

Math 210

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Problem Set 6

4/8/21

```
In [2]:
    import numpy as np
    from scipy.optimize import linprog
    import pandas as pd
```

Problem 1.

a.

I convert the problem to a single source problem:

```
\mathsf{Edges} \colon \mathcal{E} = \{(0,1), (0,2), (0,4), (1,2), (1,3), (2,3), (2,4), (2,5), (3,4), (3,5), (4,5), (4,6), (5,4), (5,6)\}.
```

Fix the flow on (0,1), (0,2), (0,4) to 30,6, and 4 respectively.

Let the currently unspecified constraint set be \mathcal{C} .

Maximize the flow into vertex 6, so $\max_{x_s \in \mathcal{C}} \{x_{46} + x_{56}\}$

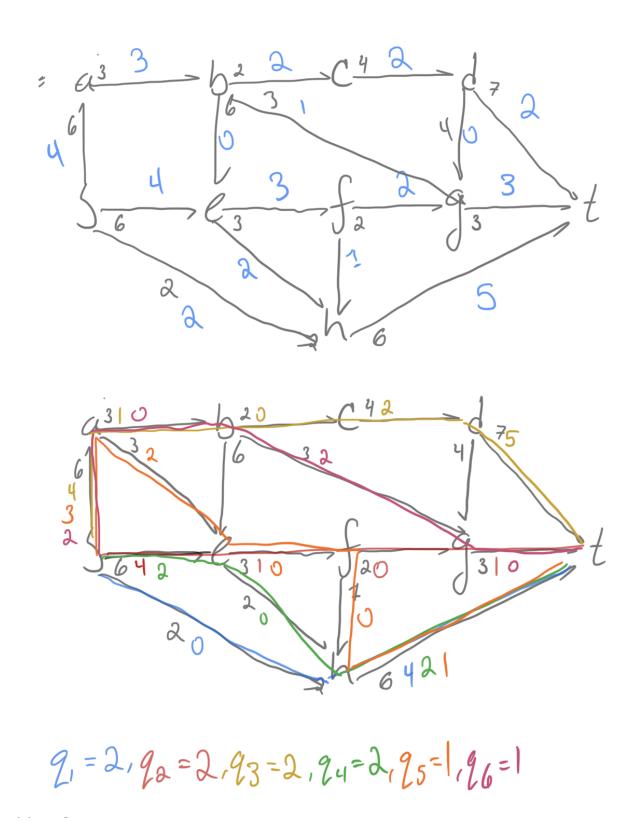
We have the following constraint set:

```
egin{array}{l} x_{12}+x_{13}=x_{01} \ x_{23}+x_{24}+x_{25}=x_{02}+x_{12} \ x_{34}+x_{35}=x_{13}+x_{23} \ x_{45}+x_{46}=x_{24}+x_{34}+x_{54} \ x_{54}+x_{56}=x_{25}+x_{35}+x_{45} \end{array}
```

```
In [3]:
        a_eq=np.array([
                     [1,0,-1,-1,-1,0,0,0,0,0,0,0],
                     [0,1,1,0,0,-1,-1,0,0,0,0]
                     [0,0,0,1,0,1,0,-1,-1,1,0],
                     [0,0,0,0,1,0,1,1,0,-1,-1]]
        print(a_eq)
        b_eq=np.zeros((4))
        print(b_eq)
         a_leq=np.identity(11)
        b leg=[14,16,9,3,8,10,6,5,16,4,15]
        c=[0,0,0,0,0,0,0,0,-1,0,-1]
        linprog(c,A_ub=a_leq,b_ub=b_leq,A_eq=a_eq,b_eq=b_eq,method="simplex")
        \hbox{\tt [[1 \ 0 \ -1 \ -1 \ -1 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0]}
         [0 1 1 0 0 -1 -1 0 0 0 0]
         [ 0 0 0 1 0 1 0 -1 -1 1 0]
         [0 0 0 0 1 0 1 1 0 -1 -1]]
        [0. 0. 0. 0.]
             con: array([0., 0., 0., 0.])
             fun: -27.0
         message: 'Optimization terminated successfully.'
            nit: 15
           slack: array([3., 0., 9., 0., 0., 0., 0., 4., 0., 0., 4.])
          status: 0
         success: True
               x: array([11., 16., 0., 3., 8., 10., 6., 1., 16., 4., 11.])
```

Problem 2.

The optimal flows are in the first chart and the process is in the second:



Problem 3.

```
In [4]: #used to make label names:
    #source: geeksforgeeks.org/python-insert-the-string-at-the-beginning-of-all-items-in-a-list/
    def prepend(list, str):

# Using '% s'
    str += '% s'
    list = [str % i for i in list]
    return(list)
```

```
In [5]: | import itertools
         def create_eq_matrix(nvert,edgemat):
           A=np.zeros((nvert,(nvert**2))) #too large will shrink later,
                                           #but makes for easy indexing
           c=np.zeros(nvert**2) # ditto
           #loop over the edgemat, taking each path as an iterand
           for count, value in enumerate(edgemat[:,0:2]):
             col_num=(nvert)*(value[0])+(value[1]) # n columns from each vertex
             if (value[0]==0): #coming from source
               #Don't have to worry about constraint on sources
               A[value[1],col num]=1
             elif (value[1]==(nvert-1)): #going to sink
               #dont have to worry about constraint on sink
               A[value[0],col num]=-1
               c[col num] = -1#Hey this is an important column, but it in the objective
             else: #intermediate
               A[value[1],col num]=1
               A[value[0],col_num]=-1
           A=np.append(A,np.array([c]),axis=0) #add the row of cs
           #Name appropriately
           col_names=[] #create vector of names
           for i in itertools.product(np.arange(nvert),repeat=2): #all combos of indexes
             col names += [str(i[0])+","+str(i[1])]
           row_names=prepend(np.arange(nvert),"V")
           row names+="c" #add one final row name
           A=pd.DataFrame(A,index=row_names,columns=col_names)# put things into pd data
           # Remove unused rows and columns
           A=A.loc[(A != 0).any(axis=1), (A != 0).any(axis=0)]
           #separate A and c again
           c=A.iloc[-1:,:]
           A=A.iloc[:-1,:]
           #create easy matrices and vectors
           b eq=np.zeros(A.shape[0])
           A_leq=np.identity(edgemat.shape[0])
           b leq=edgemat[:,2]
           #do optimization
           optimal=linprog(c,A eq=A,A ub=A leq,b eq=b eq,b ub=b leq,method="simplex")
           flows=np.array(np.array([optimal.x]))
           #generateoutput
           summary=pd.DataFrame(flows,index=["flow"],columns=A.columns)
           max="The maximum is: " +str(-optimal.fun)
           #print output and return
           print(max)
           return (summary,A)
```

