

## ORDINARY DIFFERENTIAL EQUATIONS ASSIGNMENT 6

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### Part 1. Euler's Equations

#### Exercise 1.

In each of the following sections find the solution for the initial value problem.

(1)

$$\begin{aligned}2x^2y'' + xy' - 3y &= 0 \\ y(1) &= 1 \\ y'(1) &= 4\end{aligned}$$

(2)

$$\begin{aligned}4x^2y'' + 8xy' + 17y &= 0 \\ y(1) &= 2 \\ y'(2) &= -3\end{aligned}$$

(3)

$$\begin{aligned}x^2y'' - 3xy' + 4y &= 0 \\ y(1) &= 2 \\ y'(1) &= 3\end{aligned}$$

#### Solution 1.

(1)

$$2x^2y'' + xy' - 3y = 0$$

Let

$$y = x^r$$

Therefore,

$$\begin{aligned}y' &= rx^{r-1} \\ y'' &= r(r-1)x^{r-2}\end{aligned}$$

Therefore, substituting,

$$\begin{aligned} 2x^2r(r-1)x^{r-2} + xrx^{r-1} - 3x^r &= 0 \\ \therefore x^r (2r(r-1) + r - 3) &= 0 \\ \therefore 2r^2 - 2r + r - 3 &= 0 \\ \therefore 2r^2 - r - 3 &= 0 \end{aligned}$$

Therefore,

$$\begin{aligned} r &= \frac{1 \pm \sqrt{1+24}}{4} \\ &= \frac{1 \pm 5}{4} \end{aligned}$$

Therefore,

$$\begin{aligned} r_1 &= \frac{3}{2} \\ r_2 &= -1 \end{aligned}$$

Therefore,

$$\begin{aligned} y_1 &= x^{\frac{3}{2}} \\ y_2 &= x^{-1} \end{aligned}$$

Therefore,

$$\begin{aligned} y &= c_1y_1 + c_2y_2 \\ &= c_1x^{\frac{3}{2}} + c_2x^{-1} \end{aligned}$$

Therefore,

$$y' = \frac{3}{2}c_1x^{\frac{1}{2}} - c_2x^{-2}$$

Therefore, substituting  $y(1) = 1$  and  $y'(1) = 4$ ,

$$\begin{aligned} 1 &= c_1 + c_2 \\ 4 &= \frac{3}{2}c_1 - c_2 \end{aligned}$$

Therefore,

$$\begin{aligned} c_1 &= 2 \\ c_2 &= -1 \end{aligned}$$

Therefore,

$$y = 2x^{\frac{3}{2}} - x^{-1}$$

(2)

$$4x^2y'' + 8xy' + 17y = 0$$

Let

$$y = x^r$$

Therefore,

$$y' = rx^{r-1}$$

$$y'' = r(r-1)x^{r-2}$$

Therefore, substituting,

$$4x^2r(r-1)x^{r-2} + 8xrx^{r-1} + 17x^r = 0$$

$$\therefore x^r (4r(r-1) + 8r + 17) = 0$$

$$\therefore 4r^2 - 4r + 8r + 17 = 0$$

$$\therefore 4r^2 + 4r + 17 = 0$$

Therefore,

$$\begin{aligned} r &= \frac{-4 \pm \sqrt{16 - 272}}{8} \\ &= \frac{-4 \pm 16i}{8} \end{aligned}$$

Therefore,

$$r_1 = -\frac{1}{2} + 2i$$

$$r_2 = -\frac{1}{2} - 2i$$

Therefore,

$$\begin{aligned} y_1 &= x^{r_1} \\ &= x^{-\frac{1}{2} + 2i} \\ &= e^{\ln x^{-\frac{1}{2} + 2i}} \\ &= e^{(-\frac{1}{2} + 2i) \ln x} \\ &= e^{-\frac{1}{2} \ln x} e^{2i \ln x} \\ &= e^{\ln x^{-\frac{1}{2}}} e^{2i \ln x} \\ &= x^{-\frac{1}{2}} (\cos(2 \ln x) + i \sin(2 \ln x)) \\ &= x^{-\frac{1}{2}} \cos(2 \ln x) + ix^{-\frac{1}{2}} \sin(2 \ln x) \end{aligned}$$

