MA 106 (Linear Algebra)

Tutorials- 4&5 (31st Jan and 7th Feb 2018) - Version 2 Most of these problems are from reference texts for this course

- 1. Are the following vectors linearly independent?
 - (a) $(1,3,2)^T$, $(2,1,3)^T$, $(3,2,1)^T$.
 - (b) $(1, -3, 2)^T$, $(2, 1, -3)^T$, $(-3, 2, 1)^T$.
- 2. Let $v_1 = (1,0,0)^T$, $v_2 = (1,1,0)^T$, $v_3 = (1,1,1)^T$ and $v_4 = (2,3,4)^T$.
 - (a) v_1, v_2, v_3, v_4 are linearly dependent because ____.
 - (b) Find scalars a_1, a_2, a_3, a_4 , not all zero, such that $a_1v_1 + a_2v_2 + a_3v_3 + a_4v_4 = 0$.
 - (c) Show that v_1, v_2, v_3 are linearly independent.
 - (d) Find all combinations of 3 vectors from v_1, v_2, v_3, v_4 , which are linearly independent.
 - (e) Compute the rank of $A = (v_1 \ v_2 \ v_3 \ v_4)$, and the dimensions of its four fundamental spaces.
- 3. Find the largest possible number of independent vectors among: $v_1 = (1, -1, 0, 0)^T$, $v_2 = (1, 0, -1, 0)^T$, $v_3 = (1, 0, 0, -1)^T$, $v_4 = (0, 1, -1, 0)^T$, $v_5 = (0, 1, 0, -1)^T$, $v_6 = (0, 0, 1, -1)^T$. How is this number related to Span $\{v_1, \ldots, v_6\}$?
- 4. x = v + w and y = v w are combinations of v and w. Show that v and w can be written as combinations of x and y. How are $\text{Span}\{v,w\}$ and $\text{Span}\{x,y\}$ related? When is each pair of vectors a basis for its span?
- 5. Construct a 3×3 matrix whose column space contains (1,1,0) and (1,0,1), but not (1,1,1). Construct a 3×3 matrix whose column space is only a line.
- 6. Suppose A is a 5×4 matrix with rank(A) = 4. Show that Ax = v has no solution if and only if the 5×5 matrix [A|v] is invertible. Show Ax = v is solvable when [A|v] is singular.
- 7. The matrix $A = \begin{pmatrix} 2 & -2 \\ 2 & -2 \end{pmatrix}$ is a vector in M, the space of all 2×2 matrices. Write the zero vector in this space, the vectors $\frac{1}{2}A$ and -A. What matrices are in the smallest subspace containing A?
- 8. Fill in the blanks.
 - (a) If A is an invertible 8×8 matrix, then its column space is ____. Why?
 - (b) A is a 6×4 matrix whose columns are independent. The number of pivots of A are ____. Why?
 - (c) Consider $f=1, g=x, h=x^2 \in \mathcal{C}[0,1]$. Then $\mathrm{Span}\{f,g,h\}=\dots$. It has a basis \dots and its dimension is \dots .
 - (d) Let $W = \operatorname{Span}\{\cos(x), \sin(x)\} \subset \mathcal{C}[0, 1]$. A basis of W is ___, and $\dim(W) = _{--}$.
 - (e) A basis for the subspace of symmetric 3 × 3 matrices is ___, and its dimension is ___. Do the same for the subspaces of diagonal, skew-symmetric and lower triangular matrices respectively.