Problem 1 Confirmation

flow 11.0 16.0 0.0 3.0 8.0 10.0 6.0 1.0 16.0 4.0 11.0

Problem 2 Confirmation.

```
In [7]: create_eq_matrix(10,
                                  np.array([
                                               [0,1,6],
                                               [0,5,6],
                                                [0,8,2],
                                                [1,2,3],
                                               [1,5,3],
                                                [2,3,2],
                                                [2,5,6],
                                               [2,7,3],
                                                [3,4,4],
                                                [4,7,4],
                                                [4,9,7],
                                               [5,6,3],
                                                [5,8,2],
                                                [6,7,2],
                                               [6,8,1],
                                                [7,9,3],
                                                [8,9,6]
                                                ]))[0]
          The maximum is: 10.0
                 0,1 \quad 0,5 \quad 0,8 \quad 1,2 \quad 1,5 \quad 2,3 \quad 2,5 \quad 2,7 \quad 3,4 \quad 4,7 \quad 4,9 \quad 5,6 \quad 5,8 \quad 6,7 \quad 6,8 \quad 7,9 \quad 8,9
           flow 6.0 2.0 2.0 3.0 3.0 2.0 0.0 1.0 2.0 0.0 2.0 3.0 2.0 2.0 1.0 3.0 5.0
```

Problem 4.

a.

```
A_leq=np.identity(9)
In [8]:
        A_eq=np.array([
                      [1,0,-1,-1,0,0,0,0,0],
                      [0,0,1,0,-1,-1,1,0,0],
                      [0,1,0,1,0,0,-1,-1,0],
                      [0,0,0,0,1,0,0,1,-1]
        ])
        b_eq=np.zeros(4)
        b_leq=[5,6,4,1,2,4,3,3,6]
        tab=np.concatenate((A_eq,A_leq),axis=0)
        b full=np.transpose(np.array([np.append(b eq,b leq)]))
        c=np.array([[0,0,0,0,0,1,0,0,1,0]])
        tab=np.concatenate((tab,b_full),axis=1)
        tab=np.concatenate((tab,c),axis=0)
        print(tab)
        indep_names=["x01","x03","x12","x13","x24","x25","x32","x34","x45"]
        dep names=["0","0","0","0","c01","c03","c12","c13","c24","c25","c32","c34","c45"]
        indep_names_dual=["mu1","mu2","mu3","mu4","y01","y03","y12","y13","y24","y25","y32","y34","y45"]
        dep_names_dual=["s01","s03","s12","s13","s24","s25","s32","s34","s45"]
        [[ 1. 0. -1. -1. 0. 0. 0. 0. 0. 0.]
        [ 0. 0. 1. 0. -1. -1. 1. 0. 0. 0.]
          0. 1. 0. 1. 0. 0. -1. -1. 0. 0.]
0. 0. 0. 0. 1. 0. 0. 1. -1. 0.]
          1. 0. 0. 0. 0. 0. 0. 0. 0.
              1. 0. 0. 0.
                             0. 0. 0.
                                         0. 6.]
         [0. 0. 1. 0. 0. 0. 0. 0. 4.]
          0. 0. 0.
                                         0.
                     1. 0.
                             0.
                                 0. 0.
                                             1.1
          0. 0. 0. 0. 1.
                             0.
                                 0. 0.
                                         0. 2.1
          0. 0. 0. 0. 1. 0. 0.
                                         0. 4.1
        [ 0.
              0.
                  0.
                      0.
                         0.
                             0.
                                 1.
                                     0.
                                         0.
                                             3.]
        [ 0. 0. 0. 0. 0.
                             0. 0. 1. 0. 3.1
              0.0.
          0.
                      0. 0.
                             0.
                                 0.
                                     0.
                                         1.
                                            6.1
        [ 0. 0. 0.
                     0. 0.
                             1.
                                 0.
                                     0.
                                        1.
                                            0.]]
In [9]: def print_tableau(a,indep_names,dep_names,indep_names_dual,dep_names_dual):
        # Given matrix "a" and lists of variables names "indep_names" and "dep_names",
        # and (for the dual) "indep_names_dual" and "dep_names_dual",
        # this function prints the matrix and labels in standard tableau format
```