Therefore,

$$\begin{aligned} y &= c_1 \Re(y_1) + c_2 \Im(y_1) \\ &= c_1 x^{-\frac{1}{2}} \cos(2 \ln x) + c_2 x^{-\frac{1}{2}} \sin(2 \ln x) \end{aligned}$$

Therefore,

$$\begin{aligned} y' &= -\frac{1}{2} c_1 x^{-\frac{3}{2}} \cos(2 \ln x) - \frac{2}{x} c_1 x^{-\frac{1}{2}} \sin(2 \ln x) \\ &\quad - \frac{1}{2} c_2 x^{-\frac{3}{2}} \sin(2 \ln x) + \frac{2}{x} c_2 x^{-\frac{1}{2}} \cos(2 \ln x) \end{aligned}$$

Therefore, substituting  $y(1) = 2$  and  $y'(2) = -3$ ,

$$\begin{aligned}
 2 &= c_1 \cdot 1 \cdot \cos(0) + c_2 \cdot 1 \cdot \sin(0) \\
 &= c_1 \\
 -3 &= -\frac{1}{2}c_1 2^{-\frac{3}{2}} \cos(2 \ln 2) - \frac{2}{2}c_2 2^{-\frac{1}{2}} \sin(2 \ln 2) \\
 &= -\frac{1}{2} \cdot 2 \cdot \frac{1}{2\sqrt{2}} \cos(2 \ln 2) - c_2 \frac{1}{\sqrt{2}} \sin(2 \ln 2) \\
 &= -\frac{\cos(2 \ln 2)}{2\sqrt{2}} - c_2 \frac{\sin(2 \ln 2)}{\sqrt{2}} \\
 \therefore 3 - \frac{\cos(2 \ln 2)}{2\sqrt{2}} &= c_2 \frac{\sin(2 \ln 2)}{\sqrt{2}} \\
 \therefore \frac{3\sqrt{2}}{\sin(2 \ln 2)} - \frac{1}{2 \tan(2 \ln 2)} &= c_2
 \end{aligned}$$

Therefore,

$$y = 2x^{-\frac{1}{2}} \cos(2 \ln x) + \frac{3\sqrt{2}}{\sin(2 \ln 2)} - \frac{1}{2 \tan(2 \ln 2)} x^{-\frac{1}{2}} \sin(2 \ln x)$$

(3)

$$x^2 y'' - 3xy' + 4y = 0$$

Let

$$y = x^r$$

Therefore,

$$y' = rx^{r-1}$$

$$y'' = r(r-1)x^{r-2}$$

Therefore, substituting,

$$x^2 r(r-1)x^{r-2} - 3xr x^{r-1} + 4x^r = 0$$

$$\therefore x^r (r(r-1) - 3r + 4) = 0$$

$$\therefore r(r-1) - 3r + 4 = 0$$

$$\therefore r^2 - r - 3r + 4 = 0$$

$$\therefore r^2 - 4r + 4 = 0$$

Therefore,

$$r = \frac{4 \pm \sqrt{16 - 16}}{2}$$

$$= 2$$

Therefore,

$$y_1 = x^r$$

$$= x^2$$

$$y_2 = x^r \ln x$$

$$= x^2 \ln x$$

Therefore,

$$\begin{aligned} y &= c_1 y_1 + c_2 y_2 \\ &= c_1 x^2 + c_2 x^2 \ln x \end{aligned}$$

Therefore,

$$\begin{aligned} y' &= 2c_1 x + 2c_2 x \ln x + c_2 x^2 \frac{1}{x} \\ &= 2c_1 x + 2c_2 x \ln x + c_2 x \end{aligned}$$

