Aaron Hao Tan

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Academic Experience

Stanford University Palo Alto, USA

Postdoctoral Fellow, Stanford University **Lab** Assistive Robotics and Manipulation Lab

University of Toronto Toronto, Canada

Doctor of Philosophy, Robotics Institute

2019 - 2024

Incoming 2025

Thesis Development of Inference-driven Decision Making for Mobile Robots, CGPA (4.0/4.0)

Work Experience ____

Robot Learning Researcher, Ph.D. Thesis

Toronto, Ontario

Autonomous System and Biomechatronics Lab, University of Toronto

2019 - 2024

- Vision Language Models Robot reasoning/planning for cross embodiment navigation with hand-drawn maps.
- Diffusion Models Multi-robot map prediction via contrastive learning and consistency models in 3D environments.
- **Decision Transformers** End-to-end, goal oriented multi-robot navigation in unknown, unstructured environments.
- Deep Multi-agent Reinforcement Learning Centralized training for decentralized execution to address multi-robot task inference.
- Sim 2 Real Transferred robot navigation policy from simulation to the real world using domain randomization.
- Publications Published in ICRA/IROS (oral presentation), RAL, JIRS, and ASME conferences.

Technical FounderToronto, Ontario

Syncere AI, Scholarply, ONE800

Jan. 2023 - Present

- Syncere, Robots for Modern Hospitality Building robots for the hotel industry.
- Scholarply, LLM-based Financial Agent Building LLM agents to automate the scholarship application process for students.
- ONE800, ChatGPT for Seniors Integrated generative AI technologies to iMessage to improve AI accessibility for senior population.
- Leadership Managed cross-functional teams from engineering to marketing and business operations.

Al Researcher Toronto, Ontario

Temetry Faculty of Medicine, Toronto

May. 2022 - Aug. 2022

- Language Models Built LLM-powered patient screening tool and deploying through SMS to increase healthcare accessibility.
- Deep Learning First application of deep learning to the classification of homonymous defects on automated perimetry.
- · Accessibility Quantitative analysis on the impacts of remote education for surgeons globally.
- Publications Published in British Journal of Ophthalmology.

Robotics Researcher, MASc Thesis

Oshawa, Ontario

 ${\it General Robotics \& Autonomous Systems and Processes Lab, Ontario Tech University}$

May. 2017 - May. 2019

- Mobile Robot Stack Designed and developed both hardware and software for a novel multi-terrain robot.
- Mechatronics Designed and implemented hardware architecture for robot sensing, data acquisition, and motion control.
- Publications Published 4 papers for IEEE and ASME conferences and journals.

Engineering Specialist/Advanced Technology Specialist Intern

Oshawa, Ontario

General Motors of Canada Company - Active Safety Advanced Development

2 Terms (2016/2017)

- Wearable Technology Designed wearable hardware and developed ML models to predict driver behavior based on vital signs.
- Camera System Designed an adjustable camera system for trailers to provide drivers with greater awareness.

Recognition

2022-2024	4 Ontario Graduate Scholarship (\$15k Prize), University of Toronto	Toronto, Ontario
2023	Annual Shot on iPhone Photography Award (3rd Place), IPPAWARDS	NYC, New York
2022	Apple AI/ML Scholar Nominee (1 of 3 selected across university), University of Toronto	Toronto, Ontario
2022	Undergraduate Teaching Assisstant Award (\$500 Prize), University of Toronto	Toronto, Ontario
2022	DiDi Graduate Scholarship (\$10k Prize), University of Toronto	Toronto, Ontario
2021	1st Place at RO-MAN: The Roboethics Competition (\$1k Prize), McGill University	Montreal, Quebec
2021	Best Research Day Paper in Dept. of Ophthalmology and Vision Sciences, University of Toronto	Toronto, Ontario
2019	Outstanding Thesis Award & Dean's Graduate Scholarship (\$5k Prize), Ontario Tech University	Oshawa, Ontario
2018	Photograhy for Apple's Shot on iPhone Campaign, Apple	California, USA