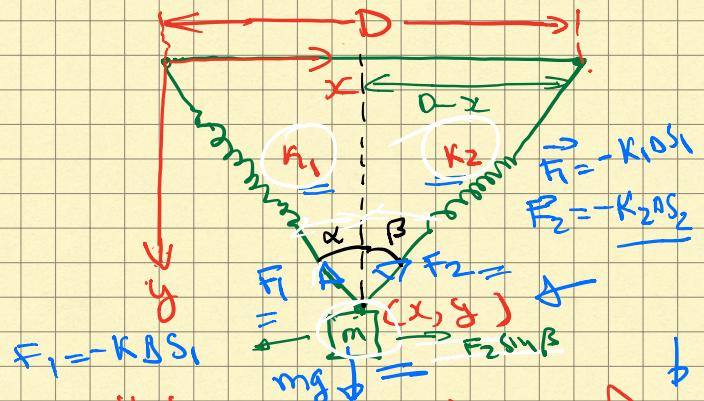


## Today's Plan:

- So far we have discussed examples from
  - Scheduling (OR)
  - Resource allocation (Economics)
- Today, we will take up a couple of examples from physical sciences
  - Our examples revolve around minimization of potential energy.

Example: [Michael Heath, Scientific Computing: An Introductory Survey, Chapter-6 Ex 6.1]

- Spring-1 has length  $L_1$  (unstretched) and spring constant  $K_1$ .
- Spring-2 has length  $L_2$  and spring constant  $K_2$ .



Q] What is the equilibrium position of mass  $m$  suspended from it?

Solution:

Let at the equilibrium position, coordinates of mass  $m$  be  $(x, y)$ . Then,

$$\text{Elongation of spring-1} = \sqrt{x^2 + y^2} - L_1 \quad PE_1 = \frac{1}{2} K_1 S_1^2$$

$$\text{Stretch in spring-2} = \sqrt{(D-x)^2 + y^2} - L_2 \quad PE_2 = \frac{1}{2} K_2 S_2^2$$

Total PE of the Spring mass system

$$V(x, y) = \frac{1}{2} K_1 (\sqrt{x^2 + y^2} - L_1)^2 + \frac{1}{2} K_2 (\sqrt{(D-x)^2 + y^2} - L_2)^2 - mgy$$

$$ss_1 = \sqrt{x^2+y^2} - l_1 \quad ss_2 = \sqrt{(D-x)^2+y^2} - l_2$$

$$\min_{(x,y)} V(x,y) \text{ and } (x^*, y^*) = \arg \min_{(x,y)} V(x,y)$$

A minimum of an unconstrained minimization problem is always a stationary point.

$$\left. \frac{\partial V}{\partial x} \right|_{xx} = 0 \Rightarrow k_1 (\sqrt{x^2+y^2} - l_1) \frac{x}{\sqrt{x^2+y^2}} + k_2 \frac{\sqrt{(D-x)^2+y^2} - l_2}{\sqrt{(D-x)^2+y^2}} (D-x) (-1) = 0$$

$$\Rightarrow k_1 (\sqrt{x^2+y^2} - l_1) \sin \alpha = k_2 \sqrt{(D-x)^2+y^2} \cdot \sin \beta.$$

$$\text{or } F_1 \sin \alpha = F_2 \sin \beta \quad \boxed{\text{Net horizontal force is zero}}$$

Similarly

$$\left. \frac{\partial V}{\partial y} \right|_{xx} = 0 \quad k_1 \left( \sqrt{x^2+y^2} - l_1 \right) \frac{y}{\sqrt{x^2+y^2}} + k_2 \frac{\sqrt{(D-x)^2+y^2} - l_2}{\sqrt{(D-x)^2+y^2}} \cdot \frac{y}{\sqrt{(D-x)^2+y^2}} - mg = 0$$

$$\text{or } k_1 (\sqrt{x^2+y^2} - l_1) \cos \alpha + k_2 (\sqrt{(D-x)^2+y^2} - l_2) \cos \beta = mg$$