Therefore, substituting  $y(1) = 2$  and  $y'(1) = 3$ ,

$$\begin{aligned} 2 &= c_1 + c_2 \ln 1 \\ &= c_1 \\ 3 &= 2c_1 + 2c_2 \ln 1 + c_2 \\ &= 2c_1 + c_2 \end{aligned}$$

Therefore,

$$\begin{aligned} c_1 &= 2 \\ c_2 &= -1 \end{aligned}$$

Therefore,

$$y = 2x^2 - x^2 \ln x$$

### Exercise 2.

Transformation into a constant coefficients equation:

(1) Substituting  $x = e^t$ , show that

$$\begin{aligned} x \frac{dy}{dx} &= \frac{dy}{dt} \\ x^2 \frac{d^2 y}{dx^2} &= \frac{d^2 y}{dt^2} - \frac{dy}{dt} \end{aligned}$$

(2) Conclude that

$$\begin{aligned} ax^2 \frac{d^2 y}{dx^2} + bx \frac{dy}{dx} + cy &= h(x) \\ \implies a \frac{d^2 y}{dt^2} + (b-a) \frac{dy}{dt} + cy &= h(e^t) \end{aligned}$$

### Solution 2.

(1)

$$\begin{aligned} x \frac{dy}{dx} &= e^t \frac{dy}{de^t} \\ &= e^t \frac{dy}{dt} \frac{dt}{de^t} \\ &= \frac{de^t}{dt} \frac{dy}{dt} \frac{dt}{de^t} \\ &= \frac{dy}{dt} \end{aligned}$$

$$\begin{aligned}
x^2 \frac{d^2 y}{dx^2} &= (e^t)^2 \frac{d^2 y}{d(e^t)^2} \\
&= \left( \frac{d(e^t)}{dt} \right)^2 \frac{d^2 y}{d(e^t)^2} \\
&= \left( \frac{d(e^t)}{dt} \right) \left( \frac{d(e^t)}{dt} \right) \frac{d}{d(e^t)} \left( \frac{dy}{d(e^t)} \right) \\
&= \left( \frac{d(e^t)}{dt} \right) \frac{d}{dt} \left( \frac{dy}{d(e^t)} \right) \\
&= \left( \frac{d(e^t)}{dt} \right) \frac{d}{dt} \left( \frac{dy}{d(e^t)} \right) + \frac{d}{dt} \left( \frac{d(e^t)}{dt} \right) \left( \frac{dy}{d(e^t)} \right) \\
&\quad - \frac{d}{dt} \left( \frac{d(e^t)}{dt} \right) \left( \frac{dy}{d(e^t)} \right) \\
&= \frac{d}{dt} \left( \frac{d(e^t)}{dt} \frac{dy}{d(e^t)} \right) - \frac{d}{dt} \left( \frac{d(e^t)}{dt} \right) \left( \frac{dy}{d(e^t)} \right) \\
&= \frac{d}{dt} \left( \frac{dy}{dt} \right) - \left( \frac{d(e^t)}{dt} \right) \left( \frac{dy}{d(e^t)} \right) \\
&= \frac{d^2 y}{dt^2} - \frac{dy}{dt}
\end{aligned}$$

(2)

$$\begin{aligned}
&ax^2 \frac{d^2 y}{dx^2} + bx \frac{dy}{dx} + cy = h(x) \\
\therefore a (e^t)^2 \frac{d^2 y}{d(e^t)^2} + b \frac{dy}{d(e^t)} + cy &= h(e^t) \\
\therefore a \left( \frac{d^2 y}{dt^2} - \frac{dy}{dt} \right) + b \frac{dy}{dt} + cy &= h(e^t) \\
\therefore a \frac{d^2 y}{dt^2} - a \frac{dy}{dt} + b \frac{dy}{dt} + cy &= h(e^t) \\
\therefore a \frac{d^2 y}{dt^2} + (b-a) \frac{dy}{dt} + cy &= h(e^t)
\end{aligned}$$

**Exercise 3.**

Use reduction of order to show that the second solution for a second-order Euler's equation with a double root  $r$  is  $x^r \ln x$ .

