CAAM 336 · DIFFERENTIAL EQUATIONS

Homework 47 · Solutions

Posted Wednesday 20 November 2013. Due 5pm Wednesday 4 December 2013.

47. [25 points] Let the norm $\|\cdot\|: \mathbb{R}^2 \to \mathbb{R}$ be defined by

$$\|\mathbf{y}\| = \sqrt{\mathbf{y} \cdot \mathbf{y}}.$$

Let the timestep $\Delta t \in \mathbb{R}$ be such that $\Delta t > 0$ and let $t_k = k\Delta t$ for $k = 0, 1, 2, \ldots$ Let

$$\mathbf{A} = \left[\begin{array}{cc} 0 & 1 \\ -1 & 0 \end{array} \right]$$

and consider the problem of finding $\mathbf{x}(t)$ such that

$$\mathbf{x}'(t) = \mathbf{A}\mathbf{x}(t), \quad t \ge 0$$

and

$$\mathbf{x}(0) = \left[\begin{array}{c} 1 \\ 1 \end{array} \right].$$

(a) Compute $\mathbf{x}(t)$. Note that for real numbers t,

$$e^{it} = \cos(t) + i\sin(t)$$

and

$$e^{-it} = \cos(t) - i\sin(t).$$

- (b) How does $\|\mathbf{x}(t)\|$ behave as t increases?
- (c) For k = 0, 1, 2, ..., let \mathbf{x}_k be the approximation to $\mathbf{x}(t_k)$ obtained using the forward Euler method. For all choices of the timestep $\Delta t > 0$, how will $\|\mathbf{x}_k\|$ behave as $k \to \infty$?
- (d) For k = 0, 1, 2, ..., let \mathbf{x}_k be the approximation to $\mathbf{x}(t_k)$ obtained using the backward Euler method. For all choices of the timestep $\Delta t > 0$, how will $\|\mathbf{x}_k\|$ behave as $k \to \infty$?

Solution.

(a) [10 points] The matrix **A** has eigenvalues $\lambda_1 = -i$ and $\lambda_2 = i$ and eigenvectors

$$\mathbf{v}_1 = \left[\begin{array}{c} \frac{1}{\sqrt{2}} \\ -\frac{i}{\sqrt{2}} \end{array} \right]$$

and

$$\mathbf{v}_2 = \left[egin{array}{c} rac{1}{\sqrt{2}} \ rac{i}{\sqrt{2}} \end{array}
ight]$$

which are such that $\mathbf{A}\mathbf{v}_1 = \lambda_1\mathbf{v}_1$ and $\mathbf{A}\mathbf{v}_2 = \lambda_2\mathbf{v}_2$. If we set

$$\mathbf{V} = [\mathbf{v}_1 \ \mathbf{v}_2] = \left[egin{array}{ccc} rac{1}{\sqrt{2}} & rac{1}{\sqrt{2}} \ -rac{i}{\sqrt{2}} & rac{i}{\sqrt{2}} \end{array}
ight]$$

and

$$oldsymbol{\Lambda} = \left[egin{array}{cc} \lambda_1 & 0 \\ 0 & \lambda_2 \end{array}
ight] = \left[egin{array}{cc} -i & 0 \\ 0 & i \end{array}
ight]$$

then we have that

$$\mathbf{A} = \mathbf{V} \mathbf{\Lambda} \mathbf{V}^{-1}$$

and

$$e^{t\mathbf{A}} = \mathbf{V}e^{t\mathbf{\Lambda}}\mathbf{V}^{-1}$$

$$= \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{i}{\sqrt{2}} & \frac{i}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} e^{-it} & 0 \\ 0 & e^{it} \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{i}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{i}{\sqrt{2}} \end{bmatrix}$$

$$= \begin{bmatrix} \frac{1}{2} \left(e^{it} + e^{-it} \right) & \frac{i}{2} \left(e^{-it} - e^{it} \right) \\ \frac{i}{2} \left(e^{it} - e^{-it} \right) & \frac{1}{2} \left(e^{it} + e^{-it} \right) \end{bmatrix}.$$

