### ORDINARY DIFFERENTIAL EQUATIONS

AAKASH JOG

#### First Order ODEs

# Linear Differential Equations with Coefficients Independent of y : y' + p(x)y = q(x)

1: Calculate the integrating factor

$$\mu(x) \!=\! e^{\int p(x)\mathrm{d}x}$$

2: Solve

$$\mu(x)y' + \mu(x)p(x)y = \mu(x)q(x)$$
$$\therefore (\mu(x)y)' = \mu(x)q(x)$$

$$y = \frac{1}{\mu(x)} \int \mu(x) q(x) dt$$

# Exact Differential Equations : M(x,y) + N(x,y)y' = 0

$$\psi = \int M(x,y) dx$$

$$= a(x,y) + h(y)$$

$$\therefore \frac{\partial \psi}{\partial y} = \frac{\partial a}{\partial y} + h'(y)$$

- 2: Compare  $\frac{\partial \psi}{\partial y}$  and N to find h'(y) and hence h(y).

### Bernoulli Differential Equations : $y' + p(x)y = q(x)y^n$ , 1.3

1: Divide the equation by  $y^n$ .

$$y^{-n}y' + p(x)y^{1-n} = q(x)$$

2: Substitute

$$\nu = y^{1-n}$$

3: Differentiate  $\nu$ 

$$\nu' = (1-n)y^{-n}y'$$

4: Substitute

$$y^{1-n} = \nu$$

$$y^{-n}y' = \frac{1}{1-n}\nu'$$

5: Solve the linear DE in 
$$\nu$$

$$\frac{1}{1-n}\nu' + p(x)\nu = q(x)$$

#### **1.4** Separable Differential Equations : N(y)y' = M(x)

1: Separate the variables and integrate

$$N(y)dy = M(x)dx$$

$$\therefore \int N(y) dy = \int M(x) dx$$

# **1.5** Homogeneous Differential Equations : y' = f(x,y) =

1: Write the function as a function of  $\frac{x}{y}$  or  $\frac{y}{x}$ 

$$\frac{\mathrm{d}y}{\mathrm{d}x} = F\left(\frac{y}{x}\right)$$

Date: 2014-15.

$$\frac{y}{x} = z$$

$$\therefore y = xz$$

$$\frac{dy}{dx} = z + x \frac{dz}{dx}$$

3: Substitute z and  $\frac{dz}{dx}$ 

$$z + x \frac{\mathrm{d}z}{\mathrm{d}x} = F(z)$$

4: Solve the differential equation in z and x

# **Riccati Equations**: $y' = f_0(t) + f_1(t)y + f_2(t)y^2$

This method is applicable only if at least one solution is known.

- 1: Let  $y_1$  be a known solution.

$$y = y_1 + \frac{1}{u(t)}$$

3: Differentiate y

$$y' = y_1' - \frac{u'}{u^2}$$

4: Substitute  $y = y_1 + \frac{1}{u(t)}$  and  $y' = y_1' - \frac{u'}{u^2}$  in original equation and

$$y_1' - \frac{u'}{u^2} = f_0(x) + f_1(x) \left( y_1 + \frac{1}{u} \right) + f_2(x) \left( y_1 + \frac{1}{u} \right)^2$$

$$\therefore y_1' - \frac{u'}{u^2} = \underbrace{\left( f_0(x) + f_1(x) y_1 + f_2(x) y_1^2 \right)}_{1} + f_1(x) \frac{1}{u} + f_2(x) \left( \frac{2y_1}{u} + \frac{1}{u^2} \right)$$

$$\therefore -\frac{u'}{u^2} = \underbrace{\frac{f_1(x)}{u} + \frac{2f_2(x) y_1 u + f_2(x)}{u^2}}_{1}$$

$$\therefore u' = \left( -f_1(x) - 2f_2 y_1 \right) u - f_2(x)$$

- 5: Solve this differential equation in u.
- 6: Substitute u in

$$y = y_1 + \frac{1}{u(t)}$$

# **1.7** Non-exact Differential Equations : M(x, y) dx +N(x,y)dy = 0 and $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$

1: If  $\frac{M_y - N_x}{N}$  is a function of x only,

$$\mu(x) = e^{\int \frac{M_y - N_x}{N} \, \mathrm{d}x}$$

2: If  $\frac{N_x - M_y}{M}$  is a function of y only,

$$\mu(y) = e^{\int \frac{N_x - M_y}{M} \, \mathrm{d}y}$$

3: If  $\frac{y^2(M_y-N_x)}{xM+yN}$  is a function of  $\frac{x}{y}$  only,

$$\mu\left(\frac{x}{y}\right) = e^{\int \frac{y^2(M_y - N_x)}{xM + yN} d\left(\frac{x}{y}\right)}$$

