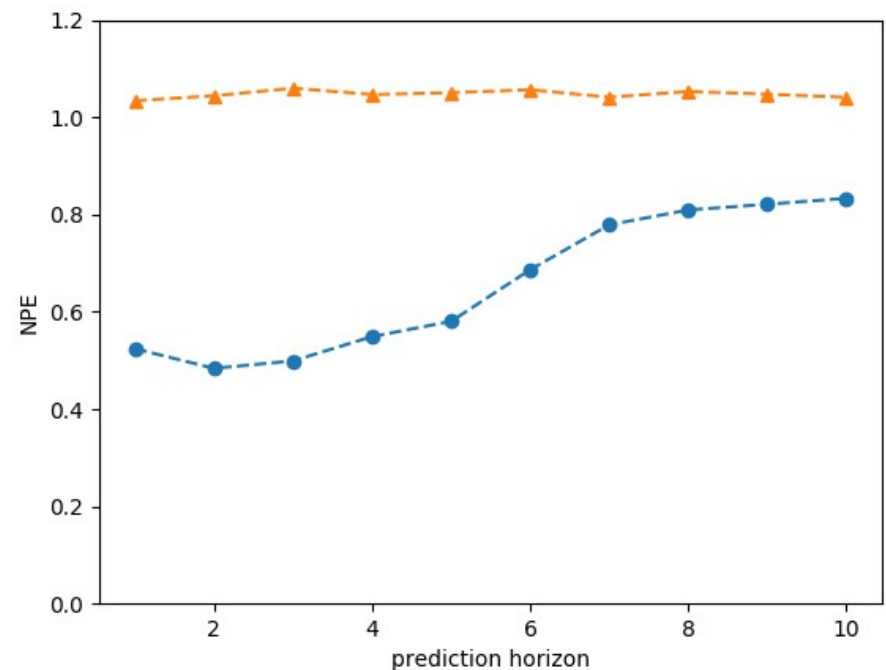
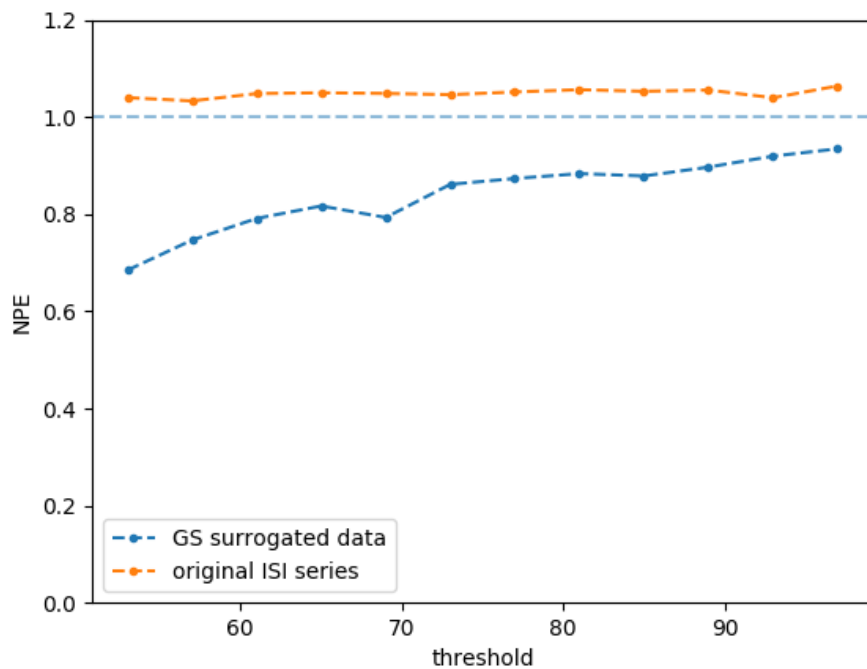


# Results II : Predictability

- Predictability assumption for NPE.
- Calcul of NPE : Gaussian shuffle & ISIs series
- Calcul of predictability limit: Gaussian shuffle & ISIs series



# Reconstruction of strange attractors via inter-spike intervals

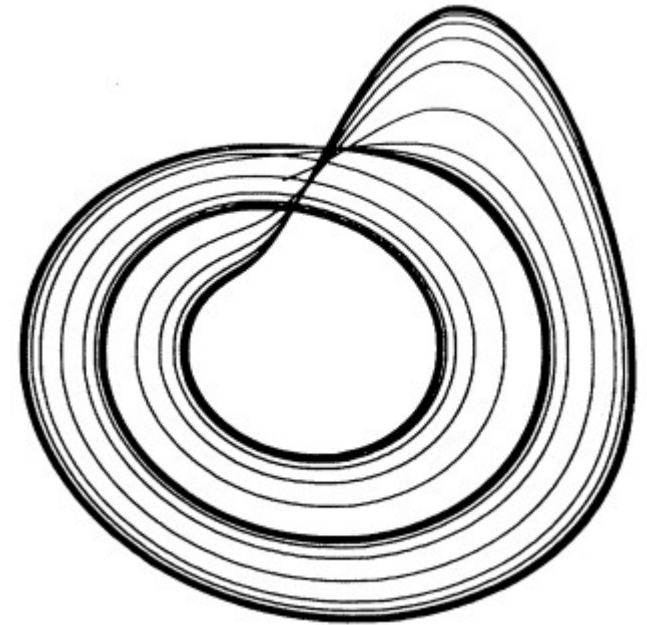
Àlex Arcas Cuerda &  
Ramón Marc García Seuma

