

# Complex Analysis

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# Chapter 1

## Complex Numbers

### 1.12 Regions in the Complex Plane

**Definition 1.1** (Epsilon neighborhood). An epsilon neighborhood around a point  $z_0$  is the set of all  $z$  such that,

$$|z - z_0| < \varepsilon$$

**Definition 1.2** (Deleted neighborhood). A deleted neighborhood around a point  $z_0$  is the set of all  $z$  such that,

$$0 < |z - z_0| < \varepsilon$$

**Remark.** A deleted neighborhood is essentially an epsilon neighborhood but does not include the point  $z_0$

**Definition 1.3** (Interior point).  $z_0$  is an interior point when there exists a neighborhood of  $z_0$  that contains only points of  $S$

**Definition 1.4** (Exterior point).  $z_0$  is an exterior point when there exists a neighborhood of  $z_0$  that contains no points of  $S$

**Definition 1.5** (Boundary point).  $z_0$  is a boundary point otherwise, i.e. all of the neighborhoods of  $z_0$  contains a point in  $S$  and a point not in  $S$

**Definition 1.6** (Open set).  $S$  is an open set if  $\forall z \in S, \exists \varepsilon$  s.t.  $B_\varepsilon(z) \subset S$

**Remark.** We can also say that an open set does not contain any of its boundary points.

**Definition 1.7** (Closed set). A set is closed if it doesn't contain its boundary points.

**Definition 1.8** (Connected Set). An open set is connected if  $z_1, z_2$  can be joined by a polygonal line, consisting of finite number of line segments, joined end to end.

**Definition 1.9** (domain). A non empty open set that is connected is called a domain

**Definition 1.10** (region). A domain together with some, none, or all of its boundary points is referred to as a region

**Definition 1.11** (accumulation point). An accumulation point or limit point of a set  $S$  is  $z_0$  if, each deleted neighborhood of  $z_0$  contains at least one point of  $S$

**Remark.** A closed set contains all of its accumulation points, but the opposite may not be true.

**Remark.** Every boundary point is not an accumulation point.

**Example.** Consider the set,  $S = 5 \cup (0, 1)$

Here, the boundary points are 5, 0 and 1 because they  $\varepsilon$ -neighborhood defined around these points contains both interior points and exterior points.

However 5 is not an accumulation point because the deleted-neighborhood does not contain any interior points (as it removes 5 ).  $\diamond$

## Chapter 2

# Analytic functions

### 2.1 13. Functions and Mappings

A translation translate a complex number to another location preserving direction and magnitude.

**Example.**  $f(z) = z_0 + z$  ◇

A rotation rotates the complex number changing magnitude or direction.

**Example.**  $f(z) = z_0 z$  This function rotates  $z$  by multiplying it with  $z_0$ . We can see this when representing it in euler notation as follows,

$$z_0 z = r r_0 e^{i(\theta + \theta_0)}.$$

**Example.**  $f(z) = z^2$  ◇

$$z = r e^{i\theta}$$

$$z^2 = r^2 e^{2i\theta}$$

So magnitude is squared and angle is doubled ◇

A reflection will reflect  $z$  along the  $x$  axis.

**Example.**  $f(z) = \bar{z}$  reflects  $z$  along the  $x$  axis. ◇

An analytic function is a differentiable function in the complex space.

$$f(z) = w.$$

$$f(x + iy) = u + iv.$$

$$= u(x, y) + iv(x, y).$$

$$u(z) = iv(z).$$

## 2.2 15. Limits

If a function  $f$  is defined at all points  $z$  in some deleted neighborhood of point  $z_0$ . Then,  $f(z)$  has a limit  $w_0$  as  $z$  approaches  $z_0$ , or

$$\lim_{z \rightarrow z_0} f(z) = w_0.$$

Essentially this means that the point  $w = f(z)$  can be made arbitrary close to  $w_0$  if we choose a point  $z$  close enough to  $z_0$  but distinct from it (deleted neighborhood).

