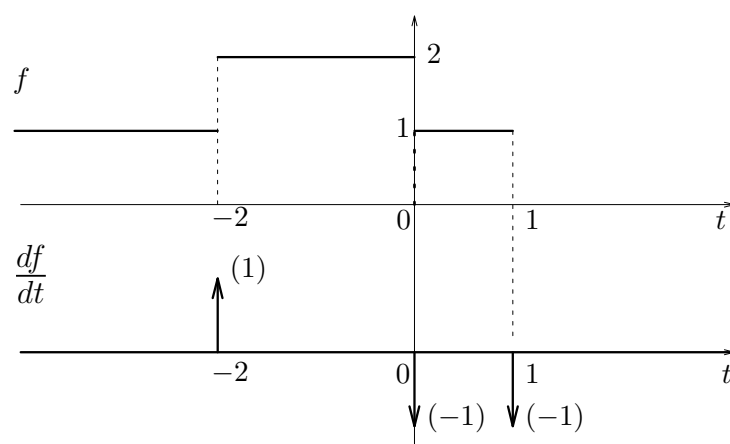


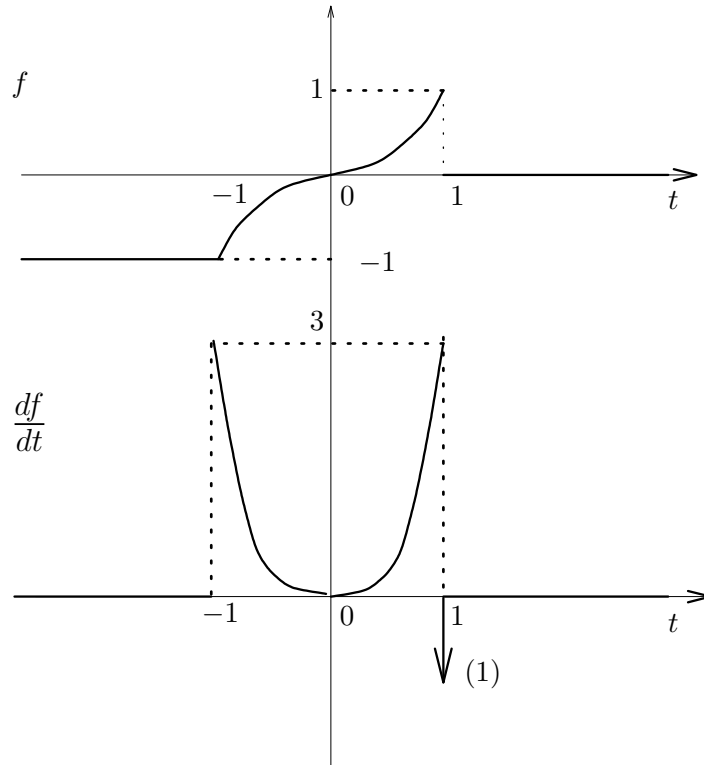
1. (a)

$$\begin{aligned}
 f(t) &= 1 - u(t) + u(t+2) - u(t-1) \\
 \frac{df(t)}{dt} &= -\delta(t) + \delta(t+2) - \delta(t-1)
 \end{aligned}$$



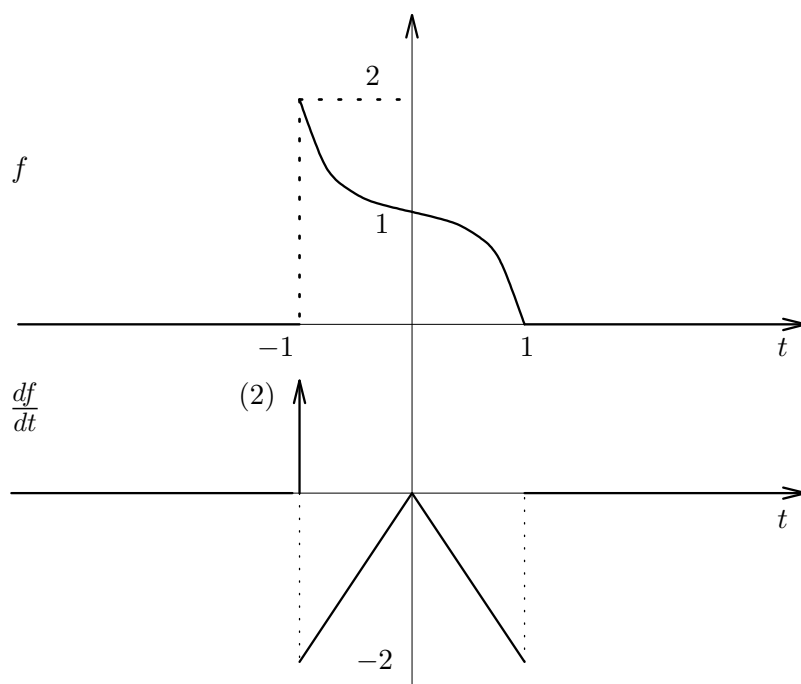
(b)

