

CAAM 336 · DIFFERENTIAL EQUATIONS

Fall 2013 Examination 1

1. [25 points]

Let the operator $L : C^2[0, 1] \rightarrow C[0, 1]$ be defined by

$$Lv = -v'' + 9v.$$

Let $u \in C^2[0, 1]$ be the solution to the differential equation

$$-u''(x) + 9u(x) = f(x), \quad 0 < x < 1$$

with boundary conditions

$$u(0) = \alpha$$

and

$$u(1) = \beta$$

where $f \in C[0, 1]$ and $\alpha, \beta \in \mathbb{R}$. Note that

$$(Lu)(x) = -u''(x) + 9u(x)$$

for all $x \in [0, 1]$. Let N be an integer which is such that $N \geq 2$ and let $h = \frac{1}{N+1}$ and $x_j = jh$ for $j = 0, \dots, N+1$.

(a) Determine whether or not L is a linear operator.

(b) By using the approximation

$$u''(x_j) \approx \frac{u(x_{j-1}) - 2u(x_j) + u(x_{j+1}))}{h^2}$$

for $j = 1, \dots, N$ we can write

$$\begin{bmatrix} (Lu)(x_1) \\ (Lu)(x_2) \\ \vdots \\ (Lu)(x_{N-1}) \\ (Lu)(x_N) \end{bmatrix} \approx \mathbf{D} \begin{bmatrix} u(x_0) \\ u(x_1) \\ u(x_2) \\ \vdots \\ u(x_{N-1}) \\ u(x_N) \\ u(x_{N+1}) \end{bmatrix}$$

where $\mathbf{D} \in \mathbb{R}^{N \times (N+2)}$. What are the entries of the matrix \mathbf{D} ? An acceptable way to present your final answer is

$$D_{jk} = \begin{cases} ? & \text{if } k = ?; \\ ? & \text{if } k = ? \text{ or } k = ?; \\ ? & \text{otherwise;} \end{cases}$$

with the question marks replaced with the correct values.

- (c) We can use the differential equation and boundary conditions satisfied by u and the approximation from the previous part to write

$$\mathbf{A} \begin{bmatrix} u(x_1) \\ u(x_2) \\ \vdots \\ u(x_{N-1}) \\ u(x_N) \end{bmatrix} \approx \mathbf{b}$$

where $\mathbf{A} \in \mathbb{R}^{N \times N}$ and $\mathbf{b} \in \mathbb{R}^N$. What are the entries of the matrix \mathbf{A} and the vector \mathbf{b} ? An acceptable way to present your final answer is

$$A_{jk} = \begin{cases} ? & \text{if } k = ?; \\ ? & \text{if } k = ? \text{ or } k = ?; \\ ? & \text{otherwise;} \end{cases}$$

and

$$b_j = \begin{cases} ? & \text{if } j = ?; \\ ? & \text{if } j = ?; \\ ? & \text{otherwise;} \end{cases}$$

with the question marks replaced with the correct values.

- (d) Let $f(x) = 18$, $\alpha = \beta = 0$ and $N = 2$. Obtain approximations u_1 and u_2 to $u(x_1)$ and $u(x_2)$, respectively, by solving

$$\mathbf{A} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \mathbf{b}.$$

Solution.

- (a) [5 points] If $v \in C^2[0, 1]$ and $w \in C^2[0, 1]$ then

$$L(v+w) = -(v+w)'' + 9(v+w) = -v'' - w'' + 9v + 9w = -v'' + 9v - w'' + 9w = Lv + Lw$$

and so $L(v+w) = Lv + Lw$ for all $v, w \in C^2[0, 1]$. If $v \in C^2[0, 1]$ and $\gamma \in \mathbb{R}$ then

$$L(\gamma v) = -(\gamma v)'' + 9(\gamma v) = -\gamma v'' + 9\gamma v = \gamma(-v'' + 9v) = \gamma Lv$$

and so $L(\gamma v) = \gamma Lv$ for all $v \in C^2[0, 1]$ and all $\gamma \in \mathbb{R}$. Consequently, L is a linear operator.

- (b) [5 points] For $j = 1, 2, \dots, N$, using the approximation

$$u''(x_j) \approx \frac{u(x_{j-1}) - 2u(x_j) + u(x_{j+1}))}{h^2}$$

yields that

$$\begin{aligned} (Lu)(x_j) &= -u''(x_j) + 9u(x_j) \approx -\frac{u(x_{j-1}) - 2u(x_j) + u(x_{j+1}))}{h^2} + 9u(x_j) \\ &= -\frac{1}{h^2}u(x_{j-1}) + \left(\frac{2}{h^2} + 9\right)u(x_j) - \frac{1}{h^2}u(x_{j+1}). \end{aligned}$$

So,

$$\begin{aligned}
& \begin{bmatrix} (Lu)(x_1) \\ (Lu)(x_2) \\ \vdots \\ (Lu)(x_{N-1}) \\ (Lu)(x_N) \end{bmatrix} \\
& \approx \begin{bmatrix} -\frac{1}{h^2}u(x_0) + \left(\frac{2}{h^2} + 9\right)u(x_1) - \frac{1}{h^2}u(x_2) \\ -\frac{1}{h^2}u(x_1) + \left(\frac{2}{h^2} + 9\right)u(x_2) - \frac{1}{h^2}u(x_3) \\ \vdots \\ -\frac{1}{h^2}u(x_{N-2}) + \left(\frac{2}{h^2} + 9\right)u(x_{N-1}) - \frac{1}{h^2}u(x_N) \\ -\frac{1}{h^2}u(x_{N-1}) + \left(\frac{2}{h^2} + 9\right)u(x_N) - \frac{1}{h^2}u(x_{N+1}) \end{bmatrix} \\
& = \begin{bmatrix} -\frac{1}{h^2} & \frac{2}{h^2} + 9 & -\frac{1}{h^2} & 0 & 0 & \cdots & 0 & 0 & 0 \\ 0 & -\frac{1}{h^2} & \frac{2}{h^2} + 9 & -\frac{1}{h^2} & 0 & \cdots & 0 & 0 & 0 \\ 0 & 0 & -\frac{1}{h^2} & \frac{2}{h^2} + 9 & -\frac{1}{h^2} & \cdots & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \ddots & \ddots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & -\frac{1}{h^2} & \frac{2}{h^2} + 9 & -\frac{1}{h^2} & 0 & 0 \\ 0 & 0 & 0 & \cdots & 0 & -\frac{1}{h^2} & \frac{2}{h^2} + 9 & -\frac{1}{h^2} & 0 \\ 0 & 0 & 0 & \cdots & 0 & 0 & -\frac{1}{h^2} & \frac{2}{h^2} + 9 & -\frac{1}{h^2} \end{bmatrix} \begin{bmatrix} u(x_0) \\ u(x_1) \\ u(x_2) \\ \vdots \\ u(x_{N-1}) \\ u(x_N) \\ u(x_{N+1}) \end{bmatrix} \\
& = \mathbf{D} \begin{bmatrix} u(x_0) \\ u(x_1) \\ u(x_2) \\ \vdots \\ u(x_{N-1}) \\ u(x_N) \\ u(x_{N+1}) \end{bmatrix}
\end{aligned}$$

