

$$\vec{BA} \wedge \vec{R}_A + \vec{BC} \wedge \vec{R}_C + \vec{BG} \wedge m\vec{g} + \vec{BG} \wedge \vec{F}_V = \vec{0}$$

$$\begin{vmatrix} 0 \\ 0 \\ -a \end{vmatrix} \wedge \begin{vmatrix} X_A \\ Y_A \\ Z_A \end{vmatrix} + \begin{vmatrix} 0 \\ -c \\ b \end{vmatrix} \wedge \begin{vmatrix} -F_3 \\ 0 \\ 0 \end{vmatrix} + \begin{vmatrix} f \\ e \\ d \end{vmatrix} \wedge \begin{vmatrix} 0 \\ 0 \\ -mg \end{vmatrix} + \begin{vmatrix} f \\ e \\ d \end{vmatrix} \wedge \begin{vmatrix} -F_V \\ 0 \\ 0 \end{vmatrix} = \begin{vmatrix} 0 \\ 0 \\ 0 \end{vmatrix}$$

$$\begin{cases} a \cdot Y_A - e \cdot mg = 0 \\ -a \cdot X_A - b \cdot F_3 + f \cdot mg - d \cdot F_V = 0 \\ -c \cdot F_3 + e \cdot F_V = 0 \end{cases}$$

$$\boxed{Y_A = \frac{e}{a} mg} \quad (1)$$

$$\boxed{X_A = \frac{1}{a} (bF_3 - fmg + dF_V)} \quad (2)$$

$$* \boxed{F_3 = \frac{e}{c} F_V} \quad (3)$$

2/ Application numérique :

$$F_3 = \frac{2}{4} \cdot 1500 \Rightarrow \boxed{F_3 = 750 \text{ daN}}$$

3/ On isole le système { console + bateau }  
B.A.M.E : (voir question 1) <sup>(1)</sup> <sup>(4)</sup>

$$\underline{TRS} : \vec{R}(1U_4 \rightarrow 1U_4) = \vec{0}$$

$$\begin{cases} X_A + X_B - F_3 - F_V = 0 & (4) \\ Y_A + Y_B = 0 & (5) \\ Z_A - mg = 0 & (6) \end{cases}$$

$$(4) \Rightarrow X_B = -X_A + F_3 + F_V$$

$$\boxed{X_B = \left(1 - \frac{b}{a}\right) F_3 + \frac{f}{a} mg + \left(1 - \frac{d}{a}\right) F_V}$$

$$(5) \Rightarrow \boxed{Y_B = -\frac{e}{a} mg}$$

$$(6) \Rightarrow \boxed{Z_A = mg}$$

4) A.N :

$$\begin{array}{ll} X_A = -4736 \text{ daN} & X_B = 7036 \text{ daN} \\ Y_A = 1962 \text{ daN} & Y_B = -1962 \text{ daN} \\ Z_A = 3924 \text{ daN} & \end{array}$$