

CS 101: Computer Programming and Utilization

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Structures & Unions
(Chapter 17++)

Recall the Student marks query program

- We used two arrays – one holding roll number and the other marks of the students.
- The programmer had to ensure that the two were tightly synchronized – i.e., the student whose roll number was at index **x** in the first array had to have the marks at index **x** in the second array.
- Often, we wish to store related information about **entities** in the problem domain.
 - Example: Customer Address, Customer ID, Customer Phone number of many customers.
- Sometimes we may also want to bind together **functions** that only operate on a specific entity's attributes.
 - Example: changeCustomerAddress, addPhoneNumber

Outline

- **Structure**
 - Basic facility provided in C++ to conveniently gather together information associated with an entity.
 - Inherited from the C language
- **Member functions**
 - New feature introduced in C++

Structures: Key Ideas

- Structure = collection of variables (aka attributes or members) denoting a new user defined type.
- Structure = *super variable*, denotes the memory used for all members
- Each structure has a name, the name refers to the super variable, i.e. entire collection and denotes the type being introduced.
- Each structure has a set of Attributes: each of a previously defined type.

Why structs?

- Open-ended user definable types
- Self-referential data structures can allow us to make useful structures
 - Lists, trees, etc.

Structure Types

- You can define a structure type for each entity that you want to represent on the computer
 - Example: To represent books, you can define a Book structure type, to represent students, you define a student data type and so on.
- When you define a structure type, you must say what variables each structure of that type will contain
 - A book type has a ISBN number, Publisher, Publish Date
 - A student has a name, roll number, address, current CPI, etc.

Defining a structure type

General form

```
struct structure-type{  
    member1-type member1-name;  
    member2-type member2-name;  
    ...  
};           // Don't forget the semicolon!
```

Example

```
struct Book{  
    char title[50];  
    double price;  
};
```

Book is a **user-defined data type**, just as **int**, **char**, **double** are primitive data types

Structure-type name and member names can be any identifiers

Self Referential....

```
struct item {  
    char *s;  
    struct item *next;  
};
```

Yes! This is legal!

- I.e., an **item** can point to another **item**
- ... which can point to another **item**
- ... which can point to yet another **item**
- ... etc.

Thereby forming a *list* of **items**

Creating Structures of A Type Defined Earlier

To create a structure variable of structure type Book, just write:

```
Book p, q;
```

This creates two structures: `p, q` of type `Book`.

Each created structure has all members defined in structure type definition.

Accessing members of a structure

```
p.price = 399;    // stores 399 into p.price.  
cout << p.title; // prints the name of the book p
```

Initializing structures

```
Book b = { "On Education" , 399};  
Book b2 = {"c++ made easy"}; // correct  
Book b3 = {456}; // Error
```

Stores “On Education” in `b.title` (null terminated as usual) and 399 into `b.price`

A value must be given for initializing each leading member

Just like with all variables, you can make a structure unmodifiable by adding the keyword `const`:

```
const Book c = { "The Outsider" , 250};
```

One Structure Can Contain Another

```
struct Point{  
    double x,y;  
};  
struct Circle{  
    Point center;    // contains Point  
    double radius;  
};  
Circle c1;  
c1.radius = 10;  
c1.center = {15, 20};  
// sets the x and y members of center member of c1
```

Assignment

One structure can be *assigned* to another

- All members of right hand side copied into corresponding members on the left
- Structure name stands for entire collection unlike array name which stands for address
- A structure can be thought of as a (super) variable

```
book b = { "On Education" , 399};  
book c;  
c = b;      // all members copied  
cout << c.price << endl; // will print 399
```

Arrays of Structures

```
Circle c[10];
```

```
Book library[100];
```

Creates arrays `c`, `library` which have elements of type `Circle` and `Book`

```
cin >> c[0].center.x;
```

Reads a value into the `x` coordinate of center of 0th Circle in array `c`

```
cout << library[5].title[3];
```

Prints 3rd character of the title of the 5th book in array `library`

Structures and Pointers

```
Book  b1;
```

```
Book* b2 = &b1;
```

```
b2 -> price = 140.99;
```

OR

```
(*b2).price = 140.99;
```

Because '.' operator
has higher precedence
than unary '*'

Structures and Functions

- Structures can be passed to functions by value (members are copied), or by reference
- Structures can also be returned. This will cause members to be copied back

Parameter Passing by Value

```
struct Point{double x, y;};  
Point midpoint(Point a, Point b){  
    Point mp;  
    mp.x = (a.x + b.x)/2;  
    mp.y = (a.y + b.y)/2;  
    return mp;  
}
```

