

Lecture 1: CS577

Aug 22, 2017

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Introduction

- Course name: Computer Vision, CS677 (4 units)
- Instructor: Prof. Ram Nevatia
 - My background, research interests...
- Today's objective
 - Describe course content
 - Conduct of the class
 - Required work, grading
 - Pre-requisites
 - Intro to potential and problems of vision

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Background

- Course web page:
 - <http://den.usc.edu>
- Office hours
 - Instructor, Tu, Th; 1:30-3:00 P.M., PHE 202; other times by appointment
 - [nevatia AT usc DOT edu](mailto:nevatia@usc.edu), 213-740-6427
- TA: Jiyang Gao [jiyangga AT usc DOT edu](mailto:jiyangga@usc.edu); office hours info will be posted
- Books:
 - Required: "Computer vision" by Forsyth and Ponce, **Second Edition**, 2012
 - Recommended: "Computer Vision: Algorithms and Applications" by Richard Szeliski; electronic copy available for personal use at <http://szeliski.org/Book>.
 - Deep Learning: Algorithms and Applications, I. Goodfellow, Y. Bengio and A. Courville, 2017. Free online version available at: <http://www.deeplearningbook.org>
- Additional reading material will be distributed electronically or available in form of tutorials and research papers online

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Class Enrollment

- Sign in waiting list if you are present in class
- We will add a few more seats but may not be able to accommodate everyone
- We have not instituted an exam but students must demonstrate knowledge of pre-requisite material to the instructor
- Adding a class after start of semester requires instructor approval; please do **not** bypass/hack this system.

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What is this course about?

- Study of techniques that attempt to create artificial vision capabilities for computers
- What does the term “vision” mean when applied to human vision?
 - Eyes provide images to the brain; perception happens in the brain.
 - Perception consists of computing “good” descriptions of the environment
 - Agree with other measurements
 - Example: class room scene
- Computer Vision
 - Camera is like an eye: provides images
 - Vision is really about perception

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Course Objectives

- Understanding key problems of vision
- Alternative approaches to fundamental problems
- Specific applications will be covered only to illustrate the basic techniques
- Provide enough background for further study and for implementation of some practical vision systems
- Vision has become a large field and undergoing revolutionary changes, largely driven by deep learning (DL) techniques
 - Some may argue that we should teach only DL as other parts of CV have become or will soon become obsolete. We will include both the “classical” and “DL” approaches.
 - It is not possible to cover “everything” about “everything” in one semester, nor all of the state-of-art methods as this changes frequently (>1000 papers published each year)

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Class Difficulty

- CS 677 is not an “easy” course
 - Other options to satisfy M.S. requirements may be easier
 - Requires skills in several math topics and good programming skills
- Though only five years old, textbook is quite out of date. In particular it lacks any coverage of DL methods.
 - Also, coverage of existing topics is uneven and some parts are very hard to read but still it is the best available
- Course is a mix of traditional, first year graduate class and an advanced, research oriented course
- At this time, there is no plan to offer a more moderately paced course in computer vision in the near future

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Pre-requisites: Programming and CS

- This is a graduate course in CS!
 - Proficiency in Python and C++.
 - Must have experience with actual programming, not just concepts of programming.
 - Familiarity with various data structures such as *lists*, *trees* and *graphs*
 - Algorithms to create and manipulate such structures
 - Basic CS algorithms such as *Sorting*, *searching*, *tree/graph traversal* etc.
- Be able to take informal or mathematical descriptions of algorithms and convert them into working programs
- Work with libraries of code with limited documentation

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Pre-requisites: Mathematics

- Calculus
 - Derivatives, partial derivatives, Integration
- Geometry
 - Coordinate systems (Cartesian, spherical, cylindrical...)
 - Equations of entities such as points, lines, planes, circles, spheres...
 - Computing relations between entities (distance, intersection, angles....)
- Linear Algebra
 - Linear transformations
 - Matrix representation, inversion, eigenvectors....
 - Solutions of systems of equations
- Elementary probability theory
 - Discrete/continuous random variables
 - Joint probability distribution/density functions, conditional probabilities
 - Bayes' theorem
- Please take the math requirements seriously!

