Aaron Low Weng Soon

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Work Experience

Work Experience	
Motional	
Research Engineer (Sensor Calibration)	2020 - 2023
Senior Research Engineer (Sensor Calibration)	2023 - Present
 Research and development of solutions for sensor (cameras, LIDARs, radars, IMU) calibration and validation for autonomous vehicles 	
 Developed tools in C++ to enable users to visually inspect sensor calibration and run calibration algorithms 	
 Developed deep learning infrastructure with PyTorch as well as training and evaluating models 	
 Implemented data pipelines for analyzing metrics, collecting deep learning datasets leveraging SQL databases and cloud solutions 	
<u>Aptiv</u>	2020
Autonomous Vehicle Intern (Sensor Calibration)	
 Implemented deep learning based methods for sensor (cameras, LIDARs) calibration for autonomous vehicles based on RegNet 	
 Processed and curated datasets to train and evaluate deep learning models Deployed models into production with <u>TensorRT</u> 	
Materialise Software Engineer Intern	2016
Designed and developed a Microsoft Paint inspired application	
Contributed to the development of 3D modelling software	
<u>Accenture</u>	2015
Solution Architect Intern	
Development of front end retail system dealing mainly with system analysis and testing	
Education	
	0010 0010
Imperial College London PhD in Machine Learning and Computer Vision (discentinged)	2018 - 2019
PhD in Machine Learning and Computer Vision (discontinued) Supervisors: Kim Tae-Kyun and Loy Chen Change	
Research area: 3D Pose Estimation	
	0014 0010
Imperial College London Electrical and Electronic Engineering MEng	2014 - 2018
First Class Honours	
Dean's List (top 10% of class) Year 2	
Selected modules: Linear Algebra • Probability and Stochastic Processes • Machine Learning • Computer Vision • Algorithms and Complexity • Parallel Computing • Optimisation	
Thesis: Depth to Colour Translation for 3D Hand Pose Estimation From Monocular RGB With Generative Adversarial Networks	
HELP Academy	2013 - 2014
Edexcel A-Levels	
4 A* Chemistry • Physics • Mathematics • Further Mathematics	

Projects

UniCal 2023 Researcher <u>Calibration and Validation</u> is a novel architecture for carrying out camera-to-LiDAR calibration and validation leveraging self-attention mechanisms using a Transformer-based network.

2021 Without Abandonware Game Developer Entry to the Game Off 2021 game jam A 2D platformer written in Unity with C# Autonomous Snack Delivery Android (ASDA) 2017 **Development of Robot Navigation** Autonomous robot that is capable of manoeuvring a building and taking an elevator to obtain and deliver snacks **Emocoaster** 2017 Game Developer Runner-Up ("Best Game") Emotion matching game built using Microsoft Cognitive Services NeuroSpell 2016 Python Developer Low-cost brain computing interface that allows motor impaired people to type by looking at an on-screen keyboard <u>ParkWare</u> 2016 Web Developer

Technologies

Programming: Python • C++ • C# • SQL

Web Development: HTML • CSS • JavaScript

Deep Learning: PyTorch • TensorFlow • Keras • Pandas Cloud Development: Serverless • AWS Services • Terraform

Other tools/frameworks: Jenkins • Ixc • ROS • docker • Bash • git • Unity

Prize Winner ("Best use of Amazon Web Services") Parking space detection web service using machine learning to detect cars in parking

Operating Systems: Windows • Linux

Teaching

HELP University 2019 - 2020

Lecturer, Faculty of Computing and Digital Technology

Lectured introductory programming

• Presented deep learning tutorials to both staff and students

Imperial College London 2016

Undergraduate Teaching Assistant, Introduction to Computer Architecture

Taught ARM assembly during programming tutorials

Imperial College London Game Development Society 2015 - 2018

Co-founder and Secretary

Provided free tutorials on game development using C# and Unity

Learning

<u>Data Science Nanodegree (Udacity)</u> 2021

<u>Dog Breed Classifier Project Article</u>

<u>Deep Learning Specialization by Andrew Ng (Coursera)</u>
2018

Additional

Languages: English (Native) • Malay (limited working)