Electrical Engineering Department EEL774 Pavameter Estimation and System Identification
Major Test

Date 5-5-09 Time allowed - Two hours. Full mains - 40 Answer all questions Q.1. Consider à non-linear différential equation  $\dot{x} + a(1-x^3)\dot{x} + b\dot{x} = 0$ Where 'a' and 'b' are unknown parameters to be estimated. De sign an experiment to identify 'a' and b using quasi-linearization method.

- 8 Marks Q.2. For the Kalman filter problem find the expression for error Covariance matrix P(k/k) in terms of P(k/k-1) - 4 Marks Q3 DeScribe a method for identification of the transfer function G(S, T) of the time-varying system. - 4 Marks 94 Consider a Scalar non-linear differential equation model of a System. The vectored of input and on that of the System is given. Use Laguerre - polynomial approach to TE estimate parameters
of the system recursively.

- 8 Marks

Q.5 Consider a Scalar linear differential equation model of a system

The record of input and output of the system is given. Use any Hermite orthogonal polynomial approach to estimate parameters of the System recurlively. Q6 Consider a system described by U(k) + Ex, when A\*(z'), B\*(z'), y(k) & Mark U(K) and Ex have What meanings.