

Why do systems need to find nodes?



Cloud Management



Cloud Management

VM Provisioning



Cloud Management

VM Provisioning
VM Migration



Cloud Management

VM Provisioning

VM Migration

Monitoring



Cloud Management

VM Provisioning
VM Migration
Monitoring



NVF Automation



Cloud Management

VM Provisioning
VM Migration
Monitoring



NVF Automation

Geo-distributed VNF Service Chain Placement



Cloud Management

VM Provisioning
VM Migration
Monitoring



NVF Automation

Geo-distributed VNF Service Chain Placement

Required information is assumed available



Cloud Management

VM Provisioning
VM Migration
Monitoring



NVF Automation

Geo-distributed VNF Service Chain Placement

Required information is assumed available

But **HOW** is node information collected?

Outline

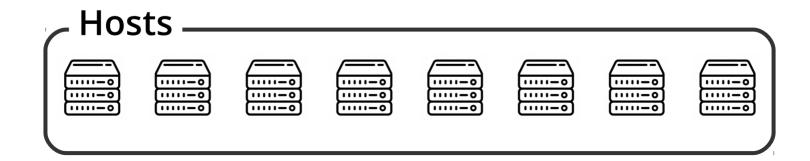
- How do systems find nodes?
- Limitations of current approaches
- FOCUS design
- Evaluation
- Conclusion

Looking Under The Hood

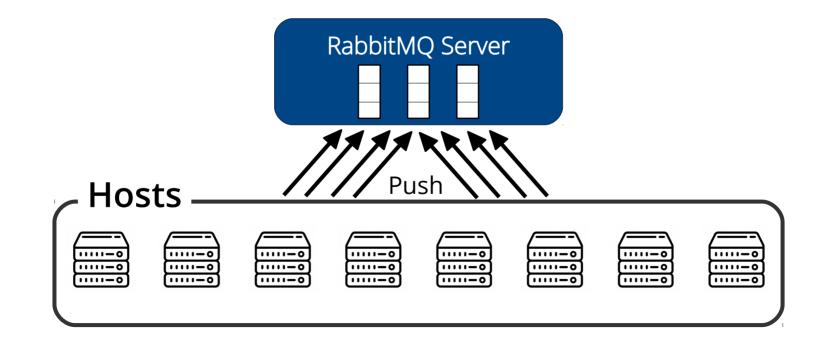
How do systems search for nodes?



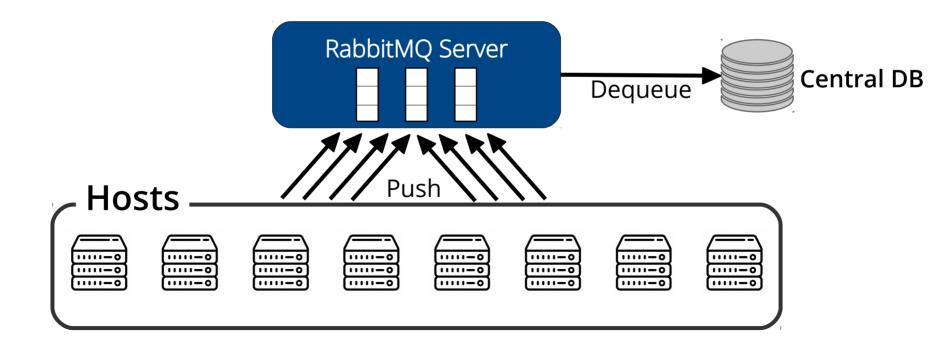




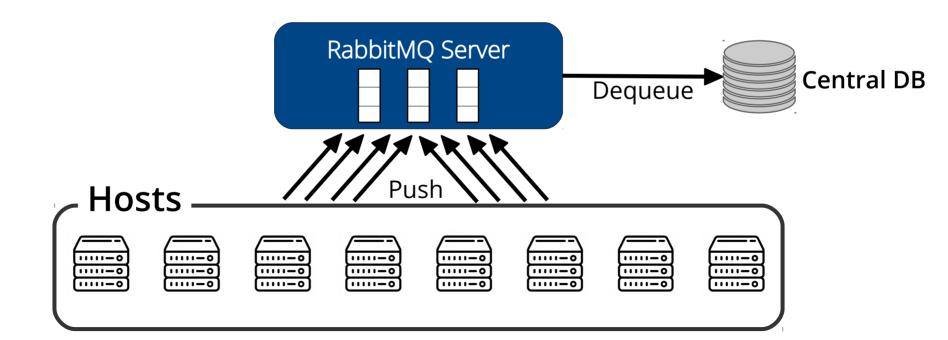




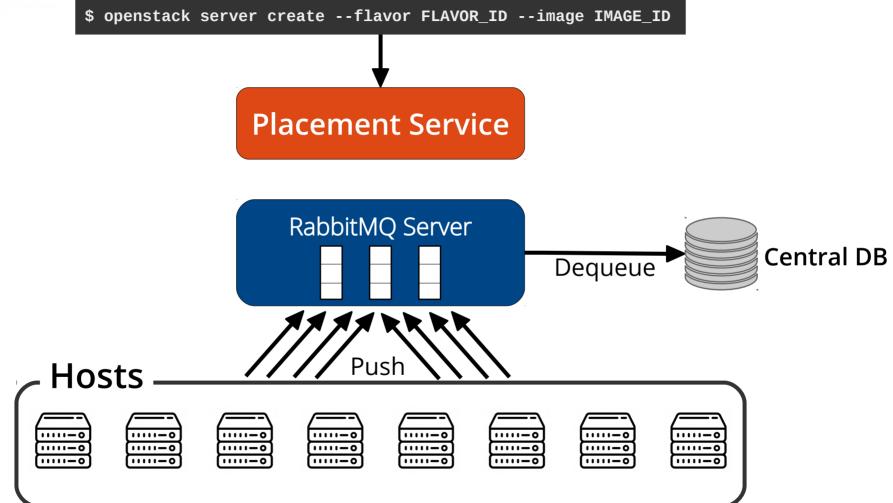




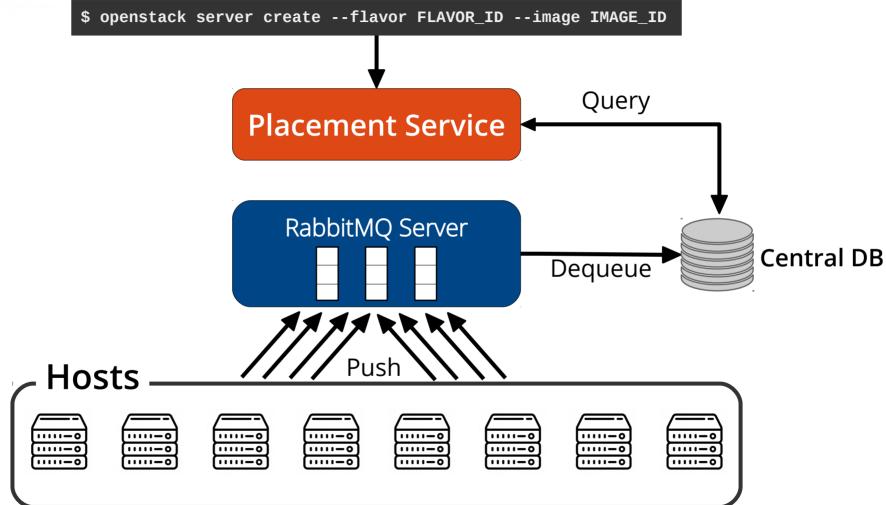




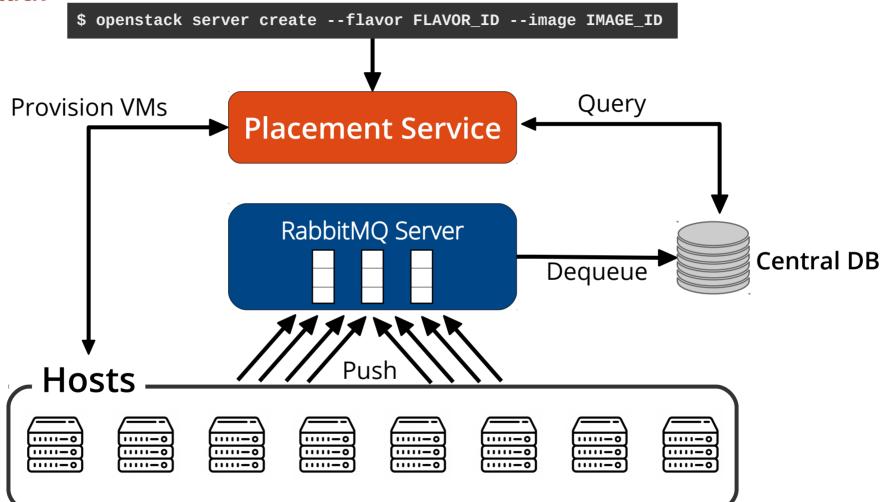






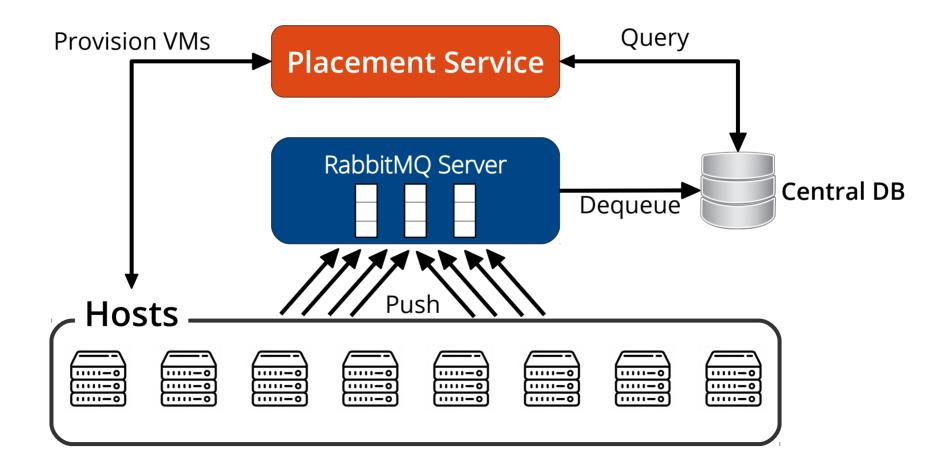






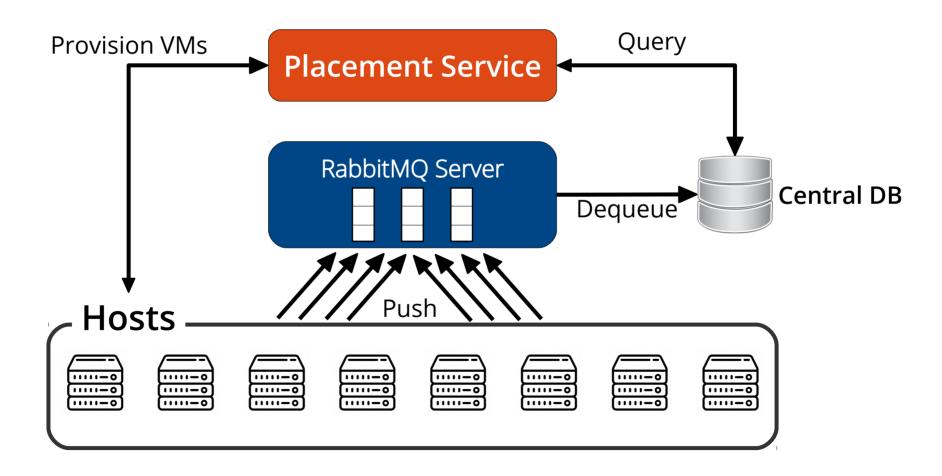
Limitations of Current Approaches





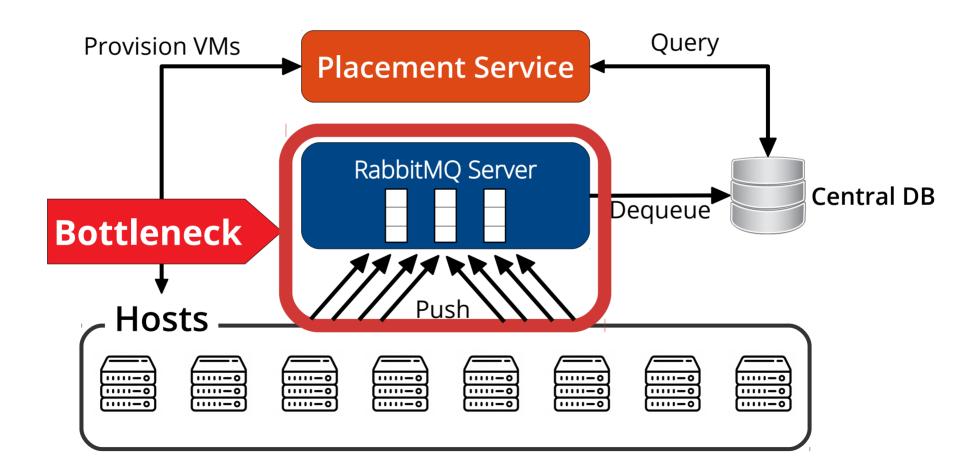


Hard to scale > 100s of nodes!





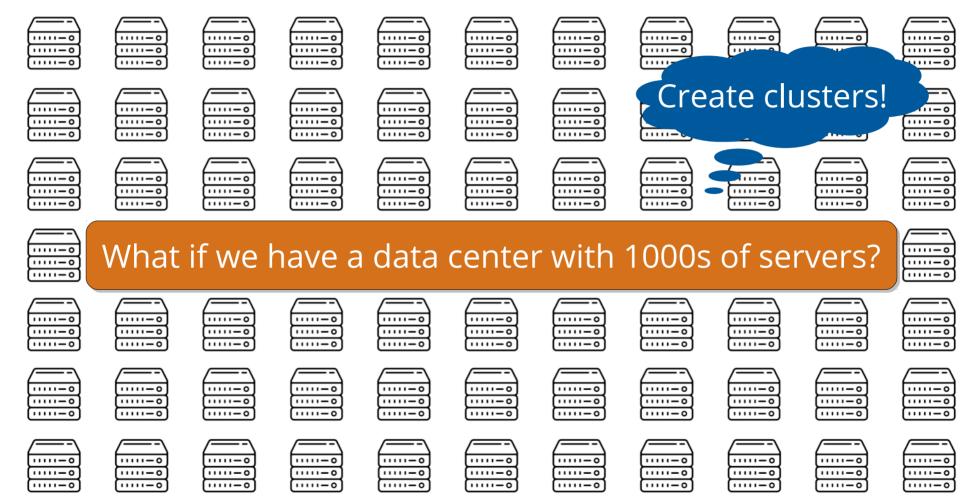
Hard to scale > 100s of nodes!







