Elasticity2DSingleNetwork_with_predefined_Learning_parameters_epochsize_2000_definedstiffness_matrix

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# Elasticity2DSingleNetwork.ipynb......
import numpy as np
import tensorflow as tf
import matplotlib.pyplot as plt
lamb = 1
mu = 0.5
lamb2mu=lamb+2*mu
# Define the Neural Network for solving the PDE
class SimplePINN(tf.keras.Model):
       def __init__(self, layer_sizes):
              super(SimplePINN, self).__init__()
              self.hidden_layers = [tf.keras.layers.Dense(size, activation='tanh') for size in layer_sizes[:-1]]
              self.output_layer = tf.keras.layers.Dense(layer_sizes[-1])
       def call(self, x):
              for layer in self.hidden_layers:
                     x = layer(x)
               return self.output_layer(x)
def stiffness_matrix(lamb, mu, case="plane_strain"):
       # Compute the stiffness matrix for plane stress and plane strain conditions.
       # Parameters:
                  E (float): Young's modulus
                  nu (float): Poisson's ratio
                 case (str): "plane_stress" or "plane_strain"
       # Returns:
                 tf.Tensor: 3x3 stiffness matrix
       lamb = tf.convert_to_tensor(lamb, dtype=tf.float32)
       mu = tf.convert_to_tensor(mu, dtype=tf.float32)
       if case == "plane stress":
              \# C11 = lamb / (1 - nu**2)
              # C12 = nu * C11
              \# C66 = E / (2 * (1 + nu))
              raise ValueError("Invalid case: Choose 'plane_stress' or 'plane_strain'")
       elif case == "plane_strain":
              C11 = lamb + 2*mu
              C12 = lamb
              C66 = mu
       else:
              raise ValueError("Invalid case: Choose 'plane_stress' or 'plane_strain'")
       C = tf.stack([
              [C11, C12, 0],
              [C12, C11, 0],
              [0, 0, C66]
       ])
       return C
def body_force_fn(points, lamb, mu, Q):
       x=points[:,0:1]
       y=points[:,1:2]
       f0 = lamb * (4 * np.pi * 2 * tf.cos(2 * np.pi * x) * tf.sin(np.pi * y) - np.pi * tf.cos(np.pi * x) * Q * y**3) + mu * (9 * np.pi * 2
       f1 = lamb * (-3 * tf.sin(np.pi * x) * Q * y**2 + 2 * (np.pi**2) * tf.sin(2 * np.pi * x) * tf.cos(np.pi * y)) + mu * (-6 * tf.sin(np.pi * x)) + mu * (-6 * tf
       return tf.stack(tf.stack([tf.reshape(f0,[-1]), tf.reshape(f1,[-1])],axis=1))
       # return tf.stack((tf.stack([tf.reshape(f0,[-1]), tf.reshape(f1,[-1])],axis=1)) # Dedented this line by one level
       # return tf.stack([tf.reshape(f0, [-1]), tf.reshape(f1, [-1])], axis=1)
# Function to compute PDE residual
def compute_pde_residual(model, points, StiffMat, lamb, mu, Q, body_force_fn):
       with tf.GradientTape(persistent=True) as outer_tape:
              outer_tape.watch(points)
              with tf.GradientTape(persistent=True) as inner_tape:
                      inner_tape.watch(points)
                      predicted_uv = model(points)
                      predicted_u=predicted_uv[:,0:1]
                      predicted_v=predicted_uv[:,1:2]
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grad_u = inner_tape.gradient(predicted_u, points)
            grad_v = inner_tape.gradient(predicted_v, points)
            Sxx = StiffMat[0,0] * grad_u[:,0:1] + StiffMat[0,1] * grad_v[:,1:2]
            Syy = StiffMat[1,0] * grad_u[:,0:1] + StiffMat[1,1] * grad_v[:,1:2]
            Sxy = StiffMat[2,2] * (grad_u[:,1:2] + grad_v[:,0:1])
      Sxx_x = outer_tape.gradient(Sxx, points)[:,0]
      Syy_y = outer_tape.gradient(Syy, points)[:,1]
      grad_Sxy = outer_tape.gradient(Sxy, points)
      Sxy_x = grad_Sxy[:,0]
      Sxy_y = grad_Sxy[:,1]
      del inner_tape, outer_tape
      body_force = body_force_fn(points, lamb, mu, Q)
      \label{eq:continuous} residue = tf.stack([Sxx\_x + Sxy\_y + body\_force[:,0], Sxy\_x + Syy\_y + body\_force[:,1]], \ axis=1)
      return residue
