TOPICS IN MATHEMATICAL SCIENCE VIII

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Introduction to quiver representations and homological algebras

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Convention

Throughout the course, k will always be a field. All rings are unital and associative. We only really work with artinian rings (but sometimes noetherian is also OK). We always compose maps from right to left.

1 Reminder on some basics of rings and modules

Definition 1.1. Let R be a ring. A right R-module M is an abelian group (M, +) equipped with a (linear) R-action on the right of $M \cdot : M \times R \to M$, meaning that for all $r, s \in R$ and $m, n \in M$, we have

- $m \cdot 1 = m$,
- $(m+n) \cdot r = m \cdot r + n \cdot r$,
- $m \cdot (r+s) = m \cdot r + m \cdot s$,
- m(sr) = (ms)r.

Dually, a left R-module is one where R acts on the left of M (details of definition left as exercise). Sometimes, for clarity, we write M_A for right A-module and AM for left A-module.

Note that, for a commutative ring, the class of left modules coincides with that of right modules.

Example 1.2. R is naturally a left, and a right, R-module. Both are free R-module of rank 1. Sometimes this is also called regular modules but it clashes with terminology used in quiver representation and so we will avoid it.

In general, a free R-module F is one where there is a basis $\{x_i\}_{i\in I}$ such that for all $x\in F$, $x=\sum_{i\in I}x_ir_i$ with $r_i\in R$. We only really work with free modules of finite rank, i.e. when the indexing set I is finite. In such a case, we write R^n .

Convention. All modules are right modules unless otherwise specified.

Definition 1.3. Suppose R is a commutative ring. A ring A is called an R-algebra if there is a (unital) ring homomorphism $\theta: R \to A$ with image $\theta(R)$ being in the center $Z(A) := \{z \in A \mid za = az \ \forall a \in A\}$ of A. In such a case, A is an R-module and so we simply write ar for $a \in A$, $r \in R$ instead of $a\theta(r)$.

An (unital) R-algebra homomorphism $f: A \to A'$ is a (unital) ring homomorphism f that intertwines R-action, i.e. f(ar) = f(a)r.

The dimension of a k-algebra A is the dimension of A as a k-vector space; we say that A is finite-dimensional if $\dim_k A < \infty$.

Note that commutative ring theorists usually use dimension to mean Krull dimension, which has a completely different meaning.

Example 1.4. Every ring is a \mathbb{Z} -algebra.

The matrix ring $M_n(R)$ given by n-by-n matrices with entries in R is an R-algebra.

We will only really work with k-algebras, where k is a field. Most of the time, we will also assume k is algebraically closed for simplicity. But it worth reminding there are many interesting R-algebras for different R, such as group algebra. Recall that the *characteristic* of R, denoted by char R, is 0 if the additive order of the identity 1 is infinite, or else the additive order itself.

Example 1.5. Let G be a finite (semi)group and R a commutative ring. Let A := R[G] be the free R-module with basis G, i.e. every $a \in A$ can be written as the formal R-linear combination $\sum_{g \in G} \lambda_g g$ with $\lambda_g \in R$. Then group multiplication extends (R-linearly) to a ring multiplication on R[G], making A an R-algebra.

Example 1.6. Recall that the direct product of two rings A, B is the ring $A \times B = \{(a, b) \mid a \in A, b \in B\}$ with unit $1_{A \times B} = (1_A, 1_B)$. It is straightforward to check that if A, B are R-algebras, then $A \times B$ is also an R-algebra.

Example 1.7. Suppose that A is a k-algebra and B is a k-subspace of A containing 1_A and closed under multiplication. Then B is also a k-algebra. We call such a B a subalgebra of A. For a concrete example, the space of diagonal matrices forms a subalgebra of $M_n(k)$.

Definition 1.8. A map $f: M \to N$ between right R-modules M, N is a homomorphism if it is a homomorphism of abelian groups (i.e. f(m+n) = f(m) + f(n) for all $m, n \in M$) that intertwines R-action (i.e. f(mr) = f(m)r for all $m \in M$ and $r \in R$). Denote by $\operatorname{Hom}_R(M, N)$ the set of all R-module homomorphisms from M to N. We also write $\operatorname{End}_R(M) := \operatorname{Hom}_R(M, M)$.