# Index

- Geometry from a Time Series
- Reconstruction of Dynamical Systems from Interspike Intervals (ISI) I: Introduction
- Reconstruction of Dynamical Systems from Interspike Intervals (ISI) II: Concepts
- Results I : Topology
- Results II : Predictability
- Conclusions

# Geometry from a time series

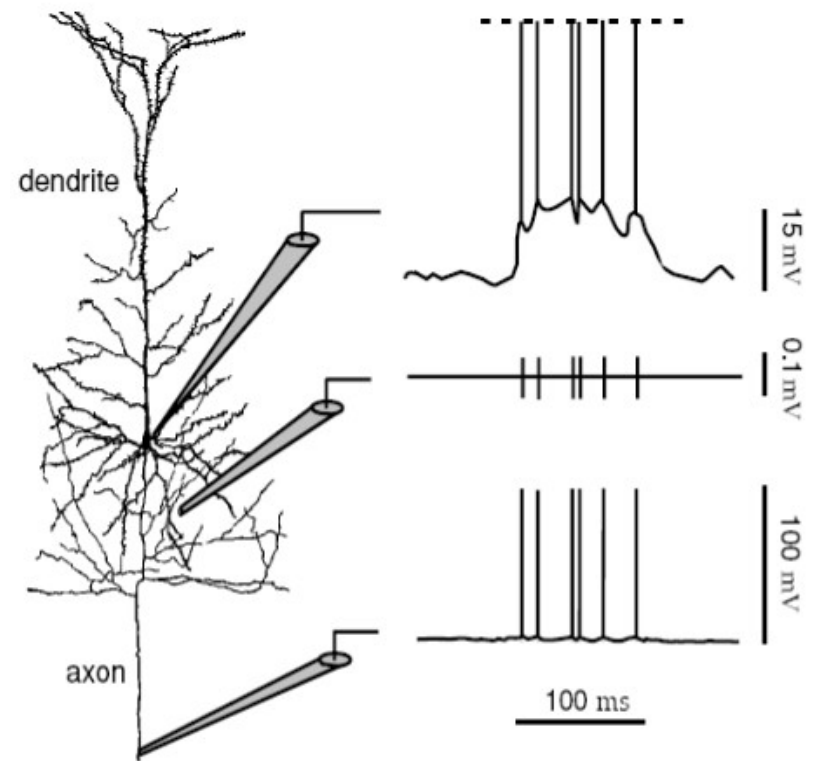
- Give insight into a dynamical system from a time series.
- Reconstruction of the topology.
- Characterization of the Liapunov exponent.
- Procedure to find the dimensionality.
- Some review.



	Characteristic exponent value
$(x, y, z)$ system [Eq. (1)]	$0.0677 \pm 0.0005$
$(y, \dot{y}, \ddot{y})$ system [Eq. (2)]	$0.0680 \pm 0.0005$
$(x, \dot{x})$ return map reconstruction	$0.0677 \pm 0.0001$

# Reconstruction of Dynamical Systems from ISI I : Introduction

- Takens's theorem for attractor reconstruction.
- Integrate-and-fire model: point process.
- Applications: noise filtering, prediction of chaotic series and control of unstable periodic orbits.



# Reconstruction of Dynamical Systems from ISI II: Concepts

- Create trajectories of a certain dynamics
- Select a signal  $S(t)$  and a threshold  $\Theta$  so to extract the firing times  $T_i$  with:

$$\int_{T_i}^{T_{i+1}} S(t) dt = \Theta.$$

- Define the Interspike Intervals as:  
 $t_i = T_i - T_{i-1}$

## Lorenz attractor

$$\frac{dx}{dt} = a(y - x)$$

$$\frac{dy}{dt} = x(b - z) - y$$

$$\frac{dz}{dt} = xy - cz$$

## Rössler attractor

$$\frac{dx}{dt} = -y - z$$

$$\frac{dy}{dt} = x + ay$$

$$\frac{dz}{dt} = b + z(x - c)$$

# Reconstruction of Dynamical Systems from ISI II: Concepts

- Vectors  $(t_i, t_{i-1}, \dots, t_{i-m+1})$  can be used to reconstruct the attractor.

