

# Deep Learning Mini Lecture

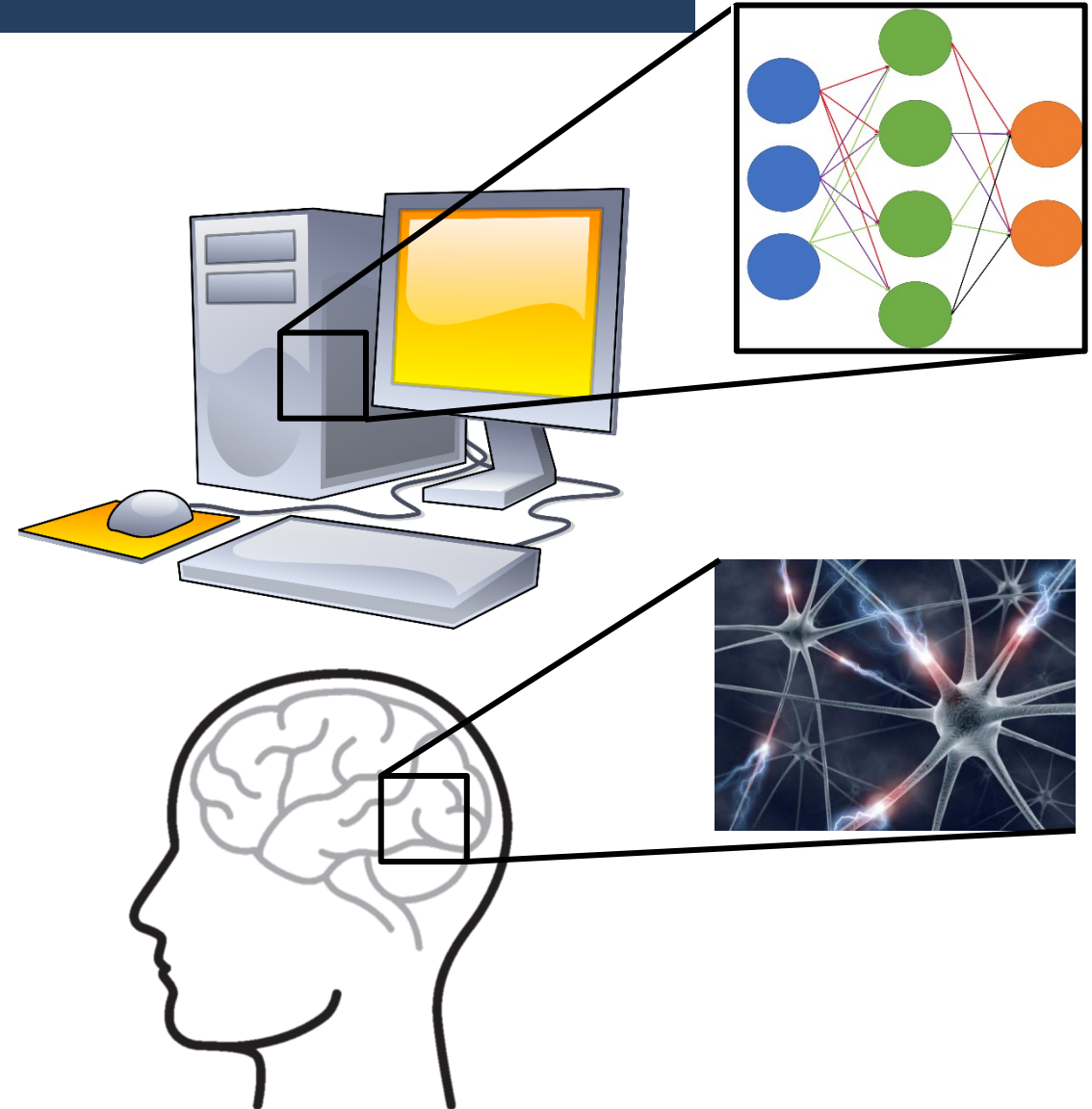
Aaron Hao Tan

# OUTLINE

- Introduction
- Deep Learning Hierarchy
- Unsupervised Learning
- Supervised Learning
- Reinforcement Learning
- Conclusion
- References

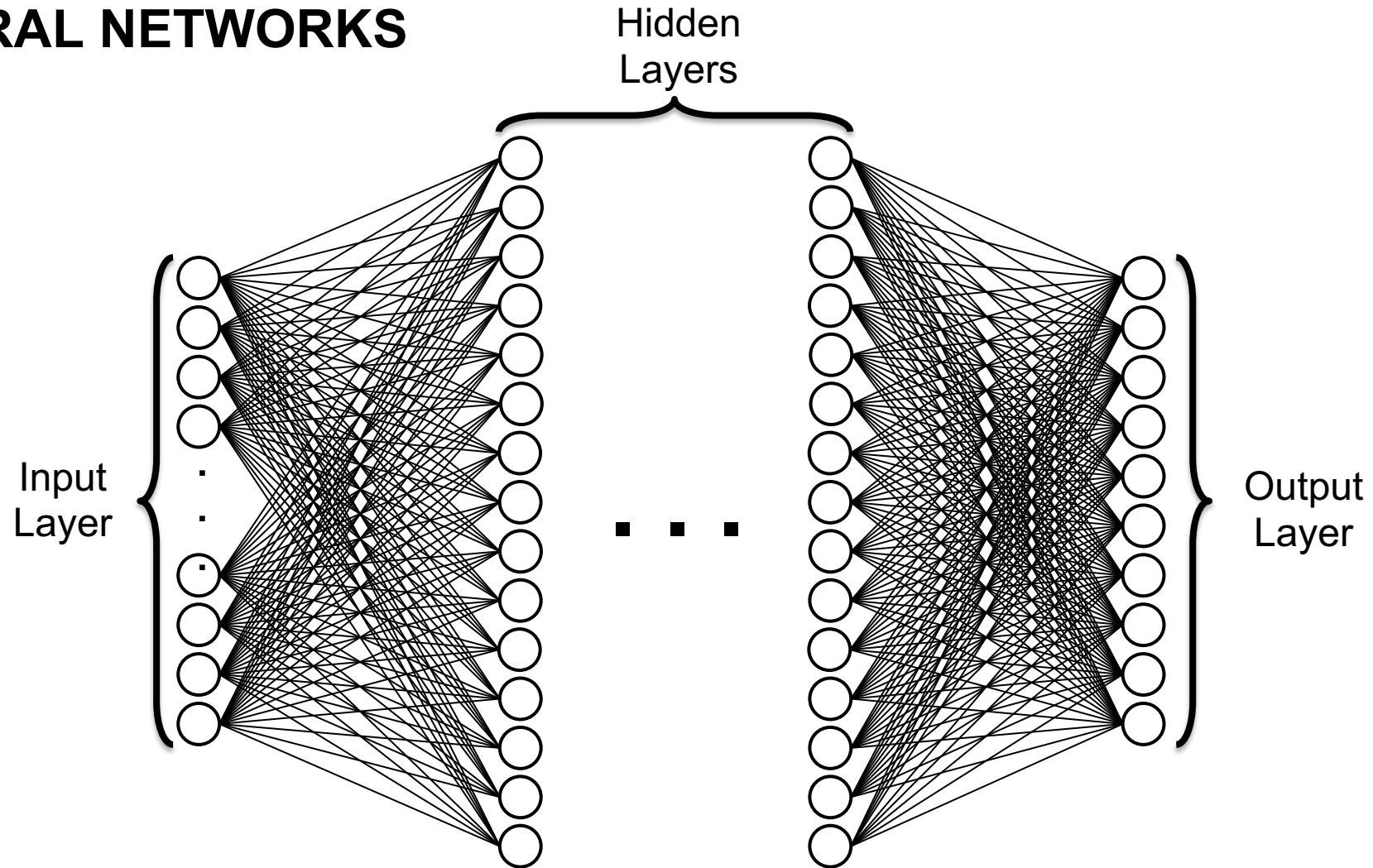
# INTRODUCTION

- Computer learning via a hierarchy of concepts
  - Each layer of the hierarchy represents a more abstract concept for the computer
  - “Deep” refers to the number of hierarchy layers
- Generally consist of a Neural Network
  - Biological analog of a Neural Network is the human brain
  - “Deep” refers to the number of hidden layers of the Neural Network



# INTRODUCTION

## DEEP NEURAL NETWORKS



# INTRODUCTION

## EXAMPLE: HANDWRITTEN DIGIT RECOGNITION

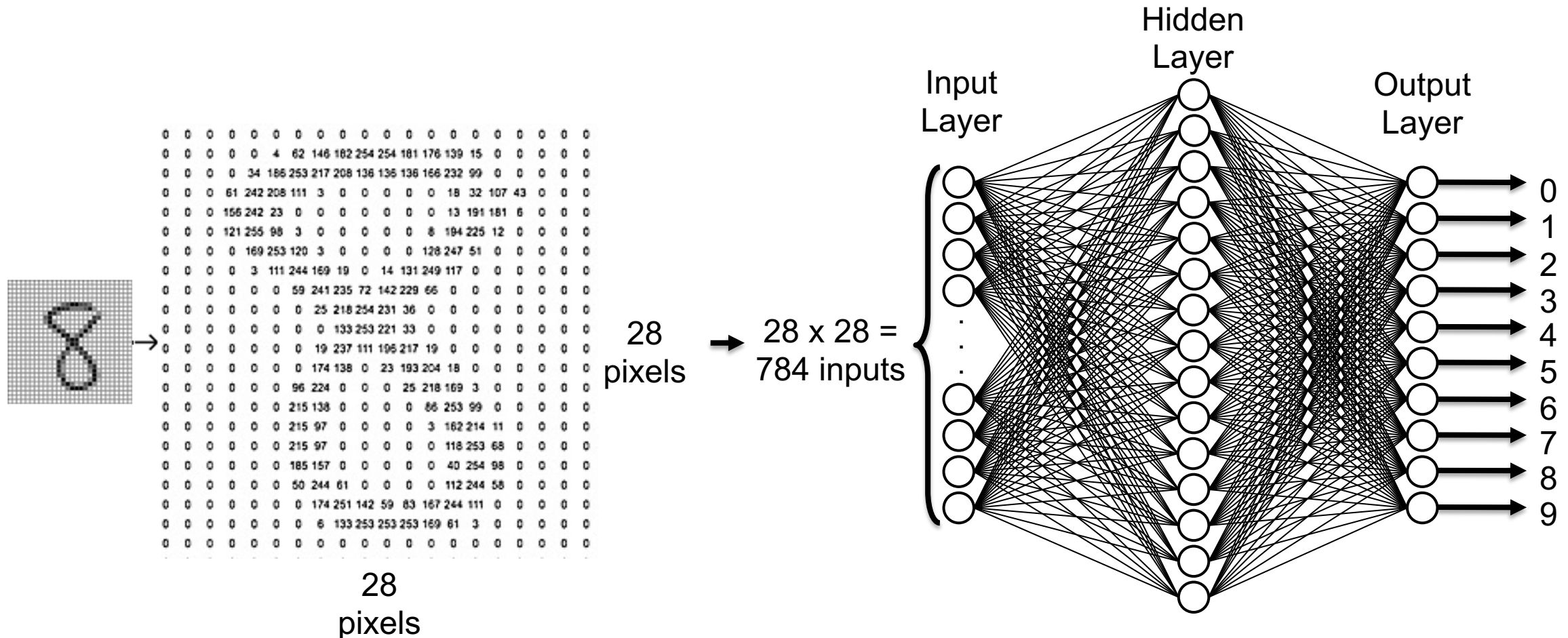
- **GOAL:** to creating and train a Neural Network to distinguish handwritten digits
- Digits are input as 28 x 28 pixel greyscale images
- System is trained using many sets of labeled training data (Supervised Learning)



