Electrical Engineering Department I.I.T. Delhi

EEL101-Fundamentals of Electrical Engineering

Major	Exam. Part I (27-	11-2006) T	otal Mar	ks: 20	Fime: 20 minutes (sharp)				
Name:	***************************************	••••••		Entry No						
Note:-	(i) Answer all questions. (ii) No clarifications on questions. (iii) Assume data if any required. (iv) Wrong answers will attract 50% negative marks.									
I. <u>Tick</u>	mark the most ac	curate answer:			[10	marks]				
(1)	Which of the follow [A] Permanent mag [C] Hysteresis moto [E] None of the abo	net stepper motor	[B] Thr		on its stator and rotor: reluctance motor					
(2)	Switched Reluctance [A] 2-Phase Unipole [C] 3-Phase Unipole	ır	[B] 2-P	ing drive circui hase Bipolar & [C] above	t configuration:					
(3)	Following combination motor: [A] 12:10		rotor teet	•	sible in a switched r	eluctance				
(4)	 The reluctance torque in a VR stepper motor is: [A] independent of the direction of the current and the variation in the inductance of the phase winding [B] dependent on the direction of the current but independent of the variation in the inductance of the phase winding [C] independent of the direction of the current but dependent of the variation in the inductance of the phase winding [D] dependent of the direction of the current and the variation in the inductance of the phase winding 									
(5)	The stepper motor: [A] can have a D.C. winding on the rotor [B] rotor can be made out of soft magnetic material without any slots cut on it [C] can have squirrel-cage winding on the rotor [D] ean have salient pole permanent magnets on the rotor									
(6)	In a linear electrom [A] field energy and [C] field energy is le	co-energy are sa	me		gy is greater than co-e is zero	energy				
(7)	In rotating electrical constant, then the [A] synchronizing to [C] hysteresis torquiting to [C]	following torque co orque	mponent i B] sta		and rotor windings ar	e				
(8)	In which of the follonot zero: [A] synchronous me [C] reluctance moto	otor	[B] ind	ed between star luction motor ne of the above	tor and rotor magnetion	c field is				

(9)	A two-phase bipolar drive circuit configuration will be all right for the following motor. [A] Variable Reluctance Stepper motor [B] PM stepper motor [C] Switched Reluctance Motor [D] None of the above
(10)	The SRM has a: [A] PM rotor [B] Soft magnetic Rotor [C] PM stator [D] Hybrid Rotor
11. <u>w</u>	rite down your answers in one or two sentences [6marks]
(1)	What is the major disadvantage of a PM motor?
(2)	What is the important advantage of an axial flux PM BLDC motor?.
(3)	What is the basic difference between an SRM and a VR Stepper Motor?
(4)	What is the use of Z-parameters of a two-port network?
(5)	Draw an integrator circuit using an OPAMP.
(6)	Draw a voltage follower circuit using an OPAMP.
III.	Fill in the missing word/words: [4 marks]
(1)	In a linear magnetic circuit, the field energy is equal to the energy stored in the magnetic field and the coenergy equal to the energy stored in the
(2)	The input and output impedances of an OPAMP respectively are
(3)	The electrical machine, which can be represented by a two-port network. is
(4)	The steady state response of R-L series circuit and R-C circuit for a step input of voltage V,

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Major Exam. Part II ((27-11-2006)	Total Marks:	0.0	Time: foe minutes	(sharn)
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Name: Entry No.....

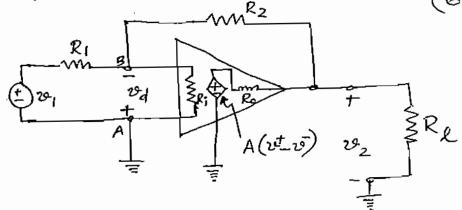
Note:- (i) Answer all questions.

(ii) No elarifications on questions except for printing mistakes, if any.

(iii) Assume data if any required.

(iv) No negative marks.

