Aaquib Tabrez

Curriculum Vitae

PhD Candidate / Research Assistant
University of Colorado Boulder

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Research Interests

I work at the intersection of explainability and human-robot interaction. In my research, I leverage and enhance human-machine communication to achieve value alignment and foster appropriate trust within human-robot teams. My broad interests include Explainable AI, Reinforcement Learning, Multimodal Human-Machine Communication, and Human-Robot Interaction.

Education

2019 - 2024 University of Colorado, Boulder, GPA: 4.0, Ph.D. Candidate, Computer Science.

(expected) Advisor: Bradley Hayes

2017–2019 University of Colorado, Boulder, GPA: 4.0, MS, Mechanical Engineering.

2010–2014 National Institute of Technology Karnataka, India, B. Tech, Mechanical Engineering.

Awards and Recognition

2024 3MT Finalist.

Selected as a finalist in the 2024 CU Boulder Three Minute Thesis (3MT) competition.

2024 Doctoral Consortium at AAAI-2024.

Selected to present on "Autonomous Policy Explanations for Effective Human-Machine Teaming" at the AAAI-2024 Doctoral Consortium.

2023 **Doctoral Consortium at AAMAS-2023**.

Selected for a workshop aimed at top early-career researchers in the field of Multi-agent systems.

2023 Annual Research Expo'23 Poster Presentation Award.

Received best research poster presentation award at the CU Boulder's Annual Research Expo '23.

2022 Robotics: Science and Systems (RSS) Pioneers.

Selected for workshop bringing together top early career researchers in robotics.

2022 Best Student Paper Award Runner-up at AAMAS.

For the paper "Descriptive and Prescriptive Visual Guidance to Improve Shared Situational Awareness in Human-Robot Teaming".

2022 Won Spring 2022 Annual Research Expo Event.

Received the best poster presentation award at the Spring 2022 Annual Research Expo from CU Boulder.

2020 IBM PhD Fellowship Finalist.

One of three students nominated by the CS department at CU Boulder.

2019 Best Paper Award Finalist for Technical Advances at ACM/IEEE HRI.

For the paper "Explanation-based Reward Coaching to Improve Human Performance via Reinforcement Learning".

2019 Human-Robot Interaction (HRI) Pioneers.

Selected for workshop bringing together top early career researchers in HRI.

2019 Awtar and Teji Singh Graduate Fellowship.

A \$5,000 fellowship for early career PhD students demonstrating a strong academic and research record.

2016 Yuva Prerna Yatra Fellowship.

Selected as a social entrepreneur fellow to travel, study, and support local entrepreneurs in the Himalayas, leveraging regional resources to foster prosperity.

Papers in Submission

Asterisk (*) denotes shared first authorship

no paper link Title omitted for blind review.

Aaquib Tabrez, Ryan Leonard, Bradley Hayes.

In submission: Robotics: Science and Systems (RSS), 2024

no paper link Title omitted for blind review.

Matthew B. Luebbers*, **Aaquib Tabrez***, Kanaka Samagna Talanki, Bradley Hayes. *In submission: IEEE International Conference on Robotics and Automation (ICRA), 2024*

Journal Articles

paper link A survey of Mental Modeling Techniques in Human-Robot Teaming.

Aaquib Tabrez, Matthew B. Luebbers, Bradley Hayes. *Springer-Nature Current Robotics Reports*, 2020

Conference Publications

paper link Autonomous Justification for Enabling Explainable Decision Support in Human-Robot Teaming.

Aaquib Tabrez*, Matthew B. Luebbers*, Kyler Ruvane*, and Bradley Hayes.

Robotics: Science and Systems (RSS), 2023

paper link Descriptive and Prescriptive Visual Guidance to Improve Shared Situational Awareness in Human-Robot Teaming.

Aaquib Tabrez*, Matthew B. Luebbers*, Bradley Hayes.

International Conference on Autonomous Agents and Multiagent Systems (AAMAS), 2022

Best Student Paper Runner-up (Top 2 of 629 submissions).

paper link Asking the Right Questions: Facilitating Semantic Constraint Specification for Robot Skill Learning and Repair.

Aaquib Tabrez*, Jack Kawell*, Bradley Hayes.

IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2021

paper link Explanation-based Reward Coaching to Improve Human Performance via Reinforcement Learning.

Aaquib Tabrez, Shivendra Agrawal, Bradley Hayes.

ACM/IEEE International Conference on Human Robot Interaction (HRI), 2019

Best Technical Paper Runner-up.

Workshop Publications

paper link Autonomous Policy Explanations for Effective Human-Machine Teaming.

Aaguib Tabrez.

Doctoral Consortium at the AAAI Conference on Artificial Intelligence, 2024

paper link Effective Human-Machine Teaming through Communicative Autonomous Agents that Explain, Coach, and Convince.

Aaquib Tabrez

Doctoral Consortium at the International Conference on Autonomous Agents and Multiagent Systems, 2023

paper link Augmented Reality and Proxy Grippers Improve Demonstration-based Robot Skill Learning.

Carl L. Mueller, Matthew B. Luebbers, **Aaquib Tabrez**, and Bradley Hayes.

Proceedings of the Workshop on Life-Long Learning with Human Help (L3H2), 2023

paper link Mediating Trust and Influence in Human-Robot Interaction via Explainable AI.

Aaguib Tabrez, Bradley Hayes.

Pioneers Workshop at Robotics: Science and Systems (RSS), 2022

paper link Augmented Reality-Based Explainable AI Strategies for Establishing Appropriate Reliance and Trust in Human-Robot Teaming.

