

Bayesian Estimation

Machine Learning Techniques

Karthik Thiagarajan

References and Credits

- The content presented in these slides is derived from professor [Arun Rajkumar](#)'s lectures and slides in the [MLT course](#). This is the "ground truth" for almost all the content in these slides. As a result, these slides should be viewed as a presentation of the same content in the professor's lectures using a different medium. At the same time, these slides are not meant to be a replacement for the lectures.
- These slides were prepared using the tool [mathcha.io](#).

Bayes' Theorem

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Belief

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$$P(\theta \mid D) = \frac{P(\theta) \cdot P(D \mid \theta)}{P(D)}$$

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1) Prior

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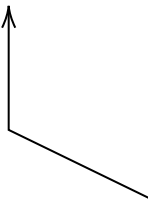
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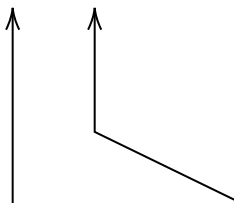

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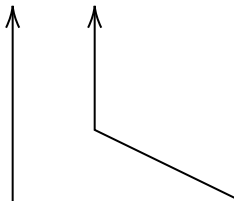
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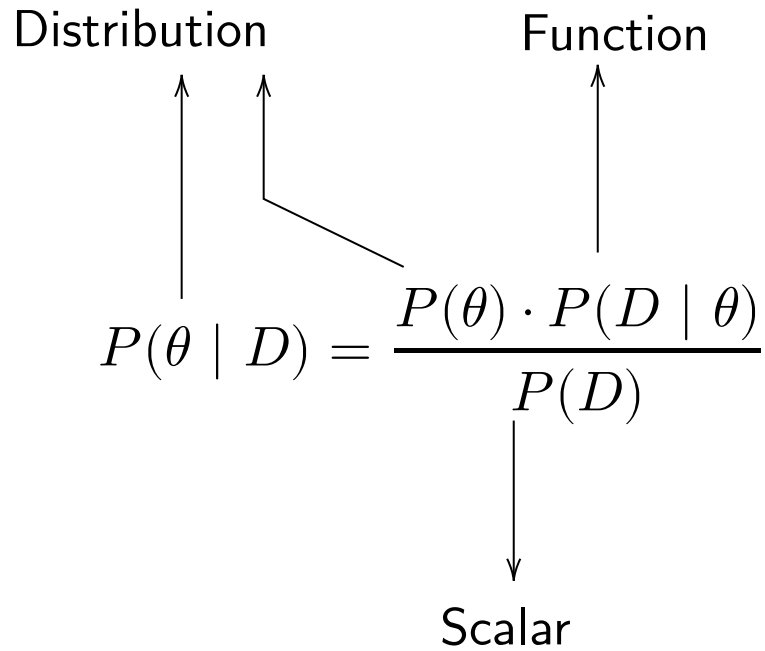
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↑ ↘

$$P(\theta \mid D) = \frac{P(\theta) \cdot P(D \mid \theta)}{P(D)}$$

↓

Scalar



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Beta Distribution

$$\text{Beta}(\alpha, \beta) \quad \alpha > 0, \beta > 0$$

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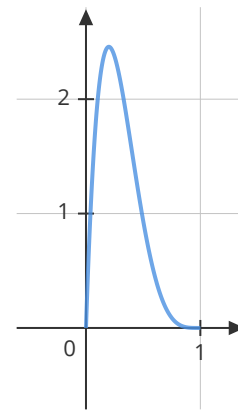
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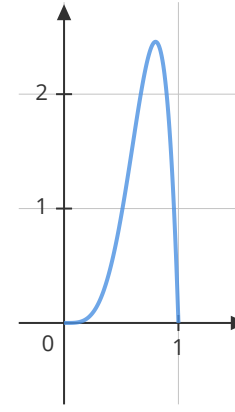
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Beta(2, 5)



Beta(5, 2)

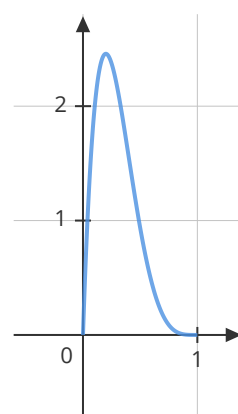
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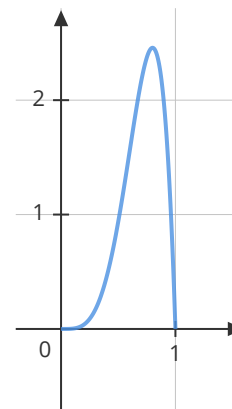
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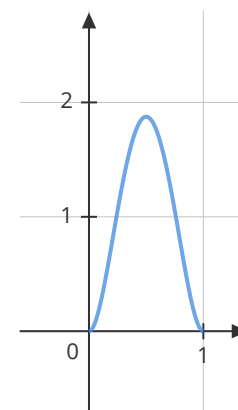
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Beta(2, 5)



