

LINEAR ALGEBRA : HOMEWORK 11

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Part 1. Eigenvalues and Eigenvectors Continued, Diagonalization

1.

a.

$$\begin{aligned} A &= \begin{pmatrix} 7 & -1 & -4 \\ 14 & 1 & -12 \\ 8 & -1 & -5 \end{pmatrix} \\ \therefore p_A(\lambda) &= \begin{vmatrix} 7-\lambda & -1 & -4 \\ 14 & 1-\lambda & -12 \\ 8 & -1 & -5-\lambda \end{vmatrix} \\ &= (7-\lambda)((1-\lambda)(-5-\lambda) - 12) \\ &\quad + (14(-5-\lambda) + 96) \\ &\quad - 4(-14 - 8(1-\lambda)) \\ &= -(\lambda+1)(\lambda^2 - 4\lambda + 5) \\ \therefore \lambda &= -1 \end{aligned}$$

Therefore, as $p_A(\lambda)$ does not split completely, A is not diagonalizable.

$$\begin{aligned} V_{-1} &= N \begin{pmatrix} 8 & -1 & -4 \\ 14 & 2 & -12 \\ 8 & -1 & -4 \end{pmatrix} \\ &= N \begin{pmatrix} 8 & -1 & -4 \\ 14 & 2 & 12 \\ 0 & 0 & 0 \end{pmatrix} \\ &= \text{span} \left\{ \begin{pmatrix} 2 \\ 4 \\ 3 \end{pmatrix} \right\} \end{aligned}$$

b.

$$\begin{aligned} p_A(\lambda) &= -(\lambda+1)(\lambda^2 - 4\lambda + 5) \\ &= -(\lambda+1)(\lambda - 2 + i)(\lambda - 2 - i) \\ \therefore \lambda &= -1, 2 + i, 2 - i \end{aligned}$$

$$\begin{aligned}
V_{-1} &= \text{span} \left\{ \begin{pmatrix} 2 \\ 4 \\ 3 \end{pmatrix} \right\} \\
V_{2+i} &= N \begin{pmatrix} 5-i & -1 & -4 \\ 14 & -1-i & -12 \\ 8 & -1 & -7-i \end{pmatrix} \\
&= \left\{ \begin{pmatrix} 1 \\ 1-i \\ 1 \end{pmatrix} \right\} \\
V_{2-i} &= N \begin{pmatrix} 5+i & -1 & -4 \\ 14 & -1+i & -12 \\ 8 & -1 & -7+i \end{pmatrix} \\
&= \left\{ \begin{pmatrix} 1 \\ 1+i \\ 1 \end{pmatrix} \right\}
\end{aligned}$$

Therefore, for all three eigenvalues, the algebraic and geometric multiplicities are 1. Therefore, A is diagonalizable.

$$\begin{aligned}
D &= \begin{pmatrix} -1 & 0 & 0 \\ 0 & 2+i & 0 \\ 0 & 2-i & 0 \end{pmatrix} \\
P &= \begin{pmatrix} 2 & 1 & 1 \\ 4 & 1-i & 1+i \\ 3 & 1 & 1 \end{pmatrix}
\end{aligned}$$

2. FOR THE FOLLOWING LINEAR TRANSFORMATION FIND THE EIGENVALUES AND A BASIS FOR THE EIGENSPACE OF EACH EIGENVALUE. DETERMINE WHETHER THE TRANSFORMATION IS DIAGONALIZABLE.

$$\begin{aligned}
T(x, y, z) &= (2x + y, y - z, 2y + 4z) \\
T : \mathbb{R}^3 &\rightarrow \mathbb{R}^3
\end{aligned}$$

$$\begin{aligned}
P_T(\lambda) &= |[T]_E - \lambda I| \\
&= \left| \begin{pmatrix} [T(1, 0, 0)]_E & [T(0, 1, 0)]_E & [T(0, 0, 1)]_E \end{pmatrix} - \lambda I \right| \\
&= \left| \begin{pmatrix} [(2, 0, 0)]_E & [(1, 1, 2)]_E & [(0, -1, 4)]_E \end{pmatrix} - \lambda I \right| \\
&= \left| \begin{pmatrix} 2 & 1 & 0 \\ 0 & 1 & -1 \\ 0 & 2 & 4 \end{pmatrix} - \begin{pmatrix} \lambda & 0 & 0 \\ 0 & \lambda & 0 \\ 0 & 0 & \lambda \end{pmatrix} \right| \\
&= \begin{vmatrix} 2-\lambda & 1 & 0 \\ 0 & 1-\lambda & -1 \\ 0 & 2 & 4-\lambda \end{vmatrix} \\
&= (2-\lambda)((1-\lambda)(4-\lambda) + 2) \\
&= (2-\lambda)(\lambda^2 - 5\lambda + 6) \\
&= -(\lambda - 2)^2(\lambda - 3) \\
\therefore \lambda &= 2, 3
\end{aligned}$$

