

Lecture 13

CMPEN 331

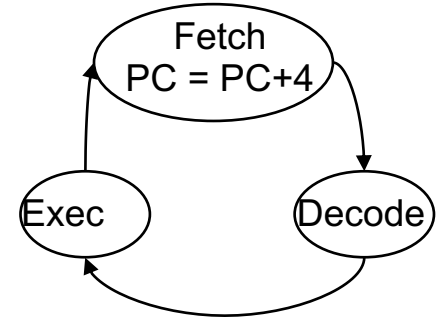
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Introduction

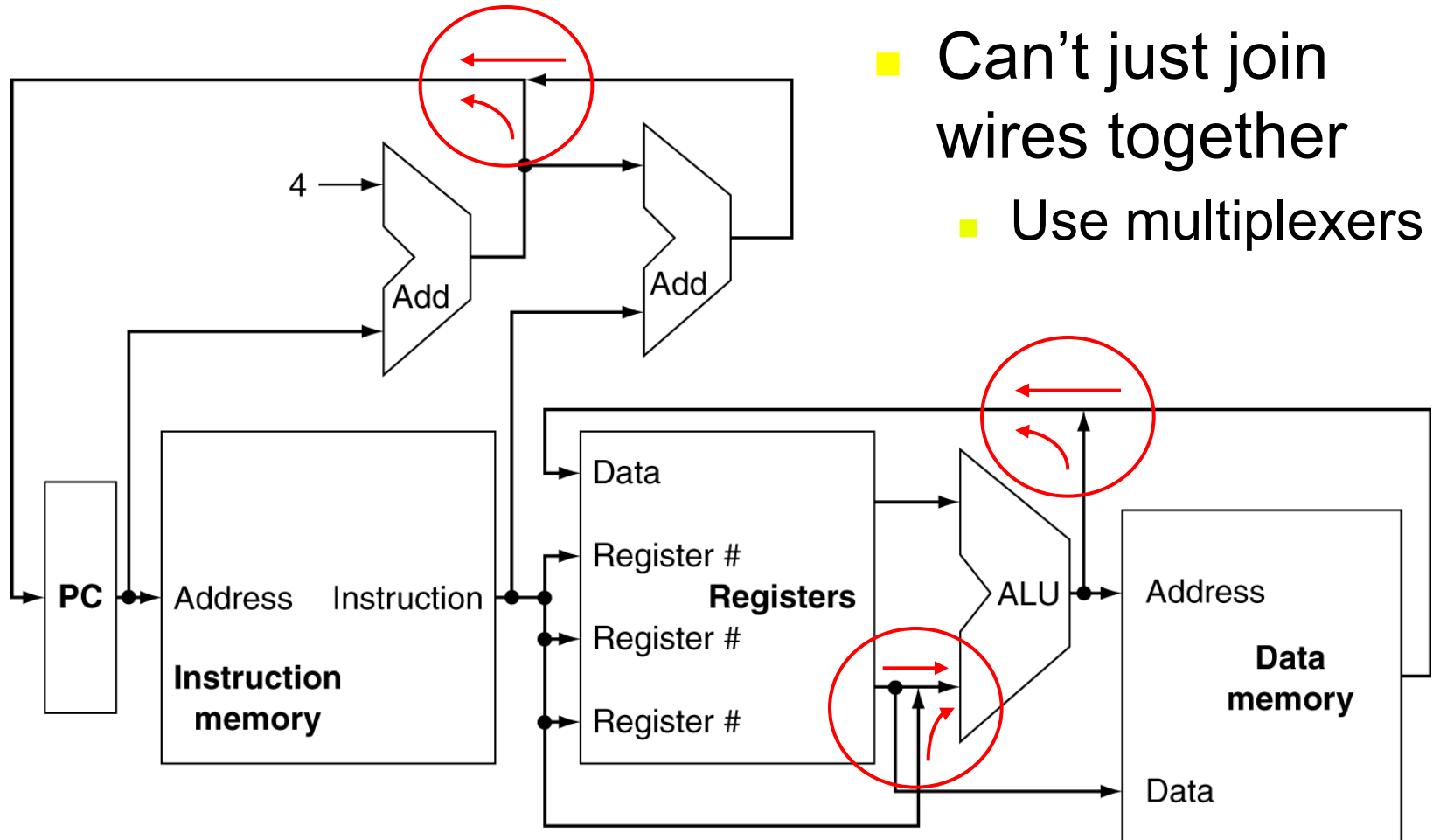
- CPU performance factors
 - Instruction count
 - Determined by ISA and compiler
 - CPI and Cycle time
 - Determined by CPU hardware
- We will examine two MIPS implementations
 - A simplified version
 - A more realistic pipelined version
- Simple subset, shows most aspects
 - Memory reference: lw, sw
 - Arithmetic/logical: add, sub, and, or, slt
 - Control transfer: beq, j

Instruction Execution

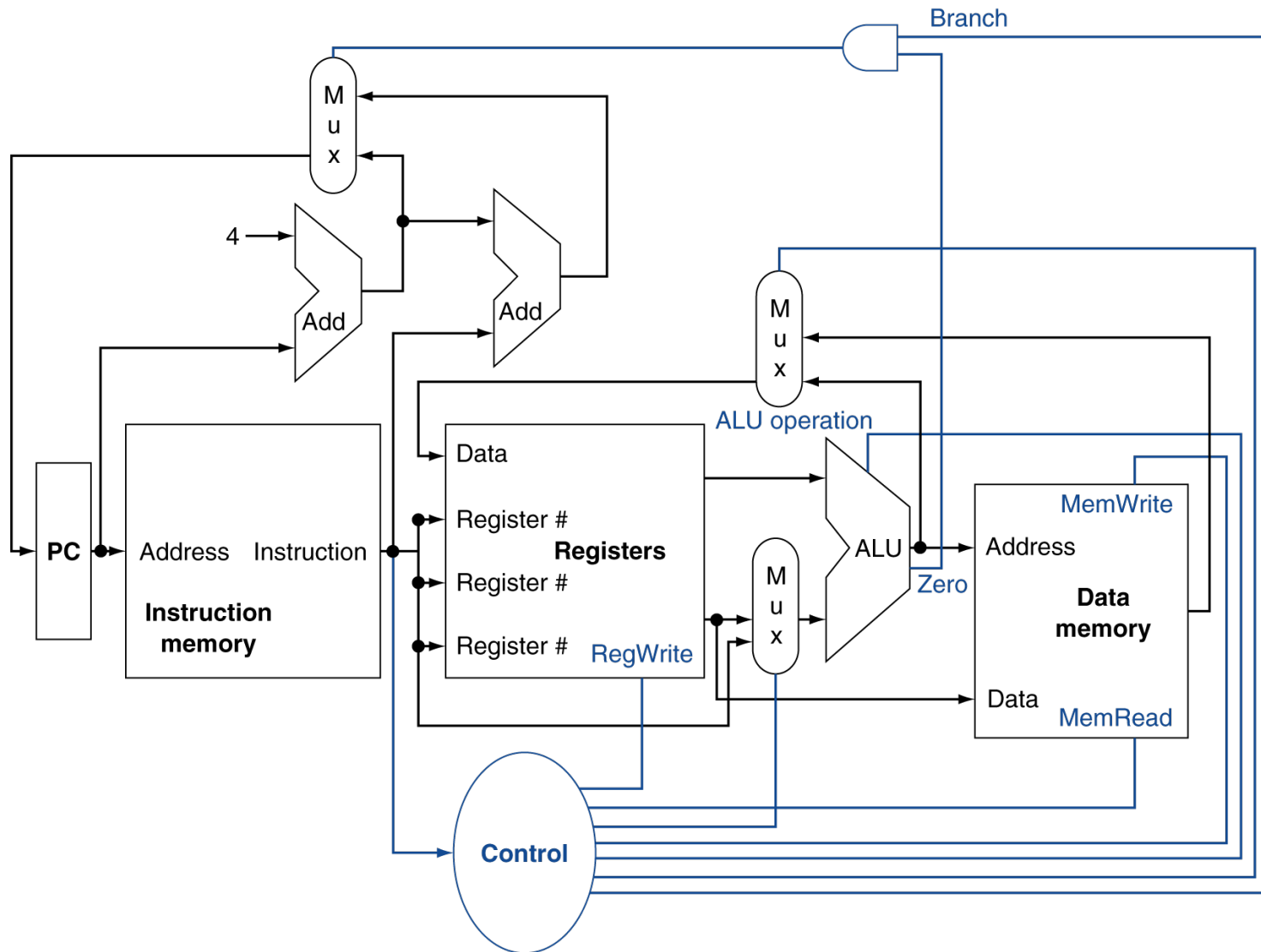
- Generic implementation
 - use the program counter (PC) to supply the instruction address and fetch the instruction from memory (and update the PC)
 - decode the instruction (and read registers)
 - execute the instruction
- All instructions (except **j**) use the ALU after reading the registers
- Depending on instruction class
 - Use ALU to calculate
 - Arithmetic result
 - Memory address for load/store
 - Branch target address
 - Access data memory for load/store
 - $PC \leftarrow \text{target address or } PC + 4$



