200

215

217

C

```
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```
CALL DECITM ('BAR1',0)
CALL POS (131071-75000-7000, 131071-25000)
CALL DRAWTR (14000,0)
CALL ENDITM
         CALL DECINS ('MBAR1', 'BAR1', 0)
CALL MAKMT2 (0, 0, 0, 1.0, IBAR1)
CALL MAT2 (IBAR1, 'KEY13')
CALL ENDINS
CALL ADD ('MBAR1', 'PIC2')
         CALL DECITM ('BAR2',0)
CALL POS (-131071+75000-7000, 131071-25000)
CALL DRAWTR (14000,0)
CALL ENDITM
         CALL DECINS ('MBAR2', 'BAR2', 0)
CALL MAKMT2 (0,0,0,1.0, IBAR2)
CALL MAT2 (IBAR2, 'KEY14')
CALL ENDINS
CALL ADD ('MBAR2', 'PIC2')
CALL ADD ('MDOT', 'PIC2')
CALL ADD ('MLINE', 'PIC2')
CALL ADD ('BORDR', 'PIC2')
CALL DISPLAY ('PIC2', 0)
RZ=0.
RX=0.
RY=-UNIT
MZ=0
MX = 0
MMOV=0
MROT=0
NDUM=1
RRAN=3.1415
CALL DREAD
CALL ADJDAT
AY=DKNOB (1) *180.
AX=DKNOB(2) * 180.
         AX IS FOR VIEW UP, DOWN.
RX=RX-XJOY*RUNIT/10.
IF (. NOT. SWITCH (17)) GOTO215
RY=RY+YJOY*RUNIT/10.
GO TO 217
RZ=RZ+YJOY*RUNIT/10.
CONTINUE
IRX=RX
IRY=RY
IRZ=RZ
RDUM=25000./131071.
RYDUM=ISIGN(1, IRY) * (((IABS(IRY)+131071)/131071)/2)
RXDUM=ISIGN(1, IRX) * (((IABS (IRX) +131071)/131071)/2)
RZDUM=ISIGN(1, IRZ) * (((IABS(IRZ)+131071)/131071)/2)
QX=RDUM* (RX-RXDUM*262142.)
QZ=RDUM* (RZ-RZDUM*262142.)
QY=RDUM*(RY-RYDUM*262142.)
CALL MAKMT2 (0,0,25000. *SIN (AX),1.0, IBAR1)
CALL UPDATE ('MAT2', 'KEY13', IBAR1)
CALL MAKMT2 (0,0,-QY, 1.0, IBAR2)
CALL UPDATE ('MAT2', 'KEY14', IBAR2)
CALL MAKMT2 (0, -QX, QZ, 1.0, IDOT)
CALL UPDATE ('MAT2', 'KEY5', IDOT)
```