- 9. Are the following true or false? Briefly explain if it is true, give a counter-example if it is false.
 - (a) There is a 3×3 matrix A whose column space is the same as its null space.
 - (b) If the columns of a matrix are dependent, so are the rows.
 - (c) The columns of a matrix are a basis for its column space.
 - (d) A and A^T have the same number of pivots.
 - (e) A and A^T have the same left null space.
 - (f) If the vectors v_1, \ldots, v_n span a subspace V, then $\dim(V) = n$.
 - (g) If v_1, \ldots, v_n are linearly independent in a vector space V, then $\dim(V) \geq n$.
 - (h) If W is a subspace of V, then $\dim(W) \leq \dim(V)$.
 - (i) The intersection of two subspaces of a vector space V cannot be empty.
 - (j) If Ax = Ay, then x = y.
 - (k) If a square matrix A has independent columns, then so does A^2 .
 - (l) If AB = 0, then C(B) is contained in N(A) (and the row space of A is contained in the left null space of B).
 - (m) If the row space equals the column space, then $A = A^{T}$.
 - (n) If $A^T = -A$, then the row space of A equals its column space.
- 10. A and B are 3×3 matrices. Mark all the correct options. Justify.
 - (a) $C(A) = \{0\} \Rightarrow A = 0$.
 - (b) C(2A) = C(A).
 - (c) C(A I) = C(A).
 - (d) $C(A) = C(A^T)$.
 - (e) $\dim(C(A)) = \dim(C(A^T))$.
 - (f) $\operatorname{rank}(AB) \leq \operatorname{rank}(A)$. (Hint: How are C(AB) and C(A) related?)
 - (g) $C(A+B) \subseteq C(A)$.
- 11. Describe the subspace of \mathbb{R}^3 spanned by:
 - (a) $u_1 = (1, 1, -1)^T$ and $u_2 = (-1, -1, 1)^T$.
 - (b) $v_1 = (0, 1, 1)^T$, $v_2 = (1, 1, 0)^T$ and $v_3 = (0, 0, 0)^T$.
 - (c) The columns of a 3×5 echelon matrix with 2 pivots.
 - (d) All vectors with positive components.
- 12. Is v in Span $\{v_1, \ldots, v_n\}$? If yes, write v as a combination of the v_i 's.
 - (a) $v_1 = (1, 1, 0)^T$, $v_2 = (2, 2, 1)^T$, $v_3 = (0, 0, 2)^T$; $b = (3, 4, 5)^T$.
 - (b) $v_1 = (1, 2, 0)^T$, $v_2 = (2, 5, 0)^T$, $v_3 = (0, 0, 2)^T$, $v_4 = (0, 0, 0)^T$; $v = (a, b, c)^T$.

In each case, find a basis of $Span\{v_1, \ldots, v_n\}$.

- 13. Let **P** be the plane x 2y + 3z = 0 in \mathbb{R}^3 .
 - (a) Find a basis for **P**.
 - (b) Find a basis for the space of all the vectors perpendicular to **P**.
 - (c) Find a basis for the intersection of \mathbf{P} with the x-y plane.

- 14. Find a basis for each of the following subspaces of \mathbb{R}^4 .
 - (a) All vectors whose components are equal.
 - (b) All vectors whose components add to zero.
 - (c) All vectors that are perpendicular to $(1,1,0,0)^T$ and $(1,0,1,1)^T$.
- 15. Find the echelon forms U, basis and the dimension of the four fundamental subspaces of:

$$A = \begin{pmatrix} 0 & 1 & 2 & 3 & 4 \\ 0 & 1 & 2 & 4 & 6 \\ 0 & 0 & 0 & 1 & 2 \end{pmatrix} \qquad B = \begin{pmatrix} 1 & 2 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 2 & 0 & 1 \end{pmatrix} \qquad C = \begin{pmatrix} 0 & 1 & 4 & 0 \\ 0 & 2 & 8 & 0 \end{pmatrix}.$$

- 16. Without computing A, find bases for the 4 fundamental subspaces: $A = \begin{pmatrix} 1 & 0 & 0 \\ 6 & 1 & 0 \\ 9 & 8 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 & 3 & 4 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 1 & 2 \end{pmatrix}$.
- 17. Let A be $m \times n$ with rank r. Suppose there are right hand sides b for which Ax = b is not solvable.
 - (a) What inequalities must be true between m, n and r?
 - (b) Explain why $A^T y = 0$ has non-trivial solutions.
- 18. Let $v_1, v_2, v_3, v_4 \in \mathbb{R}^3$ be vectors such that:
 - (i) $\text{Span}\{v_1, v_2, v_3, v_4\} = \mathbb{R}^3$ and (ii) the vectors $\{v_2, v_3, v_4\}$ are linearly independent.

For each of the following statements, state if it is true or false. Justify.