4: If  $\frac{x^2(N_x-M_y)}{xM+yN}$  is a function of  $\frac{y}{x}$  only,

$$\mu\left(\frac{y}{x}\right) = e^{\int \frac{x^2(N_x - M_y)}{xM + yN} d\left(\frac{y}{x}\right)}$$



5: If  $\frac{N_x - M_y}{xM - yN}$  is a function of xy only,

$$\mu(xy) = e^{\int \frac{N_x - M_y}{xM - yN} d(xy)}$$

6: If  $\frac{M_y - N_x}{z_- N_- z_- M}$  is a function of z(x,y) only,

$$\mu(z) = e^{\int \frac{M_y - N_x}{z_x N - z_y M} \, \mathrm{d}z}$$

7: Multiply the equation by  $\mu$  and solve the exact differential equation  $\mu M(x,y) dx + \mu N(x,y) dy = 0$ 

#### Existence and Uniqueness

**Definition 1** (Lipschitz function). A function if said to be Lipschitz in y if

$$|f(x)-f(y)| \le C|x-y|$$

for all x and y in the interval, and where C is independent of x and y.

**Theorem 1** (Existence and Uniqueness Theorem). Let f(x,y) be a continuous function of x, y in an open rectangle D, i.e. not including its boundaries, and Lipschitz in y. Then there exists an interval I such that  $x_0 \in I$  and the solution for the initial value problem y' = f(x,y),  $y(x_0) = y_0$ , exists and is unique in I.

#### Showing that a IVP has a unique solution in a particular interval

1: Let the IVP be

$$y' = f(x,y)$$
$$y(x_0) = y_0$$

- 2: Show that f(x,y) is continuous in the interval.
- 3: Show that f(x,y) is Lipschitz in y in the interval, i.e.

$$|f(x)-f(y)| \le C|x-y|$$

for all x and y in the interval, with C independent of x and y.

#### Second Order ODEs

# Linear Homogeneous Differential Equations with Constant Coefficients: ay'' + by' + cy = 0

1: Let

$$y = e^{\lambda t}$$
$$y' = \lambda e^{\lambda t}$$
$$y'' = \lambda^2 e^{\lambda t}$$

2: Substitute into the equation

$$a\lambda^{2}e^{\lambda t} + b\lambda e^{\lambda t} + ce^{\lambda t} = 0$$
$$\therefore a\lambda^{2} + b\lambda + c = 0$$

3: Solve the quadratic equation in y

$$\lambda_{1,2} = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

4: If  $\lambda_1$  and  $\lambda_2$  are real and distinct,

$$y=c_1e^{\lambda_1t}+c_2e^{\lambda_2t}$$

5: If  $\lambda_1 = \lambda_2$ ,

$$y = c_1 e^{\lambda_1 t} + t c_2 e^{\lambda_1 t}$$

6: If  $\lambda_1 = \overline{\lambda}_2 = \alpha + i\beta$ ,

$$y = c_1 e^{\alpha t} \cos \beta t + c_2 e^{\alpha t} \sin \beta t$$

# Linear Non-homogeneous Differential Equations: y'' + p(t)y' + q(t)y = g(t)

- 1: Solve the corresponding homogeneous differential equation y'' + p(t)y' +
- Let the solution of the corresponding homogeneous differential equation
- 3: Guess a particular solution,  $y_p(t)$ , using the method of undetermined coefficients or the method of variation of parameters.
- The solution to the ODE is

$$y = y_h + y_p$$

#### 2.2.1 Method of Undetermined Coefficients

1: Guess a particular solution to the equation.

	g(t)	$y_p(t)$
2:	$\sum_{i=0}^{n} a_i t^i$ $ae^{\beta t}$ $a\cos(\beta t)$ $a\sin(\beta t)$ $a\cos(\beta t) + b\sin(\beta t)$	$\sum_{i=0}^{n} A_i t^i$ $Ae^{\beta t}$ $A\cos(\beta t) + B\sin(\beta t)$ $A\cos(\beta t) + B\sin(\beta t)$ $A\cos(\beta t) + B\sin(\beta t)$