(including adding the -1, the minus signs in the last column, and labeling the lower-right as obj)

```
# First, check the inputs: indep names and dep names dual should be one shorter than the number of columns of A
                         dep names and indep names dual should be one shorter than the number of rows of A
   nrows = a.shape[0]
                        # use the shape function to determine number of rows and cols in A
   ncols = a.shape[1]
   nindep = len(indep names)
   nindep_dual = len(indep_names_dual)
   ndep = len(dep_names)
   ndep dual = len(dep names dual)
    if nindep != ncols-1:
       print("WARNING: # of indep vbles should be one fewer than # columns of matrix")
    if ndep != nrows-1:
       print("WARNING: # of dep vbles should be one fewer than # rows of matrix")
    if nindep dual != nrows-1:
       print("WARNING: # of indep dual vbles should be one fewer than # rows of matrix")
    if ndep dual != ncols-1:
       print("WARNING: # of dep dual vbles should be one fewer than # columns of matrix")
# Now do the printing (uses a variety of formatting techniques in Python)
              ",end="")
                                 # On first line, leave blank space so we can fit in dual labels lower down
    for j in range(ncols-1):
                                               # Print the independent variables in the first row
       print(indep names[j].rjust(10),end="") # rjust(10) makes fields 10 wide and right-justifies;
                                               # the end command prevents newline)
   print("
                                               # Tack on the -1 at the end of the first row
                 -1")
    for i in range(nrows-1):
       print(indep_names_dual[i].rjust(10),end="")
                                              # Print all but the last row of the matrix
       for j in range(ncols):
              print("%10.3f" % a[i][j],end="") # The syntax prints in a field 10 wide, showing 3 decimal point
       lab = "= -" + dep_names[i]
       print(lab.rjust(10))
    print("
               -1",end="")
    for j in range(ncols):
       print("%10.3f" % a[nrows-1][j],end="") # Print the last row of the matrix, with label "obj" at end
   lab = "= obj"
   print(lab.rjust(10))
    print(" ",end="")
    for j in range(ncols-1):
       lab = "=" + dep_names_dual[j]
       print(lab.rjust(10),end="")
   print(" =dualobi")
    print(" ")  # Put blank line at bottom
```

```
def pivot(a,pivrow,pivcol,indep_names,dep_names,indep_names_dual,dep_names_dual) :
# Given matrix "a", a row number "pivrow" and column number "pivcol",
# and lists of variable names "indep_names" and "dep_names", this
   function does three things:
     (1) outputs the new version of the matrix after a pivot,
     (2) updates the lists of variable names post-pivot
     (3) prints the new matrix, including labels showing the variable names
# First, check the inputs: indep_names should be one shorter than the number of columns of A
                           dep names should be one shorter than the number of rows of A
                           you should not be pivoting on the last row or last column
   nrows = a.shape[0]
                        # use the shape function to determine number of rows and cols in A
    ncols = a.shape[1]
    nindep = len(indep_names)
    nindep_dual = len(indep_names_dual)
    ndep = len(dep_names)
    ndep dual = len(dep names dual)
    if nindep != ncols-1:
       print("WARNING: # of indep vbles should be one fewer than # columns of matrix")
    if ndep != nrows-1:
        print("WARNING: # of dep vbles should be one fewer than # rows of matrix")
    if nindep dual != nrows-1:
        print("WARNING: # of indep dual vbles should be one fewer than # rows of matrix")
    if ndep_dual != ncols-1:
        print("WARNING: # of dep dual vbles should be one fewer than # columns of matrix")
    if pivrow > nrows-1 or pivcol > ncols-1:
       print("WARNING: should not pivot on last row or column")
    newa = a.copy() # make a copy of A, to be filled in below with result of pivot
    p = a[pivrow-1][pivcol-1] # identify pivot element
    newa[pivrow-1][pivcol-1] = 1/p # set new value of pivot element
    # Set entries in p's row
    for j in range(ncols):
        if j != pivcol-1:
           newa[pivrow-1][j]=a[pivrow-1][j]/p;
    # Set entries in p's column
    for i in range(nrows):
        if i != pivrow-1:
```

```
newa[i][pivcol-1]=-a[i][pivcol-1]/p;
              # Set all other entries
              for i in range(nrows):
                  for j in range(ncols):
                      if i != pivrow-1 and j != pivcol-1:
                          r = a[i][pivcol-1]
                          q = a[pivrow-1][j]
                          s = a[i][j]
                          newa[i][j]=(p*s-q*r)/p
              # Now transfer the new tableau into a
              for i in range(nrows) :
                  for j in range(ncols) :
                      a[i][j] = newa[i][j]
              # Now swap the variable names
              temp = indep names[pivcol-1]
              indep_names[pivcol-1]=dep_names[pivrow-1]
              dep_names[pivrow-1]=temp
              temp = indep names dual[pivrow-1]
              indep_names_dual[pivrow-1]=dep_names_dual[pivcol-1]
              dep names dual[pivcol-1]=temp
              print_tableau(newa,indep_names,dep_names,indep_names_dual) # Print the matrix with updated la
         def column_delete(a,col_to_remove,indep_names,dep_names,indep_names_dual,dep_names_dual) :
              import numpy as np
              anew = np.delete(a,col_to_remove-1,axis=1)
              del indep_names[col_to_remove-1]
              del dep_names_dual[col_to_remove-1]
              print tableau(anew,indep names,dep names,indep names dual,dep names dual)
              return anew
In [12]: def row_delete(a,row_to_remove,indep_names,dep_names,indep_names_dual,dep_names_dual):
              import numpy as np
              anew = np.delete(a,row_to_remove-1,axis=0)
              del dep_names[row_to_remove-1]
              del indep names dual[row to remove-1]
              print_tableau(anew,indep_names,dep_names,indep_names_dual,dep_names_dual)
