SX's internal RTCC interrupt, the actual timing of the EEPROM access will vary per read/write, depending on how often interrupts occur during the read/write sequence.

⁵Take care to set the appropriate register bank, if needed.

the EEPROM⁶) are read by calling the read routine at the *I2C_read:sequential* entry point. Take note that *seq_flag* must be reset to low before the final byte of the group is read, though the entry point called to read this final byte is still *I2C_read:sequential*. This generates the required stop signal to end the sequential read operation.

After any write/read operation, the internal address pointer of the EEPROM is set to the byte following the last byte written or read. To read this next byte without using sequential mode, the program may call the read subroutine at the *I2C_read:current* entry point. This provides a slight increase in speed over the normal random access point and also eliminates the need to pre-load the *address* register before the call.

⁶In practise, the length of sequential reads can be infinite and the address pointer will simply loop around to zero after the end of the EEPROM has been reached. This can be useful for implementing wave tables and similar repeating-loop data.

Program Listing

```
;
; Device
;
;               device      pins28,pages2,banks8,oschs
;               device      turbo,stackx,optionx
;               id          'I2C demo'
;               reset       reset_entry
;
;
; Equates
;
rx_pin          =          ra.2
tx_pin          =          ra.3
led_pin         =          rb.6
spkr_pin        =          rb.7
pwm0_pin        =          rc.0
pwm1_pin        =          rc.2
adc0_out_pin    =          rc.4
adc0_in_pin     =          rc.5
adc1_out_pin    =          rc.6
adc1_in_pin     =          rc.7
;
;
; Variables
;
;               org        8

temp            ds         1
byte            ds         1
cmd             ds         1
number_low      ds         1
number_high     ds         1
hex             ds         1
string          ds         1
;
;***** Variables Added *****
;
flags           EQU        0fh                      ;program flags register
;
;               org        70H                      ;I2C bank
I2C             EQU        $                          ;
;
data            DS         1                        ;data byte from/for R/W
address         DS         1                        ;byte address
count           DS         1                        ;bit count for R/W
delay           DS         1                        ;timing delay for write cycle
byte_count      DS         1                        ;number of bytes in R/W
num_bytes       DS         1                        ;number of byte to view at once
save_addr       DS         1                        ;backup location for address
;
scl             EQU        RA.0                      ;I2C clock
sda             EQU        RA.1                      ;I2C data I/O
```

```

in_bit      EQU      byte.0           ;bit to receive on I2C
out_bit     EQU      byte.7           ;bit to transmit on I2C
seq_flag    EQU      flags.0          ;R/W mode (if sequential=1)
got_hex     EQU      flags.1          ;flags hex value after command
got_ack     EQU      flags.2          ;flags if we got ack signal
erasing     EQU      flags.3          ;high while erasing eeprom
;
control_r   =        10100001b        ;control byte: read E2PROM
control_w   =        10100000b        ;control byte: write E2PROM
portsetup_r =        00000110b        ;Port A config: read bit
portsetup_w =        00000100b        ;Port A config: write bit
eeprom_size =        128              ;storage space of EEPROM
;
t_all       =        31                ;bit cycle delay (62=5 usec)
;*****

                org      0

                org      10h           ;bank0 variables

timers        =        $

timer_low     ds        1              ;timer
timer_high    ds        1
timer_accl    ds        1
timer_acch    ds        1

freq_low      ds        1              ;freq
freq_high     ds        1
freq_accl     ds        1
freq_acch     ds        1

                org      30h           ;bank1 variables

analog        =        $

port_buff     ds        1              ;buffer - used by all

pwm0          ds        1              ;pwm0
pwm0_acc       ds        1

pwm1          ds        1              ;pwm1
pwm1_acc       ds        1

adc0          ds        1              ;adc0
adc0_count     ds        1
adc0_acc       ds        1

adc1          ds        1              ;adc1
adc1_count     ds        1
adc1_acc       ds        1

                org      50h           ;bank2 variables