3: The general solution to the equation is

$$y = y_h + y_p$$

#### 2.2.2 Method of Variation of Parameters

- 1: Let  $y_1(t)$  and  $y_2(t)$  be two solutions to the corresponding homogeneous equation.
- 2: Solve the equation

$$\begin{pmatrix} y_1(t) & y_2(t) \\ y_1'(t) & y_2'(t) \end{pmatrix} \begin{pmatrix} u_1'(t) \\ u_2'(t) \end{pmatrix} = \begin{pmatrix} 0 \\ g(t) \end{pmatrix}$$

 $y_p = u_1(t)y_1(t) + u_2(t)y_2(t)$ 

for  $u_1'(t)$  and  $u_2'(t)$ .

for 
$$a_1$$
 (t) and  $a_2$  (t).

#### Fundamental Set of Solutions of Linear Second Or- $\overline{2.3}$ der Homogeneous ODEs

1: Find the Wronskian

$$W(y_1,y_2)(x) = \begin{vmatrix} y_1(x) & y_2(x) \\ y_1'(x) & y_2'(x) \end{vmatrix}$$
  
=  $y_1(x)y_2'(x) - y_1'(x)y_2(x)$ 

2: If  $W(y_1,y_2)(x) \neq 0$ , then  $\{y_1,y_2\}$  is a fundamental set of solutions.

### 2.4 Abel's Theorem

Theorem 2 (Abel's Theorem).

$$W(y_1,y_2)(x) = y_1(x)y_2(x)' - y_1(x)'y_2(x) = Ce^{-\int p(x)dx}$$

Therefore, as  $Ce^{-\int p(x)dx}$  can either be always zero or never zero, the Wronskian can also be always zero or never zero. Hence, a set of solutions  $y_1$  and  $y_2$ , for which the Wronskian is zero for finite values of x cannot be a fundamental set of solutions.

# **2.5** Euler's Equations : $ax^2y'' + bxy' + cy = 0$

1: Let

$$y = x^{r}$$
  
 $y' = rx^{r-1}$   
 $y'' = r(r-1)x^{r-2}$ 

2: Substitute into the equation,

$$ax^{2}r(r-1)x^{r-2} + bxrx^{r-1} + cx^{r} = 0$$
  
 $\therefore x^{r}(ar(r-1) + br + c) = 0$   
 $\therefore ar(r-1) + br + c = 0$ 

3: Solve the equation in r,

$$ar^2 - ar + br + c = 0$$

$$r^2(a)-r(b-a)+c=0$$

$$\therefore r_{1,2} = \frac{(a-b) \pm \sqrt{(b-a)^2 - 4ac}}{2a}$$

4: If  $r_1$  and  $r_2$  are real and distinct.

$$y = c_1 x^{r_1} + c_2 x^{r_2}$$

5: If  $r_1 = r_2$ ,

$$y = c_1 x^{r_1} + c_2 x^{r_1} \ln x$$

6: If  $r_1 = \overline{r}_2 = \alpha + i\beta$ ,

$$y = c_1 x^{\alpha} \cos(\beta \ln x) + c_2 x^{\alpha} \sin(\beta \ln x)$$

# 2.6 Existence and Uniqueness

Theorem 3 (Existence and Uniqueness Theorem). The IVP

$$y'' + p(t)y' + q(t) = g(t)$$
  
 $y(t_0) = y_0$   
 $y'(t_0) = y'_0$ 

has a unique solution in an interval I if and only if the functions p(t), q(t), g(t) are continuous in an interval I, and  $t_0 \in I$ .

#### $\overline{2.7}$ Reduction of Order: y''+p(t)y'+q(t)=0, $y_1(t)$

1: Let

$$y_2(t) = y_1(t)\nu(t)$$
  

$$\therefore y_2' = y_1'(t)\nu(t) + y_1(t)\nu'(t)$$
  

$$\therefore y_2'' = y_1''(t)\nu(t) + 2y_1'(t)\nu'(t) + y_1(t)\nu''(t)$$

2: Substitute into the equation to get an ODE with  $\nu''(t)$  and  $\nu'(t)$ .

$$0 = y_1''(t)\nu(t) + 2y_1'(t)\nu'(t) + y_1(t)\nu''(t) + (y_1'(t)\nu(t) + y_1(t)\nu'(t))p(t) + y_1(t)\nu(t)q(t)$$

3: Let

$$k(t) = \nu'(t)$$
$$\therefore k'(t) = \nu''(t)$$

4: Substitute and solve the first order ODE in k.