Courtesy of Neural Networks and Deep Learning  
By Michael Nielsen

# INTRODUCTION

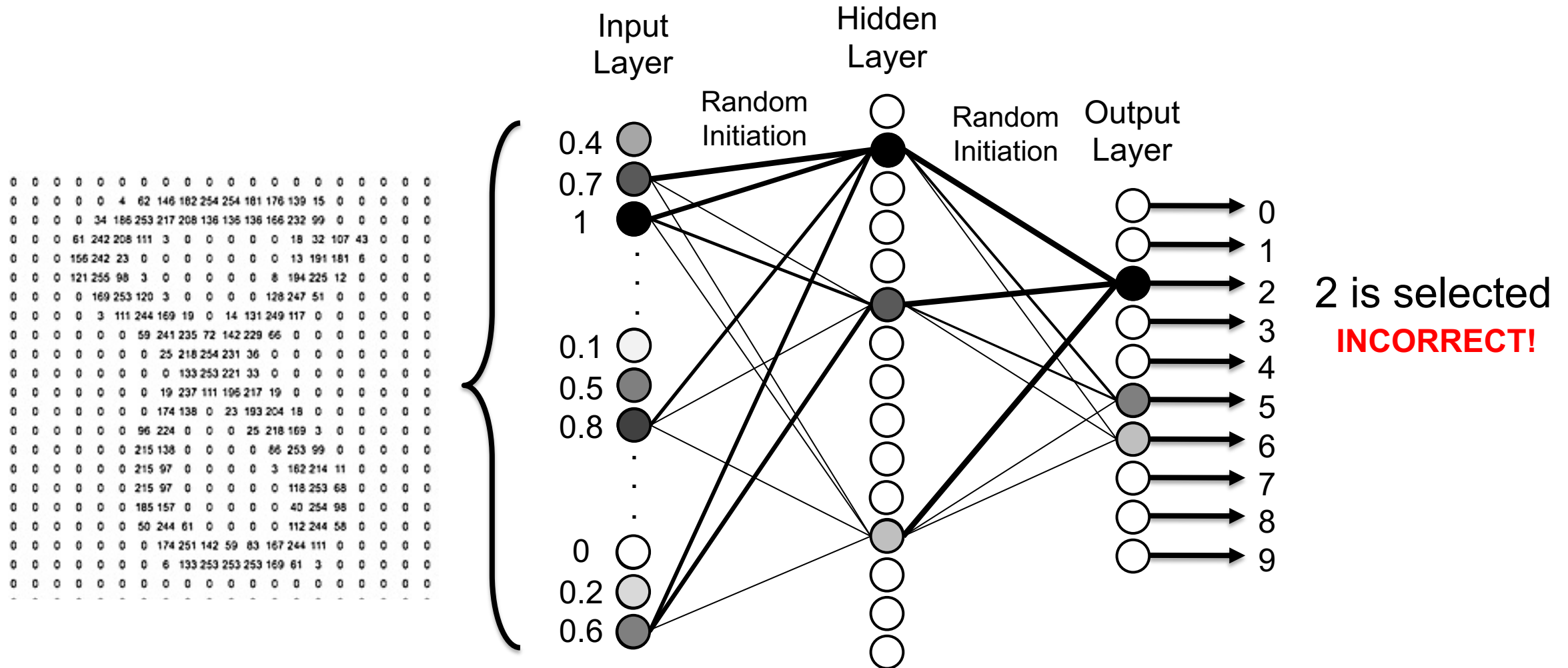
## EXAMPLE: HANDWRITTEN DIGIT RECOGNITION





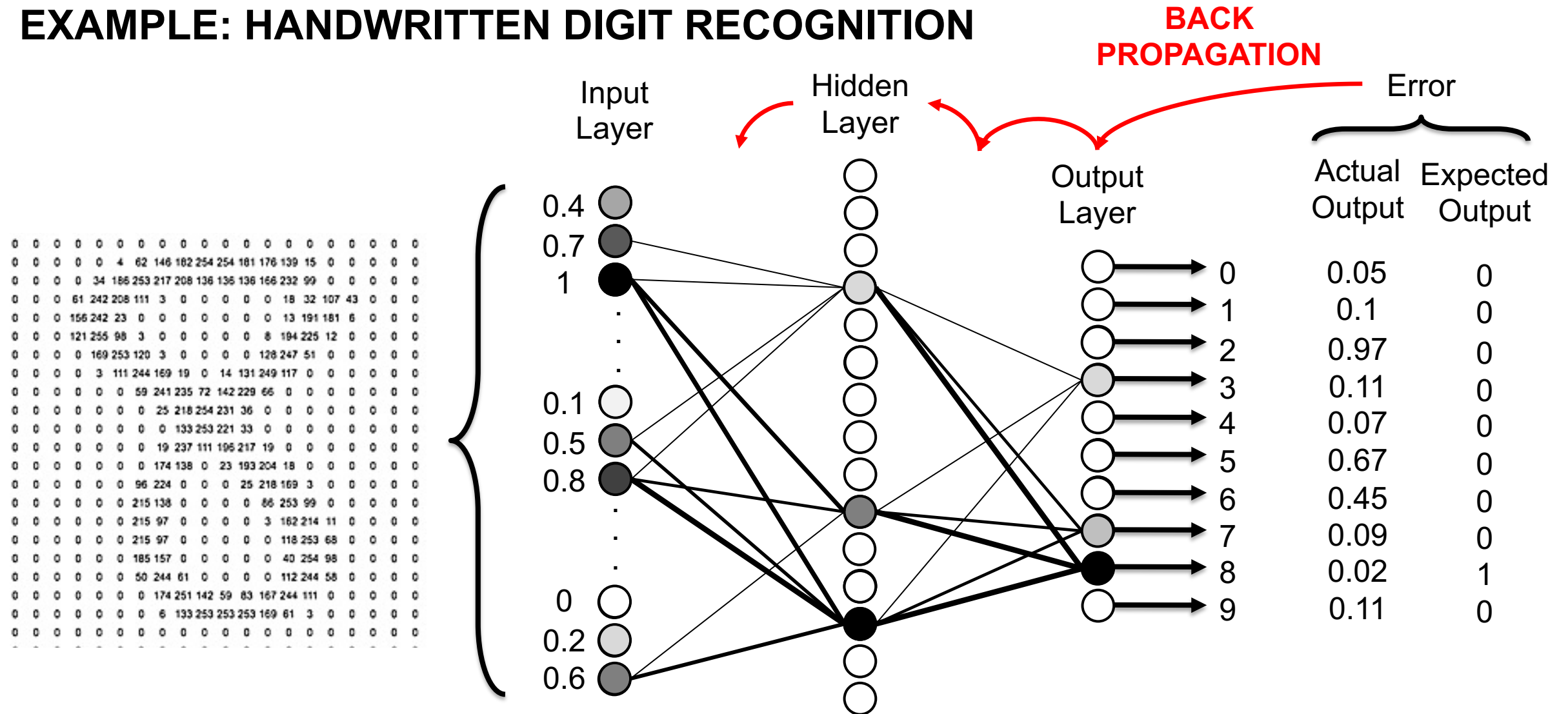
# INTRODUCTION

## EXAMPLE: HANDWRITTEN DIGIT RECOGNITION



# INTRODUCTION

## EXAMPLE: HANDWRITTEN DIGIT RECOGNITION

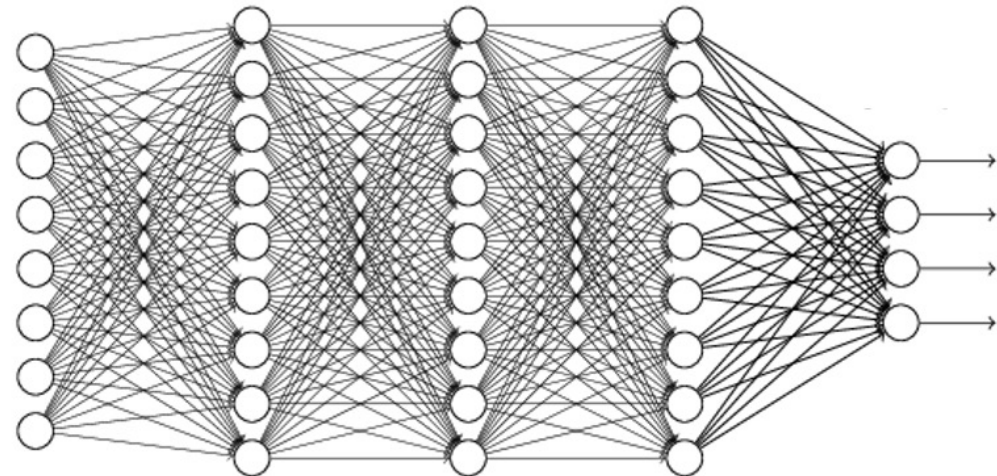
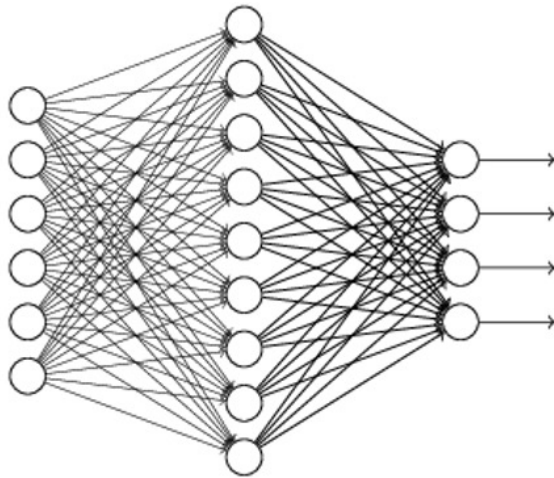




