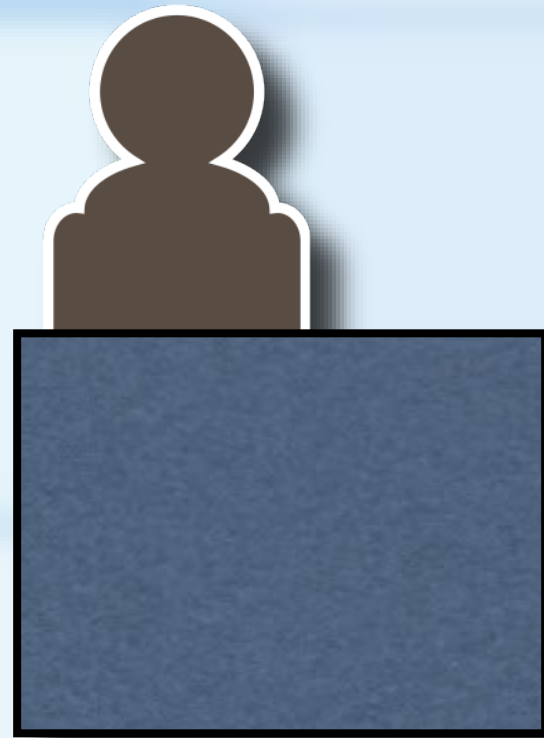
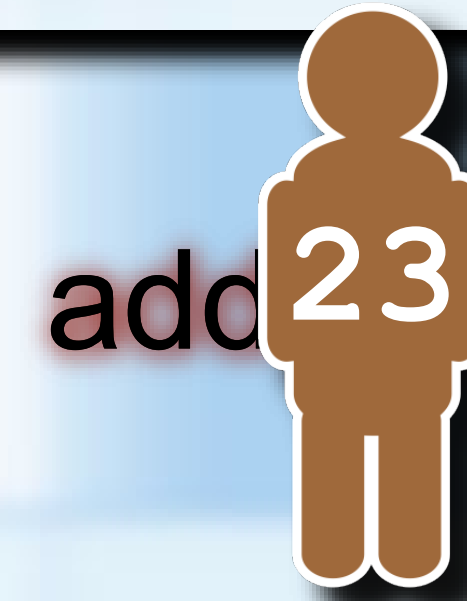


# THE ADT PRIORITY QUEUE

# THE ADT PRIORITYQUEUE

- **Removing an item always removes the highest priority item**
  - How priority is determined is implementation dependent
- **Highest priority item is at front of queue**
  - Order of other items is not important and depends on how the priority queue is implemented



dequeue()



front



# THE ADT PRIORITYQUEUE

```
template<class ItemType>
class PriorityQueueInterface
{
public:
    /** Adds a new entry to this queue. */
    virtual bool add(const ItemType& someItem) = 0;

    /** Removes high priority item from this queue. */
    virtual bool dequeue() = 0;

    /** Returns high priority item from this queue. */
    virtual ItemType peek() const = 0;

    /** Sees whether this queue is empty. */
    virtual bool isEmpty() const = 0;
}; // end PriorityQueueInterface
```