$$\begin{aligned}
 f(t) &= -u(-t-1) + t^3[u(t+1) - u(t-1)] \\
 \frac{df(t)}{dt} &= \delta(-t-1) + 3t^2[u(t+1) - u(t-1)] + t^3[\delta(t+1) - \delta(t-1)] \\
 &= \delta(t+1) + 3t^2[u(t+1) - u(t-1)] - \delta(t+1) - \delta(t-1) \\
 &= 3t^2[u(t+1) - u(t-1)] - \delta(t-1)
 \end{aligned}$$



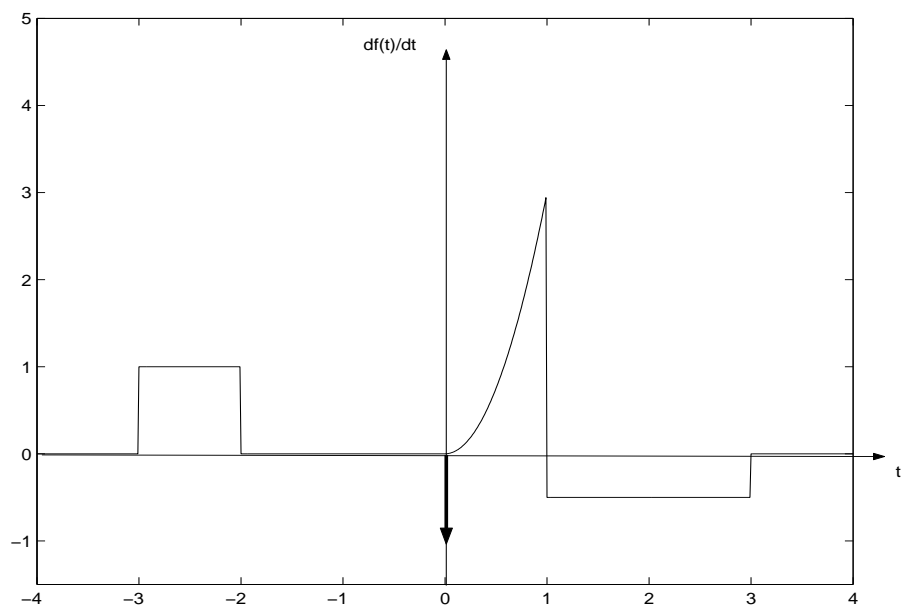
(c)

$$\begin{aligned}
 f(t) &= (t^2 + 1)[u(t + 1) - u(t)] + (1 - t^2)[u(t) - u(t - 1)] \\
 \frac{df(t)}{dt} &= (t^2 + 1)[\delta(t + 1) - \delta(t)] + 2t[u(t + 1) - u(t)] \\
 &\quad + (1 - t^2)[\delta(t) - \delta(t - 1)] - 2t[u(t) - u(t - 1)] \\
 &= 2\delta(t + 1) - \delta(t) + 2t[u(t + 1) - u(t)] + \delta(t) - 2t[u(t) - u(t - 1)] \\
 &= 2\delta(t + 1) + 2t[u(t + 1) - u(t)] - 2t[u(t) - u(t - 1)]
 \end{aligned}$$