where $\mathbf{D} \in \mathbb{R}^{N \times (N+2)}$ is the matrix with entries

$$D_{jk} = \begin{cases} \frac{2}{h^2} + 9 & \text{if } k = j + 1; \\ -\frac{1}{h^2} & \text{if } k = j \text{ or } k = j + 2; \\ 0 & \text{otherwise.} \end{cases}$$

(c) [10 points] Since

$$(Lu)(x) = f(x), \quad 0 < x < 1$$

we have that

$$\begin{bmatrix} (Lu)(x_1) \\ (Lu)(x_2) \\ \vdots \\ (Lu)(x_{N-1}) \\ (Lu)(x_N) \end{bmatrix} = \begin{bmatrix} f(x_1) \\ f(x_2) \\ \vdots \\ f(x_{N-1}) \\ f(x_N) \end{bmatrix}$$

for $j = 1, \dots, N$. Using the approximation obtained in the previous part then yields that

$$\mathbf{D} \begin{bmatrix} u(x_0) \\ u(x_1) \\ u(x_2) \\ \vdots \\ u(x_{N-1}) \\ u(x_N) \\ u(x_{N+1}) \end{bmatrix} \approx \begin{bmatrix} f(x_1) \\ f(x_2) \\ \vdots \\ f(x_{N-1}) \\ f(x_N) \end{bmatrix}$$

Moreover,

$$\begin{aligned} \mathbf{D} \begin{bmatrix} u(x_0) \\ u(x_1) \\ u(x_2) \\ \vdots \\ u(x_{N-1}) \\ u(x_N) \\ u(x_{N+1}) \end{bmatrix} &= \mathbf{D} \left(\begin{bmatrix} 0 \\ u(x_1) \\ u(x_2) \\ \vdots \\ u(x_{N-1}) \\ u(x_N) \\ 0 \end{bmatrix} + \begin{bmatrix} u(x_0) \\ 0 \\ 0 \\ \vdots \\ 0 \\ 0 \\ u(x_{N+1}) \end{bmatrix} \right) \\ &= \mathbf{D} \left(\begin{bmatrix} 0 \\ u(x_1) \\ u(x_2) \\ \vdots \\ u(x_{N-1}) \\ u(x_N) \\ 0 \end{bmatrix} + \begin{bmatrix} \alpha \\ 0 \\ 0 \\ \vdots \\ 0 \\ 0 \\ \beta \end{bmatrix} \right) \\ &= \mathbf{D} \begin{bmatrix} 0 \\ u(x_1) \\ u(x_2) \\ \vdots \\ u(x_{N-1}) \\ u(x_N) \\ 0 \end{bmatrix} + \mathbf{D} \begin{bmatrix} \alpha \\ 0 \\ 0 \\ \vdots \\ 0 \\ 0 \\ \beta \end{bmatrix} \end{aligned}$$

since $u(x_0) = u(0) = \alpha$ and $u(x_{N+1}) = u(1) = \beta$. Furthermore,

$$\begin{aligned}
& \mathbf{D} \begin{bmatrix} 0 \\ u(x_1) \\ u(x_2) \\ \vdots \\ u(x_{N-1}) \\ u(x_N) \\ 0 \end{bmatrix} \\
&= \begin{bmatrix} -\frac{1}{h^2} & \frac{2}{h^2} + 9 & -\frac{1}{h^2} & 0 & 0 & \cdots & 0 & 0 & 0 \\ 0 & -\frac{1}{h^2} & \frac{2}{h^2} + 9 & -\frac{1}{h^2} & 0 & \cdots & 0 & 0 & 0 \\ 0 & 0 & -\frac{1}{h^2} & \frac{2}{h^2} + 9 & -\frac{1}{h^2} & \cdots & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \ddots & \ddots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & -\frac{1}{h^2} & \frac{2}{h^2} + 9 & -\frac{1}{h^2} & 0 & 0 \\ 0 & 0 & 0 & \cdots & 0 & -\frac{1}{h^2} & \frac{2}{h^2} + 9 & -\frac{1}{h^2} & 0 \\ 0 & 0 & 0 & \cdots & 0 & 0 & -\frac{1}{h^2} & \frac{2}{h^2} + 9 & -\frac{1}{h^2} \end{bmatrix} \begin{bmatrix} 0 \\ u(x_1) \\ u(x_2) \\ \vdots \\ u(x_{N-1}) \\ u(x_N) \\ 0 \end{bmatrix} \\
&= \begin{bmatrix} \frac{2}{h^2} + 9 & -\frac{1}{h^2} & 0 & 0 & \cdots & 0 & 0 \\ -\frac{1}{h^2} & \frac{2}{h^2} + 9 & -\frac{1}{h^2} & 0 & \cdots & 0 & 0 \\ 0 & -\frac{1}{h^2} & \frac{2}{h^2} + 9 & -\frac{1}{h^2} & \cdots & 0 & 0 \\ \vdots & \vdots & \ddots & \ddots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & -\frac{1}{h^2} & \frac{2}{h^2} + 9 & -\frac{1}{h^2} & 0 \\ 0 & 0 & \cdots & 0 & -\frac{1}{h^2} & \frac{2}{h^2} + 9 & -\frac{1}{h^2} \\ 0 & 0 & \cdots & 0 & 0 & -\frac{1}{h^2} & \frac{2}{h^2} + 9 \end{bmatrix} \begin{bmatrix} u(x_1) \\ u(x_2) \\ \vdots \\ u(x_{N-1}) \\ u(x_N) \end{bmatrix}
\end{aligned}$$