# INTRODUCTION

## SHALLOW vs DEEP LEARNING

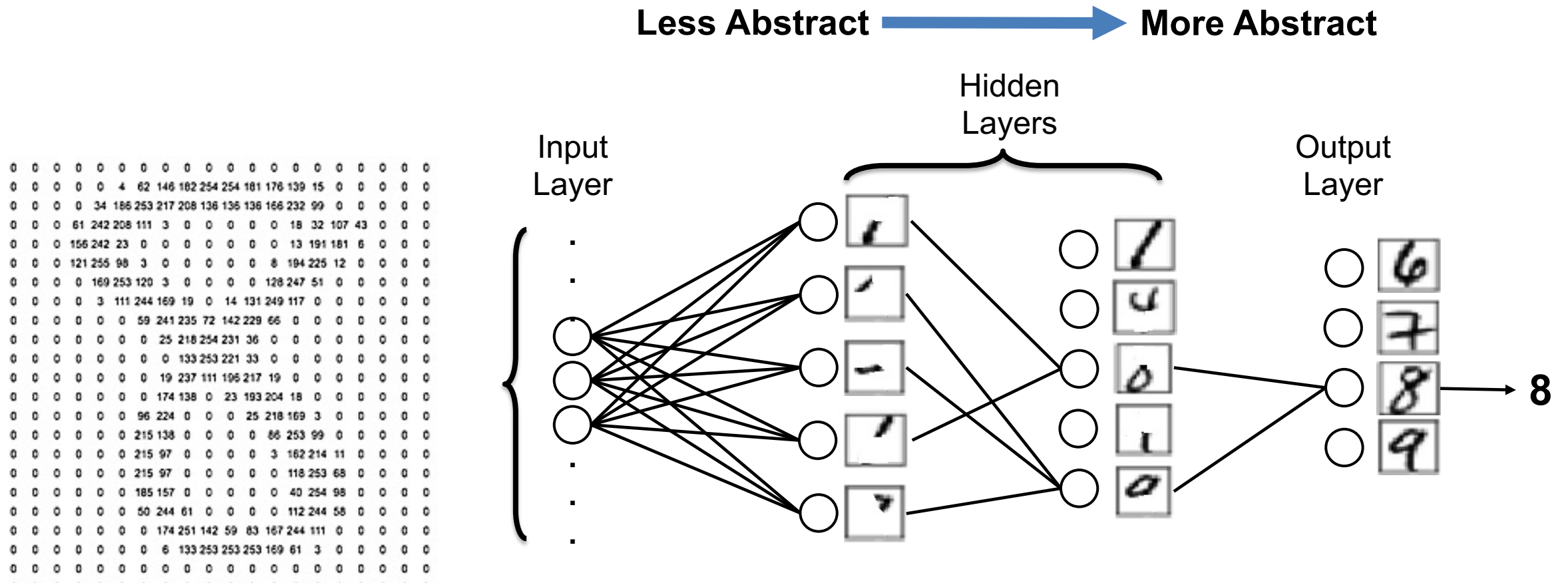
- The previous example was a case of “Shallow” learning, as the Neural Network consisted of only a single hidden layer.
- As more layers are added, the computer is able to understand and classify more abstract concepts.
- Deep Learning provides better performance with increasing depth, but at the cost of greater learning and computational time.