Lemma 1.9. Hom_R(M, N) is an abelian group with (f + g)(m) = f(m) + g(m) for all $f, g \in \text{Hom}_R(M, N)$ and all $m \in M$. If R is commutative, then $\text{Hom}_R(M, N)$ is an R-module, namely, for a homomorphism $f: M \to N$ and $r \in R$, the homomorphism fr is given by $m \mapsto f(mr)$.

Definition 1.10. End_R(M) is an associative ring where multiplication is given by composition and identity element being id_M . We call this the endomorphism ring of M.

Lemma 1.11. If A is an R-algebra over a commutative ring R, then any right A-module is also an R-module, and $\text{Hom}_A(M, N)$ is also an R-module (hence, $\text{End}_R(M)$ is an R-algebra).

Example 1.12. $A \cong \operatorname{End}_A(A)$ given by $a \mapsto (1_A \mapsto a)$ is an isomorphism of rings (or of R-algebras if A is an R-algebra). Note that if we work with left modules, then $A \cong \operatorname{End}_A(AA)^{\operatorname{op}}$, where $(-)^{\operatorname{op}}$ denotes the opposite ring given by the same underlying set with reverse direction of multiplication, i.e. $a \cdot_{\operatorname{op}} b := b \cdot a$.

Recall that an R-module M is finitely generated if there exists as surjective homomorphism $R^n \to M$, or equivalently, there is a finite set $X \subset M$ such that for any $m \in M$, we have $m = \sum_{x \in X} xr_x$ for some $r_x \in R$.

Notation. We write mod A for the collection of all finitely generated right A-modules.

2 Indecomposable modules and Krull-Schmidt property

We recall two types of building blocks of modules. The first one is indecomposability.

Definition 2.1. Let M be a R-module and N_1, \ldots, N_r be submodules. We say that M is the direct $sum\ N_1 \oplus \cdots \oplus N_r$ of the N_i 's if $M = N_1 + \cdots + N_r$ and $N_j \cap (N_1 + \cdots + N_{\hat{j}} + \cdots + N_r) = 0$. Equivalently, every $m \in M$ can be written uniquely as $n_1 + n_2 + \cdots + n_r$ with $n_i \in N_i$ for all i. In such a case, we write $M \cong N_1 \oplus \cdots \oplus N_r$. Each N_i is called a direct summand of M.

M is called indecomposable if $M \cong N_1 \oplus N_2$ implies $N_1 = 0$ or $N_2 = 0$.

We say that $M = \bigoplus_{i=1}^{m} M_i$ is an indecomposable decomposition (or just decomposition for short if context is clear) of M if each M_i is indecomposable.

Convention. We write (n_1, \ldots, n_r) instead of $n_1 + \cdots + n_r$ with $n_i \in N_i$ for a direct sum $N_1 \oplus \cdots \oplus N_r$.

We will only work with direct sum with finitely many indecomposable direct summands.

Example 2.2. Suppose that R_R is indecomposable as an R-module. If F is a free R-module of rank n, then $R^{\oplus n} := R \oplus R \oplus \cdots \oplus R$ (with n copies of R) is a decomposition of F.

Example 2.3. Consider the matrix ring $A := \operatorname{Mat}_n(\mathbb{k})$ over a field \mathbb{k} . Let V be the 'row space', i.e. $V = \{(v_j)_{1 \leq j \leq n} \mid v_j \in \mathbb{k}\}$ where $X \in \operatorname{Mat}_n(\mathbb{k})$ acts on $v \in V$ by $v \mapsto vX$ (matrix multiplication from the right). Since for any pair $u, v \in V$, there always exist X so that v = uX, we see that there is no other A-submodule of V other than 0 or V itself. Hence, V is an indecomposable A-module. In particular, the n different ways of embedding a row into an n-by-n-matrix yields an A-module isomorphism between $V^{\oplus n} \cong A_A$, which is the decomposition of the free A-module A_A .

The above example shows indecomposability by showing that V is a *simple A*-module, which is a stronger condition that we will come back later. Let us give an example of a different type of indecomposable (but non-simple) modules.

Example 2.4. Let $A = \mathbb{k}[x]/(x^k)$ the truncated polynomial ring for some $k \geq 2$. This is an algebra generated by (1_A and) x, and an A-module is just a \mathbb{k} -vector space V equipped with a linear transformation $\rho_x \in \operatorname{End}_{\mathbb{k}}(V)$ (representing the action of x) such that $\rho_x^k = 0$.