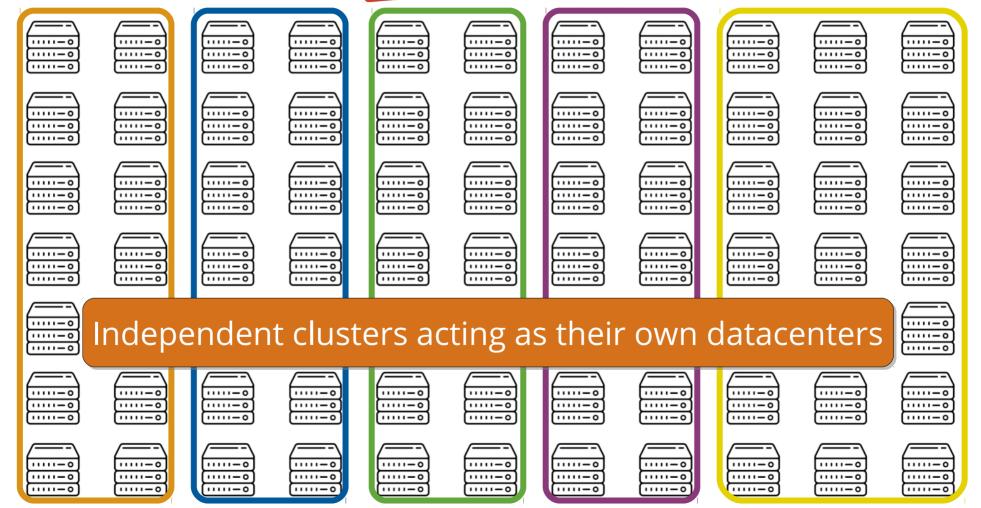




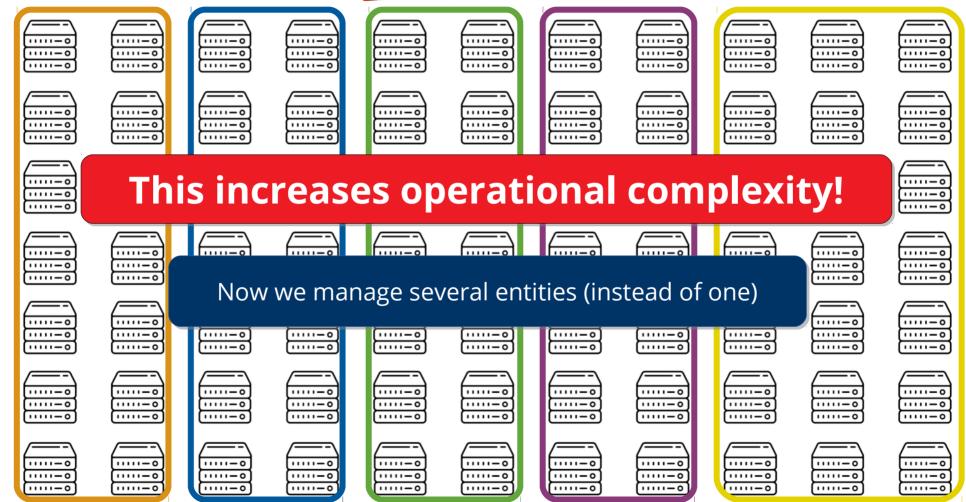


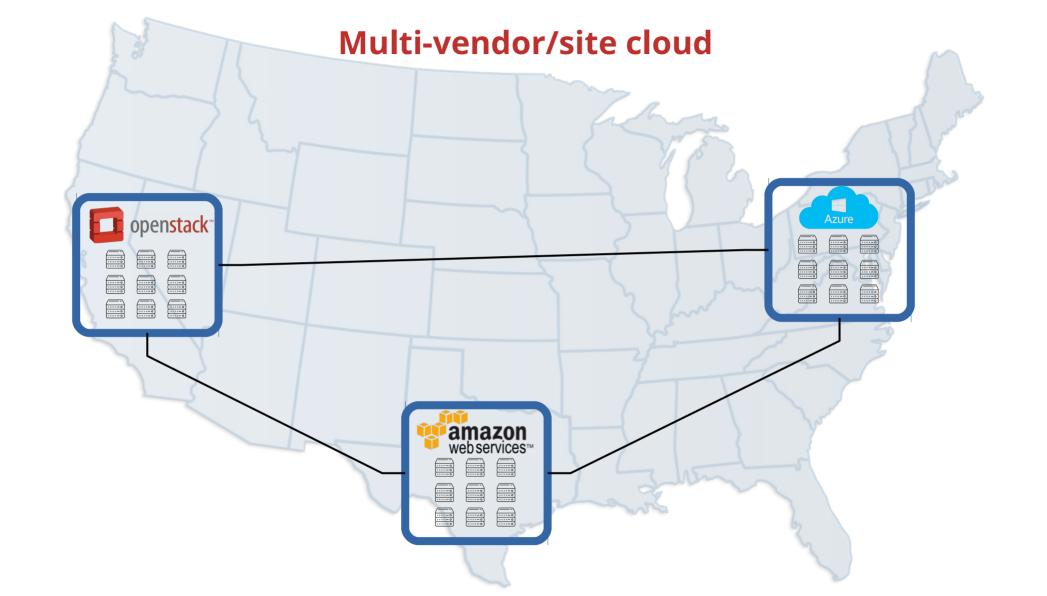
::::-0 ::::-0	1111-0	- 	::::-0 ::::-0	::::-0 ::::-0	::::-0 ::::-0	::::-0 ::::-0	::::-0 ::::-0	1111-0	0 0	::::-0 ::::-0
0	 	- 	o	0 0	o	····-o		····-0 ····-0	0 0	
0		- 	o	0	0	····-o		····-o	0 0	
	····-o		0 0		o	····-0 ····-0		····-0 ····-0		
0		- 	o	0 0	o	····-0 ····-0		····-0 ····-0	0 0	
0 0	0 0		o	0 0	o	····-0 ····-0		····-0 ····-0		
0 0		- 	o	0 0	o	····-0 ····-0	0 0	····-0 ····-0		

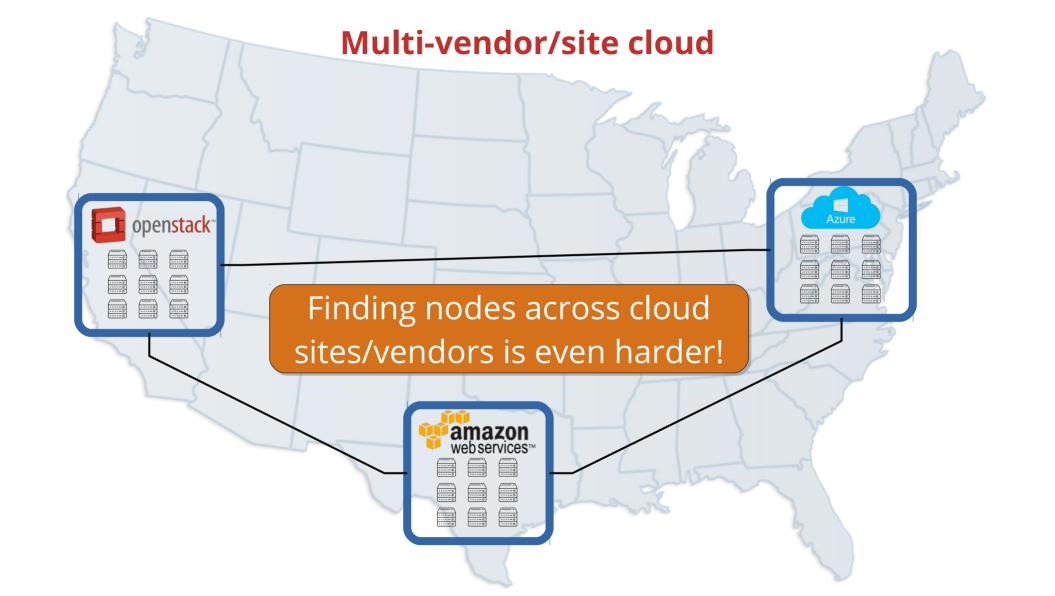












FCUS

Scalable and generic search service for distributed systems







Query Processing with Directed Pulling





Query Processing with Directed Pulling



Gossip-based Node Coordination



Query Processing with Directed Pulling



Gossip-based Node Coordination



Easy-to-integrate Query Interface

Main Components



Query Processing with Directed Pulling



Gossip-based Node Coordination



Easy-to-integrate Query Interface

Node Attributes

Node Attributes

Static

Dynamic

Node Attributes

Static

Never change

Dynamic

Node Attributes Static Never change # cpu cores, arch, etc Dynamic

```
Node Attributes
Static
     Never change
    # cpu cores, arch, etc
Dynamic
     Frequently change
```

Node Attributes Static Never change # cpu cores, arch, etc Dynamic Frequently change

Usage: cpu, ram, disk,

bandwidth, etc

Node Attributes

Static

Never change

cpu cores, arch, etc

Dynamic

Frequently change

Usage: cpu, ram, disk, bandwidth, etc

Node Attributes Static Never change # cpu cores, arch, etc Dynamic Frequently change Usage: cpu, ram, disk,

bandwidth, etc

Query Structure

Node Attributes

Static

Never change

cpu cores, arch, etc

Dynamic

Frequently change

Usage: cpu, ram, disk, bandwidth, etc

Query Structure

Attribute List

Static Never change # cpu cores, arch, etc

Frequently change

Dynamic

Usage: *cpu, ram, disk,* bandwidth, etc

Query Structure

Attribute List

name (string)

upper bound (int)

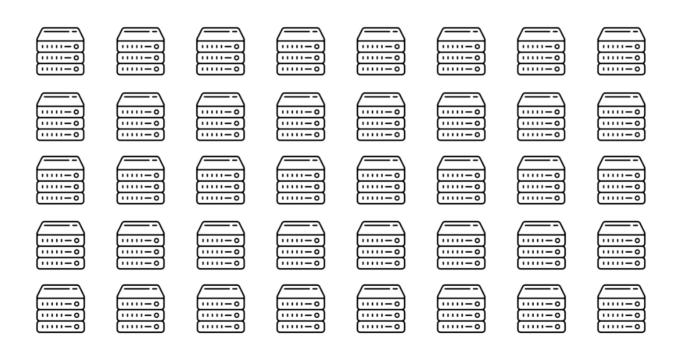
lower bound (int)

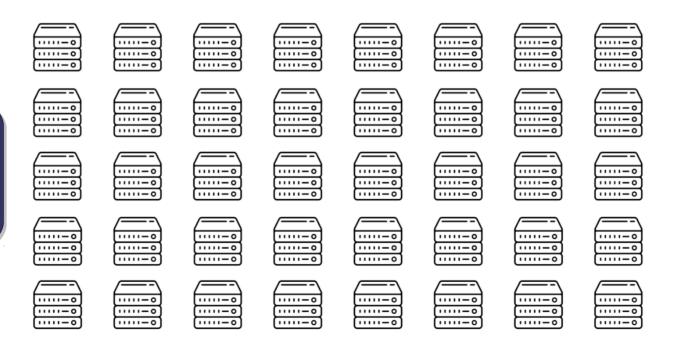
Node Attributes Static Never change # cpu cores, arch, etc Dynamic Frequently change Usage: cpu, ram, disk,

bandwidth, etc

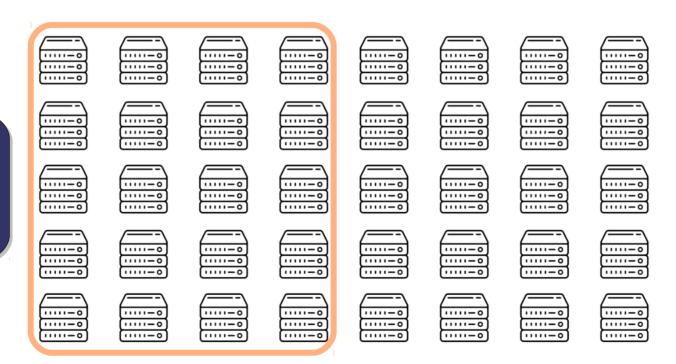
Query Structure Attribute List name (string) upper bound (int) lower bound (int) limit (int) freshness (int)

Query Processing with Directed Pulling





cpu_usage {50-100}%



11111-0

11111-0

11111-0

11111-0

11111-0

11111-0

.....

11111-0

11111-0

.....

11111-0

11111-0

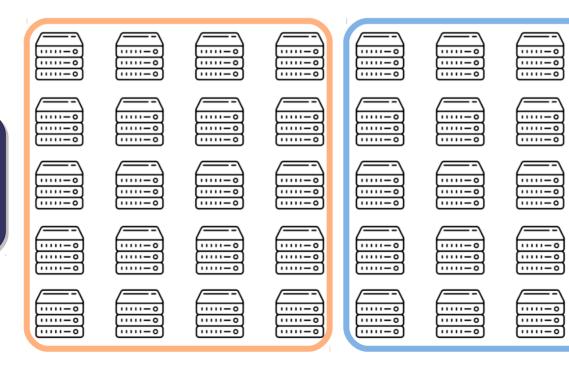
.....