Note that the
return value is
copied over to r

```
int main(){  
    Point p={10,20}, q={50,60};  
    Point r = midpoint(p,q);  
    cout << r.x << endl;  
  
    cout << midpoint(p,q).x << endl;  
}
```

Note that the
temporary
structure is used
as RHS

Parameter Passing by Reference

```
struct Point{double x, y;};  
Point midpoint(const Point &a, const Point &b){  
    Point mp;  
    mp.x = (a.x + b.x)/2;  
    mp.y = (a.y + b.y)/2;  
    return mp;  
}  
int main(){  
    Point p={10,20},    q={50,60};  
    Point r = midpoint(p,q);  
    cout << r.x << endl;  
}
```

A Structure to Represent 3 Dimensional Vectors

- Suppose you are writing a program involving velocities and accelerations of particles which move in 3 dimensional space
- These quantities will have a component each for the x, y, z directions
- Natural to represent using a structure with members x, y, z

```
struct Vec{ double x, y, z; };
```

Using Struct Vec

Vectors can be added or multiplied by a scalar. We might also need the length of a vector.

```
Vec sum(const Vec &a, const Vec &b){
    Vec v;
    v.x = a.x + b.x;
    v.y = a.y + b.y;
    v.z = a.z + b.z;
    return v;
}
Vec scale(const Vec &a, double f){
    Vec v;
    v.x = a.x * f; v.y = a.y * f; v.z = a.z * f;
    return v;
}
double length(const Vec &v){
    return sqrt(v.x*v.x + v.y*v.y + v.z*v.z);
}
```

Motion Under Uniform Acceleration

If a particle has an initial velocity u and moves under uniform acceleration a , then in time t it has a displacement $s = ut + at^2/2$, where u , a , s are vectors

To find the distance covered, we must take the length of the vector s

```
int main(){
    Vec  u, a, s;    // velocity,
                    // acceleration,
                    // displacement

    double t;        // time
    cin >> u.x >> u.y >> u.z >>
        a.x >> a.y >> a.z >> t;
    s = sum(scale(u,t), scale(a, t*t/2));
    cout << length(s) << endl;
}
```

Member functions

- Rather than creating functions that operate on structs, we sometimes find it useful to BIND these functions to the structure
 - When the function is relevant only to that collection of attributes.
- In C++, you can make the functions *a part of the struct definition itself*. Such functions are called **member functions**.
- By collecting together relevant functions into the definition of the struct, the code becomes better organized

Structures with Member Functions

```
struct Vec{  
    double x, y, z;  
    double length(){  
        return sqrt(x*x + y*y + z*z);  
    }  
};  
  
int main(){  
    Vec v={1,2,2};  
    cout << v.length() << endl;  
}
```

Length is the
member function

V is the receiver
of the call to
length.

References to
member variables
of the receiver.

The Complete Definition of Vec

```
struct Vec{  
    double x, y, z;  
    double length(){  
        return sqrt(x*x + y*y + z*z);  
    }  
    Vec sum(Vec b){  
        Vec v;  
        v.x = x+b.x; v.y=y+b.y; v.z=z+b.z;  
        return v;  
    }  
    Vec scale(double f){  
        Vec v;  
        v.x = x*f; v.y = y*f; v.z = z*f;  
        return v;  
    }  
}
```

Notice it takes only one Vec as an argument

Notice it takes only the scaling factor as an argument

Main Program

```
int main(){
    Vec u, a, s;
    double t;
    cin >> u.x >> u.y >> u.z >> a.x >> a.y
        >> a.z >> t;
    Vec ut = u.scale(t);
    Vec at2by2 = a.scale(t*t/2);
    s = ut.sum(at2by2);
    cout << s.length() << endl;

    // green statements equivalent to:
    cout << u.scale(t).sum(a.scale(t*t/2)).length()
        << endl;
}
```


One More Example: Taxi Dispatch

- Problem statement: Clients arrive and have to be assigned to (earliest waiting) taxies
- An important part of the solution was a **blackboard** on which we wrote down the ids of the waiting taxies
- How would we implement this using structs?
What structures should we create???