Consider a 2-dimensional space $V = \mathbb{k}\{v_1, v_2\}$ and a linear transformation

$$\rho_x = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}.$$

By definition $(av_1 + bv_2)x = (a + b)v_2$, and so any submodules must contains kv_2 , i.e. v_2 spans a unique non-zero submodules. If, on the contrary, V is not indecomposable, then we have $V = U_1 \oplus U_2$ for (at least) two non-zero submodules U_1, U_2 . But v_2 must be contained in any submodule of V, hence, we have $v_2 \in U_1 \cap U_2$, i.e. $U_1 \cap U_2 \neq 0$ – a contradiction not decomposability.

Proposition 2.5. There is a canonical R-module isomorphism

$$\operatorname{Hom}_{A}(\bigoplus_{j=1}^{m} M_{j}, \bigoplus_{i=1}^{n} N_{i}) \xrightarrow{\cong} \bigoplus_{i,j} \operatorname{Hom}_{A}(M_{j}, N_{i})$$
$$f \longmapsto (\pi_{i} f \iota_{j})_{i,j}$$

where $\iota_j: N_j \to \bigoplus_j N_j$ is the canonical inclusion for all j and $\pi_i: \bigoplus_i M_i \to M_i$ is the canonical projection for all i.

One can think of the right-hand space above as the space of m-by-n matrix with entries in each corresponding Hom-space.

Recall that an *idempotent* $e \in R$ is an element with $e^2 = e$. For example, the identity map $id_M \in End_A(M)$ (the unit element of the endomorphism ring) is an idempotent. From the previous proposition, we see that for a decomposition $M = N_1 \oplus N_2$, we have idempotents

$$e_i: M \xrightarrow{\pi_i} N_i \xrightarrow{\iota_i} M$$

for both i = 1, 2. Hence, being decomposable implies existence of multiple idempotents; this turns out characterise indecomposability completely.

Proposition 2.6. Let A be a finite-dimensional algebra and M be a finite-dimensional non-zero A-module. Then the following hold.

- (1) (Fitting's lemma) For any $f \in \operatorname{End}_A(M)$, there exists $n \geq 1$ such that $M \cong \operatorname{Ker}(f^n) \oplus \operatorname{Im}(f^n)$.
- (2) The following are equivalent.
 - M is indecomposable.
 - The endomorphism algebra $\operatorname{End}_A(M)$ does not contain any idempotents except 0 and id_M .
 - Every homomorphism $f \in \text{End}_A(M)$ is either an isomorphism or is nilpotent.
 - $\operatorname{End}_A(M)$ is local (see below).

Remark 2.7. It is known that if M is only artinian or only noetherian, then Fitting's lemma (and hence part (2)) fails. Nevertheless, in general, the proposition still hold for M that is both artinian and noetherian.

Let us briefly recall various characterisation of local rings.

Definition 2.8. A ring R is local if it has a unique maximal right (equivalently, left; equivalently, two-sided) ideal.

Remark 2.9. When R is non-commutative, the 'non-invertible elements' are the ones that do not admit (right) inverses.

Lemma 2.10. The following are equivalent for a finite-dimensional algebra A.

- A is local (i.e. has a unique maximal right ideal).
- Non-invertible elements of A form a two-sided ideal.
- For any $a \in A$, one of a or 1 a is invertible.
- 0 and 1_A are the only idempotents of A.
- $A/J(A) \cong \mathbb{R}$ as rings, where J(A) is the two-sided ideal of A given by the intersection of all maximal right (equivalently, left) ideals.

Example 2.11. Consider the upper triangular 2-by-2 matrix ring

$$A = \begin{pmatrix} \mathbb{k} & \mathbb{k} \\ 0 & \mathbb{k} \end{pmatrix} = \left\{ (a_{i,j})_{1 \leq i \leq j \leq 2} \middle| \begin{array}{l} a_{i,j} \in \mathbb{k} \ \forall i \leq j \\ a_{i,j} = 0 \ \forall i > j \end{array} \right\}.$$

