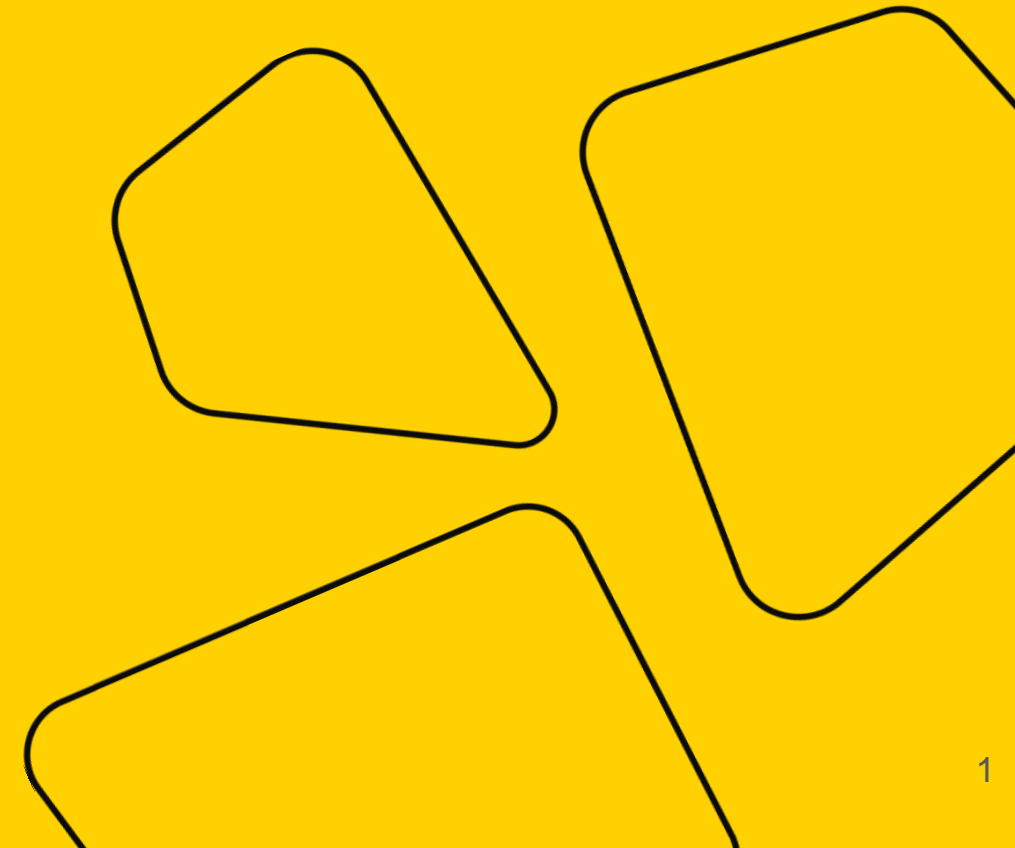




# Math Basics for DS

Practical Session 9



# Today

- Short quiz univariate calculus
- Multivariate calculus

# Quiz

- <https://forms.gle/hV6QkGjuC8RZgRMp6>

# Partial Derivatives

- Derivative for univariate functions:

$$y = f(x), \quad \frac{dy}{dx} = f'(x) = \lim_{\Delta x \rightarrow 0} \frac{f(x + \Delta x) - f(x)}{\Delta x}$$

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- Partial derivative for multivariate functions:

$$y = f(x_1, \dots, x_n), \quad \frac{\partial y}{\partial x_i} = f'_{x_i} = \lim_{\Delta x_i \rightarrow 0} \frac{f(x_1, \dots, x_i + \Delta x_i, \dots, x_n) - f(x_1, \dots, x_i, \dots, x_n)}{\Delta x_i}$$

*Compute derivative with respect to  $x_i$   
regarding all other variables as constants.*

# Partial Derivatives - Example

- Let  $f(x, y) = x^3 + x^2y^3 - 2y^2$ .
- Find  $f_x(2,1)$  and  $f_y(2,1)$ .