and so

$$\mathbf{A} \begin{bmatrix} u(x_1) \\ u(x_2) \\ \vdots \\ u(x_{N-1}) \\ u(x_N) \end{bmatrix} \approx \mathbf{b}$$

where $\mathbf{A} \in \mathbb{R}^{N \times N}$ is the matrix with entries

$$A_{jk} = \begin{cases} \frac{2}{h^2} + 9 & \text{if } k = j; \\ -\frac{1}{h^2} & \text{if } k = j - 1 \text{ or } k = j + 1; \\ 0 & \text{otherwise.} \end{cases}$$

and

$$\mathbf{b} = \begin{bmatrix} f(x_1) \\ f(x_2) \\ \vdots \\ f(x_{N-1}) \\ f(x_N) \end{bmatrix} - \mathbf{D} \begin{bmatrix} \alpha \\ 0 \\ 0 \\ \vdots \\ 0 \\ 0 \\ \beta \end{bmatrix}.$$

Now,

$$\begin{aligned}
& \mathbf{D} \begin{bmatrix} \alpha \\ 0 \\ 0 \\ \vdots \\ 0 \\ 0 \\ \beta \end{bmatrix} \\
&= \begin{bmatrix} -\frac{1}{h^2} & \frac{2}{h^2} + 9 & -\frac{1}{h^2} & 0 & 0 & \cdots & 0 & 0 & 0 \\ 0 & -\frac{1}{h^2} & \frac{2}{h^2} + 9 & -\frac{1}{h^2} & 0 & \cdots & 0 & 0 & 0 \\ 0 & 0 & -\frac{1}{h^2} & \frac{2}{h^2} + 9 & -\frac{1}{h^2} & \cdots & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \ddots & \ddots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & -\frac{1}{h^2} & \frac{2}{h^2} + 9 & -\frac{1}{h^2} & 0 & 0 \\ 0 & 0 & 0 & \cdots & 0 & -\frac{1}{h^2} & \frac{2}{h^2} + 9 & -\frac{1}{h^2} & 0 \\ 0 & 0 & 0 & \cdots & 0 & 0 & -\frac{1}{h^2} & \frac{2}{h^2} + 9 & -\frac{1}{h^2} \end{bmatrix} \begin{bmatrix} \alpha \\ 0 \\ 0 \\ \vdots \\ 0 \\ 0 \\ \beta \end{bmatrix} \\
&= \begin{bmatrix} -\frac{\alpha}{h^2} \\ 0 \\ 0 \\ \vdots \\ 0 \\ 0 \\ -\frac{\beta}{h^2} \end{bmatrix}
\end{aligned}$$

and so

$$\mathbf{b} = \begin{bmatrix} f(x_1) \\ f(x_2) \\ \vdots \\ f(x_{N-1}) \\ f(x_N) \end{bmatrix} - \begin{bmatrix} -\frac{\alpha}{h^2} \\ 0 \\ 0 \\ \vdots \\ 0 \\ 0 \\ -\frac{\beta}{h^2} \end{bmatrix} = \begin{bmatrix} f(x_1) + \frac{\alpha}{h^2} \\ f(x_2) \\ \vdots \\ f(x_{N-1}) \\ f(x_N) + \frac{\beta}{h^2} \end{bmatrix}.$$

Hence $\mathbf{b} \in \mathbb{R}^N$ is the vector with entries

$$b_j = \begin{cases} f(x_1) + \frac{\alpha}{h^2} & \text{if } j = 1; \\ f(x_N) + \frac{\beta}{h^2} & \text{if } j = N; \\ f(x_j) & \text{otherwise.} \end{cases}$$

- (d) [5 points] When $N = 2$, $h = \frac{1}{2+1} = \frac{1}{3}$ and so $h^2 = \frac{1}{3^2} = \frac{1}{9}$ and hence $\frac{1}{h^2} = 9$ and $\frac{2}{h^2} = 18$. Therefore,

$$\mathbf{A} = \begin{bmatrix} 18 + 9 & -9 \\ -9 & 18 + 9 \end{bmatrix} = \begin{bmatrix} 27 & -9 \\ -9 & 27 \end{bmatrix}.$$

Moreover, when $N = 2$, $f(x) = 18$ and $\alpha = \beta = 0$,

$$\mathbf{b} = \begin{bmatrix} 18 \\ 18 \end{bmatrix}.$$

Consequently, we have that

$$\begin{bmatrix} 27 & -9 \\ -9 & 27 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} 18 \\ 18 \end{bmatrix}$$

and hence

$$\begin{bmatrix} 3 & -1 \\ -1 & 3 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \end{bmatrix}.$$

Therefore,

$$\begin{aligned} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} &= \begin{bmatrix} 3 & -1 \\ -1 & 3 \end{bmatrix}^{-1} \begin{bmatrix} 2 \\ 2 \end{bmatrix} \\ &= \frac{1}{9-1} \begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 2 \\ 2 \end{bmatrix} \\ &= \frac{1}{8} \begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 2 \\ 2 \end{bmatrix} \\ &= \frac{1}{8} \begin{bmatrix} 6+2 \\ 2+6 \end{bmatrix} \\ &= \frac{1}{8} \begin{bmatrix} 8 \\ 8 \end{bmatrix} \\ &= \begin{bmatrix} 1 \\ 1 \end{bmatrix}. \end{aligned}$$

2. [25 points]

(a) Compute

$$\int_{-1}^1 x \, dx.$$

(b) Let

$$\mathbf{A} = \begin{bmatrix} 4 & 1 \\ 1 & 4 \end{bmatrix}$$

and

$$\mathbf{g} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}.$$

Use the spectral method to obtain the solution $\mathbf{c} \in \mathbb{R}^2$ to

$$\mathbf{A}\mathbf{c} = \mathbf{g}.$$

(c) Let

$$V_0 = \left\{ w \in C^1[0, 1] : \int_0^1 w(x) \, dx = 0 \right\}.$$

Determine whether or not V_0 is a subspace of $C^1[0, 1]$.

