## EEL 878: Artificial Intelligence for Control Applications

## MAJOR TEST

Timo: 2 hrs
Hex Herl: 30
April 30, 2008

Assume that ANFIS (Adaptive Neuro-Fuzzy Inference System) has two imputs, X, and Zz, and one output J. Each imput is represented by two fuzzy
sets, and the output by a zero-order polynomial
(J=k, where k is a constant). Represent this ANFIS by a six-layer feed-forward neural network and describe the operations involved at each layer. Q2: Consider the fuzzy system concerning the terminal rultage and speed of an electric motor, described by the membership functions

x 100 150 200 250 300

4 (x) 1 0.8 0.5 0.2 0. 7 1600 1800 2000 2200 2400 MB(4) 1 0.9 0.7 0.3 0 Input: Voltage is rather small (x i A)

Input: Voltage is rather small (X is A) THEN speed is small (X is B)

Rule: IF willage: small (X is A) THEN speed is small (X is B)

Inference: Spead is rather small (J & B')

Assume that the wiput fuzzy set A'

15 a puigleton at X0 = 125. Betermine the inference fuzzy set B' of the fuzzy ogstern. Use piecewise continuous approximations of graphs of Ma(x) and MB(J). --- 10 marks Consider the network shown in the figure. o(a) = 1-a; a' represents the activation value for the node. The bearing constant 7=0-1. The dervid output is J. The wishall weights ere: W10 = 1, W1 = 3, W12 = 4, W20 = -6, W21 = 6, W22 = 5 (e) with report reactor  $x = [1 \ 0]^T$  and desired output 18 =-3.92, 10, = 2 and 12=4 (4) y=1, update the weights for one step.
(b) Compute the error with the same updated weights.
for withal weights and updated weights. --- 10 marks A function approximation problem has to be solved. We went to attempt an SVM ( Support Vester Machini) solution. We de wide to by first a linear regression lyperplane. Explain the SVM algorithm that serves this objective.

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