Lecture 12

Aakash Jog

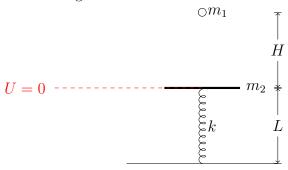
Thursday $4^{\rm th}$ December, 2014

Contents

1	Impulse and Momentum	2
2	Variable Mass Systems	3

1 Impulse and Momentum

Example 1. Assuming a plastic collision, what is the maximum compression of the string?



Solution. Applying COME before the collision,

$$m_1 g H = \frac{1}{2} m_1 v_1^2$$
$$\therefore v_1 = \sqrt{2gH}$$

The spring is already compressed due to m_2 . Therefore

$$kx_i = m_2 g$$
$$\therefore x_i = \frac{m_2 g}{k}$$

Therefore, the natural length of the spring is

$$x_i + L = \frac{m_2 g}{k} + L$$

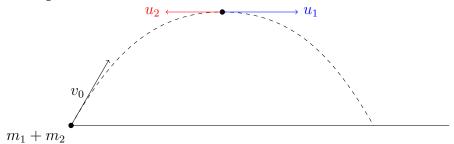
Applying COLM during the collision,

$$m_1 v_1 = (m_1 + m_2) u_{12}$$
$$\therefore u_{12} = \frac{m_1}{m_1 + m_2} v_1$$

Applying COME after the collision,

$$\frac{1}{2}(m_1 + m_2)u_{12}^2 + 0 + \frac{1}{2}kx_i^2 = 0 + (m_1 + m_2)g(-x_{\text{max}}) + \frac{1}{2}k(x_i + x_{\text{max}})^2$$

Example 2. Find x_2 .



Solution. Applying COLM,

$$(m_1 + m_2)v_0\cos\alpha = m_1u_1 + m_2u_2$$

$$v_y = v_0 \sin \alpha - gt_1$$

$$\therefore 0 = v_0 \sin \alpha - gt_1$$

$$\therefore t_1 = \frac{v_0 \sin \alpha}{g}$$

$$u_1 t = x_1$$

$$\therefore u_1 \frac{v_0 \sin \alpha}{g} = x_1$$

$$\therefore u_1 = \frac{x_1 g}{v_0 \sin \alpha}$$

2 Variable Mass Systems

Example 3. For a body, given $\frac{\mathrm{d}M}{\mathrm{d}t} = \rho A v$, find v_t .

Solution. Let the velocity and mass of the body at time t be v and m re-

spectively. Therefore, applying COLM,

$$m_0 v_0 = mv$$

$$\therefore m = \frac{m_0 v_0}{v}$$

$$\therefore \frac{dM}{dt} = -\frac{m_0 v_0}{v^2} \cdot \frac{dv}{dt}$$

$$\therefore \rho A v = -\frac{m_0 v_0}{v^2} \cdot \frac{dv}{dt}$$

$$\therefore \int_{v_0}^{v} \frac{dv}{v^3} = \int_{0}^{t} \frac{\rho A}{m_0 v_0} dt$$

$$\therefore \frac{1}{2v^2} - \frac{1}{2v_0^2} = \frac{\rho A}{m_0 v_0} t$$

Example 4. Given m_0 is the initial mass of the rocket, $\frac{\mathrm{d}m}{\mathrm{d}t} = -k$, and u is the velocity of the gas emitted from the rocket relative to the rocket, find the rocket's velocity as a function of time.

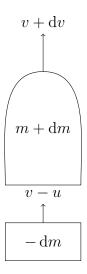
Solution.

$$\mathrm{d}p = p_{t+\mathrm{d}t} - p_t$$

At t, v m + dm -dm

$$P_t = mv$$

At t + dt,



$$p_{t+dt} = (m + df)(v + dv) + (-dm)(v - u)$$

$$dp = p_{t+dt} - P_t$$

$$= m dv + dmv + dm dv - dmv + dmu$$

$$0$$

$$\therefore \frac{\mathrm{d}p}{\mathrm{d}t} = M \frac{\mathrm{d}v}{\mathrm{d}t} + \frac{\mathrm{d}m}{\mathrm{d}t} \frac{0}{\mathrm{d}v} + \frac{\mathrm{d}m}{\mathrm{d}t} u$$
$$= M \frac{\mathrm{d}v}{\mathrm{d}t} + \frac{\mathrm{d}m}{\mathrm{d}t} u$$

$$-mg = \frac{\mathrm{d}p}{\mathrm{d}t}$$

$$= M \frac{\mathrm{d}v}{\mathrm{d}t} + \frac{\mathrm{d}m}{\mathrm{d}t} u$$

$$= m \frac{\mathrm{d}v}{\mathrm{d}t} - ku$$

$$\therefore m \frac{\mathrm{d}v}{\mathrm{d}t} = ku - mg$$

Therefore the rocket accelerates upwards iff

$$ku - mg > 0$$

 $\iff ku > mg$

Therefore, the condition for take-off is

$$ku > m_0 g$$

$$\frac{\mathrm{d}m}{\mathrm{d}t} = -k$$

$$\therefore m = m_0 - kt$$

$$m \frac{\mathrm{d}v}{\mathrm{d}t} = ku - mg$$

$$\therefore (m_0 - kt) \frac{\mathrm{d}v}{\mathrm{d}t} = ku - (m_0 - kt)g$$

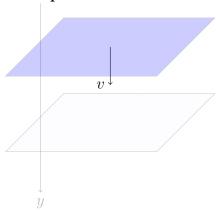
$$\therefore \int_0^v \mathrm{d}v = \int_0^t \left(\frac{ku}{m_0 - kt} - g\right) \mathrm{d}t$$

$$= -u \ln(m_0 - kt) + u \ln m_0 - gt$$

$$= u \ln\left(\frac{m_0}{m_0 - kt}\right) - gt$$

$$\therefore v(t) = u \ln\left(\frac{m_0}{m_0 - kt}\right) - gt$$

Example 5.



Solution.

$$p_{t} = m \cdot v + \rho A v \, dt \cdot 0$$

$$p_{t+dt} = (m + \rho A v \, dt)(v + dv)$$

$$\therefore dp = m \, dv + \rho A v^{2} \, dt + \rho A v \, dv \, dt$$

$$\therefore \frac{dp}{dt} = m \frac{dv}{dt} + \rho A v^{2} + \rho A v \, dv$$