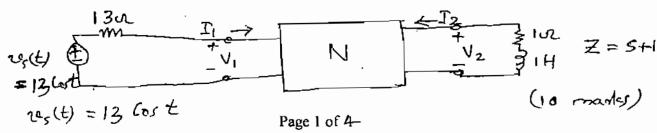
I) In figure given below, $R_1 = 15 \text{ k/L}$, $R_2 = 45 \text{ k/L}$, $R_0 = 0$ $R_1 = 400 \text{ k/L}$, and $A = 10^{4}$. Find $2^{4}2/2^{4}$. Assume the amplifier is not saturated. (6 marks)

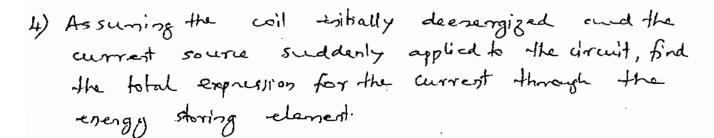


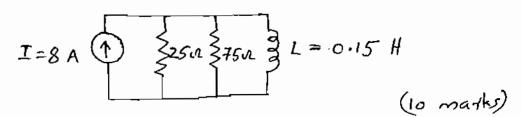
2) Design a circuit wing opamps with x(t) by input to generate output y(t) which satisfies the the following equation:

$$2y''(t) - y'(t) + 5y(t) = x(t)$$
(10 marks)

3) The Z-parameters of a two-port network are given by: $Z_{11} = 3s + 1/s$, $Z_{12} = Z_{21} = 4s$, $Z_{22} = 4s + 2$ The network is connected to a source and load as shown balow. And Z_{11} , Z_{12} , Z_{13} , and Z_{23} .







5) The A-i relationship for an electromagnet system es groven by: A = 1.8 i 1/3

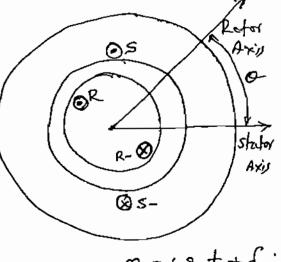
where g is the eingap length. For a current i=3A, and g = 1 mm, determine the mechanical force on the moving part.

(a) Using the field energy of the syleng by Using the wesengy of the syleng (6 marks)

The rotating machine whows in the figure has the following paraneters.

Lss = 0.19H, Lgg=0.08H, Lsa = 0.09 Cos O H

(a) The notor is discon at 3000 spro. If the stator winding carries a current of 7 A (8ms) at 50 Hz, determine the instantaneous Voltage and sms voltage induced in the



a=wmt+6

notor wil. Determine the fequenty of the notor enduced voltage. (12, marks)

- A 10 KW, 100V, 1200 April DC Shust generator has an armatune resistance Ra = 0.15 M, shust field winding resistance Rf = 85 M, and the numbered turns / pole is 1000. The rated Datamine the full load efficiency and the terminal voltage at full load.

 (6 marks)
- 3). Design the stater and roter poles/slots combinations for a density-slatted salient relutarion motor with a stap angle of 22.5°.

 If the dL = 1.5 mH/raday, Calculate the torque developed for a phase current of 10A. Show the motor sketch and ruggest

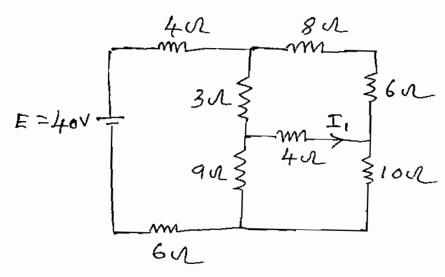
appropriate drive circuits and just for its operation in both the direction by indicating the switching sequence. (10 marks)

9) A 1-Phase, 20 KVA, 220/440 V, 50 Hz Tauntomer gave the following best results:

Open anuit Test (440V side Open): 220V, 8A, 600W Short anuit Test (220 V side shirted): 30V, 50A, 900W

- (a) Derive the approximate equivalent circuit.
- by Determine the voltage regulation at fullload, 0.8 PF lagging.
- the transfermer, and at what load this will occurs.

10) In the circuit shown below, (a) find the current delivered by the battery and (b) find the current I, throughthe 4 12 resilence.



(10 marky)

- 12) Write down the types of stators (structure and winding) and notest (structure and winding) that can be used in the following maker.
 - (a) Paromasent magnet stepper motor
 - chy Three-Phan Synchronous Mohr
 - (1) Three-Phase Induction motor
 - (d) Switched Reductione motor (4 marks)

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