CPU Overview



Control

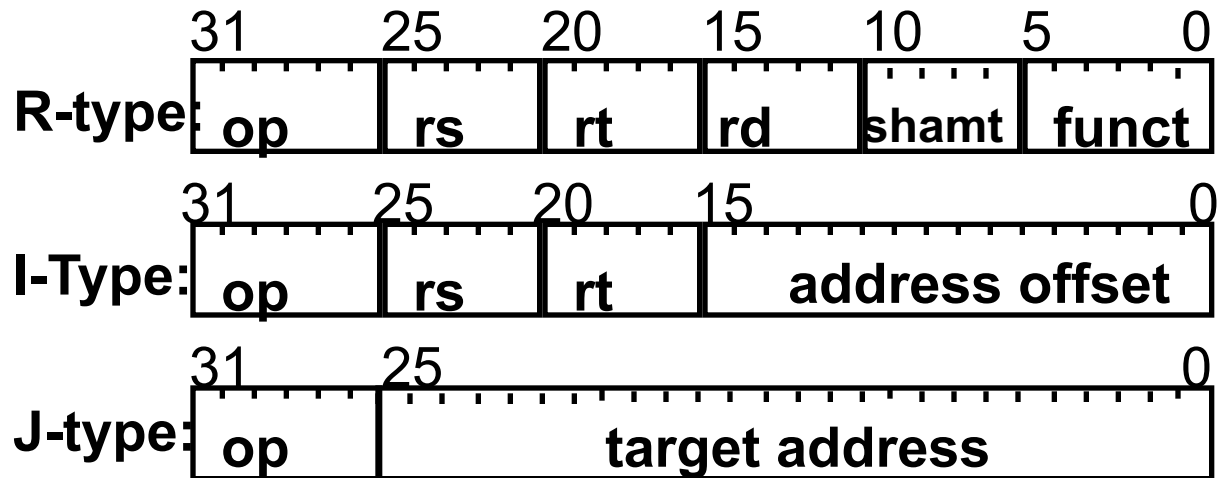


Adding the Control

- Selecting the operations to perform (ALU, Register File and Memory read/write)
- Controlling the flow of data (multiplexor inputs)

□ Observations

- op field always in bits **31-26**
- address of registers to be read are always specified by the rs field (bits **25-21**) and rt field (bits **20-16**); for lw and sw rs is the base register
- address of register to be written is in one of two places – in rt (bits **20-16**) for lw; in rd (bits **15-11**) for R-type instructions
- offset for beq, lw, and sw always in bits **15-0**



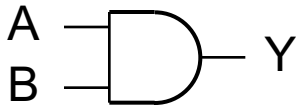
Logic Design Basics

- Information encoded in binary
 - Low voltage = 0, High voltage = 1
 - One wire per bit
 - Multi-bit data encoded on multi-wire buses
- Combinational element
 - Operate on data
 - Output is a function of input
- State (sequential) elements
 - Store information

Combinational Elements

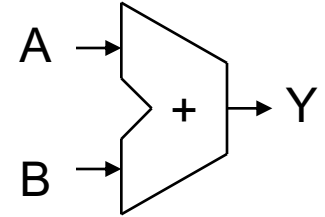
- AND-gate

- $Y = A \& B$



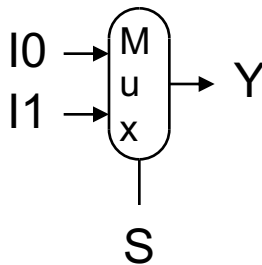
- Adder

- $Y = A + B$



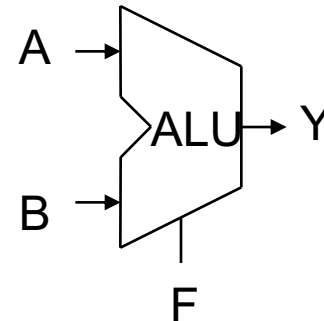
- Multiplexer

- $Y = S ? I1 : I0$



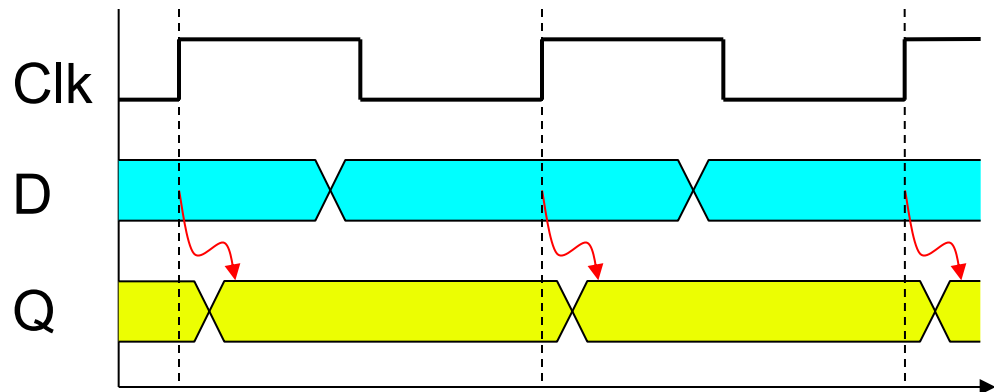
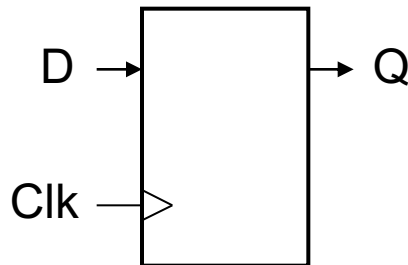
- Arithmetic/Logic Unit

- $Y = F(A, B)$



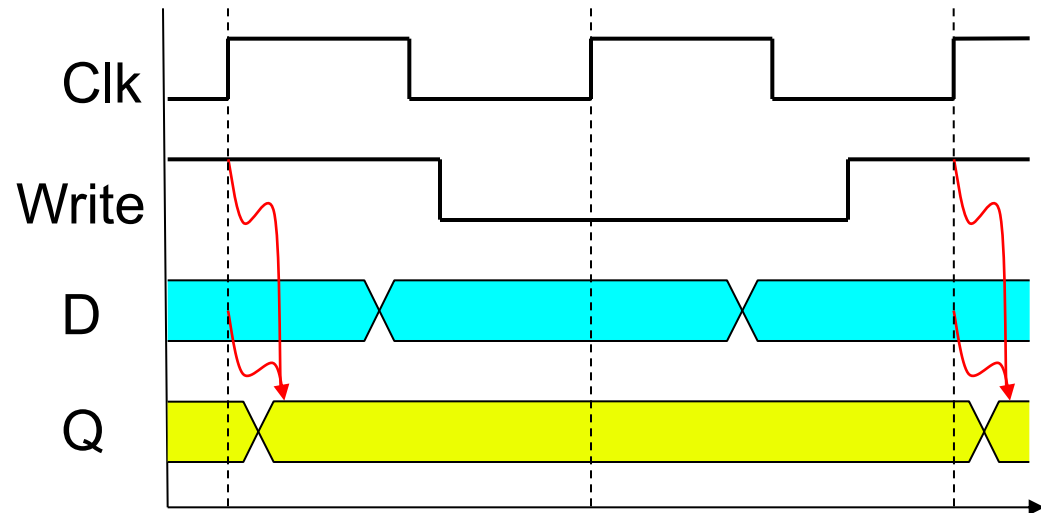
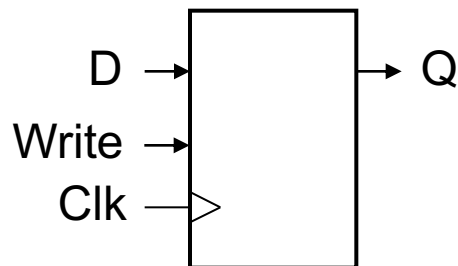
Sequential Elements

- Register: stores data in a circuit
 - Uses a clock signal to determine when to update the stored value
 - Edge-triggered: update when Clk changes from 0 to 1



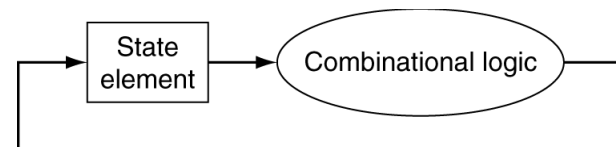
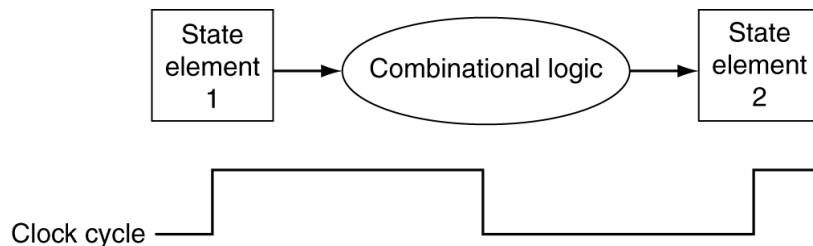
Sequential Elements

- Register with write control
 - Only updates on clock edge when write control input is 1
 - Used when stored value is required later



Clocking Methodology

- The **clocking methodology** defines when data in a state element is valid and stable relative to the clock
 - State elements - a memory element such as a register
 - Edge-triggered – all state changes occur on a clock edge
- Combinational logic transforms data during clock cycles
 - Between clock edges
 - Input from state elements, output to state element
 - Longest delay determines clock period

