

## Loss FUNCTIONS

Quadratic loss conditional expectation theorem

$$\text{Princ: } \textcircled{1} \quad L(Y, f(x)) = (Y - f(x))^2$$

$$\textcircled{2} \quad E_{x,y} [L(Y, f(x))] = E_{x,y} (Y - f(x))^2$$

Claim:  $f$  that minimizes  $\textcircled{2}$  is  $f(x) = E_{y|x} [Y|x]$

Proof:

$\textcircled{1}$  Assume that  $c$  is some constant  $\in \mathbb{R}$ . We will show that  $c = \mu$  will minimize  $E_y [(Y - c)^2]$

$$\begin{aligned} \frac{\partial}{\partial c} E_y [(Y - c)^2] &= -E [2(Y - c)] \\ &= -2E[Y] + 2c \end{aligned}$$

Setting to 0:

$$\begin{aligned} -2E[Y] + 2c &= 0 \\ c &= E[Y] \end{aligned}$$

This is also a minimum b/c we differentiated a quadratic function that opens upwards.

$\textcircled{2}$  Now, assume  $c(\hat{x})$ . From above argument,  $c(\hat{x}) = E[Y|x=\hat{x}]$  minimizes  $E_{y|x=x} [(Y - c(x))^2 | X=x]$ .

$\textcircled{3}$  By minimality, we can say that if  $Z = z(x)$ ,  $W = w(x)$ , then  $Z \geq W \Leftrightarrow \forall x, z(x) \geq w(x)$ .

Then, from  $\textcircled{2}$ , we can say for any function  $s(\cdot)$ :

$$\begin{aligned} E_y [(Y - s(x))^2 | X=x] &\geq E_y [(Y - c(\hat{x}))^2 | X=x] \\ \Rightarrow E_y [(Y - s(x))^2] &\geq E_y [(Y - c(\hat{x}))^2] \end{aligned}$$

$\textcircled{4}$  Taking  $E_x$  on both sides & using law of iterated expectation:

$$E_x [E_y [(Y - s(x))^2 | X=x]] \geq E_x [E_y [(Y - c(\hat{x}))^2 | X=x]]$$

$$E_{x,y} [(Y - s(x))^2] \geq E_{x,y} [(Y - c(\hat{x}))^2]$$

$\textcircled{5}$  This shows us that  $c(\hat{x}) = E[Y|x]$  minimizes the risk function.

## Absolute loss risk minimization

Preceq: ①  $L(Y, f(x)) = |Y - f(x)|$

Claim:  $f(\cdot)$  that minimizes  $\mathbb{E}[L(Y, f(x))]$  is Median( $Y | X=x$ )

Proof: ① Let  $f_y(y)$  be the density function of  $Y$ . Assume  $f(x)$  is a constant  $c$  for now. Then:

$$\begin{aligned}\mathbb{E}[L(Y, f(c))] &= \int_{-\infty}^{\infty} |y-c| f_y(y) dy \\ &= \int_{-\infty}^c (c-y) f_y(y) dy + \int_c^{\infty} (y-c) f_y(y) dy \\ &\quad \text{---} \quad \text{---} \\ &\quad I_1 \quad \quad \quad I_2\end{aligned}$$

Differentiating w/ respect to  $c$ :

$$\frac{\partial}{\partial c} \mathbb{E}[L(Y, f(c))] = \frac{\partial}{\partial c} I_1 + \frac{\partial}{\partial c} I_2$$

Applying Leibniz Rule which states:

$$\frac{\partial}{\partial c} \int_{a(c)}^{b(c)} f(y, c) dy = f(b(c), c) \cdot \frac{\partial b(c)}{\partial c} - f(a(c), c) \cdot \frac{\partial a(c)}{\partial c} + \int_{a(c)}^{b(c)} \frac{\partial f(s, c)}{\partial c} ds$$

$$\begin{aligned}\therefore \frac{\partial}{\partial c} I_1 &= (c-c) f_y(c) \cdot 1 - f(\infty, c) \cdot 0 + \int_{-\infty}^c f_y(y) dy \\ &= \int_{-\infty}^c f_y(y) dy\end{aligned}$$

$$\begin{aligned}\frac{\partial}{\partial c} I_2 &= (\infty-c) f_y(\infty) \cdot 0 - (c-c) f_y(c) \cdot 1 - \int_c^{\infty} f_y(y) dy \\ &= - \int_c^{\infty} f_y(y) dy\end{aligned}$$