(d) Let $(\cdot, \cdot) : C[-1, 1] \times C[-1, 1] \rightarrow \mathbb{R}$ be defined by

$$(u, v) = \int_{-1}^1 xu(x)v(x) dx.$$

Determine whether or not (\cdot, \cdot) is an inner product on $C[-1, 1]$.

(e) Let $a, b \in \mathbb{R}$ be such that $a < b$. Let $\phi \in C[a, b]$ be defined by $\phi(x) = 1$ and let the inner product $B(\cdot, \cdot) : C[a, b] \times C[a, b] \rightarrow \mathbb{R}$ be defined by

$$B(u, v) = \int_a^b u(x)v(x) dx.$$

Let the linear operator $P_0 : C[a, b] \rightarrow C[a, b]$ be defined by

$$P_0 f = \frac{1}{b-a} B(f, \phi).$$

Determine whether or not P_0 is a projection.

Solution.

(a) [1 point] We can compute that

$$\int_{-1}^1 x dx = \left[\frac{1}{2} x^2 \right]_{-1}^1 = \frac{1}{2} (1^2 - (-1)^2) = \frac{1}{2} (1 - 1) = 0.$$

(b) [6 points] Since,

$$\lambda \mathbf{I} - \mathbf{A} = \begin{bmatrix} \lambda - 4 & -1 \\ -1 & \lambda - 4 \end{bmatrix}$$

we have that

$$\det(\lambda \mathbf{I} - \mathbf{A}) = (\lambda - 4)^2 - 1 = \lambda^2 - 8\lambda + 15 = (\lambda - 3)(\lambda - 5)$$

and so

$$\det(\lambda \mathbf{I} - \mathbf{A}) = 0$$

when $\lambda = 3$ or $\lambda = 5$. Hence, the eigenvalues of \mathbf{A} are

$$\lambda_1 = 3$$

and

$$\lambda_2 = 5.$$

Moreover,

$$(\lambda_1 \mathbf{I} - \mathbf{A}) \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} -1 & -1 \\ -1 & -1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} -c_1 - c_2 \\ -c_1 - c_2 \end{bmatrix}$$

and so to make this vector zero we need to set $c_2 = -c_1$. Hence, any vector of the form

$$\begin{bmatrix} c_1 \\ -c_1 \end{bmatrix}$$

where c_1 is a nonzero constant is an eigenvector of \mathbf{A} corresponding to the eigenvalue λ_1 . Let us choose

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}.$$

Furthermore,

$$(\lambda_2 \mathbf{I} - \mathbf{A}) \begin{bmatrix} d_1 \\ d_2 \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} d_1 \\ d_2 \end{bmatrix} = \begin{bmatrix} d_1 - d_2 \\ -d_1 + d_2 \end{bmatrix}$$

and so to make this vector zero we need to set $d_2 = d_1$. Hence, any vector of the form

$$\begin{bmatrix} d_1 \\ d_1 \end{bmatrix}$$

where d_1 is a nonzero constant is an eigenvector of \mathbf{A} corresponding to the eigenvalue λ_2 . Let us choose

$$\mathbf{v}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}.$$

Since $\mathbf{A} = \mathbf{A}^T$, $\mathbf{A}\mathbf{v}_1 = \lambda_1\mathbf{v}_1$, $\mathbf{A}\mathbf{v}_2 = \lambda_2\mathbf{v}_2$ and $\lambda_1 \neq \lambda_2$, $\mathbf{v}_1 \cdot \mathbf{v}_2 = 0$. Now,

$$\mathbf{g} \cdot \mathbf{v}_1 = 2 - 3 = -1,$$

$$\mathbf{v}_1 \cdot \mathbf{v}_1 = 1^2 + (-1)^2 = 1 + 1 = 2,$$

$$\mathbf{g} \cdot \mathbf{v}_1 = 2 + 3 = 5,$$

and

$$\mathbf{v}_2 \cdot \mathbf{v}_2 = 1^2 + 1^2 = 1 + 1 = 2.$$

The spectral method then yields that

$$\begin{aligned} \mathbf{x} &= \frac{1}{\lambda_1} \frac{\mathbf{g} \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 + \frac{1}{\lambda_2} \frac{\mathbf{g} \cdot \mathbf{v}_2}{\mathbf{v}_2 \cdot \mathbf{v}_2} \mathbf{v}_2 \\ &= \frac{1}{3} \frac{-1}{2} \begin{bmatrix} 1 \\ -1 \end{bmatrix} + \frac{1}{5} \frac{5}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix} \\ &= \begin{bmatrix} -\frac{1}{6} \\ \frac{1}{6} \end{bmatrix} + \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \end{bmatrix} \\ &= \begin{bmatrix} -\frac{1}{6} + \frac{3}{6} \\ \frac{1}{6} + \frac{3}{6} \end{bmatrix} \\ &= \begin{bmatrix} \frac{2}{6} \\ \frac{4}{6} \end{bmatrix} \\ &= \begin{bmatrix} \frac{1}{3} \\ \frac{2}{3} \end{bmatrix}. \end{aligned}$$