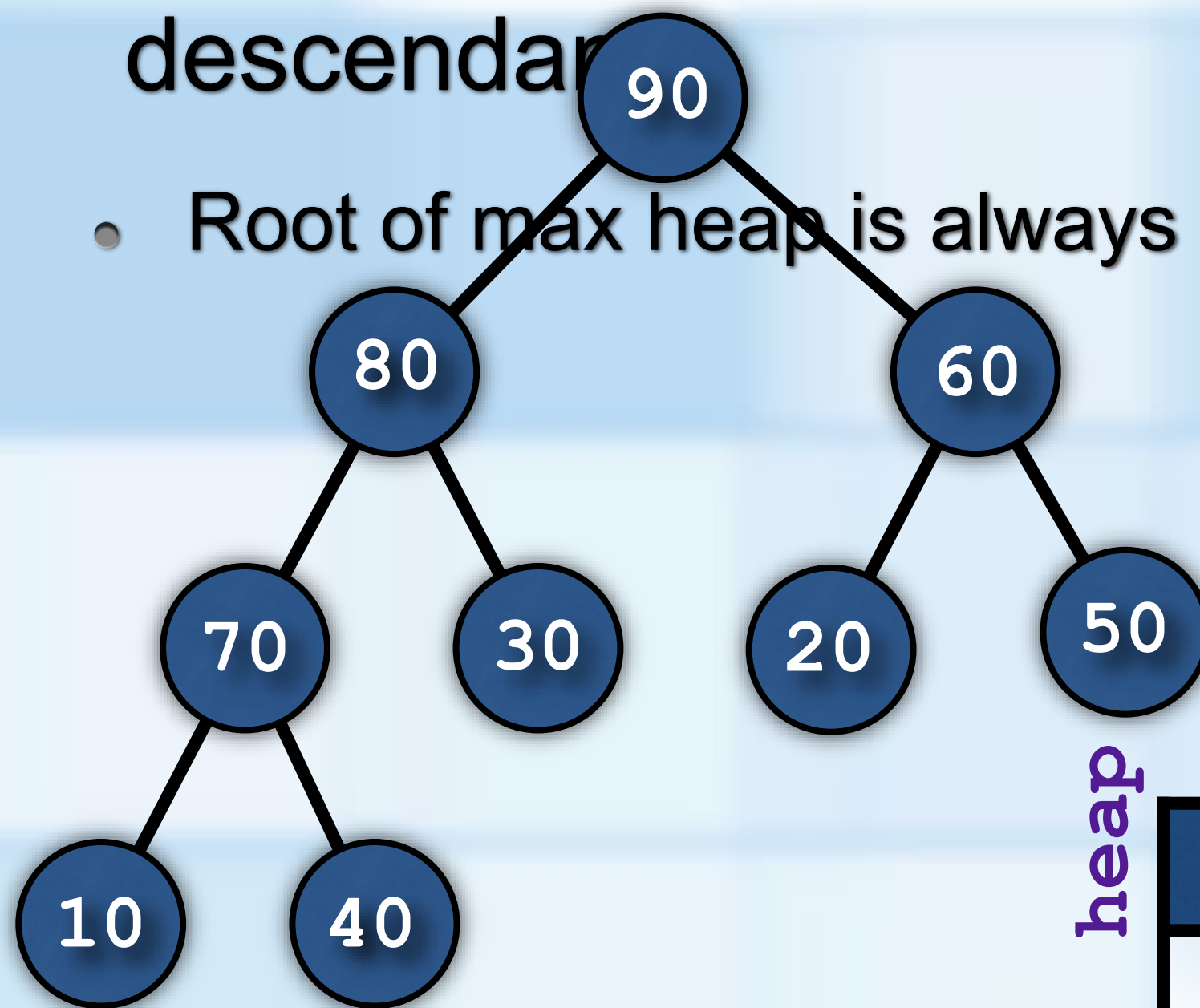
# THE ADT HEAP

# HEAPS

- A **complete** binary tree whose nodes contain objects that can be compared

- Each node contains an object that is larger than the objects in its descendants