Let $M = \{(x,y) \in \mathbb{k}^2\}$ be the 2-dimensional space where A acts as matrix multiplication (on the right). Suppose $f \in \operatorname{End}_A(M)$, say, f(x,y) = (ax + by, cx + dy) for some $a,b,c,d \in \mathbb{k}$. Then being an A-module homomorphisms means that

$$(ax + by, cx + dy)\begin{pmatrix} u & v \\ 0 & w \end{pmatrix} = f\left((x, y)\begin{pmatrix} u & v \\ 0 & w \end{pmatrix}\right) = (aux + bvx + wy, cux + dvx + dwy)$$

for all $u, v, w, x, y \in \mathbb{k}$. This means that

$$\begin{cases} buy = bvx + bwy \\ avx + bvy + cxw = cux + dvx \end{cases}.$$

The first line yields b = 0, and the second line yields c = 0 = b and a = d. In other words, $\operatorname{End}_A(M) \cong \mathbb{k}$ which is clearly a local algebra. Hence, M is indecomposable.

A natural question is to ask when is a decomposition of modules, if it exists, unique up to permuting the direct summands.

Definition 2.12. We say that an indecomposable decomposition $M = \bigoplus_{i=1}^m M_i$ is unique if any other indecomposable decomposition $M = \bigoplus_{j=1}^n N_j$ implies that m = n and there is a permutation σ such that $M_i \cong N_{\sigma(i)}$ for all $1 \leq i \leq m$. mod A is said to be Krull-Schmidt if every (finitely generated) A-module M admits a unique indecomposable decomposition.

Theorem 2.13. For a finite-dimensional algebra A, mod A is Krull-Schmidt.

Remark 2.14. This is a special case of the Krull-Schmidt theorem - whose proof we will omit to save time.

Theorem 2.15 (Krull-Schmidt). Suppose $M = \bigoplus_{i=1}^m M_i$ is an indecomposable decomposition of M. If $\operatorname{End}_A(M_i)$ is local for all $1 \leq i \leq m$, then the decomposition of M is unique.

Remark 2.16. Some people refer to this result as Krull-Remak-Schmidt theorem.

3 Simple modules, Schur's lemma

Definition 3.1. Let M be an R-module.

- (1) M is simple if $M \neq 0$, and for any submodule $L \subset M$, we have L = 0 or L = M.
- (2) M is semisimple if it is a direct sum of simples.

Remark 3.2. In the language of representations, simple modules are called *irreducible* representations, and semisimple modules are called *completely reducible* representations.

Remark 3.3. Note that a module is semisimple if and only if every submodule is a direct summand.

Example 3.4. Consider the matrix ring $A := \operatorname{Mat}_n(\mathbb{k})$ over a field \mathbb{k} . Then the row-space representation V is an n-dimensional simple module. Since $A_A \cong V^{\oplus n}$, we have that A_A is a semisimple module.

Example 3.5. The ring of dual numbers is $A := \mathbb{k}[x]/(x^2)$. The module (x) is simple. The regular representation A is non-simple (as (x) = AxA is a non-trivial submodule). It is also not semisimple. Indeed, (x) is a submodule of A, and the quotient module can be described by $\mathbb{k}v$ where v = 1 + (x). If A is semisimple, then the 1-dimensional space $\mathbb{k}v$ is isomorphic to a submodule of A. Such a submodule must be generated by a + bx (over A) for some $a, b \in \mathbb{k}$. If $a \neq 0$, then (a + bx)A = A. So a = 0, and $\mathbb{k}v \cong (x)$, a contradiction.

Lemma 3.6. S is a simple A-module if and only if for any non-zero $m \in S$, we have $mA := \{ma \mid a \in A\} = S$. In particular, simple modules are cyclic (i.e. generated by one element).

Let us see how one can find a simple module.

Definition 3.7. Let M be an A-module and take any $m \in M$. The annihilator of m (in A) is the set $\operatorname{Ann}_A(m) := \{a \in A \mid ma = 0\}.$

Note that $Ann_A(m)$ is a right ideal of A - hence, a right A-module.

Lemma 3.8. For a simple A-module S and any non-zero $m \in S$, we have $S \cong A/\operatorname{Ann}_A(m)$ as A-module. In particular, if A is finite-dimensional, then every simple A-module is also finite-dimensional.

Suppose I is a two-sided ideal of A. Then we have a quotient algebra B := A/I. For any B-module M, we have a canonical A-module structure on M given by ma := m(a+I). This is (somewhat confusingly) the restriction of M along the algebra homomorphism $A \to A/I$.

