

PIDController
<ul style="list-style-type: none">- kp:double- ki:double- kd:double- current_error:double- previous_error:double- sum_error:double- error_threshold:double- dt:double
<ul style="list-style-type: none">+ PIDController(double, double, double)+ getKp(double)+ getKi(double)+ getKd(double)+ tuneController(double,double): double+ errorFeedback(void): double+ ~PIDController(void)