- Root of max heap is always the largest entry



heap

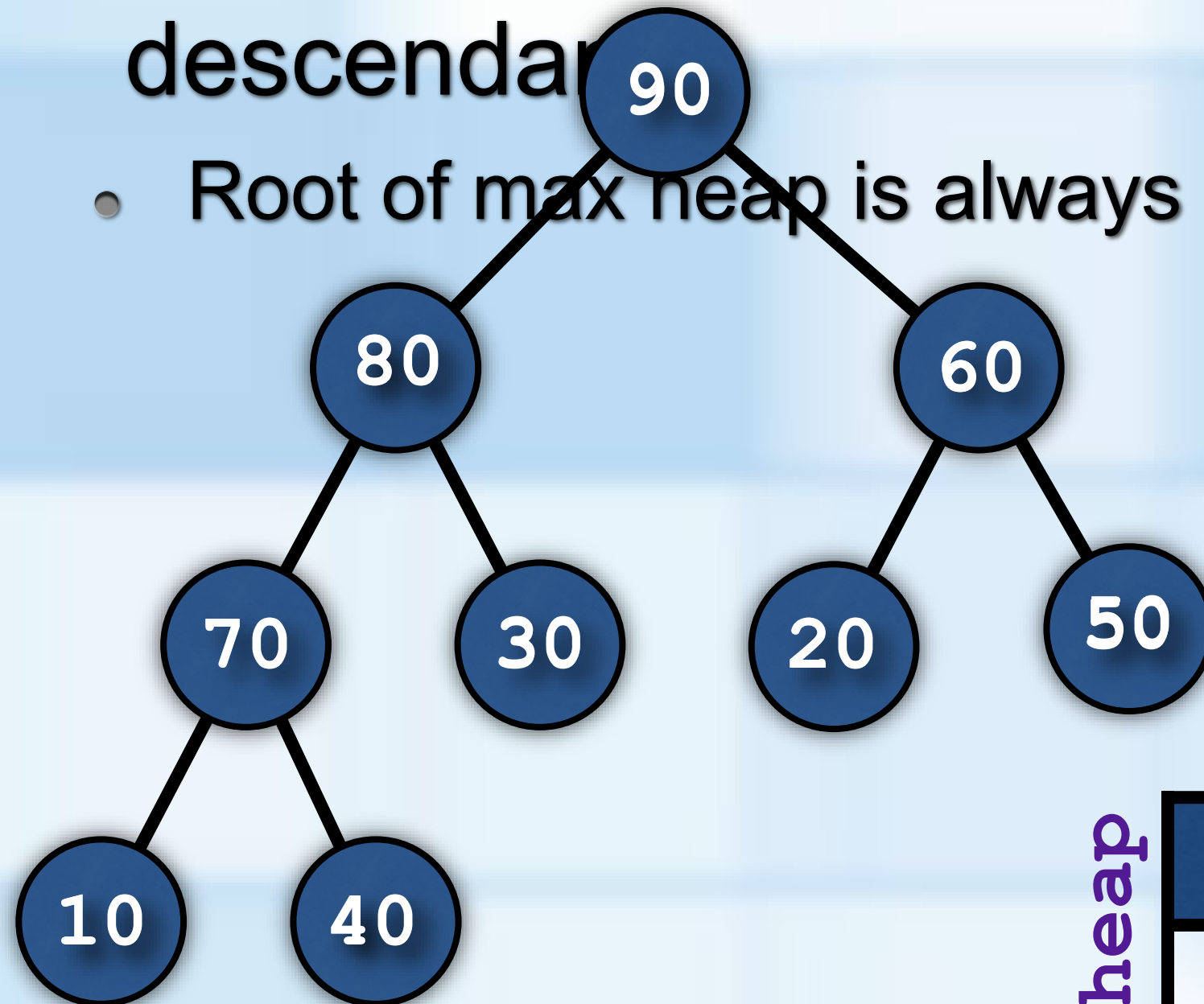
```
template<class ItemType>
class HeapInterface
{
public:
    /** Sees whether this heap is empty. */
    virtual bool isEmpty() const = 0;
    /** Gets the number of nodes in this heap. */
    virtual int getNumberOfNodes() const = 0;
    /** Gets the height of this heap. */
    virtual int getHeight() const = 0;
    /** Gets data in root (top) of this heap. */
    virtual ItemType peekTop() const = 0;
    /** Adds a new node containing to this heap. */
    virtual bool add(const ItemType& someItem) = 0;
    /** Removes the root node from this heap. */
    virtual bool remove() = 0;
    /** Removes all nodes from this heap. */
    virtual void clear() = 0;
    /** Destroys object & frees memory */
    virtual ~HeapInterface() { }
}; // end HeapInterface
```