Beta(5, 2)



Beta(3, 3)

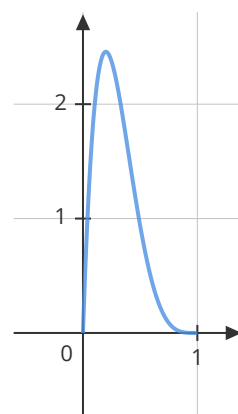
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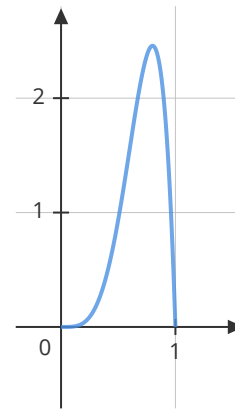
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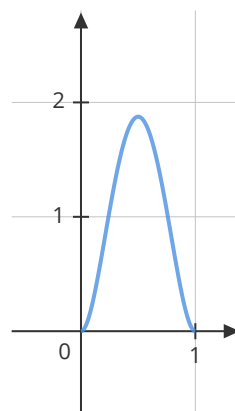
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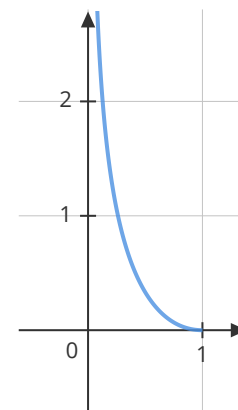
Beta(2, 5)



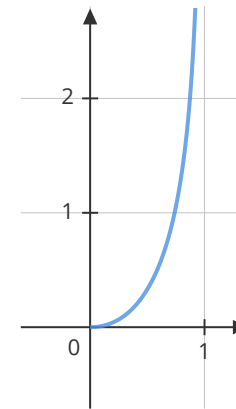
Beta(5, 2)



Beta(3, 3)



Beta(0.5, 3)



Beta(3, 0.5)

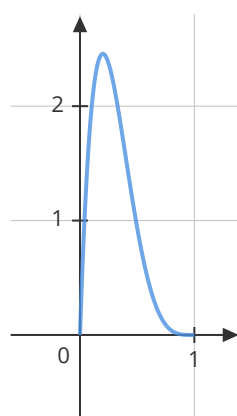
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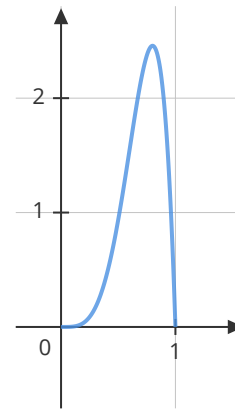
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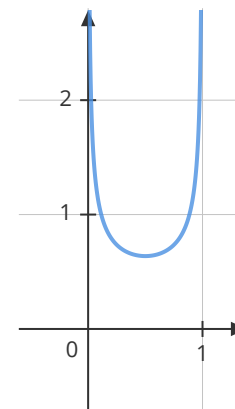
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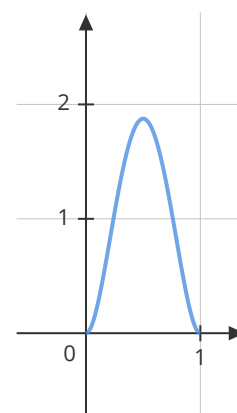
Beta(2, 5)



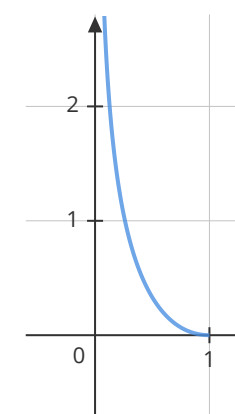
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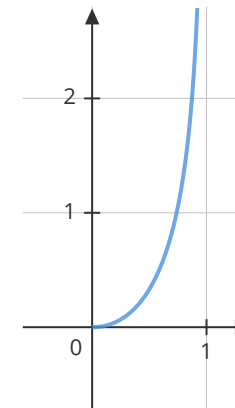
Beta(0.5, 0.5)



Beta(3, 3)



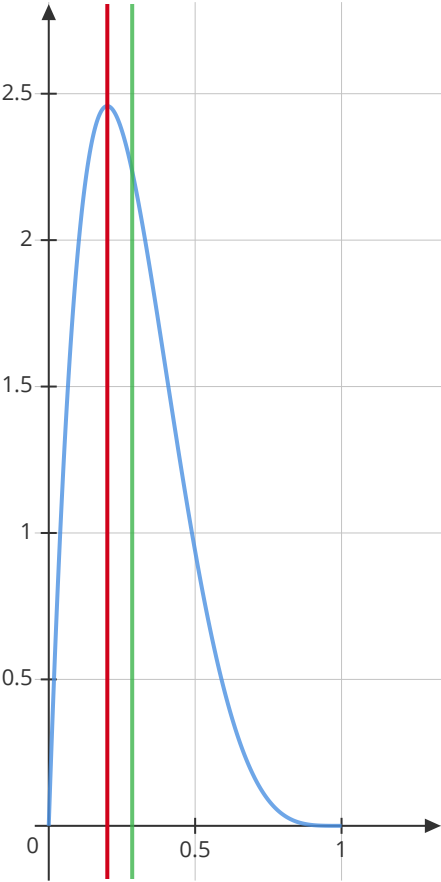
Beta(0.5, 3)



