

# Aaquib Tabrez

## Curriculum Vitae

PhD Student / Research Assistant  
University of Colorado Boulder  
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Updated: Sept 2023

### Research Interests

I work at the intersection of explainability and human-robot interaction. In my research, I leverage and enhance human-machine communication to achieve value alignment and foster appropriate trust within human-robot teams. My broad interests include Explainable AI, Reinforcement Learning, Multimodal Human-Machine Communication, and Human-AI Interaction.

### Education

- 2019 – 2024 **University of Colorado, Boulder**, GPA: 4.0, Ph.D. Student, *Computer Science*.  
(expected) Advisor: Bradley Hayes
- 2017–2019 **University of Colorado, Boulder**, GPA: 4.0, MS, *Mechanical Engineering*.
- 2010–2014 **National Institute of Technology Karnataka, India**, B.Tech, *Mechanical Engineering*.

### Awards and Recognition

- 2023 **Doctoral Consortium at AAMAS-2023**.  
Selected for a workshop aimed at top early-career researchers in the field of Multi-agent systems.
- 2023 **Annual Research Expo'23 Poster Presentation Award**.  
Received best research poster presentation award at the Annual Research Expo '23.
- 2022 **Robotics: Science and Systems (RSS) Pioneers**.  
Selected for workshop bringing together top early career researchers in robotics.
- 2022 **Best Student Paper Award Runner-up at AAMAS**.  
For the paper "Descriptive and Prescriptive Visual Guidance to Improve Shared Situational Awareness in Human-Robot Teaming".
- 2022 **Won Spring 2022 Annual Research Expo Event**.  
Received the best poster presentation award at the Spring 2022 Annual Research Expo from CU Boulder.
- 2020 **IBM PhD Fellowship Finalist**.  
One of three students nominated by the CS department at CU Boulder.
- 2019 **Best Paper Award Finalist for Technical Advances at ACM/IEEE HRI**.  
For the paper "Explanation-based Reward Coaching to Improve Human Performance via Reinforcement Learning".
- 2019 **Human-Robot Interaction (HRI) Pioneers**.  
Selected for workshop bringing together top early career researchers in HRI.
- 2019 **Awatar and Teji Singh Graduate Fellowship**.  
A \$5,000 fellowship for early career PhD students demonstrating a strong academic and research record.
- 2016 **Yuva Prerna Yatra Fellowship**.  
Selected as a social entrepreneur fellow to travel, study, and support local entrepreneurs in the Himalayas, leveraging regional resources to foster prosperity.

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## Papers in Submission

[paper link](#) **One-shot Policy Elicitation via Semantic Reward Manipulation.**

**Aaquib Tabrez**, Ryan Leonard, Bradley Hayes.

*In submission: Frontiers in Robotics and AI*

[no paper link](#) **Title omitted for blind review.**

Matthew B. Luebbers\*, **Aaquib Tabrez\***, Kanaka Samagna Talanki, Bradley Hayes.

*In submission: IEEE International Conference on Robotics and Automation (ICRA), 2024*

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## Journal Articles

[paper link](#) **A survey of Mental Modeling Techniques in Human-Robot Teaming.**

**Aaquib Tabrez**, Matthew B. Luebbers, Bradley Hayes.

*Springer-Nature Current Robotics Reports, 2020*

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## Conference Publications

Asterisk (\*) denotes shared first authorship

[paper link](#) **Autonomous Justification for Enabling Explainable Decision Support in Human-Robot Teaming.**

**Aaquib Tabrez\***, Matthew B. Luebbers\*, Kyler Ruvane\*, and Bradley Hayes.

*Robotics: Science and Systems (RSS), 2023*

[paper link](#) **Descriptive and Prescriptive Visual Guidance to Improve Shared Situational Awareness in Human-Robot Teaming.**

**Aaquib Tabrez\***, Matthew B. Luebbers\*, Bradley Hayes.

*International Conference on Autonomous Agents and Multiagent Systems (AAMAS), 2022*

*Best Student Paper Runner-up (Top 2 of 629 submissions).*

[paper link](#) **Asking the Right Questions: Facilitating Semantic Constraint Specification for Robot Skill Learning and Repair.**

**Aaquib Tabrez\***, Jack Kawell\*, Bradley Hayes.

*IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2021*

[paper link](#) **Explanation-based Reward Coaching to Improve Human Performance via Reinforcement Learning.**

**Aaquib Tabrez**, Shivendra Agrawal, Bradley Hayes.

*ACM/IEEE International Conference on Human Robot Interaction (HRI), 2019*

*Best Technical Paper Runner-up.*

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## Workshop Publications

[paper link](#) **Effective Human-Machine Teaming through Communicative Autonomous Agents that Explain, Coach, and Convince.**

**Aaquib Tabrez**, Bradley Hayes.

*Doctoral Consortium at International Conference on Autonomous Agents and Multiagent Systems, 2023*

[paper link](#) **Augmented Reality and Proxy Grippers Improve Demonstration-based Robot Skill Learning.**

Carl L. Mueller, Matthew B. Luebbers, **Aaquib Tabrez**, and Bradley Hayes.

*Proceedings of the Workshop on Life-Long Learning with Human Help (L3H2), 2023*

[paper link](#) **Mediating Trust and Influence in Human-Robot Interaction via Explainable AI.**

**Aaquib Tabrez**, Bradley Hayes.

*Pioneers Workshop at Robotics: Science and Systems (RSS), 2022*

[paper link](#) **Augmented Reality-Based Explainable AI Strategies for Establishing Appropriate Reliance and Trust in Human-Robot Teaming.**

Matthew B. Luebbers\*, **Aaquib Tabrez\***, Bradley Hayes.