0	1	2	3	4	5	6	7	8	9	10

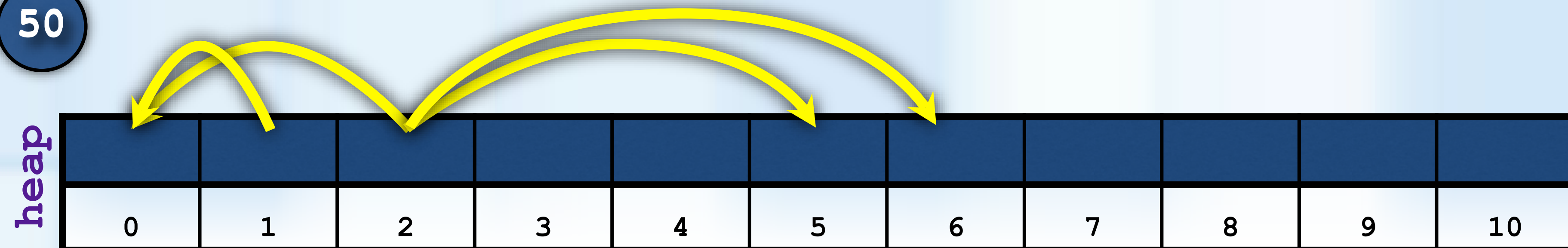


# HEAPS

- A **complete** binary tree whose nodes contain objects that can be compared
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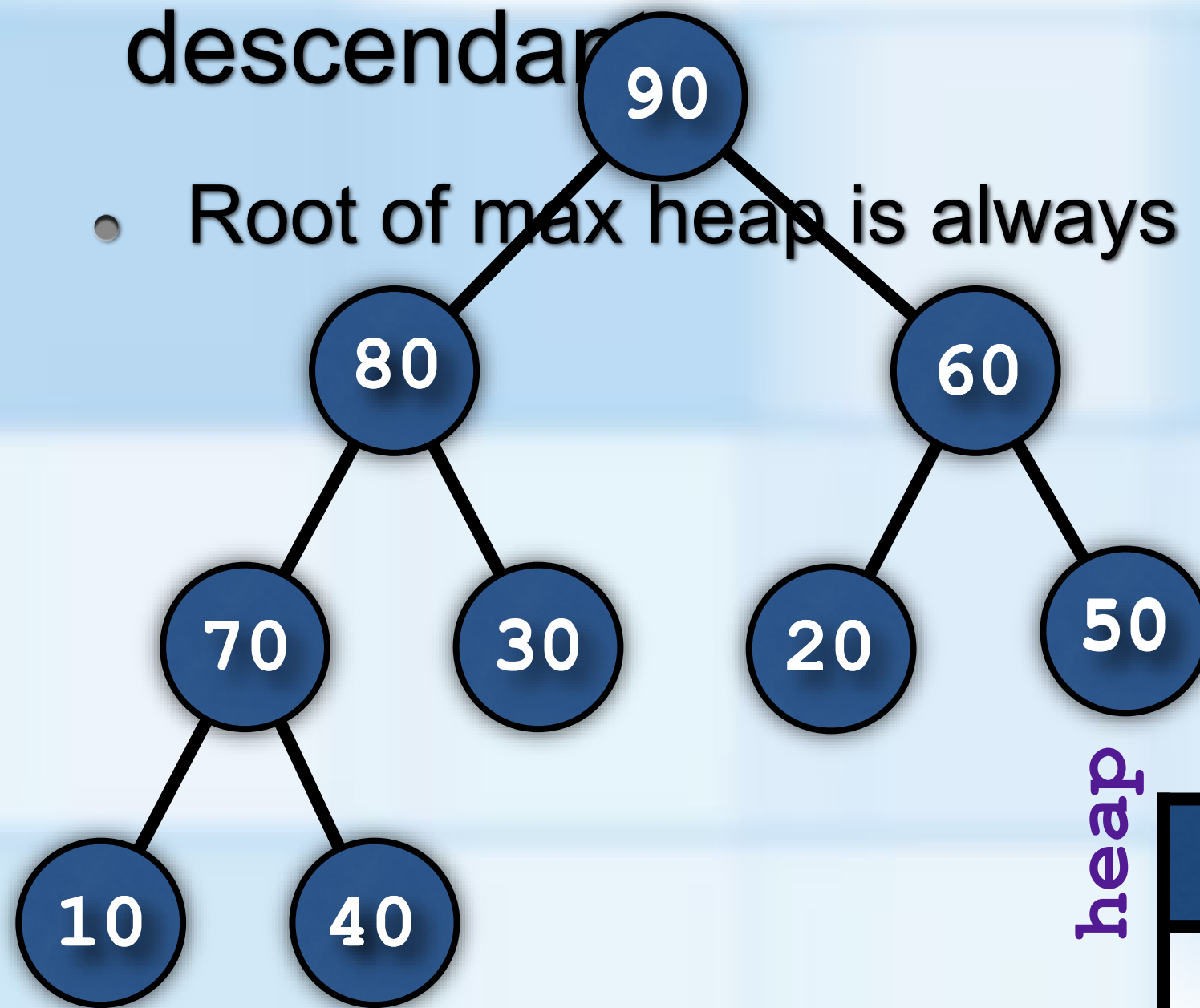


