# AMRO AL-BAALI

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**♀** Canada github.com/aalbaali

**EDUCATION** 

### M. Eng Mechanical McGill University

**6** 05/2019 - 08/2021

- CGPA: 3.77/4.00.
- Thesis title: Augmenting Sensor Measurements with INS Estimates in a Graph Based SLAM Problem.
- Supervisor: Prof. J. R. Forbes.

B. Eng Honours Mechanical, Minor in Computer Science McGill University

**1** 09/2014 - 04/2019

• CGPA: 3.83/4.00. Dean's Honour List 2015, 2018.

• Supervisor: Prof. J. R. Forbes.

### **EXPERIENCE**

ROS Software Developer - Robotics Team Vention

₩ 05/2023 - Present

Montreal, Canada

Mainly responsible for ROS-related tasks, where the tasks include maintaining the communication between the front-end and the robotic arm, both in simulation and using the real robot and maintaining Dockerfiles. The primary tools used in this job are ROS, Python, JavaScript, and Docker.

## Software Developer - Localization and Mapping Avidbots

**(1)** 09/2021 - 03/2023

♥ Kitchener, Canada

Developed and maintained the calibration, localization, and mapping algorithms for a robot equipped with a 2D LIDAR and a camera such that it is well localized within a pre-defined map. The primary tools used in this job are ROS, C++, Python, OpenCV, and nonlinear least squares (mainly using Ceres).

### Graduate Student - SLAM DECAR group (McGill University)

**1** 05/2019 - 08/2021

♥ Montreal, Canada

Collaborated with Voyis and Sonardyne to develop a SLAM back-end algorithm for an AUV equipped with a third-party INS treated as a black box and the Voyis Insight Pro high-precision laser scanner. The primary tools used in the project are: Lie groups, state estimation, optimization (convex, on-manifold), MATLAB, and C++.

#### Mechanical Engineering Intern MY01

**1** 05/2018 - 04/2019

♥ Montreal, Canada

Designed and executed mechanical tests on the MY01 device to pass the medical certification. This included programming the testing platform using Python, which involved designing a GUI for the user. Furthermore, I also customized the CAD storage tool Autodesk Vault using C# to generate reports in MY01's standards.

#### Teaching Assistant McGill University

**#** 09/2017 - 04/2021

- Montreal, Canada
- MECH 513 (Control Systems) (Winter 2021)
- MECH 309 (Numerical Methods) (Fall 2019)
- MECH 412 (System Dynamics and Control) (Fall 2017)

### **AWARDS**

- Best Seminar Award 2021
- MEUSMA Award, 2019
- NSERC-USRA Award, 2019
- McGill SURE award, 2017
- Habib Abou-Favssal Prize, 2018
- Dean's Honour List, 2015, 2018
- Rio Tinto-Evans Exchange Award, 2018

### **SKILLS**

#### Theory

Linear Algebra **Numerical Optimization Probability SLAM State Estimation** Kalman filtering Particle filtering **Factor graphs Computer Vision Multiview Geometry Matrix Lie Groups Control Systems** 



#### **Programming**

C++ **Python** Julia Bash **MATLAB** PT-X



#### Software

Linux **ROS** ROS 2 Eigen Ceres **GTSAM OpenCV** Docker



## **LANGUAGES**

**English Arabic** 