11111-0

11111-0

cpu_usage {50-100}%

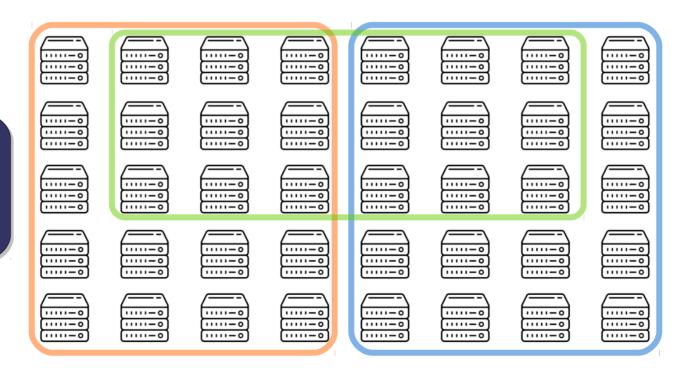
cpu_usage {0-50}%



cpu_usage {50-100}%

cpu_usage {0-50}%

avail_RAM {4-8}GB

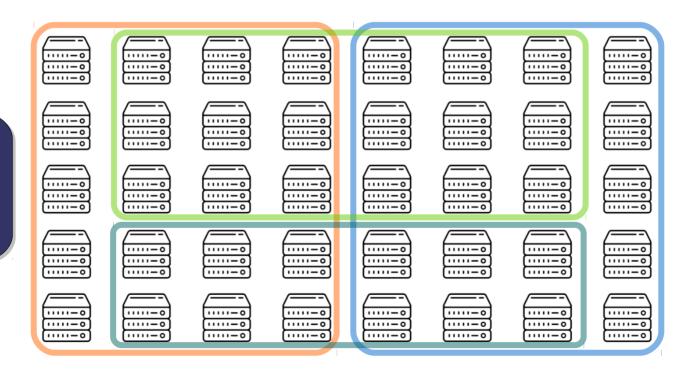


cpu_usage {50-100}%

cpu_usage {0-50}%

avail_RAM {4-8}GB

cpu_cores {8-12}



cpu_usage {50-100}%

cpu_usage {0-50}%

avail_RAM {4-8}GB

FQCUS



cpu_usage {50-100}%

cpu_usage {0-50}%

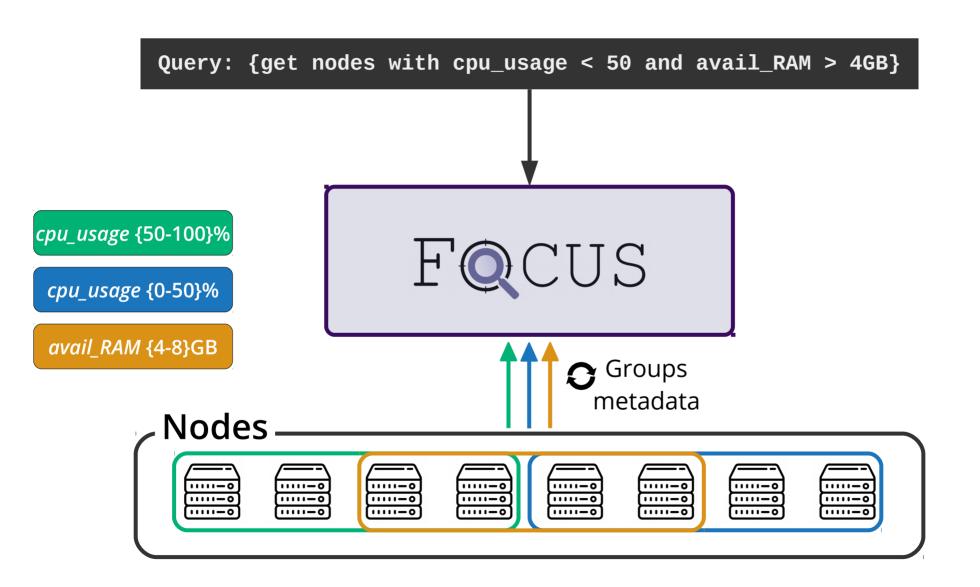
avail_RAM {4-8}GB

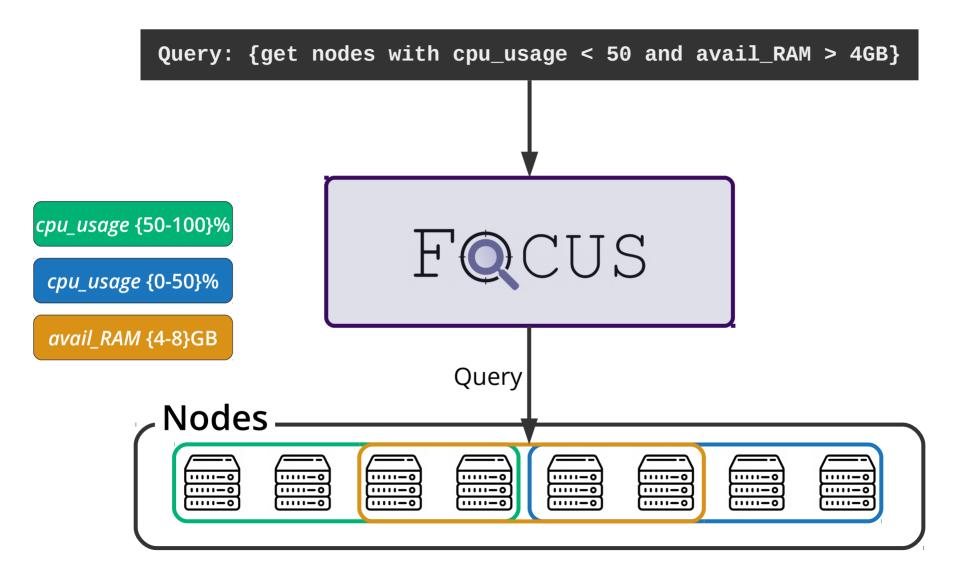


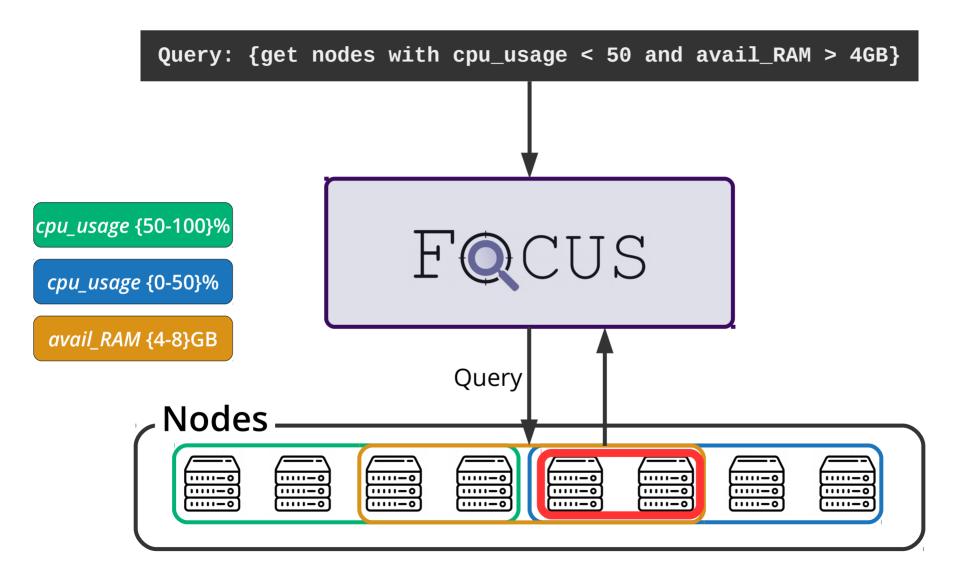


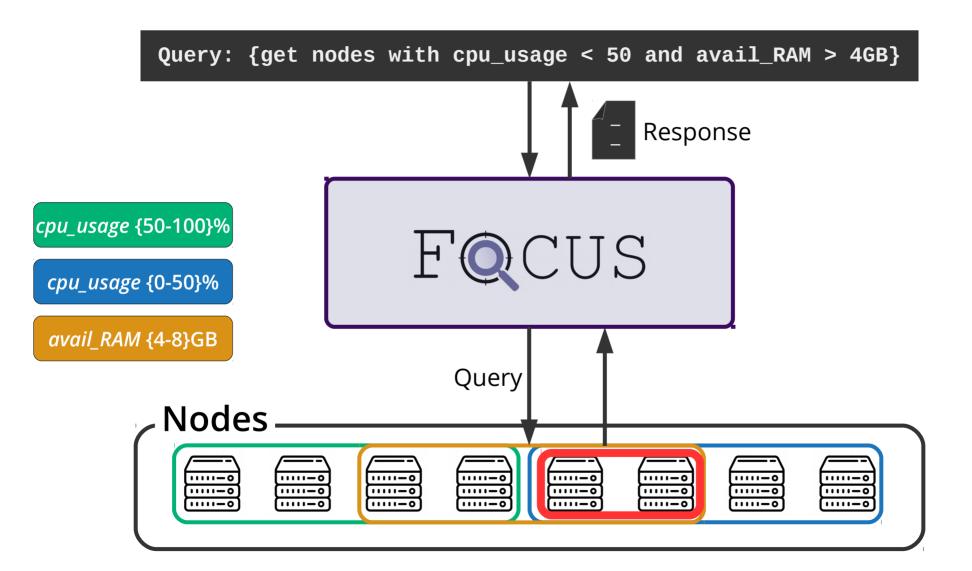




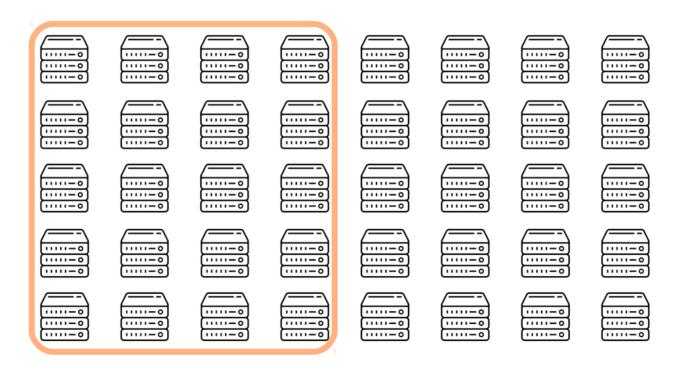




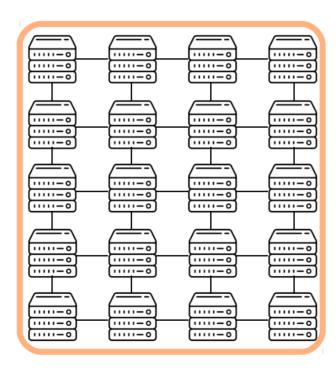




cpu_usage {50-100}%

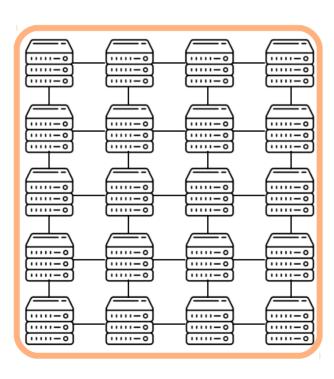


cpu_usage {50-100}%



Nodes in a group are connected through a **p2p** *gossip* channel

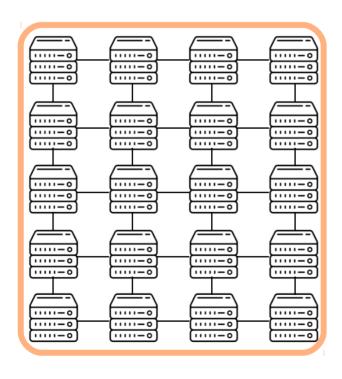
cpu_usage {50-100}%



Nodes in a group are connected through a **p2p** *gossip* channel

Nodes exchange membership information

cpu_usage {50-100}%

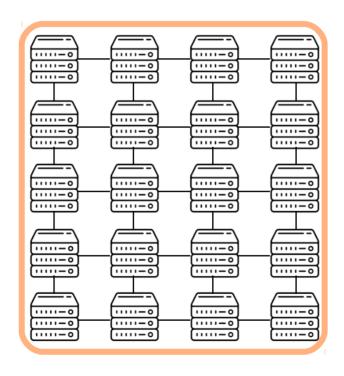


Nodes in a group are connected through a **p2p** *gossip* channel

Nodes exchange membership information

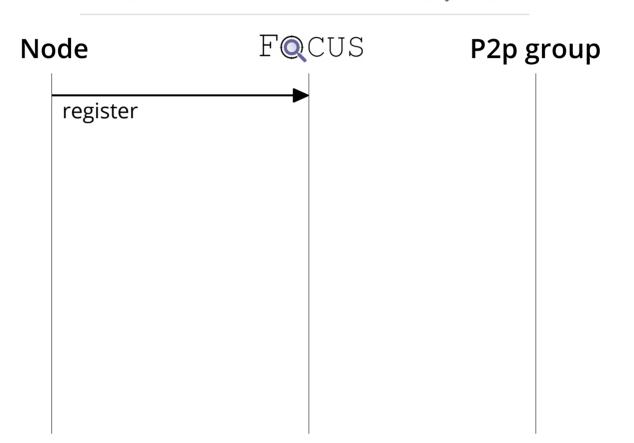
One node pushes group info to the FOCUS server

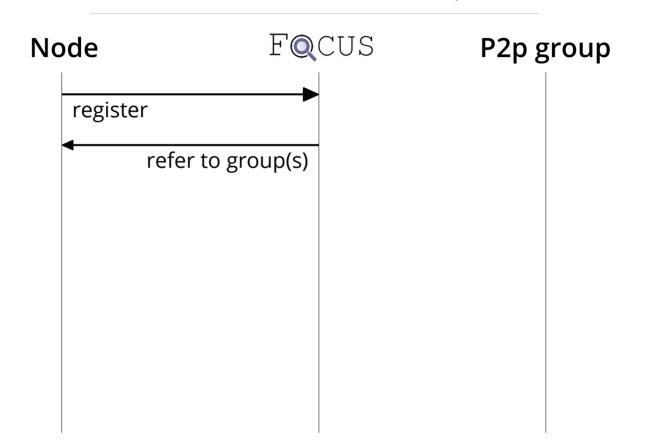
cpu_usage {50-100}%

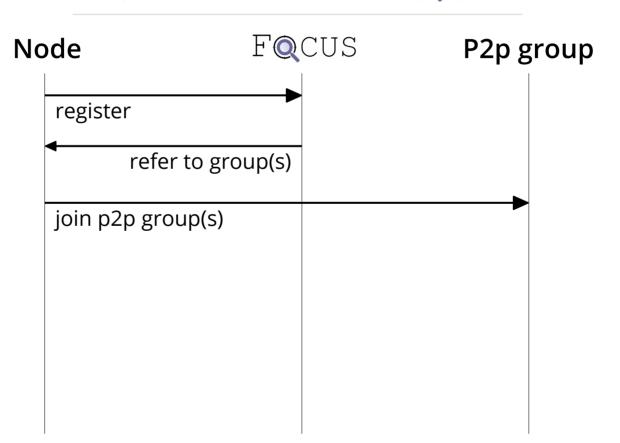


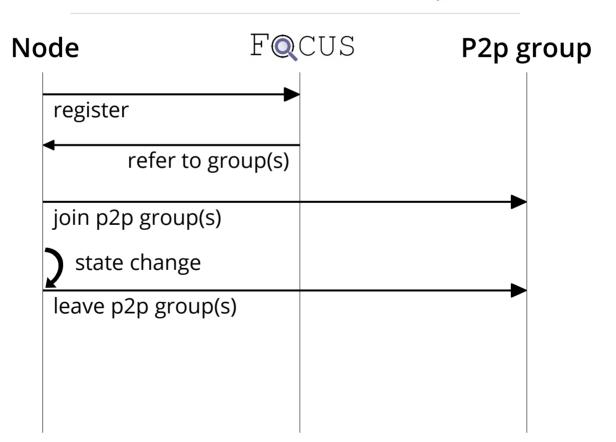
Nodes in a group are connected through a **p2p** gossip channel Nodes exchange membership information One node pushes group info to the FOCUS server Queries are propagated via gossip channel