**Definition 2.1 (Limit).** The limit of a function  $f(z)$  as  $z$  goes to  $z_0$  is  $w_0$  if,  $\forall \varepsilon > 0, \exists \delta > 0$ , s.t.

$$|f(z) - w_0| < \varepsilon \text{ whenever, } 0 < |z - z_0| < \delta.$$

**Remark.** Essentially this means that for every  $\varepsilon$ -neighborhood,  $|f(z) - w_0| < \varepsilon$  there is a deleted-neighborhood,  $0 < |z - z_0| < \delta$  of  $z_0$  such that every point  $z$  in it has an image  $w$  in the  $\varepsilon$ -neighborhood

**Remark.** All points in the deleted-neighborhood are to be considered but their images need not fill up the  $\varepsilon$ -neighborhood

**Theorem 2.2.** When a limit of a function  $f(z)$  exists at a point  $z_0$ , it is unique.

**Proof.** Suppose,

$$\lim_{z \rightarrow z_0} f(z) = w_0 \text{ and } \lim_{z \rightarrow z_0} f(z) = w_1.$$

This means that,

$$|f(z) - w_0| < \varepsilon \text{ when } 0 < |z - z_0| < \delta_0.$$

$$|f(z) - w_1| < \varepsilon \text{ when } 0 < |z - z_1| < \delta_1.$$

So,

$$|f(z) - w_0| + |f(z) - w_1| < 2\varepsilon.$$

We know that,

$$w_1 - w_0 = (f(z) - w_0) - (f(z) - w_1) \leq |f(z) - w_0| + |f(z) - w_1|$$

So,

$$w_1 - w_0 < 2\varepsilon, \text{ where } \varepsilon \text{ can be chosen arbitrary small.}$$

Hence,

$$w_1 - w_0 = 0, \text{ or, } w_1 = w_0.$$

□

**Example.** Show that,  $f(z) = \frac{i\bar{z}}{2}$  in the open disk  $|z| < 1$ , then

$$\lim_{z \rightarrow 1} f(z) = \frac{i}{2}$$

$$\left| f(z) - \frac{i}{2} \right| = \left| \frac{i\bar{z}}{2} - \frac{i}{2} \right| = \frac{|z-1|}{2}.$$

Hence, for any  $z$  and  $\varepsilon$ ,

$$\left| f(z) - \frac{i}{2} \right| < \varepsilon \text{ when } 0 < |z-1| < 2\varepsilon.$$

◇

**Example.**  $f(z) = \frac{z}{\bar{z}}$  The limit,

$$\lim_{z \rightarrow 0} f(z).$$

does not exist.

Assume that it exists, that implies that by letting the point  $z = (x, y)$  we can approach the point,  $(0, 0)$  in any manner and we would get the same limit.

Now if we approach the point from the  $x$ -axis where  $z = (x, 0)$  we get,

$$\lim_{x \rightarrow 0} f((x, 0)) = \frac{x + 0i}{x - 0i} = 1.$$

But if we approach it from the  $y$ -axis where,  $z = (0, y)$  we get,

$$\lim_{y \rightarrow 0} f((0, y)) = \frac{0 + iy}{0 - iy} = -1.$$

But we know that the limit should be unique, hence this implies that the limit does not exist. ◇

## 2.3 19. Derivatives

**Theorem 2.3.** If a function  $f(z)$  is continuous and non-zero at a point  $z_0$  then, there exists a neighborhood where,  $f(z) \neq 0$  throughout.

**Proof.** We know that  $f(z)$  is continuous which means that,  $\varepsilon > 0, \exists \delta$  such that,

$$|f(z) - f(z_0)| < \varepsilon, \text{ when } 0 < |z - z_0| < \delta.$$

But if we take,  $\varepsilon = \frac{f(z_0)}{2}$  then we have,

$$|f(z) - f(z_0)| < \frac{|f(z_0)|}{2}.$$

However, if  $f(z) = 0$  for this neighborhood then we have,

$$|f(z_0)| < \frac{|f(z_0)|}{2}.$$

which is a contradiction. □

**Theorem 2.4.**  $f$  is continuous on  $R$  which is closed and bounded,  $\exists M > 0$ , real  $|f(z)| \leq M, \forall z \in R$  equality holds for at least one  $z$ .