**Solution 3.**

$$y_1(x) = x^r$$

is a solution to the differential equation

$$ax^2 y'' + bxy' + cy = 0$$

$$y_1'(x) = rx^{r-1}$$

$$y_1''(x) = r(r-1)x^{r-2}$$

Substituting,

$$ax^2r(r-1)x^{r-2} + bxrx^{r-1} + cx^r = 0$$

$$\therefore x^r (ar(r-1) + br + c) = 0$$

$$\therefore ar(r-1) + br + c = 0$$

$$\therefore r = \frac{(a-b) \pm \sqrt{(b-a)^2 - 4ac}}{2a}$$

As the differential equation has a double root,

$$r = \frac{a-b}{2a}$$

Let

$$y_2(x) = \nu(x)y_1(x)$$

$$= \nu(x)x^r$$

$$= \nu(x)x^{\frac{a-b}{2a}}$$

Therefore,

$$y_2'(x) = \nu'(x)x^{\frac{a-b}{2a}} + \nu(x)\frac{a-b}{2a}x^{\frac{a-b-2a}{2a}}$$

$$= \nu'(x)x^{\frac{a-b}{2a}} + \nu(x)\frac{a-b}{2a}x^{\frac{-a-b}{2a}}$$

$$y_2''(x) = \nu''(x)x^{\frac{a-b}{2a}} + \nu'(x)\frac{a-b}{2a}x^{\frac{-a-b}{2a}}$$

$$+ \nu''(x)\frac{a-b}{2a}x^{\frac{-a-b}{2a}} + \nu'(x)\frac{a-b}{2a}\frac{-a-b}{2a}x^{\frac{-3a-b}{2a}}$$

Therefore, solving,

$$\nu(x) = \ln x$$

Therefore,

$$y_2(x) = \nu(x)x^r$$

$$x^2 \ln x$$

□

## Part 2. Existence and Uniqueness for High Order Equations

### Exercise 1.

In each of the following sections determine the largest interval in which the given initial value problem is certain to have a unique solution. Do not attempt to find the solution.

(1)

$$ty'' + 3y = t$$

$$y(1) = 1$$

$$y'(2) = 2$$

(2)

$$t(t-4)y'' - 3ty' + 4y = \sin t$$

$$y(-2) = 2$$

$$y'(-2) = 1$$

(3)

$$(x-2)y'' + y' + (x-2)\tan x = 0$$

$$y(3) = 1$$

$$y'(3) = 2$$

**Solution 1.**

(1)

$$ty'' + 3y = 0$$

$$\therefore y'' + \frac{3}{t}y = 0$$

$\frac{3}{t}$  is continuous on  $\mathbb{R} \setminus \{0\}$ .

Therefore, the largest interval in which the above function is continuous, which contains the given points  $t = 1$  and  $t = 2$ , is  $(0, \infty)$ .

Therefore, by the existence and uniqueness theorem, the initial value problem has a unique solution in  $(0, \infty)$ .

(2)

$$t(t-4)y'' - 3ty' + 4y = \sin t$$

$$\therefore y'' - \frac{3t}{t(t-4)} + \frac{4}{t(t-4)} = \frac{\sin t}{t(t-4)}$$

$-\frac{3t}{t(t-4)}$  is continuous on  $\mathbb{R} \setminus \{4\}$ .

$\frac{4}{t(t-4)}$  is continuous on  $\mathbb{R} \setminus \{0, 4\}$ .

$\sin t$  is continuous on  $\mathbb{R}$ .

Therefore, the largest interval in which the above functions are continuous, which contains the given point  $t = -2$ , is  $(-\infty, 0)$ .

Therefore, by the existence and uniqueness theorem, the initial value problem has a unique solution in  $(-\infty, 0)$ .