- (a) The vectors $\{v_1, v_2, v_3, v_4\}$ are linearly independent.
- (b) The vectors $\{v_1, v_2, v_3\}$ form a spanning set for \mathbb{R}^3 .
- (c) The vectors $\{v_2, v_3\}$ are linearly independent.
- (d) For any other vector v_5 in \mathbb{R}^3 , the vectors $\{v_1, v_2, v_3, v_4, v_5\}$ form a spanning set for \mathbb{R}^3 .
- (e) The vectors $v_2 + v_3$, $v_2 + v_4$, $v_3 + v_4$ are linearly independent.
- 19. If A is $m \times n$, the columns of A are n vectors in \mathbb{R}^m . If they are linearly independent, what is $\operatorname{rank}(A)$? If they span \mathbb{R}^m , what is $\operatorname{rank}(A)$? What happens if they are a basis of \mathbb{R}^m ?
- 20. Fill in the blanks: Let A be an $m \times n$ matrix, with rank r.
 - (a) If A has linearly independent columns, then $r = \dots$, the nullspace is \dots , and the row space is \dots .
 - (b) If Ax = b always has at least one solution, then the solutions to $A^Ty = 0$ is/are ____. (Hint: Find r).
 - (c) If m = n = 3 and A is invertible, then a basis for (i) N(A) is ____, (ii) C(A) is ____, (iii) $N(A^T)$ is ____ and (iv) $C(A^T)$ is ____. Do the same for the 3×6 matrix $B = \begin{pmatrix} A & A \end{pmatrix}$.
 - (d) If m=7, n=9 and r=5, then the dimension of (i) N(A) is ____, (ii) C(A) is ____, (iii) $N(A^T)$ is ____ and (iv) $C(A^T)$ is ____.
 - (e) If m=3, n=4 and r=3, then $C(A)=\ldots$ and $N(A^T)=\ldots$.
 - (f) If B is obtained by exchanging the first two rows of A, then the fundamental subspaces which remain unchanged are $___$.
 - (g) With B as above, if (1, 2, 3, 4) is in the left nullspace of A, a non-zero vector in the left nullspace of B is ___.

- 21. Let \mathcal{P} be the set of polynomials with real coefficients. Show that \mathcal{P} is a real vector space under term-wise addition and scalar multiplication. Can you find a linearly independent set of size 2? 3? 50?
- 22. Let $\mathcal{P}_2 = \{a_0 + a_1X + a_2X^2 : a_0, a_1, a_2 \text{ are in } \mathbb{R}\}$ be the set of polynomials of degree two or less.
 - (a) Show that \mathcal{P}_2 is a subspace of \mathcal{P} .
 - (b) Show that Span $\{1, X, X^2\} = \mathcal{P}_2$.
 - (c) Find a basis for \mathcal{P}_2 and its dimension.
- 23. Use the cofactor matrix C to invert matrices A and B.

$$A = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 2 \\ 1 & 2 & 3 \end{pmatrix}, \quad B = \begin{pmatrix} 1 & 2 & 0 \\ 0 & 3 & 0 \\ 0 & 4 & 1 \end{pmatrix}$$

24. Compute the determinant of the following matrices.

$$A = \begin{pmatrix} 0 & 2 & 1 & 3 \\ 1 & 0 & -2 & 2 \\ 3 & -1 & 0 & 1 \\ -1 & 1 & 2 & 0 \end{pmatrix}, \quad B = \begin{pmatrix} 1 & -1 & 2 & -1 \\ -3 & 4 & 1 & -1 \\ 2 & -5 & -3 & 8 \\ -2 & 6 & -4 & 1 \end{pmatrix}.$$

25. Find x, y, z by Cramer's rule:

$$x + 4y - z = 1$$
, $x + y + z = 0$, $2x + 3z = 0$

- 26. Find the determinant when a vector x replaces j-th column of I.
- 27. If the right side b is the last column of A, solve the 3×3 system Ax = b. Explain how each determinant in Cramer's rule leads to your solution x.
- 28. If all the cofactors are zero, is A invertible? Why or why not?
- 29. Suppose det(A) = 1 and you know all the cofactors. How will you find A?
- 30. L is lower triangular and S is symmetric. Assume they are invertible.

$$L = \begin{pmatrix} a & 0 & 0 \\ b & c & 0 \\ d & e & f \end{pmatrix}, \quad S = \begin{pmatrix} a & b & d \\ b & c & e \\ d & e & f \end{pmatrix}$$

