

Ali Anwar

<https://aanwar.netlify.com>
ali_anwar@outlook.com | +86-130-4514-9035

EDUCATION

HARBIN INST. OF TECH.

PHD IN CONTROL ENGINEERING
 Expected Dec. 2019 | Harbin, CN

MENG IN CONTROL ENGINEERING

Sept. 2013 - Jul. 2015 | Harbin, CN
 Concentration. in Control Sc. & Engg.
 School of Astronautics

NATIONAL UNIV. OF SCIENCES & TECHNOLOGY

BENG IN ELECTRONICS

ENGINEERING

Nov. 2008 - Jul. 2012 | Islamabad, Pakistan
 School of EE & CS

LINKS

Github:// [denoza](#)
 LinkedIn:// [alianwar1](#)
 ResearchGate:// [ali_anwar9](#)
 Skype: eli.enwer89
 Wechat: ali_anwar

SKILLS

PROGRAMMING

Over 5000 lines:

C++ • Matlab • \LaTeX • Python

Over 1000 lines:

C • Assembly • Ansible

Proficient:

Linux • GCC • CMake • SHELL

Libraries

OpenCV • Caffe • PCL • Keras • ViSP •

Pytorch

LANGUAGES

Fluency

English • Urdu\Hindi

Limited Working Proficiency

Mandarin • German

HARDWARE

Efort/Kuka/Universal Industrial

Manipulator • Basler Industrial Cameras

• Microsoft Kinect

EXPERIENCE

TRADEKEY (PVT). LTD | PROJECT MANAGEMENT EXECUTIVE

Jan. 2013 - Sept. 2013 | Karachi, Pakistan

- JD included Strategic Plans, Quarterly/Bi-Annual/Annual Closeouts, Support in QMS Audit, Monitoring and Control for VIP-SD Team, Standards and Documentation, Training and Development Plan for VIP-SD Associates, Process and Functional Development

RESEARCH

RESEARCH INST. OF INTELLIGENT SYSTEMS AND CONTROL, HARBIN INST. OF TECH. | PHD SCHOLAR

Sept. 2015 - Present | Harbin, CN

Worked in the research domain focused upon the visual servo control of industrial robots. Primary impact areas include computer programming of control algorithms and computer vision, design of state of the art robotics perception algorithms, and study of new ways to optimize the performance of visual servo control.

HARBIN INST. OF TECH. AEROSPACE CENTER | POST-GRADUATE RESEARCHER

Sept. 2013 - Jul. 2015 | Harbin, CN

Investigated the nonlinearities affecting the system's control signal at the input. All of the major nonlinearities were covered including, backlash, dead-zone and input saturation. Their effects upon the attitude dynamics of rigid spacecrafts were studied and nonlinear control algorithms were designed for their mitigation.

SELECTED PUBLICATIONS

- **Anwar. A.**, Lin. W et al. "Quality Inspection of Remote Radio Units using Depth-free Image based Visual Servo with Acceleration Command", IEEE Transactions of Industrial Electronics 66 (10), 8214-8223
- Lin. W, **Anwar. A** et al. "Recognition and Pose Estimation of auto-parts for a spray painting robot", IEEE Transactions of Industrial Informatics 15 (3), 1709-1719
- **Anwar. A.**, Lin. W et al. "Position based Visual Servoing in Joint Space with Deep Neural Networks", IEEE Transactions of Systems, Man and Cybernetics: Systems (*Under Peer Review*)
- **Anwar. A.**, Lin. W et al. "Remote Radio Unit Power Port Tracking using Computer Vision", IECON 2017 - 43rd Annual Conference of the IEEE Industrial Electronics Society, Beijing, 3352-3357
- **Anwar. A.**, Deng. X et al. "Quality Inspection of Remote Radio Unit (RRU) Power Port Using IBVS", 2018 IEEE Canadian Conference on Electrical & Computer Engineering (CCECE), 1-4

AWARDS

2015	Fully Funded PhD Scholarship	Harbin Inst. of Tech. (HIT)
2015	Top International Student	School of Astronautics, HIT
2013	Fully Funded PG Scholarship	Harbin Inst. of Tech.
2008	National ICT Scholar	National University of Sciences & Technology

CERTIFICATIONS

- IELTS: 8.0 / 9.0
- Certified Associate of PLC and SCADA
- 2017 Summer School on Intelligent Robotics, Harbin Inst. of Tech.