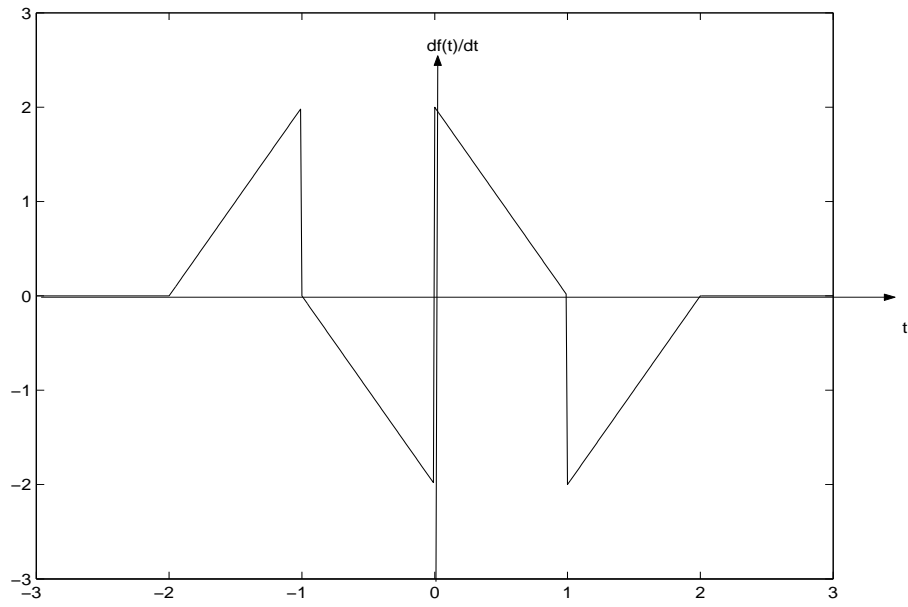
2. (a)

$$\begin{aligned}
 f(t) &= (t+3)[u(t+3) - u(t-2)] + [u(t+2) - u(t)] + t^3[u(t) - u(t-1)] \\
 &\quad - \frac{1}{2}(t-3)[u(t-1) - u(t-3)] \\
 \frac{df(t)}{dt} &= [u(t+3) - u(t-2)] + 3t^2[u(t) - u(t-1)] \\
 &\quad - \frac{1}{2}[u(t-1) - u(t-3)] - \delta(t)
 \end{aligned}$$



(b)

$$\begin{aligned}
 f(t) &= (t+2)^2[u(t+2) - u(t+1)] + (1 - (t+1)^2)[u(t+1) - u(t)] \\
 &\quad + (1 - (t-1)^2)[u(t) - u(t-1)] + (t-2)^2[u(t-1) - u(t-2)] \\
 \frac{df(t)}{dt} &= 2(t+2)[u(t+2) - u(t+1)] - 2(t+1)[u(t+1) - u(t)] \\
 &\quad - 2(t-1)[u(t) - u(t-1)] + 2(t-2)[u(t-1) - u(t-2)]
 \end{aligned}$$



3. (a)  $\int_{-\infty}^{\infty} e^{\cos(\pi t)} \delta(t-1) dt = e^{\cos(\pi)} = e^{-1}$

(b)  $\int_{-\infty}^0 \frac{\sin(t)}{t^4+1} \delta(t-1) dt = 0$  because  $1 \notin (-\infty, 0)$ .

(c)  $\int_{t^-}^{\infty} \sigma^5 \delta(t-\sigma) dt = t^5$

4.  $y(t) = \int_{-\infty}^t \sin(t-\sigma) x(\sigma+1) d\sigma$

(a)

$$\begin{aligned} h(t, \tau) &= \int_{-\infty}^t \sin(t-\sigma) \delta(\sigma+1-\tau) d\sigma \\ &= \sin(t-\tau+1) u(t-\tau+1) \end{aligned}$$

(b) The system is time-invariant because  $h(t, \tau)$  is only a function of  $(t-\tau)$ .  
The system is not causal because  $h(t, \tau) \neq 0$  for  $t < \tau$  (e.g., at  $t-\tau = -\frac{1}{2}$ ).

5. (a)

$$\begin{aligned} \frac{dy(t)}{dt} &= u(t-1)x(t) \\ \int_0^t \frac{dy(t)}{dt} &= \int_0^t u(1-\sigma)x(\sigma) d\sigma \\ y(t) - 0 &= \int_0^t u(1-\sigma)x(\sigma) d\sigma \\ h(t, \tau) &= \int_0^t u(1-\sigma) \delta(\sigma-\tau) d\sigma \\ &= u(1-\tau) u(t-\tau) \end{aligned}$$

(b) The system is time-variant because  $h(t, \tau)$  is **not** only a function of  $(t-\tau)$ .  
The system is causal because  $h(t, \tau) = 0$  for  $t < \tau$ .