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# INTRODUCTION

## SHALLOW vs DEEP LEARNING



# TOPICS OF DEEP LEARNING

DEEP LEARNING

```
graph TD; A[DEEP LEARNING] --> B[UNSUPERVISED LEARNING]; A --> C[SUPERVISED LEARNING]; A --> D[REINFORCEMENT LEARNING];
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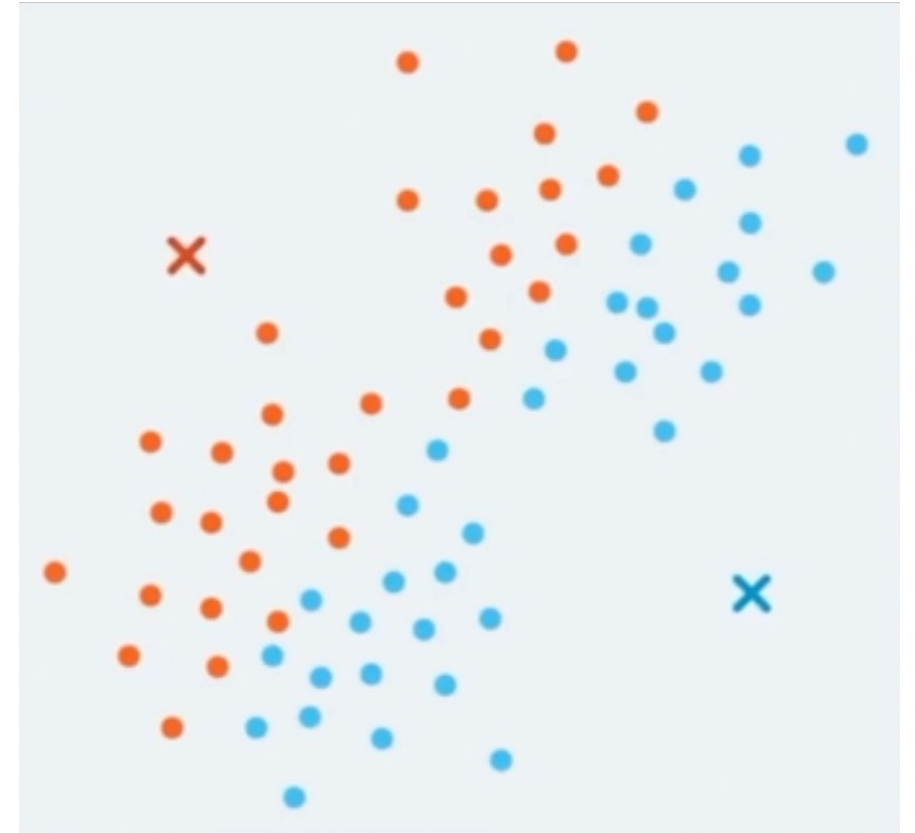
UNSUPERVISED  
LEARNING

SUPERVISED  
LEARNING

REINFORCEMENT  
LEARNING

# UNSUPERVISED LEARNING

- Method to train a Neural Network with little human interaction
- Unlabelled data fed to network for interpretation
  - No meta-data (Dates, Location Tags etc.)
- Derive patterns and correlations from the data without any labels
- “This image of a furry thing looks like these other furry things”

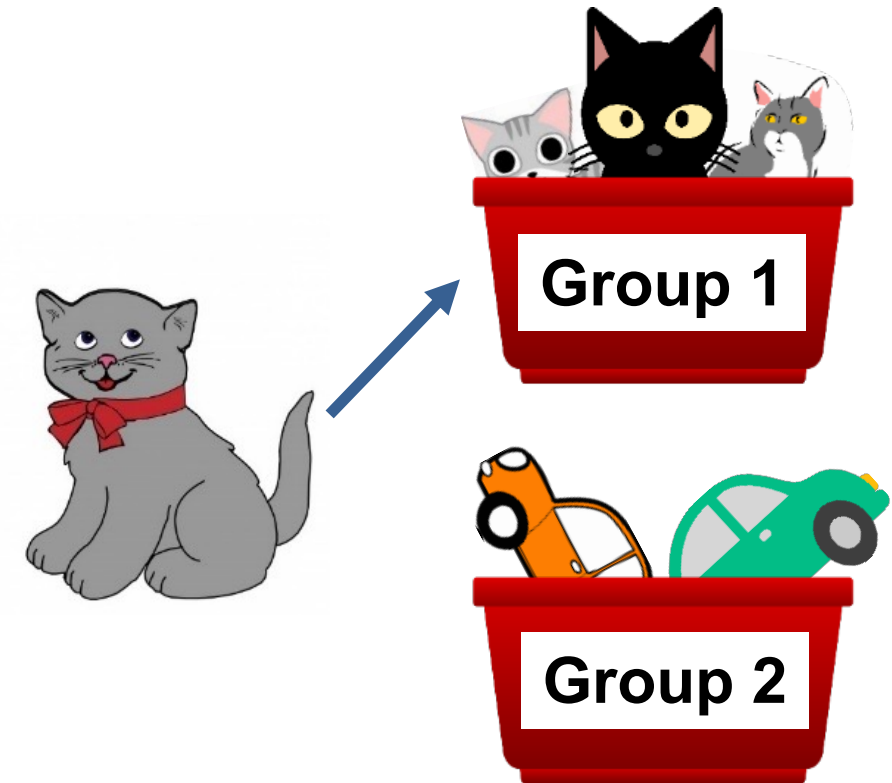


Courtesy of Toptal

# UNSUPERVISED LEARNING

## PURPOSE

- Able to make decisions from recognized patterns
- Define the problem with an unknown solution
  - Sorting photos based on image context rather than meta data
- Benefits:
  - Less man hours to label and track data
  - Solutions found with no predetermined connections
    - Driving a silver car leads to cancer
    - Investing on a Tuesday has less returns
  - Elimination of human biasing



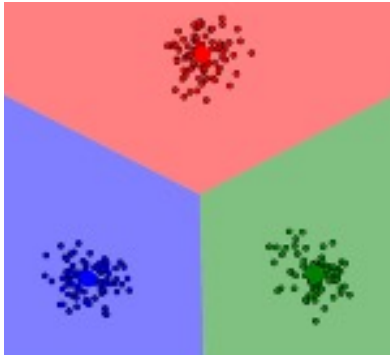
# UNSUPERVISED LEARNING

## METHODS

### ■ Clustering (Grouping Data)

#### **K-means clustering**

- K-number of clusters (Groups) created
- Centroids of clusters denoted where close data points are added to the  $k_{th}$  cluster



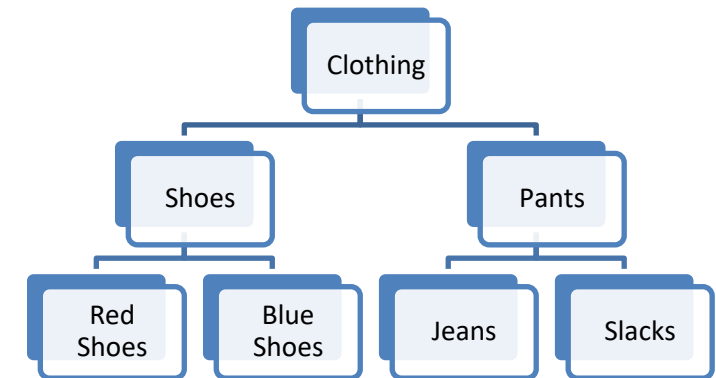
### ■ Reducing Dimensions

- Compressing data while keeping features
- Compressed data easily compared

} Effective w/ Deep Learning

#### **Hierarchical clustering**

- Clusters are grouped together creating a hierarchy
- E.g. Refine your search in online shopping



