Aaron Hao Tan

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Education

University of Toronto Toronto, Canada

Doctor of Philosophy, Robotics Institute

September. 2019 - Present

Specialization Multi-Robot Inference for Decentralized Cooperation, CGPA (4.0/4.0)

Ontario Tech University Oshawa, Canada

Master of Applied Science, Mechanical Engineering

May. 2017 - May. 2019

Specialization Vision Based Control for Mobile Robots and Manipulators, CGPA (4.3/4.3)

Ontario Tech University Oshawa, Canada

Bachelor of Engineering with Highest Distinction Sep. 2012 - Apr. 2017

Specialization Mechatronics Option with Internship, Dean's List, CGPA (4.0/4.3)

Experience _

Deep Learning and Robotics Researcher, Ph.D. Thesis

Toronto, Ontario

Autonomous System and Biomechatronics Lab, University of Toronto

Sept. 2019 - Present

- Deep Multi-agent Reinforcement Learning Centralized training for decentralized execution to address multi-robot task inference
- Convolutional Neural Network CNN with Keras for traversability estimation with heightmap images for rough terrain navigation
- Sequential Decision Making Dec-POMDP, DDQRN, A2C/A3C with PyTorch to learn sophisticated multi-robot cooperation strategies
- Sim 2 Real Successfully transferred robot navigation policy from simulation to the real world using domain randomization
- Publication Completed papers in DRL for navigation, D-MARL for coordination and Al for healthcare

Applied AI Researcher
Toronto, Ontario

Department of Ophthalmology and Vision Sciences, University of Toronto

May. 2021 - Present

- Healthcare Developed deep learning models with ophthalmologist to enhance cataract surgery and early disease detection
- Data Collection Automated data collection w/ Optical Character Recognition (OCR) to extract patient test data from PDFs
- · Postoperative Refraction Built an imbalanced regression model and outperformed current standard of care
- Disease Detection Developed a CNN model to identify homonymous deficits from Humphry Visual Field tests

Machine Learning Engineer

Toronto, Ontario

Robotics and ML Projects, University of Toronto

Sept. 2019 - Present

- Music Working with 2x Grammy Award Recipient, Sean Leon, using Stable Diffusion and GPT-3 to empower creators globally.
- AuToronto: Self-driving Car Team Worked with the Perception team to implement object detection (YOLO) and traffic sign labelling
- SmartARM Collaborated with a Microsoft funded startup to develop AI powered features for prosthetics
- Deep Learning Implemented various classical and DL models and optimized with AutoML techniques

Robotics Researcher, MASc Thesis

Oshawa, Ontario

General Robotics & Autonomous Systems and Processes Lab, Ontario Tech University

May. 2017 - May. 2019

- Mobile Robot Designed and developed a novel multi-terrain robot including digital signal processing for various autonomy sensors
- Electrical Systems Designed PCBs and implemented hardware architecture for robot sensing, data acquisition and motion control
- Computer Vision Position and image based visual servoing of mobile manipulators for autonomous robot inspection

Engineering Specialist/Advanced Technology Specialist Intern

Oshawa, Ontario

General Motors of Canada Company - Active Safety Advanced Development

2 Terms (2016/2017)

- Wearable Technology Designed wearable hardware and developed ML models to predict driver behavior based on vital signs
- Camera System Designed an adjustable camera system for trailers to provide drivers with greater awareness

Recognition

2022	Apple AI/ML Scholar Nominee (1 of 3 selected across university), University of Toronto	Toronto, Ontario
2022	Ontario Graduate Scholarship (\$15k Prize), University of Toronto	Toronto, Ontario
2022	Undergraduate Teaching Assisstant Award (\$500 Prize) , University of Toronto	Toronto, Ontario
2022	DiDi Graduate Scholarship (\$10k Prize), University of Toronto	Toronto, Ontario
2021	1st Place at RO-MAN: The Roboethics Competition (\$1k Prize), McGill University	Montreal, Quebec
2021	Best Research Day Paper in Dept. of Ophthalmology and Vision Sciences, University of Toronto	Toronto, Ontario
2018	Photograhy for Apple's Shot on iPhone Campaign, Apple	California, USA

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