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# The Chain Rule

- For univariate functions:

$$\left(f(g(x))\right)' = f'(g(x)) \cdot g'(x) \quad \Leftrightarrow \quad \frac{df}{dx} = \frac{df}{dg} \cdot \frac{dg}{dx}$$

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$$\left(f(g(x))\right)' = f'(g(x)) \cdot g'(x) \iff \frac{df}{dx} = \frac{df}{dg} \cdot \frac{dg}{dx}$$

- For multivariate functions:

$$u(x_1, \dots, x_n), \quad x_i = x_i(t_1, \dots, t_m)$$

$$\frac{\partial u}{\partial t_k} = \frac{\partial u}{\partial x_1} \cdot \frac{\partial x_1}{\partial t_k} + \frac{\partial u}{\partial x_2} \cdot \frac{\partial x_2}{\partial t_k} + \dots + \frac{\partial u}{\partial x_n} \cdot \frac{\partial x_n}{\partial t_k}, \quad k = 1, \dots, m$$

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$$u = x^2y + 3xy^4, \quad x = \sin 2t, \quad y = \cos t$$



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$$\frac{\partial u}{\partial s} = 4x^3 y \cdot re^t + (x^4 + 2yz^3) \cdot 2rse^{-t} + 3y^2 z^2 \cdot r^2 \sin t$$

# Gradient

- A vector of partial derivatives:

$$\nabla f(x_1, \dots, x_n) = \left( \frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial x_2}, \dots, \frac{\partial f}{\partial x_n} \right)$$

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# Gradient

Gradient shows the direction of the maximal growth of the function.

Negative gradient = direction of the maximal descent of the function.

# Higher Derivatives

- Consider  $f(x, y)$ .
- $f'_x(x, y)$ ,  $f'_y(x, y)$  – also functions of two variables.  
We can compute their partial derivatives!

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$$(f'_x)'_x = f''_{xx}(x, y) = \frac{\partial^2 f}{\partial x^2}, \quad (f'_x)'_y = f''_{xy}(x, y) = \frac{\partial^2 f}{\partial y \partial x}$$

$$(f'_y)'_y = f''_{yy}(x, y) = \frac{\partial^2 f}{\partial y^2}, \quad (f'_y)'_x = f''_{yx}(x, y) = \frac{\partial^2 f}{\partial x \partial y}$$



# Higher Derivatives - Example

- Consider  $f(x, y) = x^3 + x^2y^3 - 2y^2$ .

$$f_x(x, y) = \frac{\partial f}{\partial x} = 3x^2 + 2xy^3, \quad f_y(x, y) = \frac{\partial f}{\partial y} = 3x^2y^2 - 4y$$

$$f_{xx}''(x, y) = \frac{\partial^2 f}{\partial x^2} = \quad , \quad f_{xy}''(x, y) = \frac{\partial^2 f}{\partial y \partial x} =$$

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# Hessian

- A matrix of second derivatives.
- $f(x_1, \dots, x_n)$

$$H = \begin{pmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_2 \partial x_1} & \cdots & \frac{\partial^2 f}{\partial x_n \partial x_1} \\ \frac{\partial^2 f}{\partial x_1 \partial x_2} & \frac{\partial^2 f}{\partial x_2^2} & \cdots & \frac{\partial^2 f}{\partial x_2 \partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 f}{\partial x_n \partial x_1} & \frac{\partial^2 f}{\partial x_n \partial x_2} & \cdots & \frac{\partial^2 f}{\partial x_n^2} \end{pmatrix}$$

# Hessian - Example

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$$H = \begin{pmatrix} 6x + 2y^3 & 6x \\ 6x & 6x^2y - 4 \end{pmatrix}$$



# Extrema

- Univariate case: a stationary point  $x_0$  is a local minimum (maximum) if

$$f''(x_0) > 0 \text{ (} f''(x_0) < 0 \text{)}.$$

- Multivariate case:

$x_0$  is a stationary point:  $\nabla f(x_0) = 0$

$H$  – Hessian.

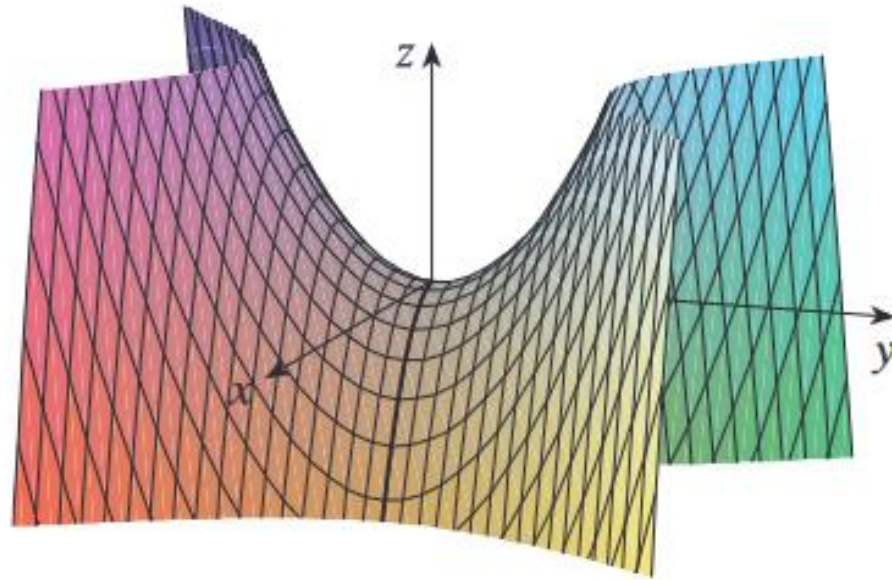
Then, if  $H$  is a **positive-definite** matrix, then  $x_0$  is a **local minimum**.

