

Alternate types of Fourier Series: Derivation and examples

Recall: the Fourier Sine Series was derived from

- 1) Looking for eigenvalues and eigenvectors of the operator $L = -K \frac{\partial^2}{\partial x^2}$. ie solving $Lu = \lambda u$
- 2) Applying the boundary conditions $u(0) = u(l) = 0$ to the general solution $C_1 \cos(\sqrt{\lambda}x) + C_2 \sin(\sqrt{\lambda}x)$ of the eigenvalue problem $Lu = \lambda u$ to get that $u(x) = \sin(\frac{n\pi}{l}x)$ are the eigenvectors of L corresponding to eigenvalue $\frac{n^2\pi^2}{l^2}$
- 3) Then the functions $\tilde{u}_n(x)$ defined by $\tilde{u}_n(x) = \sqrt{\frac{2}{l}} \sin(\frac{n\pi}{l}x)$ are orthonormal eigenvectors of the operator L .
- 4) Then we considered the subvector spaces V^K of $C_D^2[0,1]$ defined by $V^K = \text{span}\{\tilde{u}_1, \tilde{u}_2, \dots, \tilde{u}_K\}$
- 5) Given any function $g(x)$ in $C[0,1]$ we found the best approximation to $g(x)$ in V^K was given by:

$$\begin{aligned} m_K(x) &= \sum_{i=1}^K (g, \tilde{u}_i) \tilde{u}_i(x) \\ &= \sum_{i=1}^K \left(\frac{2}{l} \int_0^l g(x) \sin(\frac{n\pi}{l}x) dx \right) \sin(\frac{n\pi}{l}x) \end{aligned}$$

- 6) Then we commented that a result from mathematics tells us that the higher the value of K we select the closer $m_K(x)$ is to $g(x)$ in the sense that the error $\|g(x) - m_K(x)\|_{L^2}$ measured by the L^2 inner product norm goes to zero.

- 7) Since the approximation continues to get better then the function $m_\infty(x) = \lim_{K \rightarrow \infty} m_K(x)$ is going to give us the best possible result. This function is

$$\begin{aligned} m_\infty(x) &= \sum_{i=1}^{\infty} (g, \tilde{u}_i) \tilde{u}_i(x) \\ &= \sum_{i=1}^{\infty} \left(\frac{2}{l} \int_0^l g(x) \sin(\frac{n\pi}{l}x) dx \right) \sin(\frac{n\pi}{l}x) \end{aligned}$$

and is called the

Fourier Sine Series of $g(x)$.

Now we investigate the effects of changing the boundary conditions.

Consider the Boundary value problem:

$$\begin{cases} -k \frac{\partial^2 u}{\partial x^2} = f(x), & 0 < x < l \\ u(0) = 0 \\ \frac{\partial u}{\partial x}(l) = 0 \end{cases}$$

Our differential operator is $L = -k \frac{\partial^2}{\partial x^2}$ but now we are

considering L on the space

$$C_M^2[0, l] = \left\{ f \mid f(0) = 0, \frac{\partial f}{\partial x}(l) = 0 \right\}$$

Recall that the domain of L plays a big role in whether or not L is symmetric and whether or not its eigenvalues are positive.

Let's check symmetry:

Let $f, g \in C_M^2[0, l]$. We need to verify that $(Lf, g) = (f, Lg)$ we have:

$$\begin{aligned} (Lf, g) &= \int_0^l \left(-k \frac{\partial^2}{\partial x^2} f \right) g = \int_0^l k \frac{\partial f}{\partial x} \frac{\partial g}{\partial x} + \left. -k \frac{\partial f}{\partial x} g \right|_0^l \\ &= \int_0^l k \frac{\partial f}{\partial x} \frac{\partial g}{\partial x} + \left. -k \frac{\partial f}{\partial x} g \right|_0^l \\ &= \int_0^l f \left(-k \frac{\partial^2}{\partial x^2} g \right) + \left. k f \frac{\partial g}{\partial x} \right|_0^l \\ &= (f, Lg) + k f(l) \frac{\partial g}{\partial x}(l) - k f(0) \frac{\partial g}{\partial x}(0) \\ &= (f, Lg) \end{aligned}$$

So L is still symmetric on $C_M^2[0, l]$ but the way that the boundary term became zero was different for $C_M^2[0, l]$ than it was for $C^2[0, l]$. Since L is symmetric we know that eigenvectors for distinct eigenvalues are orthogonal and all eigenvalues are real.