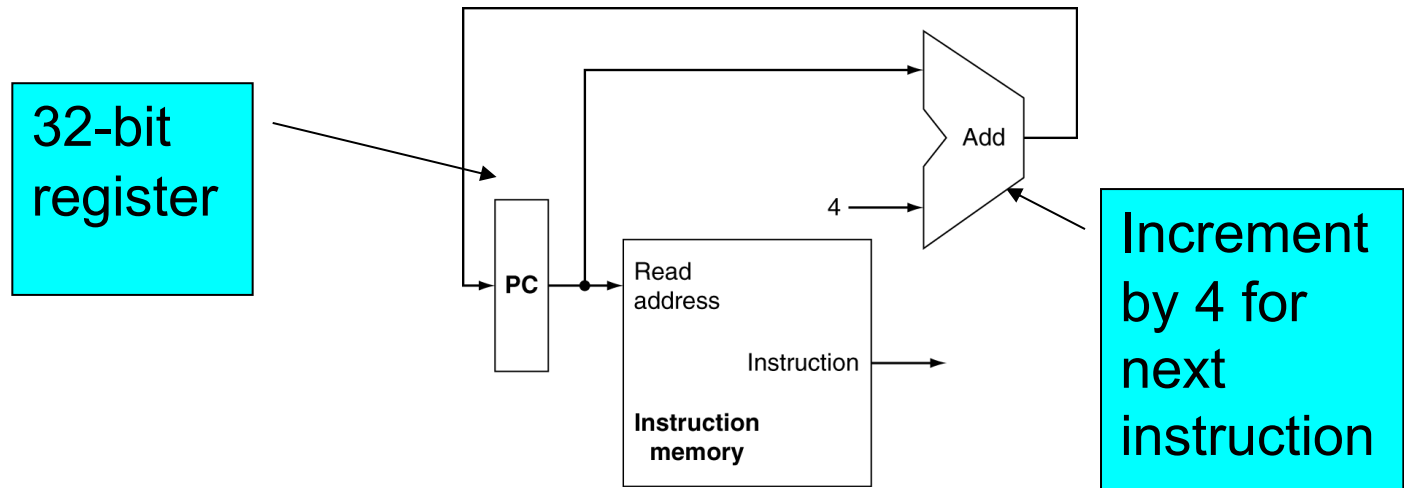


Building a Datapath

- Datapath
 - Elements that process data and addresses in the CPU
 - Registers, ALUs, mux's, memories, ...
- We will build a MIPS datapath incrementally
 - Refining the overview design

Instruction Fetch

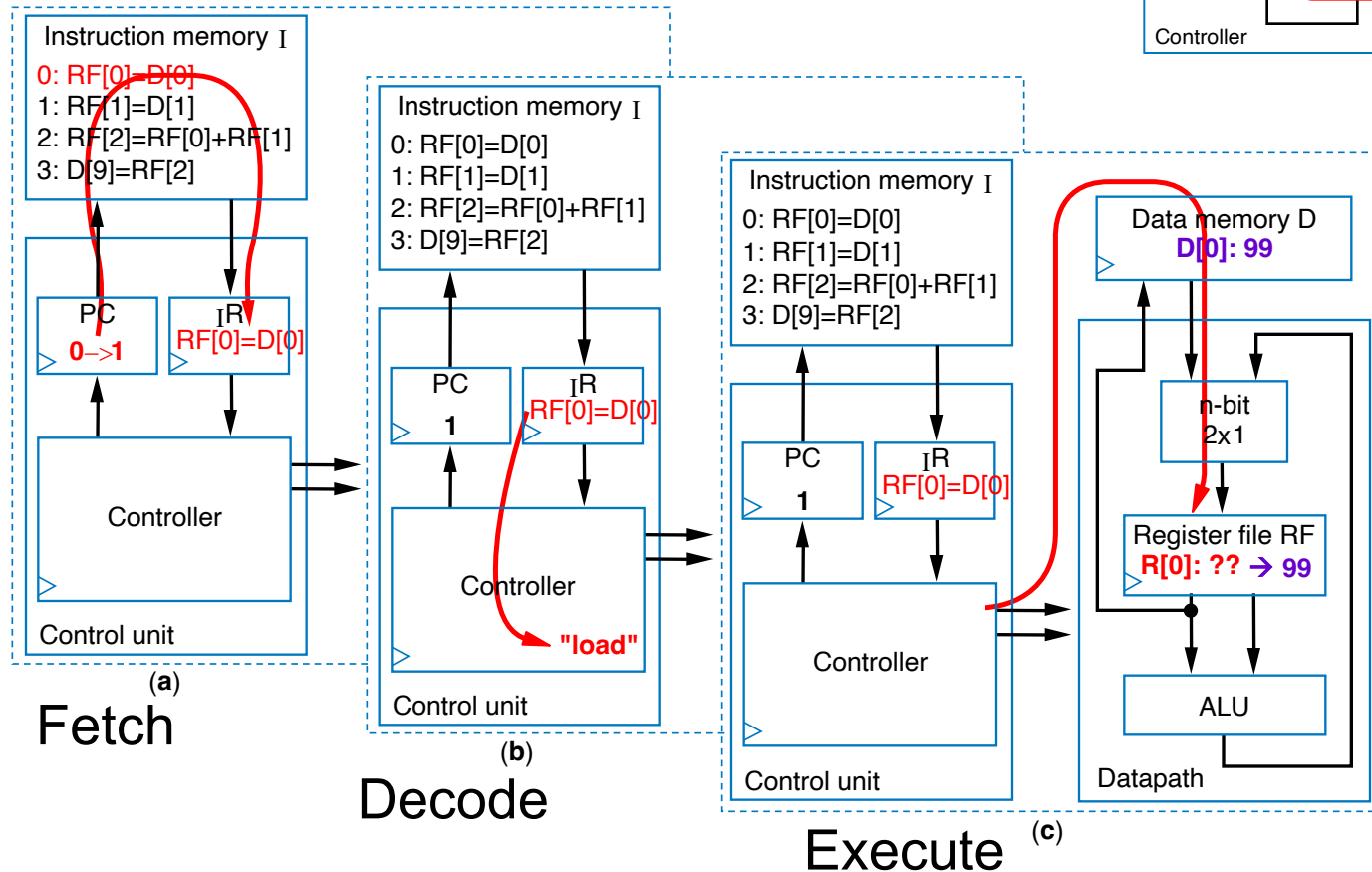
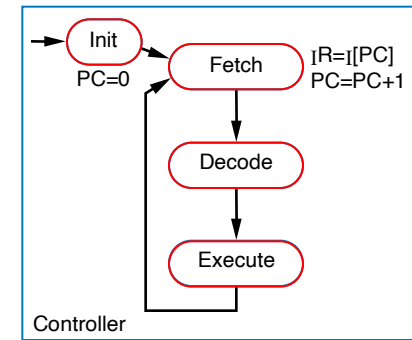
- Fetching instructions involves
 - Reading the instruction from the Instruction Memory
 - Updating the PC value to be the address of the next (sequential) instruction



- PC is updated every clock cycle, so it does not need an explicit write control signal just a clock signal
- Reading from the Instruction Memory is a combinational activity, so it doesn't need an explicit read control signal

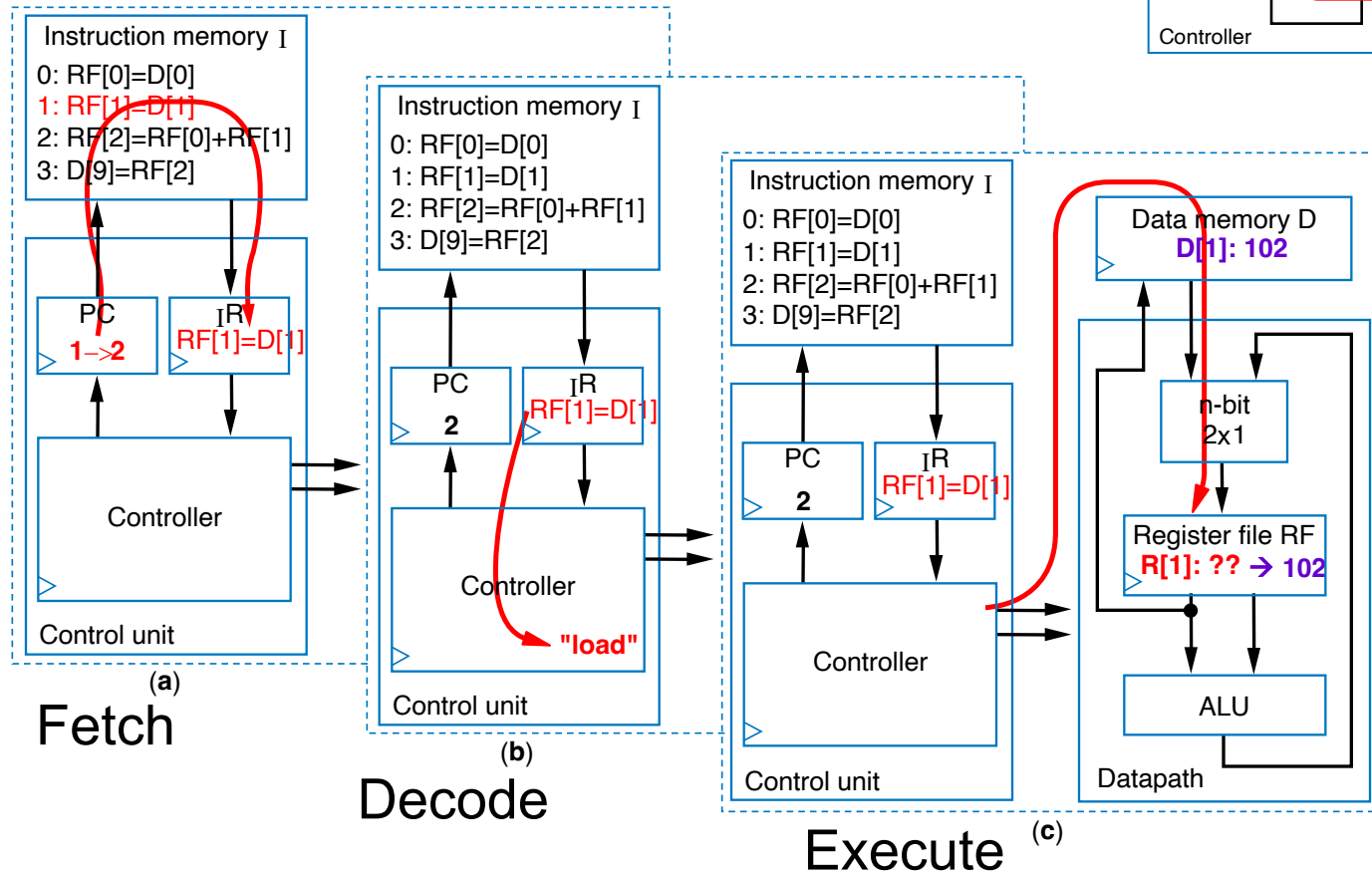
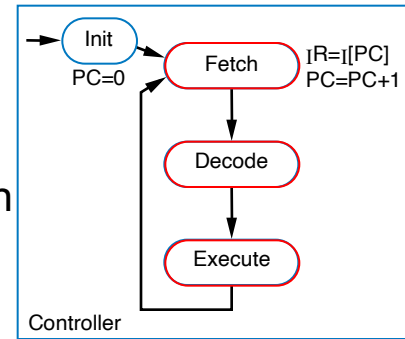
Basic Architecture – Control Unit