Thus:

$$\begin{aligned}\frac{\partial}{\partial c} \mathbb{E}[L(Y, f(c))] &= \frac{\partial}{\partial c} I_1 + \frac{\partial}{\partial c} I_2 \\ &= \int_{-\infty}^c f_y(y) dy - \int_c^{\infty} f_y(y) dy \\ &= F_y(c) - (1 - F_y(c)) \\ &= -1 + 2F_y(c)\end{aligned}$$

Setting to 0:

$$F_y(c) = \frac{1}{2} \Rightarrow \text{Median}$$

Thus,  $f(\cdot)$  that minimizes this expectation is Median( $Y$ ).

② If  $c$  now becomes  $\hat{c}(x)$ , we have:

$$\mathbb{E} [ |Y - \hat{c}(x)| \mid X = x ]$$

We know that  $c(x) = \text{Median}(Y \mid X=x)$  still holds since  $\hat{c}(x)$  is treated like a constant.

③ From minimality, we know that for any function  $g(\cdot)$ ,

$$\mathbb{E} [ |Y - g(x)| \mid X = x ] \geq \mathbb{E} [ |Y - \hat{c}(x)| \mid X = x ]$$

So:

$$\mathbb{E} [ |Y - g(x)| \mid X ] \geq \mathbb{E} [ |Y - \hat{c}(x)| \mid X ]$$

④ Taking iterated expectations:

$$\mathbb{E}_x [\mathbb{E} [ |Y - g(x)| \mid X ]] \geq \mathbb{E}_x [\mathbb{E} [ |Y - \hat{c}(x)| \mid X ]]$$

$$\mathbb{E}_{x,y} [ |Y - g(x)| ] \geq \mathbb{E}_{x,y} [ |Y - \hat{c}(x)| ]$$

⑤ This shows that  $\hat{c}(x) = \text{Median}(Y \mid X=x)$  is the minimizer for Abs-Loss.

## REGRESSION REVIEW

### Proof of $\hat{\beta}$ estimation

Claim: If  $Y = X\beta + \epsilon$ ,  $\hat{\beta}$  that best minimizes square loss is  $\hat{\beta} = (X'X)^{-1}X'Y$

① Model specification:

$$Y = X\beta + \epsilon, \quad \epsilon \sim \text{MVN}(0, \sigma^2 I).$$

② Square error loss function:

$$(Y - X\beta)'(Y - X\beta)$$

③ Differentiate:

$$\begin{aligned} \frac{\partial}{\partial \beta} [ (Y - X\beta)'(Y - X\beta) ] &= \frac{\partial}{\partial \beta} [ (Y' - \beta'X')(Y - X\beta) ] \\ &= \frac{\partial}{\partial \beta} [ Y'Y - Y'X\beta - \beta'X'Y + \beta'X'X\beta ] \\ &= -(Y'X)' - (X'Y) + (X'X + (X'X)')\beta \\ &= -2X'Y + 2X'X\beta \end{aligned}$$

④ Set to 0

$$-2x'y + 2x'x\hat{\beta} = 0$$

$$x'x\hat{\beta} = x'y$$

$$\hat{\beta} = (x'x)^{-1}x'y$$

## Idempotency of hot matrix

Claim:  $H = X(X'X)^{-1}X'$      $H = H^2$

Proof:

$$\begin{aligned} H^2 &= X(X'X)^{-1}X' \cdot X(X'X)^{-1}X' \\ &= X(X'X)^{-1}\cancel{X'X}^{\mathbb{I}} \cdot (X'X)^{-1}X' \\ &= X(X'X)^{-1}X' \\ &= H \end{aligned}$$

## Orthogonality of $\hat{r}$ & $\hat{Y}$

Claim:  $\hat{r} \cdot \hat{Y} = 0$

Proof:  $\hat{r} = Y - \hat{Y} = (I - H)Y$

$$\hat{Y} = HY$$

$$\begin{aligned} \therefore \hat{r} \cdot \hat{Y} &= \hat{r}' \hat{Y} \\ &= (Y - HY)' (HY) \\ &= Y'H Y - Y'(H'HY) \quad \text{By symmetry of } H \\ &= Y'H Y - H \cdot Y'HY \quad \text{By idempotency of } H \\ &= Y'H Y - Y'HY \\ &= 0 \end{aligned}$$

# PREDICTION W/ LINEAR REGRESSION

## Prediction interval theorem

Claim: Let  $(y_0, x_0)$  & training set. Let us define a point forecast of  $y_0$  at  $x = x_0$  as  $\hat{\mu} = x_0' \hat{\beta}$ .