- (c) [10 points] The set V_0 is a subset of $C^1[0, 1]$ and the function z defined by $z(x) = 0$ for $x \in [0, 1]$ is such that $z \in V_0$ since

$$\int_0^1 z(x) dx = \int_0^1 0 dx = 0.$$

If $f \in V_0$ and $g \in V_0$, then $\int_0^1 f(x) dx = \int_0^1 g(x) dx = 0$, and so

$$\int_0^1 (f + g)(x) dx = \int_0^1 f(x) + g(x) dx = \int_0^1 f(x) dx + \int_0^1 g(x) dx = 0 + 0 = 0$$

and hence $f + g \in V_0$ for all $f, g \in V_0$. Also, if $f \in V_0$ and $\alpha \in \mathbb{R}$, then $\int_0^1 f(x) dx = 0$, and so

$$\int_0^1 (\alpha f)(x) dx = \int_0^1 \alpha f(x) dx = \alpha \int_0^1 f(x) dx = 0$$

and hence $\alpha f \in V_0$ for all $f \in V_0$ and all $\alpha \in \mathbb{R}$. Consequently, V_0 is a subspace of $C^1[0, 1]$.

- (d) [3 points] The mapping (\cdot, \cdot) is not an inner product on $C[-1, 1]$ since if $w(x) = 1$ for all $x \in [-1, 1]$ then $w \in C[-1, 1]$ and $w \neq 0$ but

$$(w, w) = \int_{-1}^1 xw(x)w(x) dx = \int_{-1}^1 x dx = 0$$

and so (\cdot, \cdot) is not positive definite.

- (e) [5 points] If $f \in C[a, b]$ then

$$P_0 f = \frac{1}{b-a} B(f, \phi)$$

and so

$$\begin{aligned} P_0(P_0 f) &= \frac{1}{b-a} B(P_0 f, \phi) \\ &= \frac{1}{b-a} \int_a^b \frac{1}{b-a} B(f, \phi) dx \\ &= \frac{1}{b-a} B(f, \phi) \int_a^b \frac{1}{b-a} dx \\ &= \frac{1}{b-a} B(f, \phi) \left[\frac{x}{b-a} \right]_a^b \\ &= \frac{1}{b-a} B(f, \phi) \left(\frac{b}{b-a} - \frac{a}{b-a} \right) \\ &= \frac{1}{b-a} B(f, \phi) \frac{b-a}{b-a} \\ &= \frac{1}{b-a} B(f, \phi) \\ &= P_0 f. \end{aligned}$$

Hence, $P_0(P_0 f) = P_0 f$ for all $f \in C[a, b]$ and so P_0 is a projection.

3. [25 points]

Let the inner product $(\cdot, \cdot) : C[0, 1] \times C[0, 1] \rightarrow \mathbb{R}$ be defined by

$$(v, w) = \int_0^1 v(x)w(x) dx$$

and let the norm $\|\cdot\| : C[0, 1] \rightarrow \mathbb{R}$ be defined by

$$\|v\| = \sqrt{(v, v)}.$$

Let the linear operator $L : S \rightarrow C[0, 1]$ be defined by

$$Lv = -v''$$

where

$$S = \{w \in C^2[0, 1] : w'(0) = w(1) = 0\}.$$

Note that S is a subspace of $C[0, 1]$ and that

$$(Lv, w) = (v, Lw) \text{ for all } v, w \in S.$$

Let N be a positive integer and let $f \in C[0, 1]$ be defined by

$$f(x) = \begin{cases} 1 - 2x & \text{if } x \in [0, \frac{1}{2}]; \\ 0 & \text{otherwise.} \end{cases}$$

(a) The operator L has eigenvalues λ_n with corresponding eigenfunctions

$$\psi_n(x) = \sqrt{2} \cos\left(\frac{2n-1}{2}\pi x\right)$$

for $n = 1, 2, \dots$. Note that, for $m, n = 1, 2, \dots$,

$$(\psi_m, \psi_n) = \begin{cases} 1 & \text{if } m = n; \\ 0 & \text{if } m \neq n. \end{cases}$$

Obtain a formula for the eigenvalues λ_n for $n = 1, 2, \dots$.

(b) Compute the best approximation to f from $\text{span}\{\psi_1, \dots, \psi_N\}$ with respect to the norm $\|\cdot\|$.

(c) Use the spectral method to obtain a series solution to the problem of finding $\tilde{u} \in C^2[0, 1]$ such that

$$-\tilde{u}''(x) = f(x), \quad 0 < x < 1$$

and

$$\tilde{u}'(0) = \tilde{u}(1) = 0.$$

(d) What is the best approximation to \tilde{u} from $\text{span}\{\psi_1, \dots, \psi_N\}$ with respect to the norm $\|\cdot\|$?

(e) By shifting the data, obtain a series solution to the problem of finding $u \in C^2[0, 1]$ such that

$$-u''(x) = f(x), \quad 0 < x < 1$$

and

$$u'(0) = u(1) = 1.$$

Solution.

(a) [3 points] We can compute that, for $n = 1, 2, \dots$,

$$\psi'_n(x) = -\sqrt{2} \left(\frac{2n-1}{2} \right) \pi \sin \left(\frac{2n-1}{2} \pi x \right).$$

and

$$\psi''_n(x) = -\sqrt{2} \left(\frac{2n-1}{2} \right)^2 \pi^2 \cos \left(\frac{2n-1}{2} \pi x \right).$$

and so

$$L\psi_n = -\psi''_n = \left(\frac{2n-1}{2} \right)^2 \pi^2 \psi_n.$$

Hence,

$$\lambda_n = \left(\frac{2n-1}{2} \right)^2 \pi^2 = (2n-1)^2 \frac{\pi^2}{4} \text{ for } n = 1, 2, \dots$$