Now,

$$e^{it} + e^{-it} = \cos(t) + i\sin(t) + \cos(t) - i\sin(t) = 2\cos(t),$$

$$i(e^{it} - e^{-it}) = i(\cos(t) + i\sin(t) - (\cos(t) - i\sin(t)))$$

$$= i(\cos(t) + i\sin(t) - \cos(t) + i\sin(t))$$

$$= 2i^2\sin(t)$$

$$= -2\sin(t)$$

and

$$i(e^{-it} - e^{it}) = -i(e^{it} - e^{-it}) = 2\sin(t).$$

Therefore,

$$e^{t\mathbf{A}} = \begin{bmatrix} \cos(t) & \sin(t) \\ -\sin(t) & \cos(t) \end{bmatrix}.$$

Hence,

$$\mathbf{x}(t) = e^{t\mathbf{A}} \mathbf{x}_0 = \begin{bmatrix} \cos(t) & \sin(t) \\ -\sin(t) & \cos(t) \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} \cos(t) + \sin(t) \\ \cos(t) - \sin(t) \end{bmatrix}.$$

(b) [5 points] We can compute that, for each $t \in \mathbb{R}$,

$$\|\mathbf{x}(t)\|^{2} = (\cos(t) + \sin(t))^{2} + (\cos(t) - \sin(t))^{2}$$

$$= (\cos(t))^{2} + 2\cos(t)\sin(t) + (\sin(t))^{2} + (\cos(t))^{2} - 2\cos(t)\sin(t) + (\sin(t))^{2}$$

$$= 2\left((\cos(t))^{2} + (\sin(t))^{2}\right)$$

$$= 2.$$

Hence, for all $t \geq 0$,

$$\|\mathbf{x}(t)\| = \sqrt{2}$$

and so $\|\mathbf{x}(t)\|$ does not change as t increases.

(c) [5 points] Now,

$$\mathbf{x}_k = (\mathbf{I} + \Delta t \mathbf{A})^k \mathbf{x}_0.$$

Moreover, the eigenvalues of $\mathbf{I} + \Delta t \mathbf{A}$ are $1 + \Delta t \lambda_1 = 1 - \Delta t i$ and $1 + \Delta t \lambda_2 = 1 + \Delta t i$ and

$$\mathbf{I} + \Delta t \mathbf{A} = \mathbf{V} \begin{bmatrix} 1 - \Delta t i & 0 \\ 0 & 1 + \Delta t i \end{bmatrix} \mathbf{V}^{-1}.$$

Furthermore, for all choices of the timestep $\Delta t > 0$,

$$|1 - \Delta ti| = \sqrt{1 + (\Delta t)^2} > 1$$

and

$$|1 + \Delta ti| = \sqrt{1 + (\Delta t)^2} > 1.$$

Hence, for all choices of the timestep $\Delta t > 0$, $\|\mathbf{x}_k\| \to \infty$ as $k \to \infty$.

(d) [5 points] Now,

$$\mathbf{x}_k = ((\mathbf{I} - \Delta t \mathbf{A})^{-1})^k \mathbf{x}_0.$$

Moreover, the eigenvalues of $(\mathbf{I} - \Delta t \mathbf{A})^{-1}$ are $\frac{1}{1 - \Delta t \lambda_1} = \frac{1}{1 + \Delta t i}$ and $\frac{1}{1 - \Delta t \lambda_2} = \frac{1}{1 - \Delta t i}$ and

$$(\mathbf{I} - \Delta t \mathbf{A})^{-1} = \mathbf{V} \begin{bmatrix} \frac{1}{1 + \Delta t i} & 0 \\ 0 & \frac{1}{1 - \Delta t i} \end{bmatrix} \mathbf{V}^{-1}.$$

Furthermore, for all choices of the timestep $\Delta t > 0$,

$$\left| \frac{1}{1 + \Delta ti} \right| = \frac{|1|}{|1 + \Delta ti|} = \frac{1}{\sqrt{1 + (\Delta t)^2}} < 1$$

and

$$\left| \frac{1}{1 - \Delta ti} \right| = \frac{|1|}{|1 - \Delta ti|} = \frac{1}{\sqrt{1 + (\Delta t)^2}} < 1$$

since

$$\sqrt{1 + \left(\Delta t\right)^2} > 1.$$

Hence, for all choices of the timestep $\Delta t > 0$, $\|\mathbf{x}_k\| \to 0$ as $k \to \infty$.