Then,  $100(1-\alpha)\%$  prediction interval is:

$$\hat{\mu} \pm c_\alpha \hat{\sigma} \sqrt{1 + x_0' (x'x)^{-1} x_0'}$$

Proof: We know that:

$$y_0 - x_0' \hat{\beta} \sim N(0, \sigma^2 (1 + x_0' (x'x)^{-1} x_0'))$$

Then:

$$T := \frac{y_0 - x_0' \hat{\beta}}{\hat{\sigma} \sqrt{1 + x_0' (x'x)^{-1} x_0'}} \sim t_{n-p-1}$$

For a confidence interval:

$$P(-c_\alpha \leq T \leq c_\alpha) = 1 - \frac{\alpha}{2}$$

$$\therefore \hat{\mu} \pm c_\alpha \hat{\sigma} \sqrt{1 + x_0' (x'x)^{-1} x_0'} \text{ is } 100(1-\alpha)\% \text{ prediction interval}$$

## BIAS-VARIANCE TRADEOFF

### Decomposition

Claim: We have a training set  $T$  & an estimate of  $\beta$ ,  $\hat{\beta} = \hat{\beta}(T)$ . We calculate the forecasting error for new  $x_0$ ,  $\hat{y}_0 = x_0' \hat{\beta}$ .

Then:

$$MSE(x_0) = Bias^2(y_0) + Var_T(y_0)$$

Proof:

$$\begin{aligned} MSE(x_0) &:= E_T \{ (y_0 - \hat{y}_0)^2 \} \\ &= E_T \{ (y_0 - E_T(\hat{y}_0)) + E_T(\hat{y}_0) - \hat{y}_0 \}^2 \} \\ &= (y_0 - E_T(\hat{y}_0))^2 + E_T ((\hat{y}_0 - E_T(\hat{y}_0))^2) \\ &\quad \underbrace{\hspace{1cm}}_{\text{Bias}^2} \quad \underbrace{\hspace{1cm}}_{\text{Variance}} \end{aligned}$$

## Prediction error decomposition

Claim:  $Y = f(x) + \epsilon$ ,  $\text{Var}(\epsilon) = \sigma_\epsilon^2$ . For some input  $X_0 = x_0$ , output is  $\hat{f}(x_0)$

Then:  $\text{Err}(x_0) = \sigma_\epsilon^2 + \text{Bias}^2 + \text{Variance}$

$$\begin{aligned}
 \text{Proof: } \text{Err}(x_0) &= E[(Y - \hat{f}(x_0))^2 | X_0 = x_0] \\
 &= E[Y^2 + \hat{f}(x_0)^2 - 2Y\hat{f}(x_0) | X_0 = x_0] \\
 &= E[Y^2 | X_0 = x_0] + E[\hat{f}(x_0)^2 | X_0 = x_0] - 2E[Y\hat{f}(x_0) | X_0 = x_0] \\
 &= \underset{\text{Var}(Y|X_0=x_0)}{\text{Var}(Y|X_0=x_0)} + \underset{\text{constant}}{E[Y|X_0=x_0]^2} + \underset{\text{Bias}}{-2E[(f(x_0) + \epsilon)\hat{f}(x_0)|X_0=x_0]} \\
 &= \sigma_\epsilon^2 + E[\hat{f}(x_0)^2 | X_0 = x_0] + \underset{\text{Bias}}{-2E[\hat{f}(x_0)\hat{f}(x_0) | X_0 = x_0]} \\
 &= \sigma_\epsilon^2 + \underset{\text{Bias}}{f(x_0)^2} + E[\hat{f}(x_0)^2 | X_0 = x_0] - 2E[\hat{f}(x_0)\hat{f}(x_0) | X_0 = x_0] \\
 &= \sigma_\epsilon^2 + E[(f(x_0) - \hat{f}(x_0))^2 | X_0 = x_0] \quad \pm E[\hat{f}(x_0)] \\
 &= \sigma_\epsilon^2 + E[(f(x_0) - E[\hat{f}(x_0)])^2 | X_0 = x_0] + E[(E[\hat{f}(x_0)] - \hat{f}(x_0))^2 | X_0 = x_0] \\
 &= \sigma_\epsilon^2 + \text{Bias}^2 + \text{Variance}
 \end{aligned}$$