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Requirements

- Assignments (~6-8)
 - 1-2 “written” (mathematical) assignments
 - 5-6 programming assignments
 - Will make extensive use of functions in the Intel **OpenCV** library, Caffe and TensorFlow
 - Preferred language for programming is Python though much can be done using C++ or MATLAB.
- Grading:
 - Assignments 30%
 - Exam1: 30%, Exam 2: 30%; note Exam 2 is not a “cumulative final”
 - Exam 1, 7th or 8th week of classes (will be announced >1 week in advance); Exam 2, Nov 30, last class day (tentative date)
 - Class attendance and participation 10% (not applicable to DEN students or students with special exemption; their others scores will be scaled accordingly).
- All assignments and exams are required, missing any will result in a grade of “F”. Late submissions will be accepted with prior permission only.

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Academic Integrity

- Assignments and Exams are to be completed *individually*, unless otherwise specified.
- We encourage discussions among students but *not copying* of the answers.
- The class will be conducted on the basis of mutual trust and respect; for USC ethics code, see <http://web-app.usc.edu/scampus/principles-of-community/>
- Unfortunately, there are occasional instances of gross abuse; these instances will be referred for action according to the USC Student Conduct Code, which can be found at this link:
 - <http://web-app.usc.edu/scampus/university-student-conduct-code/>
- Grades can only be assigned based on performance, not need.

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Related Courses

- Artificial Intelligence (cs561)
 - Many AI techniques are used in vision but this course is not a pre-req
- Machine Learning (cs576)
 - Modern computer vision makes heavy use of these techniques; again it may be helpful but is not a pre-requisite
- Deep Learning (CS599)
 - CV is now dominated by DL (and DL by CV)
 - DL599 is a new course, syllabus is not fully defined yet
 - Possible significant overlap with 677; we will focus only on use of DL, not a broader study of DL.
- Mathematical Pattern Recognition (ee559)
 - Overlaps with 573 and 576 to some extent
- Image Processing (ee 569)
 - In image processing, goal is usual to enhance, compress or modify images for better human perception or transmission
 - Recent versions of the course may material that overlaps 677.
- Robotics and Graphics
 - Cover some major applications of vision

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Why Study Computer Vision (or not)?

- Required course for some tracks
 - Easier alternatives may exist
- Many important and exciting applications
 - Number of applications has been growing rapidly
 - Good job prospects
- Exciting intellectually
 - Vision is one of few remaining mysteries of natural world
 - Vision problems seem fundamentally unsolvable, great intellectual challenge to discover methods for solving them
 - Computer vision is a fast changing field, what is exciting today maybe obsolete in just a few years
 - Many fundamental problems remain unsolved, even difficult to formulate precisely
 - Theories are not always coherent
 - Many advanced mathematical tools are required

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5-minute Break

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Two Major Components of the Field

- Infer 3-D scene geometry
 - Needed for navigation and manipulation
 - May be helpful for object/activity recognition
 - How can we infer 3-D info from a single 2-D image?
 - Can we use multiple images to simplify the problem?
 - Can we measure 3-D directly (and bypass some basic vision problems)?
 - Above problems relatively well understood, many working systems
- Semantic understanding
 - Recognition of objects, relations, activities....
 - Difficult to formulate mathematically
 - Very active area of research: methods have changed from “intuitive” to “statistical” to “deep learning”

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Traditional (classic) vs Current Approaches

- Field of vision is < 50 years old
- Work older than five years is being called “classic”
- Major changes have come from machine learning, most recently deep learning
- Deep learning has proved very effective for recognition, less important for 3-D geometry topics
- We could just teach a course based on deep learning but geometry topics are useful for many important applications, e.g. vehicle navigation, augmented reality, movie making...
- Deep learning experiments require use of GPU
 - This will limit the range of assignments for the course.

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What is Vision useful for?

