Department of Electrical Engineering 17 Delhi

EEL 841 Solvel State Controlles for Donés

Max Marks 40 MAJOR TEST 05/05/07 Time 2 hrs Attempt All questions

- Q1 (a) In a 3-phase, 2-pole squired cage, distributed states winding induction meter, fed from a 50 Hz, 3-phase six stepped invertor, from the basic principles derive the expression for MMF waveform in terms of 'h' and 'k' th order space and time harmonines.
- (b) For the above operating conditions, goto oibtain the speed and direction of rotation the MMF harmonics with respect to the synchronous speed induction meter for the following space and time harmonics
- (i) h=17 and K=11 (ii) h= 13 and k=31 and (iii) h=7 and k=7
- Q2. In a magnetisation flux ordented indirect vector control of a 3-phase squincel cage induction motor didox, from the basic principles obtain the expressions for St and decoupling stringial i'dg in synchronometry obtating reference frame with Yam =0 and Y = 4 net flux linkago. Draw suitable thator dragram and the block dragram for the above decoupling [10]
- Q3. (a) A 8/6 pole SRM has starta/rotar pole emples of 20°, draw the inductance profiles for four phases of the planter. The SRM is fed from a 1000 to supply has Lmin = 5 m/H and Lmay = 20 mH it draws 5 Amp under steachy state (onclition with wr = 100 rad/s. It has a tolar position encoder having four optical servors and interrupting disk with the rotor profile sensors are blaced on the left edge.

Obtain the sensor sygnals in real time.

[5]

- (b) Give suitable hardware layout for the above nontioned of SRM drive chosed loop control using .TI 32 bit DSP, supports by a control block dragram. Give flow charet for a software algorithm for the abovementament drive white in sperathon in real time.
- Q4. (a) Give description of operation of a PMBLDCMotor which is a trapozolded voltage SPM drive. Give suitable layout find control signals for a feed back mode 2/3/3 angle Smitch on mode operation in Phill mode, current controlled operation. for a 3-phase stator winding layoutand its power circut. [6]
 - (b) Above PMBLDC motor is fed from a 1000 DC SWPBy having base speed of 500 pm, runs with trapizordal back vertage of 45 V (peak). Find its running speed. If the input anneal be 10ADC, obtain the resistance [4] perphase.

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