              return anew
In [13]: | def target(a) :
              nrows = a.shape[0]
                                    # use the shape function to determine number of rows and cols in "a"
              ncols = a.shape[1]
              import numpy as np
              v = np.empty(ncols-1)
              for i in range(ncols-1):
                  v[i]=a[nrows-1,i]
              biggest_c = np.max(v)
              where_is_biggest_c = np.argmax(v)+1
              if biggest c > 0 :
                  return where_is_biggest_c
              else :
                  return -1
In [14]:
         def select(a,pivcolnum) :
                                    # use the shape function to determine number of rows and cols in A
              nrows = a.shape[0]
              ncols = a.shape[1]
          # First task: work down the column and record the b/a ratios in a vector v
               except record -1 if a is negative or zero
              import numpy as np
              v = np.zeros(nrows-1)
              for i in range(nrows-1):
                  if a[i,pivcolnum-1]>0 :
                     v[i] = a[i,ncols-1]/a[i,pivcolnum-1]
                  else :
                      v[i] = -1
          # Second task: if max b/a > -1, find min b/a by hand (ignoring zero entries in v)
              if np.max(v) > -1:
                  \min_{so_{tan}} = \min_{so_{tan}} \max_{so_{tan}} (v) + 1 # Initialize min to be for-sure bigger than the min
                  for i in range(nrows-1):
                      if v[i] > -1 and v[i] < min so far :
                          min_so_far = v[i]
                                               # Add 1 to use human numbering
                          where_is_min = i+1
                                           # Once we've scanned v for min, we can return result
                  return where is min
              else :
                              # Otherwise, we find the m
                  return -1
         def simplexbf(a,indep_names,dep_names,dual_indep_names,dual_dep_names):
          # Run the simplexbf algorithm
```

```
# Inputs: np.array "a" (assumed to be basic feasible)
          lists of variable names indep_names and dep_names (pivot will catch if they're wrong size)
\# Output: -1 if we stop because problem is unbounded, 0 if we continue to a solution
          -9 if we take too many steps
                         # use shape to find # of rows and cols in A
    nrows = a.shape[0]
    ncols = a.shape[1]
    print("Starting SimplexBF (will do nothing if solution can already be determined)")
    pivcol = target(a)
    nsteps = 0
    while pivcol > -1 and nsteps < 50: # Repeat until either solution found or 50 pivots completed
        pivrow = select(a,pivcol)
        if pivrow == -1:
           return -1
                       # If select reports -1, problem is unbounded, so exit this function
        else :
           pivot(a,pivrow,pivcol,indep names,dep names,dual indep names,dual dep names)
           nsteps=nsteps+1
           pivcol = target(a)
    if nsteps >= 50:
       return -9
                   # we took too many pivots
    else:
        return 0
```

```
In [16]: def targetnbf(a):
    nrows = a.shape[0]
    ncols = a.shape[1]
    import numpy as np
    checkrow = nrows-2
    while a[checkrow,ncols-1] >= -0.00000001:
        if checkrow == 0: # if still in the "while" and at the top,
            return -1 # all the b's were >= 0, so return -1
        else:
            checkrow = checkrow-1
    return checkrow+1 # if we exit the "while", we found a negative
            b, so return current row # (in human numbering)
```

```
def selectnbf(a,targetrow) :
# Given inputs "a" (tableau as an np.array, numbers only, no labels)
       and "targetrow" (a row that has a negative b; start-at-1 numbering assumed),
\# computes a pivot that could be chosen by SimplexNBF and
# outputs "pivrow" and "pivcol", the row and column (start-at-1 numbering) of that pivot
# If the targeted row has no negative aij, returns -2 for both pivrow and pivcol
   nrows = a.shape[0]
    ncols = a.shape[1]
    import numpy as np
    targetrow = targetrow-1 # convert to start-at-0
    pivcol = ncols-2  # column index of last aij
    while a[targetrow,pivcol] >= 0 :
        if pivcol == 0 : # if pivcol makes it to zero, all aij
           return [-2,-2] # in this row were >= 0, so problem infeasible
        else :
           pivcol = pivcol-1
    minsofar = a[targetrow,ncols-1]/a[targetrow,pivcol] # we found a negative aij
    pivrow = targetrow
    for i in range(targetrow+1, nrows-2): # now check below it for a smaller bi/aij with aij>0
        if a[i,pivcol]>0 and a[i,ncols-1]/a[i,pivcol] < minsofar :</pre>
            minsofar = a[i,ncols-1]/a[i,pivcol]
            pivrow = i
    return [pivrow+1,pivcol+1] # Return result (shifted to start-at-1 numbering)
```

```
In [18]: def simplexnbf(a,indep_names,dep_names,dual_indep_names,dual_dep_names):
          # Run the simplexnbf algorithm
          # Inputs: np.array "a"
                   lists of variable names indep_names and dep_names (pivot will catch if they're wrong size)
          # Output: -2 if we stop because problem is infeasible, 0 if we stop at a basic feasible tableau
                   -9 if we take too many pivots
              (Also, the tableau "a" and variable-lists are updated with each pivot)
              nrows = a.shape[0]
              ncols = a.shape[1]
              print("Starting SimplexNBF (will do nothing if already basic feasible)")
              nsteps = 0
              targetrow = targetnbf(a)
              while targetrow > -1 and nsteps < 50: # Repeat until either basic feasible tableau produced or 50 pivots co
                  [pivrow,pivcol] = selectnbf(a,targetrow)
                  if pivrow == -2 :
                                 # If selectnbf reports -2, problem is infeasible, so exit this function
                  else :
                     pivot(a,pivrow,pivcol,indep_names,dep_names,dual_indep_names,dual_dep_names)
                      nsteps=nsteps+1
                      targetrow = targetnbf(a)
              if nsteps >= 50:
```