```

```

serial      =      $

tx_high     ds      1                      ;tx
tx_low      ds      1
tx_count    ds      1
tx_divide   ds      1

rx_count    ds      1                      ;rx
rx_divide   ds      1
rx_byte     ds      1
rx_flag     ds      1

            org      0

;
;
; Interrupt routine - virtual peripherals
;
interrupt    bank    timers                      ;1

            clc                        ;1      ;timer
            add      timer_accl,timer_low      ;2
            addb     timer_acch,c              ;2
            add      timer_acch,timer_high     ;2
:toggle_LED  movb     led_pin,timer_acch.7      ;4 =11

            clc                        ;1      ;freq
            add      freq_accl,freq_low        ;2
            addb     freq_acch,c              ;2
            add      freq_acch,freq_high       ;2
            movb     spkr_pin,freq_acch.7      ;4 =11

            bank     analog                ;1

            clr      port_buff              ;1

            add      pwm0_acc,pwm0            ;2      ;pwm0
            snc                        ;1
            setb     port_buff.0              ;1 =4

            add      pwm1_acc,pwm1            ;2      ;pwm1
            snc                        ;1
            setb     port_buff.2              ;1 =4

            mov      w,>>rc                  ;1      ;adc0/adc1
            not      w                        ;1      ;complement inputs to

outputs

            and      w,#%01010000            ;1
            or       port_buff,w              ;1 =4

            mov      rc,port_buff              ;2 =2 ;update port pins

            sb       port_buff.4              ;1      ;adc0
            inc      adc0_acc                  ;1      ;if was high, inc acc
            mov      w,adc0_acc                ;1      ;get acc into w
            inc      adc0_count                ;1      ;done?

```

```

snz                                ;1    ;if so, update adc0
mov      adc0,w                    ;1
snz                                ;1    ;if so, reset acc
clr      adc0_acc                  ;1 =8

sb      port_buff.6                ;1    ;adc1
inc      adc1_acc                  ;1    ;if was high, inc acc
mov      w,adc1_acc                ;1    ;get acc into w
inc      adc1_count                ;1    ;done?
snz                                ;1    ;if so, update adc1
mov      adc1,w                    ;1
snz                                ;1    ;if so, reset acc
clr      adc1_acc                  ;1 =8

bank    serial                     ;1

time
clrb     tx_divide.4                ;1    ;serial transmit
inc      tx_divide                 ;1    ;only execute every 16th

mov      w,tx_divide                ;1
and      w,#$10                    ;1
sz                                ;1
test     tx_count                  ;1    ;busy?
clc                                ;1    ;ready stop bit
sz                                ;1    ;if busy, shift bits
rr      tx_high                    ;1
sz                                ;1
rr      tx_low                     ;1
sz                                ;1    ;if busy, dec counter
dec      tx_count                  ;1
movb     tx_pin,/tx_low.6           ;4 =17    ;output next bit

movb     c,rx_pin                   ;4    ;serial receive
test     rx_count                  ;1    ;waiting for stop bit?
jnz      :rxbit                    ;3,2    ;if not, :bit
mov      w,#9                      ;1    ;in case start, ready 9

bits
sc                                ;1    ;if start, set rx_count
mov      rx_count,w                ;1
mov      rx_divide,#16+8+1          ;2    ;ready 1.5 bit periods
:djnz     rx_divide,:rxdone          ;3,2    ;8th time through?
setb     rx_divide.4                ;1    ;yes, ready 1 bit period
dec      rx_count                  ;1    ;last bit?
sz                                ;1    ;if not, save bit
rr      rx_byte                    ;1
snz                                ;1    ;if so, set flag
setb     rx_flag                    ;1 =20

:rxdone
;****Changed****
mov      w,#-167                    ;1    ;interrupt every 164

clocks
;*****
retiw                                ;3
;
;
```

```

; Data
;
_hello      dw      13,10,13,10,'SX Virtual Peripheral Demo'
_cr         DW      13,10,0
_prompt     dw      13,10,'>',0
_error      dw      'Error!',13,10,0
_hex        dw      '0123456789ABCDEF'
;
;*****Added*****
_space      DW      ' ',0
_sample     DW      13,10,'Sample=',0
_view       DW      13,10,'Bytes stored:',0
;*****
;
;*****
;* Subroutines *
;*****
;
;
; Get byte via serial port
;
get_byte     jnb     rx_flag,$
             clr     rx_flag
             mov     byte,rx_byte           ;followed by send_byte
;
;
; Send byte via serial port
;
send_byte    bank    serial

:wait        test    tx_count              ;wait for not busy
             jnz     :wait

             not     w                     ;ready bits
             mov     tx_high,w
             setb     tx_low.7

             mov     tx_count,#10          ;1 start + 8 data + 1 stop bit

             RETP                          ;leave and fix page bits
;
;
; Send hex byte (2 digits)
;
send_hex      mov     w,#13                ;send cr lf
             call    send_byte
             mov     w,#10
             call    send_byte

:num_only     mov     w,<>number_low        ;send first digit
             call    :digit

             mov     w,number_low          ;send second digit

:digit        and     w,#$F                ;read hex chr