**Definition 2.5 (Derivative).**  $f$  is differentiable at  $z_0$  when  $f'(z_0)$  exists where,

$$f'(z_0) = \lim_{z \rightarrow z_0} \frac{f(z) - f(z_0)}{z - z_0}$$

**Remark.** Can also solve,

$$\lim_{z_0 \rightarrow 0} \frac{f(z + z_0) - f(z)}{z_0}$$

**Example.** Find derivative of,  $f(z) = \frac{1}{z}$

$$\begin{aligned} \lim_{z_0 \rightarrow 0} \left( \frac{1}{z + z_0} - \frac{1}{z} \right) \frac{1}{z_0} \\ \lim_{z_0 \rightarrow 0} \frac{z - z - z_0}{z(z + z_0)} \frac{1}{z_0} \\ \lim_{z_0 \rightarrow 0} \frac{-1}{z(z + z_0)} \\ = \frac{-1}{z^2} \end{aligned}$$

◇

**Example.**  $f(z) = \bar{z}$

$$\lim_{z_0 \rightarrow 0} \frac{z + \bar{z}_0 - \bar{z}}{z_0}$$

Go from  $x$  and  $y$  axis.

From  $x$ ,

$$\lim_{x_0 \rightarrow 0} \frac{\bar{z} + x_0 - \bar{z}}{x_0} = 1.$$

Similarly if we go from  $y$  we get  $-1$ , so the derivative doesn't exist.

◇

If we have a function  $f(z) = u(x, y) + iv(x, y)$  then,

$$z_0 = x_0 + iy_0.$$

$$\Delta z = \Delta x + i\Delta y.$$

We have to show the following exist,

$$\lim_{\Delta z \rightarrow 0} \frac{f(z_0 + \Delta z) - f(z_0)}{\Delta z}.$$



$$= \frac{u(x_0 + \Delta x, y_0 + \Delta y) + iv(x_0 + \Delta x, y_0 + \Delta y) - (u(x_0, y_0) + iv(x_0, y_0))}{\Delta x + i\Delta y}.$$

Horizontally,  $\Delta y = 0$ .

So,

$$\begin{aligned} & \frac{u(x_0 + \Delta x, y_0) - u(x_0, y_0)}{\Delta x} + \frac{i(v(x_0 + \Delta x, y_0) - v(x_0, y_0))}{\Delta x} \\ &= u_x + iv_x. \end{aligned}$$

Similary, if we go vertically,  $\Delta x = 0$  and we get,

$$= v_y - iu_y.$$

**Theorem 2.6.** If,  $f(z) = u + iv$ ,  $f'(z)$  exists at,  $z_0 = x_0 + iy_0$ . Then,  $u_x, u_y, v_x, v_y$  exists at  $(x_0, y_0)$  and must satisfy the Cauchy-Reimann equation.

$$f'(z_0) = u_x + iv_x \text{ at } (x_0, y_0).$$

**Theorem 2.7.**  $f(z) = u(x, y) + iv(x, y)$  defined throughout the  $\varepsilon$ -neighborhood of  $z_0 = x_0 + iy_0$ ,

- (a)  $u_x, u_y, v_x, v_y$  exists everywhere in the neighborhood
- (b)  $u_x, u_y, v_x, v_y$  continuous at  $(x_0, y_0)$  and satisfy the Cauchy-Reimann equations

$$u_x = v_y, u_y = -v_x \text{ at } (x_0, y_0)$$

Then  $f'(z_0)$  exists and,

$$f'(z_0) = u_x + iv_x \text{ at } (x_0, y_0).$$

**Proof.** We need to show,

$$\lim_{\Delta z \rightarrow 0} \frac{f(z_0 + \Delta z) - f(z_0)}{\Delta z}.$$

$$= \lim_{\Delta z \rightarrow 0} \frac{u(x_0 + \Delta x, y_0 + \Delta y) + iv(x_0 + \Delta x, y_0 + \Delta y) - (u(x_0, y_0) + iv(x_0, y_0))}{\Delta z}.$$

Using taylor expansion we know,

$$f(x + \Delta x) = f(x) + \Delta x f'(x) + \frac{(\Delta x)^2}{2} f''(x).$$

$$u(x_0 + \Delta x, y_0 + \Delta y) - u(x_0, y_0) =$$

$$= u(x_0, y_0) + \Delta x u_x(x_0, y_0) + \frac{(\Delta x)^2}{2} u_{xx}(x_0, y_0) + \Delta y u_y(x_0, y_0) + \frac{(\Delta y)^2}{2} u_{yy}(x_0, y_0).$$