## REGULARIZATION METHODS

### Hidge regression closed form derivation

#### ① Minimization:

$$\underset{\beta_0, \vec{\beta}}{\operatorname{argmin}} \text{RSS}(\lambda) = \underset{\beta_0, \vec{\beta}}{\operatorname{argmin}} (y - \beta_0 \vec{1} - x \vec{\beta})'(y - \beta_0 \vec{1} - x \vec{\beta}) + \lambda \vec{\beta}' \vec{\beta}$$

#### ② Derivative.

$$\begin{aligned}
 \text{RSS}(\lambda) &= (y' - \vec{1}' \beta_0 - \vec{\beta}' x') (y - \beta_0 \vec{1} - x \vec{\beta}) + \lambda \vec{\beta}' \vec{\beta} \\
 &= y'y - y'\beta_0 \vec{1} - y'x\vec{\beta} - \vec{1}'\beta_0'y - \vec{1}'\beta_0' \beta_0 \vec{1} - \vec{1}'\beta_0' x\vec{\beta} - \vec{\beta}'x'y \\
 &\quad + \vec{\beta}'x'\beta_0 \vec{1} + \vec{\beta}'x'x\vec{\beta} + \lambda \vec{\beta}' \vec{\beta}
 \end{aligned}$$

$$\begin{aligned}
 \frac{\partial}{\partial \beta} \text{RSS}(\lambda) &= -(y'x)' - (\vec{1}' \beta_0' x)' - (x'y) + (x'\beta_0 \vec{1}) + (x'x + x'x)\beta + 2\lambda \beta \\
 &= -2x'y + 2x'x\beta + 2\lambda \beta
 \end{aligned}$$

⑦ Setting to 0:

$$\begin{aligned} -2X'Y + 2X'X\hat{\beta} + 2\lambda\hat{\beta} &= 0 \\ -X'Y + X'X\hat{\beta} + \lambda\hat{\beta} &= 0 \\ (X'X + \lambda I)\hat{\beta} &= X'Y \\ \hat{\beta} &= (X'X + \lambda I)^{-1}X'Y \end{aligned}$$

## STATIONARY PROCESSES

Strictly stationary & weakly stationary relationship

Claim: Strictly stationary process  $\Rightarrow$  weakly stationary process

Proof: Assume that  $\{X_t\}$  is a strictly stationary process. We will show that it is weakly stationary.

①  $E[X_t^2] < \infty$  and indep. of  $t$  by defn.

②  $E[X_t]$ : Since  $F_{x_1}(x) = \dots = F_{x_n}(x) \forall x$ , the mean function  $\mu_x(t)$  must be constant & indep. of  $t$ .

③  $\gamma(h)$ :

$$\begin{aligned} \gamma(h) &= \text{Cov}(X_t, X_{t+h}) \\ &= E[X_t X_{t+h}] - E[X_t] E[X_{t+h}] \\ &= E[X_1 X_{1+h}] - E[X_1] E[X_{1+h}] \end{aligned}$$

Since  $\{X_t\}$  is strictly stationary, we know that  $F_{x_1, x_2}(x_1, x_2) = F_{x_{1+h}, x_{1+h}}(x_1, x_2) \forall k, l$ . Thus:

$$E[X_t X_{t+h}] = E[X_1 X_{1+h}]$$

We also know that all univariate distributions will be the same as  $\forall h$ ,  $F_{x_1}(x_1) = F_{x_{1+h}}(x_1)$ . Thus:

$$E[X_t] = E[X_1]$$

$$E[X_{t+h}] = E[X_{1+h}]$$

Since all components of  $\text{Cov}(X_t, X_{t+h})$  is independent of  $t$ , the covariance will also be indep. of  $t$ .

$\therefore ①, ②, ③ \Rightarrow$  weakly stationary

## SMOOTHING METHODS

### Exponential Smoothing (Closed) Form

Claim: The closed form solution of an exponentially smoothed average is

$$\hat{m}_t = \sum_{j=0}^{t-2} \alpha (1-\alpha)^j x_{t-j} + (1-\alpha)^{t-1} x_t, \quad (t \geq 2)$$

Proof: The recursive defn. is:

$$\hat{m}_t = \begin{cases} \alpha x_t + (1-\alpha) \hat{m}_{t-1}, & t > 1 \\ x_1, & t = 1 \end{cases}$$

We will use induction to prove that the closed form (hereby called  $p_t$ ) is equivalent to the recursive form.