- To carry out *each instruction*, the control unit must:
 - Fetch – Read instruction from inst. mem.
 - Decode – Determine the operation and operands of the instruction
 - Execute – Carry out the instruction's operation using the datapath



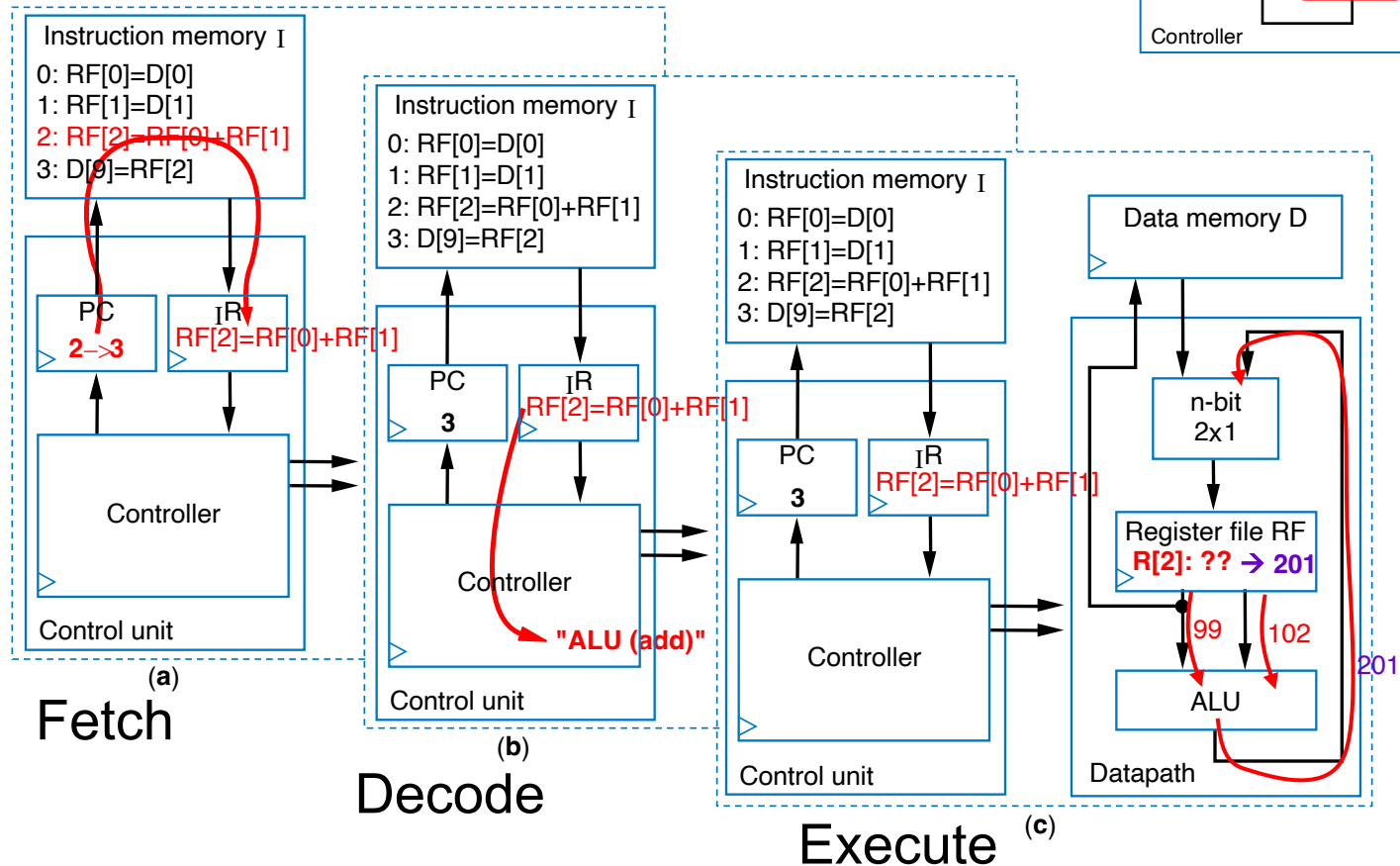
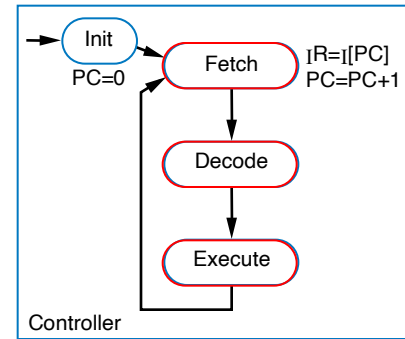
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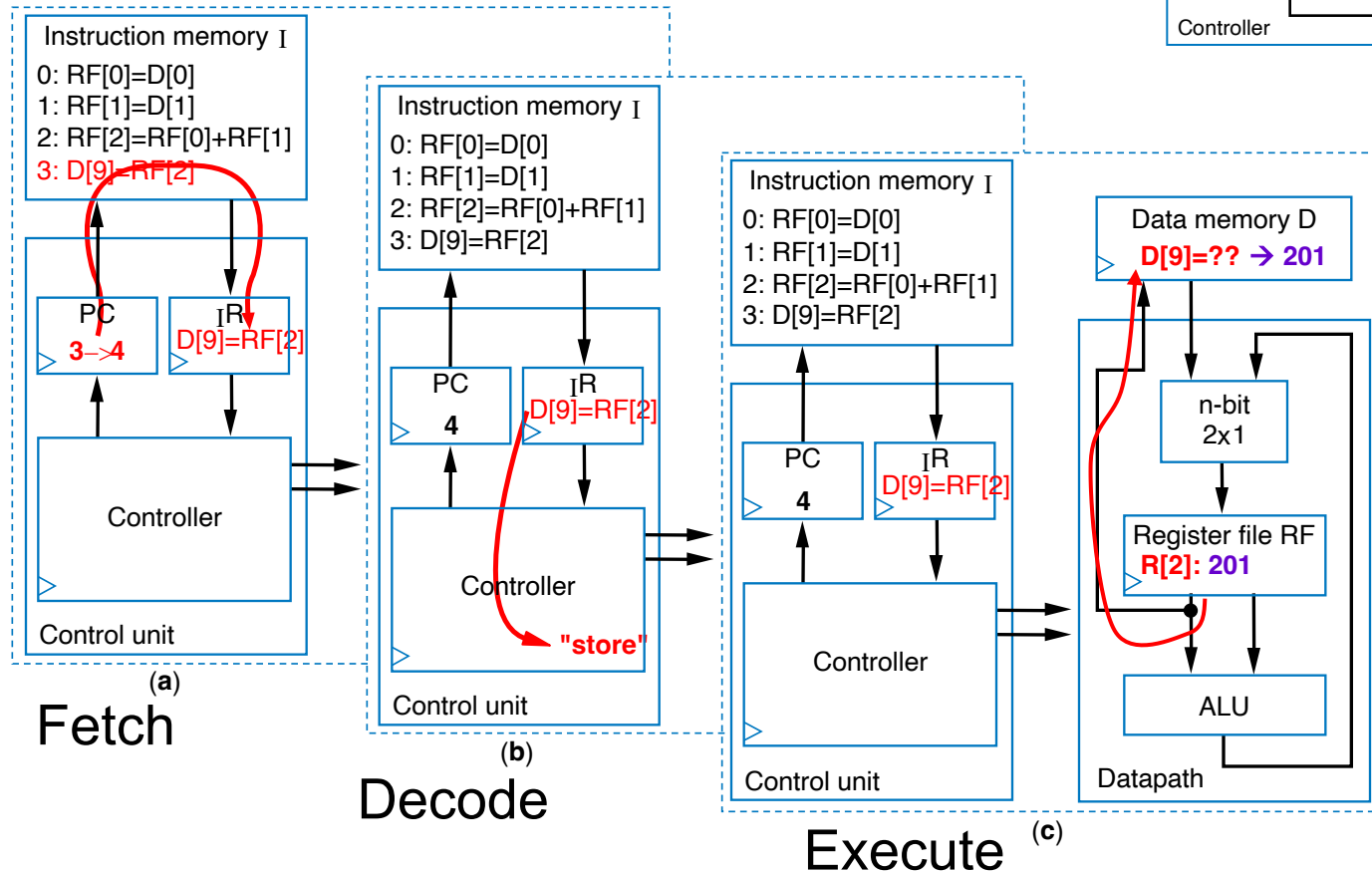
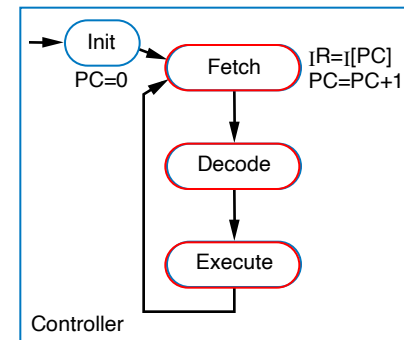
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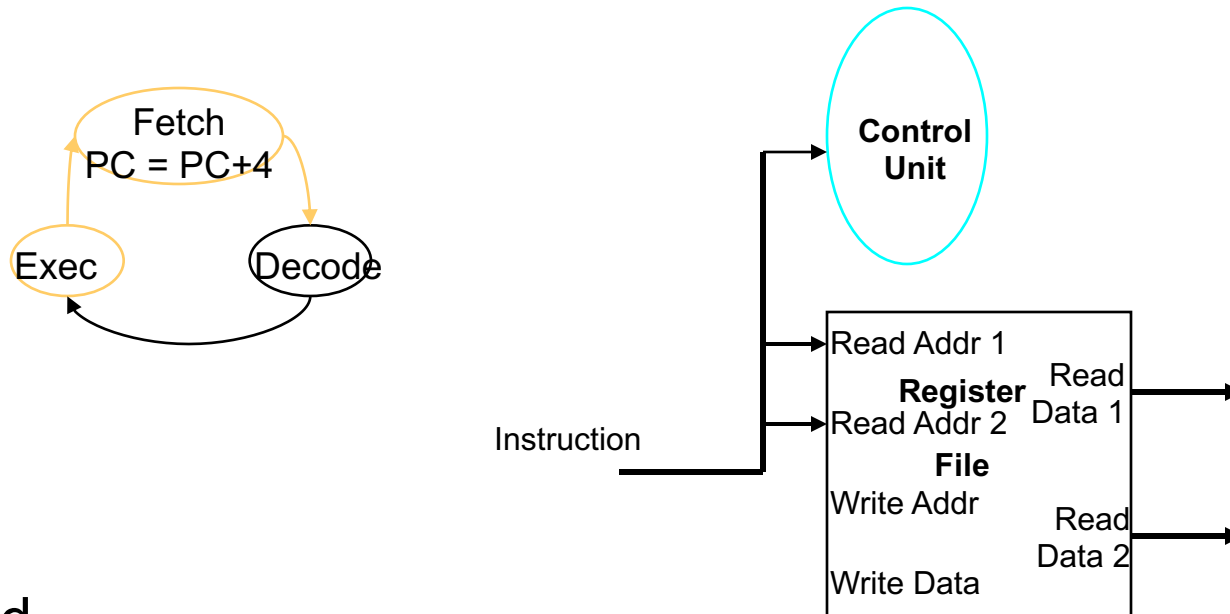
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Decoding Instructions