We can write the limit as,

$$\frac{u_x(x_0, y_0)\Delta x + u_y(x_0, y_0)\Delta y + \varepsilon_1(\Delta x^2) + \varepsilon_2(\Delta y^2)}{\Delta z} +$$

$$i \frac{v_x(x_0, y_0)\Delta x + v_y(x_0, y_0)\Delta y + \varepsilon_3(\Delta x) + \varepsilon_4(\Delta y)}{\Delta z}.$$

We know  $u_x(x_0, y_0) = v_y(x_0, y_0)$  and  $u_y(x_0, y_0) = -v_x(x_0, y_0)$ , so,

$$\frac{u_x(x_0, y_0)\Delta x - v_x(x_0, y_0)\Delta y + \varepsilon_1(\Delta x^2) + \varepsilon_2(\Delta y^2)}{\Delta z} +$$

$$i \frac{v_x(x_0, y_0)\Delta x + u_x(x_0, y_0)\Delta y + \varepsilon_3(\Delta x) + \varepsilon_4(\Delta y)}{\Delta z}.$$

$$= \frac{u_x(x_0, y_0)(\Delta x + i\Delta y) + u_y(x_0, y_0)(\Delta y - i\Delta x) + \varepsilon_4}{\Delta z}.$$

and  $\Delta z = \Delta x + i\Delta y$

$$= \frac{u_x(x_0, y_0)(\Delta x + i\Delta y) + u_y(x_0, y_0)(\Delta y - i\Delta x) + \varepsilon_4}{\Delta x + i\Delta y}.$$

□

**Definition 2.8** (Analytic function). A function  $f$  is analytic in an open set  $S$ , if  $f$  has derivative everywhere in  $S$ . It is analytic at a point  $z_0$  if it is analytic in some neighborhood of  $z_0$

**Remark.** Analytic function has to be on an open set.

**Remark.** For it to be analytic at  $z_0$  derivative should exist in the neighborhood of  $z_0$  (not just the point  $z_0$ )

**Example.**  $f(z) = (|z|)^2 = \sqrt{x^2 + y^2}^2$

$$u = x^2 + y^2, v = 0$$

$$u_x = 2x, u_y = 2y.$$

$$v_x = 0, v_y = 0.$$

So the Cauchy-Reimann equation is only satisfied at  $(0, 0)$

$f'(0) = 0$  and it exists. ◇

**Remark.**  $f(z) = |z|^2$  is not analytic anywhere. So even if the derivative exists at  $z = 0$ . The function is not analytic at  $z = 0$  (or at any point)

Because, (1).  $f'(z)$  exists at  $z = 0$

(2).  $u_x, u_y, v_x, v_y$  exists  $\nRightarrow f'(z)$

(3).  $f(z)$  is continuous  $\nRightarrow f'(z)$

Essentially it only exists for  $z = 0$  and not in the neighborhood around it.

**Definition 2.9** (Entire function). A function  $f$  is analytic at each point in the entire plane.

**Definition 2.10** (Singular point).  $z_0$  is a singular point if  $f$  fails to be analytic at  $z_0$  but is analytic at some point in every neighborhood at  $z_0$

**Example.**  $f(z) = 2 + 3z^2 + z^3$

Is analytic everywhere so it is an entire function ◇

**Example.**  $f(z) = \frac{1}{z}$

Is analytic at all non-zero, but  $z = 0$  is a singular point ◇

**Example.**  $f(z) = |z|^2 = x^2 + y^2$

Is not analytic, no singular points either. ◇

## 2.4 Harmonic Function

**Definition 2.11** (Harmonic function). A real valued function of  $H(x, y)$  is said to be harmonic if in a given domain of the  $x, y$  plane, it has a continuous partial derivative of the first and second order ( $H_x, H_y, H_{xx}, H_{yy}, H_{xy}$ ) and satisfies,

$$H_{xx}(x, y) + H_{yy}(x, y) = 0 \text{ Laplace equation.}$$

**Theorem 2.12.** If  $f = u(x, y) + i v(x, y)$  is analytic in a domain  $D$ , then  $u, v$  are harmonic in  $D$

**Theorem 2.13.** If  $f'(z) = 0$  everywhere in  $D$  then  $f(z)$  is a constant in  $D$ .

**Proof.** Consider  $f(z) = u(x, y) + i v(x, y)$  given that

$$f'(z) = u_x + i v_x = 0$$

Using Cauchy-Reimann equation we have,  $u_y, v_y = 0$ . So all of the first order derivatives are equal to 0 in  $D$ .