One More Example: Taxi Dispatch

- Customers are assigned taxis immediately if available
Information about customers never needs to be stored
- Each taxi is associated with just one piece of information: id . We can just use an `int` to store the id
- The blackboard however is associated with a lot of information:
array of ids of waiting taxis, front/last indices into the array

So we should create a struct to represent the blackboard

Representing the Blackboard

```
const int N=100;
struct Queue{
    int elements[N],
        nwaiting,
        front;

    bool insert(int v){
        ...
    }

    bool remove(int &v){
        ...
    }
};
```

- **N** = max no. of waiting taxis
- We call the struct a **Queue** rather than blackboard to reflect its function
- **nwaiting** = no. of taxis currently waiting
- **front** = index
- Elements[N] holds the IDs of the waiting taxis.
- Two operations on Queue: **inserting** elements and **removing** elements.
These become member functions

Member Function Insert

```
struct Queue{  
    ...  
    bool insert(int v){  
        if(nWaiting >= N) return false;  
        elements[(front + nWaiting)%N] = v;  
        nWaiting++;  
        return true;  
    }  
};
```

- A value can be inserted only if the queue has space
- The value must be inserted into the next empty index in the queue
- The number of waiting elements in the queue is updated
- Return value indicates whether operation was successful

Main Program

```
int main(){
    Queue q;
    q.front = q.nWaiting = 0;
    while(true){
        char c; cin >> c;
        if(c == 'd' ){
            int driver;
            cin >> driver;
            if(!q.insert(driver))
                cout << "Q is full\n" ;
        }
        else if(c == 'c' ){
            int driver;
            if(!q.remove(driver))
                cout << "No taxi available.\n" ;
            else cout << "Assigning <<driver<< endl;
        }
    }
}
```

A note on precedence of Operators . - > []

```
struct triangle tr, *trp=&tr;
```

```
tr.pkt1.x
```

```
trp->pt1.x
```

```
(tr.pt1).x
```

```
(trp->pt1).x    // Are all equivalent
```

```
++trp->pt1.x;    // will increment x by 1
```

Example: Arrays of structures

- Use of two parallel arrays

```
char *keyword[NKEYS]; /* keywords */  
int keycount[NKEYS]; /* counters of keywords */
```

- use of structures

```
struct key {  
    char *word;  
    int count;  
} keytab[NKEYS];
```

OR

```
struct key {  
    char *word;  
    int count;  
};  
struct key keytab[NKEYS];
```

Unions

- A **union** is like a **struct**, but only one of its members is stored, not all
 - I.e., a single variable may hold different types at different times
 - Storage is enough to hold largest member

- E.g.,

```
union {  
    int ival;  
    float fval;  
    char *sval;  
} u;
```


Unions (continued)

- It is *programmer's responsibility* to keep track of which type is stored in a **union** at any given time!
- E.g.,

```
struct taggedItem {  
    enum {iType, fType, cType} tag;  
    union {  
        int ival;  
        float fval;  
        char *sval;  
    } u;  
};
```

Members of **struct** are:–

enum tag;

union u;

Value of **tag** says which member of **u** to use

Union Types

- E.g.,

```
typedef union{  
    bool wears_wig;  
    char color[20];  
} hair_t;
```

- Suppose we declare a variable

```
hair_t hair_data;
```

- `hair_data` contains either the `wears_wig` component or the `color` component but not both.