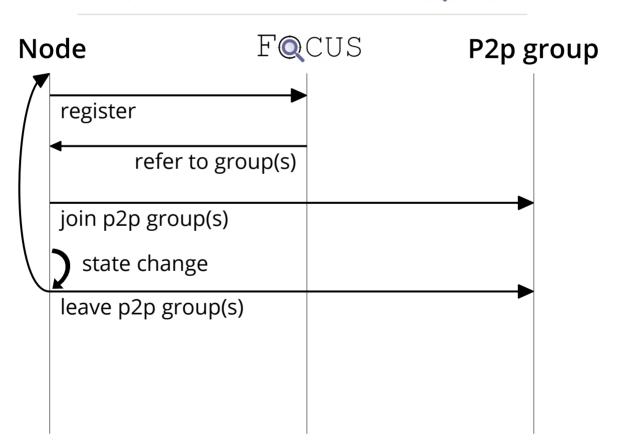
Node	F@cus	P2p group

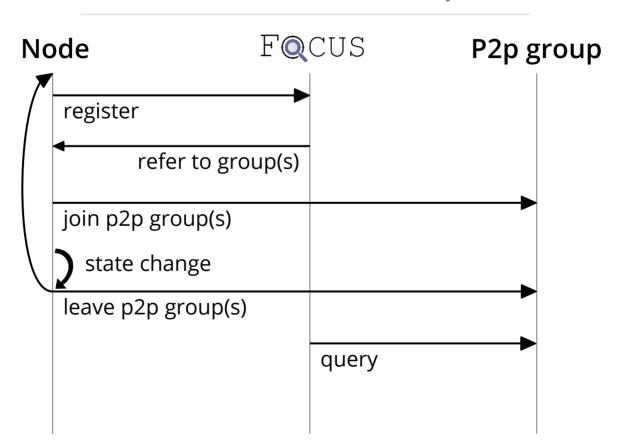


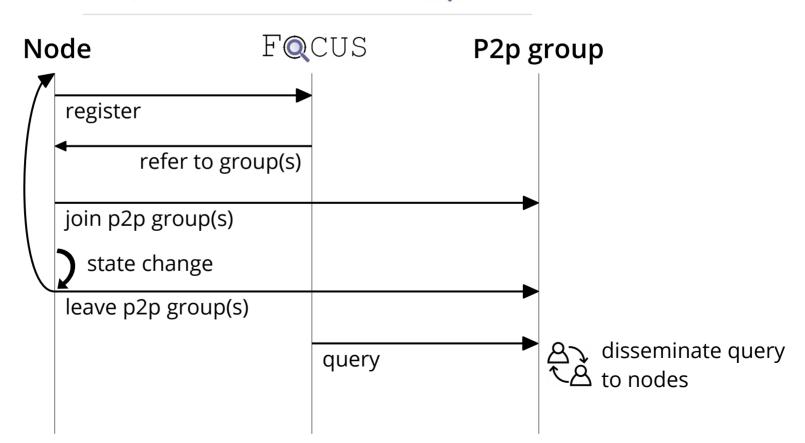


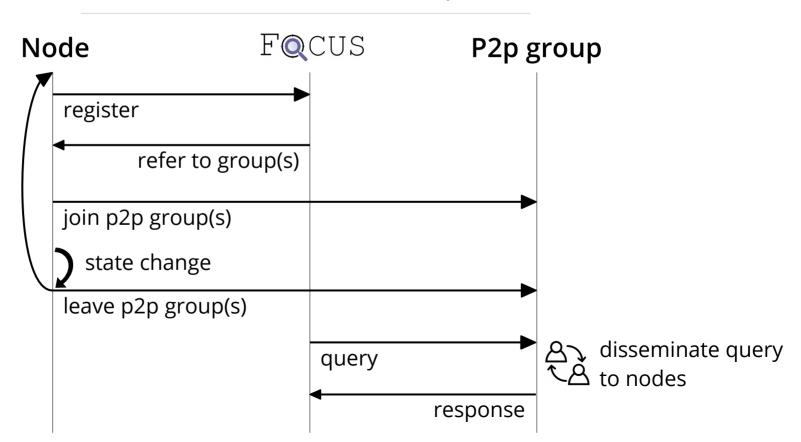






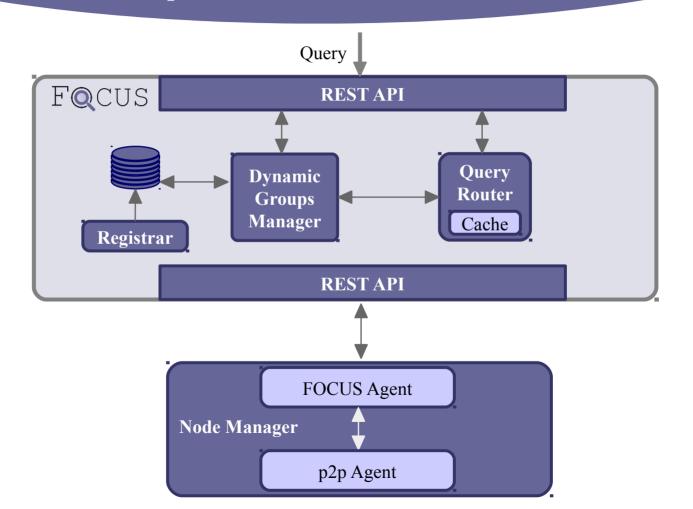




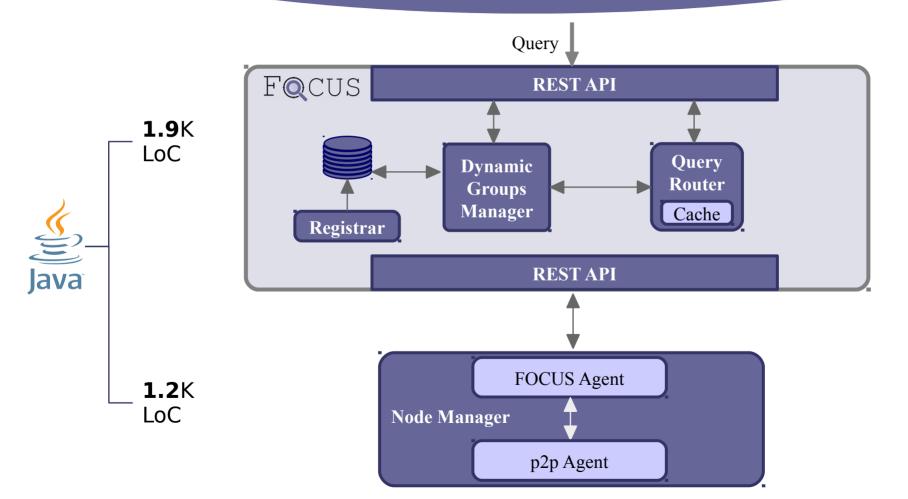


Implementation & Evaluation

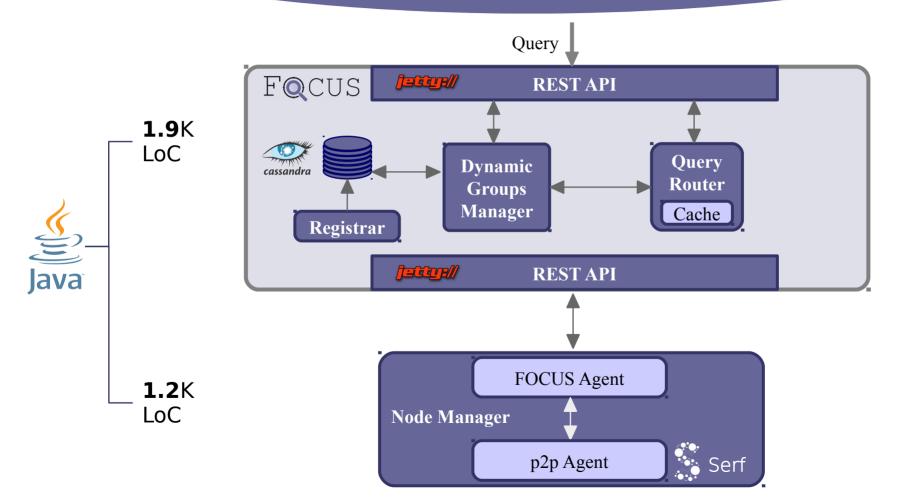
Implementation



Implementation



Implementation



Evaluation

- Deployed in Amazon EC2
- 4 regions: Canada, California, Ohio, Oregon
- In each region: 8 VMs (4 vCPUs, 16GB RAM)
- FOCUS server running in California (same VM config)
- Testing up to 1600 simulated node agents

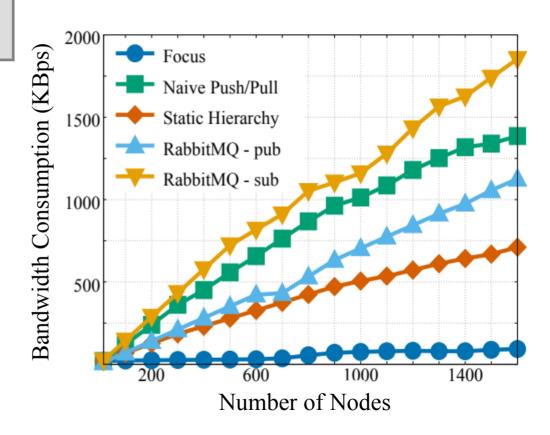
Measuring BW Consumption at the Query Server (frequency = 1 query/update per second)

Naive Push/Pull

Static Hierarchy

RabbitMQ (Publish)

RabbitMQ (Subscribe)



Measuring BW Consumption at the Query Server (frequency = 1 query/update per second)

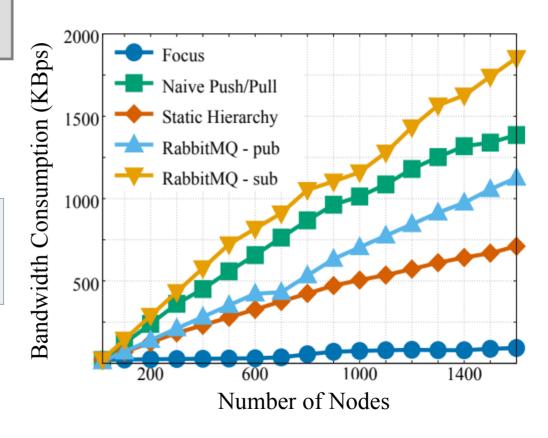
Naive Push/Pull

Static Hierarchy

RabbitMQ (Publish)

Adding a layer of intermediate nodes acting as aggregators

RabbitMQ (Subscribe)



Measuring BW Consumption at the Query Server (frequency = 1 query/update per second)

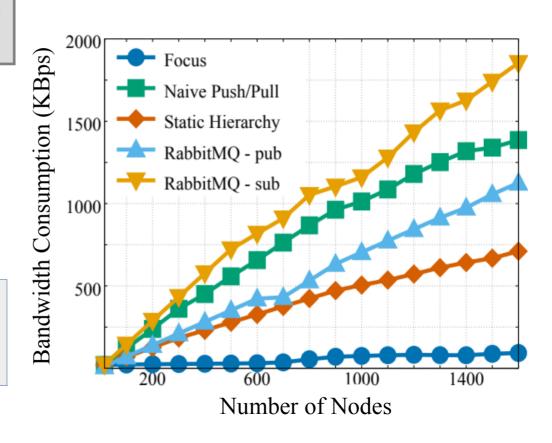
Naive Push/Pull

Static Hierarchy

RabbitMQ (Publish)

RabbitMQ (Subscribe)

Nodes publish their state (i.e.,fancy push)



Measuring BW Consumption at the Query Server (frequency = 1 query/update per second)

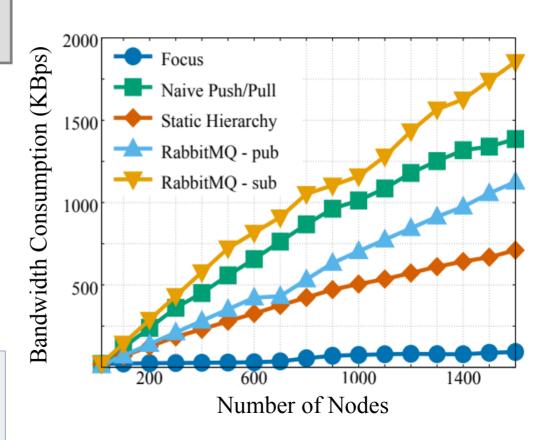
Naive Push/Pull

Static Hierarchy

RabbitMQ (Publish)

RabbitMQ (Subscribe)

Nodes subscribe for queries



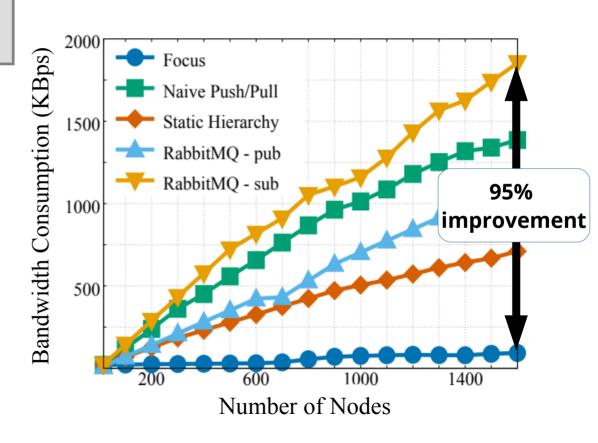
Measuring BW Consumption at the Query Server (frequency = 1 query/update per second)

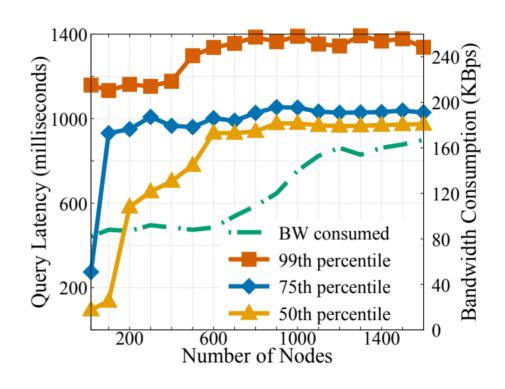
Naive Push/Pull

Static Hierarchy

RabbitMQ (Publish)

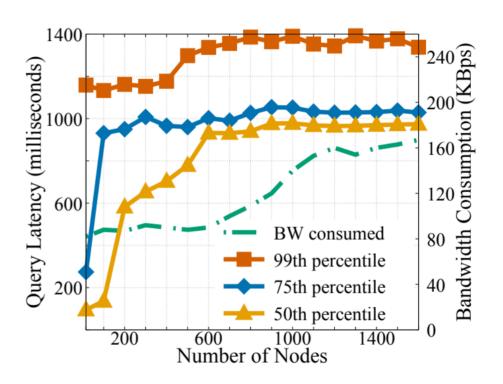
RabbitMQ (Subscribe)





^{* &}quot;Chameleon Cloud: A configurable experimental environment for largescale cloud research," https://www.chameleoncloud.org/.

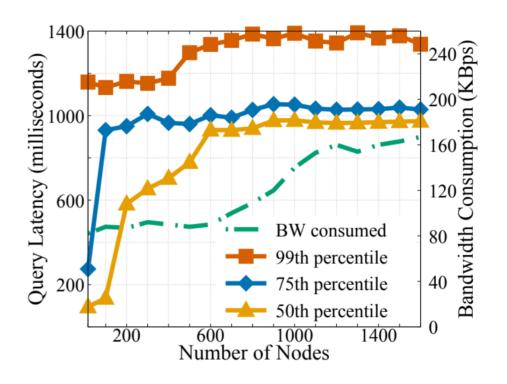
75K OpenStack VM placement requests



^{* &}quot;Chameleon Cloud: A configurable experimental environment for largescale cloud research," https://www.chameleoncloud.org/.

75K OpenStack VM placement requests

Replayed at accelerated rate (15,000x)



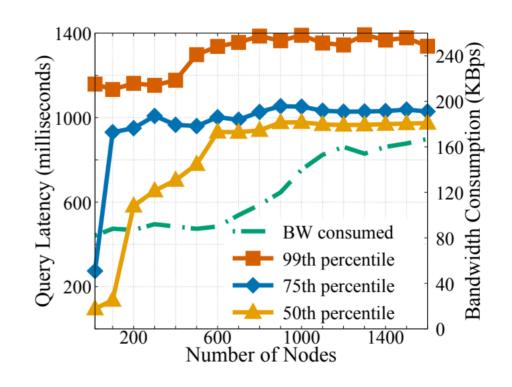
^{* &}quot;Chameleon Cloud: A configurable experimental environment for largescale cloud research," https://www.chameleoncloud.org/.

75K OpenStack VM placement requests

Replayed at accelerated rate (15,000x)

Latency stabilizes after 600 nodes

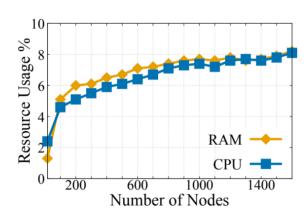
→ because group size is capped (~150 nodes per group)



^{* &}quot;Chameleon Cloud: A configurable experimental environment for largescale cloud research," https://www.chameleoncloud.org/.

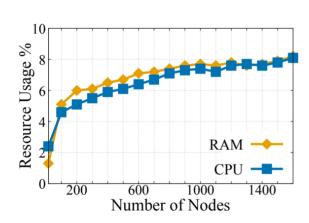
Microbenchmarks

Resource usage of the FOCUS server (40 queries/s)

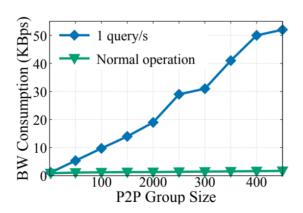


Microbenchmarks

Resource usage of the FOCUS server (40 queries/s)

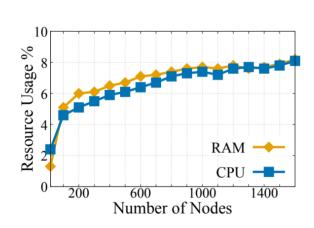


Overhead imposed by node agent (KBps)

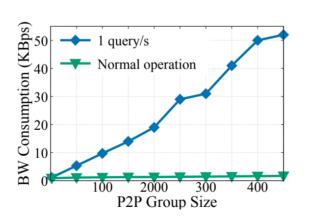


Microbenchmarks

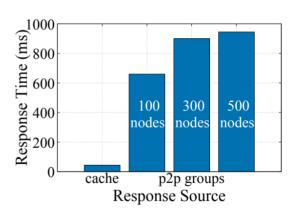
Resource usage of the FOCUS server (40 queries/s)



Overhead imposed by node agent (KBps)



Query response time for different group sizes



Conclusion

- Current systems' scalability is limited
 - This is due to tightly-coupled node management

Conclusion

- Current systems' scalability is limited
 - This is due to tightly-coupled node management
- FOCUS is scalable search service
 - Employs a *loosely-coupled* node management (p2p)
 - Scales better than current approaches (15x improvement)
 - Imposes *minimal* overhead on nodes
 - Integrates well with current systems

Thank You!

Questions?

FOCUS: Scalable Search Over Highly Dynamic Geo-distributed State

Azzam Alsudais

Mohammad Hashemi

Eric Keller

Zhe Huang, Bharath Balasubramanian Shankaranarayanan Puzhavakath Narayanan Kaustubh Joshi

IEEE ICDCS 2019 – Dallas, TX, USA July 9, 2019

Today, I'm presenting FOCUS: a generic and scalable search service for distributed systems in general with a focus on cloud systems.

This work is done in collaboration between University of Colorado Boulder and AT&T Labs Research.

Why do systems need to find nodes?

First, let's take a look at why systems need a search service to find a selection of their nodes that satisfy certain criteria.



I'll present 2 use-cases that motivate the need for a search service.

.

In cloud management platforms, we need to find nodes for various reasons.

Cloud Management

VM Provisioning

For instance, we need to find the best nodes to do things like VM placement and provisioning.

Cloud Management

VM Provisioning
VM Migration

Also, an extension to the previous example is that we need to find nodes to do VM migration.

For example, we need to find nodes that have enough capacities to migrate live Vms.

Cloud Management

VM Provisioning
VM Migration
Monitoring

Doing Health-checks and Monitoring, in general, is critical in Datacenter environments.

For instance, we might want an alarm that gets triggered whenever there's some overload on certain nodes so that we can do things like VM migration.

Cloud Management

VM Provisioning
VM Migration
Monitoring

NVF Automation

Another use-case for a search service is doing automation for Network Function Virtualization (or NFV) systems.