*Takens's theorem:  $m > 2D_0$  is sufficient,  $m=3$*

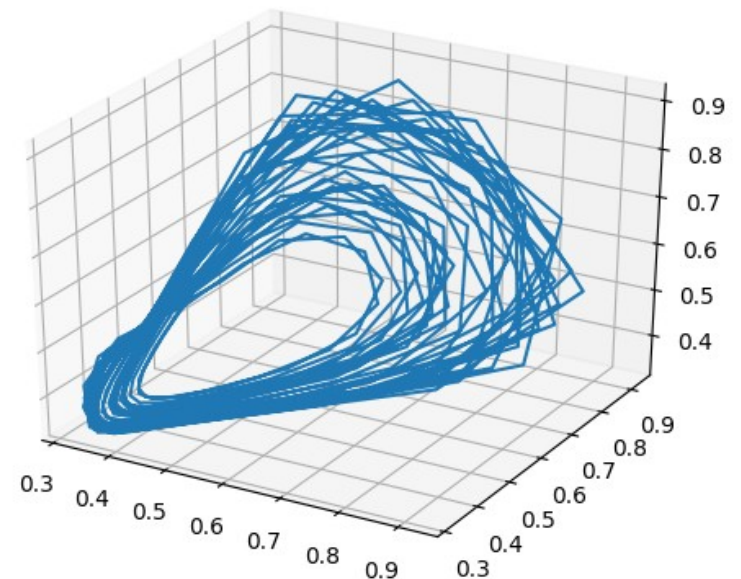
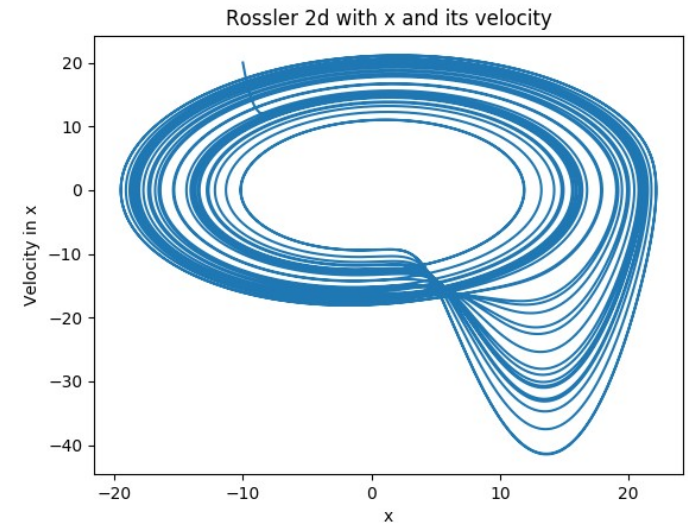
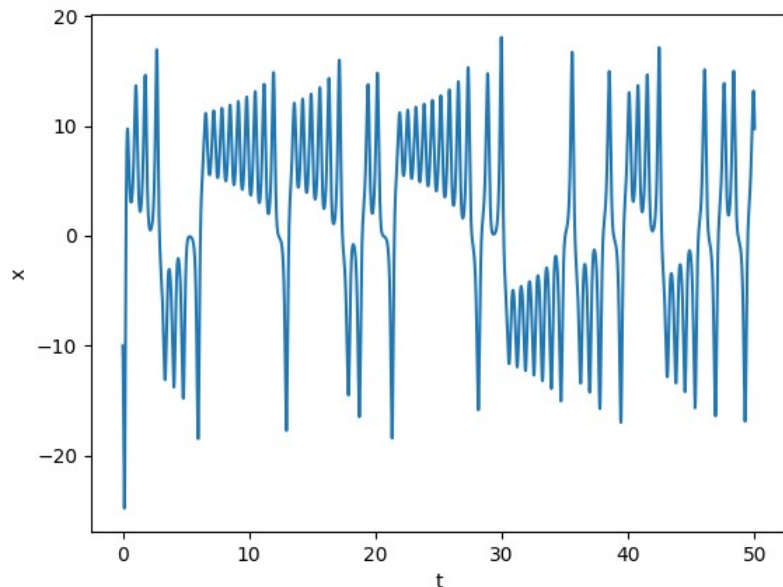
- Prediction algorithm: Determinism can be recognized in front of surrogate data using:

$$\text{NPE} = \frac{\langle (p_{i_0} - t_{i_0+h})^2 \rangle^{1/2}}{\langle (m - t_{i_0+h})^2 \rangle^{1/2}},$$



# Results I : Topology

- Reconstruction of trajectories :  
Rossler & Lorentz
- Reconstruction of phase space :  
2d & 3d





# Conclusions

- Really counter intuitive and interesting new ideas of studying chaos learned.
- Succeeded while reproducing the paper results, although not all.
- Glad to see how our lecture during the course helped us to understand the papers even to notice some mistakes.

