AMRO AL-BAALI

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EDUCATION

M. Eng Mechanical McGill University
05/2019 - 08/2021

- CGPA: 3.77/4.00. Supervisor: Prof. J. R. Forbes.
- Thesis title: *Augmenting Sensor Measurements with INS Estimates in a Graph Based SLAM Problem*.
- Publication[1]: A. Al-Baali, T. Hitchcox, and J. Forbes, "Combining DVL-INS and Laser-Based Loop Closures in a Batch Estimation Framework for Underwater Positioning," 2023, arXiv:2307.04885.

B. Eng Honours Mechanical, Minor in Computer Science McGill University
09/2014 - 04/2019

- CGPA: 3.83/4.00. Supervisor: Prof. J. R. Forbes.
- Thesis title: *Parallel Feedforward Control Using Linear Matrix Inequalities*.

EXPERIENCE

Software Developer - Robotics Team Vention
05/2023 – Present Montreal, Canada

Mainly responsible for developing and supporting the robot API that allows clients to write custom software that controls the robot operation, both in simulation and on the real robot. The primary tools used in this job are **ROS**, **C++**, **Python**, **JavaScript**, and **Docker**.

Software Developer - Localization and Mapping Avidbots
09/2021 – 03/2023 Kitchener, Canada

Developed and maintained the calibration, localization, and mapping algorithms for a robot equipped with a 2D LIDAR and a camera such that it is well localized within a pre-defined map. The primary tools used in this job are **ROS**, **C++**, **Python**, **OpenCV**, and nonlinear least squares (mainly using **Ceres**).

Graduate Student - SLAM DECAR group (McGill University)
05/2019 – 08/2021 Montreal, Canada

Collaborated with Voyis and Sonardyne to develop a SLAM back-end algorithm for an AUV equipped with a third-party INS treated as a black box and the Voyis Insight Pro high-precision laser scanner. The primary tools used in the project are: Lie groups, state estimation, optimization (convex, on-manifold), **MATLAB**, and **C++**.

Mechanical Engineering Intern MY01
05/2018 – 04/2019 Montreal, Canada

Designed and executed mechanical tests on the MY01 device to pass the medical certification. This included programming the testing platform using **Python**, which involved designing a GUI for the user. Furthermore, I also customized the CAD storage tool Autodesk Vault using **C#** to generate reports in MY01's standards.

Teaching Assistant McGill University
09/2017 – 04/2021 Montreal, Canada

- MECH 513 (Control Systems) (Winter 2021)
- MECH 309 (Numerical Methods) (Fall 2019)
- MECH 412 (System Dynamics and Control) (Fall 2017)

[1]The article is accepted for publication at the IEEE Journal of Oceanic Engineering

AWARDS

- Best Seminar Award 2021
- MEUSMA Award, 2019
- NSERC-USRA Award, 2019
- McGill SURE award, 2017
- Habib Abou-Fayssal Prize, 2018
- Dean's Honour List, 2015, 2018
- Rio Tinto-Evans Exchange Award, 2018

SKILLS

Theory

Linear Algebra
Numerical Optimization
Probability
SLAM
State Estimation
Kalman filtering
Particle filtering
Factor graphs
Computer Vision
Multiview Geometry
Matrix Lie Groups
Control Systems

Programming

C++
Python
Julia
Bash
MATLAB
LaTeX

Software

Linux
ROS
ROS 2
Eigen
Ceres
GTSAM
OpenCV
Docker

LANGUAGES

English
Arabic