- Using an array to represent a Heap
  - Root is stored in element [0]
  - Index of left child is  $2 * i + 1$
  - Index of right child is  $2 * (i + 1)$
  - Parent is at index  $(i - 1) / 2$
  - Array represents the level order traversal of the heap (a complete tree)

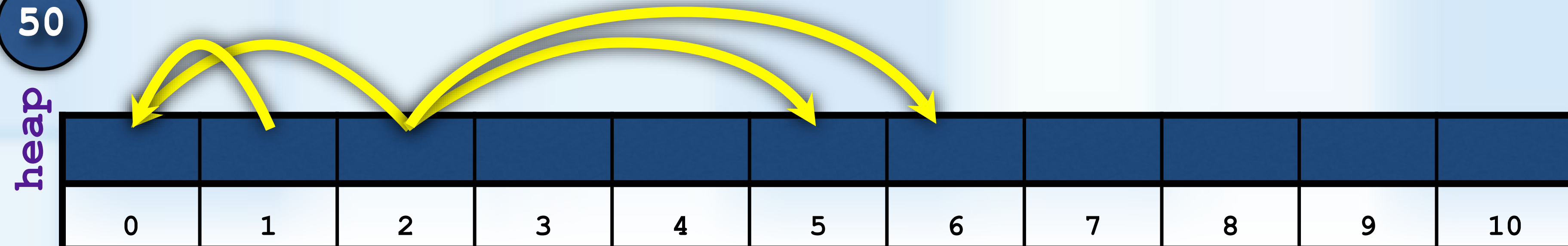


# HEAPS

- A **complete** binary tree whose nodes contain objects that can be compared
- Each node contains an object that is larger than the objects in its descendants
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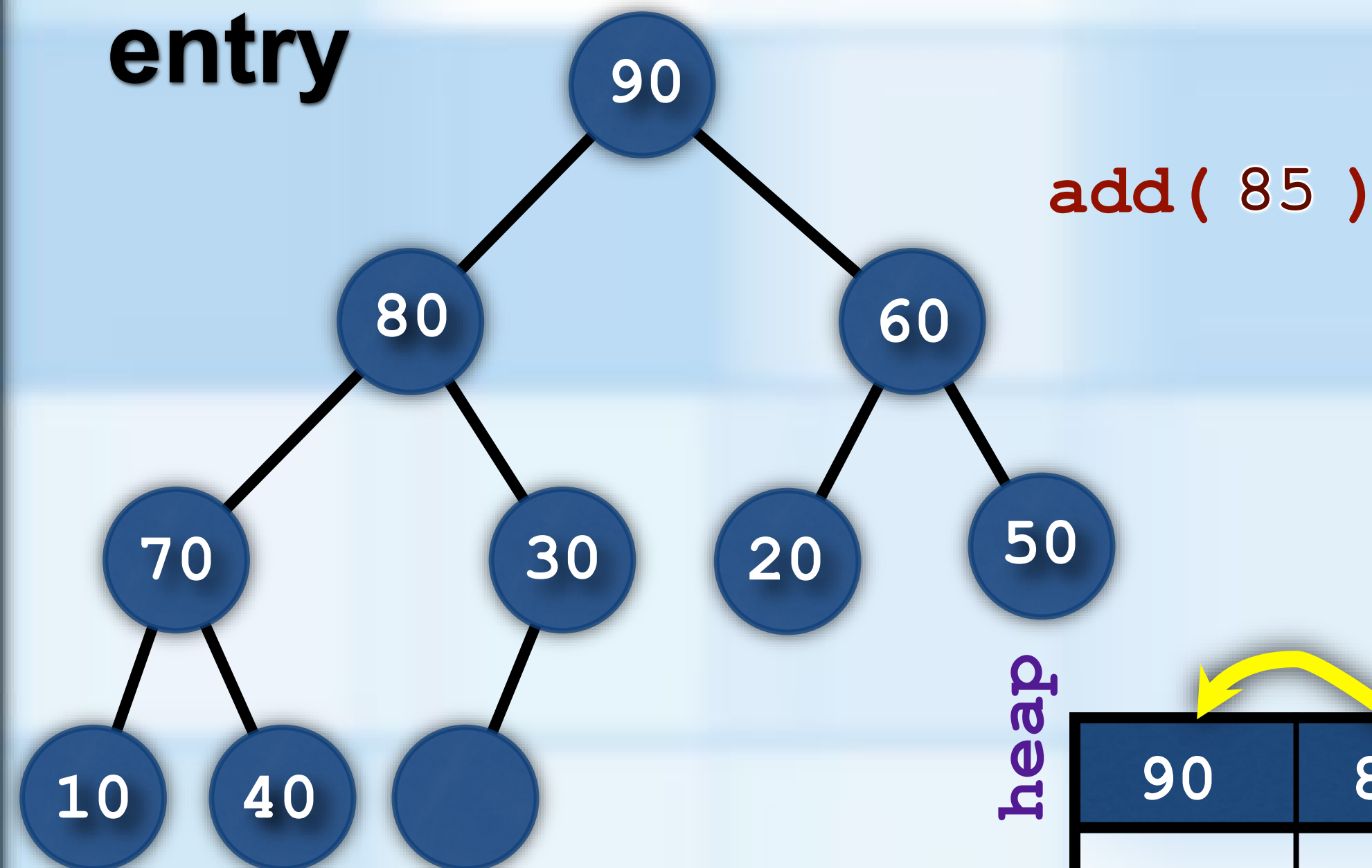
```
template<class ItemType>
class ArrayMaxHeap : public HeapInterface<ItemType>
{
private:
    // Helps with readability
    static const int ROOT_INDEX = 0;
    // Small capacity to test for a full heap
    static const int DEFAULT_CAPACITY = 21;
    // Array of heap items
    ItemType* items;
    // Current count of heap items
    int itemCount;
```





