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# Md Ashfaqur Rahaman

## Research Interests

My research interest is in the intersection of computer architecture, operating systems and compilers. I want to work on problems where coordination between these is needed to improve system performance.

## Experience

Research

2019-Present Voluntary Research Assistant, Prof. Baris Kasikci's Lab, University of Michigan, Ann Arbor.

Mentor: Tanvir Ahmed Khan

I am working on profile guided optimizations of large application binaries in warehouse scale computers to reduce i-cache misses.

2018-2019 Research Assistant, Climate Modeling and Simulation Lab, IWFM, BUET.

Advisor: A.K.M. Saiful Islam

I worked as a system developer in Flash Flood Early Warning System (FFEWS) project. We have developed a real time flash flood warning system by integrating weather, hydrologic and river modeling systems into a single platform.

Professional

2018-2019 **Software Engineer**, NextGen DigiTech, Dhaka.

Worked on NextGen Tower, a desktop application for designing wind turbines. I contributed in the core software architecture and developed the GUI.

2017-2018 Firmware Engineer, 2RA Technology Limited, Dhaka.

I worked on various embedded projects based on Raspberry Pi and AVR Microcontrollers.

Competitions

2018 Google Kickstart Coding Competition, Google.

Participated in the qualification round and solved all the problems.

2016 **RoboSoccer Competition**, Engineering Student Association Bangladesh (ESAB).

My team got honorable mention in the competition.

2015 Model Ship Propulsion Competition, BUET.

My team secured third position. I worked in programming and hardware interfacing part

2015 Android App Contest, EATL-Prothomalo.

We developed an Android application for checking OMR sheets by using image processing algorithms. Our app was in the top 100 list.

Education

2012-2019 **B.Sc in Naval Architecture and Marine Engineering**, Bangladesh University of Engineering and Technology (BUET), CGPA – 2.69 on 4.00.

Bachelor Thesis

Title Power Efficient Remotely Operated Underwater Vehicle Using Buoyancy Chambers

Supervisor Dr. Md. Mashud Karim

Description In this thesis, a power efficient remotely operated underwater vehicle (ROV) has been built using buoyancy chambers. Conventionally, thruster motors are used for the propulsion of the ROV. In this system to keep the vehicle at rest in a fixed position under water, thruster motors are used and battery power is consumed continuously. This power loss can be removed by adding simple buoyancy mechanism. A control algorithm has been developed to control all the valves and pump. Also a computer program has been developed to communicate with the on board controller of the ROV.

#### Courses

- o Operating System and System Programming CS162, UC Berkeley
- o Digital Design & Computer Architecture, Prof. Onur Mutlu
- o Compilers CS143, Stanford
- o Mathematics for Computer Science 6.042J, MIT OCW
- o Introduction to Algorithms 6.006, MIT OCW
- o Practical Programming in C 6.087, MIT OCW

### Skills

Languages C, C++, Python, JAVA, Assembly(AVR, X86), Shell script, SQL, PHP, HTML, CSS

Tools Qt, Android, LLVM, Linux perf, BOLT, Awk, Flex/Bison

Embedded AVR Microcontrollers, Raspberry Pi, Arduino

Text Editing Vim, LATEX