Deliverable 3

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1	Namespace Index	1
	1.1 Namespace List	1
2	Hierarchical Index	3
	2.1 Class Hierarchy	3
3	Class Index	5
	3.1 Class List	5
4	File Index	7
	4.1 File List	7
5	Namespace Documentation	9
	5.1 boost Namespace Reference	9
	5.2 boost::test_tools Namespace Reference	9
	5.3 boost::test_tools::tt_detail Namespace Reference	9
	5.4 GPS Namespace Reference	9
	5.4.1 Typedef Documentation	10
	5.4.1.1 degrees	10
	5.4.1.2 metres	10
	5.4.1.3 radians	10
	5.4.1.4 seconds	11
	5.4.1.5 speed	11
	5.4.2 Function Documentation	11
	5.4.2.1 ddmTodd()	11
	5.4.2.2 degToRad()	11
	5.4.2.3 normaliseDeg()	11
	5.4.2.4 radToDeg()	11
	5.4.2.5 sinSqr()	11
	5.4.3 Variable Documentation	12
	5.4.3.1 antiMeridianLongitude	12
	5.4.3.2 fullRotation	12
	5.4.3.3 halfRotation	12
	5.4.3.4 pi	12
	5.4.3.5 poleLatitude	12
	5.5 GPS::Earth Namespace Reference	12
	5.5.1 Function Documentation	13
	5.5.1.1 latitudeSubtendedBy()	13
	5.5.1.2 longitudeSubtendedBy()	13
	5.5.2 Variable Documentation	13
	5.5.2.1 CityCampus	13
	5.5.2.2 CliftonCampus	13
	5.5.2.3 EquatorialAntiMeridian	14
	5.5.2.4 equatorialCircumference	14
	5.5.2.7 equatorial of cultification	14

5.5.2.5 EquatorialMeridian	
5.5.2.6 meanRadius	
5.5.2.7 NorthPole	
5.5.2.8 polarCircumference	
5.5.2.9 Pontianak	
5.6 GPS::LogFiles Namespace Reference	
5.6.1 Variable Documentation	
5.6.1.1 GPXRoutesDir	
5.6.1.2 GPXTracksDir	
5.6.1.3 logsDir	
5.6.1.4 NMEALogsDir	
5.7 NMEA Namespace Reference	
5.7.1 Typedef Documentation	
5.7.1.1 Route	
5.7.1.2 SentenceData	
5.7.2 Function Documentation	
5.7.2.1 extractSentenceData()	
5.7.2.2 hasValidChecksum()	
5.7.2.3 isWellFormedSentence()	
5.7.2.4 positionFromSentenceData()	
5.7.2.5 routeFromLog()	
0 Oliver Breeze and 18 or	
6 Class Documentation	17
6.1 GPS::Position Class Reference	
6.1.1 Constructor & Destructor Documentation	
6.1.1.1 Position() [1/3]	
6.1.1.2 Position() [2/3]	
6.1.1.3 Position() [3/3]	
6.1.2 Member Function Documentation	
6.1.2.1 distanceBetween()	
6.1.2.2 elevation()	
6.1.2.3 latitude()	
6.1.2.4 longitude()	
6.1.2.5 toString()	
6.2 boost::test_tools::tt_detail::print_log_value< std::vector< std:	
6.2.1 Member Function Documentation	
6.2.1.1 operator()()	
6.3 GPS::Route Class Reference	
6.3.1 Constructor & Destructor Documentation	
6.3.1.1 Route() [1/2]	
6.3.1.2 Route() [2/2]	
6.3.2 Member Function Documentation	

6.3.2.1 areSameLocation()	. 21
6.3.2.2 containsCycles()	. 21
6.3.2.3 findNameOf()	. 21
6.3.2.4 findPosition()	. 21
6.3.2.5 maxElevation()	. 21
6.3.2.6 maxGradient()	. 21
6.3.2.7 maxLatitude()	. 22
6.3.2.8 maxLongitude()	. 22
6.3.2.9 minElevation()	. 22
6.3.2.10 minGradient()	. 22
6.3.2.11 minLatitude()	. 22
6.3.2.12 minLongitude()	. 22
6.3.2.13 name()	. 22
6.3.2.14 netHeightGain()	. 22
6.3.2.15 netLength()	. 23
6.3.2.16 numPositions()	. 23
6.3.2.17 operator[]()	. 23
6.3.2.18 setGranularity()	. 23
6.3.2.19 steepestGradient()	. 23
<b>6.3.2.20 timesVisited()</b> [1/2]	. 23
<b>6.3.2.21 timesVisited()</b> [2/2]	. 23
6.3.2.22 totalHeightGain()	. 24
6.3.2.23 totalLength()	. 24
6.3.3 Member Data Documentation	. 24
6.3.3.1 granularity	. 24
6.3.3.2 positionNames	. 24
6.3.3.3 positions	. 24
6.3.3.4 routeLength	. 24
6.3.3.5 routeName	. 24
6.4 GPS::Track Class Reference	. 25
6.4.1 Constructor & Destructor Documentation	. 25
6.4.1.1 Track()	. 25
6.4.2 Member Function Documentation	. 25
6.4.2.1 averageSpeed()	. 26
6.4.2.2 longestRest()	. 26
6.4.2.3 maxRateOfAscent()	. 26
6.4.2.4 maxRateOfDescent()	. 26
6.4.2.5 maxSpeed()	. 26
6.4.2.6 restingTime()	. 26
6.4.2.7 setGranularity()	. 26
6.4.2.8 totalTime()	. 27
6.4.2.9 travellingTime()	. 27

6.4.3 Member Data Documentation	 . 27
6.4.3.1 arrived	 . 27
6.4.3.2 departed	 . 27
7 File Documentation	29
7.1 earth.cpp File Reference	 . 29
7.2 earth.h File Reference	 . 29
7.3 geometry.cpp File Reference	 . 30
7.4 geometry.h File Reference	 . 30
7.5 gpx-tests.cpp File Reference	 . 30
7.5.1 Macro Definition Documentation	 . 31
7.5.1.1 BOOST_TEST_DYN_LINK	 . 31
7.5.1.2 BOOST_TEST_MODULE	 . 31
7.6 logs.cpp File Reference	 . 31
7.7 logs.h File Reference	 . 31
7.8 nmea-tests.cpp File Reference	 . 32
7.8.1 Macro Definition Documentation	 . 34
7.8.1.1 BOOST_TEST_DYN_LINK	 . 34
7.8.1.2 BOOST_TEST_MODULE	 . 34
7.8.2 Function Documentation	 . 34
7.8.2.1 BOOST_AUTO_TEST_CASE() [1/61]	 . 34
7.8.2.2 BOOST_AUTO_TEST_CASE() [2/61]	 . 34
7.8.2.3 BOOST_AUTO_TEST_CASE() [3/61]	 . 35
7.8.2.4 BOOST_AUTO_TEST_CASE() [4/61]	 . 35
7.8.2.5 BOOST_AUTO_TEST_CASE() [5/61]	 . 35
7.8.2.6 BOOST_AUTO_TEST_CASE() [6/61]	 . 35
7.8.2.7 BOOST_AUTO_TEST_CASE() [7/61]	 . 35
7.8.2.8 BOOST_AUTO_TEST_CASE() [8/61]	 . 35
7.8.2.9 BOOST_AUTO_TEST_CASE() [9/61]	 . 35
7.8.2.10 BOOST_AUTO_TEST_CASE() [10/61]	 . 36
7.8.2.11 BOOST_AUTO_TEST_CASE() [11/61]	 . 36
7.8.2.12 BOOST_AUTO_TEST_CASE() [12/61]	 . 36
7.8.2.13 BOOST_AUTO_TEST_CASE() [13/61]	 . 36
7.8.2.14 BOOST_AUTO_TEST_CASE() [14/61]	
7.8.2.15 BOOST_AUTO_TEST_CASE() [15/61]	
7.8.2.16 BOOST_AUTO_TEST_CASE() [16/61]	
7.8.2.17 BOOST_AUTO_TEST_CASE() [17/61]	
7.8.2.18 BOOST_AUTO_TEST_CASE() [18/61]	
7.8.2.19 BOOST_AUTO_TEST_CASE() [19/61]	
7.8.2.20 BOOST_AUTO_TEST_CASE() [20/61]	
7.8.2.21 BOOST_AUTO_TEST_CASE() [21/61]	
7.8.2.22 BOOST_AUTO_TEST_CASE() [22/61]	
· · · · · · · · · · · · · · · · ·	