# ADDING TO A HEAP

- Add a node at next location to keep a complete tree
- Compare entry to parent
  - Swap with parent if entry is larger
- Stop when parent is larger than entry



heap

90	80	60	70	30	20	50	10	40	85	
0	1	2	3	4	5	6	7	8	9	10

```
template<class ItemType>
bool ArrayMaxHeap<ItemType>::add(const ItemType& someItem)
{
    bool isSuccessful = false;
    if (itemCount < DEFAULT_CAPACITY)
    {
        items[itemCount] = someItem;

        bool inPlace = false;
        int someItemIndex = itemCount;
        while ((someItemIndex > 0) && !inPlace)
        {
            int parentIndex = (someItemIndex - 1) / 2;
            if (items[someItemIndex] < items[parentIndex])
            {
                inPlace = true;
            }
            else
            {
                std::swap(items[someItemIndex], items[parentIndex]);
                someItemIndex = parentIndex;
            } // end if
        } // end while

        itemCount++;
        isSuccessful = true;
    } // end if

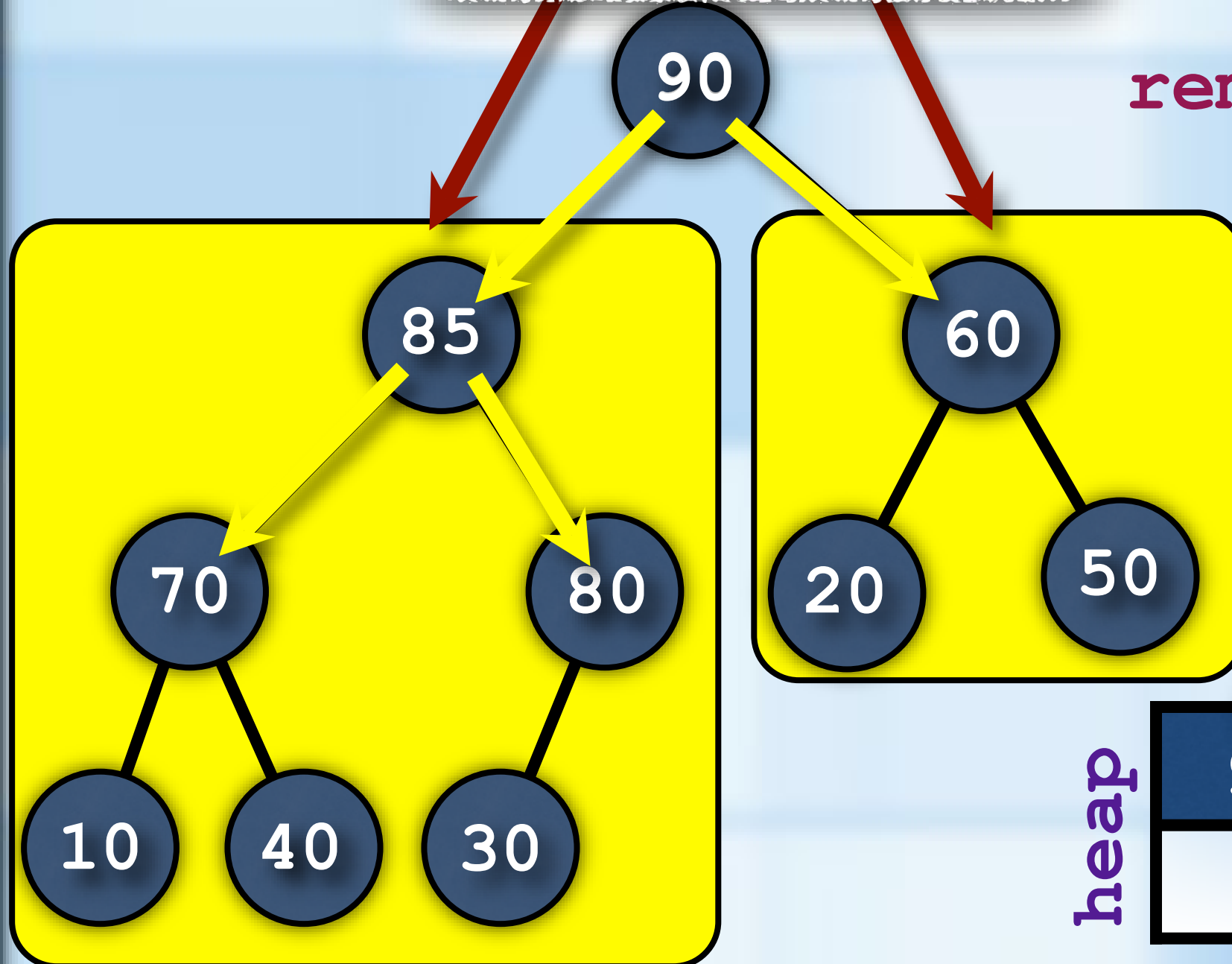
    return isSuccessful;
} // end add
```