The fact that eigenvalues are still positive follows from the fact that if \tilde{u} is a unit eigenvector of L with eigenvalue λ then:

$$\begin{aligned} \lambda &= \lambda \cdot 1 = \lambda (\tilde{u}, \tilde{u}) = (\lambda \tilde{u}, \tilde{u}) = (L\tilde{u}, \tilde{u}) \\ &= \int_0^l \left(-k \frac{\partial^2}{\partial x^2} \tilde{u} \right) \tilde{u} = k \int_0^l \frac{\partial}{\partial x} \tilde{u} \frac{\partial}{\partial x} \tilde{u} + \left. k \frac{\partial}{\partial x} \tilde{u} \tilde{u} \right|_0^l = k \int_0^l \left(\frac{\partial}{\partial x} \tilde{u} \right)^2 > 0 \end{aligned}$$

So each eigenvalue λ satisfies $\lambda = \theta^2 > 0$ for some θ . Finding the eigenvalues for L on $C_m^2[0, l]$ then amounts to solving:

$$\frac{\partial^2}{\partial x^2} u + \theta^2 u = 0$$

$$u(0) = 0$$

$$\frac{\partial u}{\partial x}(l) = 0$$

We mentioned that the general solution to " $\frac{\partial^2}{\partial x^2} u + \theta^2 u = 0$ " is given by: $u(x) = C_1 \cos(\theta x) + C_2 \sin(\theta x)$

The boundary conditions give: $u(0) = C_1 = 0$
and $\frac{\partial u}{\partial x}(l) = 0 \Rightarrow C_2 \theta \cos(\theta l) = 0$

which means that $\theta l = \frac{\pi}{2}, \frac{3\pi}{2}, \dots, \frac{(2n-1)\pi}{2}$ for $n=1, 2, \dots$
so that:

$$\theta = \frac{(2n-1)\pi}{2l}, n=1, 2, \dots$$

Therefore the eigenvalues are $\lambda_n = \theta_n^2 = \frac{(2n-1)^2 \pi^2}{4l^2}$ $n=1, 2, \dots$

and the corresponding eigenvectors are $\tilde{\varphi}_n = \sin\left(\frac{(2n-1)\pi}{2l} x\right)$

A computation shows that $(\tilde{\varphi}_n, \tilde{\varphi}_n) = l/2$ so that $\tilde{\varphi}_n = \sqrt{\frac{2}{l}} \varphi_n(x)$ defines an orthonormal set of eigenvectors $\{\tilde{\varphi}_n\}_{n=1}^\infty$ to L defined on $C_m^2[0, l]$.

Now if we let $f(x)$ be any continuous function then the best approximation to f from the vector space $V^k = \text{span}\{\tilde{\varphi}_1, \dots, \tilde{\varphi}_k\}$ is:

$$m_k(x) = \sum_{n=1}^k b_n \sqrt{\frac{2}{l}} \sin\left(\frac{(2n-1)\pi}{2l} x\right)$$

$$\text{where } b_n = (f, \tilde{\varphi}_n) = \sqrt{\frac{2}{l}} \int_0^l f(x) \sin\left(\frac{(2n-1)\pi}{2l} x\right) dx$$

$$\text{so that } m_k(x) = \sum_{n=1}^k \frac{2}{l} \left(\int_0^l f(x) \sin\left(\frac{(2n-1)\pi}{2l} x\right) dx \right) \sin\left(\frac{(2n-1)\pi}{2l} x\right)$$

Like we saw in the previous case where L was considered as defined on $C_0^2[0, l]$ as $k \rightarrow \infty$ $m_k(x)$ is a better approximation

for $f(x)$. Hence

$$m_\infty(x) = \lim_{k \rightarrow \infty} M_k(x) = \sum_{n=1}^{\infty} \frac{2}{l} \left(\int_0^l f(x) \sin\left(\frac{(2n-1)\pi}{2l}x\right) dx \right) \sin\left(\frac{(2n-1)\pi}{2l}x\right)$$

is the "best" approximation for $f(x)$ in $C^0[0, l]$ in terms of the eigenvectors of L . $m_\infty(x)$ is called the

Fourier quarter-wave sine series of $f(x)$.

If time permits:

- * Example 5.7 pg 146
- * Exercise 3 pg 147