7.8.2.23 BOOST_AUTO_TEST_CASE() [23/61]	 37
7.8.2.24 BOOST_AUTO_TEST_CASE() [24/61]	 38
7.8.2.25 BOOST_AUTO_TEST_CASE() [25/61]	 38
7.8.2.26 BOOST_AUTO_TEST_CASE() [26/61]	 38
7.8.2.27 BOOST_AUTO_TEST_CASE() [27/61]	 38
7.8.2.28 BOOST_AUTO_TEST_CASE() [28/61]	 38
7.8.2.29 BOOST_AUTO_TEST_CASE() [29/61]	 38
7.8.2.30 BOOST_AUTO_TEST_CASE() [30/61]	 38
7.8.2.31 BOOST_AUTO_TEST_CASE() [31/61]	 39
7.8.2.32 BOOST_AUTO_TEST_CASE() [32/61]	 39
7.8.2.33 BOOST_AUTO_TEST_CASE() [33/61]	 39
7.8.2.34 BOOST_AUTO_TEST_CASE() [34/61]	 39
7.8.2.35 BOOST_AUTO_TEST_CASE() [35/61]	 39
7.8.2.36 BOOST_AUTO_TEST_CASE() [36/61]	 39
7.8.2.37 BOOST_AUTO_TEST_CASE() [37/61]	 39
7.8.2.38 BOOST_AUTO_TEST_CASE() [38/61]	 40
7.8.2.39 BOOST_AUTO_TEST_CASE() [39/61]	 40
7.8.2.40 BOOST_AUTO_TEST_CASE() [40/61]	 40
7.8.2.41 BOOST_AUTO_TEST_CASE() [41/61]	 40
7.8.2.42 BOOST_AUTO_TEST_CASE() [42/61]	 40
7.8.2.43 BOOST_AUTO_TEST_CASE() [43/61]	 40
7.8.2.44 BOOST_AUTO_TEST_CASE() [44/61]	 40
7.8.2.45 BOOST_AUTO_TEST_CASE() [45/61]	 41
7.8.2.46 BOOST_AUTO_TEST_CASE() [46/61]	 41
7.8.2.47 BOOST_AUTO_TEST_CASE() [47/61]	 41
7.8.2.48 BOOST_AUTO_TEST_CASE() [48/61]	 41
7.8.2.49 BOOST_AUTO_TEST_CASE() [49/61]	 41
7.8.2.50 BOOST_AUTO_TEST_CASE() [50/61]	 41
7.8.2.51 BOOST_AUTO_TEST_CASE() [51/61]	 41
7.8.2.52 BOOST_AUTO_TEST_CASE() [52/61]	 42
<b>7.8.2.53 BOOST_AUTO_TEST_CASE()</b> [53/61]	 42
7.8.2.54 BOOST_AUTO_TEST_CASE() [54/61]	 42
<b>7.8.2.55 BOOST_AUTO_TEST_CASE()</b> [55/61]	 42
<b>7.8.2.56 BOOST_AUTO_TEST_CASE()</b> [56/61]	 42
<b>7.8.2.57 BOOST_AUTO_TEST_CASE()</b> [57/61]	 42
<b>7.8.2.58 BOOST_AUTO_TEST_CASE()</b> [58/61]	 42
<b>7.8.2.59 BOOST_AUTO_TEST_CASE()</b> [59/61]	 43
7.8.2.60 BOOST_AUTO_TEST_CASE() [60/61]	 43
7.8.2.61 BOOST_AUTO_TEST_CASE() [61/61]	 43
7.8.3 Variable Documentation	 43
7.8.3.1 epsilon	 43
7 8 3 2 allPos	43

7.8.3.3 percentageAccuracy	43
7.8.3.4 rmcPos	43
7.8.3.5 validGLLSentence	44
7.8.3.6 validMSSSentence	44
7.8.3.7 validRMCSentence	44
7.9 parseNMEA.cpp File Reference	44
7.10 parseNMEA.h File Reference	44
7.11 position.cpp File Reference	45
7.12 position.h File Reference	45
7.13 route.cpp File Reference	46
7.14 route.h File Reference	46
7.15 timesVisited(string).cpp File Reference	46
7.15.1 Function Documentation	47
7.15.1.1 BOOST_AUTO_TEST_CASE() [1/9]	47
7.15.1.2 BOOST_AUTO_TEST_CASE() [2/9]	47
<b>7.15.1.3 BOOST_AUTO_TEST_CASE()</b> [3/9]	48
7.15.1.4 BOOST_AUTO_TEST_CASE() [4/9]	48
<b>7.15.1.5 BOOST_AUTO_TEST_CASE()</b> [5/9]	48
<b>7.15.1.6 BOOST_AUTO_TEST_CASE()</b> [6/9]	48
<b>7.15.1.7 BOOST_AUTO_TEST_CASE()</b> [7/9]	48
7.15.1.8 BOOST_AUTO_TEST_CASE() [8/9]	48
<b>7.15.1.9 BOOST_AUTO_TEST_CASE()</b> [9/9]	49
7.15.2 Variable Documentation	49
7.15.2.1 isFileName	49
7.16 track.cpp File Reference	49
7.17 track.h File Reference	49
7.18 types.h File Reference	50
Index	51

# Namespace Index

# 1.1 Namespace List

Here is a list of all namespaces with brief descriptions:

poost	. 9
poost::test_tools	. 9
poost::test_tools::tt_detail	. 9
GPS	. 9
GPS::Earth	
GPS::LogFiles	. 14
NMEA	. 15

2 Namespace Index

# **Hierarchical Index**

# 2.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

GPS::Position	17
boost::test_tools::tt_detail::print_log_value< std::vector< std::string >>	19
GPS::Route	19
GPS: Track	25

4 Hierarchical Index

# **Class Index**

# 3.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

GPS::Position	17
boost::test_tools::tt_detail::print_log_value< std::vector< std::string >>	19
GPS::Route	19
GPS::Track	25

6 Class Index

# File Index

# 4.1 File List

Here is a list of all files with brief descriptions:

earth.cpp	29
earth.h	29
geometry.cpp	30
geometry.h	30
gpx-tests.cpp	30
logs.cpp	31
$logs.h  \dots $	31
nmea-tests.cpp	32
parseNMEA.cpp	44
parseNMEA.h	44
position.cpp	45
position.h	45
route.cpp	46
route.h	46
timesVisited(string).cpp	46
track.cpp	49
$track.h \ldots \ldots$	49
types.h	50

8 File Index

# **Namespace Documentation**

# 5.1 boost Namespace Reference

# **Namespaces**

test\_tools

# 5.2 boost::test\_tools Namespace Reference

# **Namespaces**

tt\_detail

# 5.3 boost::test\_tools::tt\_detail Namespace Reference

#### **Classes**

struct print\_log\_value< std::vector< std::string > >

# 5.4 GPS Namespace Reference

#### **Namespaces**

- Earth
- LogFiles

#### **Classes**

- class Position
- class Route
- class Track

# **Typedefs**

- using degrees = double
- using radians = double
- using metres = double
- using seconds = unsigned long long int
- using speed = double