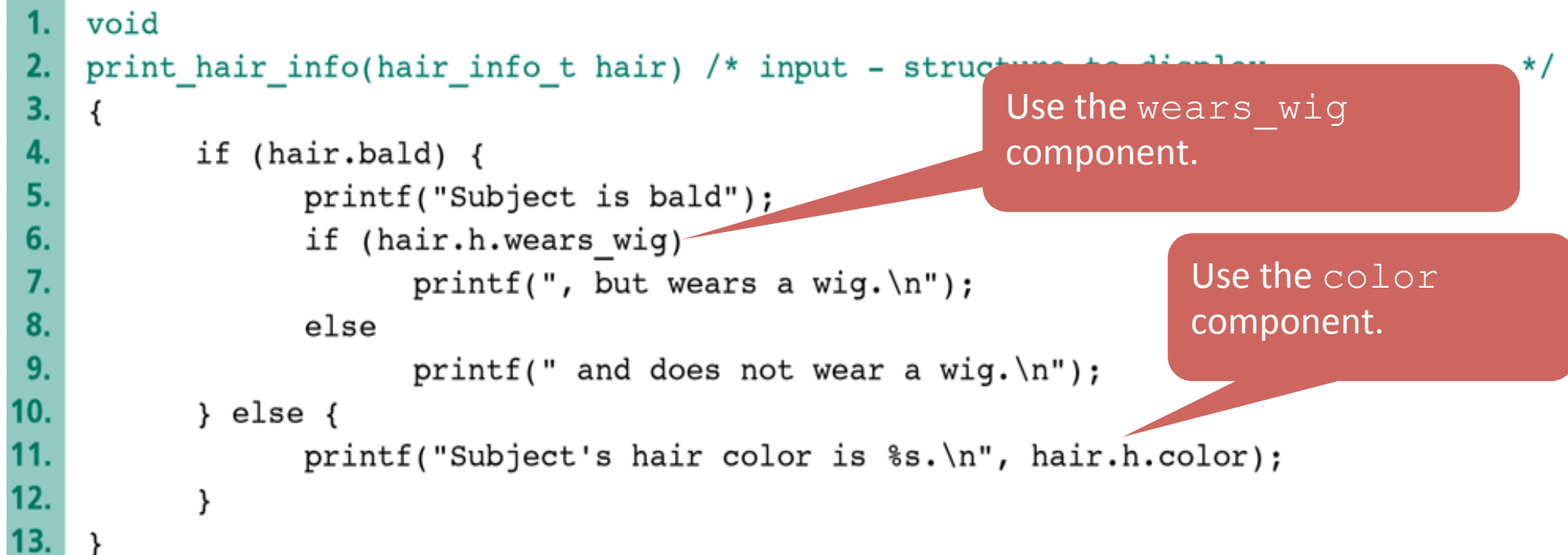
A Function Using a Union Structure

- Suppose we have a structure variable.

```
Struct hair_info_t {  
    bool bald;  
    hair_t h;  
};
```

- We can use this structure to reference the correct component.

```
1. void  
2. print_hair_info(hair_info_t hair) /* input - structure to display */  
3. {  
4.     if (hair.bald) {  
5.         printf("Subject is bald");  
6.         if (hair.h.wears_wig)  
7.             printf(", but wears a wig.\n");  
8.         else  
9.             printf(" and does not wear a wig.\n");  
10.    } else {  
11.        printf("Subject's hair color is %s.\n", hair.h.color);  
12.    }  
13. }
```

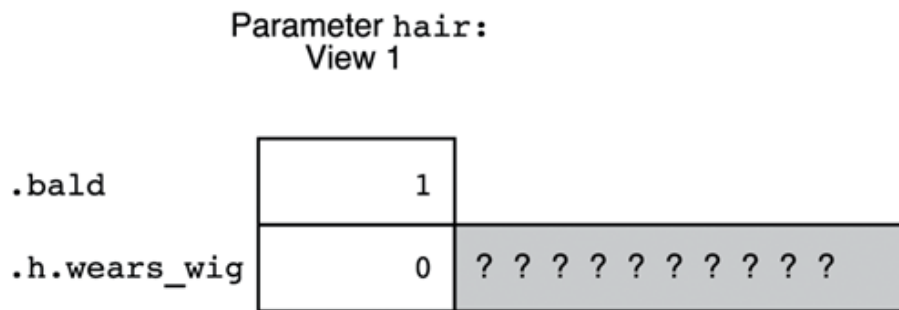


Use the wears_wig component.

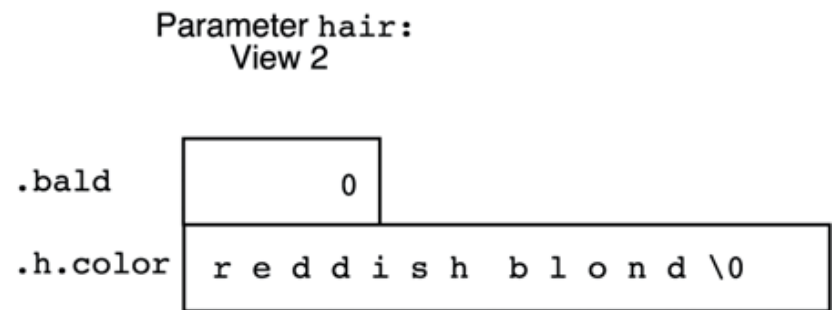
Use the color component.

Two Interpretations of the Union Variable `hair_t`

- The memory content of `hair_t` depends on which component is referenced.
 - The memory allocated for `hair_t` is determined by the **largest** component in the union.



The `wears_wig` component is referenced.



The `color` component is referenced.

Unions (continued)

- **unions** are used much less frequently than **structs** — mostly
 - in the inner details of operating system
 - in device drivers
 - in embedded systems where you have to access registers defined by the hardware