# **Aaron Low Weng Soon**

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# **TECHNICAL SKILLS**

Programming Languages: Python • C++ • C#

**Deep Learning Frameworks**: PyTorch • TensorFlow • Keras

Data Science Tools: Pandas · SQL

Cloud Development: Serverless · AWS Services · Terraform

Web Development: HTML · CSS · JavaScript

Build Tools: CMake · Bazel

Operating Systems: Windows · Linux

Other Tools: Git · Jenkins · ROS · Docker · Bash · Unity

## **WORK EXPERIENCE**

Motional 2020 - 2024

Senior Research Engineer (Sensor Calibration) • 2023 - 2024 Research Engineer (Sensor Calibration) • 2020 - 2023

**Singapore** 

- Developed solutions for sensor (cameras, LIDARs, radars, IMU) calibration and validation of autonomous vehicles.
- Researched deep learning solutions for sensor calibration as well as implementing the infrastructure for training and evaluation.
  - <u>UniCal: a Single-Branch Transformer-Based Model for Camera-to-LiDAR Calibration and Validation</u> is a novel architecture for carrying out camera-to-LiDAR calibration and validation leveraging self-attention mechanisms using a Transformer-based network.
- Built and maintained cloud-based systems for continuous validation of vehicle sensor data.
  - Our automated system ran daily on a fleet of hundreds of vehicles allowing data-driven calibrations.
- Automated dataset generation and curation for algorithm research.
- · Worked on vehicle hardware to deploy online sensor calibration algorithms.

## **Hyundai-Aptiv Autonomous Driving Joint Venture**

2020

**Autonomous Vehicle Intern (Sensor Calibration)** 

Singapore

- Researched deep learning solutions for camera-to-LiDAR calibration of autonomous vehicles.
- Deployed a RegNet based model into production with TensorRT.

Materialise 2016

Software Engineer Intern Kuala Lumpur, Malaysia

· Designed and developed a Microsoft Paint inspired application.

Accenture 2015

Solution Architect Intern Kuala Lumpur, Malaysia

Development of front end retail system dealing mainly with system analysis and testing.

# **EDUCATION**

## **Imperial College London**

2018 - 2019

PhD in Machine Learning and Computer Vision (discontinued)

- Supervisors: Kim Tae-Kyun and Loy Chen Change
- · Research area: 3D Pose Estimation

### Imperial College London

2014 - 2018

**Electrical and Electronic Engineering MEng** 

• First Class Honours

- Dean's List (top 10% of class) Year 2
- Thesis: <u>Depth to Colour Translation for 3D Hand Pose Estimation From Monocular RGB With Generative Adversarial Networks</u>
- Selected modules: Linear Algebra Probability and Stochastic Processes Machine Learning Computer Vision Algorithms and Complexity Parallel Computing Optimisation

<u>HELP Academy</u> 2013 - 2014

**Edexcel A-Levels** 

• 4 A\* Chemistry • Physics • Mathematics • Further Mathematics

# **TEACHING**

HELP University 2019 - 2020

**Lecturer, Faculty of Computing and Digital Technology** 

- · Lectured introductory programming.
- Presented deep learning tutorials to both staff and students.

Imperial College London

2016

**Undergraduate Teaching Assistant, Introduction to Computer Architecture** 

Taught ARM assembly during programming tutorials.

## Imperial College London Game Development Society

2015 - 2018

Co-founder and Secretary

Provided tutorials on game development using C# and Unity.

# **PROJECTS**

## **Distance to Space 1000**

2024

Unity/C# Developer

• Entry to the SpeedJam 5 2024 game jam. A 2D card-based puzzle game written in Unity with C#.

#### **Without Abandonware**

2021

Unity/C# Developer

• Entry to the Game Off 2021 game jam. A 2D platformer written in Unity with C#.

## **Autonomous Snack Delivery Android (ASDA)**

2017

**Development of Robot Navigation** 

 Autonomous robot that is capable of manoeuvring a building and taking an elevator to obtain and deliver snacks.

Emocoaster 2017

C# Developer

• Runner-Up ("Best Game") Emotion matching game built using Microsoft Cognitive Services.

ParkWare 2016

**Web Developer** 

• Prize Winner ("Best use of Amazon Web Services") Parking space detection web service using machine learning to detect cars in parking lots.

# **LEARNING**

#### <u>Data Science Nanodegree (Udacity)</u>

2021

• Dog Breed Classifier Project Article

**Deep Learning Specialization by Andrew Ng (Coursera)** 

2018

# LANGUAGES AND INTERESTS

**Languages:** English (Native) • Malay (Limited Working)

Interests: Game Development • Bouldering • Movies