- (a) Which three cofactors of L are zero? (L^{-1} is lower triangular)
- (b) Which three pairs of cofactors of S are equal? $(S^{-1}$ is symmetric)
- 31. The parallelogram with sides (2,1) and (2,3) has the same area as the parallelogram with sides (2,2) and (1,3). Find those area by determinants and say why they must be equal.
- 32. (a) The corners of a triangle are (2,1),(3,4),(0,5). What is the area?
 - (b) A new corner at (-1,0) makes it lopsided (four sides). Find the area.
- 33. State true or false. If true, prove the statement, and if false, explain why and give a counter-example.
 - (a) Let V be a vector space. Then the union of two linearly independent subsets of V is linearly independent.

- (b) Let V be a vector space. Then the intersection of two linearly independent subsets of V is linearly independent.
- (c) Let $\dim(V) = n$. Any set $S \subseteq V$ with n elements spans V.
- (d) Let $\dim(V) = n$ Any set $S \subseteq V$ with n elements that spans V is linearly independent.
- (e) If $T:V\to V$ is a linear transformation of vector space V and $W\subseteq V$ a subspace of V. Then T(W) is a subspace of V.
- (f) There is no one-one linear transformation from $\mathbb{R}^3 \to \mathbb{R}^2$.
- (g) There is no onto linear transformation from $\mathbb{R}^3 \to \mathbb{R}^2$.
- (h) There is no one-one linear transformation from $\mathbb{R}^2 \to \mathbb{R}^3$.
- (i) There is no onto linear transformation from $\mathbb{R}^2 \to \mathbb{R}^3$.
- 34. Let $\dim(V) = n$ and $\mathcal{B} = \{v_1, v_2, \dots v_n\}$ be a basis of V.
 - (a) Let $T: V \to V$ be the transformation defined by $T(v_i) = v_{i+1}$ for all $i = 1, 2, \dots, n-1$ and $T(v_n) = 0$. Find the matrix A representing T with respect to the basis \mathcal{B} .
 - (b) Prove that $T^n = 0$ but $T^{n-1} \neq 0$.
- 35. Define $T: \mathbb{R}^2 \longrightarrow \mathbb{R}^2$ as Tu = Au. Describe what T does geometrically to a point in \mathbb{R}^2 for $A = \begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}$ (ii) $\begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$ (iii) $\begin{pmatrix} \frac{1}{2} & \frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & \frac{1}{2} \end{pmatrix}$ (iv) $\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$ (v) $\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$.
- 36. Show that the function $T: \mathcal{M}_{2\times 3} \to \mathcal{M}_{3\times 2}$ defined as $T(A) = A^t$ is a linear transformation. Show that this map is an isomorphism.
- 37. Show that $T: \mathbb{R}^4 \to \mathbb{R}^3$ defined as $T(x_1, x_2, x_3, x_4) = (x_1 + x_2, x_2 + x_3, x_3 + x_4)$ is a linear transformation. Find the standard matrix of T.
- 38. Find the standard matrix of $T: \mathbb{R}^2 \to \mathbb{R}^2$ defined as $T(x_1, x_2) = (x_1 + 2x_2, x_2)$. Can you find a basis \mathcal{B} of \mathbb{R}^2 such that $[T]_{\mathcal{B}}^{\mathcal{B}}$ is diagonal?
- 39. Define $D: \mathcal{P}_3 \to \mathcal{P}_2$ as $D(f) = \frac{df}{dx}$ for all polynomials f of degree less than or equal to 3. Show that this is a linear transformation. Find N(D) and C(D).
- 40. Show that $S_1, S_2 : \mathcal{M}_{n \times n} \to \mathcal{M}_{n \times n}$ defined as $S_1(A) = A + A^T$ and $S_2(A) = A A^T$ are linear transformations. Find $N(S_1), N(S_2), C(S_1)$ and $C(S_2)$.
- 41. Is $I: \mathcal{P} \to \mathcal{P}$ defined as $I(f) = \int f \, dx$ a linear transformation? Prove or disprove.
- 42. Construct a linear map T from $P_2(\mathbb{R}) \to \mathbb{R}$ such that T(1) = 1, T(1-x) = 2 and $T(x^2) = 3$. What is N(T) and C(T)? How many such maps can you construct? Is there one with T(x) = 0?

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