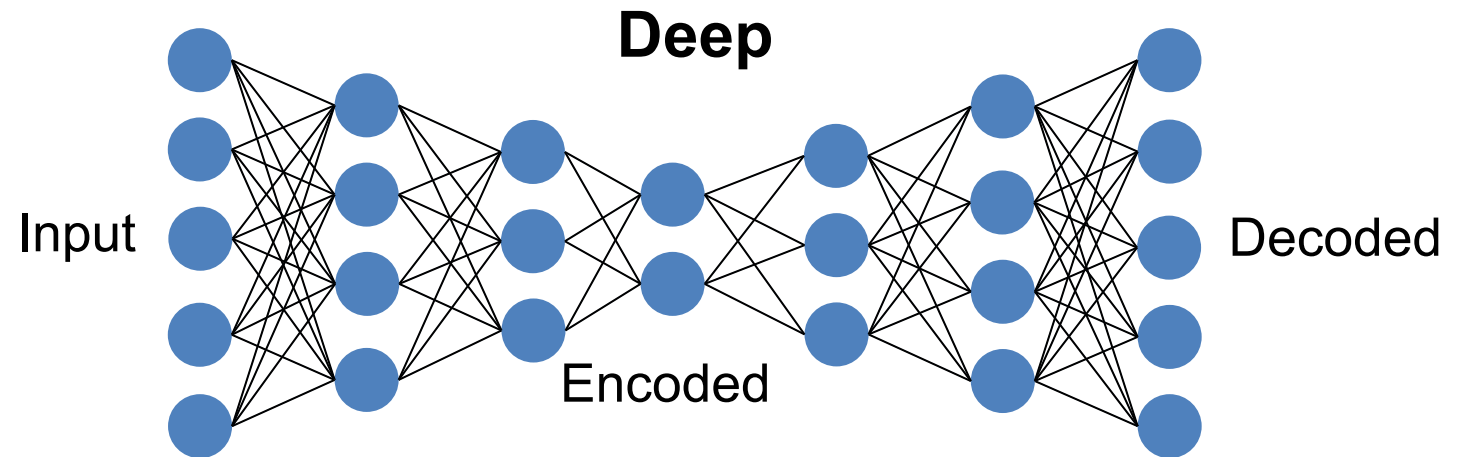
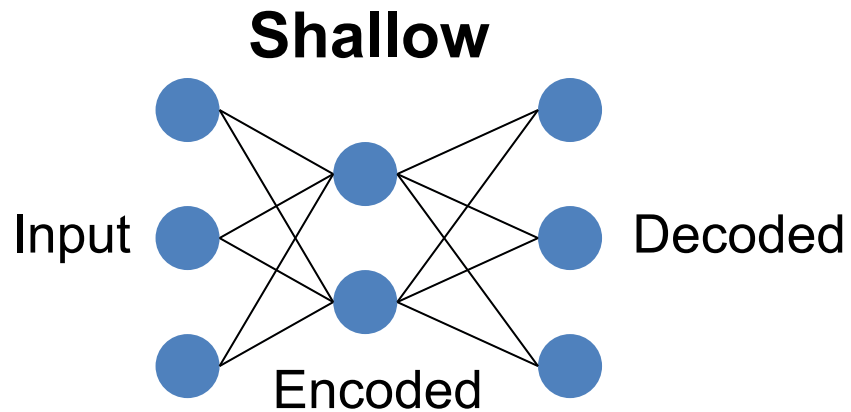
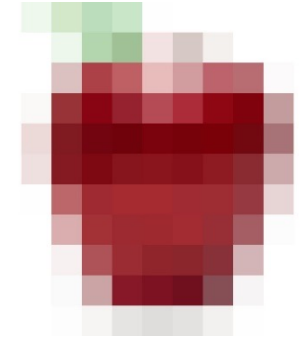
Images Courtesy of Medium.com



# UNSUPERVISED LEARNING

## AUTOENCODERS

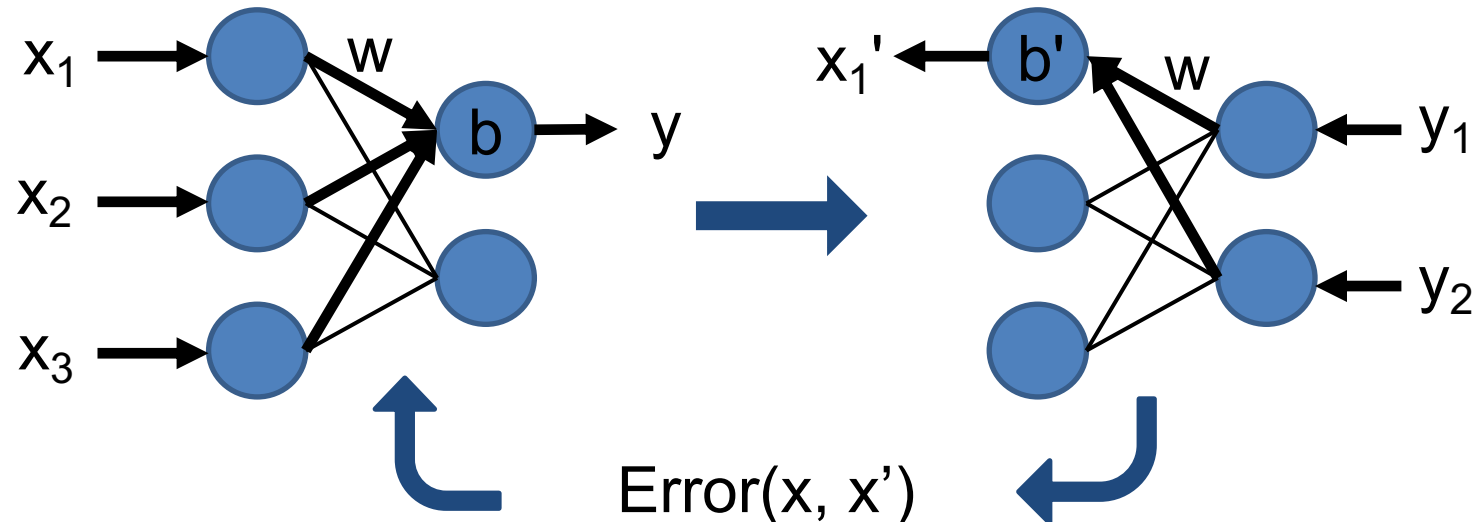
- Taking large data and outputting a smaller size for comparison
  - Attributes of a 784 pixel image condensed to a 30 unit vector
- Performed by symmetrical neural network structure
  - Output is trained to generate the same as the input
  - Center layer represents the compressed feature vector
  - Network can be shallow or deep



# UNSUPERVISED LEARNING

## RESTRICTED BOLTZMANN MACHINE (RBM)

- Construction
  - Two Layer (Visible and Hidden)
  - “Restricted”
- Forward and backward passes train the weights in unsupervised manor
  - Outputs from the forward pass become inputs on the backward pass
  - New outputs from the backward pass are compared to initial inputs

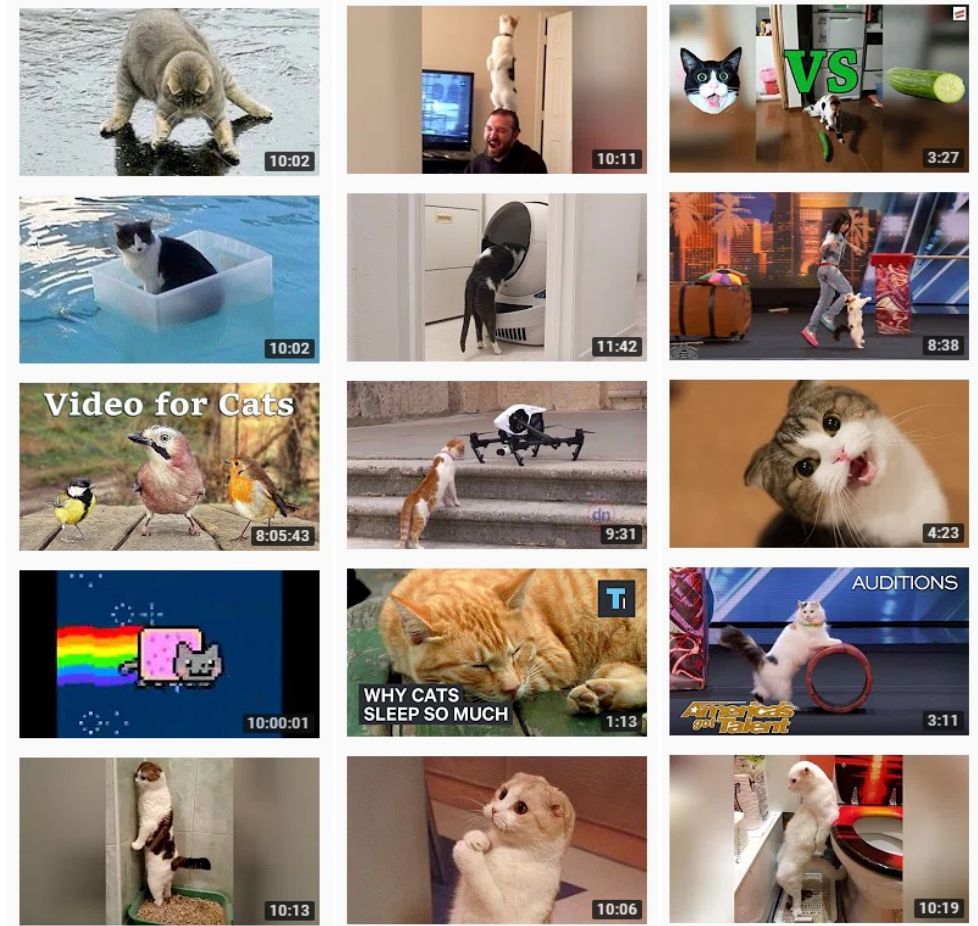


# UNSUPERVISED LEARNING

## GOOGLE'S CAT VIDEO FINDER

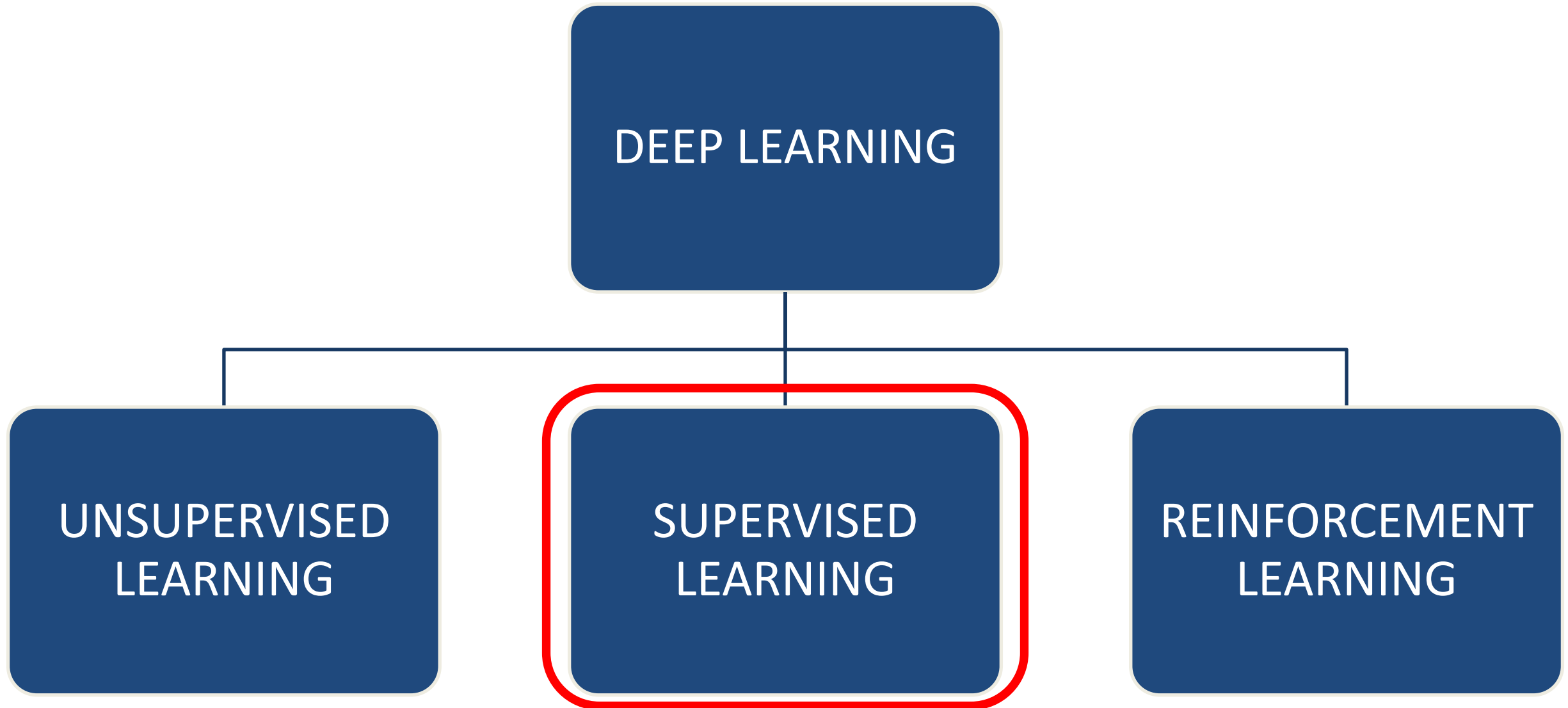
- Data Set
  - Unlabeled images from YouTube
- Network
  - 1 Billion connections
  - 9 Layer Autoencoder

} Deep Belief Network
- Output
  - Found Specific Neuron Related to Cat Faces
  - Captured “Complex Invariances”
    - Related to human capability
    - AKA Understanding the “important things” in pictures



Courtesy of Youtube

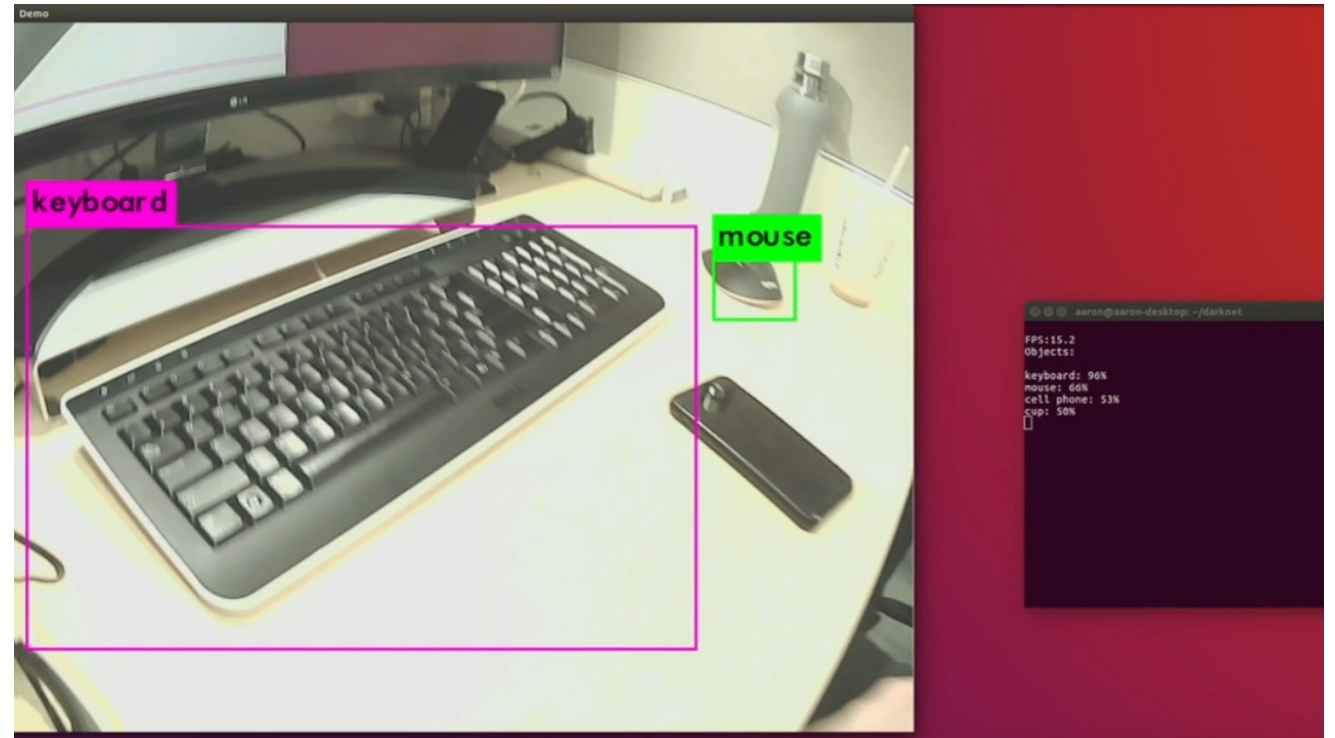
# TOPICS OF DEEP LEARNING



# SUPERVISED LEARNING

Supervised learning is useful for building a classifier of **LABELLED DATA**

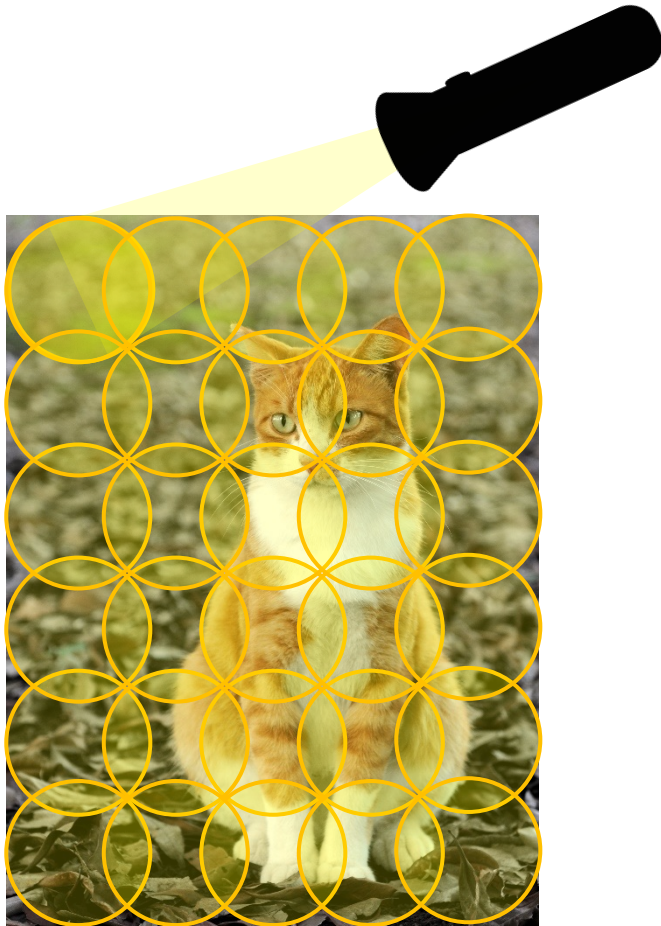
- Text Processing
  - Recursive Neural Tensor Network
  - Recurrent Network
- Image Recognition
  - Deep Belief Network
  - Convolutional Neural Network
- Object Recognition
  - Recursive Neural Tensor Network
  - Convolutional Neural Network