- Decoding instructions involves
 - sending the fetched instruction's opcode and function field bits to the control unit



and

- reading two values from the Register File
 - Register File addresses are contained in the instruction

Fixed Program Counter

```
module program_counter
```

```
(
```

```
    input                                update,
```

```
    input                                clk,
```

```
    input                                rst,
```

```
    output reg [31:0]    pc
```

```
);
```

```
parameter INCREMENT_AMOUNT = 32'd4;
```

```
always @(posedge clk or posedge rst)
```

```
begin
```

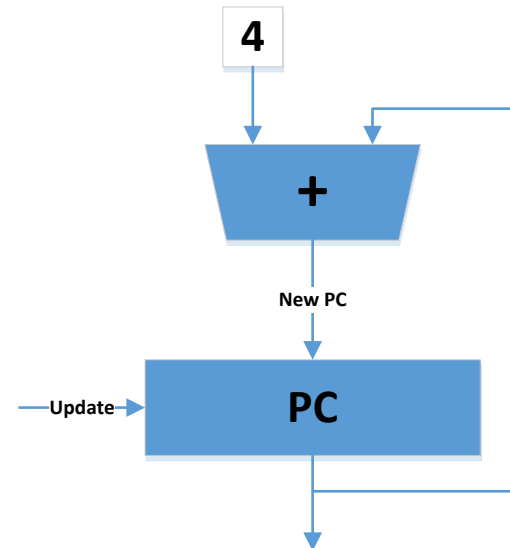
```
    if (rst)
```

```
        pc <= 0;
```

```
    else if (update)
```

```
        pc <= pc + INCREMENT_AMOUNT;
```

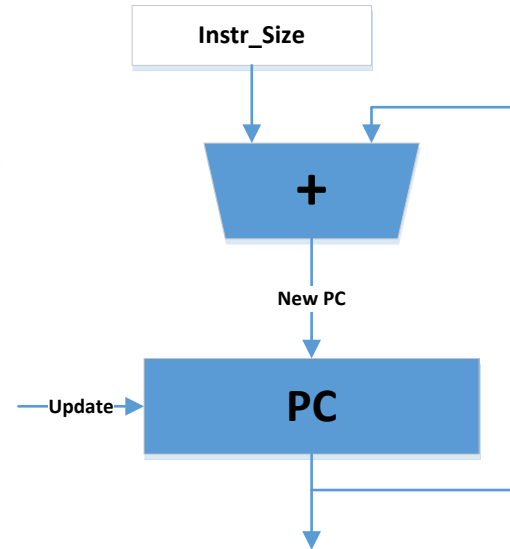
```
end
```



Variable Program Counter

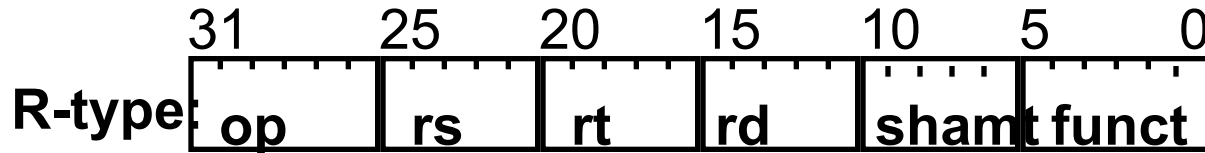
```
module program_counter
(
    input                update,
    input                [31:0] instruction_size,
    input                clk,
    input                rst,
    output reg [31:0] pc
);

always @(posedge clk or posedge rst)
begin
    if (rst)
        pc <= 0;
    else if (update)
        pc <= pc + instruction_size;
end
```

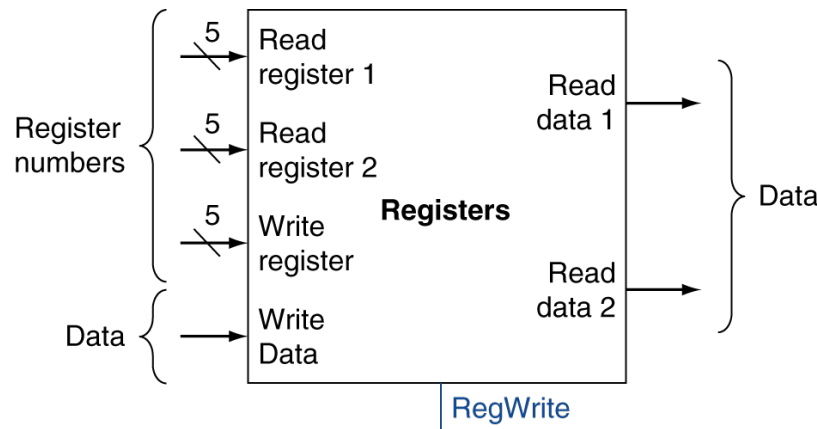


R-Format Instructions

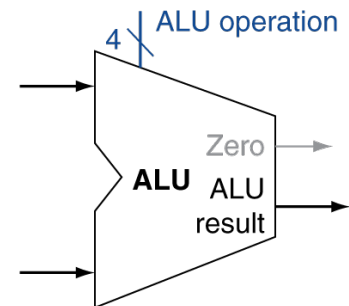
- R format operations (**add**, **sub**, **slt**, **and**, **or**)



- perform operation (**op** and **funct**) on values in **rs** and **rt**
- store the result back into the Register File (into location **rd**)
- Note that Register File is not written every cycle (e.g. **sw**), so we need an explicit write control signal for the Register File