(b) [8 points] Since $\{\psi_1, \dots, \psi_N\}$ is orthonormal with respect to the inner product (\cdot, \cdot) , the best approximation to f from $\text{span}\{\psi_1, \dots, \psi_N\}$ with respect to the norm $\|\cdot\|$ is

$$f_N = \sum_{n=1}^N (f, \psi_n) \psi_n.$$

Now, for $n = 1, 2, \dots$,

$$\begin{aligned}
& (f, \psi_n) \\
&= \int_0^1 f(x) \psi_n(x) dx \\
&= \int_0^{1/2} f(x) \psi_n(x) dx + \int_{1/2}^1 f(x) \psi_n(x) dx \\
&= \int_0^{1/2} (1-2x) \sqrt{2} \cos\left(\frac{2n-1}{2}\pi x\right) dx + \int_{1/2}^1 0 dx \\
&= \sqrt{2} \int_0^{1/2} (1-2x) \cos\left(\frac{2n-1}{2}\pi x\right) dx + 0 \\
&= \sqrt{2} \left(\left[(1-2x) \frac{2}{(2n-1)\pi} \sin\left(\frac{2n-1}{2}\pi x\right) \right]_0^{1/2} - \int_0^{1/2} (-2) \frac{2}{(2n-1)\pi} \sin\left(\frac{2n-1}{2}\pi x\right) dx \right) \\
&= \sqrt{2} \left(0 - 0 + \frac{4}{(2n-1)\pi} \int_0^{1/2} \sin\left(\frac{2n-1}{2}\pi x\right) dx \right) \\
&= \sqrt{2} \frac{4}{(2n-1)\pi} \left[-\frac{2}{(2n-1)\pi} \cos\left(\frac{2n-1}{2}\pi x\right) \right]_0^{1/2} \\
&= \frac{4\sqrt{2}}{(2n-1)\pi} \left(-\frac{2}{(2n-1)\pi} \cos\left(\frac{2n-1}{4}\pi\right) - \left(-\frac{2}{(2n-1)\pi} \right) \right) \\
&= \frac{8\sqrt{2}}{(2n-1)^2 \pi^2} \left(1 - \cos\left(\frac{2n-1}{4}\pi\right) \right).
\end{aligned}$$

Hence,

$$\begin{aligned}
f_N(x) &= \sum_{n=1}^N (f, \psi_n) \psi_n(x) \\
&= \sum_{n=1}^N (f, \psi_n) \sqrt{2} \cos\left(\frac{2n-1}{2}\pi x\right) \\
&= \sum_{n=1}^N \frac{16}{(2n-1)^2 \pi^2} \left(1 - \cos\left(\frac{2n-1}{4}\pi\right) \right) \cos\left(\frac{2n-1}{2}\pi x\right).
\end{aligned}$$

- (c) [4 points] Now, \tilde{u} is the solution to $L\tilde{u} = f$ and so the spectral method yields the series solution

$$\tilde{u}(x) = \sum_{n=1}^{\infty} \frac{(f, \psi_n)}{\lambda_n} \psi_n(x) = \sum_{n=1}^{\infty} \frac{64}{(2n-1)^4 \pi^4} \left(1 - \cos\left(\frac{2n-1}{4}\pi\right) \right) \cos\left(\frac{2n-1}{2}\pi x\right).$$

- (d) [4 points] The best approximation to \tilde{u} from $\text{span}\{\psi_1, \dots, \psi_N\}$ with respect to the norm $\|\cdot\|$ is

$$\tilde{u}_N(x) = \sum_{n=1}^N \frac{(f, \psi_n)}{\lambda_n} \psi_n(x) = \sum_{n=1}^N \frac{64}{(2n-1)^4 \pi^4} \left(1 - \cos\left(\frac{2n-1}{4}\pi\right) \right) \cos\left(\frac{2n-1}{2}\pi x\right).$$

(e) [6 points] Let \tilde{u} be the solution to $L\tilde{u} = f$ and let $w \in C^2[0, 1]$ be such that

$$-w''(x) = 0, \quad 0 < x < 1$$

and

$$w'(0) = w(1) = 1.$$

Then $u(x) = w(x) + \tilde{u}(x)$ will be such that

$$-u''(x) = -w''(x) - \tilde{u}''(x) = 0 + f(x) = f(x);$$

$$u'(0) = w'(0) + \tilde{u}'(0) = 1 + 0 = 1;$$

and

$$u(1) = w(1) + \tilde{u}(1) = 1 + 0 = 1.$$

Now, the general solution to

$$-w''(x) = 0$$

is $w(x) = Ax + B$ where A and B are constants. Moreover, $w'(x) = A$ and so $w'(0) = 1$ when $A = 1$. Hence, $w(x) = x + B$ and so $w(1) = 1$ when $B = 0$. Consequently,

$$w(x) = x$$

and so

$$u(x) = x + \tilde{u}(x).$$

We can then use the series solution to $L\tilde{u} = f$ that we obtained in part (c) to obtain the series solution

$$u(x) = x + \sum_{n=1}^{\infty} \frac{64}{(2n-1)^4 \pi^4} \left(1 - \cos\left(\frac{2n-1}{4}\pi\right) \right) \cos\left(\frac{2n-1}{2}\pi x\right)$$

to the problem of finding $u \in C^2[0, 1]$ such that

$$-u''(x) = f(x), \quad 0 < x < 1;$$

$$u'(0) = u(1) = 1.$$

4. [25 points]