For  $t = 2$ :

$$\begin{aligned} p_2 &= \sum_{j=0}^{2-2} \alpha (1-\alpha)^j x_{2-j} + (1-\alpha)^{2-1} x_2 \\ &= \alpha x_2 + (1-\alpha) x_1 \end{aligned}$$

This is equivalent to the recursive version

Assume  $p_t$  is equivalent to  $\hat{m}_t$   $\forall 2 \leq t \leq k$ .

Consider  $p_{t+1}$ :

$$p_{t+1} = \sum_{j=0}^{t+1-2} \alpha (1-\alpha)^j x_{t+1-j} + (1-\alpha)^{t+1-1} x_t$$

$$= \sum_{j=0}^{t-1} \alpha (1-\alpha)^j x_{t+1-j} + (1-\alpha)^t x_t$$

=

## STATIONARY LINEAR PROCESSES

### Stationary MA(2) process

Claim: MA(2) process is stationary

Proof:

Let  $X_t$  be an MA(q) process w/ the following process

$$X_t = Z_t + \theta_1 Z_{t-1} + \dots + \theta_q Z_{t-q} \quad \text{where } Z_i \sim WN(0, \sigma^2)$$

① Expectation:

$$\begin{aligned} E[X_t] &= E[Z_t] + \theta_1 E[Z_{t-1}] + \dots + \theta_q E[Z_{t-q}] \\ &= 0 \Rightarrow \text{indep. of } t \end{aligned}$$

② Variance:

$$\begin{aligned} \text{Var}[Z_t] \\ \text{Var}[X_t] &= \theta_1^2 \text{Var}[Z_t] + \dots + \theta_q^2 \text{Var}[Z_{t-q}] + \underbrace{\theta_1 \theta_2 \text{Cov}(Z_t, Z_{t-1}) \dots}_{0 \text{ b/c WN}} \\ &= \theta_1^2 \sigma^2 + \dots + \theta_q^2 \sigma^2 + \sigma^2 \\ &= \sigma^2 (1 + \theta_1^2 + \dots + \theta_q^2) \end{aligned}$$

Variance is finite & indep. of t.

③ ACVF

$$\begin{aligned} \gamma(h) &= \text{Cov}(X_t, X_{t+h}) \\ &= \text{Cov}(Z_t + \theta_1 Z_{t-1} + \dots + \theta_q Z_{t-q}, Z_{t+h} + \theta_1 Z_{t-1+h} + \dots + \theta_q Z_{t-q+h}) \end{aligned}$$

If  $h=1$ :

$$\gamma(h) = \theta_0 \theta_1 \sigma^2 + \theta_1 \theta_2 \sigma^2 + \dots + \theta_{q-1} \theta_q \sigma^2$$

If  $0 < h < q$

$$\gamma(h) = \theta_0 \theta_h \sigma^2 + \dots + \theta_{q-h} \theta_q \sigma^2$$

If  $h=q$ :

$$\gamma(h) = \theta_0 \theta_q \sigma^2$$

$h \geq q$ :  $\gamma(h) = 0$

Since  $\gamma(h)$  is not dependent on  $t$ , ①, ②, ③ are satisfied  $\Rightarrow$  MA(q) is stationary.

Best linear predictor

Claim:  $\hat{P}_n X_{n+h} = a_0 + a_1 X_n + \dots + a_n X_1$  is the best linear predictor in terms of MSE if:

$$a) a_0 = \mu(1 - \sum_{i=1}^n a_i)$$

$$b) a_1, \dots, a_n \text{ satisfy } \vec{\Gamma}_n \vec{a}_n = \vec{\gamma}_n(h)$$