Lemma 3.9. Suppose B := A/I is a quotient algebra of A by a strict two-sided ideal $I \neq A$. If $S \in \text{mod } B$ is simple, then S is also simple as A-module

Proof This follows from the easy observation that any a B-submodule of S_B is also a A-submodule of S_A under restriction.

The following easy, yet fundamental, lemma describes the relation between simple modules. Recall that a division ring is one where every non-zero element admits an inverse (but the ring is not necessarily commutative).

Lemma 3.10 (Schur's lemma). Suppose S, T are simple A-modules, then

$$\operatorname{Hom}_A(S,T) = \begin{cases} a \text{ division ring,} & \text{if } S \cong T; \\ 0, & \text{otherwise.} \end{cases}$$

Remark 3.11. Note that if A is an R-algebra, then the division ring appearing is also an R-algebra (since it is the endomorphism ring of an A-module). In particular, if R is an algebraically closed field $\mathbb{k} = \overline{\mathbb{k}}$, then any division \mathbb{k} -algebra is just \mathbb{k} itself.

Proof The claim is equivalent to saying that any $f \in \text{Hom}_A(S,T)$ is either zero or an isomorphism. Since Im(f) is a submodule of T, simplicity of T says that Im(f) = 0, i.e. f = 0, or $\text{Im}(f) \cong T$. In the latter case, we can consider Ker(f), which is a submodule of S, so by simplicity of S it is either S or S itself. But this cannot be S as this means S as the means S is an isomorphism. \square

Example 3.12. In Example 2.11, we showed that the upper triangular 2-by-2 matrix ring A has a 2-dimensional indecomposable module $P_1 = \{(x,y) \mid x,y \in \mathbb{k}^2\}$ given by 'row vectors'. It is straightforward to check that there is a 1-dimensional (hence, simple) submodule given by $S_2 := \{(0,y) \mid y \in \mathbb{k}^2\}$.

Consider the module $S_1 := P_1/S_2$. This is a 1-dimensional (simple) module spanned by, say, w with A-action given by

$$w\begin{pmatrix} a & b \\ 0 & c \end{pmatrix} := wa.$$

Consider a homomorphism $f \in \text{Hom}_A(S_1, S_2)$. This will be of the form $w \mapsto (0, y)$ for some $y \in \mathbb{k}$ and has to satisfy

$$(0, ya) = (0, y)a = f(wa) = f(w \begin{pmatrix} a & b \\ 0 & c \end{pmatrix}) = f(w) \begin{pmatrix} a & b \\ 0 & c \end{pmatrix} = (0, y)c = (0, yc)$$

for any $a,b,c \in \mathbb{k}$. Hence, we must have y=0, which means that f=0. In particular, by Schur's lemma $S_1 \ncong S_2$.

Lemma 3.13. Suppose that S is a simple A-module. Consider a semisimple A-module $M = S_1 \oplus \cdots \oplus S_n$ with $S_i \cong S$ for all i. Then $\operatorname{End}_A(M) \cong \operatorname{Mat}_n(D)$, where $D := \operatorname{End}_A(S)$.

Proof We have canonical inclusion $\iota_j: S_j \hookrightarrow M$ and projection $\pi_i: M \twoheadrightarrow S_i$. So for $f \in \operatorname{End}_A(M)$, we have a homomorphism $\pi_i f \iota_j: S_j \to S_i$, and by Schur's lemma, this is an element of D. Now we have a ring homomorphism

$$\operatorname{End}_A(M) \to \operatorname{Mat}_r(D), \quad f \mapsto (\pi_i f \iota_i)_{1 \le i,j \le r},$$

which is clearly injective. Conversely, for $(a_{i,j})_{1 \leq i,j \leq r} \in \operatorname{Mat}_r(D)$, we have an endomorphism $M \stackrel{\pi_j}{\to} S_i \stackrel{\iota_i}{\hookrightarrow} M$, which yields the required surjection.

Example 3.14. For a tautological example, take $A = \mathbb{k}$ to be just a field. Then we have a 1-dimensional simple A-module $S = \mathbb{k}$ with $\operatorname{End}_A(S^{\oplus n}) = \operatorname{Mat}_n(\operatorname{End}_A(\mathbb{k})) = \operatorname{Mat}_n(\mathbb{k})$. Note that now we have an n-dimensional simple $\operatorname{Mat}_n(\mathbb{k})$ -module (given by the row vectors).