$U(x, y)$  is constant along any line  $L$ , extending from  $p$  to  $p'$ . Let the vector from  $p$  to  $p'$  be  $u$ . So we have,

$$\frac{du}{ds} = (\text{grad } u)u$$

$$\text{grad } u = u_x i + u_y j = 0$$

So  $u$  is a constant (a) on  $L$ . Similarly for  $v = b$

$$f(z) = a + bi$$

□

**Lemma 2.14.** Suppose,

(a).  $f(z)$  is analytic throughout  $D$

(b).  $f(z) = 0$  at each point of the domain or line segment containing  $D$

Then  $f(z) \equiv 0$  in  $D$

## Chapter 3

# Elementary Functions

### 3.1 Exponential Function

The exponential function is  $e^z$ . But we can write this as

$$e^z = e^{x+iy} = e^x e^{iy} = e^x (\cos(y) + i \sin(y))$$

We can also write,

$$e^z = \rho e^{i\phi} \text{ where } \rho = |e^x| \text{ and } \phi = y$$

For a function,  $e^{z_1} e^{z_2}$  we can write,

$$\begin{aligned} e^{z_1} e^{z_2} &= e^{x_1+iy_1} e^{x_2+iy_2} \\ &= e^{x_1+x_2} e^{i(y_1+y_2)} \\ &= e^{z_1+z_2}. \end{aligned}$$

The derivative of  $e^z$  is an entire function

$$\frac{d}{dz} e^z = e^z \text{ which is an entire function.}$$

$$e^{z+2} = e^z + e^2 = e^z$$

### 3.2 Log Function

The log function is  $f(z) = \log(z) = w = u + iv$ . We know

$$e^w = z = e^{u+iv} = e^u e^{iv}.$$

We see that  $r = e^u$  and  $\theta = v + 2n\pi$

$$r = e^u \Rightarrow \ln(r) = u$$

Similarly,

$$\theta = v + 2n\pi.$$

So we have,

$$f(z) = \log(z) = \ln |z| + i \arg(z).$$

and the principal direction is,

$$f(z) = \log(z) = \ln |z| + i\theta, \quad -\pi < \theta < \pi.$$

Some properties are,

$$(1). e^{\log z} = z, (z \neq 0)$$

$$(2). |e^z| = e^x$$

$$(3). \log(e^z) = \ln |e^z| + i \arg(e^z)$$

$$= \ln |e^x| + i(y + 2n\pi), n = 0, \pm 1, \pm 2.$$

$$= \ln e^x + iy + i2n\pi.$$

$$= z + 2n\pi.$$

## Branches

The principal branch is

$$\log z = \ln r + i\theta \text{ where } r > 0, -\pi < \theta < \pi.$$

A branch cut is a portion of a line or curve that is introduced in order to define a branch  $F$  of a multiple-valued function  $f$ .

Points on the branch cut for  $F$  are singular points of  $F$  and any point that is common to all branches of  $f$  are called branch points.

**Example.**

$$\frac{d}{dz} \log z = \frac{1}{z}, \text{ where } |z| > 0$$

The branches can be  $\alpha < \arg z < \alpha + 2\pi$

◇

**Property.**  $\log z_1 z_2 = \log z_1 + \log z_2$

**Proof.**

$$\begin{aligned} \log z_1 z_2 &= \ln(r_1 r_2) + i(\theta_1 + \theta_2 + 2n\pi) \\ &= \log z_1 z_2 = \ln(r_1) + \ln(r_2) + i(\theta_1 + \theta_2 + 2n\pi) \\ &= \log z_1 z_2 = \ln(r_1) + i(\theta_1 + 2n\pi) + \ln(r_2) + i(\theta_2 + 2n\pi) \\ &= \log z_1 z_2 = \ln(r_1) + i(\theta_1 + 2n\pi) + \ln(r_2) + i(\theta_2 + 2n\pi) \\ &= \log z_1 z_2 = \log z_1 + \log z_2 \end{aligned}$$