- Biological organisms
 - Navigate: avoid obstacles, don't get lost...
 - Recognize objects of interest: predators, food, friends...
 - Estimate motion, observe activities, predict...
 - Visual communication
 - Entertainment
 -
- Note: capabilities of biological vision span a broad spectrum: there are single cell organisms that can just sense presence/absence of light but still find it useful for survival
- Artificial mechanisms
 - Capabilities depend on the goals and the environment
 - Human level generality is difficult to achieve and not required in all cases

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Application Areas

- **Manufacturing:**
 - Inspection, assembly...
- **Mobile robots**
 - Self-driving cars, vehicles for hazardous environments, military vehicles..
- **Remote Sensing**
 - Maps (2-D and 3-D), change detection, crop/weather assessment...
- **Biomedical**
 - Large population screening, assisted surgery....
- **Visual surveillance, security**
- **Biometrics**
 - Face/Iris, fingerprint recognition
- **Visual aids**
 - Lane warnings, aid for the blind, ...
- **Multi-media**
 - Visual communication, enhanced reality, models for virtual environments, content based retrieval...

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Why is Vision Hard?

- Seems easy to us, no conscious effort is needed by human viewers
- Small variations in human population's ability to see/perceive
 - Does not require training/education for everyday tasks
- Can't we just recognize objects based on "how they look"?
 - Isn't a pen (a chair) a pen (chair) because it looks like a pen (chair)?
 - What does a pen (chair) look like?
 - Do we memorize images of pens or extract some more abstract representations (such as thin, mostly cylindrical objects with a conical section narrowing to a small circle at the end)?
 - We also need to detect/segment objects from others

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Same Object Class?



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Some Issues: Representation

- What is representation of an object
- Objects of same class can have large variations in shape, size, color, material and other properties
 - Think about every day objects, such as chairs, coffee mugs, telephones...
- What is representation of an action (say throw an object)?
- Same action can be performed in different ways by different actors or even the same actor at different times or in different contexts

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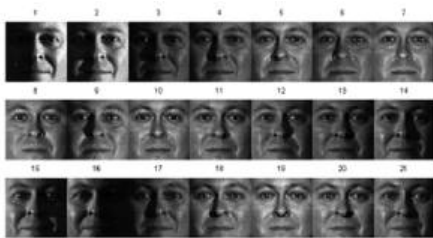
Viewpoint Change Examples



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Illumination Change Examples



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Depth Ambiguity and Occlusions

- World is 3-D, images are 2-D
 - There is an inherent loss of information; process is not truly invertible
 - Many 3-D environments could produce the same 2-D images
 - Our perception of 3-D from single 2-D images must take advantage of some regularities of the natural world
 - How do we isolate and exploit these regularities?
- Occlusion is (almost) ever-present
 - Objects occlude one another
 - Self-occlusion

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Multiple Objects in a Scene



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Complexity



How many objects are in this image?

What can we say about each?

What can we say about this scene?

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Video Analysis

- Adds difficulties of detecting and tracking moving objects
 - If camera also moves, we need to distinguish between object and background motion
- We want to detect not only objects but also events/activities taking place in the environment
- Make inferences about the intentions/plans of actors
- With expansion of the course to 4 units, we expect to have 1-2 weeks coverage of video analysis; this is a new component of the course.

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Topics to be studied in this class

- **Introduction (1 week)**
Background, requirements and issues, human vision.
- **Image formation: geometry and photometry (2 weeks)**
Geometry, brightness, quantization, camera calibration, photometry (brightness and color)
- **Image segmentation (1 week)**
Region segmentation, Edge and line finding
- **Multi-view Geometry (3 weeks)**
Shape from stereo and motion, feature matching, surface fitting, Active ranging
- **Object Recognition: Traditional Methods (2 weeks)**
HoG/SIFT features, Bayes classifiers, SVM classifiers
- **Object Recognition: Deep Learning Methods (2-3 weeks)**
Deep neural networks, classification networks, object proposal networks
- **Motion analysis (1-2 weeks)**
Motion detection and tracking, inference of activity from image sequences

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Next Class

- Read ch. 1 of Forsyth/Ponce book
 - Sections 1.1, 1.2.