4 Quiver and path algebra

Definition 4.1. A (finite) quiver is a datum $Q = (Q_0, Q_1, s, t : Q_1 \to Q_0)$ for finite sets Q_0, Q_1 . The elements of Q_0 are called vertices and those of Q_1 are called arrows. The source (resp. target) of an arrow $\alpha \in Q_1$ is the vertex $s(\alpha)$ (resp. $t(\alpha)$).

This is equivalent to specifying an oriented graph (possibly with multi-edges and loops); Gabriel coined the term quiver as a way to emphasise the context is not really about the graph itself.

Definition 4.2. Let Q be a quiver.

- A trivial path on Q is a "stationary walk at i", denoted by e_i for some $i \in Q_0$.
- A path of Q is either a trivial path or a word $\alpha_1 \alpha_2 \cdots \alpha_\ell$ of arrows with $s(\alpha_i) = t(\alpha_{i+1})$.

The source and target functions extend naturally to paths, with $s(e_i) = i = t(e_i)$. Two paths p, q can be concatenated to a new one pq if t(p) = s(q); note that our convention is to read from left to right.

Definition 4.3. The path algebra $\mathbb{k}Q$ of a quiver Q is the \mathbb{k} -algebra whose underlying vector space is given by $\bigoplus_{p:paths\ of\ Q} \mathbb{k}p$, with multiplication given by path concatenation. That is $x \in \mathbb{k}Q$ is a formal linear combinations of paths on Q.

Note that $e_i e_j = \delta_{i,j} e_i$, where $\delta_{i,j} = 1$ if i = j else 0. In other words, e_i is an *idempotent* of the path algebra kQ. Moreover, we have an idempotent decomposition

$$1_{\Bbbk Q} = \sum_{i \in Q_0} e_i$$

of the unit element of $\mathbb{k}Q$.

Example 4.4. Consider the one-looped quiver, a.k.a. Jordan quiver,

$$Q = \left(\begin{array}{c} \alpha \\ \end{array} \right)$$

Then kQ has basis $\{\alpha^k \mid k \geq 0\}$ (note that the trivial path at the unique vertex is the identity element). Then $kQ \cong k[x]$.

An oriented cycle is a path of the form $v_1 \to v_2 \to \cdots v_r \to v_1$, i.e. starts and ends at the same vertex. If Q does not contain any oriented cycle, we say that it is acyclic.

Proposition 4.5. $\mathbb{k}Q$ is finite-dimensional if, and only if, Q is finite acyclic.

Proof If there is an oriented cycle c, then $c^k \in \mathbb{k}Q$ for all $k \geq 0$, and so $\mathbb{k}Q$ is infinite-dimensional. Otherwise, there are only finitely many paths on Q.

Example 4.6. Consider the linearly oriented $\vec{\mathbb{A}}_n$ -quiver

$$Q = \vec{\mathbb{A}}_n = 1 \xrightarrow{\alpha_1} 2 \xrightarrow{\alpha_2} \cdots \xrightarrow{\alpha_{n-1}} n.$$

Then the path algebra $\mathbb{k}Q$ has basis $\{e_i, \alpha_{j,k} \mid 1 \leq i \leq n, 1 \leq j \leq k \leq n\}$, where $\alpha_{j,k} := \alpha_j \alpha_{j+1} \cdots \alpha_k$.

Consider the upper triangular n-by-n matrix ring

$$\begin{pmatrix} \mathbb{k} & \mathbb{k} & \cdots & \mathbb{k} \\ 0 & \mathbb{k} & \cdots & \mathbb{k} \\ 0 & 0 & \ddots & \vdots \\ 0 & 0 & 0 & \mathbb{k} \end{pmatrix} = \left\{ (a_{i,j})_{1 \le i \le j \le n} \middle| \begin{array}{l} a_{i,j} \in \mathbb{k} \ \forall i \le j \\ a_{i,j} = 0 \ \forall i > j \end{array} \right\}.$$

Denote by $E_{i,j}$ the elementary matrix whose entries are all zero except at (i,j) where it is one. This ring is isomorphic to $\mathbb{k}Q$ via $E_{i,i} \mapsto e_i$ and $E_{i,j} \mapsto \alpha_{i,j-1}$ for $1 \leq j < k \leq n$.