$$\begin{aligned} V_1 &= N \begin{pmatrix} 0 & 1 & 0 \\ 0 & -1 & -1 \\ 0 & 2 & 2 \end{pmatrix} \\ &= \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \right\} \end{aligned}$$

$$\begin{aligned} V_2 &= N \begin{pmatrix} -1 & 1 & 0 \\ 0 & -2 & -1 \\ 0 & 2 & 1 \end{pmatrix} \\ &= N \begin{pmatrix} -1 & 1 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 0 \end{pmatrix} \\ &= \text{span} \left\{ \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix} \right\} \end{aligned}$$

For eigenvalue 2, the geometric multiplicity is not equal to the algebraic multiplicity. Therefore, the transformation is not diagonalizable.

3.

$$\begin{aligned} \det(A - I) &= 0 \\ Ax &= 3x \end{aligned}$$

Therefore, 1 and 3 are eigenvalues of A .

As $\text{rank}(A + I) = 2$, there is a zero row in $(A - I)$. Therefore,

$$\det(A + I) = 0$$

Therefore, -1 is an eigenvalue of A .

a. As

$$\lambda = -1, 1, 3$$

$$P_A(\lambda) = (\lambda + 1)(\lambda - 1)(\lambda - 3)$$

b.

$$D = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 3 \end{pmatrix}$$

As $A \sim D$, the trace of A is equal to the trace of D .

Therefore, the trace of A is 3.

c. As $A \sim D$, $\det A = \det D$.

Therefore,

$$\det A = -3$$

d. As -3 is not an eigenvalue of A ,

$$\det(A + 3I) \neq 0$$

Therefore, $(A + 3I)$ is invertible.

Part 2. Orthogonality

1. WHICH OF THE FOLLOWING VECTOR SPACES IS AN INNER PRODUCT SPACE?

a.

$$\left\langle \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}, \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \right\rangle = 8x_1x_2$$

As $8x_1x_2$ may be negative, it is not an inner product space.

b.

$$\left\langle \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}, \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \right\rangle = x_1^2 + 7x_2^2$$

$$\therefore \langle v_1, v_1 \rangle \geq 0$$

The equality holds if and only if $v_1 = \mathbb{O}$.

$$\begin{aligned} \langle v_1 + v_2, v_3 \rangle &= (x_1 + y_1)z_1 + 7(x_2 + y_2)z_2 \\ &= x_1z_1 + y_1z_1 + 7x_2z_2 + 7y_2z_2 \\ &= \langle v_1, v_3 \rangle + \langle v_2, v_3 \rangle \end{aligned}$$

$$\begin{aligned} \langle \alpha v_1, v_2 \rangle &= \alpha x_1y_1 + 7\alpha x_2y_2 \\ &= 7\langle v_1, v_2 \rangle \end{aligned}$$

$$\begin{aligned} \overline{\langle v_2, v_1 \rangle} &= x_1y_1 + 7x_2y_2 \\ &= \langle v_1, v_2 \rangle \end{aligned}$$

Therefore, it is an inner product space.

c. Let

$$\begin{aligned} A &= \begin{pmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \end{pmatrix} \\ B &= \begin{pmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{pmatrix} \\ \therefore AB &= \begin{pmatrix} x_{11}y_{11} + x_{12}y_{21} & x_{11}y_{12} + x_{12}y_{22} \\ x_{21}y_{11} + x_{22}y_{21} & x_{21}y_{12} + x_{22}y_{22} \end{pmatrix} \\ \therefore \text{trace}(AB) &= x_{11}y_{11} + x_{12}y_{21} + x_{21}y_{12} + x_{22}y_{22} \end{aligned}$$

$$\begin{aligned} \langle A, B \rangle &= \text{trace}(AB) \\ &= x_{11}y_{11} + x_{12}y_{21} + x_{21}y_{12} + x_{22}y_{22} \end{aligned}$$

Therefore,

$$\langle A, A \rangle = x_{11}^2 + 2x_{12}x_{21} + x_{22}^2$$

$\text{trace}(A^2)$ may be negative. Therefore, it is not an inner product space.