Let $\phi_1 \in C[-1, 1]$, $\phi_2 \in C[-1, 1]$, $f_1 \in C[-1, 1]$, and $f_2 \in C[-1, 1]$ be defined by

$$\phi_1(x) = \frac{1}{\sqrt{2}},$$

$$\phi_2(x) = \frac{\sqrt{3}}{\sqrt{2}}x,$$

$$f_1(x) = \sin(\pi x),$$

and

$$f_2(x) = \cos(\pi x),$$

for all $x \in [-1, 1]$. Note that $\{\phi_1, \phi_2\}$ is linearly independent. Let the inner product $(\cdot, \cdot) : C[-1, 1] \times C[-1, 1] \rightarrow \mathbb{R}$ be defined by

$$(u, v) = \int_{-1}^1 u(x)v(x) dx$$

and let the norm $\|\cdot\| : C[-1, 1] \rightarrow \mathbb{R}$ be defined by

$$\|u\| = \sqrt{(u, u)}.$$

Note that $\{\phi_1, \phi_2\}$ is orthonormal with respect to the inner product (\cdot, \cdot) . Also, let $\psi_1 \in C[0, 1]$, $\psi_2 \in C[0, 1]$, $g_1 \in C[0, 1]$, and $g_2 \in C[0, 1]$ be defined by

$$\psi_1(x) = \frac{1}{\sqrt{2}},$$

$$\psi_2(x) = \frac{\sqrt{3}}{\sqrt{2}}x,$$

$$g_1(x) = \sin(\pi x),$$

and

$$g_2(x) = \cos(\pi x),$$

for all $x \in [0, 1]$. Note that $\{\psi_1, \psi_2\}$ is linearly independent. Let the inner product $B(\cdot, \cdot) : C[0, 1] \times C[0, 1] \rightarrow \mathbb{R}$ be defined by

$$B(u, v) = \int_0^1 u(x)v(x) dx$$

and let the norm $\|\cdot\|_B : C[0, 1] \rightarrow \mathbb{R}$ be defined by

$$\|u\|_B = \sqrt{B(u, u)}.$$

Note that

$$(f_1, \phi_2) = \frac{\sqrt{6}}{\pi},$$

$$B(g_1, \psi_1) = \frac{\sqrt{2}}{\pi},$$

$$B(g_1, \psi_2) = \frac{\sqrt{6}}{2\pi},$$

$$B(g_2, \psi_2) = -\frac{\sqrt{6}}{\pi^2},$$

and

$$(f_1, \phi_1) = (f_2, \phi_1) = (f_2, \phi_2) = B(g_2, \psi_1) = 0.$$

(a) Construct the best approximation to f_1 from $\text{span}\{\phi_1, \phi_2\}$ with respect to the norm $\|\cdot\|$.

- (b) Construct the best approximation to f_2 from $\text{span}\{\phi_1, \phi_2\}$ with respect to the norm $\|\cdot\|$.
- (c) Construct the best approximation to g_1 from $\text{span}\{\psi_1, \psi_2\}$ with respect to the norm $\|\cdot\|_B$.
- (d) Construct the best approximation to g_2 from $\text{span}\{\psi_1, \psi_2\}$ with respect to the norm $\|\cdot\|_B$.

Solution.

- (a) [5 points] Since $\{\phi_1, \phi_2\}$ is orthonormal with respect to the inner product (\cdot, \cdot) , the best approximation to f_1 from $\text{span}\{\phi_1, \phi_2\}$ with respect to the norm $\|\cdot\|$ is

$$\tilde{f}_1(x) = (f_1, \phi_1)\phi_1(x) + (f_1, \phi_2)\phi_2(x) = 0 + \frac{\sqrt{6}\sqrt{3}}{\pi\sqrt{2}}x = \frac{\sqrt{2}\sqrt{3}}{\pi}\frac{\sqrt{3}}{\sqrt{2}}x = \frac{\sqrt{9}}{\pi}x = \frac{3}{\pi}x.$$

- (b) [4 points] Since $\{\phi_1, \phi_2\}$ is orthonormal with respect to the inner product (\cdot, \cdot) , the best approximation to f_2 from $\text{span}\{\phi_1, \phi_2\}$ with respect to the norm $\|\cdot\|$ is

$$\tilde{f}_2(x) = (f_2, \phi_1)\phi_1(x) + (f_2, \phi_2)\phi_2(x) = 0 + 0 = 0.$$

- (c) [10 points] Now,

$$B(\psi_1, \psi_2) = \int_0^1 \psi_1(x)\psi_2(x) dx = \int_0^1 \frac{1}{\sqrt{2}}\frac{\sqrt{3}}{\sqrt{2}}x dx = \frac{\sqrt{3}}{2} \int_0^1 x dx = \frac{\sqrt{3}}{2} \left[\frac{1}{2}x^2 \right]_0^1 = \frac{\sqrt{3}}{2} \frac{1}{2} = \frac{\sqrt{3}}{4}$$

and so $\{\psi_1, \psi_2\}$ is not orthogonal with respect to the inner product $B(\cdot, \cdot)$. Consequently, the best approximation to g_1 from $\text{span}\{\psi_1, \psi_2\}$ with respect to the norm $\|\cdot\|_B$ is

$$\tilde{g}_1(x) = c_1\psi_1(x) + c_2\psi_2(x)$$

where the coefficients $c_1, c_2 \in \mathbb{R}$ are such that

$$\mathbf{G} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} B(g_1, \psi_1) \\ B(g_1, \psi_2) \end{bmatrix} = \begin{bmatrix} \frac{\sqrt{2}}{\pi} \\ \frac{\sqrt{6}}{2\pi} \end{bmatrix}$$

where

$$\mathbf{G} = \begin{bmatrix} B(\psi_1, \psi_1) & B(\psi_1, \psi_2) \\ B(\psi_1, \psi_2) & B(\psi_2, \psi_2) \end{bmatrix}.$$

Now,

$$B(\psi_1, \psi_1) = \int_0^1 \psi_1(x)\psi_1(x) dx = \int_0^1 \frac{1}{\sqrt{2}}\frac{1}{\sqrt{2}} dx = \frac{1}{2} \int_0^1 1 dx = \frac{1}{2} [x]_0^1 = \frac{1}{2}$$

and

$$B(\psi_2, \psi_2) = \int_0^1 \psi_2(x)\psi_2(x) dx = \int_0^1 \frac{\sqrt{3}}{\sqrt{2}}x\frac{\sqrt{3}}{\sqrt{2}}x dx = \frac{3}{2} \int_0^1 x^2 dx = \frac{3}{2} \left[\frac{1}{3}x^3 \right]_0^1 = \frac{3}{2} \frac{1}{3} = \frac{1}{2}.$$