(3)

$$(x-2)y'' + y' + (x-2)\tan x = 0$$

$$\therefore y'' + \frac{1}{x-2}y' + \tan x = 0$$

$\frac{1}{x-2}$  is continuous on  $\mathbb{R} \setminus \{2\}$ .

$\tan x$  is continuous on  $\mathbb{R} \setminus \{\frac{\pi}{2} + k\pi | k \in \mathbb{Z}\}$ . Therefore, the largest interval in which the above functions are continuous, which contains the given



point  $t = 3$ , is  $\left(2, \frac{3\pi}{2}\right)$ .

Therefore, by the existence and uniqueness theorem, the initial value problem has a unique solution in  $\left(2, \frac{3\pi}{2}\right)$ .

### Part 3. The Wronskian

#### Exercise 1.

In each of the following sections find the Wronskian of the given pair of functions.

- (1)  $e^{2t}, e^{-\frac{3t}{2}}$
- (2)  $e^{-2t}, te^{-2t}$
- (3)  $e^t \sin t, e^t \cos t$
- (4)  $\cos^2 \theta, 1 + \cos 2\theta$

#### Solution 1.

(1)

$$y_1(t) = e^{2t}$$

$$y_2(t) = e^{-\frac{3t}{2}}$$

$$W = \begin{vmatrix} y_1(t) & y_2(t) \\ y_1'(t) & y_2'(t) \end{vmatrix}$$

Therefore,

$$\begin{aligned} W &= \begin{vmatrix} e^{2t} & e^{-\frac{3t}{2}} \\ 2e^{2t} & -\frac{3}{2}e^{-\frac{3t}{2}} \end{vmatrix} \\ &= \frac{3}{2}e^{2t}e^{-\frac{3t}{2}} - 2e^{2t}e^{-\frac{3t}{2}} \\ &= -\frac{e^{\frac{t}{2}}}{2} \end{aligned}$$

(2)

$$y_1(t) = e^{-2t}$$

$$y_2(t) = te^{-2t}$$

$$W = \begin{vmatrix} y_1(t) & y_2(t) \\ y_1'(t) & y_2'(t) \end{vmatrix}$$

Therefore,

$$\begin{aligned} W &= \begin{vmatrix} e^{-2t} & te^{-2t} \\ -2e^{-2t} & -2te^{-2t} \end{vmatrix} \\ &= -2te^{-2t}e^{-2t} + 2e^{-2t}e^{-2t} \\ &= 2e^{-4t} - 2te^{-4t} \end{aligned}$$

(3)

$$y_1(t) = e^t \sin t$$

$$y_2(t) = e^t \cos t$$

$$W = \begin{vmatrix} y_1(t) & y_2(t) \\ y_1'(t) & y_2'(t) \end{vmatrix}$$

Therefore,

$$\begin{aligned} W &= \begin{vmatrix} e^t \sin t & e^t \cos t \\ e^t \sin t + e^t \cos t & e^t \cos t - e^t \sin t \end{vmatrix} \\ &= (e^t \sin t) (e^t \cos t - e^t \sin t) - (e^t \cos t) (e^t \sin t + e^t \cos t) \\ &= e^{2t} \sin t \cos t - e^{2t} \sin^2 t - e^{2t} \sin t \cos t - e^{2t} \cos^2 t \\ &= -e^{2t} \end{aligned}$$

(4)

$$y_1(\theta) = \cos^2 \theta$$

$$y_2(\theta) = 1 + \cos 2\theta$$

$$W = \begin{vmatrix} y_1(\theta) & y_2(\theta) \\ y_1'(\theta) & y_2'(\theta) \end{vmatrix}$$

Therefore,

$$\begin{aligned} W &= \begin{vmatrix} \cos^2 \theta & 1 + \cos 2\theta \\ -2 \sin \theta \cos \theta & -2 \sin 2\theta \end{vmatrix} \\ &= -2 \sin 2\theta \cos^2 \theta + 2 \sin \theta \cos \theta (1 + \cos 2\theta) \\ &= -2 \sin 2\theta \cos^2 \theta + 2 \sin \theta \cos \theta + 2 \sin \theta \cos \theta \cos 2\theta \end{aligned}$$

**Exercise 2.**

If the Wronskian  $W$  of  $f$  and  $g$  is  $t^2 e^t$ , and if  $f(t) = t$ , find  $g(t)$ .