#### **Functions**

- radians degToRad (degrees)
- radians radToDeg (degrees)
- double sinSqr (radians)
- degrees normaliseDeg (degrees)
- degrees ddmTodd (std::string)

#### **Variables**

- const double pi = 3.141592653589793
- const degrees fullRotation = 360
- const degrees halfRotation = fullRotation/2
- const degrees poleLatitude = fullRotation/4
- const degrees antiMeridianLongitude = fullRotation/2

# 5.4.1 Typedef Documentation

#### 5.4.1.1 degrees

```
using GPS::degrees = typedef double
```

# 5.4.1.2 metres

```
using GPS::metres = typedef double
```

#### 5.4.1.3 radians

```
using GPS::radians = typedef double
```

#### 5.4.1.4 seconds

```
using GPS::seconds = typedef unsigned long long int
```

#### 5.4.1.5 speed

```
using GPS::speed = typedef double
```

#### 5.4.2 Function Documentation

#### 5.4.2.1 ddmTodd()

```
degrees GPS::ddmTodd (
          std::string ddmStr )
```

# 5.4.2.2 degToRad()

### 5.4.2.3 normaliseDeg()

```
degrees GPS::normaliseDeg ( degrees d )
```

# 5.4.2.4 radToDeg()

```
degrees GPS::radToDeg ( degrees r)
```

### 5.4.2.5 sinSqr()

#### 5.4.3 Variable Documentation

#### 5.4.3.1 antiMeridianLongitude

const degrees GPS::antiMeridianLongitude = fullRotation/2

#### 5.4.3.2 fullRotation

const degrees GPS::fullRotation = 360

#### 5.4.3.3 halfRotation

const degrees GPS::halfRotation = fullRotation/2

#### 5.4.3.4 pi

const double GPS::pi = 3.141592653589793

#### 5.4.3.5 poleLatitude

const degrees GPS::poleLatitude = fullRotation/4

# 5.5 GPS::Earth Namespace Reference

#### **Functions**

- degrees latitudeSubtendedBy (metres)
- degrees longitudeSubtendedBy (metres, degrees lat)

#### **Variables**

- const Position NorthPole = Position(poleLatitude,0,0)
- const Position EquatorialMeridian = Position(0,0,0)
- const Position EquatorialAntiMeridian = Position(0,antiMeridianLongitude,0)
- const Position CliftonCampus = Position(52.91249953,-1.18402513,58)
- const Position CityCampus = Position(52.9581383,-1.1542364,53)
- const Position Pontianak = Position(0,109.322134,0)
- const metres meanRadius = 6371008.8
- const metres equatorialCircumference = 40075160
- const metres polarCircumference = 40008000

#### 5.5.1 Function Documentation

#### 5.5.1.1 latitudeSubtendedBy()

#### 5.5.1.2 longitudeSubtendedBy()

### 5.5.2 Variable Documentation

#### 5.5.2.1 CityCampus

```
const Position GPS::Earth::CityCampus = Position(52.9581383,-1.1542364,53)
```

#### 5.5.2.2 CliftonCampus

```
const Position GPS::Earth::CliftonCampus = Position(52.91249953,-1.18402513,58)
```

#### 5.5.2.3 EquatorialAntiMeridian

const Position GPS::Earth::EquatorialAntiMeridian = Position(0,antiMeridianLongitude,0)

#### 5.5.2.4 equatorialCircumference

const metres GPS::Earth::equatorialCircumference = 40075160

#### 5.5.2.5 EquatorialMeridian

const Position GPS::Earth::EquatorialMeridian = Position(0,0,0)

#### 5.5.2.6 meanRadius

const metres GPS::Earth::meanRadius = 6371008.8

#### 5.5.2.7 NorthPole

const Position GPS::Earth::NorthPole = Position(poleLatitude,0,0)

#### 5.5.2.8 polarCircumference

const metres GPS::Earth::polarCircumference = 40008000

#### 5.5.2.9 Pontianak

const Position GPS::Earth::Pontianak = Position(0,109.322134,0)

# 5.6 GPS::LogFiles Namespace Reference

#### **Variables**

- const std::string logsDir = "../logs/"
- const std::string NMEALogsDir = logsDir + "NMEA/"
- const std::string GPXRoutesDir = logsDir + "GPX/routes/"
- const std::string GPXTracksDir = logsDir + "GPX/tracks/"

#### 5.6.1 Variable Documentation

#### 5.6.1.1 GPXRoutesDir

```
const std::string GPS::LogFiles::GPXRoutesDir = logsDir + "GPX/routes/"
```

#### 5.6.1.2 GPXTracksDir

```
const std::string GPS::LogFiles::GPXTracksDir = logsDir + "GPX/tracks/"
```

#### 5.6.1.3 logsDir

```
const std::string GPS::LogFiles::logsDir = "../logs/"
```

#### 5.6.1.4 NMEALogsDir

```
const std::string GPS::LogFiles::NMEALogsDir = logsDir + "NMEA/"
```

# 5.7 NMEA Namespace Reference

# **Typedefs**

- using SentenceData = std::pair< std::string, std::vector< std::string > >
- using Route = std::vector < GPS::Position >

#### **Functions**

- bool isWellFormedSentence (std::string)
- bool hasValidChecksum (std::string)
- SentenceData extractSentenceData (std::string)
- GPS::Position positionFromSentenceData (SentenceData)
- Route routeFromLog (std::istream &)

# 5.7.1 Typedef Documentation

#### 5.7.1.1 Route

```
using NMEA::Route = typedef std::vector<GPS::Position>
```

#### 5.7.1.2 SentenceData

```
using NMEA::SentenceData = typedef std::pair<std::string, std::vector<std::string> >
```

#### 5.7.2 Function Documentation

#### 5.7.2.1 extractSentenceData()

#### 5.7.2.2 hasValidChecksum()

### 5.7.2.3 isWellFormedSentence()

#### 5.7.2.4 positionFromSentenceData()

#### 5.7.2.5 routeFromLog()

# **Class Documentation**

# 6.1 GPS::Position Class Reference

```
#include <position.h>
```

#### **Public Member Functions**

- Position (degrees lat, degrees lon, metres ele=0.0)
- Position (std::string latStr, std::string lonStr, std::string eleStr="0")
- Position (std::string ddmLatStr, char northing, std::string ddmLonStr, char easting, std::string eleSt="0")
- degrees latitude () const
- · degrees longitude () const
- metres elevation () const
- std::string toString (bool includeElevation=true) const

#### **Static Public Member Functions**

• static metres distanceBetween (Position, Position)

#### 6.1.1 Constructor & Destructor Documentation

#### 6.1.1.1 Position() [1/3]

```
GPS::Position::Position (
          degrees lat,
          degrees lon,
          metres ele = 0.0 )
```

#### 6.1.1.2 Position() [2/3]

# 6.1.1.3 Position() [3/3]

```
GPS::Position::Position (
    std::string ddmLatStr,
    char northing,
    std::string ddmLonStr,
    char easting,
    std::string eleSt = "0" )
```

#### 6.1.2 Member Function Documentation

#### 6.1.2.1 distanceBetween()

#### 6.1.2.2 elevation()

```
\begin{tabular}{ll} metres & GPS:: Position:: elevation ( ) & const \\ \end{tabular}
```

#### 6.1.2.3 latitude()

```
degrees GPS::Position::latitude ( ) const
```

#### 6.1.2.4 longitude()

```
degrees GPS::Position::longitude ( ) const
```

#### 6.1.2.5 toString()

The documentation for this class was generated from the following files:

- position.h
- position.cpp

# 6.2 boost::test\_tools::tt\_detail::print\_log\_value< std::vector< std::string >> Struct Reference

#### **Public Member Functions**

void operator() (std::ostream &os, std::vector< std::string > const &v)

#### 6.2.1 Member Function Documentation

#### 6.2.1.1 operator()()

The documentation for this struct was generated from the following file:

• nmea-tests.cpp

# 6.3 GPS::Route Class Reference

```
#include <route.h>
```

Inheritance diagram for GPS::Route:

#### **Public Member Functions**

- · Route (std::string source, bool isFileName, metres granularity=20)
- virtual void setGranularity (metres)
- std::string name () const
- unsigned int numPositions () const
- · metres totalLength () const
- · metres netLength () const
- metres totalHeightGain () const
- metres netHeightGain () const
- degrees maxGradient () const
- · degrees minGradient () const
- · degrees steepestGradient () const
- · degrees minLatitude () const
- · degrees maxLatitude () const
- · degrees minLongitude () const
- · degrees maxLongitude () const
- · metres minElevation () const
- metres maxElevation () const
- Position operator[] (unsigned int) const
- Position findPosition (std::string soughtName) const
- std::string findNameOf (Position) const
- unsigned int timesVisited (std::string soughtName) const
- · unsigned int timesVisited (Position) const
- · bool containsCycles () const

#### **Protected Member Functions**

- Route ()
- · bool areSameLocation (Position, Position) const

#### **Protected Attributes**

- std::vector< Position > positions
- std::vector< std::string > positionNames
- std::string routeName
- · metres routeLength
- · metres granularity

#### 6.3.1 Constructor & Destructor Documentation

#### 6.3.1.1 Route() [1/2]

#### 6.3.1.2 Route() [2/2]

```
GPS::Route::Route ( ) [inline], [protected]
```

#### 6.3.2 Member Function Documentation

#### 6.3.2.1 areSameLocation()

#### 6.3.2.2 containsCycles()

```
bool Route::containsCycles ( ) const
```

#### 6.3.2.3 findNameOf()

#### 6.3.2.4 findPosition()

#### 6.3.2.5 maxElevation()

```
metres Route::maxElevation ( ) const
```

# 6.3.2.6 maxGradient()

```
degrees Route::maxGradient ( ) const
```

# 6.3.2.7 maxLatitude()

```
degrees Route::maxLatitude ( ) const
```

#### 6.3.2.8 maxLongitude()

```
degrees Route::maxLongitude ( ) const
```

#### 6.3.2.9 minElevation()

```
metres Route::minElevation ( ) const
```

#### 6.3.2.10 minGradient()

```
degrees Route::minGradient ( ) const
```

# 6.3.2.11 minLatitude()

```
degrees Route::minLatitude ( ) const
```

#### 6.3.2.12 minLongitude()

```
degrees Route::minLongitude ( ) const
```

# 6.3.2.13 name()

```
std::string Route::name ( ) const
```

#### 6.3.2.14 netHeightGain()

```
metres Route::netHeightGain ( ) const
```

#### 6.3.2.15 netLength()

```
metres Route::netLength ( ) const
```

#### 6.3.2.16 numPositions()

```
unsigned int Route::numPositions ( ) const
```

#### 6.3.2.17 operator[]()

```
Position Route::operator[] (
         unsigned int idx ) const
```

# 6.3.2.18 setGranularity()

Reimplemented in GPS::Track.

#### 6.3.2.19 steepestGradient()

```
degrees Route::steepestGradient ( ) const
```

#### 6.3.2.20 timesVisited() [1/2]

#### 6.3.2.21 timesVisited() [2/2]

#### 6.3.2.22 totalHeightGain()

```
metres Route::totalHeightGain ( ) const
```

# 6.3.2.23 totalLength()

```
metres Route::totalLength ( ) const
```

#### 6.3.3 Member Data Documentation

#### 6.3.3.1 granularity

```
metres GPS::Route::granularity [protected]
```

#### 6.3.3.2 positionNames

```
std::vector<std::string> GPS::Route::positionNames [protected]
```

#### 6.3.3.3 positions

```
std::vector<Position> GPS::Route::positions [protected]
```

#### 6.3.3.4 routeLength

```
metres GPS::Route::routeLength [protected]
```

#### 6.3.3.5 routeName

```
std::string GPS::Route::routeName [protected]
```

The documentation for this class was generated from the following files:

- · route.h
- route.cpp

### 6.4 GPS::Track Class Reference

```
#include <track.h>
```

Inheritance diagram for GPS::Track:

Collaboration diagram for GPS::Track:

# **Public Member Functions**

- Track (std::string source, bool isFileName, metres granularity=10)
- void setGranularity (metres) override
- seconds totalTime () const
- seconds travellingTime () const
- seconds restingTime () const
- seconds longestRest () const
- speed maxSpeed () const
- speed averageSpeed (bool includeRests) const
- speed maxRateOfAscent () const
- · speed maxRateOfDescent () const

#### **Protected Attributes**

```
    std::vector< seconds > arrived
```

• std::vector< seconds > departed

#### **Additional Inherited Members**

#### 6.4.1 Constructor & Destructor Documentation

#### 6.4.1.1 Track()

### 6.4.2 Member Function Documentation

#### 6.4.2.1 averageSpeed()

```
speed Track::averageSpeed (
          bool includeRests ) const
```

#### 6.4.2.2 longestRest()

```
seconds Track::longestRest ( ) const
```

# 6.4.2.3 maxRateOfAscent()

```
speed Track::maxRateOfAscent ( ) const
```

#### 6.4.2.4 maxRateOfDescent()

```
speed Track::maxRateOfDescent ( ) const
```

#### 6.4.2.5 maxSpeed()

```
speed Track::maxSpeed ( ) const
```

# 6.4.2.6 restingTime()

```
seconds Track::restingTime ( ) const
```

# 6.4.2.7 setGranularity()

Reimplemented from GPS::Route.

# 6.4.2.8 totalTime()

```
seconds Track::totalTime ( ) const
```

# 6.4.2.9 travellingTime()

```
seconds Track::travellingTime ( ) const
```

#### 6.4.3 Member Data Documentation

#### 6.4.3.1 arrived

```
std::vector<seconds> GPS::Track::arrived [protected]
```

#### 6.4.3.2 departed

```
std::vector<seconds> GPS::Track::departed [protected]
```

The documentation for this class was generated from the following files:

- track.h
- track.cpp

# **Chapter 7**

# **File Documentation**

# 7.1 earth.cpp File Reference

```
#include <cmath>
#include "geometry.h"
#include "earth.h"
Include dependency graph for earth.cpp:
```

# 7.2 earth.h File Reference

```
#include "position.h"
```

Include dependency graph for earth.h: This graph shows which files directly or indirectly include this file:

# **Namespaces**

- GPS
- · GPS::Earth

#### **Functions**

- degrees GPS::Earth::latitudeSubtendedBy (metres)
- degrees GPS::Earth::longitudeSubtendedBy (metres, degrees lat)

#### **Variables**

- const Position GPS::Earth::NorthPole = Position(poleLatitude,0,0)
- const Position GPS::Earth::EquatorialMeridian = Position(0,0,0)
- const Position GPS::Earth::EquatorialAntiMeridian = Position(0,antiMeridianLongitude,0)
- const Position GPS::Earth::CliftonCampus = Position(52.91249953,-1.18402513,58)
- const Position GPS::Earth::CityCampus = Position(52.9581383,-1.1542364,53)
- const Position GPS::Earth::Pontianak = Position(0,109.322134,0)
- const metres GPS::Earth::meanRadius = 6371008.8
- const metres GPS::Earth::equatorialCircumference = 40075160
- const metres GPS::Earth::polarCircumference = 40008000

# 7.3 geometry.cpp File Reference

```
#include <cmath>
#include "geometry.h"
Include dependency graph for geometry.cpp:
```