- Speech Recognition
  - Recurrent Network



Live YOLO V3 Demo on NVIDIA GTX 1060

# SUPERVISED LEARNING

## FLASHLIGHT EXAMPLE



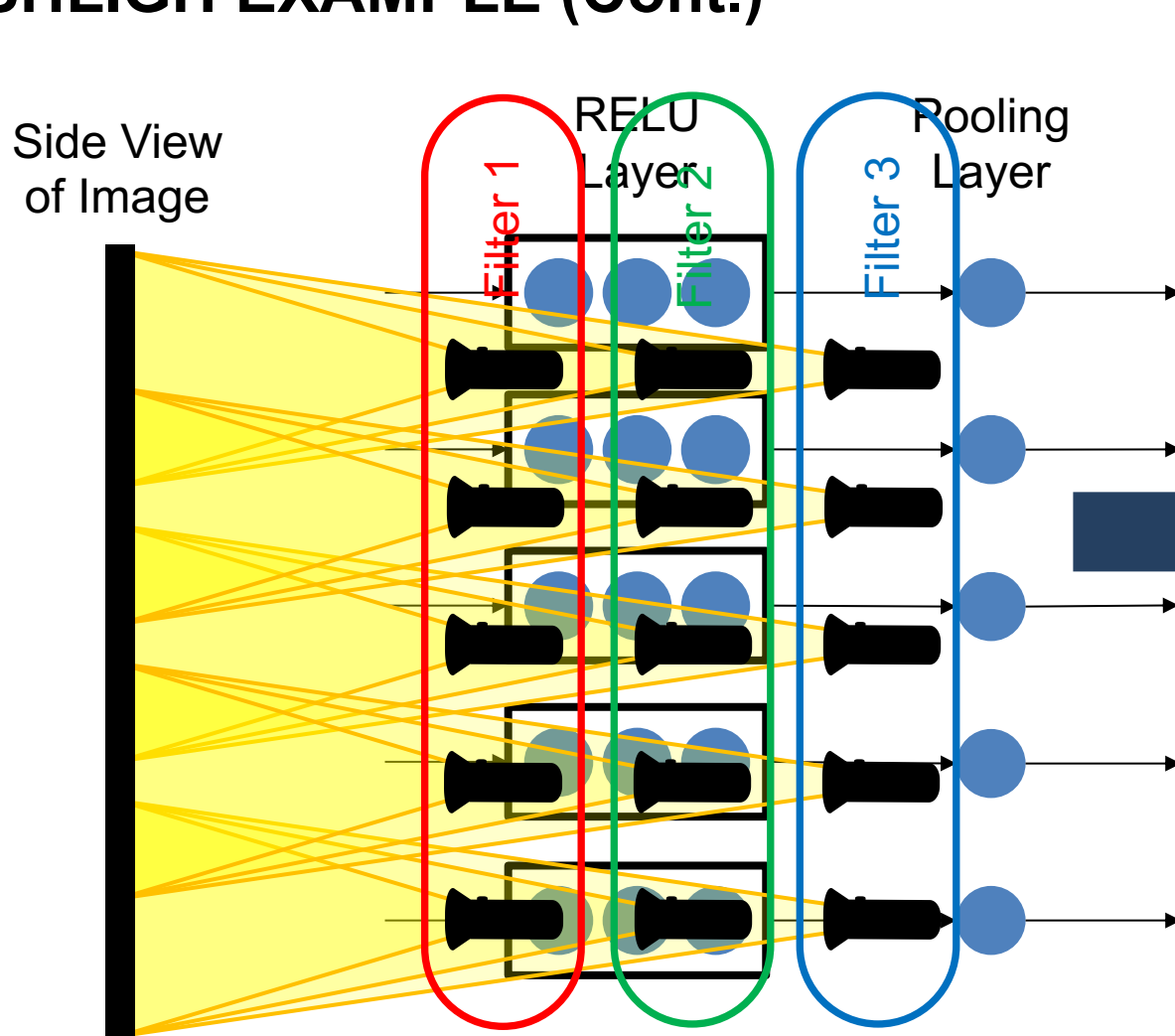
- The flashlight “slides” (convolves) along the image pixel by pixel, leaving behind a spot of light
- Each spot of light, called a filter, seeks out a specific pattern at that specific location in the image
- Since each filter can only look for one specific pattern, multiple filters must be used at each location on the image.

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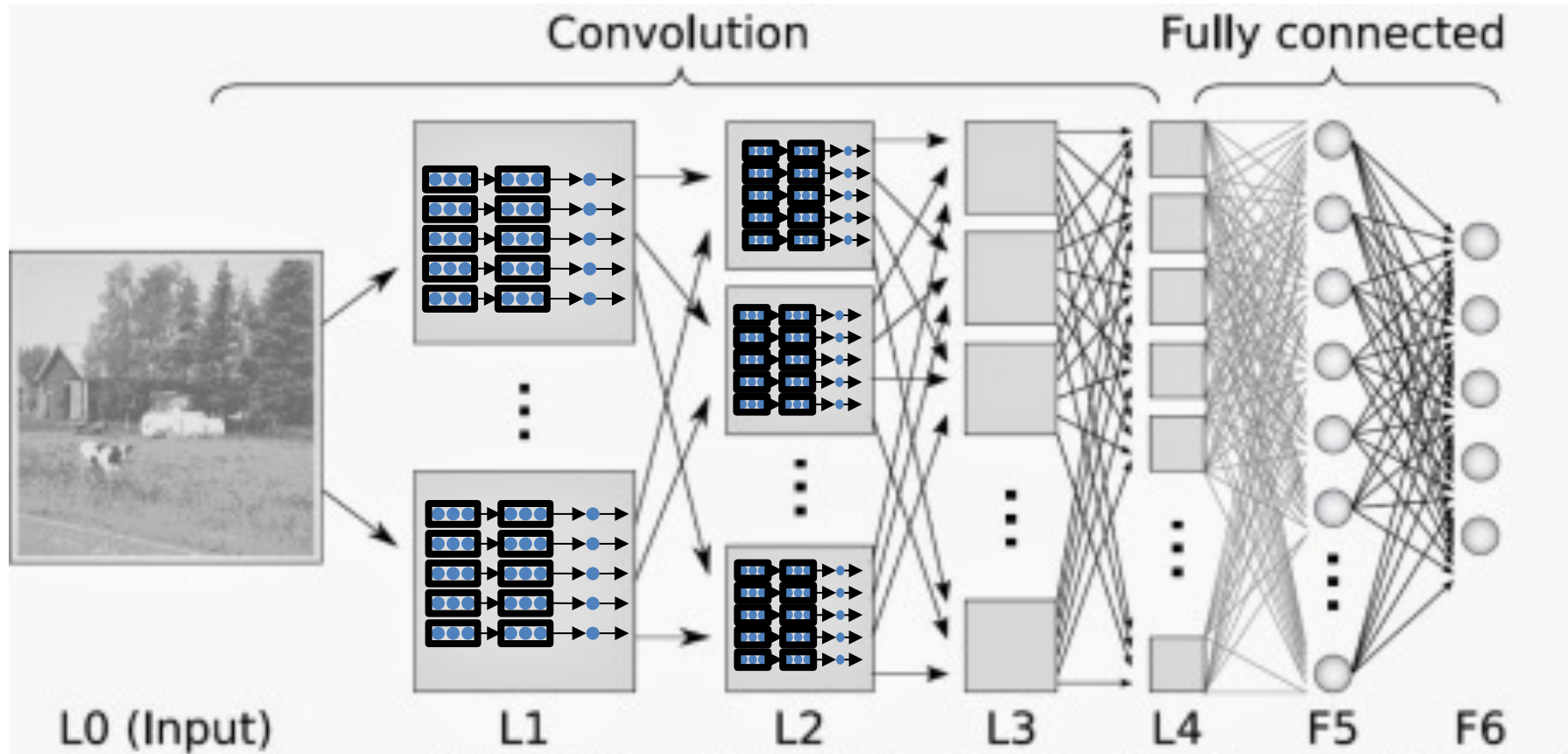
# SUPERVISED LEARNING

## FLASHLIGHT EXAMPLE (Cont.)



- Input Layer – holds the raw pixel data
- Conv. Layer – calculates the dot product of the pixel data and the filter(s) created for a specific region
- ReLU Layer – applies an element-wise activation function (i.e.  $\max(0, x)$ )
- Pooling Layer – Performs a down sampling operation, reducing the dataset size

# SUPERVISED LEARNING

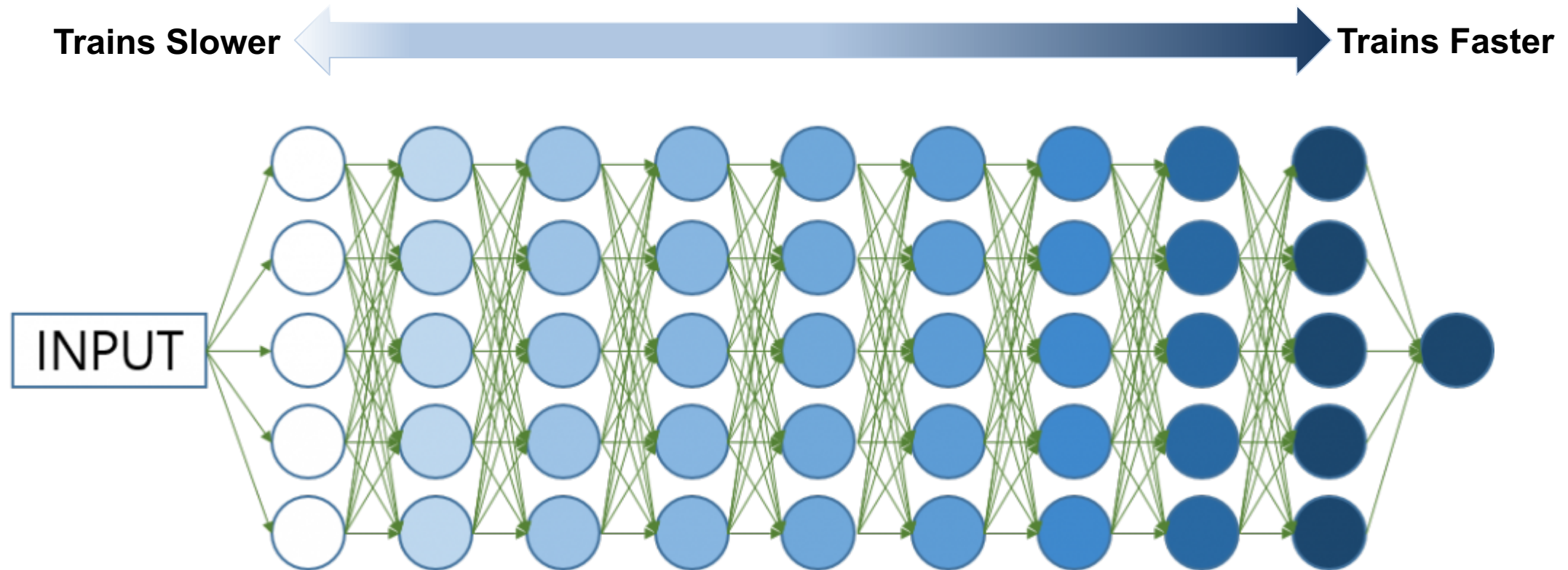


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# SUPERVISED LEARNING

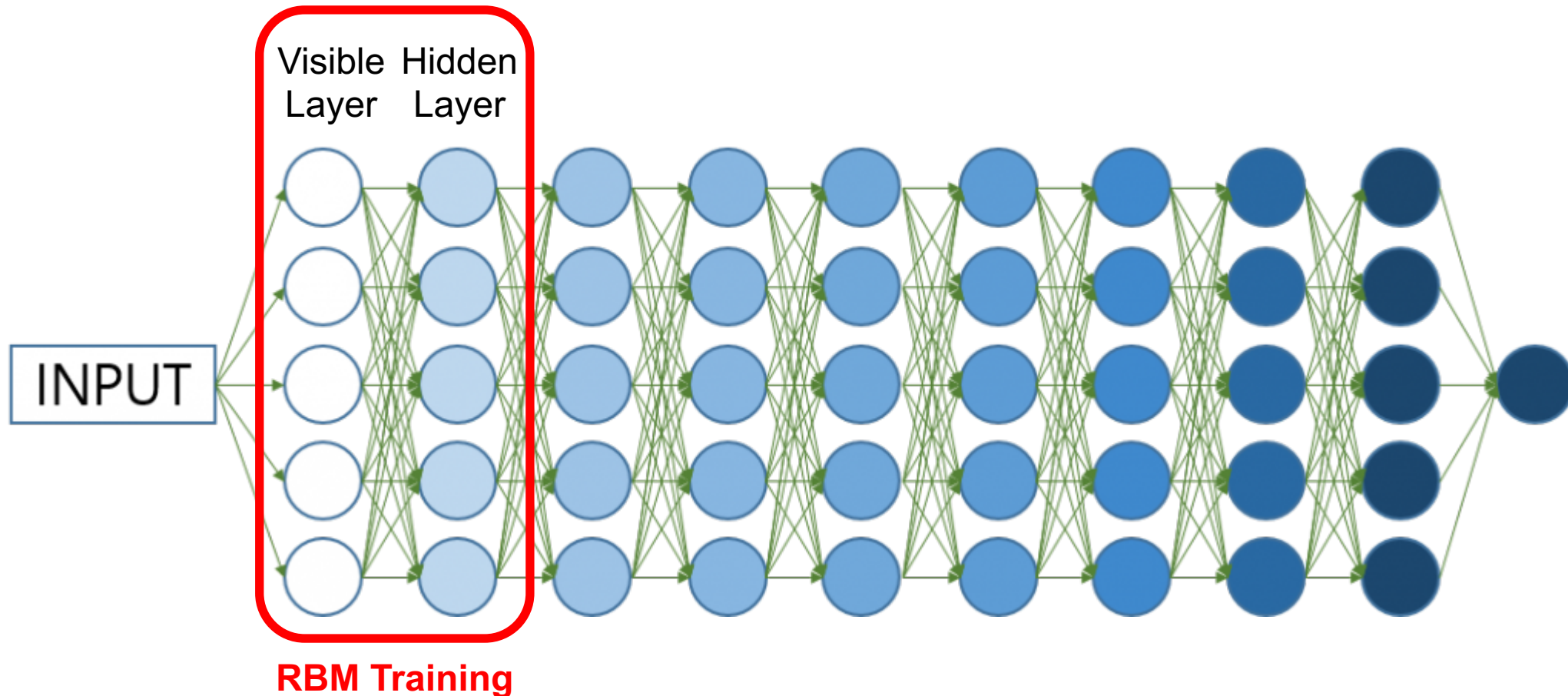
## CHALLENGES

- Requires Large Set of Training Data (10's of millions)
- The Fundamental Issue: Vanishing Gradient



# SUPERVISED LEARNING

- Geoffrey Hinton of UofT proposed a solution in 2006
  - Utilizes Restricted Boltzmann Machine which trains two layers at a time



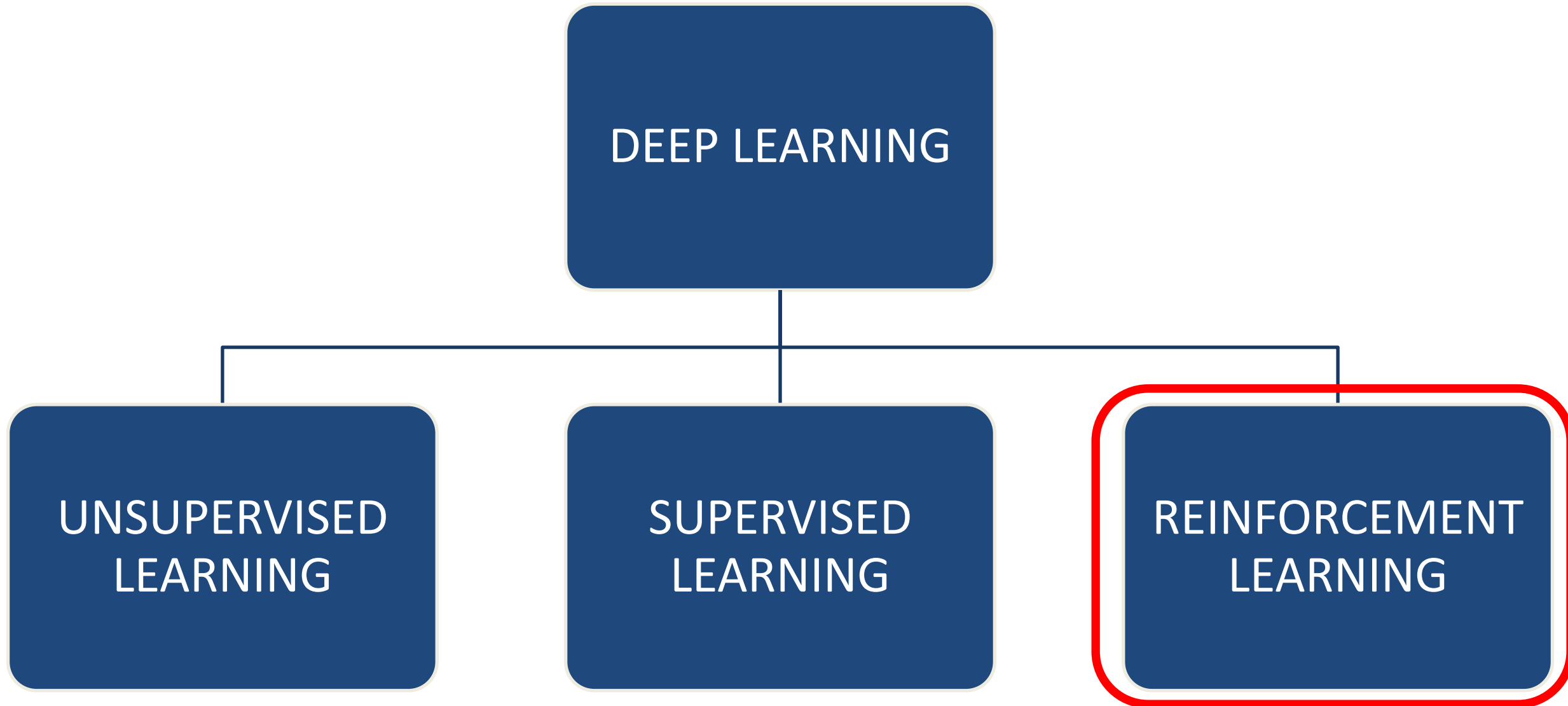
# SUPERVISED LEARNING

## HISTORY OF PROGRESS

- 2012 – AlexNet
  - CNN surpasses traditional image processing methods to win the 2012 ImageNet Large-Scale Visual Recognition Challenge
  - Reduced error from previous **26.2% to 15.4%** with CNN
- 2013 – ZF Net
  - Error reduced to only 11.2%
  - Trained with only 1.3 million datasets opposed to 15 million with AlexNet
- 2015 – Microsoft ResNet