# Total loss function
def compute_total_loss(model, points, left, right, bottom, top, StiffMat, lamb, mu, Q, body_force_fn):
      residue = compute_pde_residual(model, points, StiffMat, lamb, mu, Q, body_force_fn)
      pde_loss = tf.reduce_mean(tf.square(residue[:,0:1])) + tf.reduce_mean(tf.square(residue[:,1:2]))
      with tf.GradientTape(persistent=True) as inner_tape:
         inner_tape.watch(left)
         predicted_uv = model(left)
         predicted_u=predicted_uv[:,0:1]
         predicted_v=predicted_uv[:,1:2]
      grad_u = inner_tape.gradient(predicted_u, left)
      grad_v = inner_tape.gradient(predicted_v, left)
      del inner_tape
      Sxx = StiffMat[0,0] * grad_u[:,0:1] + StiffMat[0,1] * grad_v[:,1:2]
      left_boundary_loss = tf.reduce_mean(tf.square(predicted_v))+tf.reduce_mean(tf.square(Sxx))
      with tf.GradientTape(persistent=True) as inner_tape:
         inner_tape.watch(right)
         predicted_uv = model(right)
         predicted_u=predicted_uv[:,0:1]
         predicted_v=predicted_uv[:,1:2]
      grad_u = inner_tape.gradient(predicted_u, right)
      grad_v = inner_tape.gradient(predicted_v, right)
      del inner tape
      \label{eq:sxx}  \text{Sxx} = \text{StiffMat[0,0]} * \text{grad\_u[:,0:1]} + \text{StiffMat[0,1]} * \text{grad\_v[:,1:2]} 
      right_boundary_loss = tf.reduce_mean(tf.square(predicted_v))+tf.reduce_mean(tf.square(Sxx))
      bottom_boundary_loss = tf.reduce_mean(tf.square(model(bottom)[:,0:1]))+tf.reduce_mean(tf.square(model(bottom)[:,1:2]))
      with tf.GradientTape(persistent=True) as inner tape:
         inner_tape.watch(top)
         predicted_uv = model(top)
         predicted_u=predicted_uv[:,0:1]
         predicted_v=predicted_uv[:,1:2]
      grad_u = inner_tape.gradient(predicted_u, top)
      grad_v = inner_tape.gradient(predicted_v, top)
      del inner_tape
      Syy = StiffMat[1,0] * grad\_u[:,0:1] + StiffMat[1,1] * grad\_v[:,1:2]
      top\_boundary\_loss = tf.reduce\_mean(tf.square(predicted\_u)) + tf.reduce\_mean(tf.square(Syy-(lamb+2*mu)*Q*tf.sin(np.pi*top[:,0:1]))) + tf.reduce\_mean(tf.square(Syy-(lamb+2*mu)*Q*tf.sin(np.pi*top[:,0:1])) + tf.reduce\_mean(tf.square(Syy-(lamb+2*mu)*Q*tf.sin(np.pi*
      return pde_loss + left_boundary_loss + right_boundary_loss + top_boundary_loss + bottom_boundary_loss
# Problem setup
num collocation points = 50
x_points, y_points = tf.meshgrid(tf.linspace(0.0, 1.0, num_collocation_points), tf.linspace(0.0, 1.0, num_collocation_points), indexing="
points=tf.stack([tf.reshape(x\_points, \ [-1]), \ tf.reshape(y\_points, \ [-1])], \ axis=1)
x\_left, \ y\_left = tf.meshgrid(tf.linspace(0.0, \ 0.0, \ 1), \ tf.linspace(0.0, \ 1.0, \ num\_collocation\_points), \ indexing="ij")
left=tf.stack([tf.reshape(x_left, [-1]), tf.reshape(y_left, [-1])], axis=1)
x_right, y_right = tf.meshgrid(tf.linspace(1.0, 1.0, 1), tf.linspace(0.0, 1.0, num_collocation_points), indexing="ij")
right=tf.stack([tf.reshape(x_right, [-1]), tf.reshape(y_right, [-1])], axis=1)
 x\_top, \ y\_top = tf.meshgrid(tf.linspace(0.0, \ 1.0, \ num\_collocation\_points), \ tf.linspace(1.0, \ 1.0, \ 1), \ indexing="ij") 
top=tf.stack([tf.reshape(x_top, [-1]), tf.reshape(y_top, [-1])], axis=1)
 x\_bottom, \ y\_bottom = tf.meshgrid(tf.linspace(0.0, 1.0, num\_collocation\_points), \ tf.linspace(0.0, 0.0, 1), \ indexing="ij") 
bottom=tf.stack([tf.reshape(x\_bottom, [-1]), tf.reshape(y\_bottom, [-1])], \ axis=1)
\# lamb = 1
# mu = 0.5
# lamb2mu=lamb+2*mu
case2D="plane_strain"
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StiffMat=stiffness_matrix(lamb, mu, case2D)
model = SimplePINN(layer_sizes)
optimizer = tf.keras.optimizers.Adam(learning_rate=0.001)
# Training loop
num epochs = 2000
tolerance = 1e-6
previous_loss = float('inf')
for epoch in range(num_epochs):
    with tf.GradientTape() as tape:
       loss = compute_total_loss(model, points, left, right, bottom, top, StiffMat, lamb, mu, Q, body_force_fn)
