# **Anomaly Detection**

# What is an Anomaly?

 Anomaly is synonymous with an outlier. These terms are often interchanged and may be called Novelty depending on the context.

## What's the difference?

- Anomaly means something which is not a part of the normal behavior
- Novelty means something unique, or something that you haven't seen before(novel)

## 1. Distribution Based

• The simplest way to detect an outlier would be to use distribution parameters (mean and standard deviation).

# Problem with this approach:

- While we know the distribution, the parameter estimates of the distribution are often corrupted by the noise/outlier
- Hence, we need to robustly estimate the parameters of the distribution.

#### 2. z-score

**Calculate the z-score for each data point**: The z-score of a data point (x) is calculated using the formula:

$$z = \frac{x-\mu}{\sigma}$$

## **Identify outliers**:

• you can identify outliers based on a chosen threshold( $\tau$ )

•  $|z| > \tau$ , the point is an outlier

This method is particularly useful when dealing with normally distributed data.

A common threshold  $\tau$ =2,3

- If (|z|>2), the data point is often considered a mild outlier.
- If (|z|>3), the data point is often considered a significant outlier.

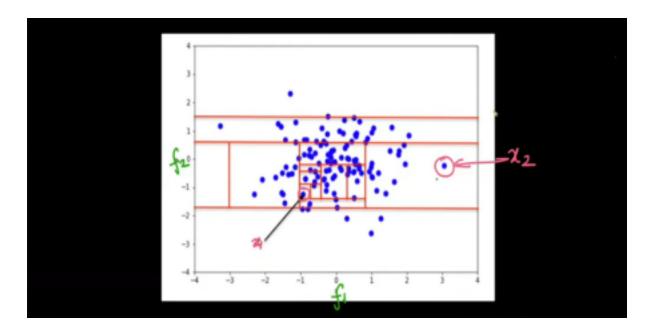
### 3. DBSCAN

It randomly picks a point and checks its neighborhood using eps

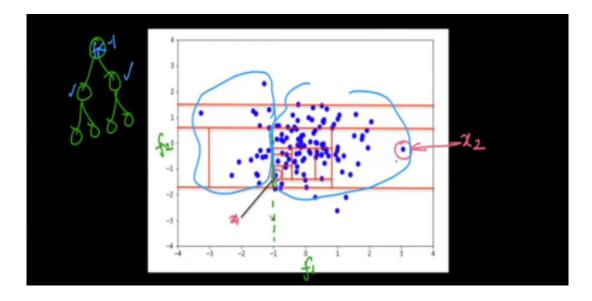
- if num of points ≥ min\_num\_pts → core point
- if num of points < min\_num\_pts, but contains at least one core point → Boarder point
- if num of points < min\_num\_pts, but not a border point → Noise point

# 4. Isolation Forests (iForests)

- Consider a dataset D which contains data points x<sub>1</sub>, x<sub>2</sub>,..., x<sub>n</sub>. Just like Random forests, Isolation Forests build many trees.
- Following are the steps involved in Isolation Forest:
  - Build many trees like random forests
  - o For each tree:
    - Randomly pick a feature
    - Randomly threshold that features
    - Build each tree until the leaf consists of only one datapoint



- In isolation forests, we are building random trees. So if we pick feature f₁ and put a threshold there will be a vertical bar.
- Similarly, if we pick feature f<sub>2</sub> and put a threshold there will be a horizontal bar.
- For example, if we pick feature  $f_1$  and select threshold as  $f_1 < 1$ , then our first root node will be based on this condition



- Based on the diagram above,
  - $\circ$  The node containing  $x_1$  will be at more depth.
  - $\circ$  Observe that the point  $x_1$  is in a dense region, and point  $x_2$  is far away

- $\circ$  That is because, to break point  $x_1$  from all the other points, more and more splits will be required and that will increase the depth of the node containing point  $x_1$ .
- So, to sum it up, the idea behind Isolation Forest is:
  - On average outliers have lower depth in the random trees
  - o On average, inliers have more depth in the random trees