From now on, we will focus in the following setting.

Assumption 4.7. (1) Quivers are finite (i.e. finitely many vertices and arrows).

(2) Representations (equivalently, modules) are finite-dimensional.

5 Duality

For a quiver Q, the opposite quiver Q^{op} has the same set of vertices with the reverse direction of arrows, i.e. $Q_0^{\text{op}} = Q_0, Q_1^{\text{op}} = Q_1, s_{Q^{\text{op}}} = t_Q$, and $t_{Q^{\text{op}}} = s_Q$.

Exercise 5.1. Show that there is a canonical isomorphism $(\Bbbk Q)^{\operatorname{op}} \cong \Bbbk(Q^{\operatorname{op}})$.

Let M be a finite-dimensional A-module. Then we have a dual space

$$D(M) := M^* := \operatorname{Hom}_{\mathbb{k}}(M, \mathbb{k}),$$

which has a natural A^{op} -module structure, namely, $(a \cdot f)(m) := f(ma)$ for any $a \in A$, $f \in M^*$, $m \in M$. Moreover, for an A-module homomorphism $\theta : M \to N$, we have also an A^{op} -module homomorphism $\theta^* : N^* \to M^*$ with $\theta^*(f)(m) = f(\theta(m))$.

Lemma 5.2. There is a \mathbb{k} -vector space isomorphism $\operatorname{Hom}_A(M,N) \cong \operatorname{Hom}_{A^{\operatorname{op}}}(DN,DM)$.

Proof Just a straightforward check that $(\theta^*)^* = \theta$.

We note as a fact that D preserves indecomposability of (finite-dimensional) modules. This can be seen using the fact that $\operatorname{Hom}_A(M,N) \cong \operatorname{Hom}_{A^{\operatorname{op}}}(DN,DM)$ and can be upgraded to an algebra isomorphism for the case when N=M; then uses characterisation of indecomposable module by local endomorphism ring.

Example 5.3. The left A-module ${}_{A}A$ yields a right A-module structure on D(A). More generally, suppose we have a left ideal Ae of A for some element $e \in A$, then D(Ae) is a right ideal of A.

Remark 5.4. There is another natural duality, which we will not used, between $\operatorname{\mathsf{mod}} A$ and $\operatorname{\mathsf{mod}} A^{\operatorname{op}}$ given by sending M to $\operatorname{\mathsf{Hom}}_A(M,A)$. In general, this duality is different from the \Bbbk -linear dual unless A is a so-called symmetric algebra, meaning that $A \cong DA$ as bimodule; in which case, $\operatorname{\mathsf{Hom}}_A(-,A)$ dual is naturally isomorphic to D (as functors).

6 Representations of quiver

Definition 6.1. A \Bbbk -linear representation of Q is a datum $(\{M_i\}_{i\in Q_0}, \{M_\alpha\}_{\alpha\in Q_1})$ where M_i is a \Bbbk -vector space for each $i\in Q_0$ and $M_\alpha: M_{s(\alpha)}\to M_{t(\alpha)}$ is K-linear map for each $\alpha\in Q_1$.

Such a representation is finite-dimensional if $\dim_{\mathbb{K}} M_i < \infty$ for all $i \in Q_0$.

Notation. For a representation M of Q, we take $M_p := M_{\alpha_1} \cdots M_{\alpha_\ell}$ for a path $p = \alpha_1 \cdots \alpha_\ell$.

It is easy to notice that every representation of Q is equivalent to a kQ-module, namely,

representation
$$(\{M_i\}_{i \in Q_0}, \{M_{\alpha}\}_{\alpha \in Q_1}) \leftrightarrow \begin{cases} \mathbb{k}Q\text{-module } \prod_{i \in Q_0} M_i \\ \text{s.t. } \sum_{p:\text{path}} \lambda_p p \text{ acts as } \sum_p \lambda_p M_p. \end{cases}$$

Example 6.2 (Simple). For $x \in Q_0$, denote by S_x (or S(x)) the representation given by putting a 1-dimensional space on x, zero on all other vertices, and zero on all arrows. This corresponds to a 1-dimensional $\mathbb{k}Q$ -module and so we call it the simple at x.