```



```

        mov     temp,w
        mov     w,#_hex
        clc
        add     w,temp
        mov     m,#0
        iread
        mov     m,$F

        jmp     send_byte                ;send hex chr
;
;
; Send string at w
;
send_string  mov     string,w            ;send string at w
:loop        mov     w,string            ;read chr at w
            mov     m,#0
            iread
            mov     m,$F

            test    w                    ;if 0, exit
            snz
            RETP                          ;leave and fix page bits

            call    send_byte            ;not 0, send chr

            inc     string                ;next chr
            jmp     :loop
;
;
; Make byte uppercase
;
uppercase    csae     byte,#'a'
            ret

            sub     byte,#'a'-'A'
            RETP                          ;leave and fix page bits
;
;
; Get hex number
;
get_hex      clr     number_low          ;reset number
            clr     number_high
;*****Added*****
            CLRB     got_hex              ;reset hex value flag
;*****
:loop        call    get_byte            ;get digit
            cje     byte,#' ',:loop      ;ignore spaces

            mov     w,<>byte              ;get <>byte into hex
            mov     hex,w

            cjb     byte,#'0',:done      ;if below '0', done
            cjbe    byte,#'9',:got       ;if '0'-'9', got hex digit

```

```

        call    uppercase                ;make byte uppercase
        cjb     byte, #'A', :done        ;if below 'A', done
        cja     byte, #'F', :done        ;if above 'F', done
        add     hex, #\$90               ;'A'-'F', adjust hex digit

:got      mov     temp, #4                ;shift digit into number
:shift    rl      hex
          rl      number_low
          rl      number_high
          djnz    temp, :shift
;*****Added*****
          SETB    got_hex                ;flag that we got a value
;*****
          jmp     :loop                  ;next digit

:cr        call   get_byte                ;wait for cr
:done      cjne   byte, #13, :cr

          RETP                          ;leave and fix page bits
;
;
;
;***** I2C Subroutines *****
;
; These routines write/read data to/from the 24LCxx EEPROM at a rate of approx.
; 200kHz. For faster* reads (up to 400 kHz max), read, write, start and stop
; bit cycles and time between each bus access must be individually tailored
; using the CALL Bus_delay: custom entry point with appropriate values in the W
; register - in turbo mode: delay[usec] = 1/xtal[MHz] * (6 + 4 * (W-1)).
; Acknowledge polling is used to reduce delays between successive operations
; where the first of the two is a write operation. In this case, the speed
; is limited by the EEPROM's storage time.
;
; Note: These subroutines are in the 2nd memory page, so appropriate care
; should be used for accessing them ion regards to setting page select bits.
          ORG     200h
;
;
;***** Subroutine(s) : Write to I2C EEPROM
; These routines write a byte to the 24LCxxB EEPROM. Before calling this
; subroutine, the address and data registers should be loaded accordingly. The
; sequential mode flag should be clear for normal byte writing operation.
; To write in page mode, please see application note.
;
; Input variable(s) : data, address, seq_flag
; Output variable(s) : none
; Variable(s) affected : byte, temp, count, delay
; Flag(s) affected : none
; Timing (turbo) : approx. 200 Kbps write rate
;                  approx. 10 msec between successive writes
;
I2C_write  CALL    Set_address            ;write address to slave
:page_mode MOV     W, data                ;get byte to be sent
          CALL    Write_byte             ;Send data byte