**Solution 2.**

$$\begin{aligned} W &= \begin{vmatrix} f(t) & g(t) \\ f'(t) & g'(t) \end{vmatrix} \\ &= \begin{vmatrix} t & g(t) \\ 1 & g'(t) \end{vmatrix} \\ &= tg'(t) - g(t) \end{aligned}$$

Therefore,

$$\begin{aligned} tg'(t) - g(t) &= t^2 e^t \\ \therefore g'(t) - \frac{1}{t}g(t) &= te^t \end{aligned}$$

Therefore,

$$\begin{aligned}\mu(t) &= e^{\int -\frac{1}{t} dt} \\ &= e^{-\ln t} \\ &= t^{-1}\end{aligned}$$

Therefore,

$$\begin{aligned}g(t) &= t \int t^{-1} t^2 e^t dt \\ &= t \int t e^t dt = 2te^{-4t} - 2te^{-4t} \\ &= t (2e^{-4t} - 2te^{-4t} + c) \\ &= 2te^{-4t} - 2t^2 e^{-4t} + ct\end{aligned}$$

### Exercise 3.

Verify that the functions  $y_1(x) = x$  and  $y_2(x) = xe^x$  are solutions for the equation

$$\begin{aligned}x^2 y'' - x(x+2)y' + (x+2)y &= 0 \\ x &> 0\end{aligned}$$

Do they constitute a fundamental set of solutions?

### Solution 3.

$$\begin{aligned}x^2 y'' - x(x+2)y' + (x+2)y &= x^2 y_1'' - x(x+2)y_1' + (x+2)y_1 \\ &= x^2 x'' - x(x+2)x' + (x+2)x \\ &= 0 - x(x+2) + x(x+2) \\ &= 0\end{aligned}$$

Therefore,  $y_1(x) = x$  is a solution to the equation.

$$\begin{aligned}x^2 y'' - x(x+2)y' + (x+2)y &= x^2 y_2'' - x(x+2)y_2' + (x+2)y_2 \\ &= x^2 (xe^x)'' - x(x+2)(xe^x)' + (x+2)xe^x \\ &= x^2 (2e^x + e^x x) - x(x+2)(e^x + e^x x) + (x+2)xe^x \\ &= 0\end{aligned}$$

Therefore,  $y_2(x) = xe^x$  is a solution to the equation.

$$\begin{aligned}W &= \begin{vmatrix} x & xe^x \\ 1 & e^x + e^x x \end{vmatrix} \\ &= xe^x + x^2 e^x - e^x\end{aligned}$$

As  $\forall x \in \mathbb{R}$ ,  $W \neq 0$ , the solutions form a fundamental set of solutions.

**Part 4. Linear Independence/ Independence of Functions****Exercise 1.**

In each of the following sections, determine whether the given pair of functions is linearly independent or linearly dependent using the linear dependence definition and using the Wronskian.

- (1)  $f(t) = t^2 + 5t$ ,  $g(t) = t^2 - 5t$   
 (2)  $f(\theta) = \cos 3\theta$ ,  $g(\theta) = 4 \cos^3 \theta - 3 \cos \theta$   
 (3)  $f(x) = e^{3x}$ ,  $g(x) = e^{3(x-1)}$

**Solution 1.**

(1)

$$\begin{aligned} f(t) &= t^2 + 5t \\ g(t) &= t^2 - 5t \end{aligned}$$

Therefore,

$$\begin{aligned} W &= \begin{vmatrix} f(t) & g(t) \\ f'(t) & g'(t) \end{vmatrix} \\ &= \begin{vmatrix} t^2 + 5t & t^2 - 5t \\ 2t + 5 & 2t - 5 \end{vmatrix} \\ &= (t^2 + 5t)(2t - 5) - (t^2 - 5t)(2t + 5) \\ &= 10t^2 \end{aligned}$$

If  $t = 0$ ,  $W = 0$ .