took too many pivots

return -9

```
else:
                 return 0
         def simplex(a,indep_names,dep_names,dual_indep_names,dual_dep_names) :
In [19]:
          # Runs the simplex algorithm (doing NBF if needed, then BF)
          # Inputs: np.array "a"
                   lists of variable names indep_names and dep_names (pivot will catch if they're wrong size)
          # Output: -2 if problem is infeasible
                   -1 if problem is unbounded
                   0 if problem has a solution
               (Also, the tableau "a" and variable-lists are updated with each pivot)
             nrows = a.shape[0]
             ncols = a.shape[1]
             print("Initial tableau")
             print_tableau(a,indep_names,dep_names,dual_indep_names,dual_dep_names)
             code = simplexnbf(a,indep_names,dep_names,dual_indep_names,dual_dep_names)
             if code == -2:
                 print("Problem is infeasible")
                 return -2
              elif code == -9 :
                 print("SimplexNBF took too many pivots")
             else :
                 code = simplexbf(a,indep_names,dep_names,dual_indep_names,dual_dep_names)
                 if code == -1:
                     print("Problem is unbounded")
                     return -1
                 elif code == -9:
                     print("SimplexBF took too many pivots")
                 else :
                     print("Problem has solution, final tableau is shown above")
                     return 0
         def simplexeq(a,k,indep_names,dep_names,dual_indep_names,dual_dep_names) :
In [20]:
           Specialized function to do the "pre-simplex" step to handle tableaus where the
             first k rows correspond to equality constraints.
             nrows = a.shape[0]
             ncols = a.shape[1]
             print_tableau(a,indep_names,dep_names,dual_indep_names,dual_dep_names)
              for i in range(k) :
                 j=0
                 pivcol=-1
                 for j in range(ncols-1) :
                      if abs(a[i,j]) > 0.000001:
                         pivrow=i+1
                         pivcol=j+1
                         break
                 if pivcol == -1 :
                     return -3
                 else :
                     pivot(a,pivrow,pivcol,indep_names,dep_names,dual_indep_names,dual_dep_names)
                     a=column delete(a,pivcol,indep names,dep names,dual indep names,dual dep names)
                     ncols=ncols-1
              code = simplex(a,indep_names,dep_names,dual_indep_names,dual_dep_names)
             return code
In [21]: tab,4,indep_names,dep_names,indep_names_dual,dep_names_dual
                       0., -1., -1., 0., 0., 0., 0.,
                                                          0.,
Out[21]: (array([[ 1.,
                                                               0.1,
                  0.,
                       0., 1., 0., -1., -1., 1., 0., 0., 0.],
                  0.,
                       1., 0., 1., 0., 0., -1., -1., 0.,
                                                               0.],
                            0.,
                                 0.,
                                      1.,
                                           0.,
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          ['x01', 'x03', 'x12', 'x13', 'x24', 'x25', 'x32', 'x34', 'x45'],
          ['0',
           '0',
           '0',
           'c01',
           'c03'
           'c12'
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'c24',

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'c25'
             'c32'
             'c34'
             'c45'],
           ['mu1'.
             mu2
             'mu3'
             'mu4
             'y01',
             'y03'
             y12
             'y13',
             y24
             y25
             'v32'
             'y34'
           'y45'],
['s01', 's03', 's12', 's13', 's24', 's25', 's32', 's34', 's45'])
In [22]:
          simplexeq(tab, 4, indep names, dep names, indep names dual, dep names dual)
                                                                                     x25
                             x01
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					ProblemSet	:7				
mu3	1.000	0.000	1.000	0.000	0.000	-1.000	-1.000	0.000	0.000	= -0
mu4	0.000	0.000	0.000	1.000	0.000	0.000	1.000	-1.000	0.000	= -0
y01	0.000	1.000	1.000	0.000	0.000	0.000	0.000	0.000	5.000	= -c01
y03	1.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	6.000	= -c03
y12	0.000	1.000	0.000	0.000	0.000	0.000	0.000	0.000	4.000	= -c12
y13	0.000	0.000	1.000	0.000	0.000	0.000	0.000	0.000	1.000	= -c13
y24	0.000	0.000	0.000	1.000	0.000	0.000	0.000	0.000	2.000	= -c24
y25	0.000	0.000	0.000	0.000	1.000	0.000	0.000	0.000	4.000	= -c25
y32	0.000	0.000	0.000	0.000	0.000	1.000	0.000	0.000	3.000	= -c32
y34	0.000	0.000	0.000	0.000	0.000	0.000	1.000	0.000	3.000	= -c34
y45	0.000	0.000	0.000	0.000	0.000	0.000	0.000	1.000	6.000	= -c45
-1	0.000	0.000	0.000	0.000	1.000	0.000	0.000	1.000	0.000	= obj
	=s03	=s12	=s13	=s24	=s25	=s32	=s34	=s45	=dualobj	
									-	
	x03	0	x13	x24	x25	x32	x34	x45	-1	
s01	0.000	1.000	-1.000	-1.000	-1.000	1.000	0.000	0.000	0.000	= -x01
s12	0.000	1.000	0.000	-1.000	-1.000	1.000	0.000	0.000	0.000	= -x12
mu3	1.000	-0.000	1.000	0.000	0.000	-1.000	-1.000	0.000	0.000	= -0
mu4	0.000	-0.000	0.000	1.000	0.000	0.000	1.000	-1.000	0.000	= -0
y01	0.000	-1.000	1.000	1.000	1.000	-1.000	0.000	0.000	5.000	= -c01
y03	1.000	-0.000	0.000	0.000	0.000	0.000	0.000	0.000	6.000	= -c03
y12	0.000	-1.000	0.000	1.000	1.000	-1.000	0.000	0.000	4.000	= -c12
y13	0.000	-0.000	1.000	0.000	0.000	0.000	0.000	0.000	1.000	= -c13
y24	0.000	-0.000	0.000	1.000	0.000	0.000	0.000	0.000	2.000	= -c24
y25	0.000	-0.000	0.000	0.000	1.000	0.000	0.000	0.000	4.000	= -c25
y32	0.000	-0.000	0.000	0.000	0.000	1.000	0.000	0.000	3.000	= -c32
y34	0.000	-0.000	0.000	0.000	0.000	0.000	1.000	0.000	3.000	= -c34
y45	0.000	-0.000	0.000	0.000	0.000	0.000	0.000	1.000	6.000	= -c45
-1	0.000	-0.000	0.000	0.000	1.000	0.000	0.000	1.000	0.000	= obj
	=s03	=mu2	=s13	=s24	=s25	=s32	=s34	=s45	=dualobj	
	x03	x13	x24	x25	x32	x34	x45	-1		
s01	0.000	-1.000	-1.000	-1.000	1.000	0.000	0.000	0.000	= -x01	
s12	0.000	0.000	-1.000	-1.000	1.000	0.000	0.000	0.000	= -x12	
mu3	1.000	1.000	0.000	0.000	-1.000	-1.000	0.000	0.000	= -0	
mu4	0.000	0.000	1.000	0.000	0.000	1.000	-1.000	0.000	= -0	
y01	0.000	1.000	1.000	1.000	-1.000	0.000	0.000	5.000	= -c01	
y03	1.000	0.000	0.000	0.000	0.000	0.000	0.000	6.000	= -c03	
y12	0.000	0.000	1.000	1.000	-1.000	0.000	0.000	4.000	= -c12	
y13	0.000	1.000	0.000	0.000	0.000	0.000	0.000	1.000	= -c13	
y24	0.000	0.000	1.000	0.000	0.000	0.000	0.000	2.000	= -c24	
y25	0.000	0.000	0.000	1.000	0.000	0.000	0.000	4.000	= -c25	
y32	0.000	0.000	0.000	0.000	1.000	0.000	0.000	3.000	= -c32	
y34	0.000	0.000	0.000	0.000	0.000	1.000	0.000	3.000	= -c34	
y45	0.000	0.000	0.000	0.000	0.000	0.000	1.000	6.000	= -c45	
-1	0.000	0.000	0.000	1.000	0.000	0.000	1.000	0.000	= obj	
	=s03	=s13	=s24	=s25	=s32	=s34	=s45	=dualobj		
	0	x13	x24	x25	x32	x34	x45	-1		
s01	-0.000	-1.000	-1.000	-1.000	1.000	0.000	0.000	0.000	= -x01	
s12	-0.000	0.000	-1.000	-1.000	1.000	0.000	0.000	0.000	= -x12	
s03	1.000	1.000	0.000	0.000	-1.000	-1.000	0.000	0.000	= -x03	
mu4	-0.000	0.000	1.000	0.000	0.000	1.000	-1.000	0.000	= -0	
y01	-0.000	1.000	1.000	1.000	-1.000	0.000	0.000	5.000	= -c01	
y03	-1.000	-1.000	0.000	0.000	1.000	1.000	0.000	6.000	= -c03	
y12	-0.000	0.000	1.000	1.000	-1.000	0.000	0.000	4.000	= -c12	
y13	-0.000	1.000	0.000	0.000	0.000	0.000	0.000	1.000	= -c13	
y24	-0.000	0.000	1.000	0.000	0.000	0.000	0.000	2.000	= -c24	
y25	-0.000	0.000	0.000	1.000	0.000	0.000	0.000	4.000	= -c25	
у32	-0.000	0.000	0.000	0.000	1.000	0.000	0.000	3.000	= -c32	
y34	-0.000	0.000	0.000	0.000	0.000	1.000	0.000	3.000	= -c34	
y45	-0.000	0.000	0.000	0.000	0.000	0.000	1.000	6.000	= -c45	
-1	-0.000	0.000	0.000	1.000	0.000	0.000	1.000	0.000	= obj	
	=mu3	=s13	=s24	=s25	=s32	=s34	=s45	=dualobj		
	12	2.4	25	2.2	2.4	4 5	1			
s01	x13 -1.000	x24	x25 -1.000	x32	x34 0.000	x45 0.000	$-1 \\ 0.000$	01		
		-1.000		1.000				= -x01		
s12	0.000	-1.000	-1.000	1.000	0.000	0.000	0.000	= -x12		
s03	1.000	0.000 1.000	0.000	-1.000 0.000	-1.000 1.000	0.000 -1.000	0.000	= -x03 = -0		
mu4										
y01	1.000	1.000	1.000	-1.000 1.000	0.000	0.000	5.000	= -c01		
y03	-1.000 0.000	1.000	0.000 1.000	-1.000	1.000	0.000	6.000 4.000	= -c03 = -c12		
y12 y13	1.000	0.000	0.000	0.000	0.000	0.000	1.000	= -c12 = -c13		
y13 y24	0.000	1.000	0.000	0.000	0.000	0.000	2.000	= -c13 = $-c24$		
y24 y25	0.000	0.000	1.000	0.000	0.000	0.000	4.000	= -c24 = $-c25$		
y25 y32	0.000	0.000	0.000	1.000	0.000	0.000	3.000	= -c25 = -c32		
y32 y34	0.000	0.000	0.000	0.000	1.000	0.000	3.000	= -c32 = -c34		
y34 y45	0.000	0.000	0.000	0.000	0.000	1.000	6.000	= -c34 = $-c45$		
-1	0.000	0.000	1.000	0.000	0.000	1.000	0.000	045 = obj		
-1	=s13	=s24	=s25	=s32	=s34	=s45	=dualobj	_ (00)		
	-513	-524	-543	-532	-534	-543	-duaron]			
	v 12	n	¥25	×33	¥34	y45	_1			
g01	x13 -1.000	0 1.000	x25 -1.000	x32 1.000	x34 1.000	x45 -1.000	-1 0.000	= _x01		
s01 s12	-1.000	1.000	-1.000	1.000	1.000	-1.000	0.000	= -x01 = $-x12$		
s12	-1.000 0.000	1.000 1.000	-1.000 -1.000	1.000 1.000	1.000 1.000	-1.000 -1.000	0.000	= -x12		
	-1.000	1.000	-1.000	1.000	1.000	-1.000	0.000			

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y01
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                                                                       0.000
                                                                                 3.000
       y45
                0.000
                          -0.000
                                      0.000
                                                 0.000
                                                            0.000
                                                                       1.000
                                                                                  6.000
        -1
                0.000
                          -0.000
                                      1.000
                                                 0.000
                                                            0.000
                                                                       1.000
                                                                                  0.000
                 =s13
                                       =s25
                                                  =s32
                                                            =s34
                                                                        =s45
                                                                              =dualobi
                            =mu4
                  x13
                             x25
                                        x32
                                                   x34
                                                              x45
                                                                          -1
       s01
               -1.000
                          -1.000
                                      1.000
                                                 1.000
                                                           -1.000
                                                                       0.000
                                                                                = -x01
       s12
                0.000
                          -1.000
                                     1.000
                                                1.000
                                                           -1.000
