

Problem Statement and Goals

The Nursery Project

Aaron Billones, billonea
Gillian Ford, fordg
Juan Moncada, moncada.j
Steven Ramundi, ramundis

September 26. 2022

Table 1: Revision History

Date	Developer(s)	Change
2022-09-25	Juan Moncada, Aaron Billones, Steven Ramundi, Gillian Ford	Initial release

1 Problem Statement

Sheridan Nurseries is one of Canadas largest nursery operations and is growing year by year. In the past few years, the company has taken steps to automate their production line and streamline their operation. A significant amount of manual labour was seen in between the delivery of skidded pots/trays and the beginning of the propagation assembly line. In the current state, one employee is used to recieve stacks of pots and trays from their respective skids, populate the trays with pots, and feed the now filled trays into the assembly line where the propagation of plants into the pots begins. This process currently requires full-time labour from at minimum one employee, if not more, to yield the required output.

1.1 Problem

Sheridan Nurseries currently has no automation in their process of populating their trays and pots thus needing significant manual labour.

1.2 Inputs and Outputs

1.2.1 Physical input

Physical inputs will be stacks of trays and pots. The sytem should be able to tell that there is stacks of skids and trays are present and ready to be populated.

1.2.2 Software input

The system should also have a software trigger that there is sufficient trays and pots in order to carry out its operation. there should also, like in all machinery be a safety on and off.

1.2.3 Physical output

The physical output of this project will be the trays filled with pots ready to move on to propagation.

1.2.4 Software output

the systems should be able to display a series of warnings such as load trays, load pots, and verification failed.

1.3 Stakeholders

The main stakeholders for this project will be the nursery manager, owner, aswell as the individual working the assembly line.

1.4 Environment

This project will be an even split between hardware and software as there is a need to build and incorporate into an existing assembly line. Hardware will have to be used in order to manipulate pots and trays, while software will be used to control said hardware as well as take care of any verification that trays have been populated properly.

2 Goals

The main goal of this project is to develop a system for Sheridan Nurseries that will replace the need for human workers in the current process of populating plant trays with pots. This will reduce the cost of labour for the nursery, while being significantly less expensive than current alternatives. The goal of the system is to populate a standard tray with 10 pots in 30 seconds, equating to 2 trays per minute and 960 trays in an 8 hour shift. This is based on output numbers provided by the manager for the current system. Another goal for the project is to reload the trays and pots every 15 minutes. This would require space for 30 trays and 300 pots.

3 Stretch Goals

The first stretch goal is to double the potential output of the machine. This will approximately equate the output rate to maximum rate of the machine responsible for populating pots with soil. The second stretch goal is to increase machine capacity to 60 trays and 600 pots to maintain the goal of reloading the machine every 15 minutes. The third stretch goal is to make the machine capable of dealing with variable tray and pot sizes.