Cloud Management

VM Provisioning
VM Migration
Monitoring

NVF Automation

Geo-distributed VNF
Service Chain Placement

This includes performing VNF placement across geodistributed sites.

To some extent, it's similar to doing VM placement, but at a larger scale and with more complex requirements and policies.

In this use-case, we need to find nodes that are best suited to host our Network Functions.

Cloud Management

VM Provisioning
VM Migration
Monitoring

NVF Automation

Geo-distributed VNF
Service Chain Placement

Required information is assumed available

So, in such use-cases, systems make the assumption that required information (like current capacities of the nodes) is always available whenever they wish.

Cloud Management

VM Provisioning
VM Migration
Monitoring

NVF Automation

Geo-distributed VNF
Service Chain Placement

Required information is assumed available

But **HOW** is node information collected?

Now, let's take a look at how such systems collect this critical information in order to perform tasks such as VM, or VNF placement.

Outline

- How do systems find nodes?
- Limitations of current approaches
- FOCUS design
- Evaluation
- Conclusion

In the rest of the presentation, I'll talk about:

- how systems find nodes
- also, we will look at why those are limited, especially when deploying them at a large scale.
- Then, I will present our solution, FOCUS, which leverages concepts from p2p systems to scale.
- At the end, I will conclude with our evaluation.

Looking Under The Hood

How do systems search for nodes?

Ok, so let's go back to the question: How do systems find nodes that satisfy certain criteria?

Node finding in

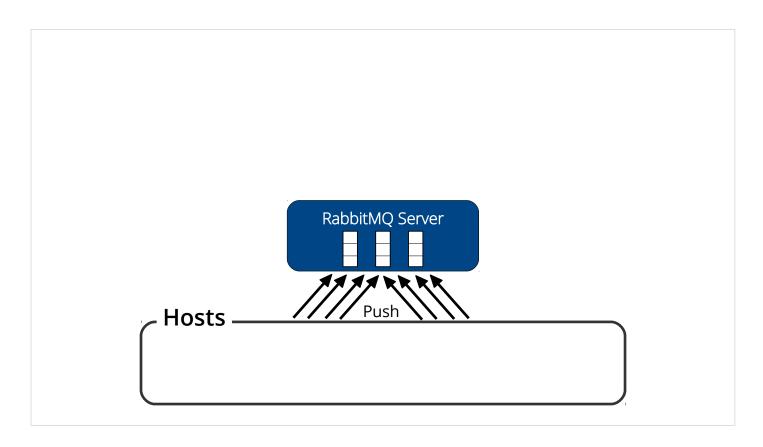
And to be practical, I'll use OpenStack to better demonstrate the answer.

For those who are not familiar with OpenStack, it is considered the de-facto standard for managing cloud infrastructures.

Hosts ——		

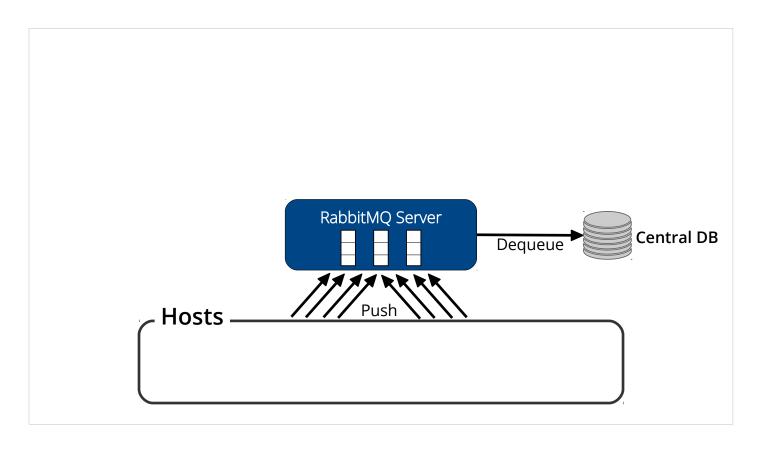
In OpenStack, there are physical hosts that comprise the system.

They are called Nova compute nodes, which are used as resources for things like VM placement.

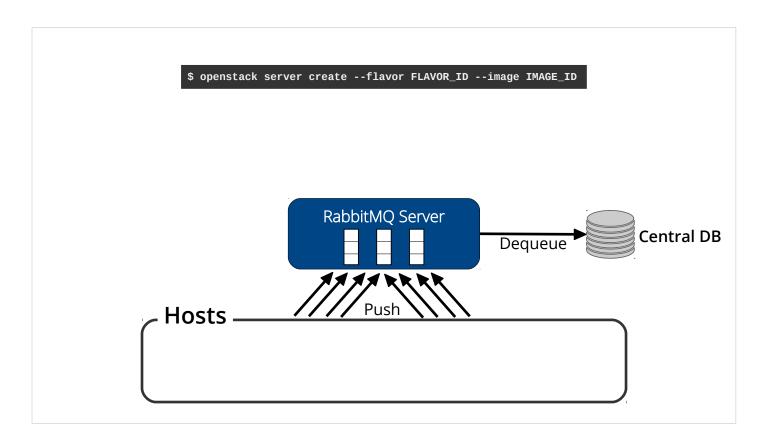


To obtain a current view of the system so that we know which nodes have which capacities, nodes periodically push their status to a special node that serves as a message bus.

In OpenStack, RabbitMQ (a pub-sub service) is used by default.

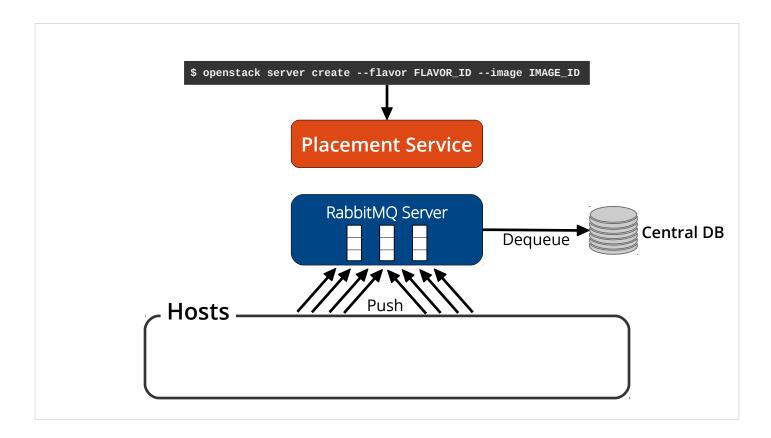


Then, a worker will dequeue information from the RabbitMQ node, and store it on a central database.



Now, when we issue a command like this to OpenStack (where we want to provision some VM)

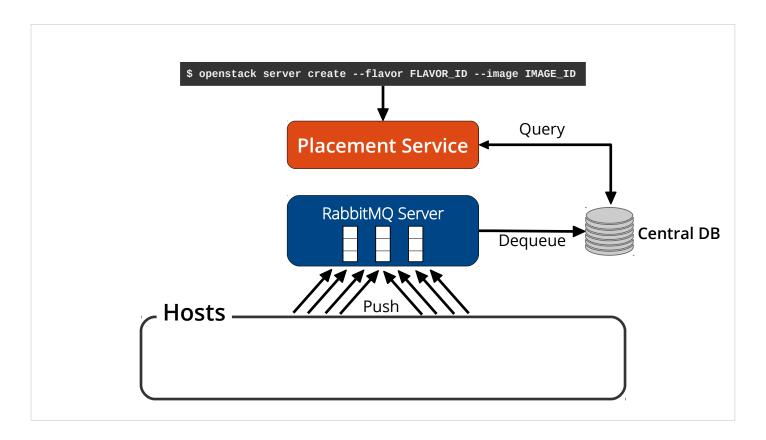
CLICK



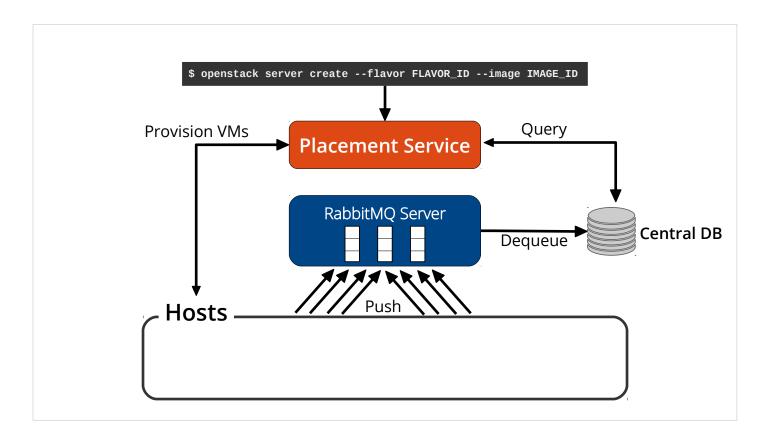
It will go through OpenStack's placement service, which parses the request, And then

.

CLICK



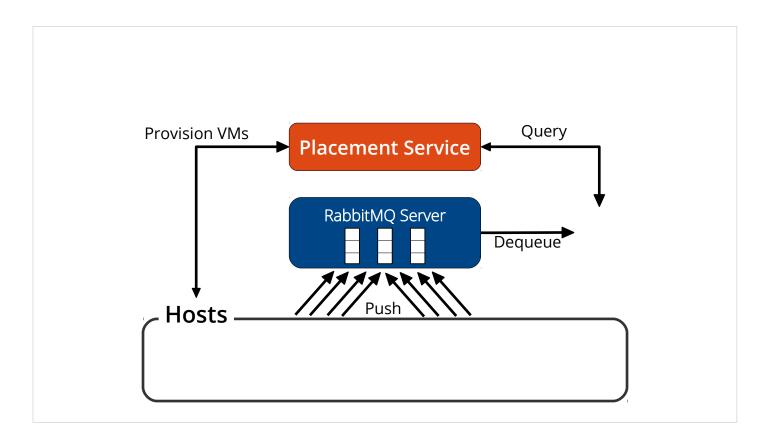
It will query the central Database to get host resource information.



It uses that information, then, to provision the VM using any placement logic (e.g., first-fit, greedy, etc).

Limitations of Current Approaches

Everything might seem to be fine. However, there are fundamental limitations to such approaches.

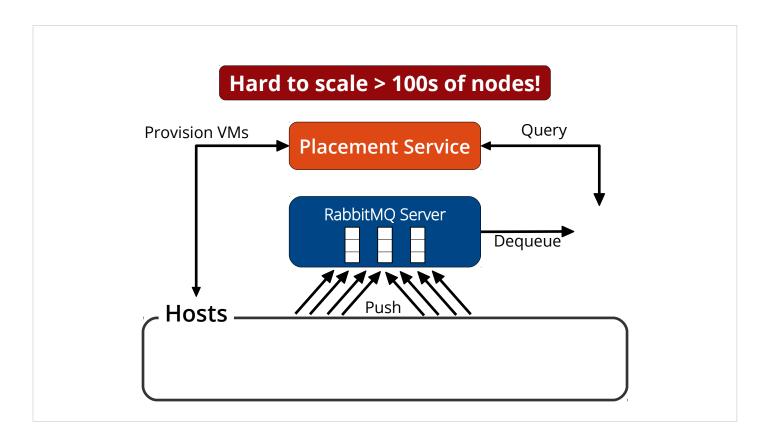


Specifically, there are 2 problems with this design.

First: The information we get from the local DB can be stale. And thus, it might cause incorrect behavior when we act on outdated information.

Another, and more critical, problem that we have identified is that ...

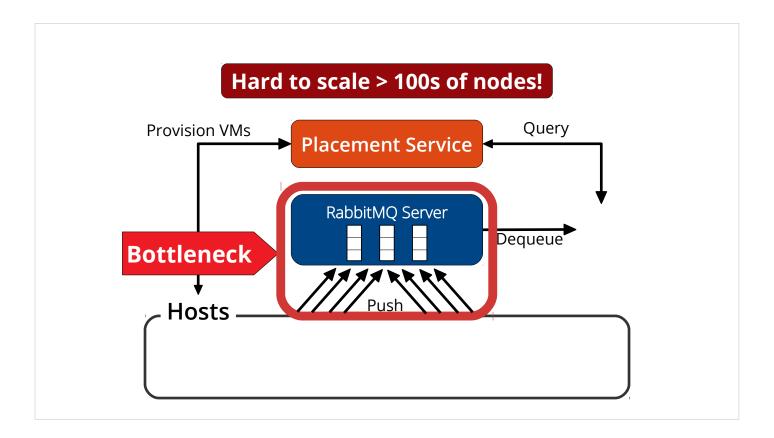
CLICK



It's hard to scale such deployment beyond a few hundreds of hosts.

-

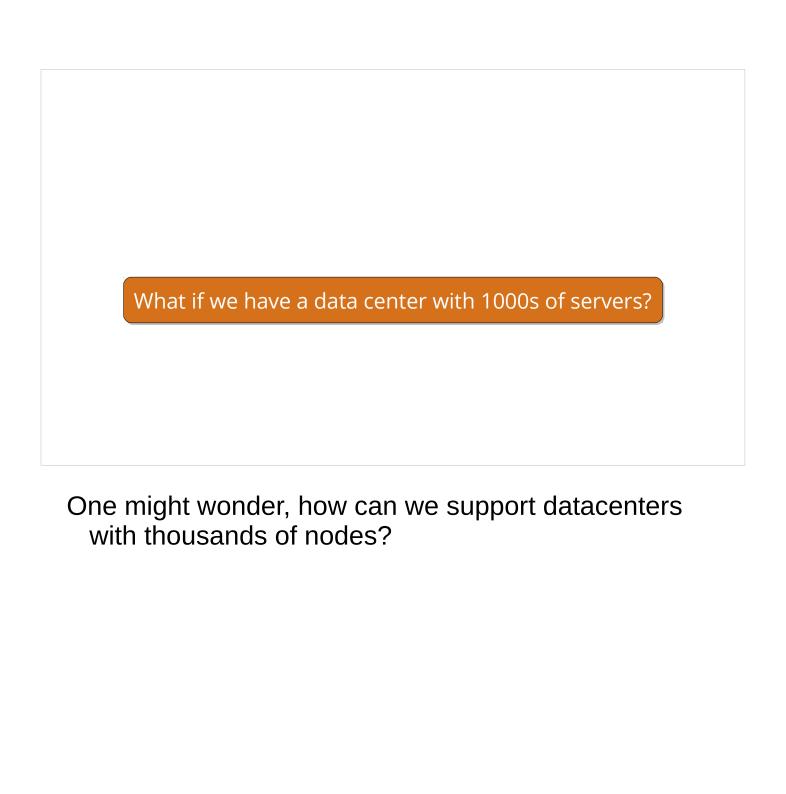
This is clearly a small number when we talk about multi-site clouds and geo-distributed network services.



Through some experimentation, we conclude that the bottleneck here is the use of message buses such as RabbitMQ.

Our experiments are also backed by experiments performed by the OpenStack community.

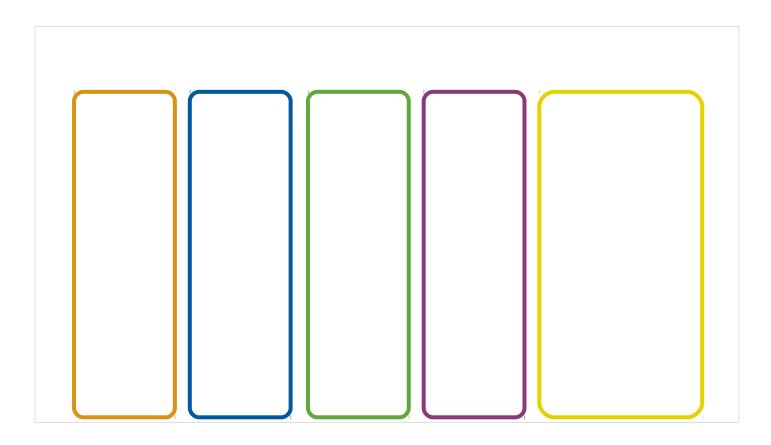
You can find the details of our experiment in the motivation section of the paper.





What if we have a data center with 1000s of servers?

A typical solution would be to create clusters inside the datacenter



So, here we divide the datacenter into multiple clusters.