If  $H$  is a **negative-definite** matrix, then  $x_0$  is a **local maximum**.

If  $\det H = 0$ , we need to check manually.

Otherwise,  $x_0$  is a **saddle point**.

# Saddle Points



# Positive vs Negative Definite Matrices

- A matrix  $A$  is called positive-definite if

$$x^T A x > 0 \quad \forall x$$

- A matrix  $A$  is called negative-definite if

$$x^T A x < 0 \quad \forall x$$

# Positive vs Negative Definite Matrices



- How to check if a matrix is positive (negative) definite?

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- How to check if a matrix is positive (negative) definite?

Check principal minors  $D_k$ !

For positive definite:

$$D_1 > 0, \quad D_2 > 0, \quad \dots, D_n > 0$$

For negative definite:

$$D_1 < 0, \quad D_2 > 0, \quad D_3 < 0, \dots$$

$$H = \begin{pmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_2 \partial x_1} & \dots & \frac{\partial^2 f}{\partial x_n \partial x_1} \\ \frac{\partial^2 f}{\partial x_1 \partial x_2} & \frac{\partial^2 f}{\partial x_2^2} & \dots & \frac{\partial^2 f}{\partial x_2 \partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 f}{\partial x_n \partial x_1} & \frac{\partial^2 f}{\partial x_n \partial x_2} & \dots & \frac{\partial^2 f}{\partial x_n^2} \end{pmatrix}$$

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Stationary points:  $\nabla f = 0 \iff$

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$$\begin{aligned} 4x^3 - 4y &= 0 \\ 4y^3 - 4x &= 0 \end{aligned} \iff$$

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$\det H = 144x^2y^2 - 16|_{(0;0)} < 0$ ,  $(0, 0)$  – saddle point.



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$(1, 1)$  – local minimum.

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Stationary points:  $(0, 0)$ ,  $(-1, -1)$ ,  $(1, 1)$

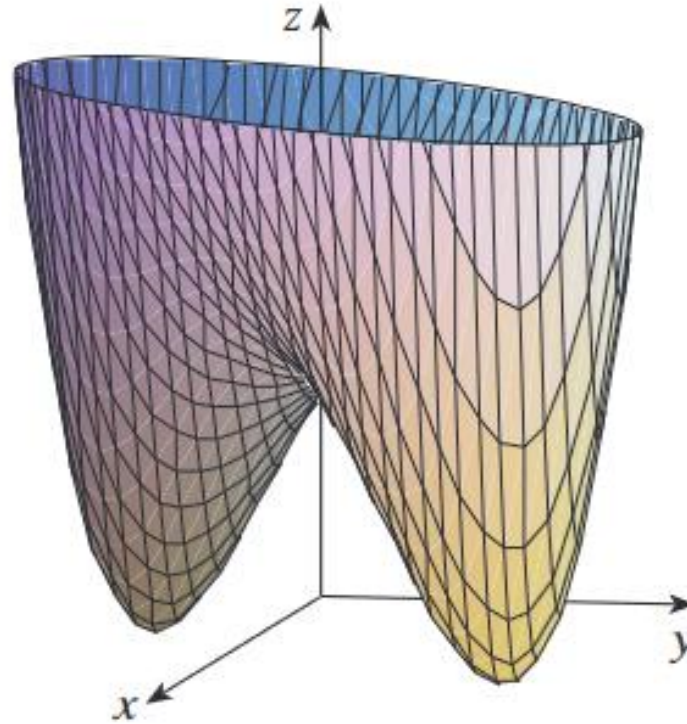
$$H = \begin{pmatrix} 12x^2 & -4 \\ -4 & 12y^2 \end{pmatrix}$$

$$\det H = 144x^2y^2 - 16 \Big|_{(-1,-1)} > 0, \quad \det H_1 = 12x^2 \Big|_{(-1,-1)} > 0$$

$(-1, -1)$  – local minimum.