*Workshop on Virtual, Augmented and Mixed Reality for Human-Robot Interaction (VAM-HRI), 2022*

- [paper link](#) **Solutions for Socially Intelligent HRI in Real-World Scenarios (SSIR-HRI).**  
Karen Tatarian, Sera Buyukgoz, Marine Chamoux, **Aaquib Tabrez**, Bradley Hayes, Mohamed Chetouani.  
*Companion of the ACM/IEEE International Conference on Human-Robot Interaction, 2021*
- [paper link](#) **Interactive Constrained Learning from Demonstration Using Visual Robot Behavior Counterfactuals.**  
Carl Mueller, **Aaquib Tabrez**, Bradley Hayes  
*Workshop on Accessibility of Robot Programming and Work of the Future at RSS, 2021*
- [paper link](#) **Emerging Autonomy Solutions for Human and Robotic Deep Space Exploration.**  
Matthew B. Luebbbers\*, Christine T. Chang\*, **Aaquib Tabrez\***, Jordan Dixon\*, Bradley Hayes.  
*SpaceCHI: Human-Computer Interaction for Space Exploration, 2021*
- [paper link](#) **Automated Failure-Mode Clustering and Labeling for Informed Car-To-Driver Handover in Autonomous Vehicles.**  
**Aaquib Tabrez\***, Matthew B. Luebbbers\*, Bradley Hayes.  
*Workshop on Assessing, Explaining, and Conveying Robot Proficiency for Human-Robot Teaming, 2020*
- [paper link](#) **Improving human-robot interaction through explainable reinforcement learning.**  
**Aaquib Tabrez**, Bradley Hayes.  
*Companion of the ACM/IEEE International Conference on Human-Robot Interaction, 2019*

## Teaching & Research Assistantships

- Spring 2021 - Present **Army Research Lab [STRONG Program](#): Strengthening Teamwork for Robust Operations in Novel Groups**, *University of Colorado Boulder, CO.*  
Research Assistant, Prof. Bradley Hayes
- Fall 2020 **CSCI 5302/4302: Advanced Robotics**, *University of Colorado Boulder, CO.*  
Teaching Assistant, Prof. Bradley Hayes
- Fall 2020 **CSCI 3302: Introduction to Robotics**, *University of Colorado Boulder, CO.*  
Teaching Assistant, Prof. Bradley Hayes
- Spring 2020 **CSCI 5922: Neural Networks and Deep Learning**, *University of Colorado Boulder, CO.*  
Teaching Assistant, Profs. Adam Bloniarz & Shumin Wu
- Fall 2019 **CSCI 3302: Introduction to Robotics**, *University of Colorado Boulder, CO.*  
Teaching Assistant, Prof. Bradley Hayes
- Spring 2019 **CSCI 5322: Algorithmic Human-Robot Interaction**, *University of Colorado Boulder, CO.*  
Course Grader, Prof. Bradley Hayes
- Spring 2018 **MCEN-4026: Manufacturing Processes and Systems**, *University of Colorado Boulder, CO.*  
Course Grader, Prof. Jenifer Blacklock

## Workshop Committee Leadership

- August 2023 **[Workshop on Human-Robot Interaction for Explainability in Robotics](#)**, *RO-MAN 2023.*  
Co-Organizer
- June 2023 **[RSS Pioneers 2023 Workshop](#)**, *RSS 2023.*  
Program Committee Chair
- March 2021 **[Solutions for socially intelligent HRI in real-world scenarios workshop](#)**, *HRI 2021.*  
Co-Organizer
- March 2021 **[HRI Pioneers 2021 Workshop](#)**, *HRI 2021.*  
Program Chair
- August 2020 **[Solutions for socially intelligent HRI in real-world scenarios workshop](#)**, *RO-MAN 2020.*  
Co-Organizer
- March 2020 **[HRI Pioneers 2020 Workshop](#)**, *HRI 2020.*  
Program Chair

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## Professional Experience

- 2014 – 2016 **Daimler, Chennai, India.**  
Procurement Manager
- Aug 2012 – **Kudremukh Iron Ore Company, Kudremukh, India.**  
Dec 2012 Industrial Intern

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## Research Mentorship

- 2023 - **Nathan Howard, Masters, CU Boulder.**
- 2022 - 2023 **Kanaka Talanki Sreenivasa Murthy, Masters, CU Boulder.**
- 2021 - 2022 **Karthik Siddaramanna, Masters, CU Boulder.**
- 2020 - 2021 **Aditi Periyannan, Undergraduate, Tufts University.**
- 2019 **Felix Moses, Berkeley High School.**
- 2019 **Stephen Kwak, Bellarmine High School.**
- 2018 - 2019 **Xi Hu, Undergraduate, CU Boulder.**

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## Conference and Journal Review

IEEE Robotics and Automation Letters (RA-L)

ACM Transactions on Human-Robot Interaction (T-HRI)

International Journal of Human-Computer Interaction (IJHCI)

ACM/IEEE International Conference on Human-Robot Interaction (HRI)

IEEE International Conference on Robotics and Automation (ICRA)

IEEE International Conference on Intelligent Robots and Systems (IROS)

CHI: Conference on Human Factors in Computing Systems (CHI)

IEEE International Conference on Robot and Human Interactive Communication (RO-MAN)

Explainable AI Planning Workshop (XAIP), ICAPS

Workshop on Explainable Artificial Intelligence (XAI), IJCAI

Companion of the Robotics: Science and Systems (RSS Pioneers)

Companion of the International Conference on Human-Robot Interaction (HRI Pioneers)

Late Breaking Reports at HRI