```

```

        JB      seq_flag,:done          ;is this a page write?
        CALL    Send_stop              ;no, signal stop condition
:done    RETP                          ;leave and fix page bits
;
Set_address CALL    Send_start          ;send start bit
        MOV     W,#control_w          ;get write control byte
        CALL    Write_byte            ;Write it & use ack polling
        JNB     got_ack,Set_address    ; until EEPROM ready
        MOV     W,address             ;get EEPROM address pointer
        CALL    Write_byte            ; and send it
        RETP                          ;leave and fix page bits
;
Write_byte MOV     byte,W              ;store byte to send
        MOV     count,#8              ;set up to write 8 bits
:next_bit CALL    Write_bit            ;write next bit
        RL      byte                 ;shift over to next bit
        DJNZ    count,:next_bit       ;whole byte written yet?
        CALL    Read_bit              ;yes, get acknowledge bit
        SETB    got_ack               ;assume we got it
        SNB     in_bit                ;did we get ack (low=yes)?
        CLRB    got_ack               ;if not, flag it
;
; to use the LED as a 'no_ack' signal, the ':toggle_led' line in the interrupt
; section must be commented out, and the next 3 instructions uncommented.
;         CLRB    led_pin              ;default: LED off
;         SNB     in_bit                ;did we get ack (low=yes)?
;         SETB    led_pin              ; if not, flag it with LED
;
        RETP                          ;leave and fix page bits
;
Write_bit  MOVVB   sda,out_bit          ;put tx bit on data line
        MOV     !ra,#portsetup_w      ;set Port A up to write
        JMP     :delay1                ;100ns data setup delay
:delay1    JMP     :delay2              ; (note: 250ns at low power)
:delay2    SETB    scl                 ;flip I2C clock to high
;         MOV     W,#t_high             ;get write cycle timing*
        CALL    Bus_delay              ;do delay while bus settles
        CLRB    scl                   ;return I2C clock low
        MOV     !ra,#portsetup_r      ;set sda->input in case ack
;         MOV     W,#t_low              ;get clock=low cycle timing*
        CALL    Bus_delay              ;allow for clock=low cycle
        RETP                          ;leave and fix page bits
;
Send_start SETB    sda                 ;pull data line high
        MOV     !ra,#portsetup_w      ;setup I2C to write bit
        JMP     :delay1                ;100ns data setup delay
:delay1    JMP     :delay2              ; (note: 250ns at low power)
:delay2    SETB    scl                 ;pull I2C clock high
;         MOV     W,#t_su_sta           ;get setup cycle timing*
        CALL    Bus_delay              ;allow start setup time
:new       CLRB    sda                 ;data line goes high->low
;         MOV     W,#t_hd_sta           ;get start hold cycle timing*
        CALL    Bus_delay              ;allow start hold time
        CLRB    scl                   ;pull I2C clock low
;         MOV     W,#t_buf              ;get bus=free cycle timing*

```

```

CALL    Bus_delay                ;pause before next function

RETP                                ;leave and fix page bits
;
Send_stop    CLRB    sda                ;pull data line low
MOV         !ra,#portsetup_w        ;setup I2C to write bit
JMP         :delay1                ;100ns data setup delay
:delay1      JMP         :delay2                ; (note: 250ns at low power)
:delay2      SETB    scl                ;pull I2C clock high
;           MOV         W,#t_su_sto        ;get setup cycle timing*
CALL        Bus_delay                ;allow stop setup time
SETB        sda                    ;data line goes low->high
;           MOV         W,#t_low           ;get stop cycle timing*
CALL        Bus_delay                ;allow start/stop hold time

RETP                                ;leave and fix page bits
;
Bus_delay    MOV         W,#t_all        ;get timing for delay loop
:custom      MOV         temp,W         ;save it
:loop        DJNZ        temp,:loop      ;do delay
RETP                                ;leave and fix page bits
;
;***** Subroutine(s) : Read from I2C EEPROM
; These routines read a byte from a 24LCXXB E2PROM either from a new address
; (random access mode), from the current address in the EEPROM's internal
; address pointer (CALL Read_byte:current), or as a sequential read. In either
; the random access or current address mode, seq_flag should be clear. Please
; refer to the application note on how to access the sequential read mode.
;
;   Input variable(s) : address, seq_flag
;   Output variable(s) : data
;   Variable(s) affected : byte, temp, count, delay
;   Flag(s) affected : none
;   Timing (turbo) : reads at approx. 200Kbps
;
I2C_read     CALL        Set_address        ;write address to slave
:current      CALL        Send_start        ;signal start of read
MOV          W,#control_r        ; get read control byte
CALL         Write_byte        ; and send it
:sequential   MOV         count,#8        ;set up for 8 bits
CLR          byte                ;zero result holder
:next_bit     RL          byte            ;shift result for next bit
CALL         Read_bit          ;get next bit
DJNZ         count,:next_bit      ;got whole byte yet?
MOV          data,byte          ;yes, store what was read
SB          seq_flag            ;is this a sequential read?
:non_seq      JMP         Send_stop        ; no, signal stop & exit
CLR          out_bit            ; yes, setup acknowledge bit
CALL         Write_bit         ; and send it
RETP                                ;leave and fix page bits
;
Read_bit     CLRB          in_bit        ;assume input bit low
MOV          !ra,#portsetup_r      ;set Port A up to read
SETB        scl                ;flip I2C clock to high
;           MOV         W,#t_high        ;get read cycle timing*