□

**Property.**  $\log |z_1 z_2| = \log |z_1| + \log |z_2|$

**Property.**  $\log\left(\frac{z_1}{z_2}\right) = \log(z_1) - \log(z_2)$

**Property.**  $z^n = e^{n \log(z)}$

### 3.3 Power Function

We have a complex number  $c$  and we have  $f(z) = z^c$ . By definition we have  $z^c = e^{c \log z}$

The derivative is  $\frac{d}{dz}f(z) = \frac{d}{dz}(z^c)$

$$\frac{d}{dz}e^{c \log z} = e^{c \log z} \frac{d}{dz}c \log z = e^{c \log z} \frac{c}{z}$$

But we can write  $\frac{e^{c \log z} c}{e^{\log z}} = ce^{(c-1) \log z} = cz^{c-1}$ . The principal value of  $z^c = e^{c \operatorname{Log} z}$

If the function is  $f(z) = c^z$  then we have

$$\frac{d}{dz}c^z = \frac{d}{dz}e^{z \log c} = e^{z \log c} \frac{d}{dz}z \log c = e^{z \log c} \log c = c^z \log c$$

### 3.4 Trigonometric Function

We know that  $e^{i\theta} = \cos \theta + i \sin \theta$  and  $e^{-i\theta} = \cos \theta - i \sin \theta$ . So we can write,

$$\cos \theta = \frac{e^{i\theta} + e^{-i\theta}}{2}$$

and,

$$\sin \theta = \frac{e^{i\theta} - e^{-i\theta}}{2i}$$

We have  $\frac{d}{dz} \sin z = \cos z$  and  $\frac{d}{dz} \cos z = -\sin z$

**Property.**  $\sin(-z) = -\sin(z)$  and  $\cos(-z) = \cos(z)$

**Property.**  $\sin(z_1 + z_2) = \sin z_1 \cos z_2 + \cos z_1 \sin z_2$

**Property.**  $\sin(2z) = 2 \sin(z) \cos(z)$

**Property.**  $\sin(z + \frac{\pi}{2}) = \cos(z)$

Consider the hyperbolic sin and cos functions,

$$\sinh z = \frac{e^z - e^{-z}}{2}, \cosh z = \frac{e^z + e^{-z}}{2}$$

We can write  $\sin z = \sin(x + iy)$ . Now expanding this we get,

$$\sin(x) \cos(iy) + \cos(x) \sin(iy) = \sin(x) \cosh(y) + i \cos x \sinh(y)$$

And we have,

$$\begin{aligned} |\sin z|^2 &= \sin^2 x + \sinh^2 y \\ |\cos z|^2 &= \cos^2 x + \cosh^2 y \end{aligned}$$

### 3.5 Inverse Trigonometric Functions

The function is  $w = f(z) = \sin^{-1} z$ . So we have

$$\sin(w) = z = \frac{e^{iw} - e^{-iw}}{2}$$

We know  $2iz = (e^{iw} - e^{-iw}) \times e^{iw}$ ,

$$2ize^{iw} = e^{2iw} - e^0$$

$$e^{iw^2} - 2ize^{iw} - 1 = 0$$

Solving this we get,

$$e^{iw} = iz \pm (1 - z^2)^{\frac{1}{2}}$$

## Chapter 4

# Integrals

Consider  $f(z) = f(x + iy) = u(x, y) + iv(x, y)$ . We can write this as,

$$w(t) = u(t) + iv(t)$$

$$w'(t) = u'(t) + iv'(t)$$

**Example.**  $\frac{d}{dt}(w(t))^2 = \frac{d}{dt}(u + iv)^2$

$$\begin{aligned} &= \frac{d}{dt}(u^2 - v^2 + 2uvi) \\ &= 2uu' - 2vv' + i(2u'v + 2uv') \\ &= 2(u + iv)(u' + iv') \\ &= 2w(t)w'(t) \end{aligned}$$

◇

### 4.1 Definite Integrals

The integral of  $w(t)$  with respect to  $t$  is,

$$\int_a^b w(t)dt = \int_a^b u(t)dt + i \int_a^b v(t)dt$$

**Exercise.** Find  $c$  such that,

$$\int_a^b w(t)dt = w(c)(b - a) \text{ where } w(t) = e^{it}, a = 0, b = 2\pi$$

**Solution.** We have,

$$\int_0^{2\pi} e^{it} = \int_0^{2\pi} (\cos(t) + i \sin(t)) = [\sin(t) - i \cos(t)]_0^{2\pi} = 0$$

Generally for arbitrary  $a$  and  $b$  we can show that, ...