#### **Namespaces**

• GPS

#### **Functions**

- radians GPS::degToRad (degrees)
- radians GPS::radToDeg (degrees)
- double GPS::sinSqr (radians)
- degrees GPS::normaliseDeg (degrees)

# 7.4 geometry.h File Reference

```
#include "types.h"
```

Include dependency graph for geometry.h: This graph shows which files directly or indirectly include this file:

#### **Namespaces**

• GPS

# **Functions**

- radians GPS::degToRad (degrees)
- radians GPS::radToDeg (degrees)
- double GPS::sinSqr (radians)
- degrees GPS::normaliseDeg (degrees)

#### **Variables**

- const double GPS::pi = 3.141592653589793
- const degrees GPS::fullRotation = 360
- const degrees GPS::halfRotation = fullRotation/2
- const degrees GPS::poleLatitude = fullRotation/4
- const degrees GPS::antiMeridianLongitude = fullRotation/2

# 7.5 gpx-tests.cpp File Reference

```
#include <boost/test/unit_test.hpp>
Include dependency graph for gpx-tests.cpp:
```

#### **Macros**

- #define BOOST\_TEST\_DYN\_LINK
- #define BOOST\_TEST\_MODULE GPXTests

#### 7.5.1 Macro Definition Documentation

# 7.5.1.1 BOOST\_TEST\_DYN\_LINK

#define BOOST\_TEST\_DYN\_LINK

# 7.5.1.2 BOOST\_TEST\_MODULE

#define BOOST\_TEST\_MODULE GPXTests

# 7.6 logs.cpp File Reference

```
#include <string>
#include "logs.h"
Include dependency graph for logs.cpp:
```

# **Namespaces**

- GPS
- GPS::LogFiles

# 7.7 logs.h File Reference

#include <string>

Include dependency graph for logs.h: This graph shows which files directly or indirectly include this file:

# **Namespaces**

- GPS
- GPS::LogFiles

#### **Variables**

- const std::string GPS::LogFiles::logsDir = "../logs/"
- const std::string GPS::LogFiles::NMEALogsDir = logsDir + "NMEA/"
- const std::string GPS::LogFiles::GPXRoutesDir = logsDir + "GPX/routes/"
- const std::string GPS::LogFiles::GPXTracksDir = logsDir + "GPX/tracks/"

# 7.8 nmea-tests.cpp File Reference

```
#include <boost/test/unit_test.hpp>
#include <string>
#include <stdexcept>
#include <vector>
#include <utility>
#include <ostream>
#include <fstream>
#include <isstream>
#include <iostream>
#include <ipstream>
#include <ipstream>
#include dependency graph for nmea-tests.cpp:
```

#### Classes

struct boost::test\_tools::tt\_detail::print\_log\_value< std::vector< std::string > >

# **Namespaces**

- boost
- · boost::test\_tools
- boost::test\_tools::tt\_detail

#### **Macros**

- #define BOOST\_TEST\_DYN\_LINK
- #define BOOST\_TEST\_MODULE ParseNMEATests

# **Functions**

- BOOST\_AUTO\_TEST\_CASE (WellFormedNoFields)
- BOOST AUTO TEST CASE (WellFormedOneField)
- BOOST\_AUTO\_TEST\_CASE (WellFormedTwoFields)
- BOOST\_AUTO\_TEST\_CASE (WellFormedEmptyField)
- BOOST\_AUTO\_TEST\_CASE (WellFormedManyFields)
- BOOST\_AUTO\_TEST\_CASE (WellFormedWithLowercaseHexCharacters)
- BOOST AUTO TEST CASE (WellFormedWithUppercaseHexCharacters)
- BOOST\_AUTO\_TEST\_CASE (WellFormedTypicalSentences)
- BOOST AUTO TEST CASE (IIIFormedMissingSuffix)
- BOOST\_AUTO\_TEST\_CASE (IIIFormedDollar)

 BOOST\_AUTO\_TEST\_CASE (IIIFormedGP) BOOST\_AUTO\_TEST\_CASE (IllFormedType) BOOST AUTO TEST CASE (IllFormedReservedCharInField) BOOST\_AUTO\_TEST\_CASE (IIIFormedStar) BOOST\_AUTO\_TEST\_CASE (IllFormedChecksum) • BOOST\_AUTO\_TEST\_CASE (ValidChecksumMinimalSentence) BOOST AUTO TEST CASE (IncorrectChecksumMinimalSentence) • BOOST\_AUTO\_TEST\_CASE (ValidChecksumTypicalSentences) BOOST AUTO TEST CASE (IncorrectChecksumTypicalSentences) BOOST AUTO TEST CASE (CorrectChecksumWithUppercaseHexDigit) BOOST AUTO TEST CASE (CorrectChecksumWithLowercaseHexDigit) BOOST AUTO TEST CASE (IncorrectChecksumsithUppercaseHexDigit) BOOST AUTO TEST CASE (IncorrectChecksumWithLowercaseHexDigit) BOOST\_AUTO\_TEST\_CASE (ExtractZeroFields) BOOST AUTO TEST CASE (ExtractOneField) BOOST\_AUTO\_TEST\_CASE (ExtractTwoFields) BOOST\_AUTO\_TEST\_CASE (ExtractGLL) • BOOST\_AUTO\_TEST\_CASE (ExtractGGA) BOOST AUTO TEST CASE (ExtractRMC) BOOST AUTO TEST CASE (ExtractMSS) BOOST\_AUTO\_TEST\_CASE (GLL\_NW) BOOST AUTO TEST CASE (GLL NE) BOOST AUTO TEST CASE (GLL SE) BOOST AUTO TEST CASE (GLL SW) BOOST\_AUTO\_TEST\_CASE (RMC\_NW) BOOST AUTO TEST CASE (RMC NE) BOOST AUTO TEST CASE (RMC SE) BOOST\_AUTO\_TEST\_CASE (RMC\_SW) BOOST\_AUTO\_TEST\_CASE (GGA\_NW) • BOOST AUTO TEST CASE (GGA NE) BOOST\_AUTO\_TEST\_CASE (GGA\_SE) BOOST\_AUTO\_TEST\_CASE (GGA\_SW) • BOOST\_AUTO\_TEST\_CASE (GGA\_NegativeElevation) BOOST AUTO TEST CASE (UnsupportedFormat) BOOST AUTO TEST CASE (EmptyFieldVector) BOOST AUTO TEST CASE (MissingFieldsGLL) BOOST AUTO TEST CASE (MissingFieldsRMC) BOOST AUTO TEST CASE (MissingFieldsGGA) BOOST AUTO TEST CASE (InvalidFieldData) BOOST\_AUTO\_TEST\_CASE (EmptyLog) • BOOST AUTO TEST CASE (LogWithOneValidSentence) • BOOST\_AUTO\_TEST\_CASE (LogWithTwoValidSentences) BOOST\_AUTO\_TEST\_CASE (LogWithBlankLines) BOOST\_AUTO\_TEST\_CASE (LogWithoutLineBreaks) BOOST AUTO TEST CASE (LogWithIllFormedSentences) BOOST AUTO TEST CASE (LogWithInvalidChecksums) BOOST AUTO TEST CASE (LogWithUnsupportedSentenceTypes) BOOST\_AUTO\_TEST\_CASE (LogWithMissingFields) BOOST AUTO TEST CASE (LogWithInvalidFields)

BOOST\_AUTO\_TEST\_CASE (LargeLog\_GLL)

BOOST\_AUTO\_TEST\_CASE (LargeLog\_GGA\_RMC)