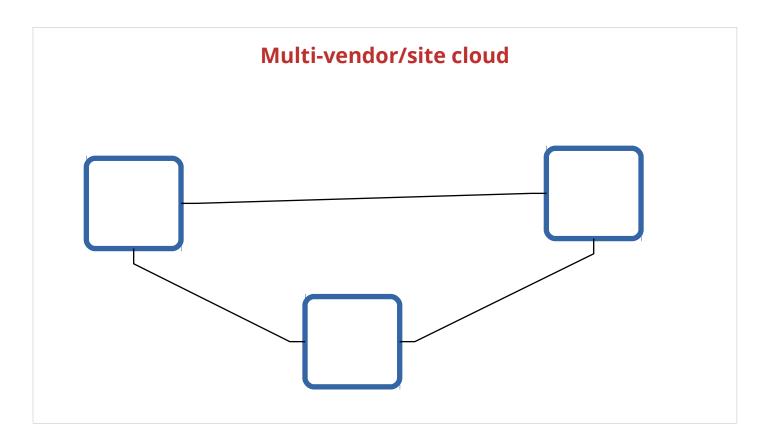
Each cluster acts as a standalone datacenter.



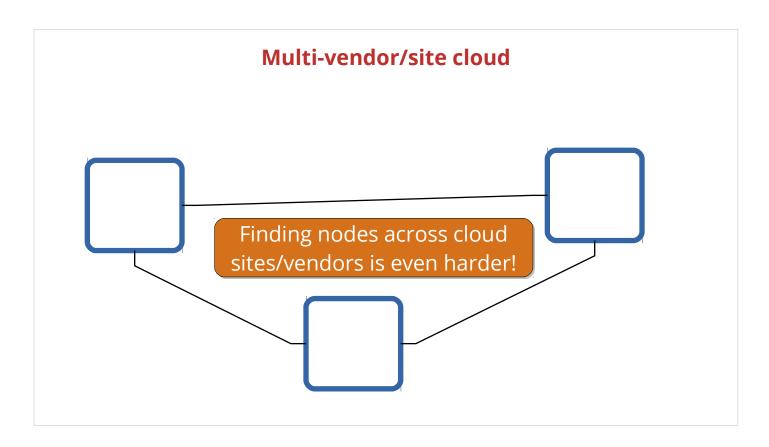
But this increases operational complexity.

•

We now, manage multiple datacenters instead of actually one.



Another challenge is when dealing with multi-site or multi-vendor cloud environments.

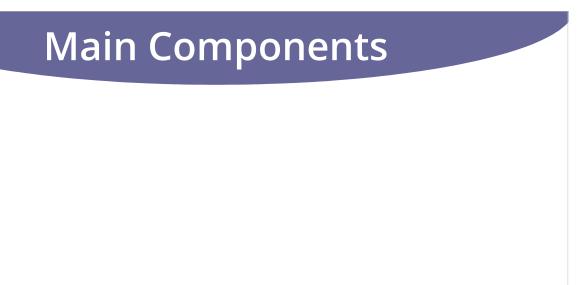


The problem is even worse in such environments. There are multiple players and it's not longer the case where we have only one control plane.



To that end, we present FOCUS:

A salable and generic search service for distributed systems.



There are three main components or concepts that make up FOCUS.



Query Processing with Directed Pulling

First, we perform optimized querying with a concept we call directed pulling.

.

So, instead of querying all nodes in the system, we only query those that we think will have the potential to satisfy such queries.



Query Processing with Directed Pulling

Gossip-based Node Coordination

Another concept that we employ is that nodes in the system connect to one another and manage themselves.

_

This form of decoupling allows us to reduce the load on a centralized control entity, and thus scale much better than current approaches.



Query Processing with Directed Pulling

Gossip-based Node Coordination



Easy-to-integrate Query Interface

Lastly, we design the system in a way that allows it to easily integrate with existing systems through providing a neutral API, and we actually show how it can be done by integrating with OpenStack.



Query Processing with Directed Pulling

Gossip-based Node Coordination



Easy-to-integrate Query Interface

However, due to the limited time, I will only go over the first two concepts, and you can find details on our integration with OpenStack in section 9 in the paper.

Abstractions

First, I'll describe some of the important abstractions we made.

Abstractions

Node Attributes

Each node in the system has some attributes.



Which can be divided into either static or dynamic

Abstractions Node Attributes Static Never change Dynamic

Static attributes never change

Abstractions Node Attributes Never change

Dynamic

cpu cores, arch, etc

Static

For instance, the number of physical cores, or the architecture of the machine are things that never change.

Abstractions

```
Node Attributes

Static

Never change

# cpu cores, arch, etc

Dynamic

Frequently change
```

However, dynamic attributes DO change..

And they might change too frequently, depending on the workload and the environment.

Abstractions Node Attributes Static Never change # cpu cores, arch, etc Dynamic Frequently change Usage: cpu, ram, disk, bandwidth, etc

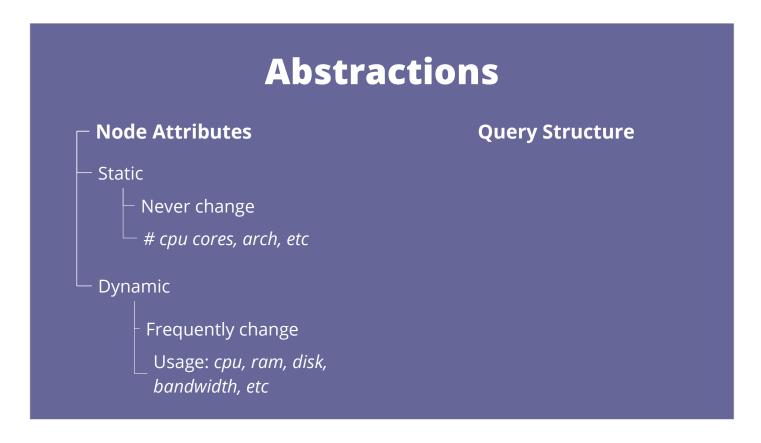
These are things like, usage information such as CPU, RAM, DISK, or bandwidth.

.

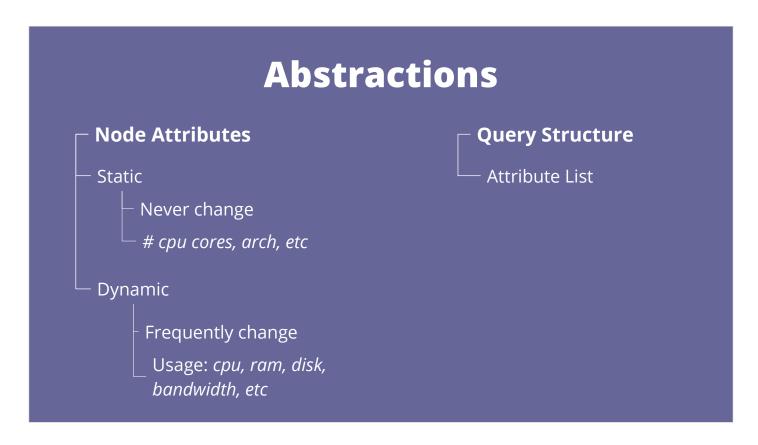
Abstractions Node Attributes Static Never change # cpu cores, arch, etc Dynamic Frequently change Usage: cpu, ram, disk, bandwidth, etc

Since static attributes can be cached once and obtained anytime,

We focus on dynamic attributes, and design our system accordingly.



Another important abstraction is the Query structure.



Each query will have a list of attributes and their desired values.

Abstractions Node Attributes Static Never change # cpu cores, arch, etc Dynamic Frequently change Usage: cpu, ram, disk, bandwidth, etc Attribute List name (string) upper bound (int) lower bound (int)

Which is made of three fields:

- 1- name of the attribute.
- 2- upper bound of the value
- 3- and lower bound of the value

Abstractions Node Attributes Query Structure Attribute List Static Never change name (string) # cpu cores, arch, etc upper bound (int) *lower bound (int)* Dynamic limit (int) Frequently change freshness (int) Usage: cpu, ram, disk, bandwidth, etc

Two other parameters are: limit and freshness of the results.

.

You can specify a limit on the number of returned results because if the limit is smaller, then we can return results in a much shorter time.

And you can specify how fresh the results should be. If the query does not require fresh results, then we can always get cached information to boost the performance.

Query Processing with Directed Pulling

Ok, so how can we send queries to only those nodes that we "think" will have the potential to satisfy the query?



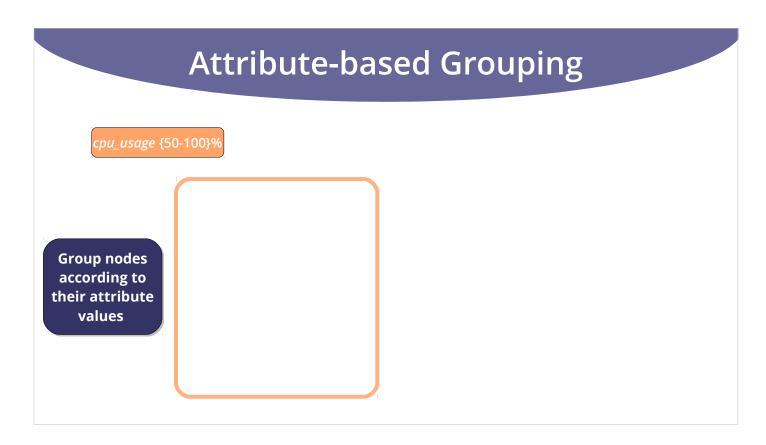
We achieve that by using a novel concept we call: attribute-based grouping.

Attribute-based Grouping

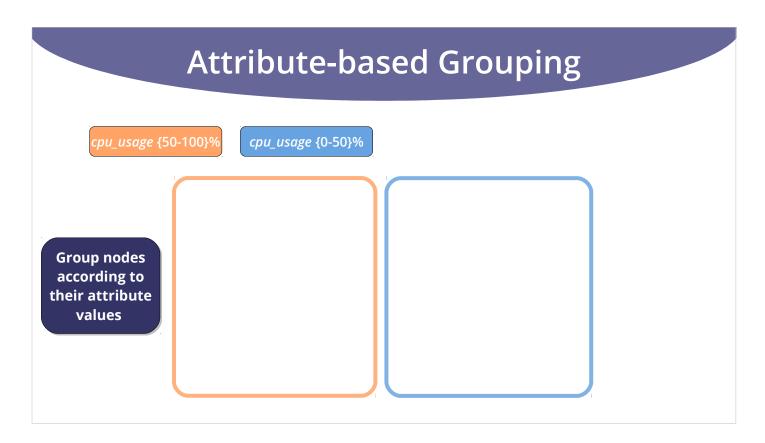
Group nodes according to their attribute values

That is, we group nodes that have similar attribute values together.

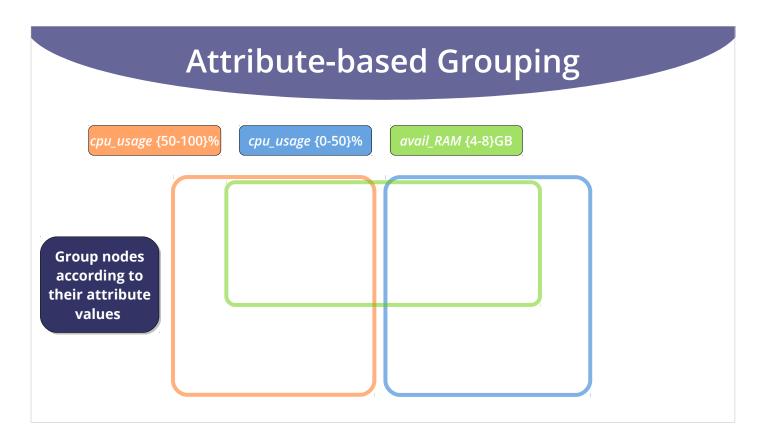
One group per attribute value range.



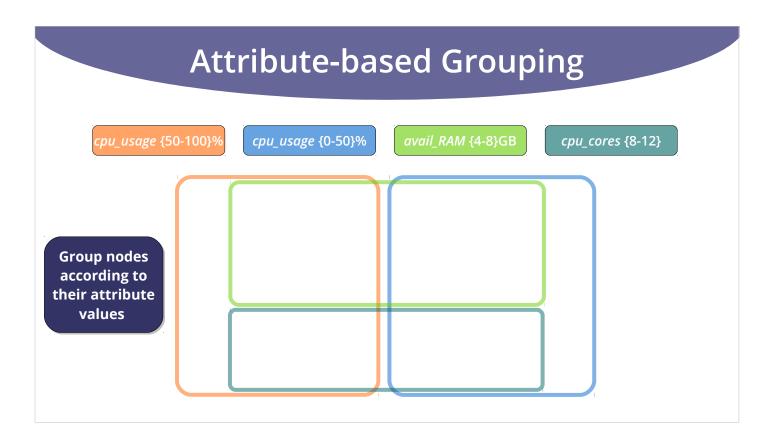
For instance, we might want to group nodes that have a cpu usage above 50%.



And another group for the other nodes.



And for other attributes, we create separate groups.

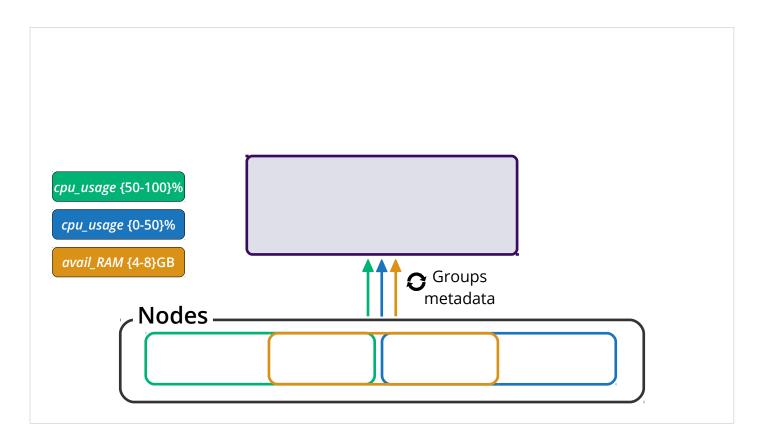


And so on.

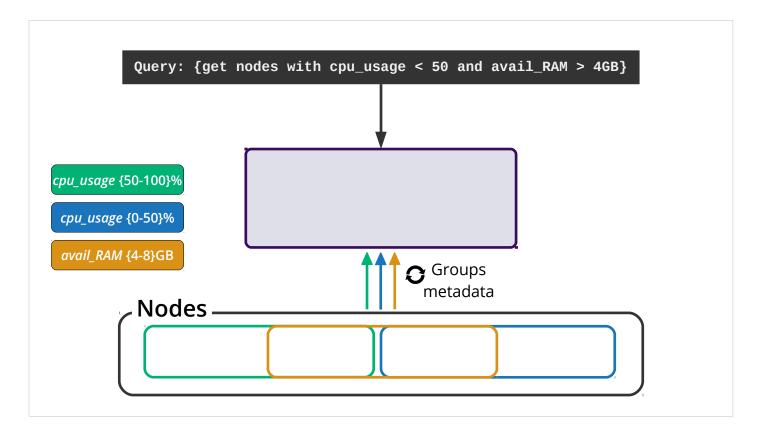
A key thing here is that a node can be in X number of groups if it has X number of attributes.

cpu_usage {50-100}% cpu_usage {0-50}% avail_RAM {4-8}GB	
Nodes —	

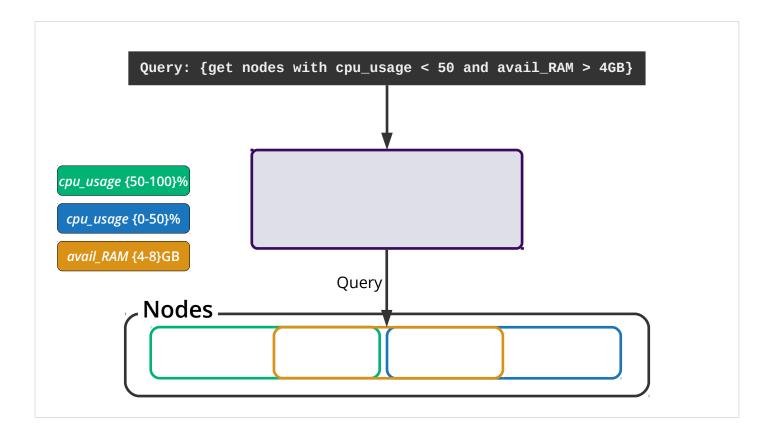
Now that we logically organized nodes into different groups based on their attribute values, how can we actually tell which nodes are in which group?



