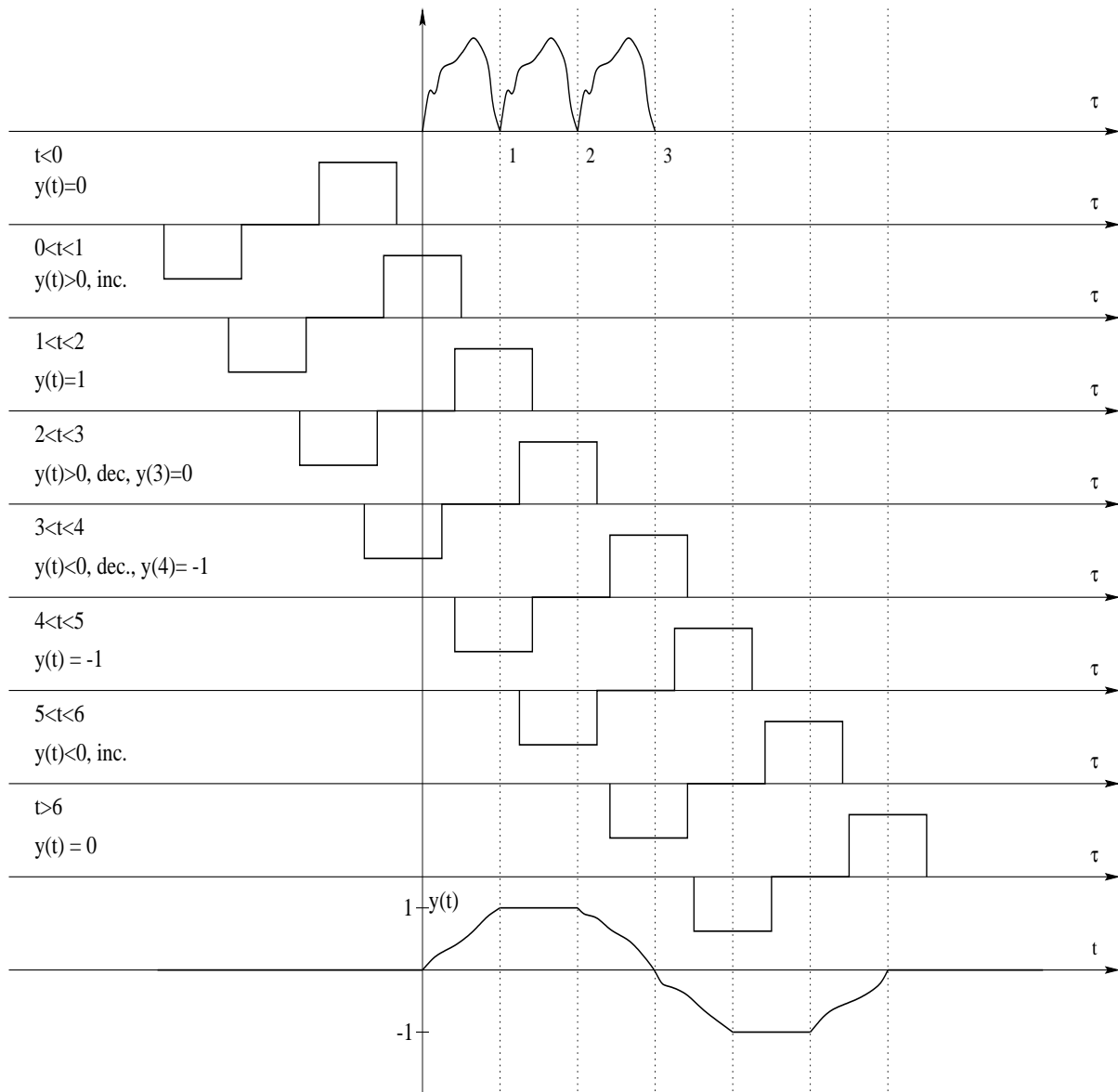


Professor Paganini

1. The step-by-step graphs corresponding to the convolution can be seen below:



2. (a)

$$\begin{aligned}
(f * g)(t) &= \int_{-\infty}^{\infty} f(\tau)g(t - \tau)d\tau \\
&= \int_{-\infty}^{\infty} e^{-\tau}u(\tau)[u(t - \tau) - u(t - \tau - 1)]d\tau \\
&= \begin{cases} 0 & \text{if } t \leq 0 \\ \int_0^t e^{-\tau}d\tau = [-e^{-\tau}]_0^t = 1 - e^{-t} & \text{if } 0 < t \leq 1 \\ \int_{t-1}^t e^{-\tau}d\tau = [-e^{-\tau}]_{t-1}^t = e^{-t}(e - 1) & \text{if } 1 < t \end{cases} \\
&= [u(t) - u(t - 1)](1 - e^{-t}) + u(t - 1)e^{-t}(e - 1)
\end{aligned}$$