#### **Variables**

- const double epsilon = 0.0001
- const double percentageAccuracy = 0.0001
- const std::string validGLLSentence = "\$GPGLL,5425.31,N,107.03,W,82610\*69"
- const std::string validRMCSentence = "\$GPRMC,113922.000,A,3722.5993,N,00559.2458,W,0.000,0. $\leftarrow$  00,150914,A\*62"
- const std::string validMSSSentence = "\$GPMSS,55,27,318.0,100,\*66"
- const GPS::Position gllPos = GPS::Position("5425.31",'N',"107.03",'W')
- const GPS::Position rmcPos = GPS::Position("3722.5993",'N',"00559.2458",'W')

#### 7.8.1 Macro Definition Documentation

#### 7.8.1.1 BOOST\_TEST\_DYN\_LINK

```
#define BOOST_TEST_DYN_LINK
```

# 7.8.1.2 BOOST\_TEST\_MODULE

```
#define BOOST_TEST_MODULE ParseNMEATests
```

#### 7.8.2 Function Documentation

# 7.8.2.1 BOOST\_AUTO\_TEST\_CASE() [1/61]

```
BOOST_AUTO_TEST_CASE (

CorrectChecksumWithLowercaseHexDigit )
```

#### 7.8.2.2 BOOST AUTO TEST CASE() [2/61]

```
BOOST_AUTO_TEST_CASE (

CorrectChecksumWithUppercaseHexDigit )
```

# 7.8.2.3 BOOST\_AUTO\_TEST\_CASE() [3/61]

#### 7.8.2.4 BOOST AUTO TEST CASE() [4/61]

```
BOOST_AUTO_TEST_CASE (

EmptyLog )
```

#### 7.8.2.5 BOOST\_AUTO\_TEST\_CASE() [5/61]

# 7.8.2.6 BOOST\_AUTO\_TEST\_CASE() [6/61]

# 7.8.2.7 BOOST\_AUTO\_TEST\_CASE() [7/61]

```
BOOST_AUTO_TEST_CASE (

ExtractMSS )
```

# 7.8.2.8 BOOST\_AUTO\_TEST\_CASE() [8/61]

# 7.8.2.9 BOOST\_AUTO\_TEST\_CASE() [9/61]

```
BOOST_AUTO_TEST_CASE (

ExtractRMC )
```

# 7.8.2.10 BOOST\_AUTO\_TEST\_CASE() [10/61]

# 7.8.2.11 BOOST\_AUTO\_TEST\_CASE() [11/61]

#### 7.8.2.12 BOOST\_AUTO\_TEST\_CASE() [12/61]

```
BOOST_AUTO_TEST_CASE (

GGA_NE )
```

# 7.8.2.13 BOOST\_AUTO\_TEST\_CASE() [13/61]

# 7.8.2.14 BOOST\_AUTO\_TEST\_CASE() [14/61]

# 7.8.2.15 BOOST\_AUTO\_TEST\_CASE() [15/61]

# 7.8.2.16 BOOST\_AUTO\_TEST\_CASE() [16/61]

# 7.8.2.17 BOOST\_AUTO\_TEST\_CASE() [17/61]

```
BOOST_AUTO_TEST_CASE (

GLL_NE )
```

# 7.8.2.18 BOOST\_AUTO\_TEST\_CASE() [18/61]

```
BOOST_AUTO_TEST_CASE (

GLL_NW )
```

#### 7.8.2.19 BOOST\_AUTO\_TEST\_CASE() [19/61]

```
BOOST_AUTO_TEST_CASE (
GLL_SE )
```

# 7.8.2.20 BOOST\_AUTO\_TEST\_CASE() [20/61]

```
BOOST_AUTO_TEST_CASE (
GLL_SW )
```

# 7.8.2.21 BOOST\_AUTO\_TEST\_CASE() [21/61]

# 7.8.2.22 BOOST\_AUTO\_TEST\_CASE() [22/61]

# 7.8.2.23 BOOST\_AUTO\_TEST\_CASE() [23/61]

```
7.8.2.24 BOOST_AUTO_TEST_CASE() [24/61]
```

# 7.8.2.25 BOOST\_AUTO\_TEST\_CASE() [25/61]

#### 7.8.2.26 BOOST\_AUTO\_TEST\_CASE() [26/61]

# 7.8.2.27 BOOST\_AUTO\_TEST\_CASE() [27/61]

# 7.8.2.28 BOOST\_AUTO\_TEST\_CASE() [28/61]

# 7.8.2.29 BOOST\_AUTO\_TEST\_CASE() [29/61]

# 7.8.2.30 BOOST\_AUTO\_TEST\_CASE() [30/61]

# 7.8.2.31 BOOST\_AUTO\_TEST\_CASE() [31/61]

```
{\tt BOOST\_AUTO\_TEST\_CASE} \ \ ( {\tt IncorrectChecksumWithLowercaseHexDigit} \ \ )
```