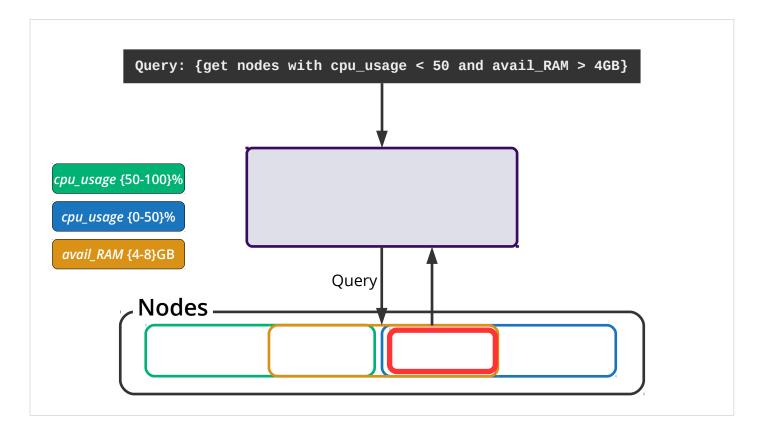
For each of those groups, we select a node that periodically pushes group-wide information (containing membership information) to our service.



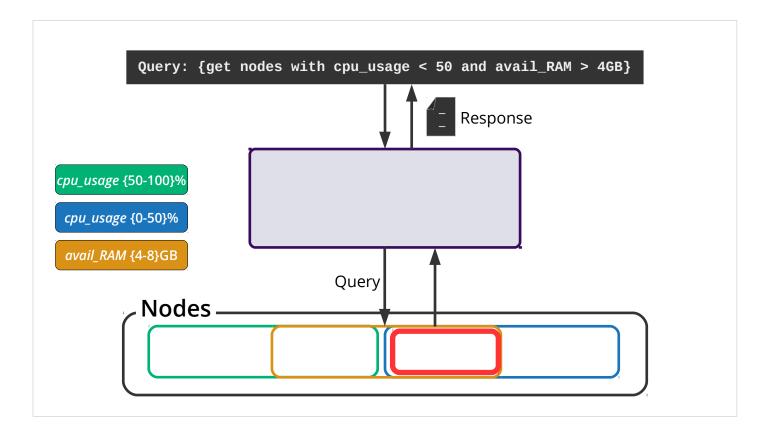
Then whenever we receive a query like this,



Acting on the group-wide information we periodically get, we send the query only to the group that satisfies the query.



In this case, we get up-to-date responses from nodes in the group.



And return a list of nodes that actually satisfy the query.

.

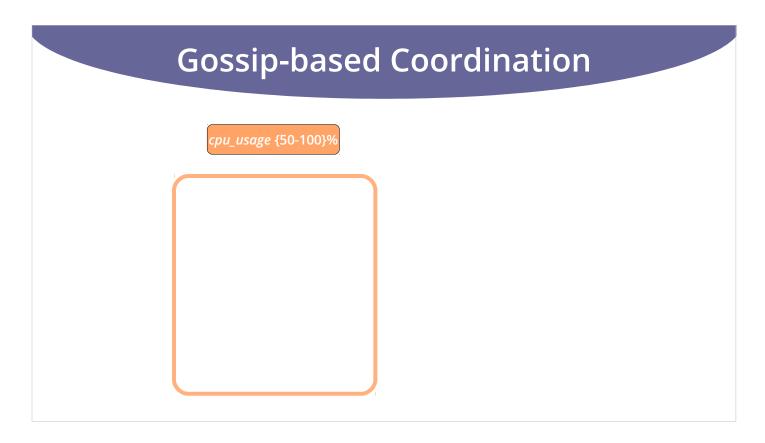
So, attribute-based grouping allows us to know inadvance which nodes are part of which group, and hence, which nodes have which information.

All of this is done in a dynamic and loosely-coupled manner.

Gossip-based Node Coordination

Ok, the second concept that motivates the design of FOCUS is that those groups are self-formed by the nodes.

And to coordinate how that's done, we let nodes form p2p groups that use the lightweight gossip-protocol to exchange messages.



So, revisiting the example from earlier, here we have a group for nodes with CPU usage larger than 50%.

Gossip-based Coordination

cpu_usage {50-100}%

Nodes in a group are connected through a **p2p** *gossip* channel

Each node of the group connects to only a few other members in the group.

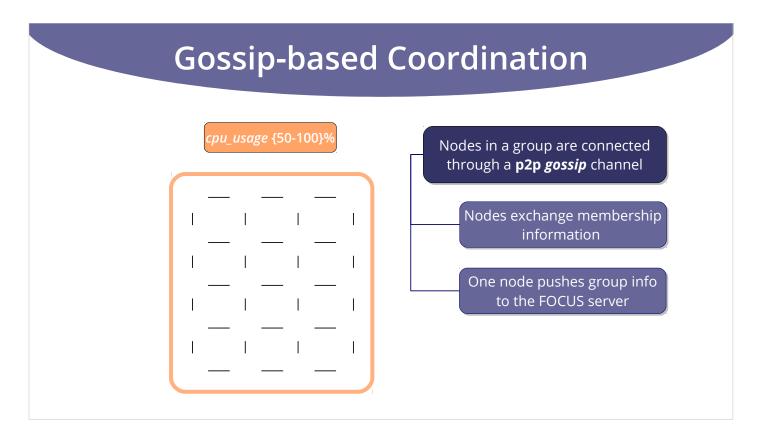
.

The number of peer nodes is referred to as the "fanout" parameter, which can be configured at start time.

Nodes within the same gossip group exchange messages with one another.

.

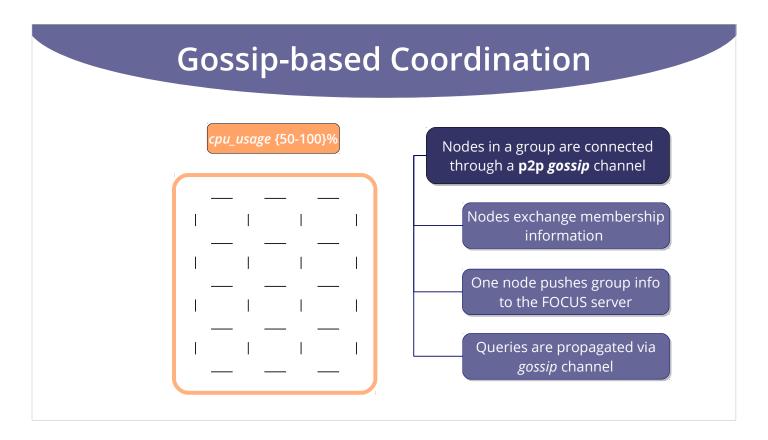
Such messages are mainly membership messages (telling who's a member of the group)



We select one node in the group to be a group representative.

.

Its main job is to periodically synchronize the membership list with the FOCUS server.



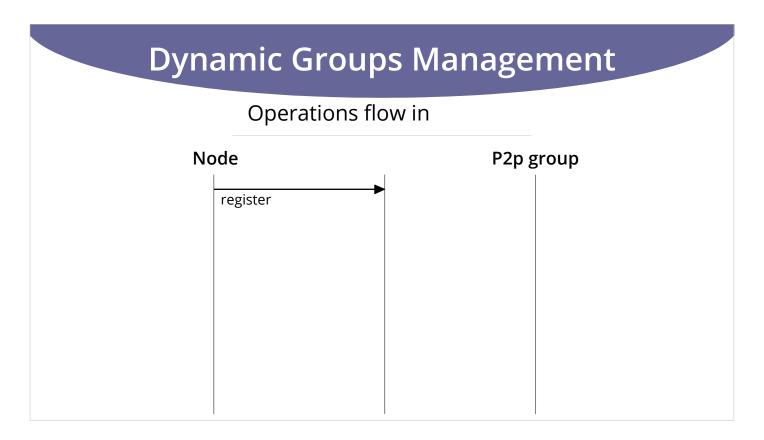
Then whenever the FOCUS server receives a query, it will forward it to the group whose metadata (i.e., the group attribute value range) satisfies the query.

.

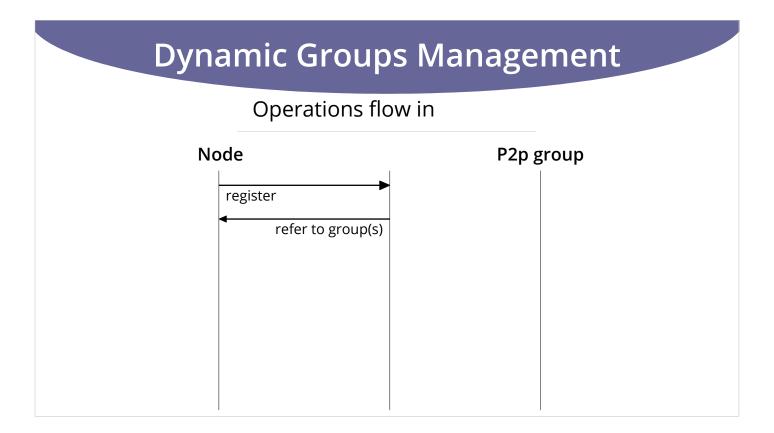
Then the member who receives the query will broadcast it to all other members of the group, who then will respond by sending their responses to the gossip-channel so that the query issuer does not get overwhelmed.

Dynamic Groups Management				
Operations flow in				
Node		P2p group		

Ok, let me describe the end-to-end flow of operations in FOCUS so that it's clear how everything fits together.

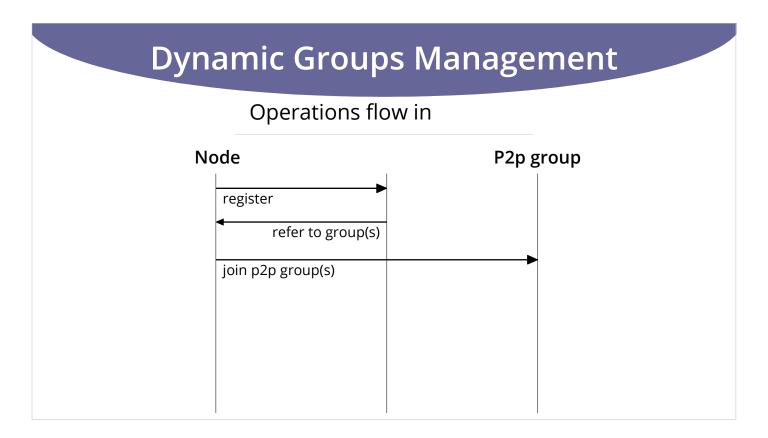


When a node starts up, its FOCUS agent will contact the FOCUS server and register its attributes.

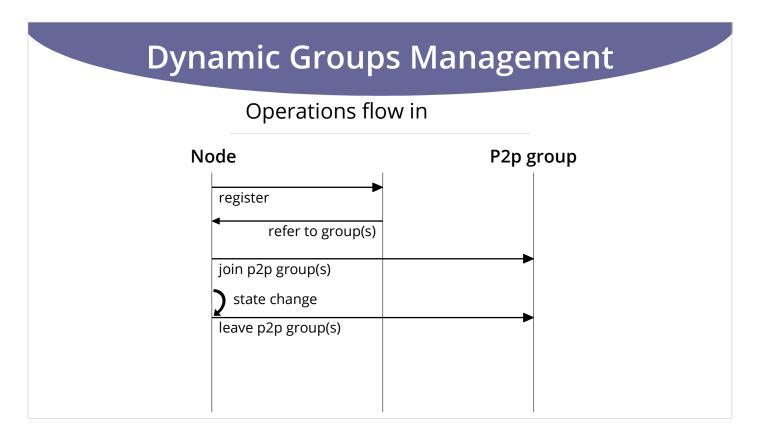


The FOCUS server will parse those attributes and look up the local information that it has about the already established p2p groups,

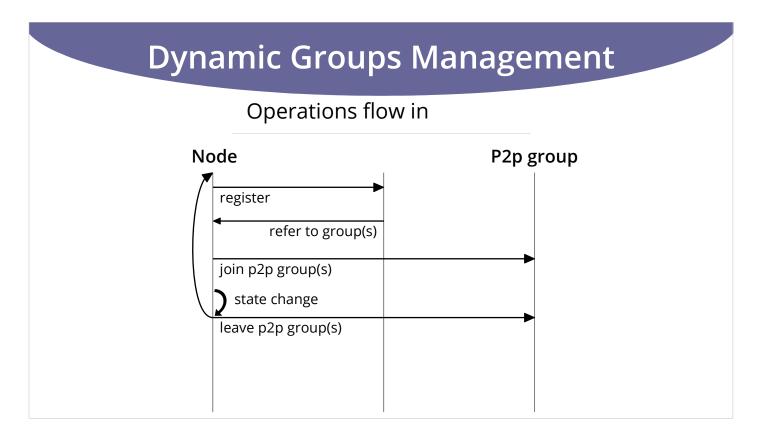
Then it will refer the newly registered node to the right groups.



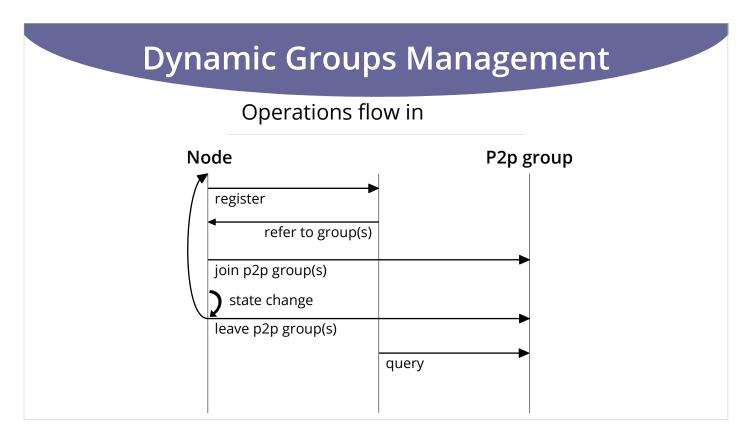
Consequently, the node will go ahead and request to join each of those groups, and start gossiping with other members of the same group.



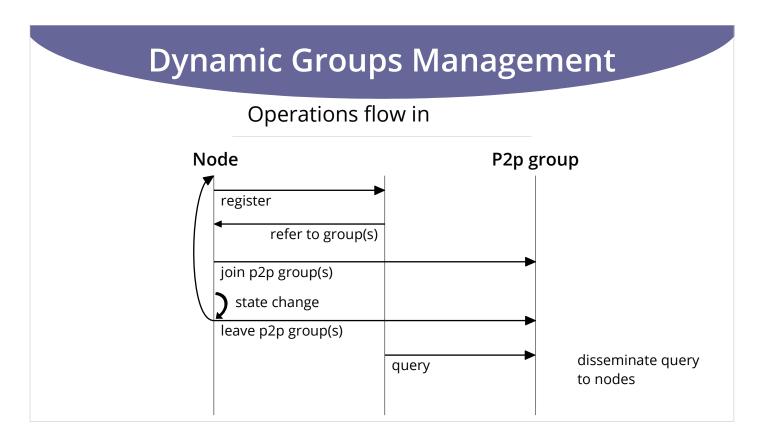
Now, whenever one of the node's attribute changes, the FOCUS node agent will detect that, and determine if we need to leave the corresponding group for that attribute (which is when the new value falls outside the group value range).



