



Trade-off Ratio for Variant Design



Definition of Trade-off Ratios

Trade-off **ratios** are nothing but partial **derivatives** of the rocket performance **equations** with respect to the structural or the propellant mass **ratios**.

In general, the **aim** is to keep V_* as an **invariant**, while allowing m_* to change.



Trade-off Ratio Formulation

Thus, **we** can determine the **changes** in m_* for changes in stage **masses**.

Basic procedure uses V_* expression to **examine** the applicable **sensitivities**.

$$\text{Let } V_* = g_0 \sum_{i=1}^N I_{spi} \ln \frac{m_{0i}}{m_{fi}}, \text{ which is an invariant.}$$



Trade-off Ratio Formulation

Let the **initial** and final **masses** of i^{th} stage be,

$$\begin{aligned} m_{0i} &= m_* + m_{pi} + m_{si} + \sum_{j=i+1}^N (m_{sj} + m_{pj}) \\ m_{fi} &= m_* + m_{si} + \sum_{j=i+1}^N (m_{sj} + m_{pj}) \end{aligned}$$

We can write the **ideal** burnout velocity in **terms** of the above **expressions**, as follows.



Trade-off Ratio Formulation

$$V_* = g_0 \sum_{i=1}^N I_{spi} \ln \left(\frac{m_* + m_{pi} + m_{si} + \sum_{j=i+1}^N (m_{sj} + m_{pj})}{m_* + m_{si} + \sum_{j=i+1}^N (m_{sj} + m_{pj})} \right)$$

It is seen that V_* is a discrete **sum** of individual stage **contributions**, resulting in **sensitivities** as the **derivatives** of a piecewise continuous **function**.



Trade-off Ratio Solution

We define **total** variation of V_* , **along** with the **condition** of invariance of V_* , as follows.

$$dV_* = \frac{\partial V_*}{\partial m_{zi}} \delta m_{zi} + \frac{\partial V_*}{\partial m_*} \delta m_*; \quad dV_* = 0; \quad \frac{\delta m_*}{\delta m_{zi}} = - \frac{\left(\frac{\partial V_*}{\partial m_{zi}} \right)}{\left(\frac{\partial V_*}{\partial m_*} \right)}$$

$$dV_* = \frac{\partial V_*}{\partial m_{pi}} \delta m_{pi} + \frac{\partial V_*}{\partial m_*} \delta m_*; \quad dV_* = 0; \quad \frac{\delta m_*}{\delta m_{pi}} = - \frac{\left(\frac{\partial V_*}{\partial m_{pi}} \right)}{\left(\frac{\partial V_*}{\partial m_*} \right)}$$

Above **solution** establishes the possible **changes in m_*** due to changes in **m_{si} & m_{pi}** , for a constant V_* .



Trade-off Ratio Solution

Here, the **partial** derivatives (2 for each stage) establish the **sensitivity** of velocity to both m_* , $m_{si/pi}$.

Further, **evaluation** of these **derivatives** is to be carried out in the **context** of velocity being a discrete **function**.

This is demonstrated for a **2-stage** rocket next.



Trade-off Ratios for m_{si}

$$V_* = g_0 I_{sp1} \ln \frac{m_{01}}{m_{f1}} + g_0 I_{sp2} \ln \frac{m_{02}}{m_{f2}}$$

$$m_{01} = m_* + m_{s1} + m_{p1} + m_{s2} + m_{p2}$$

$$m_{f1} = m_* + m_{s1} + m_{s2} + m_{p2}$$

$$m_{02} = m_* + m_{s2} + m_{p2}; \quad m_{f2} = m_* + m_{s2}$$



Trade-off Ratios for m_{si}

$$\begin{aligned}\frac{\partial V_*}{\partial m_*} &= g_0 I_{sp1} \left(\frac{1}{m_{01}} - \frac{1}{m_{f1}} \right) + g_0 I_{sp2} \left(\frac{1}{m_{02}} - \frac{1}{m_{f2}} \right) \\ \frac{\partial V_*}{\partial m_{s1}} &= g_0 I_{sp1} \left(\frac{1}{m_{01}} - \frac{1}{m_{f1}} \right) \\ \frac{\partial V_*}{\partial m_{s2}} &= g_0 I_{sp1} \left(\frac{1}{m_{01}} - \frac{1}{m_{f1}} \right) + g_0 I_{sp2} \left(\frac{1}{m_{02}} - \frac{1}{m_{f2}} \right)\end{aligned}$$