```

```

CALL    Bus_delay           ;Go do delay
SNB      sda                ;is data line high?
SETB     in_bit             ;yes, switch input bit high
CLRB     scl                ;return I2C clock low
;
MOV      W,#t_buf           ;get bus=free cycle timing*
CALL     Bus_delay          ;Go do delay
RETP     ;leave and fix page bits
;
;
Take_sample BANK    analog           ;switch to analog bank
MOV      W,ADC1             ;get ADC1 value
BANK     I2C                ;switch to EEPROM bank
SNB      got_hex            ;did user enter a value?
MOV      W,number_low       ;yes, load it instead
MOV      data,W             ;save ADC1 value
CALL     I2C_Write          ;store it in EEPROM
INC      address            ;move to next address
INC      byte_count         ;adjust # bytes stored
MOV      W,eeeprom_size     ;get memory size
MOV      W,address-W        ;are we past end?
SNZ      ;if not, skip ahead
CLR      address            ;if so, reset it
RETP     ;leave and fix page bits
;
View_Mem MOV      W,byte_count       ;get # bytes stored
:all      MOV      num_bytes,W       ;store it into view count
MOV      W,#_view           ;get view message
PAGE     send_string        ;set up for long call
CALL     send_string        ;dump it
BANK     I2C                ;switch to EEPROM bank
MOV      number_low,byte_count ;get byte storage count
PAGE     send_hex           ;set up for long call
CALL     send_hex:num_only   ;dump it
BANK     I2C                ;switch to I2C bank
MOV      W,#0               ;Address = start of EEPROM
JMP      :address           ;Go store address
:single  MOV      num_bytes,#1       ;only a single byte
MOV      W,number_low       ;get the address pointer
:address MOV      address,W          ;store requested address
MOV      W,#_cr             ;get carriage return
:dump    PAGE     send_string        ;set up for long call
CALL     send_string        ;send it
BANK     I2C                ;Switch to I2C bank
SB       erasing            ;viewing after erase cycle
SNB      got_hex            ; or special hex value?
JMP      :viewloop          ;yes, go dump it
TEST     save_addr          ;no, is EEPROM empty?
SNZ      ;if not, skip ahead
JMP      :done              ;yes, so leave
:viewloop CALL     I2C_read          ;fetch byte from EEPROM
MOV      number_low,data     ;setup to send it
PAGE     send_hex           ;set up for long call
CALL     send_hex:num_only   ;transmit it (RS232)
BANK     I2C                ;switch to I2C bank
DEC      num_bytes          ;decrement byte count

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        SNZ                ;skip ahead if not done
        JMP      :done     ;all bytes dumped, exit
        INC      address   ;move to next address
        MOV      W,#00001111b ;keep low nibble
        AND      W,address ; of address pointer
        MOV      W,#_space ;default=send a space
        SNZ                ;have we done 16 bytes?
        MOV      W,#_cr    ;yes, point to a <cr>
        JMP      :dump     ;go dump it and continue
:done    MOV      address,save_addr ;restore address pointer
        RETP              ;leave and fix page bits
;
Erase_Mem    CLR      address ;restore address pointer
        SETB     erasing    ;flag erase operation
        MOV      num_bytes,#eeprom_size ;wipe whole mem
:wipeloop   CLR      data    ;byte to wipe with=0
;           MOV      data,address ;byte to wipe with=addr
        CALL     I2C_write  ;wipe EEPROM byte
        INC      address    ;move to next address
        DJNZ     num_bytes,:wipeloop ;Erased enough yet?
        CLR      byte_count ;done, reset stored count
        CLR      save_addr  ;reset backup address
        MOV      W,#eeprom_size ;load mem size into W
        CALL     View_mem:all ; and view cleared memory
        CLRB     erasing    ;flag operation done
        RETP              ;leave and fix page bits
;***** End of I2C Subroutines *****
;
;*****
;* Main *
;*****
;
        ORG      140h
;
; Reset entry
;
reset_entry
;***Changed****
        mov      ra,##%1011 ;init ra
        mov      !ra,##%0100
        mov      rb,##%10000000 ;init rb
        mov      !rb,##%00001111
;*****

        clr      rc         ;init rc
        mov      !rc,##%10101010
        mov      m,#$D       ;set cmos input levels
        mov      !rc,#0
        mov      m,#$F

;****Changed****
:zero_ram   CLR      FSR      ;reset all ram starting at 08h
        SB      FSR.4        ;are we on low half of bank?
        SETB     FSR.3       ;If so, don't touch regs 0-7
        CLR      IND         ;clear using indirect addressing