                                                                       0.000
                                                                                = -x12
                                                                                = -x03
       s03
                1.000
                          0.000
                                     -1.000
                                                -1.000
                                                           0.000
                                                                       0.000
                           0.000
                                                                                = -x24
       s24
                0.000
                                     0.000
                                                1.000
                                                           -1.000
                                                                       0.000
       y01
                1.000
                           1.000
                                     -1.000
                                                -1.000
                                                           1.000
                                                                       5.000
                                                                                = -c01
               -1.000
                           0.000
                                                 1.000
                                                            0.000
                                                                       6.000
       v03
                                     1.000
                                                                                = -c03
       y12
                0.000
                           1.000
                                     -1.000
                                                -1.000
                                                            1.000
                                                                       4.000
                                                                                = -c12
       y13
                1,000
                           0.000
                                      0.000
                                                0.000
                                                            0.000
                                                                       1.000
                                                                                = -c13
                0.000
                           0.000
                                      0.000
                                                -1.000
                                                            1.000
                                                                                = -c24
       y24
                                                                       2.000
       y25
                0.000
                           1.000
                                      0.000
                                                 0.000
                                                            0.000
                                                                       4.000
                                                                                = -c25
       y32
                0.000
                           0.000
                                      1.000
                                                 0.000
                                                            0.000
                                                                       3.000
                                                                                = -c32
                                                                                = -c34
       y34
                0.000
                           0.000
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                                                 1.000
                                                            0.000
                                                                       3.000
       y45
                0.000
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                                                                                = -c45
                0.000
                           1.000
                                      0.000
                                                 0.000
                                                            1.000
                                                                       0.000
        _1
                                                                                 = obj
                 =s13
                            =s25
                                       =s32
                                                  =s34
                                                             =s45
                                                                   =dualobj
Initial tableau
                  x13
                             x25
                                        x32
                                                   x34
                                                             x45
                                                                          -1
       s01
               -1.000
                                                                       0.000
                          -1.000
                                     1.000
                                                 1.000
                                                          -1.000
                                                                                = -x01
       s12
                0.000
                          -1.000
                                     1.000
                                                 1.000
                                                           -1.000
                                                                       0.000
                                                                                = -x12
       s03
                1.000
                           0.000
                                     -1.000
                                                -1.000
                                                            0.000
                                                                       0.000
                                                                                = -x03
       s24
                0.000
                           0.000
                                     0.000
                                                1.000
                                                           -1.000
                                                                       0.000
                                                                                = -x24
                                                                                = -c01
       v01
                1.000
                           1.000
                                     -1.000
                                                -1.000
                                                           1.000
                                                                       5.000
               -1.000
                           0.000
                                     1.000
                                                1.000
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                                                                                = -c03
       y03
       y12
                0.000
                           1.000
                                     -1.000
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                                                                       4.000
                                                                                = -c12
       y13
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                                                                                = -c13
                           0.000
       y24
                0.000
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                                                                       2.000
       y25
                0.000
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                                                                       4.000
                                                                                = -c25
                0.000
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                                                                       3.000
                                                                                = -c32
                           0.000
                                      1.000
       y32
                                                                       3.000
                0.000
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                                                            0.000
       y34
                           0.000
                                      0.000
                                                                                = -c34
       y45
                0.000
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                                                            1.000
                                                                       6.000
                                                                                = -c45
        -1
                0.000
                           1.000
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                                                 0.000
                                                            1.000
                                                                       0.000
                                                                                 = obj
                            =s25
                                                  =s34
                                                             =s45
                 =s13
                                       =s32
                                                                   =dualobi
Starting SimplexNBF (will do nothing if already basic feasible)
Starting SimplexBF (will do nothing if solution can already be determined)
                  x13
                             c12
                                       x32
                                                  x34
                                                             x45
       s01
               -1.000
                           1.000
                                      0.000
                                                 0.000
                                                            0.000
                                                                       4.000
                                                                                = -x01
                                                                       4.000
       s12
                0.000
                          1.000
                                     0.000
                                                0.000
                                                            0.000
                                                                                = -x12
       s03
                1,000
                          -0.000
                                     -1.000
                                                -1.000
                                                            0.000
                                                                       0.000