#### 7.8.2.32 BOOST AUTO TEST CASE() [32/61]

#### 7.8.2.33 BOOST\_AUTO\_TEST\_CASE() [33/61]

```
BOOST_AUTO_TEST_CASE (

LargeLog_GGA_RMC )
```

# 7.8.2.34 BOOST\_AUTO\_TEST\_CASE() [34/61]

```
BOOST_AUTO_TEST_CASE (

LargeLog_GLL )
```

#### 7.8.2.35 BOOST\_AUTO\_TEST\_CASE() [35/61]

# 7.8.2.36 BOOST\_AUTO\_TEST\_CASE() [36/61]

# 7.8.2.37 BOOST\_AUTO\_TEST\_CASE() [37/61]

```
7.8.2.38 BOOST_AUTO_TEST_CASE() [38/61]
```

# 7.8.2.39 BOOST\_AUTO\_TEST\_CASE() [39/61]

#### 7.8.2.40 BOOST\_AUTO\_TEST\_CASE() [40/61]

# 7.8.2.41 BOOST\_AUTO\_TEST\_CASE() [41/61]

#### 7.8.2.42 BOOST\_AUTO\_TEST\_CASE() [42/61]

# 7.8.2.43 BOOST\_AUTO\_TEST\_CASE() [43/61]

# 7.8.2.44 BOOST\_AUTO\_TEST\_CASE() [44/61]

# 7.8.2.45 BOOST\_AUTO\_TEST\_CASE() [45/61]

#### 7.8.2.46 BOOST AUTO TEST CASE() [46/61]

#### 7.8.2.47 BOOST\_AUTO\_TEST\_CASE() [47/61]

```
BOOST_AUTO_TEST_CASE (

RMC_NE )
```

# 7.8.2.48 BOOST\_AUTO\_TEST\_CASE() [48/61]

```
BOOST_AUTO_TEST_CASE (

RMC_NW )
```

# 7.8.2.49 BOOST\_AUTO\_TEST\_CASE() [49/61]

```
BOOST_AUTO_TEST_CASE (

RMC_SE )
```

# 7.8.2.50 BOOST\_AUTO\_TEST\_CASE() [50/61]

```
BOOST_AUTO_TEST_CASE (
RMC_SW )
```

# 7.8.2.51 BOOST\_AUTO\_TEST\_CASE() [51/61]

```
7.8.2.52 BOOST_AUTO_TEST_CASE() [52/61]
```

#### 7.8.2.53 BOOST AUTO TEST CASE() [53/61]

#### 7.8.2.54 BOOST\_AUTO\_TEST\_CASE() [54/61]

# 7.8.2.55 BOOST\_AUTO\_TEST\_CASE() [55/61]

#### 7.8.2.56 BOOST\_AUTO\_TEST\_CASE() [56/61]

# 7.8.2.57 BOOST\_AUTO\_TEST\_CASE() [57/61]

# 7.8.2.58 BOOST\_AUTO\_TEST\_CASE() [58/61]

# 7.8.2.59 BOOST\_AUTO\_TEST\_CASE() [59/61]

# 7.8.2.60 BOOST\_AUTO\_TEST\_CASE() [60/61]

```
BOOST_AUTO_TEST_CASE (

WellFormedWithLowercaseHexCharacters )
```

#### 7.8.2.61 BOOST\_AUTO\_TEST\_CASE() [61/61]

#### 7.8.3 Variable Documentation

#### 7.8.3.1 epsilon

```
const double epsilon = 0.0001
```

#### 7.8.3.2 gIIPos

```
\texttt{const GPS::Position gllPos} = \texttt{GPS::Position("5425.31",'N',"107.03",'W')}
```

#### 7.8.3.3 percentageAccuracy

```
const double percentageAccuracy = 0.0001
```

#### 7.8.3.4 rmcPos

```
const GPS::Position rmcPos = GPS::Position("3722.5993",'N',"00559.2458",'W')
```

#### 7.8.3.5 validGLLSentence

```
const std::string validGLLSentence = "$GPGLL,5425.31,N,107.03,W,82610*69"
```

#### 7.8.3.6 validMSSSentence

```
const std::string validMSSSentence = "$GPMSS,55,27,318.0,100,*66"
```

#### 7.8.3.7 validRMCSentence

```
const std::string validRMCSentence = "$GPRMC,113922.000,A,3722.5993,N,00559.2458,W,0.000,0.\leftrightarrow 00,150914,A*62"
```

# 7.9 parseNMEA.cpp File Reference

```
#include "earth.h"
#include "parseNMEA.h"
Include dependency graph for parseNMEA.cpp:
```

# **Namespaces**

• NMEA

#### **Functions**

- bool NMEA::isWellFormedSentence (std::string)
- bool NMEA::hasValidChecksum (std::string)
- SentenceData NMEA::extractSentenceData (std::string)
- GPS::Position NMEA::positionFromSentenceData (SentenceData)
- Route NMEA::routeFromLog (std::istream &)

# 7.10 parseNMEA.h File Reference

```
#include <string>
#include <list>
#include <vector>
#include <utility>
#include <istream>
#include "position.h"
```

Include dependency graph for parseNMEA.h: This graph shows which files directly or indirectly include this file:

# **Namespaces**

NMEA

# **Typedefs**

- using NMEA::SentenceData = std::pair< std::string, std::vector< std::string >>
- using NMEA::Route = std::vector< GPS::Position >

#### **Functions**

- bool NMEA::isWellFormedSentence (std::string)
- bool NMEA::hasValidChecksum (std::string)
- SentenceData NMEA::extractSentenceData (std::string)
- GPS::Position NMEA::positionFromSentenceData (SentenceData)
- Route NMEA::routeFromLog (std::istream &)

# 7.11 position.cpp File Reference

```
#include <cassert>
#include <cmath>
#include <sstream>
#include <stdexcept>
#include "geometry.h"
#include "earth.h"
#include "position.h"
Include dependency graph for position.cpp:
```

# **Namespaces**

• GPS

# **Functions**

· degrees GPS::ddmTodd (std::string)

# 7.12 position.h File Reference

```
#include <string>
#include "types.h"
```

Include dependency graph for position.h: This graph shows which files directly or indirectly include this file:

# Classes

· class GPS::Position

# **Namespaces**

• GPS

#### **Functions**

· degrees GPS::ddmTodd (std::string)

# 7.13 route.cpp File Reference

```
#include <sstream>
#include <fstream>
#include <iostream>
#include <cassert>
#include <cmath>
#include <algorithm>
#include <iterator>
#include <stdexcept>
#include "geometry.h"
#include "xml/element.h"
#include "xml/parser.h"
#include "route.h"
Include dependency graph for route.cpp:
```

# 7.14 route.h File Reference

```
#include <string>
#include <vector>
#include "types.h"
#include "position.h"
#include "xml/parser.h"
```

Include dependency graph for route.h: This graph shows which files directly or indirectly include this file:

#### **Classes**

· class GPS::Route

# **Namespaces**

• GPS

# 7.15 timesVisited(string).cpp File Reference

```
#include <boost/test/unit_test.hpp>
#include "logs.h"
#include "route.h"
Include dependency graph for timesVisited(string).cpp:
```

#### **Functions**

BOOST\_AUTO\_TEST\_CASE (singleton\_route)

A simple route with one point and one name to check.

BOOST\_AUTO\_TEST\_CASE (position\_not\_visited)

A simple route with one point and checking the number of times for a position that wasn't visited.

• BOOST\_AUTO\_TEST\_CASE (singleton\_route\_with\_spaces)

A simple route with one point and one name to check, with leading and trailing spaces to check the constructor.

BOOST\_AUTO\_TEST\_CASE (bad\_input\_string)

A simple route with one point and checking invalid\_argument is thrown when a blank string is passed in.

• BOOST AUTO TEST CASE (two consecutive visits)

A simple route with two positions that are the same location.

BOOST\_AUTO\_TEST\_CASE (one\_name\_multiple\_positions)

A complex route where many positions share the same name.

• BOOST\_AUTO\_TEST\_CASE (one\_position\_many\_visits)

A complex route where one position is visited many times.

BOOST\_AUTO\_TEST\_CASE (one\_name\_many\_positions\_and\_many\_visits)

A complex route where there are many positions with the same name, visited multiple times.

• BOOST\_AUTO\_TEST\_CASE (one\_position\_many\_names)

A complex route where there is one position visited multiple times, but with different names.

#### **Variables**

• const bool isFileName = false

all data for this test suite is passed in as strings, not files.

# 7.15.1 Function Documentation

#### 7.15.1.1 BOOST\_AUTO\_TEST\_CASE() [1/9]

```
BOOST_AUTO_TEST_CASE (
          bad_input_string )
```

A simple route with one point and checking invalid\_argument is thrown when a blank string is passed in.

#### 7.15.1.2 BOOST\_AUTO\_TEST\_CASE() [2/9]

A complex route where there are many positions with the same name, visited multiple times.

# 7.15.1.3 BOOST\_AUTO\_TEST\_CASE() [3/9]

A complex route where many positions share the same name.

#### 7.15.1.4 BOOST\_AUTO\_TEST\_CASE() [4/9]

A complex route where there is one position visited multiple times, but with different names.

#### 7.15.1.5 BOOST\_AUTO\_TEST\_CASE() [5/9]

A complex route where one position is visited many times.

# 7.15.1.6 BOOST\_AUTO\_TEST\_CASE() [6/9]

A simple route with one point and checking the number of times for a position that wasn't visited.

# 7.15.1.7 BOOST\_AUTO\_TEST\_CASE() [7/9]

A simple route with one point and one name to check.

# 7.15.1.8 BOOST\_AUTO\_TEST\_CASE() [8/9]

A simple route with one point and one name to check, with leading and trailing spaces to check the constructor.

#### 7.15.1.9 BOOST\_AUTO\_TEST\_CASE() [9/9]

A simple route with two positions that are the same location.

#### 7.15.2 Variable Documentation

#### 7.15.2.1 isFileName

```
const bool isFileName = false
```

all data for this test suite is passed in as strings, not files.