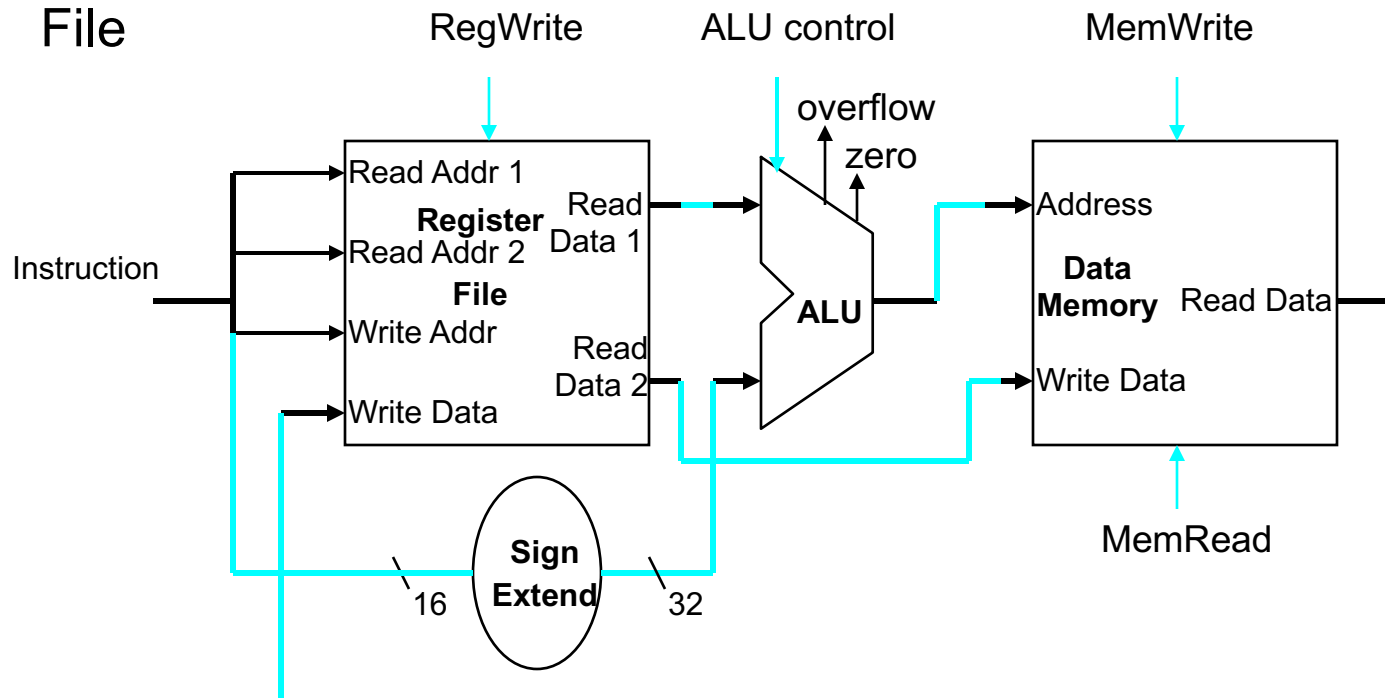
a. Registers



b. ALU

Executing Load and Store Operations

- Load and store operations involves
 - compute memory address by adding the base register (read from the Register File during decode) to the 16-bit signed-extended offset field in the instruction
 - **store** value (read from the Register File during decode) written to the Data Memory
 - **load** value, read from the Data Memory, written to the Register File



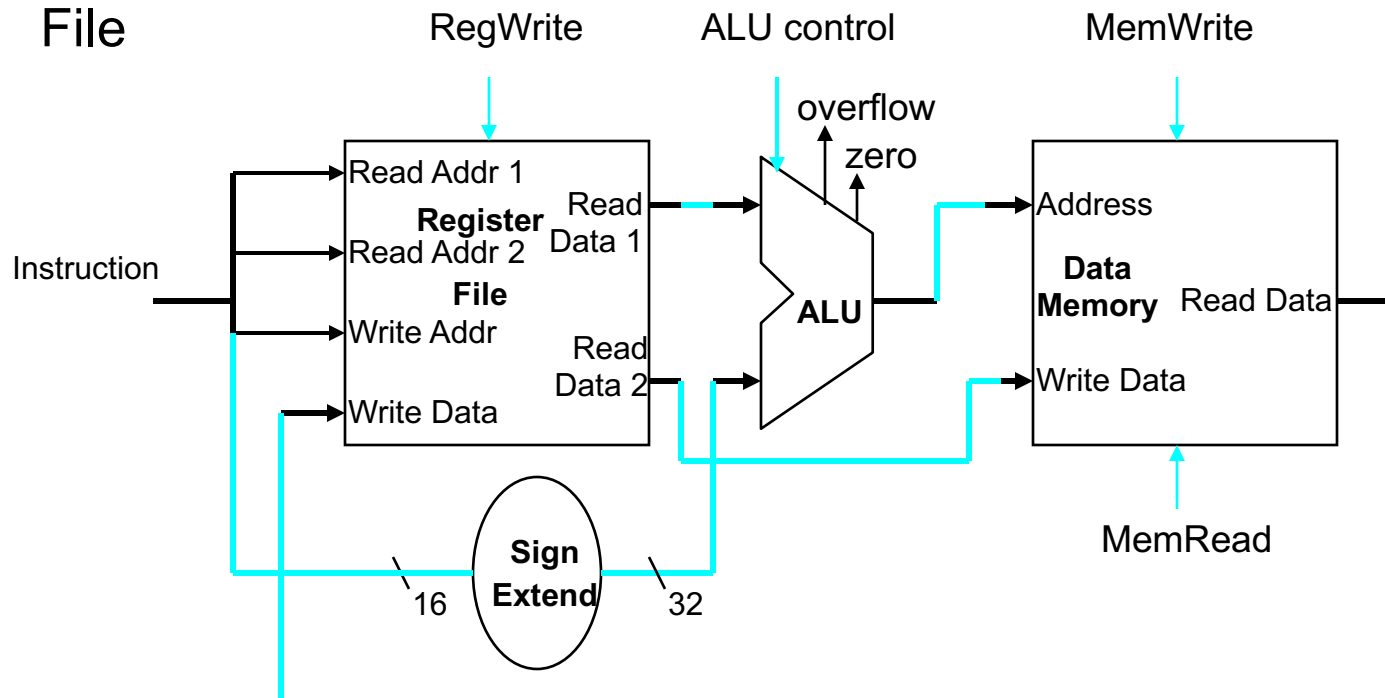
Lecture 14

CMPEN 331

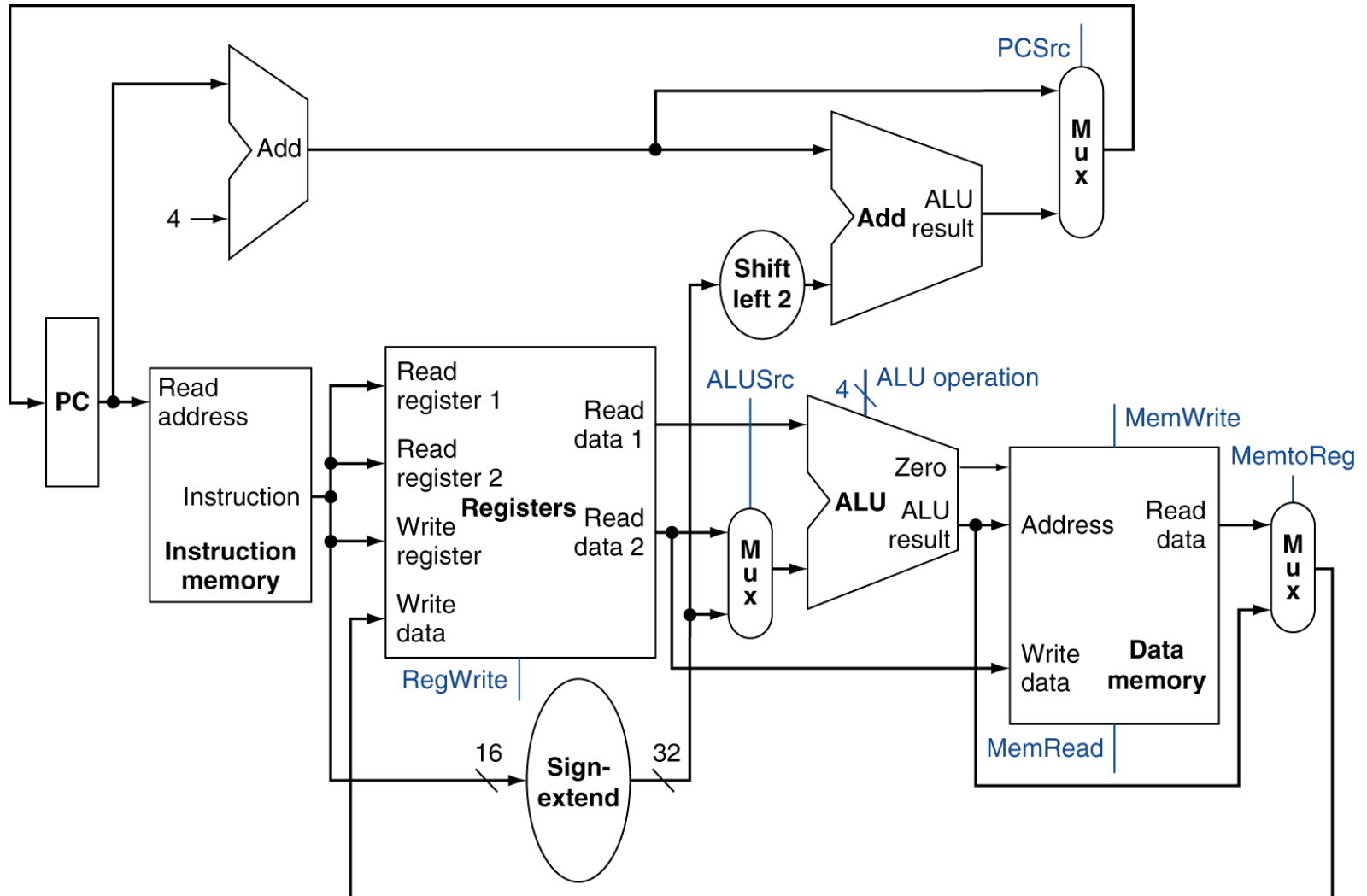
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Executing Load and Store Operations