Proof: ① Minimization

$$S = \underset{\alpha_0, \dots, \alpha_n}{\operatorname{argmin}} \mathbb{E} [(X_{n+h} - P_n X_{n+h})^2]$$

$$\textcircled{2} \quad \frac{\partial S}{\partial \alpha_j}$$

$$\begin{aligned} \text{Eq 1: } \frac{\partial S}{\partial \alpha_0} &= \frac{\partial}{\partial \alpha_0} \mathbb{E} [(X_{n+h} - \alpha_0 - \alpha_1 x_n - \dots - \alpha_n x_n)^2] = 0 \\ &= -2 \mathbb{E} [X_{n+h} - \alpha_0 - \alpha_1 x_1 - \dots - \alpha_n x_n] = 0 \\ &\mu - \alpha_0 - \alpha_1 \mu - \dots - \alpha_n \mu = 0 \\ \alpha_0 &= \mu + \alpha_1 \mu + \dots + \alpha_n \mu \\ &= \mu \left( 1 + \sum_{i=1}^n \alpha_i \right) \end{aligned}$$

Eq 2: For  $j = 1, 2, \dots, n$

$$\begin{aligned} \frac{\partial S}{\partial \alpha_j} &= \frac{\partial}{\partial \alpha_j} \mathbb{E} [(X_{n+h} - \alpha_0 - \alpha_1 x_n - \dots - \alpha_n x_n)^2] = 0 \\ \Rightarrow -2 \mathbb{E} [X_{n+1-j} (X_{n+h} - \alpha_0 - \alpha_1 x_n - \dots - \alpha_n x_n)] &= 0 \\ \Rightarrow \mathbb{E} [X_{n+1-j} X_{n+h}] - \alpha_0 \mathbb{E} [X_{n+1-j}] - \alpha_1 \mathbb{E} [X_n X_{n+1-j}] - \dots &= 0 \\ \Rightarrow \mathbb{E} [X_{n+1-j} X_{n+h}] - \mu^2 \left( 1 - \sum_{i=1}^n \alpha_i \right) - \sum_{i=1}^n \alpha_i \mathbb{E} [X_{n+1-j} X_{n+1-i}] &= 0 \\ \Rightarrow (\mathbb{E} [X_{n+1-j} X_{n+h}] - \mu^2) + \mu^2 \sum_{i=1}^n \alpha_i - \sum_{i=1}^n \alpha_i \mathbb{E} [X_{n+1-j} X_{n+1-i}] &= 0 \\ \Rightarrow \gamma(h+j-1) - \sum_{i=1}^n \alpha_i (\mathbb{E} [X_{n+1-j} X_{n+1-i}] - \mu^2) &= 0 \\ \Rightarrow \gamma(h+j-1) - \sum_{i=1}^n \alpha_i \gamma(i-j) &= 0 \end{aligned}$$

$\therefore$  For diff values of  $j$

$$\gamma_n(h) = \sum_{i=1}^n \alpha_i$$

Best linear predictor - MSE

$$\text{Claim: } \mathbb{E} [(X_{n+h} - P_n X_{n+h})^2] = \gamma(0) - \alpha_n' \gamma_n(h)$$

Proof:

$$\mathbb{E} [(X_{n+h} - P_n X_{n+h})^2] = \mathbb{E} \left[ \left( (X_{n+h} - \mu) - \alpha' (\vec{x} - \mu) \right)^2 \right]$$

$$= \mathbb{E} \left[ (x_{n+h} - \mu)^2 - 2(x_{n+h} - \mu) \alpha' (\vec{x} - \mu) + (\alpha' (\vec{x} - \mu))^2 \right]$$

?? I don't know how to prove this.

## BOX-JENKINS MODELS

### ACVF of ARMA(p, q)

Claim: ACVF of stationary & causal ARMA(p, q) process is

$$\gamma(h) = \sigma^2 \sum_{j=0}^{\infty} \psi_j \psi_{j+h}$$

Proof: If  $x_t$  is an ARMA(p, q) process, then it can be written as:

$$x_t = \sum_{j=0}^{\infty} \psi_j z_{t-j}$$

We can now evaluate:

$$\begin{aligned}
 \gamma(h) &= \text{Cov}(x_t, x_{t+h}) \\
 &= \mathbb{E}[x_t x_{t+h}] - \cancel{\mathbb{E}[x_t] \mathbb{E}[x_{t+h}]}^0 \\
 &= \mathbb{E} \left[ \sum_{j=0}^{\infty} \psi_j z_{t-j} \sum_{i=0}^{\infty} \psi_i z_{t+h-i} \right] \\
 &\quad \text{Reindex} \\
 &= \sum_{j=0}^{\infty} \psi_j \psi_{j+h} \mathbb{E}[z_j^2] \\
 &= \sigma^2 \sum_{j=0}^{\infty} \psi_j \psi_{j+h}
 \end{aligned}$$