# 7.16 track.cpp File Reference

```
#include <sstream>
#include <fstream>
#include <iostream>
#include <cassert>
#include <cmath>
#include <stdexcept>
#include "geometry.h"
#include "xml/element.h"
#include "xml/parser.h"
#include "track.h"
```

Include dependency graph for track.cpp:

# 7.17 track.h File Reference

```
#include <string>
#include <vector>
#include "types.h"
#include "position.h"
#include "route.h"
#include "xml/parser.h"
```

Include dependency graph for track.h: This graph shows which files directly or indirectly include this file:

#### **Classes**

· class GPS::Track

# **Namespaces**

• GPS

# 7.18 types.h File Reference

This graph shows which files directly or indirectly include this file:

# **Namespaces**

• GPS

# **Typedefs**

```
• using GPS::degrees = double
```

- using GPS::radians = double
- using GPS::metres = double
- using GPS::seconds = unsigned long long int
- using GPS::speed = double

# Index

antiMeridianLongitude	GPS::Earth, 13
GPS, 12	equatorialCircumference
areSameLocation	GPS::Earth, 14
GPS::Route, 21	EquatorialMeridian
arrived	GPS::Earth, 14
GPS::Track, 27	extractSentenceData
averageSpeed	NMEA, 16
GPS::Track, 25	
	findNameOf
boost, 9	GPS::Route, 21
boost::test_tools, 9	findPosition
boost::test_tools::tt_detail, 9	GPS::Route, 21
boost::test_tools::tt_detail::print_log_value< std::vector<	fullRotation
std::string $>>$ , 19	GPS, 12
operator(), 19	
BOOST_AUTO_TEST_CASE	geometry.cpp, 30
nmea-tests.cpp, 34–43	geometry.h, 30
timesVisited(string).cpp, 47, 48	gllPos
BOOST_TEST_DYN_LINK	nmea-tests.cpp, 43
gpx-tests.cpp, 31	GPS, 9
nmea-tests.cpp, 34	antiMeridianLongitude, 12
BOOST_TEST_MODULE	ddmTodd, 11
gpx-tests.cpp, 31	degrees, 10
nmea-tests.cpp, 34	degToRad, 11
117	fullRotation, 12
CityCampus	halfRotation, 12
GPS::Earth, 13	metres, 10
CliftonCampus	normaliseDeg, 11
GPS::Earth, 13	pi, 12
containsCycles	poleLatitude, 12
GPS::Route, 21	radians, 10
,	radToDeg, 11
ddmTodd	seconds, 10
GPS, 11	sinSqr, 11
degrees	speed, 11
GPS, 10	GPS::Earth, 12
degToRad	CityCampus, 13
GPS, 11	CliftonCampus, 13
departed	EquatorialAntiMeridian, 13
GPS::Track, 27	equatorialCircumference, 14
distanceBetween	EquatorialMeridian, 14
GPS::Position, 18	latitudeSubtendedBy, 13
	longitudeSubtendedBy, 13
earth.cpp, 29	meanRadius, 14
earth.h, 29	NorthPole, 14
elevation	polarCircumference, 14
GPS::Position, 18	Pontianak, 14
epsilon	GPS::LogFiles, 14
nmea-tests.cpp, 43	GPXRoutesDir, 15
EquatorialAntiMeridian	GPXTracksDir. 15

52 INDEX

logsDir, 15	granularity
NMEALogsDir, 15	GPS::Route, 24
GPS::Position, 17	L KD + C
distanceBetween, 18	halfRotation
elevation, 18	GPS, 12
latitude, 18	hasValidChecksum
longitude, 18	NMEA, 16
Position, 17, 18	
toString, 18	isFileName
GPS::Route, 19	timesVisited(string).cpp, 49
areSameLocation, 21	isWellFormedSentence
containsCycles, 21	NMEA, 16
findNameOf, 21	
findPosition, 21	latitude
granularity, 24	GPS::Position, 18
maxElevation, 21	latitudeSubtendedBy
maxGradient, 21	GPS::Earth, 13
maxLatitude, 21	logs.cpp, 31
maxLongitude, 22	logs.h, 31
minElevation, 22	logsDir
minGradient, 22	GPS::LogFiles, 15
minLatitude, 22	longestRest
	GPS::Track, 26
minLongitude, 22	longitude
name, 22	GPS::Position, 18
netHeightGain, 22	IongitudeSubtendedBy
netLength, 22	GPS::Earth, 13
numPositions, 23	,
operator[], 23	maxElevation
positionNames, 24	GPS::Route, 21
positions, 24	maxGradient
Route, 20	GPS::Route, 21
routeLength, 24	maxLatitude
routeName, 24	GPS::Route, 21
setGranularity, 23	maxLongitude
steepestGradient, 23	GPS::Route, 22
timesVisited, 23	maxRateOfAscent
totalHeightGain, 23	GPS::Track, 26
totalLength, 24	maxRateOfDescent
GPS::Track, 25	GPS::Track, 26
arrived, 27	maxSpeed
averageSpeed, 25	GPS::Track, 26
departed, 27	meanRadius
longestRest, 26	GPS::Earth, 14
maxRateOfAscent, 26	metres
maxRateOfDescent, 26	GPS. 10
maxSpeed, 26	minElevation
restingTime, 26	GPS::Route, 22
setGranularity, 26	minGradient
totalTime, 26	
Track, 25	GPS::Route, 22
travellingTime, 27	minLatitude
gpx-tests.cpp, 30	GPS::Route, 22
	minLongitude
BOOST_TEST_DYN_LINK, 31	GPS::Route, 22
BOOST_TEST_MODULE, 31	
GPXRoutesDir	name
GPS::LogFiles, 15	GPS::Route, 22
GPXTracksDir	netHeightGain
GPS::LogFiles, 15	GPS::Route, 22

INDEX 53

netLength	radians
GPS::Route, 22	GPS, 10
NMEA, 15	radToDeg
extractSentenceData, 16	GPS, 11
hasValidChecksum, 16	restingTime
isWellFormedSentence, 16	GPS::Track, 26
positionFromSentenceData, 16	rmcPos
Route, 15	nmea-tests.cpp, 43
routeFromLog, 16	Route
SentenceData, 16	GPS::Route, 20
nmea-tests.cpp, 32	NMEA, 15
BOOST_AUTO_TEST_CASE, 34-43	route.cpp, 46
BOOST TEST DYN LINK, 34	route.h, 46
BOOST_TEST_MODULE, 34	routeFromLog
epsilon, 43	NMEA, 16
gllPos, 43	routeLength
percentageAccuracy, 43	GPS::Route, 24
rmcPos, 43	routeName
validGLLSentence, 43	GPS::Route, 24
validMSSSentence, 44	,
validRMCSentence, 44	seconds
NMEALogsDir	GPS, 10
GPS::LogFiles, 15	SentenceData
normaliseDeg	NMEA, 16
_	setGranularity
GPS, 11	GPS::Route, 23
NorthPole	GPS::Track, 26
GPS::Earth, 14	sinSgr
numPositions	GPS, 11
GPS::Route, 23	speed
	GPS, 11
operator()	steepestGradient
boost::test_tools::tt_detail::print_log_value<	GPS::Route, 23
std::vector< std::string >>, 19	ar omredie, 20
operator[]	timesVisited
GPS::Route, 23	GPS::Route, 23
	timesVisited(string).cpp, 46
parseNMEA.cpp, 44	BOOST_AUTO_TEST_CASE, 47, 48
parseNMEA.h, 44	isFileName, 49
percentageAccuracy	toString
nmea-tests.cpp, 43	GPS::Position, 18
pi	totalHeightGain
GPS, 12	GPS::Route, 23
polarCircumference	totalLength
GPS::Earth, 14	GPS::Route, 24
poleLatitude	totalTime
GPS, 12	GPS::Track, 26
Pontianak	Track
GPS::Earth, 14	
Position	GPS::Track, 25
GPS::Position, 17, 18	track.cpp, 49
position.cpp, 45	track.h, 49
position.h, 45	travellingTime
positionFromSentenceData	GPS::Track, 27
NMEA, 16	types.h, 50
	validCLL Contana
positionNames  CRS::Pouto 24	validGLLSentence
GPS::Route, 24	nmea-tests.cpp, 43
positions GPS::Route, 24	validMSSSentence
	nmea-tests.cpp, 44

54 INDEX

validRMCSentence nmea-tests.cpp, 44