#### **Evaluation of Isolation Forest**

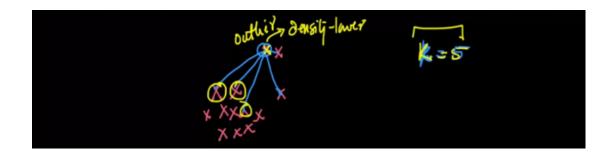
- Imagine, we have to build random trees.
  - $\circ$  For each point  $x_i$  in the dataset, we can get an average depth.
- We use this average depth to convert it into a metric.
- The basic intuition is that the lesser the average depth, the higher the likelihood is there that it is an outlier

## **Disadvantages**

- They are biased towards axis parallel splits.
  - Because of this, the boundary will not be smoothened.
  - Because the model is biased towards the axis, it will classify the point as an inlier and as an outlier

# **Local Outlier Factor (LOF)**

- Core idea: to compare the density of a point with its neighbors' density
- If the density of a point is less than the density of its neighbors, we flag that point as an outlier
- Imagine a bunch of datapoints as shown below



- We compute the density of a point based on average distance.
- If the average distance between a point and its **K** nearest neighbors is large, it is more likely that the point will be an outlier
- Also, the larger the value of **K**, the more confident are the results.

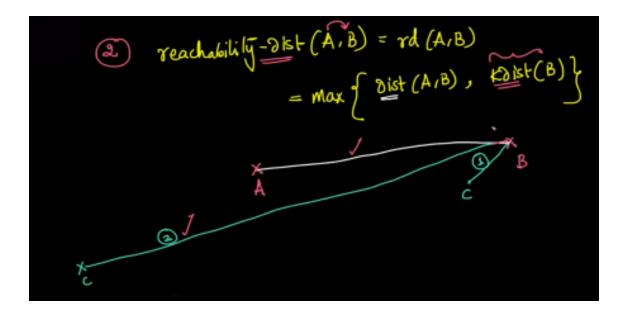
## 1(a) K-distance

- We define the K-distance of point **A** as the distance of point **A** to its **K**<sup>th</sup> nearest neighbor
- In general, the larger the value of k-distance is, the farther away the point is from other data points

1(b) Set: Nk (A): It is a set of k-nearest neighbors of point A.

## 2. Reachability distance

- From point **A** to point **B**, we define reachability distance as
  - a maximum of the distance from point A to point B and the maximum k-distance of point B
- Consider point **B** with some **k** nearest neighbors shown in the diagram below.



- There is a possibility that some neighbors might be close(condition 1) and some neighbors might be very far away(condition 2)
- In this case, there is a neighbor of point B whose k-distance is greater than the
  distance between point A and B, and hence, it is considered as its reachability
  distance.

## 3. Local Reachability Density

- It is often represented as  $Ird_k(A)$ , which tells the local reachability density of point **A**.
- It is defined as the average reachability distance between point A and k neighbors

So, 
$$lrd_k(A) = \frac{\sum_{B \in N_k(A)} rd_k(A,B)\$}{N_k(A)}$$

- The summation in the above equation represents the sum of reachability distances from a point A and a set of neighbors B as  $B \in N_k(A)$
- We define the Local Outlier Factor of the point as follows:

$$LOF_k(A) = \frac{\sum_{B \in N_k(A)} lrd_k(B)}{|N_k(A)| . ldr_k(A)}$$

o Ird<sub>k</sub>(A) is the density of point A

$$\frac{\sum_{B \in N_k(A)} lrd_k(B)}{|N_k(A)|}$$

The expression

- is the average neighborhood density
- So, LOF of point A is nothing but the average neighborhood density(Ird) of point A divided by the density of A

# Interpretation of LOF

- If LOF(A) = 1, then we can say that the point has the same density(Ird) as its k nearest neighbors
- If LOF(A) > 1, then the k neighbors of point A have a higher density than point Α.
  - That does not mean point A is an outlier. It may or may not be.
    But if LOF(A) >>> 1, then the point is an outlier.
- If LOF(A) < 1, then the point has more density than its nearest neighbors.

# **Disadvantages of LOF**

- Finding optimal K
- Finding threshold.
  - If LOF(A) >> 1, what is the threshold??
- Cannot handle high dimensional data efficiently
- High Time Complexity