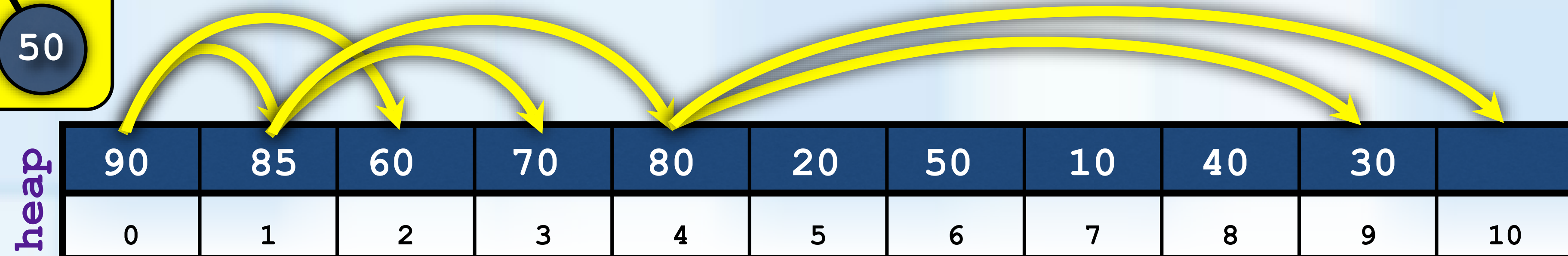
# REMOVING FROM A HEAP

Two Disjoint  
**semiheap**  
only root is out  
of place

**removeMax()**



- Remove entry at root
- Replace with entry in last node
- Trickle down value to correct position (**reheap** or **rebuildHeap**)
  - If at least one child has a larger entry
    - Swap with larger child
  - Stop when
    - entry is larger than both children **or**
    - entry is in a leaf



# CREATING A HEAP

- If beginning with an empty heap
  - Repeatedly add entries using `add()`
  - $O(n \log n)$
- If given an an array of randomly ordered entries
  - Repeatedly use `reheap()`
    - beginning with element  $[n/2]$  and
    - working back to root (element  $[0]$ )
  - $O(n)$