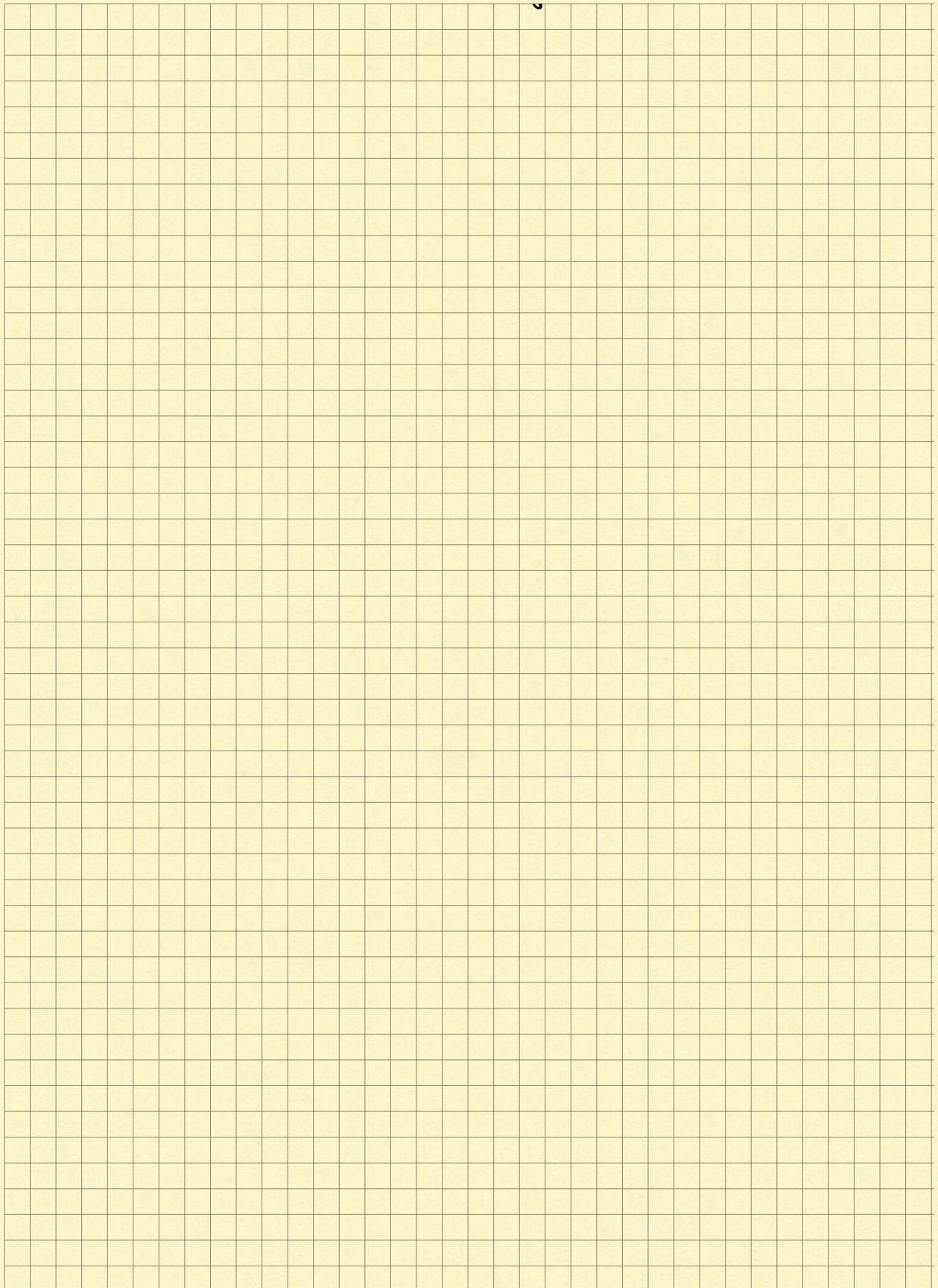
$$F_1 \cos \alpha + F_2 \cos \beta = mg.$$

From the fact that net force acting on mass  $m$  when at equilibrium, we get the same solution

$$F_1 \sin \alpha = F_2 \sin \beta$$

$$F_1 \sin \alpha + F_2 \cos \beta = mg$$

where  $F_1$  &  $F_2$  are the restoring forces set in the two springs



## An Example from Molecular Biology

Ref: J. Frédéric Bonnans, J. Charles Gilbert,  
Claude Lemaréchal and Claudia A.  
Sagastizábal: Numerical Optimization:  
Theoretical and Practical Aspects.

Problem: Determine the geometry of a molecule (application in pharmacy, biochemistry)

- Experimental methods like X-ray, crystallography, nuclear magnetic resonance give you initial estimates
- Choice of method depends upon whether
  - chemical formula of the molecule is known
  - molecule is not available, for experiments
  - existing knowledge on its shape has to be refined.

Principle: The position of atoms in the space will be such that associated potential energy is minimum.

Let  $N$  be the number of atoms  
e.g., 1000.

$x_i \in \mathbb{R}^3$  is the spatial position  
of  $i$ th atom.

Let  $X = (x_1, x_2, \dots, x_N) \in \underline{\mathbb{R}^{3N}}$ .

Let  $F(X) \rightarrow$  associated PE or conformation energy

$$F(X) = \sum_{ij} (\lambda_{ij} (x_i, x_j) + V_{ij} (x_i, x_j)) + \sum_{ijk} A_{ijk} (x_i, x_j, x_k)$$

where bond length component:

$$\lambda_{ij} (x_i, x_j) = \lambda_{ij} ((x_i - x_j) - d_{ij})^2$$

Van der Waals energy:

$$V_{ij} (x_i, x_j) = \frac{4\pi}{3} \left( \frac{\delta_{ij}}{|x_i - x_j|} \right)^3 - \frac{w_{ij}}{|x_i - x_j|}$$

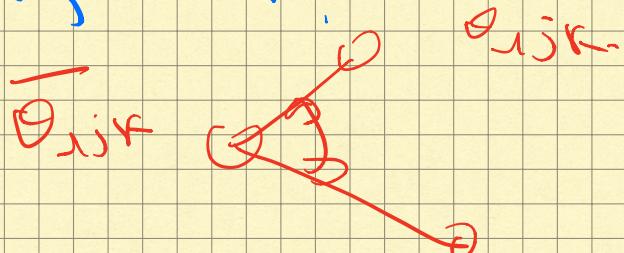
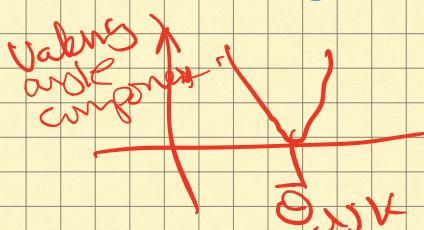
Here, the  $\lambda_{ij}$ ,  $V_{ij}$ ,  $w_{ij}$ ,  $\delta_{ij}$  are known constants depending upon pair of atoms involved (C-C, C-N etc)

Valency angle component:

$$A_{ijk} (x_i, x_j, x_k) = \alpha_{ijk} (\theta_{ijk} - \bar{\theta}_{ijk})^2$$

where  $\alpha_{ijk}$  and  $\bar{\theta}_{ijk}$  are known constants

- Even galaxies seek minimum energy configuration!



$\min f(x)$