



Parallel Staging Strategy



Series Staging Features

Staging concept and formulation **presented** previously is **typically** termed '**series**' or '**simple**' **staging**.

A basic **drawback** of series **staging** is the possible **interference** between the **two** stages at the **hand-shake** point. (i.e. burnout of one, **ignition** of next).



Series Staging Drawbacks

In particular, if **hand** shaking is to take place at a **lower** velocity in denser **atmosphere**, it can lead to **loss** of control of the vehicle due to **disturbances**.

Another issue with **series** staging is the **increase** in vehicle **length** with the increase in **number** of stages.



Series Staging Drawbacks

First impact of **increased** length is to **lower** the buckling **strength**, leading to extra structural **mass**.

Second impact is on the design of **control** systems due to very **low** structural vibration **frequencies**.



Parallel Staging Concept

Lastly, **longer** vehicles require a taller **launch** tower, resulting in significant **cost** escalation.

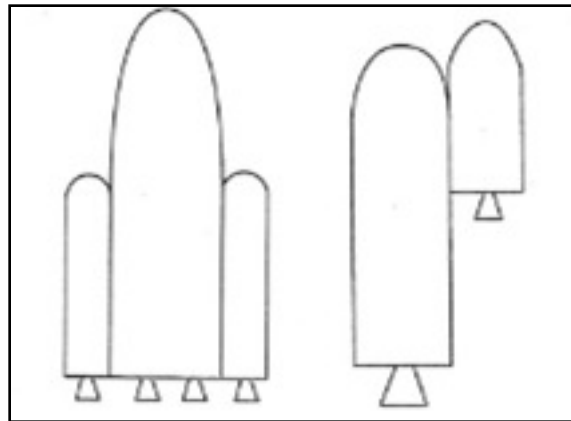
All these have given **rise** to the concept of 'strap-on boosters' bringing in the philosophy of **parallel** staging.



Parallel Staging Philosophy

Parallel staging aims to significantly **improve** the rocket **performance**, while maintaining its overall **length** and simplifying the **separation** manoeuvre.

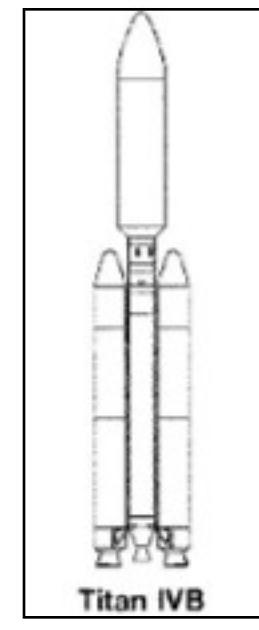
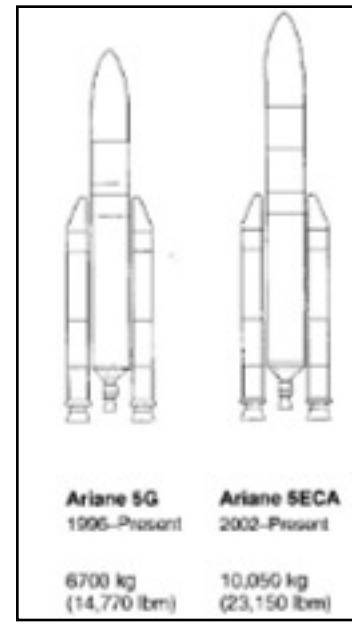
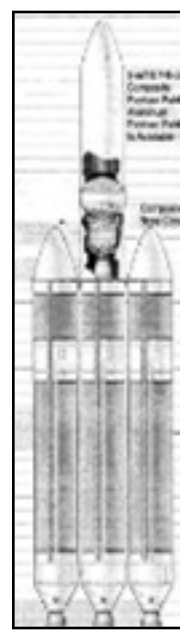
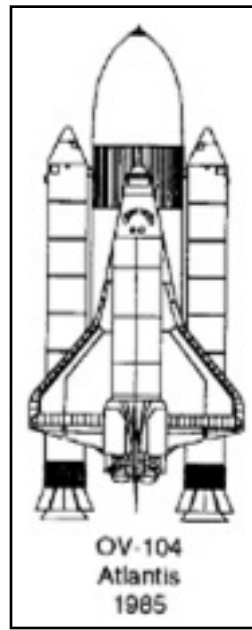
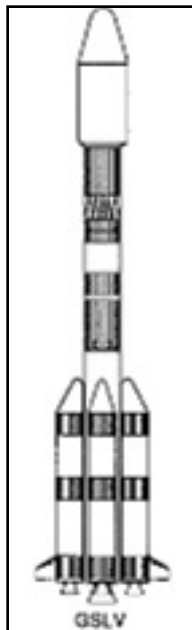
Given below are a few **typical** parallel staging **schemes**.





Parallel Staging Examples

Most **current** day launch vehicles employ **parallel staging**, as shown below.





PSLV Strap-on Configuration

PSLV has m_0 of **295T** & m_* of **3.5T**, for a mission in **space** station orbit at 407 km **altitude**.

$$\text{0-Stage: } I_{sp0} = 262s, \quad \varepsilon_0 = 0.182, \quad \pi_0 = 0.776$$

$$\text{1-Stage: } I_{sp1} = 264s, \quad \varepsilon_1 = 0.178, \quad \pi_1 = 0.267$$

$$\text{2-Stage: } I_{sp2} = 293s, \quad \varepsilon_2 = 0.116, \quad \pi_2 = 0.250$$

$$\text{3-Stage: } I_{sp3} = 291s, \quad \varepsilon_3 = 0.106, \quad \pi_3 = 0.444$$

$$\text{4-Stage: } I_{sp4} = 307s, \quad \varepsilon_4 = 0.251, \quad \pi_4 = 0.515$$



PSLV Strap-on Configuration

Individual **stage-masses** are as follows.

0-Stage: $m = 66T$; 1-Stage: $m = 168T$; 2-Stage: $m = 45.8T$
3-Stage: $m = 8.5T$; 4-Stage: $m = 3.3T$; $\pi_* = 0.0119$

We see that the strap-on **stage**, while not the heaviest, is **quite** bulky, which is trend common to **most** rockets.



Summary

To **summarize**, parallel staging is a **useful** concept that aims to **improve** the launch vehicle **performance**, while limiting the associated **drawbacks**.

We also note that booster or **strap-on** stage is quite bulky and **sometimes** can also be the heaviest **stage** in a rocket.