                                                                                = -x03
       s24
                0.000
                          -0.000
                                      0.000
                                                 1.000
                                                           -1.000
                                                                       0.000
                                                                                = -x24
                                                                       1.000
       y01
                1.000
                          -1.000
                                      0.000
                                                 0.000
                                                            0.000
       y03
               -1.000
                          -0.000
                                     1.000
                                                 1.000
                                                            0.000
                                                                       6.000
                                                                                = -c03
       s25
                0.000
                          1.000
                                     -1.000
                                                -1.000
                                                            1.000
                                                                       4.000
                                                                                = -x25
       y13
                1.000
                          -0.000
                                     0.000
                                                0.000
                                                            0.000
                                                                       1.000
                                                                                = -c13
       y24
                0.000
                          -0.000
                                      0.000
                                                -1.000
                                                           1.000
                                                                       2.000
                                                                                = -c24
       y25
                0.000
                          -1.000
                                      1.000
                                                 1.000
                                                           -1.000
                                                                       0.000
                                                                                = -c25
       y32
                0.000
                          -0.000
                                      1.000
                                                 0.000
                                                            0.000
                                                                       3.000
                                                                                = -c32
                0.000
                                                 1.000
                                                                       3.000
       v34
                          -0.000
                                      0.000
                                                            0.000
                                                                                = -c34
                                      0.000
                                                 0.000
                                                                       6.000
                0.000
                                                            1.000
       y45
                          -0.000
                                                                                = -c45
        -1
                0.000
                          -1.000
                                      1.000
                                                 1.000
                                                            0.000
                                                                      -4.000
                                                                                 = obj
                 =s13
                            =y12
                                       =s32
                                                  =s34
                                                            =s45
                                                                   =dualobj
                             c12
                  x13
                                        c25
                                                   x34
                                                             x45
                                                                          _1
       s01
                                     -0.000
                                                           0.000
                                                                       4.000
               -1.000
                           1.000
                                                 0.000
                                                                                = -x01
       s12
                0.000
                           1.000
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                                                 0.000
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                                                                       4.000
                                                                                = -x12
                1.000
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                                                                       0.000
                                                                                = -x03
       s24
                0.000
                          0.000
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                                                           -1.000
                                                                       0.000
                                                                                = -x24
       y01
                1.000
                          -1.000
                                     -0.000
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                                                                       1.000
                                                                                = -c01
               -1.000
                          1.000
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                                                            1.000
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       y03
                                                                                = -c03
       s25
                0.000
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                                                                                = -x25
                                                                                = -c13
                1.000
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                                     -0.000
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                                                            0.000
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       y13
       y24
                0.000
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                                     -0.000
                                                -1.000
                                                            1.000
                                                                       2.000
                                                                                = -c24
       s32
                0.000
                          -1.000
                                     1.000
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                                                           -1.000
                                                                       0.000
                                                                                = -x32
                          1.000
                                                -1.000
                0.000
                                     -1.000
                                                           1.000
                                                                       3.000
       y32
                                                                                = -c32
       y34
                0.000
                           0.000
                                     -0.000
                                                 1.000
                                                            0.000
                                                                       3.000
                                                                                = -c34
                0.000
                           0.000
                                     -0.000
                                                 0.000
                                                            1.000
                                                                       6.000
       y45
                                                                                = -c45
        -1
                0.000
                           0.000
                                     -1.000
                                                 0.000
                                                            1.000
                                                                      -4.000
                                                                                 = obj
                                       =y25
                 =s13
                            =y12
                                                  =s34
                                                            =s45
                                                                   =dualobi
                  x13
                             c12
                                        c25
                                                   x34
                                                              c24
                                                                          -1
       s01
               -1.000
                           1.000
                                      0.000
                                                 0.000
                                                           -0.000
                                                                       4.000
                                                                                = -x01
       s12
                0.000
                          1.000
                                      0.000
                                                 0.000
                                                           -0.000
                                                                       4.000
                                                                                = -x12
                          -1.000
                                                -1.000
       s03
                1.000
                                      1.000
                                                            1.000
                                                                       2.000
                                                                                = -x03
```