Note: at this stage, it is not clear if these are all the simple kQ-modules (up to isomorphism) yet.

Example 6.3 (Projective). For $x \in Q_0$, denote by P_x (or P(x)) the representation given by $(\{M_y\}_{y\in Q_0}, \{M_\alpha\}_{\alpha\in Q_1})$, where

$$M_{y} := \bigoplus_{\substack{p:path \ with \\ s(p)=x, \\ t(p)=y}} \mathbb{k}p, \quad and \quad (M_{\alpha}: M_{y} \to M_{z}) := \sum_{p\alpha=q} (M_{y} \twoheadrightarrow \mathbb{k}p \xrightarrow{\mathrm{id}} \mathbb{k}q \hookrightarrow M_{z}).$$

This is called the projective at x. This corresponds to the right ideal $e_x \mathbb{k}Q$ of $\mathbb{k}Q$.

Example 6.4 (Injective). Dual to the projective module construction, for $x \in Q_0$, denote by I_x (or I(x)) the representation given by $(\{M_y\}_{y\in Q_0}, \{M_\alpha\}_{\alpha\in Q_1})$, where

$$M_y := \bigoplus_{\substack{p:path \ with \\ s(p) = y, \\ t(p) = x}} \Bbbk p, \quad and \quad (M_\alpha : M_y \to M_z) := \sum_{\substack{p = \alpha q}} (M_y \twoheadrightarrow \Bbbk p \xrightarrow{\mathrm{id}} \Bbbk q \hookrightarrow M_z).$$

This is called the injective at x. This corresponds to the dual of the left ideal generated by e_x , i.e. $D(\mathbb{k}Qe_x)$.

Example 6.5. The representation of $Q = \vec{\mathbb{A}}_n$ given by

$$U_{i,j} := 0 \to \cdots \to \mathbb{k} \xrightarrow{\mathrm{id}} \to \cdots \xrightarrow{\mathrm{id}} \mathbb{k} \to 0 \to \cdots \to 0$$

with a copy of k on vertices $i, i+1, \ldots, j$ is the uniserial kQ-module corresponding to the column space (under the isomorphism of kQ with the lower triangular matrix ring) with non-zero entries in the k-th row for $i \leq k \leq j$.

Example 6.6. Let Q be the Jordan quiver with unique arrow α . Then a representation of Q is nothing but an n-dimensional vector space equipped with a linear endomorphism, equivalently, an n-by-n matrix.

Definition 6.7. A homomorphism $f: M \to N$ of (k-linear) quiver representations $M = (M_i, M_{\alpha})_{i,\alpha}$ and $N = (N_i, N_{\alpha})_{i,\alpha}$ is a collection of linear maps $f_i: M_i \to N_i$ that intertwines arrows' actions, i.e. we have a commutative diagram

$$M_{i} \xrightarrow{f_{i}} N_{i}$$

$$M_{\alpha} \downarrow \qquad \qquad \downarrow N_{\alpha}$$

$$M_{j} \xrightarrow{f_{i}} N_{j}$$

for all arrows $\alpha: i \to j$ in Q.

A homomorphism $f = (f_i)_{i \in Q_0} : M \to N$ of quiver representations is injective, resp. surjective, resp. an isomorphism, if every f_i is injective, resp. surjective, resp. an isomorphism, for all $i \in Q_0$.

Example 6.8. Let Q be the Jordan quiver. Recall that a representation of Q is equivalent to a choice of n-by-n matrix M_{α} . By definition, the isomorphism class of such a representation is given by the conjugacy classes of M_{α} . If we assume \mathbb{k} is algebraically closed, then a representative of the isomorphism class of M_{α} is given by the Jordan normal form of M_{α} . That is, M_{α} can be block-diagonalise into Jordan blocks $J_{m_1}(\lambda_1), \ldots, J_{m_l}(\lambda_l)$, where $J_m(\lambda)$ is the m-by-m Jordan block with eigenvalue $\lambda \in \mathbb{k}$.

Proposition 6.9. There is an isomorphism between the category of representations of Q and mod & Q, where $(M_i, M_{\alpha})_{i,\alpha}$ corresponds to $M = \prod_{i \in Q_0} M_i$ with & Q-action given by (linear combinations of compositions of) M_{α} 's, and isomorphism classes of Q-representations correspond to isomorphism classes of & Q-modules.