Hence,

$$\mathbf{G} = \begin{bmatrix} \frac{1}{2} & \frac{\sqrt{3}}{4} \\ \frac{\sqrt{3}}{4} & \frac{1}{2} \end{bmatrix}$$

and so

$$\mathbf{G}^{-1} = 16 \begin{bmatrix} \frac{1}{2} & -\frac{\sqrt{3}}{4} \\ -\frac{\sqrt{3}}{4} & \frac{1}{2} \end{bmatrix} = \begin{bmatrix} 8 & -4\sqrt{3} \\ -4\sqrt{3} & 8 \end{bmatrix}$$

since

$$\frac{1}{2} \frac{1}{2} - \frac{\sqrt{3}}{4} \frac{\sqrt{3}}{4} = \frac{1}{4} - \frac{3}{16} = \frac{4}{16} - \frac{3}{16} = \frac{1}{16}.$$

Therefore

$$\begin{aligned} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} &= \mathbf{G}^{-1} \begin{bmatrix} \frac{\sqrt{2}}{\pi} \\ \frac{\sqrt{6}}{2\pi} \end{bmatrix} \\ &= \begin{bmatrix} 8 & -4\sqrt{3} \\ -4\sqrt{3} & 8 \end{bmatrix} \begin{bmatrix} \frac{\sqrt{2}}{\pi} \\ \frac{\sqrt{6}}{2\pi} \end{bmatrix} \\ &= \begin{bmatrix} 8\frac{\sqrt{2}}{\pi} - 4\sqrt{3}\frac{\sqrt{6}}{2\pi} \\ -4\sqrt{3}\frac{\sqrt{2}}{\pi} + 8\frac{\sqrt{6}}{2\pi} \end{bmatrix} \\ &= \begin{bmatrix} \frac{8\sqrt{2}}{\pi} - \frac{2\sqrt{18}}{\pi} \\ \frac{4\sqrt{6}}{\pi} + \frac{4\sqrt{6}}{\pi} \end{bmatrix} \\ &= \begin{bmatrix} \frac{8\sqrt{2}}{\pi} - \frac{2\sqrt{2}\sqrt{9}}{\pi} \\ \frac{4\sqrt{6}}{\pi} + \frac{4\sqrt{6}}{\pi} \end{bmatrix} \\ &= \begin{bmatrix} \frac{8\sqrt{2}}{\pi} - \frac{6\sqrt{2}}{\pi} \\ \frac{4\sqrt{6}}{\pi} + \frac{4\sqrt{6}}{\pi} \end{bmatrix} \\ &= \begin{bmatrix} \frac{2\sqrt{2}}{\pi} \\ 0 \end{bmatrix}. \end{aligned}$$

Consequently, the best approximation to g_1 from $\text{span}\{\psi_1, \psi_2\}$ with respect to the norm $\|\cdot\|_B$ is

$$\tilde{g}_1(x) = c_1\psi_1(x) + c_2\psi_2(x) = \frac{2\sqrt{2}}{\pi} \frac{1}{\sqrt{2}} + 0 = \frac{2}{\pi}.$$

- (d) [6 points] Since $B(\psi_1, \psi_2) \neq 0$, the best approximation to g_2 from $\text{span}\{\psi_1, \psi_2\}$ with respect to the norm $\|\cdot\|_B$ is

$$\tilde{g}_2(x) = d_1\psi_1(x) + d_2\psi_2(x)$$

where the coefficients $d_1, d_2 \in \mathbb{R}$ are such that

$$\mathbf{G} \begin{bmatrix} d_1 \\ d_2 \end{bmatrix} = \begin{bmatrix} B(g_2, \psi_1) \\ B(g_2, \psi_2) \end{bmatrix} = \begin{bmatrix} 0 \\ -\frac{\sqrt{6}}{\pi^2} \end{bmatrix}$$

where

$$\mathbf{G} = \begin{bmatrix} B(\psi_1, \psi_1) & B(\psi_1, \psi_2) \\ B(\psi_1, \psi_2) & B(\psi_2, \psi_2) \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{\sqrt{3}}{4} \\ \frac{\sqrt{3}}{4} & \frac{1}{2} \end{bmatrix}.$$

Therefore

$$\begin{aligned} \begin{bmatrix} d_1 \\ d_2 \end{bmatrix} &= \mathbf{G}^{-1} \begin{bmatrix} 0 \\ -\frac{\sqrt{6}}{\pi^2} \end{bmatrix} \\ &= \begin{bmatrix} 8 & -4\sqrt{3} \\ -4\sqrt{3} & 8 \end{bmatrix} \begin{bmatrix} 0 \\ -\frac{\sqrt{6}}{\pi^2} \end{bmatrix} \\ &= \begin{bmatrix} 4\sqrt{3}\frac{\sqrt{6}}{\pi^2} \\ -8\frac{\sqrt{6}}{\pi^2} \end{bmatrix} \\ &= \begin{bmatrix} 4\frac{\sqrt{18}}{\pi^2} \\ -8\frac{\sqrt{6}}{\pi^2} \end{bmatrix} \\ &= \begin{bmatrix} 4\frac{\sqrt{2}\sqrt{9}}{\pi^2} \\ -8\frac{\sqrt{2}\sqrt{3}}{\pi^2} \end{bmatrix} \\ &= \begin{bmatrix} 12\frac{\sqrt{2}}{\pi^2} \\ -8\frac{\sqrt{2}\sqrt{3}}{\pi^2} \end{bmatrix} \end{aligned}$$

Consequently, the best approximation to g_2 from $\text{span}\{\psi_1, \psi_2\}$ with respect to the norm $\|\cdot\|_B$ is

$$\tilde{g}_2(x) = d_1\psi_1(x) + d_2\psi_2(x) = 12\frac{\sqrt{2}}{\pi^2}\frac{1}{\sqrt{2}} - 8\frac{\sqrt{2}\sqrt{3}}{\pi^2}\frac{\sqrt{3}}{\sqrt{2}}x = \frac{12}{\pi^2} - \frac{24}{\pi^2}x = \frac{12}{\pi^2}(1 - 2x).$$