Matthew B. Luebbers*, Aaquib Tabrez*, Bradley Hayes.

Workshop on Virtual, Augmented and Mixed Reality for Human-Robot Interaction (VAM-HRI), 2022

paper link Solutions for Socially Intelligent HRI in Real-World Scenarios (SSIR-HRI).

Karen Tatarian, Sera Buyukgoz, Marine Chamoux, **Aaquib Tabrez**, Bradley Hayes, Mohamed Chetouani. *Companion of the ACM/IEEE International Conference on Human-Robot Interaction, 2021*

paper link Interactive Constrained Learning from Demonstration Using Visual Robot Behavior Counterfactuals.

Carl Mueller, Aaquib Tabrez, Bradley Hayes

Workshop on Accessibility of Robot Programming and Work of the Future at RSS, 2021

paper link Emerging Autonomy Solutions for Human and Robotic Deep Space Exploration.

Matthew B. Luebbers*, Christine T. Chang*, Aaquib Tabrez*, Jordan Dixon*, Bradley Hayes.

SpaceCHI: Human-Computer Interaction for Space Exploration, 2021

paper link Automated Failure-Mode Clustering and Labeling for Informed Car-To-Driver Handover in Autonomous Vehicles.

Aaquib Tabrez*, Matthew B. Luebbers*, Bradley Hayes.

Workshop on Assessing, Explaining, and Conveying Robot Proficiency for Human-Robot Teaming, 2020

paper link Improving human-robot interaction through explainable reinforcement learning.

Aaquib Tabrez, Bradley Hayes.

Companion of the ACM/IEEE International Conference on Human-Robot Interaction, 2019

Teaching & Research Assistantships

Spring 2021 - Army Research Lab STRONG Program: Strengthening Teamwork for Robust Operations
Present in Novel Groups, University of Colorado Boulder, CO.

Research Assistant, Prof. Bradley Hayes

Fall 2020 **CSCI 5302/4302: Advanced Robotics**, *University of Colorado Boulder, CO.* **Teaching Assistant**, Prof. Bradley Hayes

Fall 2020 **CSCI 3302: Introduction to Robotics**, *University of Colorado Boulder, CO.* **Teaching Assistant**, Prof. Bradley Hayes

Spring 2020 **CSCI 5922: Neural Networks and Deep Learning**, *University of Colorado Boulder, CO.* **Teaching Assistant**, Profs. Adam Bloniarz & Shumin Wu

Fall 2019 **CSCI 3302: Introduction to Robotics**, *University of Colorado Boulder, CO.* **Teaching Assistant**, Prof. Bradley Hayes

Spring 2019 CSCI 5322: Algorithmic Human-Robot Interaction, University of Colorado Boulder, CO. Course Grader, Prof. Bradley Hayes

Spring 2018 MCEN-4026: Manufacturing Processes and Systems, *University of Colorado Boulder, CO.*Course Grader, Prof. Jenifer Blacklock

Workshop Committee Leadership

August 2023 Workshop on Human-Robot Interaction for Explainability in Robotics, RO-MAN 2023.

Co-Organizer

June 2023 RSS Pioneers 2023 Workshop, RSS 2023.

Program Committee Chair

March 2021 Solutions for socially intelligent HRI in real-world scenarios workshop, HRI 2021.

Co-Organizer

March 2021 HRI Pioneers 2021 Workshop, HRI 2021. Program Chair

- August 2020 Solutions for socially intelligent HRI in real-world scenarios workshop, RO-MAN 2020.

 Co-Organizer
- March 2020 HRI Pioneers 2020 Workshop, HRI 2020.

Program Chair

Invited Panels and Talks

- 2023 **Talking Robotics**, Building Trust and Transparency through Explainable Multimodal Communication.
- 2021 **University of Colorado Boulder**, *Mediating Trust and Influence in Human-Robot Interaction via Explainable AI*, Robotics Summer Seminar Series.

Professional Experience

- 2014 2016 **Daimler**, Chennai, India.
 - Procurement Manager
- Aug 2012 Kudremukh Iron Ore Company, Kudremukh, India.
 - Dec 2012 Industrial Intern

Research Mentorship

- 2024 David Chaparro, Masters, CU Boulder.
- 2023 Kyler Ruvane, Masters, CU Boulder.
 - 2023 Nathan Howard, Masters, CU Boulder.
- 2022 2023 Kanaka Talanki Sreenivasa Murthy, Masters, CU Boulder.
- 2021 2022 Karthik Siddaramanna, Masters, CU Boulder.
- 2020 2021 Aditi Periyannan, Undergraduate, Tufts University.
 - 2019 Felix Moses, Berkeley High School.
 - 2019 Stephen Kwak, Bellarmine High School.
- 2018 2019 Xi Hu, Undergraduate, CU Boulder.

Conference and Journal Review

IEEE Robotics and Automation Letters (RA-L)

ACM Transactions on Human-Robot Interaction (T-HRI)

International Journal of Human-Computer Interaction (IJHCI)

ACM/IEEE International Conference on Human-Robot Interaction (HRI)

IEEE International Conference on Robotics and Automation (ICRA)

IEEE International Conference on Intelligent Robots and Systems (IROS)

CHI: Conference on Human Factors in Computing Systems (CHI)

IEEE International Conference on Robot and Human Interactive Communication (RO-MAN)

Explainable AI Planning Workshop (XAIP), ICAPS

Workshop on Explainable Artificial Intelligence (XAI), IJCAI

Companion of the Robotics: Science and Systems (RSS Pioneers)

Companion of the International Conference on Human-Robot Interaction (HRI Pioneers)

Late Breaking Reports at HRI