Therefore, as the Wronskian can be 0,  $f(t)$  and  $g(t)$  are linearly dependent.

(2)

$$\begin{aligned} f(\theta) &= \cos 3\theta \\ g(\theta) &= 4 \cos^3 \theta - 3 \cos \theta \\ &= \cos 3\theta \end{aligned}$$

Therefore,

$$\begin{aligned} W &= \begin{vmatrix} f(\theta) & g(\theta) \\ f'(\theta) & g'(\theta) \end{vmatrix} \\ &= \begin{vmatrix} \cos 3\theta & \cos 3\theta \\ -3 \sin 3\theta & -3 \sin 3\theta \end{vmatrix} \\ &= 0 \end{aligned}$$

Therefore, as the Wronskian is 0,  $f(t)$  and  $g(t)$  are linearly dependent.

(3)

$$\begin{aligned}
 f(x) &= e^{3x} \\
 g(x) &= e^{3(x-1)} \\
 &= e^{3x-3} \\
 &= \frac{e^{3x}}{e^3} \\
 &= \frac{f(x)}{e^3}
 \end{aligned}$$

Therefore,

$$\begin{aligned}
 W &= \begin{vmatrix} f(x) & g(x) \\ f'(x) & g'(x) \end{vmatrix} \\
 &= \begin{vmatrix} f(x) & \frac{f(x)}{e^3} \\ f'(x) & \frac{f'(x)}{e^3} \end{vmatrix} \\
 &= \frac{f(x)f'(x)}{e^3} - \frac{f'(x)f(x)}{e^3} \\
 &= 0
 \end{aligned}$$

Therefore, as the Wronskian is 0,  $f(t)$  and  $g(t)$  are linearly dependent.

## Part 5. Abel's Theorem

### Exercise 1.

Prove that if  $y_1$  and  $y_2$  are zero at the same point in  $I$ , then they cannot be a fundamental set of solutions on that interval.

### Solution 1.

Let  $t_0 \in I$ , such that  $y_1(t_0) = y_2(t_0) = 0$ .

Therefore,

$$\begin{aligned}
 W(t_0) &= \begin{vmatrix} y_1(t_0) & y_2(t_0) \\ y_1'(t_0) & y_2'(t_0) \end{vmatrix} \\
 &= \begin{vmatrix} 0 & 0 \\ y_1'(t_0) & y_2'(t_0) \end{vmatrix} \\
 &= 0
 \end{aligned}$$

Therefore, as the Wronskian is 0 at  $t_0$ ,  $y_1$  and  $y_2$  cannot be a fundamental set of solutions in  $I$ .  $\square$

### Exercise 2.

Prove that if  $y_1$  and  $y_2$  have maxima or minima at the same point in  $I$ , then they cannot be a fundamental set of solutions on that interval.

**Solution 2.**

If  $y_1$  and  $y_2$  have maxima or minima at some point  $t_0$  in  $I$ ,  $y_1'(t_0) = y_2'(t_0) = 0$ .

Therefore,

$$\begin{aligned} W(t_0) &= \begin{vmatrix} y_1(t_0) & y_2(t_0) \\ y_1'(t_0) & y_2'(t_0) \end{vmatrix} \\ &= \begin{vmatrix} y_1(t_0) & y_2(t_0) \\ 0 & 0 \end{vmatrix} \\ &= 0 \end{aligned}$$

Therefore, as the Wronskian is 0 at  $t_0$ ,  $y_1$  and  $y_2$  cannot be a fundamental set of solutions in  $I$ .