(b)

$$\begin{aligned}
(f * h)(t) &= \int_{-\infty}^{\infty} e^{-(t-\tau)}u(t - \tau)u(\tau + 1)e^{-\tau}d\tau \\
&= \begin{cases} 0 & \text{if } t < -1 \\ \int_{-1}^t e^{-(t-\tau)}e^{-\tau}d\tau = e^{-t}(t + 1) & \text{otherwise} \end{cases} \\
&= e^{-t}(t + 1)u(t + 1)
\end{aligned}$$

3. We know that for an LTI system, if applying input  $x(t)$  generates output  $y(t)$ , then applying input  $\frac{dx}{dt}$  generates output  $\frac{dy}{dt}$ . Using this fact for the system  $\mathcal{S}_1$ , we find the input-output pair  $\frac{dx}{dt} = \delta(t)$  and  $\frac{dy}{dt} = u(t) + t\delta(t) = u(t)$ . So  $h_1(t) = u(t)$  (this system is an integrator).

Now we repeat the same argument for the second system  $\mathcal{S}_2$ , with input  $y(t)$  and output  $z(t)$ . Taking derivatives of the given  $y$  and  $z$ , we obtain the new input-output pair  $y_1(t) = \frac{dy}{dt} = u(t)$ ,  $z_1(t) = \frac{dz}{dt} = u(t) - u(t - 1)$ . Since we want to find an impulse response, we take another derivative and see that  $\frac{dy_1}{dt} = \delta(t)$  will generate the output  $\frac{dz_1}{dt} = \delta(t) - \delta(t - 1)$ . So  $h_2(t) = \delta(t) - \delta(t - 1)$ . The following schematic summarizes our reasoning.

$$\begin{array}{ccc}
y(t) = tu(t) & \rightsquigarrow & z(t) = t[u(t) - u(t - 1)] + u(t - 1) \\
\downarrow & & \downarrow \\
\frac{dy}{dt} = u(t) = y_1(t) & \rightsquigarrow & z_1(t) = \frac{dz}{dt} = u(t) - u(t - 1) \\
\downarrow & & \downarrow \\
\frac{dy_1}{dt} = \delta(t) & \rightsquigarrow & \frac{dz_1}{dt} = \delta(t) - \delta(t - 1)
\end{array}$$

4. (a)

$$\begin{aligned}
 F(s) &= \int_{0-}^{\infty} e^{-st} u(t-1) e^t dt \\
 &= \int_1^{\infty} e^{t(1-s)} dt \\
 &= \frac{1}{1-s} \left[ e^{t(1-s)} \right]_1^{\infty} \\
 &= \frac{1}{1-s} [0 - e^{1-s}] \quad (\text{if } \operatorname{Re}[s] > 1) \\
 &= \frac{e^{1-s}}{s-1}
 \end{aligned}$$

with  $\text{DOC} = \{s | \operatorname{Re}[s] > 1\}$ .

(b)

$$\begin{aligned}
 F(s) &= \int_{0-}^{\infty} e^{-st} (u(t-a) - u(t-b)) dt \\
 &= \int_a^b e^{-st} dt \\
 &= \frac{1}{-s} \left[ e^{-st} \right]_a^b \\
 &= \frac{e^{-as} - e^{-bs}}{s}
 \end{aligned}$$

with  $\text{DOC} = \text{the whole complex plane}$ .

**Note:** Superficially, it seems there is a pole at  $s = 0$  which would limit the  $\text{DOC}$ . However, note that the numerator is also zero at that point.

(c)

$$\begin{aligned}
 F(s) &= \int_{0-}^{\infty} e^{-st} e^{t^3} u(t) dt \\
 &= \int_{0-}^{\infty} e^{t(t^2-s)} dt \\
 &= \infty \quad (\text{no matter what } s \text{ is})
 \end{aligned}$$

So the Laplace transform of  $u(t)e^{t^3}$  is not defined for any  $s$ .