    gradients = tape.gradient(loss, model.trainable_variables)
    optimizer.apply_gradients(zip(gradients, model.trainable_variables))
    if epoch % 50 == 0:
       print(f"Epoch {epoch}, Loss: {loss.numpy()}")
       if abs(previous_loss - loss.numpy()) < tolerance:</pre>
           print(f"Converged at epoch {epoch}, Loss: {loss.numpy()}")
           break
       previous_loss = loss.numpy()
# Predictions and analytical solution
num_collocation_points = 100
x_points, y_points = tf.meshgrid(tf.linspace(0.0, 1.0, num_collocation_points), tf.linspace(0.0, 1.0, num_collocation_points), indexing="
test_points=tf.stack([tf.reshape(x_points, [-1]), tf.reshape(y_points, [-1])], axis=1)
predicted uv = model(test points)
analy_u = tf.cos(2*np.pi*test_points[:,0:1])*tf.sin(np.pi*test_points[:,1:2])
analy_v = tf.sin(np.pi*test_points[:,0:1])*Q*test_points[:,1:2]*4/4
predicted\_u = \texttt{tf.reshape}(predicted\_uv[:, \emptyset:1], \ (num\_collocation\_points, \ num\_collocation\_points)). numpy()
predicted_v = tf.reshape(predicted_uv[:,1:2], (num_collocation_points, num_collocation_points)).numpy()
analy_u = tf.reshape(analy_u, (num_collocation_points, num_collocation_points)).numpy()
analy_v = tf.reshape(analy_v, (num_collocation_points, num_collocation_points)).numpy()
# Convert grid points to NumPy for plotting
x points = x points.numpy()
y_points = y_points.numpy()
# Plot contour for u
plt.figure(figsize=(12, 5))
plt.subplot(2, 2, 1)
plt.contourf(x_points, y_points, predicted_u, levels=50, cmap="jet")
plt.colorbar(label="Displacement u")
plt.xlabel("x")
plt.ylabel("y")
plt.title("Contour Plot of u")
# Plot contour for v
plt.subplot(2, 2, 2)
plt.contourf(x_points, y_points, predicted_v, levels=50, cmap="jet")
plt.colorbar(label="Displacement v")
plt.xlabel("x")
plt.ylabel("y")
plt.title("Contour Plot of v")
# Plot contour for u
plt.subplot(2, 2, 3)
plt.contourf(x_points, y_points, analy_u, levels=50, cmap="jet")
plt.colorbar(label="Displacement u")
plt.xlabel("x")
plt.ylabel("y")
plt.title("Contour Plot of u")
\# Plot contour for v
plt.subplot(2, 2, 4)
plt.contourf(x_points, y_points, analy_v, levels=50, cmap="jet")
plt.colorbar(label="Displacement v")
plt.xlabel("x")
plt.ylabel("y")
plt.title("Contour Plot of v")
plt.tight_layout()
plt.show()
```

Epoch 100, Loss: 31.1301212310791

Epoch 150, Loss: 6.93492317199707

Epoch 200, Loss: 3.764542818069458 Epoch 250, Loss: 9.972660064697266

Epoch 300, Loss: 2.425288677215576 Epoch 350, Loss: 2.0470805168151855

Epoch 400, Loss: 1.874656319618225

Epoch 400, Loss: 1.874656319618225 Epoch 450, Loss: 1.6459819078445435

Epoch 500, Loss: 18.886882781982422

Epoch 550, Loss: 1.4802024364471436 Epoch 600, Loss: 1.3139303922653198

Epoch 650, Loss: 1.3139303922653198 Epoch 650, Loss: 1.3346936702728271

Epoch 700, Loss: 1.3130624294281006

Epoch 750, Loss: 1.3003398180007935 Epoch 800, Loss: 6.311061859130859

Epoch 800, Loss: 6.311061859130859 Epoch 850, Loss: 0.947367787361145

Epoch 900, Loss: 4.044435977935791

Epoch 950, Loss: 0.8189219236373901

Epoch 1000, Loss: 0.9208244681358337

Epoch 1050, Loss: 0.8142282962799072

Epoch 1100, Loss: 0.7176125645637512

Epoch 1150, Loss: 5.696923732757568 Epoch 1200, Loss: 0.6756508350372314

Epoch 1250, Loss: 1.9389762878417969

Epoch 1300, Loss: 0.6683669686317444

Epoch 1350, Loss: 0.6044776439666748

Epoch 1400, Loss: 8.434494972229004

Epoch 1450, Loss: 0.7129753232002258 Epoch 1500, Loss: 0.5505603551864624

Epoch 1500, Loss: 0.5505603551864624 Epoch 1550, Loss: 0.8428434133529663

Epoch 1600, Loss: 0.707373321056366 Epoch 1650, Loss: 0.5056918263435364

Epoch 1700, Loss: 0.5436434149742126

Epoch 1750, Loss: 0.47828546166419983 Epoch 1800, Loss: 1.0008797645568848

Epoch 1850, Loss: 0.46900495886802673 Epoch 1900, Loss: 0.9447423815727234

Epoch 1950, Loss: 1.316414713859558