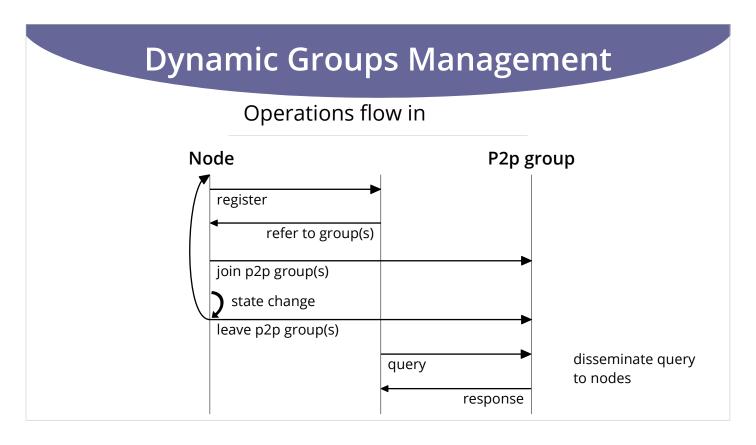
If it decides to leave one of the groups, it will go back to and ask the FOCUS server for new group suggestions and so on.



Now, when the FOCUS server receives a query, it will decide which group to forward it to (based on the information it already has from the group representatives).



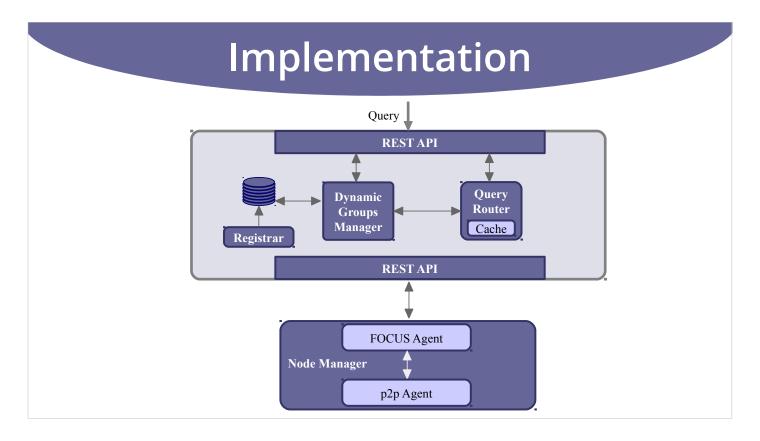
Upon receiving a query from the FOCUS server, a member will disseminate it to other members of the group.



The results then are aggregated and sent back to the FOCUS server.

Implementation & Evaluation

So, now let's take a look at what tools we used to implement FOCUS, and how it performs.

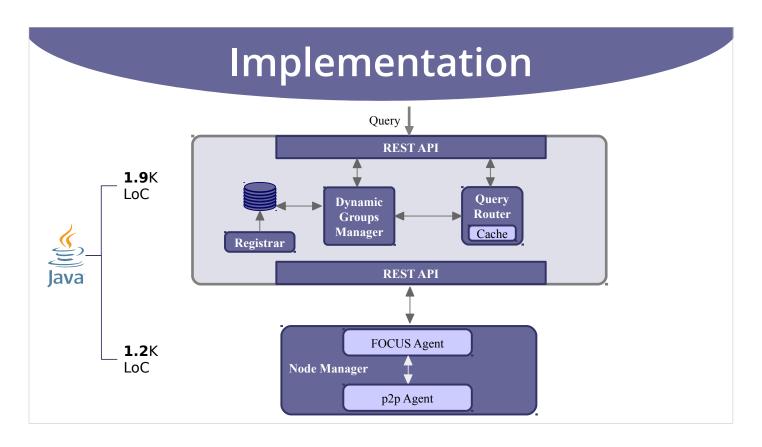


This is a detailed design of FOCUS, showing its internal components.

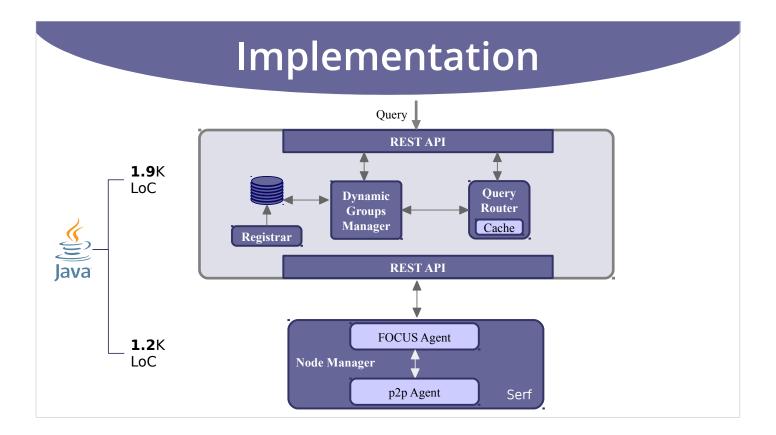
.

We have 3 main components, in addition to the node agent.

- 1- The Registrar, which is basically an entry point to the system (and holds static info).
- 2- The Dynamic Groups Manager (DGM), which holds dynamic information on which nodes belong to which groups.
- 3- The Query Router: provides a REST API to FOCUS client applications (like OpenStack) to make queries and receive responses.



FOCUS is implemented in Java with a total of 3.1K LoCs.



And here are some of the tools that we have used to implement FOCUS.

.

CLICK SKIP

.

For our REST APIs, we used Eclipse's Jetty web server wrapper.

-

And for our data-store (which has mostly static information), we used the Apache Cassandra: a fast geo-distributed data store.

And we used HashiCorp's Serf as our gossip p2p fabric.

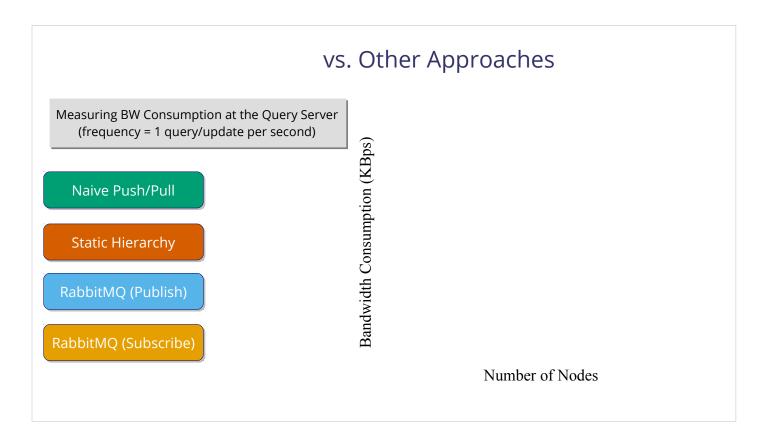
Evaluation

- Deployed in Amazon EC2
- 4 regions: Canada, California, Ohio, Oregon
- In each region: 8 VMs (4 vCPUs, 16GB RAM)
- FOCUS server running in California (same VM config)
- Testing up to 1600 simulated node agents

To evaluate FOCUS, we deployed it in 4 regions of Amazon's EC2.

And we ran tests with up to 1600 nodes.

Note that these are simulated nodes and we consolidated many simulated node agents in each of VMs we had.



In our first experiment, we compare FOCUS to other approaches of node finding.

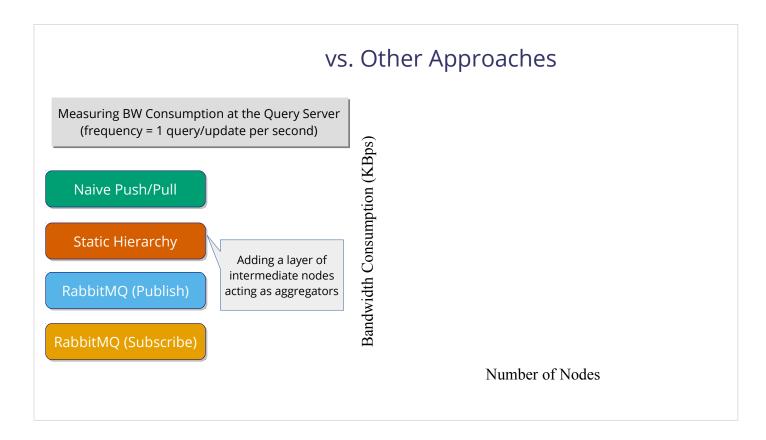
We measured BW consumption on the query server and used that as an indicator for how well each of these approaches scale.

The query or update frequency is set to once per second.

.

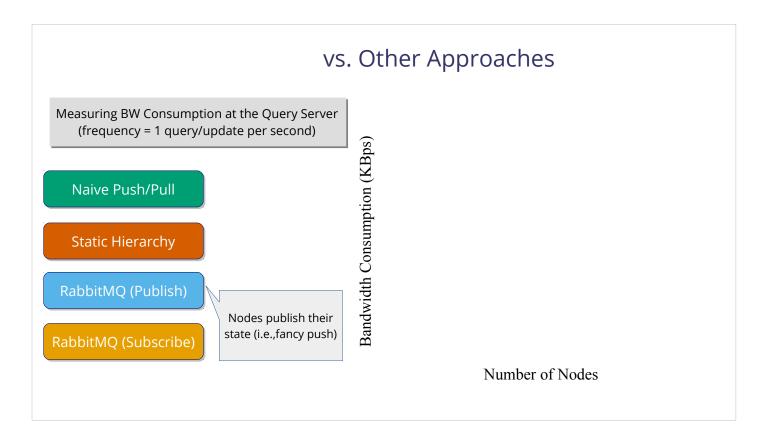
Let me describe really quickly what each of these approaches do.

For the naive push/pull, we simply had nodes either push their information individually, or we made the FOCUS server pull from each of them.



We also implemented a system, in which we introduce static hierarchy.

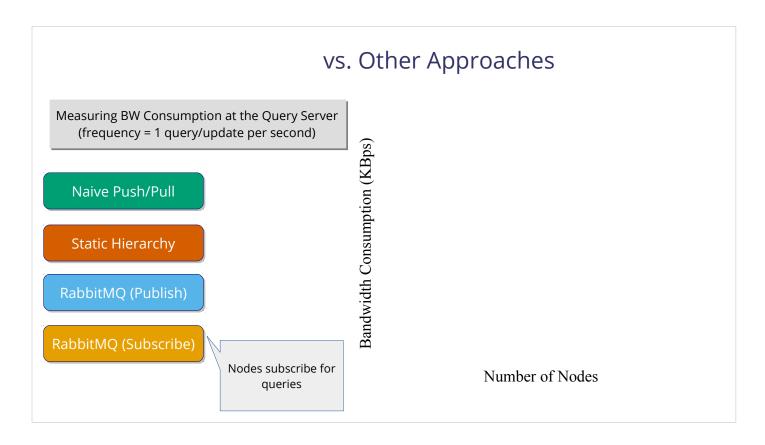
In this system, we had a layer of intermediate nodes to which other nodes would send their updates. Who, in turn, will aggregate those updates and send them to the query server.



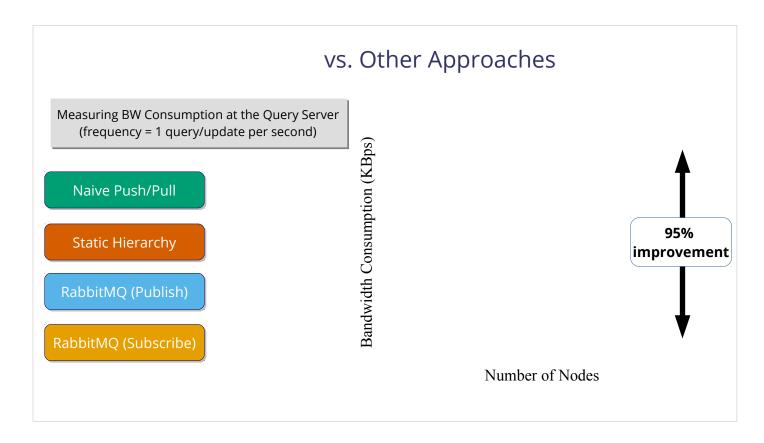
We also compare against RabbitMQ, the message Q used by OpenStack.

There are two configurations for RabbitMQ.

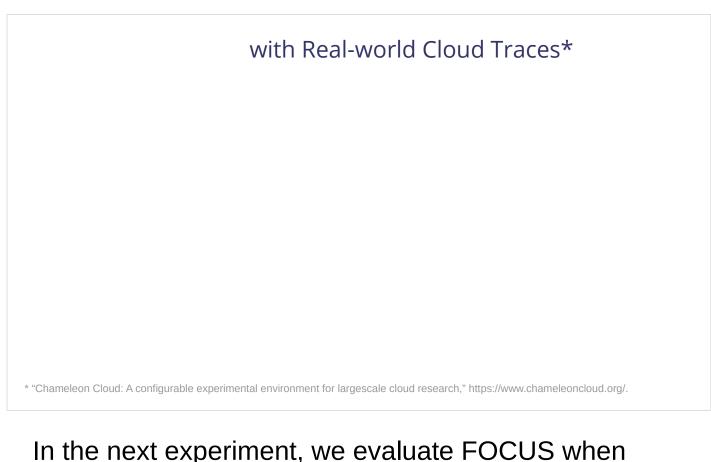
The publish configuration is where nodes publish their state (which is sort of a fancy push). And the query server will subscribe for those updates.



And the subscribe configuration is where nodes subscribe for queries, which are published by the Query Server.



Thanks to our loosely-coupled node management and attribute-based grouping, we were able to provide up to 95% improvement (or reduction of BW consumption) when compared with RabbitMQ subscribe configuration.



In the next experiment, we evaluate FOCUS when processing real-world cloud queries.

with Real-world Cloud Traces*

75K OpenStack VM placement requests

We had a trace of 75K OpenStack VM placement requests.

^{* &}quot;Chameleon Cloud: A configurable experimental environment for largescale cloud research," https://www.chameleoncloud.org/.



75K OpenStack VM placement requests

Replayed at accelerated rate (15,000x)

And replayed the trace at an accelerated rate to test how FOCUS performed under high load.

^{* &}quot;Chameleon Cloud: A configurable experimental environment for largescale cloud research," https://www.chameleoncloud.org/.

with Real-world Cloud Traces*

75K OpenStack VM placement requests

Replayed at accelerated rate (15,000x)

Latency stabilizes after 600 nodes

→ because group size is capped (~150 nodes per group)

* "Chameleon Cloud: A configurable experimental environment for largescale cloud research," https://www.chameleoncloud.org/.

You can see here that the latency stabilizes after having 600 nodes in the system.

This is due to the fact that we capped the group size (and hence, quickly respond to queries without compromising on accuracy).

Microbenchmarks

Resource usage of the FOCUS server (40 queries/s)

In this last part, we provide some micro-benchmarks for our FOCUS server as well as the node agent.

In this graph, we measured resource usage of the FOCUS server under a heavy load, where it processed 40 queries / second.

And thanks to the loosely-coupled design, you can see that it's not resource hungry.

Microbenchmarks

Resource usage of the FOCUS server (40 queries/s)

Overhead imposed by node agent (KBps)

We have also measured the overhead imposed by our node agent (especially for the p2p gossip-part)

.

We had two configurations for this experiment:

- 1- when the node processes 1 Query / second
- 2- and the normal behavior of a node (i.e., when it gossips with other nodes.)

.

The overhead here is negligible even if we have large groups of up to 500 nodes.

.

The reason here is because in normal operation, the number of peer nodes with which we gossip is irrelevant to the group size.

Resource usage of the FOCUS server (40 queries/s) Overhead imposed by node agent (KBps) Query response time for different group sizes

In this last experiment, we measure the query response latency when we vary the group size (which has a direct impact on how quickly the group converges).

In addition, we measure the latency if the query response is to be fetched from a local cache.

You can see that query response latency does not grow rapidly as the group size increases.

Conclusion

- · Current systems' scalability is limited
 - This is due to tightly-coupled node management

To conclude with, We showed that current systems' scalability is limited.

.

We studied the underlying cause of this and concluded that the reason of this limitation is because such systems impose an unneeded tightly-coupled node management.

Conclusion

- Current systems' scalability is limited
 - This is due to tightly-coupled node management
- FOCUS is scalable search service
 - Employs a *loosely-coupled* node management (p2p)
 - Scales better than current approaches (15x improvement)
 - Imposes *minimal* overhead on nodes
 - Integrates well with current systems

To that end, we designed FOCUS: a scalable search service for distributed systems.

Through loosely-coupled node management and attribute-based grouping, we were able to scale much better than current approaches.

And at the same time impose a minimal overhead on the nodes in the system.

We also believe in practicality, so we designed FOCUS in a way that it allows it to integrate easily well with existing systems.



Questions?