# Extrema – Example

$$f(x, y) = x^4 + y^4 - 4xy + 1$$



# **Linear Regression the Other Way**



# Least Squares (Again)

- Remember the Least Squares problem:

$$\hat{y}_i = w_0 + w_1 x_1^i + \cdots + w_n x_n^i, \quad y_i = \hat{y}_i + e_i, \quad w = ?$$



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- We can also see this as an optimization problem:

$$\mathcal{L}(w_0, \dots, w_n) = \sum e_i^2 = \sum (y_i - \hat{y})^2 = \sum \left( y_i - (w_0 + w_1 x_1^i + \cdots + w_n x_n^i) \right)^2 \rightarrow \min_{w_0, \dots, w_n}$$

# Least Squares

- Let's consider a simple case: fitting a line to a set of points

$$(x_1, y_1), \quad (x_2, y_2), \quad \dots, \quad (x_n, y_n)$$

$$y \approx w_0 + w_1 x$$

We want to pick the weights  $w_0$ ,  $w_1$   
so that the sum of squares of the errors is the smallest possible:

$$\mathcal{L}(w_0, w_1) = \rightarrow \min_{w_0, w_1}$$

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# Least Squares

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$$\frac{\partial \mathcal{L}}{\partial w_1} = -2 \sum_{i=1}^n x_i \cdot (y_i - w_0 - w_1 x_i) = 0$$

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# Least Squares

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$$\frac{\partial \mathcal{L}}{\partial w_1} = \sum_{i=1}^n x_i y_i - w_0 \sum_{i=1}^n x_i - w_1 \sum_{i=1}^n x_i^2 = 0$$

$$\frac{\partial \mathcal{L}}{\partial w_0} = \sum_{i=1}^n y_i - w_1 \sum_{i=1}^n x_i - n w_0 = 0$$

# Least Squares

$$\mathcal{L}(w_0, w_1) = \sum_{i=1}^n (y_i - w_0 - w_1 x_i)^2 \rightarrow \min_{w_0, w_1}$$

$$w_0 \sum_{i=1}^n x_i + w_1 \sum_{i=1}^n x_i^2 = \sum_{i=1}^n x_i y_i$$

$$nw_0 + w_1 \sum_{i=1}^n x_i = \sum_{i=1}^n y_i$$



# Least Squares

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$$w_0 + w_1 \frac{1}{n} \sum_{i=1}^n x_i = \frac{1}{n} \sum_{i=1}^n y_i \iff w_0 + w_1 \bar{x} = \bar{y}$$

# Least Squares

$$\mathcal{L}(w_0, w_1) = \sum_{i=1}^n (y_i - w_0 - w_1 x_i)^2 \rightarrow \min_{w_0, w_1}$$

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# Least Squares

$$\mathcal{L}(w_0, w_1) = \sum_{i=1}^n (y_i - w_0 - w_1 x_i)^2 \rightarrow \min_{w_0, w_1}$$

$$nw_0 \sum_{i=1}^n x_i + nw_1 \sum_{i=1}^n x_i^2 = n \sum_{i=1}^n x_i y_i$$

$$nw_0 \sum_{i=1}^n x_i + w_1 \left( \sum_{i=1}^n x_i \right)^2 = \sum_{i=1}^n x_i \sum_{i=1}^n y_i$$

$$w_0 + w_1 \bar{x} = \bar{y}$$

# Least Squares

$$\mathcal{L}(w_0, w_1) = \sum_{i=1}^n (y_i - w_0 - w_1 x_i)^2 \rightarrow \min_{w_0, w_1}$$

$$w_1 \left( \sum_{i=1}^n x_i \right)^2 - n w_1 \sum_{i=1}^n x_i^2 = \sum_{i=1}^n x_i \sum_{i=1}^n y_i - n \sum_{i=1}^n x_i y_i$$

$$w_1 = \frac{n \sum_{i=1}^n x_i y_i - \sum_{i=1}^n x_i \sum_{i=1}^n y_i}{n \sum_{i=1}^n x_i^2 - \left( \sum_{i=1}^n x_i \right)^2}$$

# Least Squares

$$\mathcal{L}(w_0, w_1) = \sum_{i=1}^n (y_i - w_0 - w_1 x_i)^2 \rightarrow \min_{w_0, w_1}$$

$$\hat{w}_0 = \hat{w}_1 \bar{x} = \bar{y},$$

$$\hat{w}_1 = \frac{n \sum_{i=1}^n x_i y_i - \sum_{i=1}^n x_i \sum_{i=1}^n y_i}{n \sum_{i=1}^n x_i^2 - \left( \sum_{i=1}^n x_i \right)^2}$$