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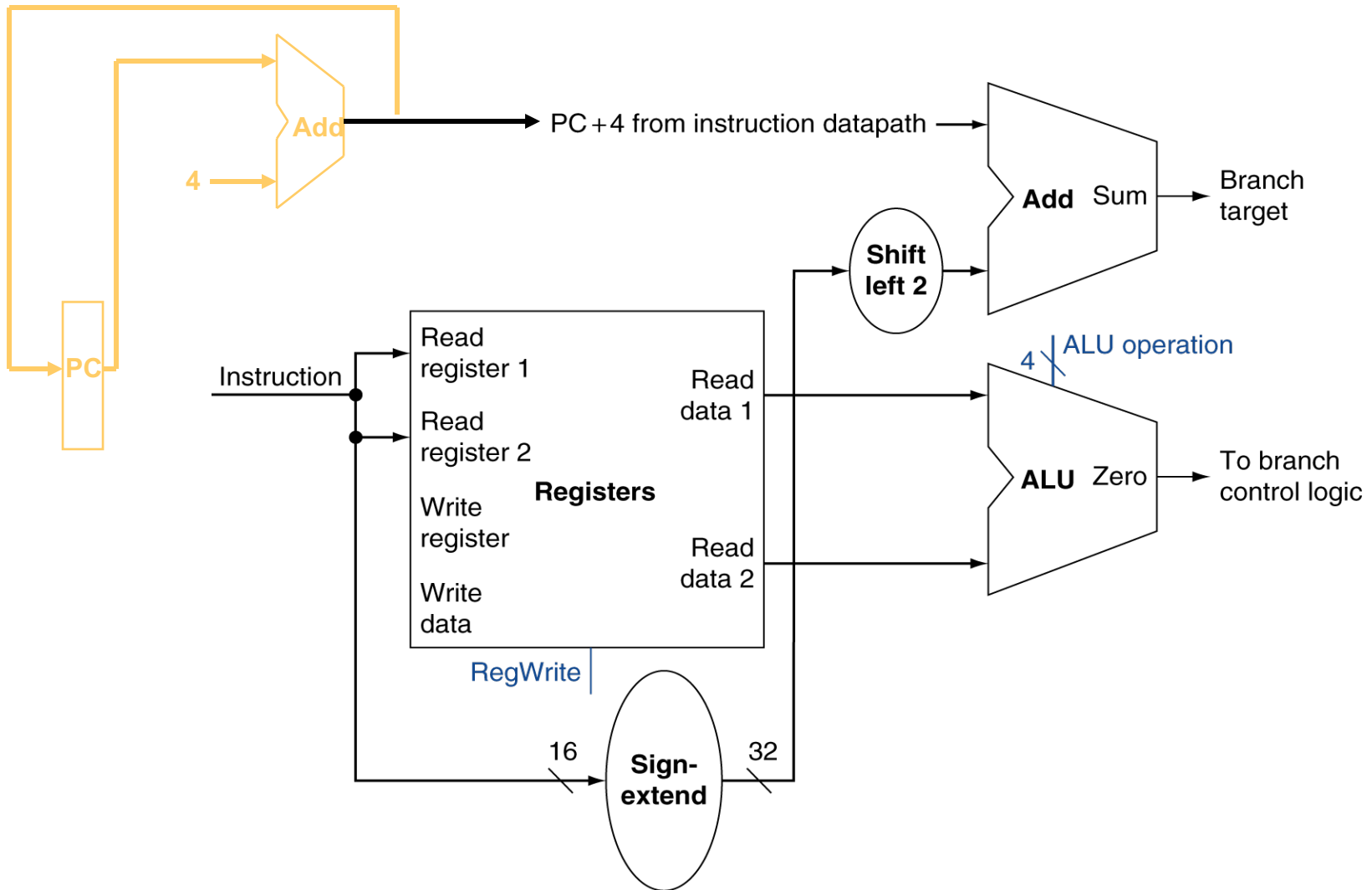
Data path



Branch Instructions

- Read register operands
- Compare operands
 - Use ALU, subtract and check Zero output
- Calculate target address
 - Sign-extend displacement
 - Shift left 2 places (word displacement)
 - Add to PC + 4
 - Already calculated by instruction fetch

Branch Instructions

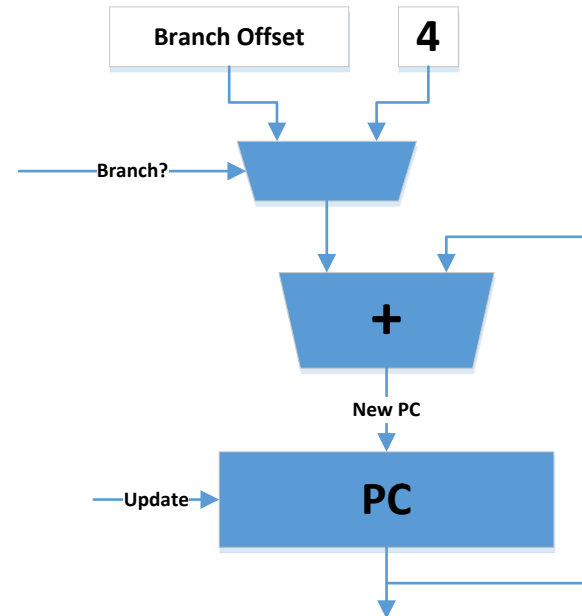


Fixed Program Counter with Offset Branching

```
module program_counter
(
    input                update,
    input                branch,
    input                [15:0]branch_offset,
    input                clk,
    input                rst,
    output reg [31:0]    pc
);

parameter INCREMENT_AMOUNT = 32'd4;

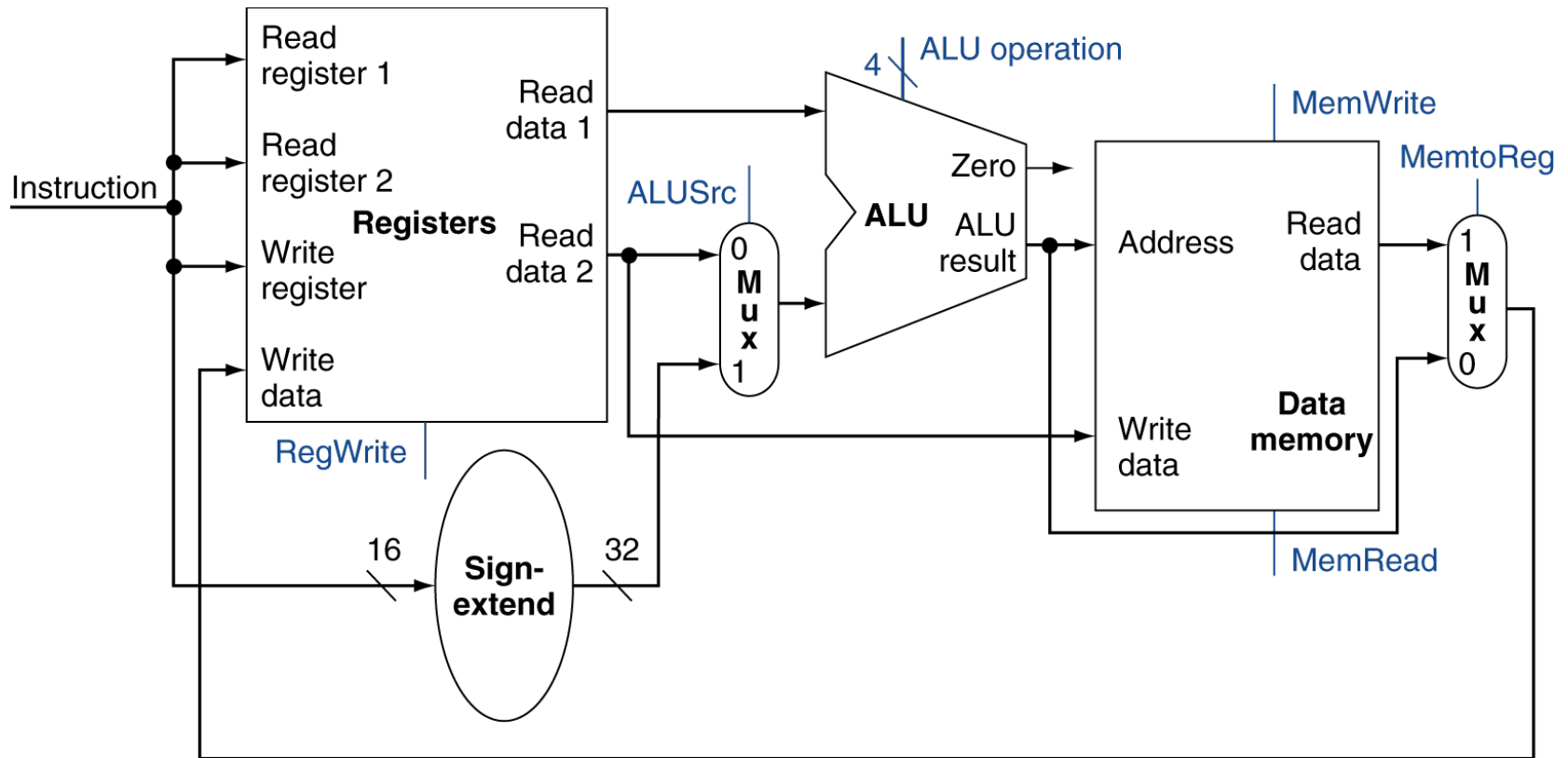
always @(posedge clk or posedge rst)
begin
    if (rst)
        pc <= 0;
    else if (update)
        if (branch)
            pc <= pc + {16'd0,branch_offset};
        else
            pc <= pc + INCREMENT_AMOUNT;
end
```