  - Error further reduced to **3.6%** to surpass **humans (generally 5-10%)**
  - “Ultra Deep” CNN architecture consisting of 152 layers



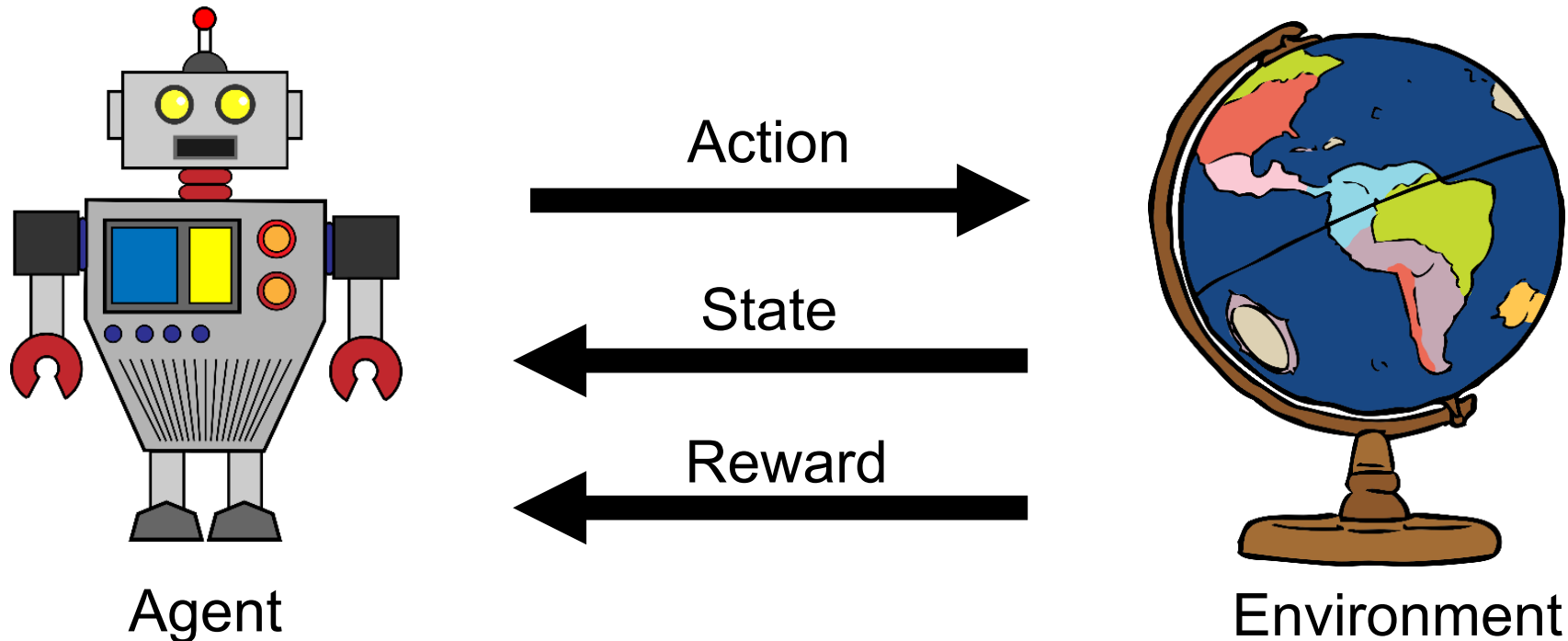
# TOPICS OF DEEP LEARNING





# REINFORCEMENT LEARNING

- The goal is to learn sequences of actions that will lead an agent towards its goal
- There are **rewards for right decisions** and **penalties for wrong decisions**
- Feedback is delayed, not instantaneous
- 2 Types of Rewards: Shaped Reward vs Sparse Reward



# REINFORCEMENT LEARNING

## Policy Gradients

Focuses on directly inferring a policy that maximizes the reward on a specific environment

Agent would plan to move in a way that achieve certain well known position



VS

## Q Learning

Tries to quantify the value of every state-action pair

Agent would assign a value to every position and select the move that score higher



# Q LEARNING

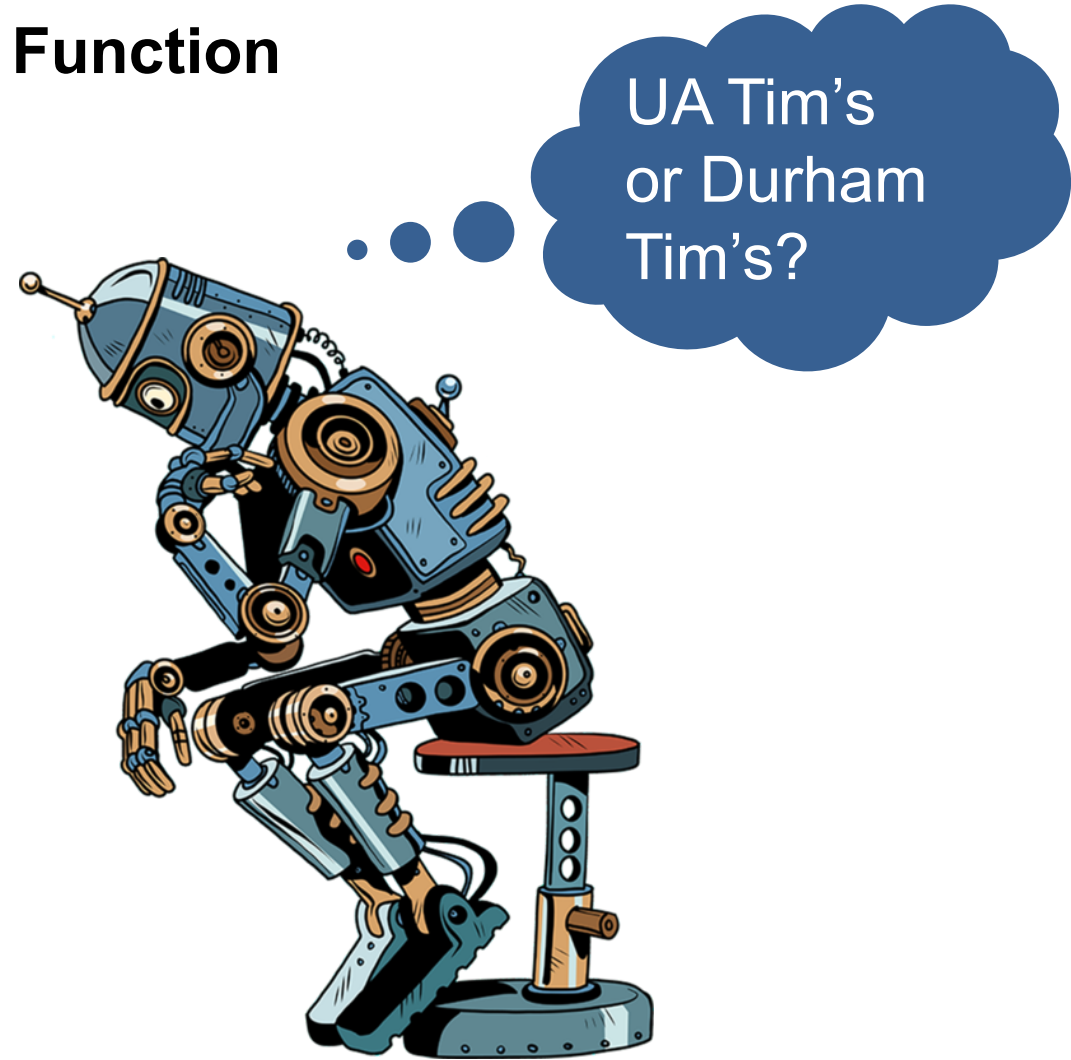
The goal of Q Learning is to approximate a Q Function and use it to infer the optimal policy

**Q Function: Quantify state-action pairs**

$$Q(s, a) = r + \gamma \max_{a'} Q(s', a')$$

## Key Vocabulary

- State: an immediate situation
- Action: an action
- Reward: the feedback
- Discount Factor: dampen future rewards



# DEEP REINFORCEMENT LEARNING

## ATARI BREAKOUT: AN EXAMPLE

- Supervised Learning
  - a good human gamer play for a couple of hours, then create a data set where all the frames are logged as well as the response the gamer is outputting
    - Feed this data in to the NN to train it to replicate the actions of a human gamer
- Reinforcement Learning
  - Q Learning would define states such as location of paddle, location/direction of ball and presence of brick as states
  - The Q-table will be too large with many pixel combinations that doesn't occur

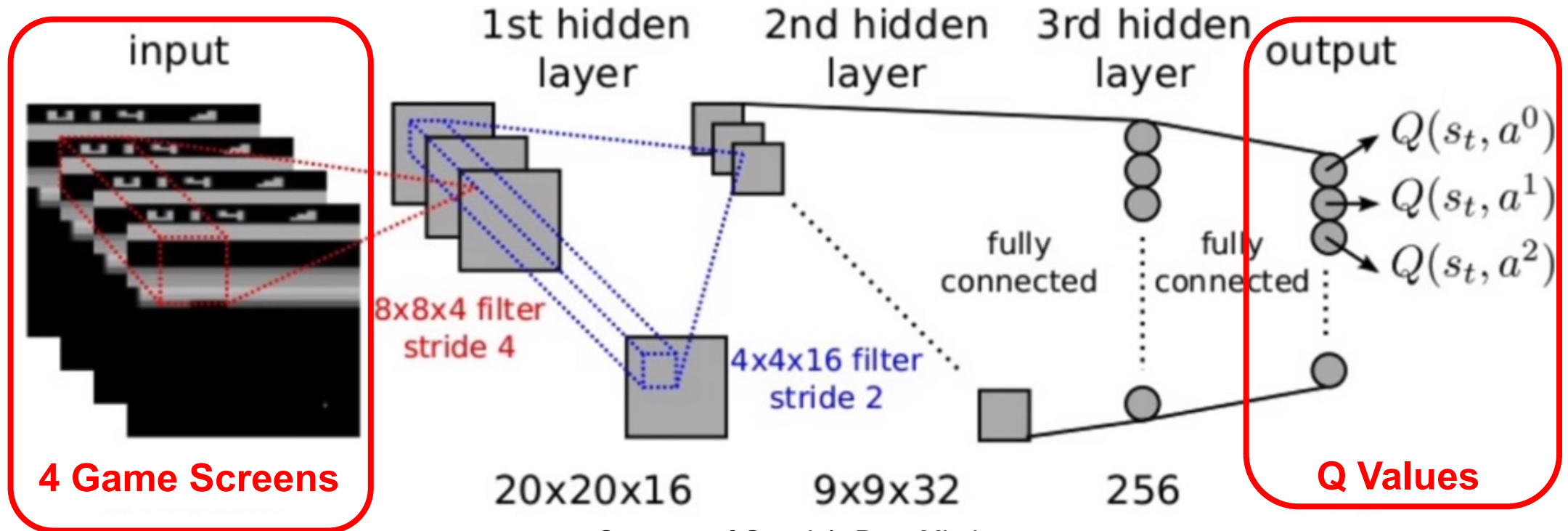


