$PT'' \leftarrow P(K) + 000$ $\frac{1}{2} \left(\frac{1}{2} \left(\frac{1}{2} \right) \right) = \frac{1}{2} \left(\frac{1}{2} \left(\frac{1}{2}$ A & B eun BEFFTU AFRB => A-C-FPT **Definition 13.1 (Parameterized reduction).** Let $A, B \subseteq \Sigma^* \times \mathbb{N}$ be two parameterized problems. A parameterized reduction from A to B is an algorithm that, given an instance (x,k) of A, outputs an instance (x',k') of B such that 1. (x,k) is a yes-instance of A if and only if (x',k') is a yes-instance of B, $2. k' \leq g(k) \text{ for some computable function } g, \text{ and}$ $3. \text{ the running time is } f(k) \cdot |x|^{\mathcal{O}(1)} \text{ for some computable function } f.$

BEFTTTO h(k)

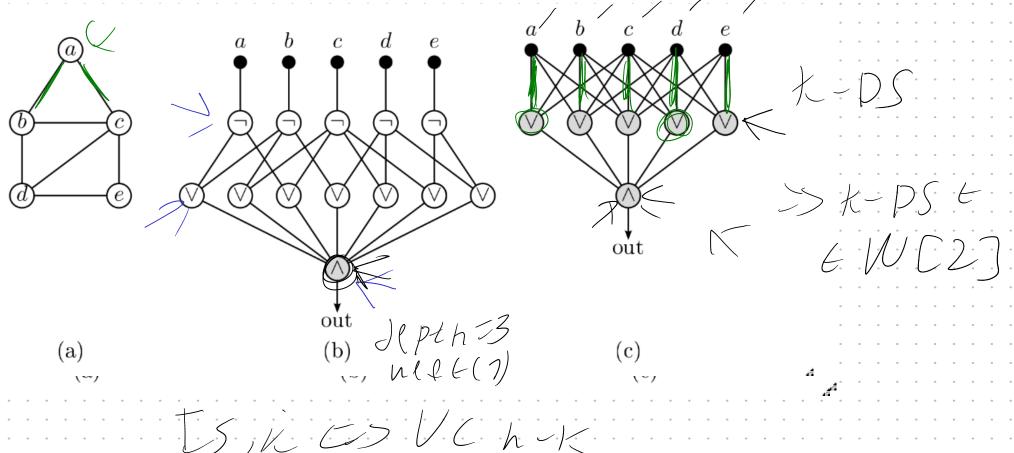
KIS ->K-C/i9hl K-Clight $(6,K) \rightarrow (6,K) K - 15 L_{PT} K - dight$ $\frac{1}{2} \left(\frac{1}{2} \right) = \frac{1}{2} \left(\frac{1}{2} \right) = \frac{1}$ $(G,K) \rightarrow (G,K) V f$ LIS LR K-VC

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A CEPT B - FPT C -> A CEPT C

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KxK LITTING Set 275; 505; tø u Socolubuci) + 1 ETH THE KXK HS & + (20 (KI OGK) O()) 1 S (O (O (M m h (i))) (I) /

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Som - in Stance KxK H-S $S_{\chi} \rightarrow S_{\chi,\mathcal{G}} \left(\mathcal{G}_{\chi,\mathcal{G}} \right) \left(\mathcal{G}_{\chi,\mathcal{G}} \right)$ CSXC) plan Sx O Colunto) SX14 (j) = Zytk lan Syncolnowij P'DOD(K) (D(1)D(2), P(K))P

 $= \int_{\mathcal{A}} \frac{f(y)}{f(y)} \int_{\mathcal{A}} \frac{f(y)}{f(y)} dy$ $\int_{\mathcal{A}} \int_{\mathcal{A}} \int$ $\int_{a}^{b} \int_{a}^{b} \int_{a$ D(i) I I Juhan

 $XP = IIAE(n^{f(K)})$ K-COlbhikg EXP, Junga 2-66/64: ng Et(h(3))->