= -c01

= -c03

= -c12= -c13

= -c24

= -c25

= -c32

= -c34

= -c45

= obj

= -x24	2.000	1.000	0.000	-0.000	0.000	0.000	s24
= -c01	1.000	-0.000	0.000	0.000	-1.000	1.000	y01
= -c03	4.000	-1.000	1.000	-1.000	1.000	-1.000	y03
= -x25	4.000	-0.000	0.000	1.000	0.000	0.000	s25
= -c13	1.000	-0.000	0.000	0.000	0.000	1.000	y13
= -x45	2.000	1.000	-1.000	-0.000	0.000	0.000	s45
= -x32	2.000	1.000	0.000	1.000	-1.000	0.000	s32
= -c32	1.000	-1.000	0.000	-1.000	1.000	0.000	y32
= -c34	3.000	-0.000	1.000	0.000	0.000	0.000	y34
= -c45	4.000	-1.000	1.000	0.000	0.000	0.000	y45
= obj	-6.000	-1.000	1.000	-1.000	0.000	0.000	-1
	=dualobj	=y24	=s34	=y25	=y12	=s13	
	-1	c24	c34	c25	c12	x13	
= -x01	4.000	0.000	-0.000	0.000	1.000	-1.000	s01
= -x12	4.000	0.000	-0.000	0.000	1.000	0.000	s12
= -x03	5.000	1.000	1.000	1.000	-1.000	1.000	s03
= -x24	2.000	1.000	-0.000	-0.000	0.000	0.000	s24
= -c01	1.000	0.000	-0.000	0.000	-1.000	1.000	y01
= -c03	1.000	-1.000	-1.000	-1.000	1.000	-1.000	y03
= -x25	4.000	0.000	-0.000	1.000	0.000	0.000	s25
= -c13	1.000	0.000	-0.000	0.000	0.000	1.000	y13
= -x45	5.000	1.000	1.000	0.000	0.000	0.000	s45
= -x32	2.000	1.000	-0.000	1.000	-1.000	0.000	s32
= -c32	1.000	-1.000	-0.000	-1.000	1.000	0.000	y32
= -x34	3.000	-0.000	1.000	0.000	0.000	0.000	s34
= -c45	1.000	-1.000	-1.000	0.000	0.000	0.000	y45
= obj	-9.000	-1.000	-1.000	-1.000	0.000	0.000	-1
	=dualobj	=y24	=y34	=y25	=y12	=s13	

Problem has solution, final tableau is shown above

Out[22]: 0

Reading off of the output above, the maximium flow is nine. With flow as indicated in the table. They are:

x01 = 4 x03 = 5 x12 = 4 x13 = 0 x24 = 2 x25 = 4 x32 = 2 x34 = 3 x45 = 5

We can tell that there is an edge between cuts between (1,2),(2,5),(3,4),&~(2,4). This implies that $V_1=0,1,2,3$ and $V_2=4,5$.