Atari Breakout

# DEEP REINFORCEMENT LEARNING

## DEEP Q NETWORK

- Can represent our Q-Function with a NN that use game screens and outputs the corresponding Q-Value for the next best action
- 3 Convolutional Layers and 2 fully connected layers



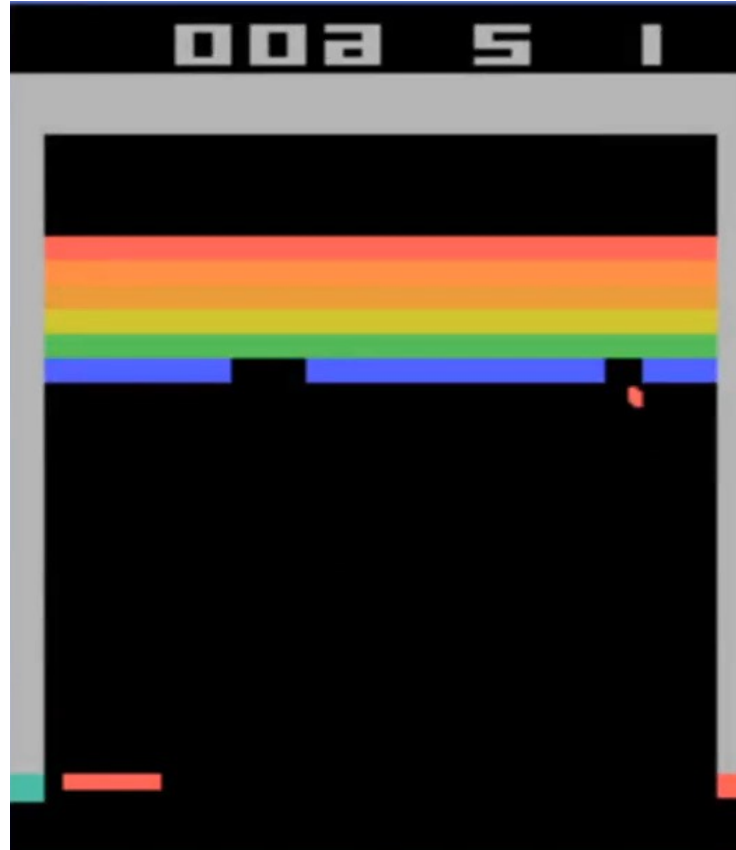
Courtesy of Google's DeepMind

# DEEP REINFORCEMENT LEARNING

## ATARI BREAKOUT



10 minutes of training



120 minutes of training



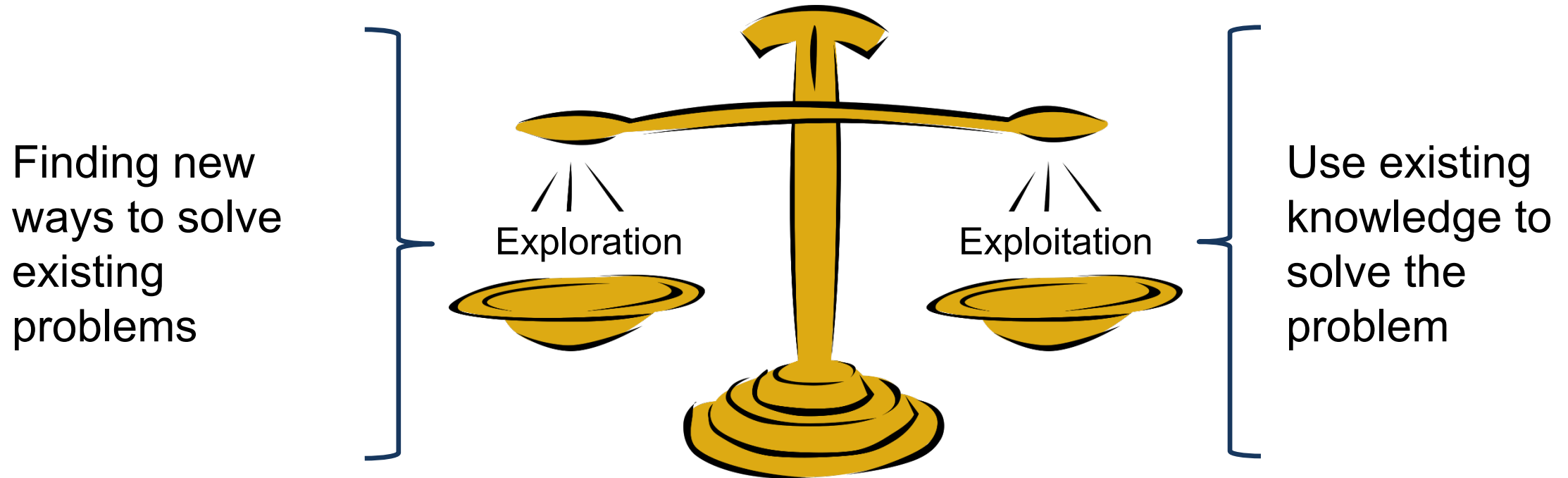
240 minutes of training

Video Courtesy of Google's DeepMind



# DEEP REINFORCEMENT LEARNING

## CHALLENGES

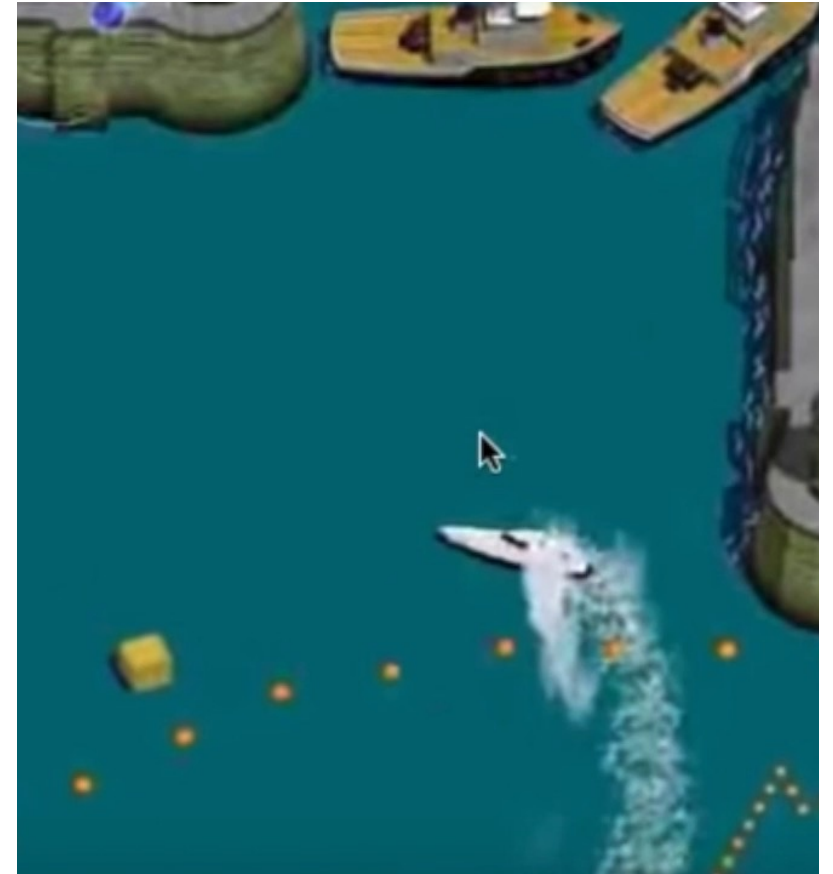


- As Q Function converges, it returns more consistent Q-values and the amount of exploration decreases
- Agent starts to settle with the first effective strategy it finds

# DEEP REINFORCEMENT LEARNING

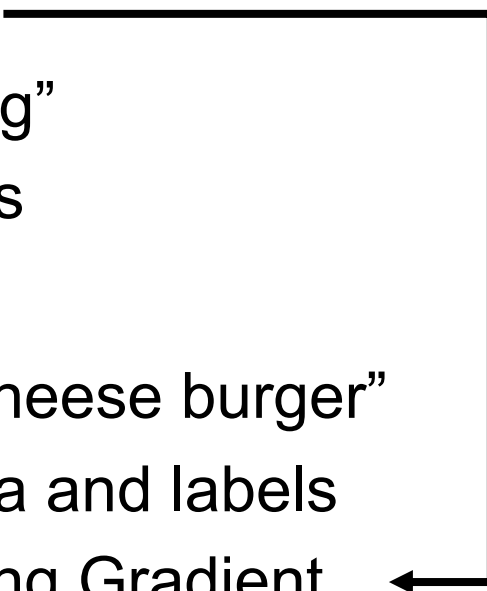
## CHALLENGES

- Takes days to learning something that humans may be able to pick up in a few minutes
- Often times, the problems you are trying to solve with DRL may be solved easier with other classical techniques
- Reward function design is difficult
  - Could lead to “reward hacking”



Video Courtesy of Jack Clark “Coast Runners 7”

# CONCLUSION

- Unsupervised Learning
    - “That thing is like this other thing”
    - Learn similarities without names
  - Supervised Learning
    - “That thing is a double bacon cheese burger”
    - Learn correlations between data and labels
    - Fundamental Problem: Vanishing Gradient
  - Reinforcement Learning
    - “Eat that thing because it tastes good and will keep you alive longer”
    - Actions based on short/long term rewards – trial and error
    - Highest potential to achieve Artificial General Intelligence
- 

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**THE END**  
**THANK YOU**  
**QUESTIONS?**