**Remark.** In this case  $t$  is moving from 0 to  $2\pi$ . But because we are in the complex plane it represents a loop.



## 4.2 Contour

**Definition 4.1.** We have  $z(t) = x(t) + iy(t)$  is a contour if,  
 (1)  $C$  is simple arc or Jordan arc, it does not cross itself.

$$z(t_1) \neq z(t_2), t_1 \neq t_2$$

(2)  $z(a) = z(b)$ ;  $C$  simple closed curve.  
 It is positively oriented if the direction is anticlockwise

**Example.**  $x = \begin{cases} x + ix, 0 \leq x \leq 1 \\ x + i, 1 \leq x \leq 2 \end{cases}$  ◇

**Example.**  $z = re^{i\theta}, 0 \leq \theta \leq 2\pi$  ◇

**Example.**  $z = re^{i3\theta}, 0 \leq \theta \leq 2\pi$  ◇

Not a simple arc ◇

**Example.**  $\int_C w(z)dz = \int_{C_1} f[z(x)]z'(x)dx + \int_{C_2} f[z(x)]z'(x)dx$

Here  $C$  is the contour from example (1). ◇

We can define the differential arc to be  $z'(t) = x'(t) + y'(t)i$  which is continuous on  $a \leq t \leq b$  then,  $C : z(t)$  is a differential arc and

$$\int_a^b |z'(t)|dt = \int_a^b \sqrt{|x'(t)|^2 + |y'(t)|^2} \text{ length.}$$

$$L = \int_a^b |z'(t)|dt$$

$$t = \phi(\tau), dt = \phi'(\tau)d\tau$$

$$L = \int_a^b |z'(t)|dt = \int_\alpha^\beta |z'(\phi(\tau))|\phi'(\tau)d\tau$$

$$T = \frac{z'(t)}{|z'(t)|} \text{ tangent vector}$$

Contour: piecewise smooth arc.

## 4.3 Contour Integral

Consider the integral,

$$\int_C f(z)dz \text{ or } \int_{z_1}^{z_2} f(z)dz$$

We can parametrize in terms of  $t$  as,

$$\int_C f(z)dz = \int_a^b f(z(t))z'(t)dt$$

$\int_{-C} f(z)dz$  represents going backwards from the curve.

An integral along a given curve  $C$  can be written as a sum of integrals of curves within it,

$$\int_C f(z)dz = \int_{C_1} f(z)dz + \int_{C_2} f(z)dz$$

**Example.**  $\int_{C_1} \frac{dz}{z}$  where  $C_1$  is the upper semicircle and  $\int_{C_2} \frac{dz}{z}$  is the lower semicircle.

◇

**Solution.** For  $C_1$

$$z = re^{i\theta}, r = 1, 0 \leq \theta \leq \pi$$

And for  $C_2$  we have,

$$z = re^{i\theta}, r = 1, \pi \leq \theta \leq 2\pi$$

$$dz = ire^{i\theta} d\theta$$

For  $C_1$  we have,

$$\begin{aligned} \int_{C_1} \frac{dz}{z} &= \int_0^\pi \frac{1}{e^{i\theta}} ie^{i\theta} d\theta \\ &= [i\theta]_0^\pi = i\pi \end{aligned}$$

Similarly for  $C_2$ ,

$$\begin{aligned} \int_{C_2} \frac{dz}{z} &= - \int_\pi^{2\pi} \frac{1}{e^{i\theta}} ie^{i\theta} d\theta \\ &= -[i\theta]_\pi^{2\pi} = [i\pi - i2\pi] = -i\pi \end{aligned}$$

We see that it is not path independent.