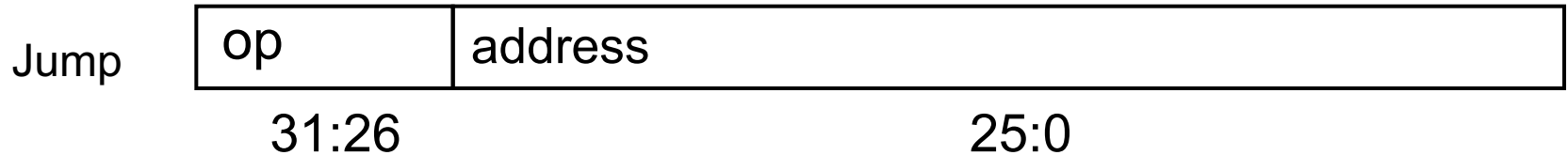
Composing the Elements

- First-cut data path does an instruction in one clock cycle
 - Each data path element can only do one function at a time
 - Hence, we need separate instruction and data memories
- Use multiplexers where alternate data sources are used for different instructions

R-Type/Load/Store Datapath

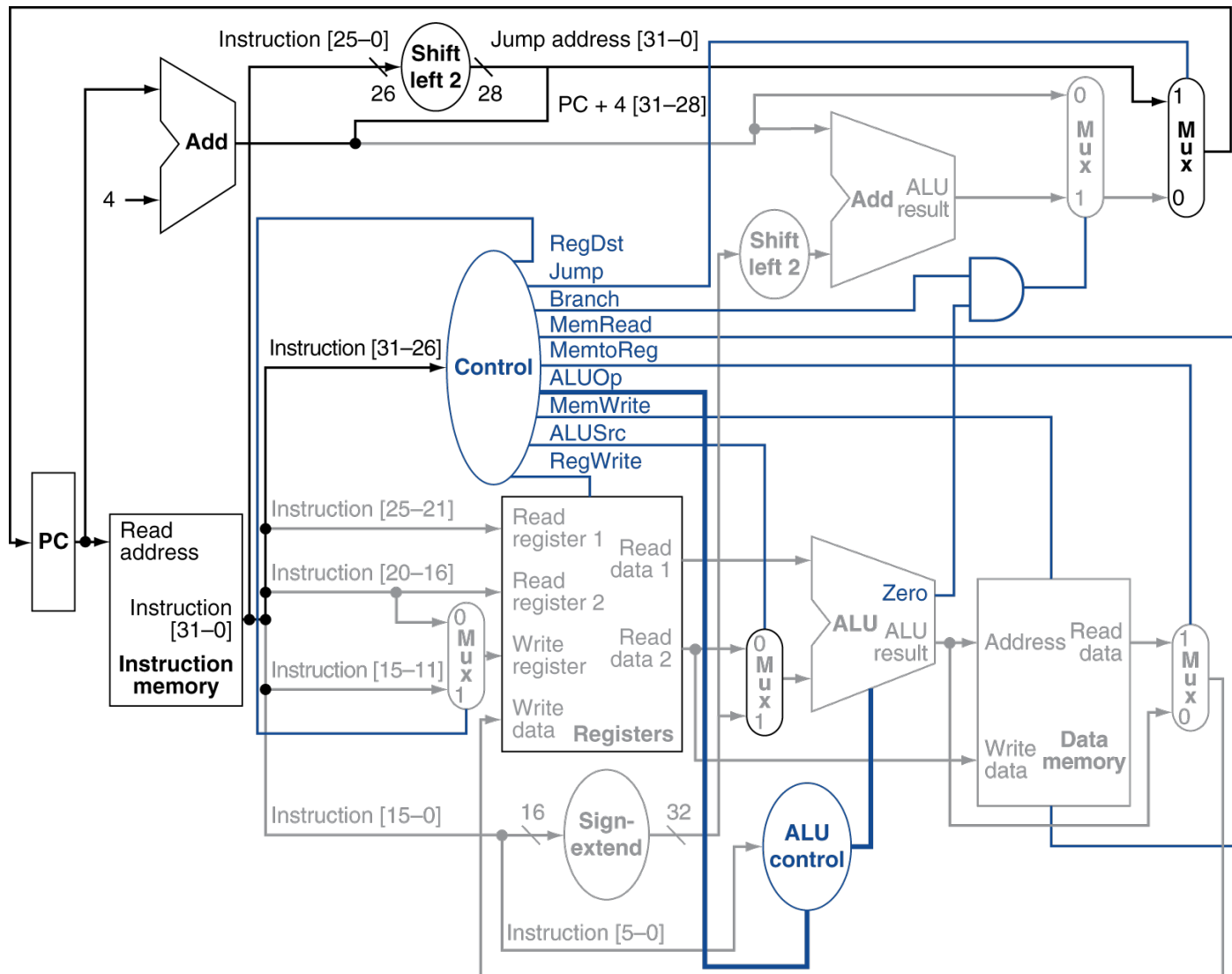


Implementing Jumps



- Jump uses word address
- Update PC with concatenation of
 - Top 4 bits of old PC
 - 26-bit jump address
 - 00
- Need an extra control signal decoded from opcode

Datapath With Jumps Added



ALU Control

- ALU used for
 - Load/Store: F = add
 - Branch: F = subtract
 - R-type: F depends on funct field

ALU control	Function
0000	AND
0001	OR
0010	add
0110	subtract
0111	set-on-less-than
1100	NOR

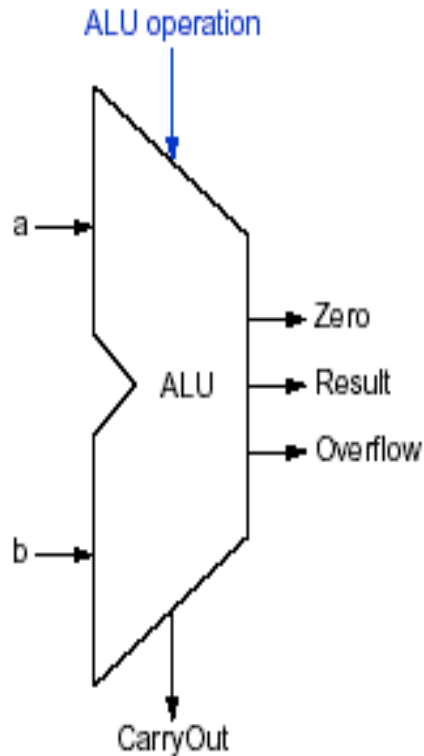
ALU Control

- Assume 2-bit ALUOp derived from opcode
 - Combinational logic derives ALU control

opcode	ALUOp	Operation	funct	ALU function	ALU control
lw	00	load word	XXXXXX	add	0010
sw	00	store word	XXXXXX	add	0010
beq	01	branch equal	XXXXXX	subtract	0110
R-type	10	add	100000	add	0010
		subtract	100010	subtract	0110
		AND	100100	AND	0000
		OR	100101	OR	0001
		set-on-less-than	101010	set-on-less-than	0111

MIPS ALU in Verilog

- The ALU has 7 ports.



ALU control lines	Function
0000	AND
0001	OR
0010	add
0110	subtract
0111	set on less than
1100	NOR

A Verilog behavioral definition of a MIPS ALU

Pseudo code

```
module MIPSALU (ALUctl, A, B, ALUOut, Zero);
input [3:0] ALUctl;
input [31:0] A,B;
output reg [31:0] ALUOut;
output Zero;
assign Zero = (ALUOut==0); //Zero is true if ALUOut is 0
always @(ALUctl, A, B)
    begin //reevaluate if these change
        case (ALUctl)
            0: ALUOut <= A & B;
            1: ALUOut <= A | B;
            2: ALUOut <= A + B;
            6: ALUOut <= A - B;
            7: ALUOut <= A < B ? 1 : 0;
            12: ALUOut <= ~(A | B); //result is nor default: ALUOut <= 0;
        endcase
    end
endmodule
```

The MIPS ALU control

This is a combinational control logic. (Pseudo code)

```
module ALUControl (ALUOp, FuncCode, ALUCtl);  
input [1:0] ALUOp;  
input [5:0] FuncCode;  
output [3:0] reg ALUCtl;  
always @(*)  
case (FuncCode)  
    32: ALUCtl <=2; // add  
    34: ALUCtl <=6; //subtract  
    36: ALUCtl <=0; // and  
    37: ALUCtl <=1; // or  
    39: ALUCtl <=12; // nor  
    42: ALUCtl <=7; // slt  
    default: ALUCtl <=15; // should not happen  
endcase  
endmodule
```

The Main Control Unit

- Control signals derived from instruction