Trade-off Ratios for m_{si}

$$\frac{\delta m_*}{\delta m_{s1}} \Big|_{dV_*=0} = - \frac{\left(\frac{\partial V_*}{\partial m_{s1}} \right)}{\left(\frac{\partial V_*}{\partial m_*} \right)} = - \frac{I_{sp1} \left(\frac{1}{m_{01}} - \frac{1}{m_{f1}} \right)}{I_{sp1} \left(\frac{1}{m_{01}} - \frac{1}{m_{f1}} \right) + I_{sp2} \left(\frac{1}{m_{02}} - \frac{1}{m_{f2}} \right)}$$

$$\frac{\delta m_*}{\delta m_{s2}} \Big|_{dV_*=0} = - \frac{\left(\frac{\partial V_*}{\partial m_{s2}} \right)}{\left(\frac{\partial V_*}{\partial m_*} \right)} = -1$$



Trade-off Ratio for m_{pi}

$$\frac{\partial V_*}{\partial m_{p1}} = g_0 I_{sp1} \left(\frac{1}{m_{01}} - 0 \right)$$
$$\frac{\partial V_*}{\partial m_{p2}} = g_0 I_{sp1} \left(\frac{1}{m_{01}} - \frac{1}{m_{f1}} \right) + g_0 I_{sp2} \left(\frac{1}{m_{02}} - 0 \right)$$



Trade-off Ratio for m_{pi}

$$\frac{\delta m_*}{\delta m_{p1}} \Big|_{dV_*=0} - \frac{\left(\frac{\partial V_*}{\partial m_{p1}} \right)}{\left(\frac{\partial V_*}{\partial m_*} \right)} = - \frac{I_{sp1} \left(\frac{1}{m_{01}} \right)}{I_{sp1} \left(\frac{1}{m_{01}} - \frac{1}{m_{f1}} \right) + I_{sp2} \left(\frac{1}{m_{02}} - \frac{1}{m_{f2}} \right)}$$

$$\frac{\delta m_*}{\delta m_{p2}} \Big|_{dV_*=0} - \frac{\left(\frac{\partial V_*}{\partial m_{p2}} \right)}{\left(\frac{\partial V_*}{\partial m_*} \right)} = - \frac{I_{sp1} \left(\frac{1}{m_{01}} - \frac{1}{m_{f1}} \right) + I_{sp2} \left(\frac{1}{m_{02}} \right)}{I_{sp1} \left(\frac{1}{m_{01}} - \frac{1}{m_{f1}} \right) + I_{sp2} \left(\frac{1}{m_{02}} - \frac{1}{m_{f2}} \right)}$$



Trade-off Ratio Generalization

$$\frac{\delta m_*}{\delta m_{si}} \Big|_{dV_*=0} = - \frac{\sum_{j=1}^i I_{spj} \left(\frac{1}{m_{0j}} - \frac{1}{m_{fj}} \right)}{\sum_{k=1}^N I_{spk} \left(\frac{1}{m_{0k}} - \frac{1}{m_{fk}} \right)}; \quad \frac{\delta m_*}{\delta m_{\varepsilon N}} = -1; \quad \text{Always} < 0$$

$$\frac{\delta m_*}{\delta m_{pi}} \Big|_{dV_*=0} = - \frac{\sum_{j=1}^{i-1} I_{spj} \left(\frac{1}{m_{0j}} - \frac{1}{m_{fj}} \right) + \frac{I_{spi}}{m_{0i}}}{\sum_{k=1}^N I_{spk} \left(\frac{1}{m_{0k}} - \frac{1}{m_{fk}} \right)}; \quad \text{Always} > 0$$



Summary

We see that trade-off **ratios** are an elegant mechanism to **understand** the launch vehicle stage **sensitivities**.

We also **note** that a small change in **configuration** based on the sensitivity, in the **vicinity** of parent configuration, has the **potential** to preserve the optimality of **solution**.