**Theorem 4.2.** Suppose a function  $f(z)$  is cont. in  $D$  the following statements are equivalent,

1.  $f(z)$  has an antiderivative  $F(z)$  throughout  $D$ .
2. Any contours entirely in  $D$  all have the same value,

$$\int_{z_1}^{z_2} f(z) dz = F(z)]_{z_1}^{z_2} = F(z_2) - F(z_1)$$

3.  $\int_C f(z) = 0$ ,  $C$  closed contours entirely in  $D$

## 4.4 Branch Cuts

**Example.**  $z = 3e^{i\theta}, (0 \leq \theta \leq \pi)$

◇

**Lemma 4.3.** If  $w(t)$  is piecewise cont. then,

$$\left| \int_a^b w(t) dt \right| \leq \int_a^b |w(t)| dt$$

**Proof.** Let,

$$\int_a^b w(t) dt = re^{i\theta}$$

$r = \int_a^b e^{-i\theta} w(t) dt$ . Both sides of this equations are real.

$$r = \int_a^b \operatorname{Re}[e^{i\theta} w(t)] dt$$

But,

$$\operatorname{Re}[e^{i\theta} w(t)] \leq |e^{-i\theta} w(t)| = |e^{-i\theta}| |w(t)| \leq |w(t)|$$

So,

$$r \leq \int_a^b |w(t)| dt$$

Or,

$$\left| \int_a^b w(t) dt \right| \leq \int_a^b |w(t)| dt$$

□

**Theorem 4.4.**  $C$  has a length  $L$  and  $f(z)$  is piecewise cont. on  $C$  and let  $|f(z)| \leq M$  then,

$$\left| \int_C f(z) dz \right| \leq ML$$

**Proof.**  $\int_C f(z) dz = \int_a^b f(z(t)) z'(t) dt$ . So we have,

$$\left| \int_C f(z) dz \right| \leq \int_a^b |f(z(t)) z'(t)| dt \leq \int_a^b |M z'(t)| dt = ML$$

□

**Theorem 4.5.**  $f(z)$  is cont. over  $D$  then,

(a).  $f(z)$  has antiderivative  $F(z)$  throughout  $D$

(b).  $\int_{z_1}^{z_2} f(z) dz = F(z_2) - F(z_1)$

The antiderivative is independent to the path.

(c).  $\int_C f(z)$  where  $c$  is a closed contour entirely in  $D$

**Proof.** 1. (a)  $\Rightarrow$  (b). We have,  $c : z = z(t), z_1 = z(a), z_2 = z(b)$

$$\frac{d}{dt}[F[z(t)]] = F'[z(t)] z'(t) = f(z) z'(t)$$

So taking,

$$\begin{aligned} \int_C f(z) dz &= \int_a^b f[z(t)] z'(t) dt = F[z(t)] \\ &= F[z(t)]_a^b = F(z_2) - F(z_1) \end{aligned}$$

2. (b)  $\Rightarrow$  (c)

$$\int_{C_1} f(z)dz = F(z_2) - F(z_1)$$

$$\int_{C_2} f(z)dz = F(z_2) - F(z_1)$$

So,

$$\int_{C_1} f(z)dz = F(z_2) - F(z_1) = \int_{C_2} f(z)dz = F(z_2) - F(z_1)$$

$$\int_{C_1} f(z)dz = F(z_2) - F(z_1) - \int_{C_2} f(z)dz = F(z_2) - F(z_1) = 0$$

$C = C_1 - C_2$  : a closed contour in  $D$

$$\int_C f(z)dz = 0$$

3. (c)  $\Rightarrow$  (a)

We define

$$F(z) = \int_{z_1}^{z_2} f(s)ds$$

$$\lim_{\Delta z \rightarrow 0} \frac{F(z + \Delta z) - F(z)}{\Delta z} = \lim_{\Delta z \rightarrow 0} \frac{1}{\Delta z} \left[ \int_{z_0}^{z+\Delta z} f(s)ds - \int_{z_0}^z f(z)ds \right]$$

$$= \lim_{\Delta z \rightarrow 0} \frac{1}{\Delta z} \int_z^{z+\Delta z} f(s)ds$$

**Remark.**

$$\int_z^{z+\Delta z} ds = s \Big|_z^{z+\Delta z} = \Delta z$$

**Remark.**

$$f(z) = \frac{1}{\Delta z} \int_z^{z+\Delta z} f(z)ds$$

$$\frac{F(z + \Delta z) - F(z)}{\Delta z} - f(z) = \frac{1}{\Delta z} \int_z^{z+\Delta z} [f(s) - f(z)]ds$$

By cont. of  $f(z)$ ,  $\forall \varepsilon, \exists \delta$ ,

$$|f(s) - f(z)| < \varepsilon \text{ whenever } |s - z| < \delta$$

□