```

```

        IJNZ     FSR,:zero_ram                ;repeat until done
;*****

        bank     timers                       ;set defaults
        setb     timer_low.0
        setb     freq_low.0

        mov      !option, #%10011111         ;enable rtcc interrupt
;
;
; Terminal - main loop
;
terminal    mov      w, #_hello                ;send hello string
            call     send_string

:loop       mov      w, #_prompt                ;send prompt string
            call     send_string

            call     get_byte                    ;get command
            call     uppercase
            mov      cmd, byte
            call     get_hex                    ;get any hex number

            cje      cmd, #'T', :timer           ;T xxxx
            cje      cmd, #'F', :freq           ;F xxxx
            cje      cmd, #'A', :pwm0          ;A xx
            cje      cmd, #'B', :pwm1          ;B xx
            cje      cmd, #'C', :adc0          ;C
            cje      cmd, #'D', :adc1          ;D

;**** Added ****
; Command: S [xx] - Store sample (if xx is left out, ADC1 is sampled)
;
            cje      cmd, #'S', :sample         ;S [xx] =store sample
;
; Command: V [xx] - View stored byte(s)
;           - if xx is left out, all stored byted are shown
;           - if xx=ff then whole eeprom is dumped
;
            cje      cmd, #'V', :view           ;V [xx] =View EEPROM contents
;
; Command: E - Erase EEPROM contents and reset storage pointer
;
            cje      cmd, #'E', :erase          ;E = Erase whole EEPROM
;*****
            mov      w, #_error                ;bad command
            call     send_string                ;send error string
            jmp      :loop                    ;try again

:timer      bank     timers                       ;timer write
            mov      timer_low, number_low
            mov      timer_high, number_high
            jmp      :loop

:freq       bank     timers                       ;freq write

```

```

mov      freq_low,number_low
mov      freq_high,number_high
jmp      :loop

:pwm0     bank    analog                      ;pwm0 write
mov      pwm0,number_low
jmp      :loop

:pwm1     bank    analog                      ;pwm1 write
mov      pwm1,number_low
jmp      :loop

:adc0     bank    analog                      ;adc0 read
mov      number_low,adc0
call     send_hex
jmp      :loop

:adc1     bank    analog                      ;adc1 read
mov      number_low,adc1
call     send_hex
jmp      :loop

;**** Added ****
:sample   BANK    I2C                        ;Switch to I2C bank
          PAGE    Take_sample                ;I2C subroutine page
          CALL    Take_sample                ;Go take a sample
          MOV     W,#_sample                 ;get sample message
          CALL    send_string                ;dump it
          BANK    I2C                        ;switch to EEPROM bank
          MOV     number_low,data            ;byte sent
          CALL    send_hex:num_only          ;dump it
          JMP     :loop                      ;back to main loop

;
:view     BANK    I2C                        ;switch to I2C bank
          MOV     save_addr,address          ;backup address pointer
          SNB     got_hex                    ;Was this "V xx" command?
          JMP     :v_special                 ;if so, jump
          PAGE    View_mem                  ;I2C subroutine page
          CALL    View_mem                  ;no, view stored data
          JMP     :loop                      ;back to main loop
:v_special MOV     W,++number_low            ;View whole mem=> "V ff"
          JZ      :v_whole                  ;Was this requested?
          PAGE    View_mem                  ;I2C subroutine page
          CALL    View_mem:single           ;yes, go dump it
          JMP     :loop                      ;back to main loop
:v_whole  MOV     W,#eeprom_size            ;Get eeprom mem size
          PAGE    View_mem                  ;I2C subroutine page
          CALL    View_mem:all              ;Go dump the whole thing
          JMP     :loop                      ;back to main loop

;
:erase    BANK    I2C                        ;switch to I2C bank
          PAGE    Erase_mem                 ;I2C subroutine page
          CALL    Erase_mem                 ;no, wipe whole EEPROM
          JMP     :loop                      ;back to main loop

;*****

```