Beta(3, 0.5)

Beta Distribution

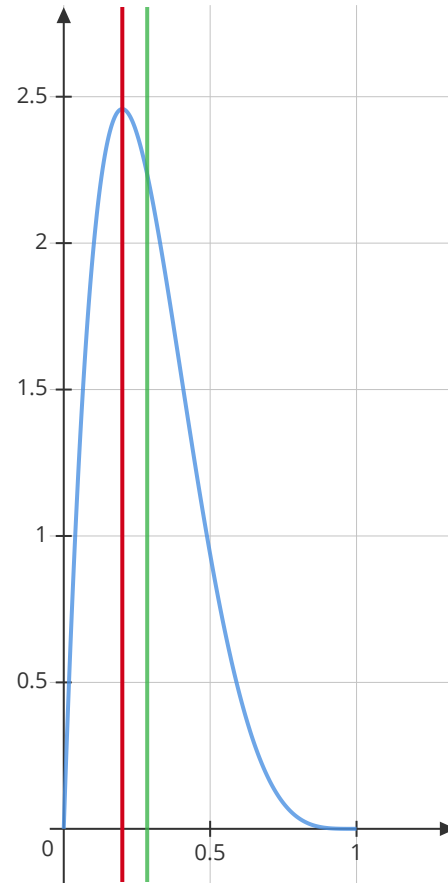
Beta(2, 5)



Beta Distribution

$$\text{Mean} = \frac{\alpha}{\alpha + \beta}$$

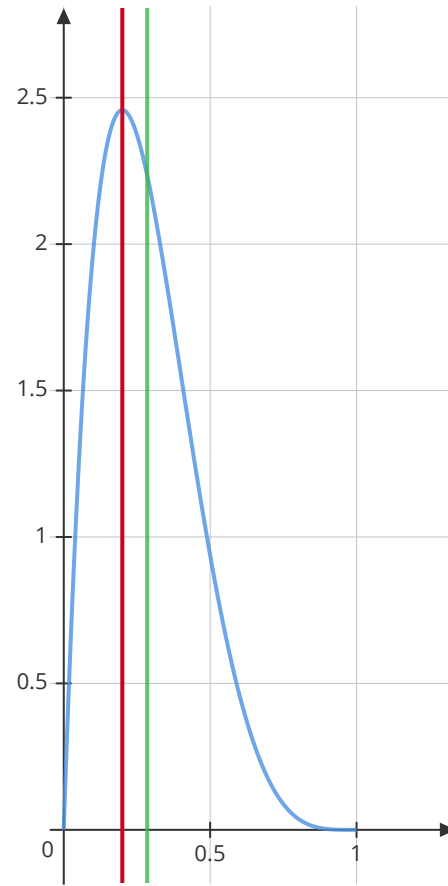
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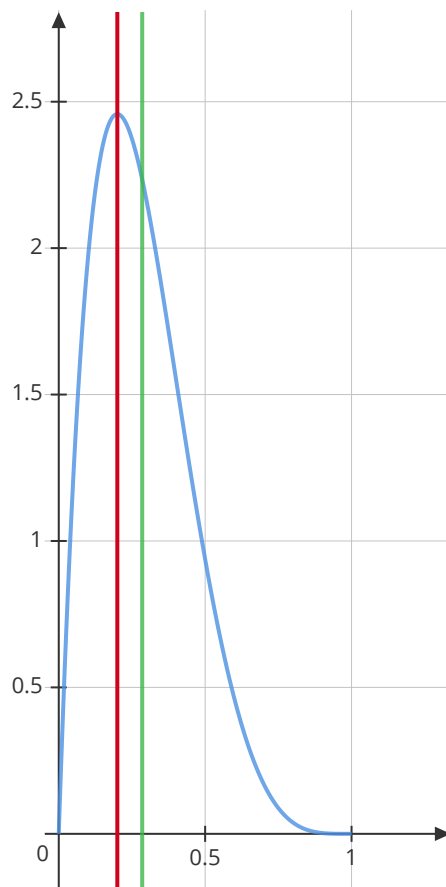


$$\text{Mode} = \begin{cases} \frac{\alpha - 1}{\alpha + \beta - 2} & \alpha, \beta > 1 \\ 0 & \alpha \leq 1, \beta > 1 \\ 1 & \alpha > 1, \beta \leq 1 \\ (0, 1) & \alpha = \beta = 1 \\ \{0, 1\} & \alpha, \beta < 1 \end{cases}$$

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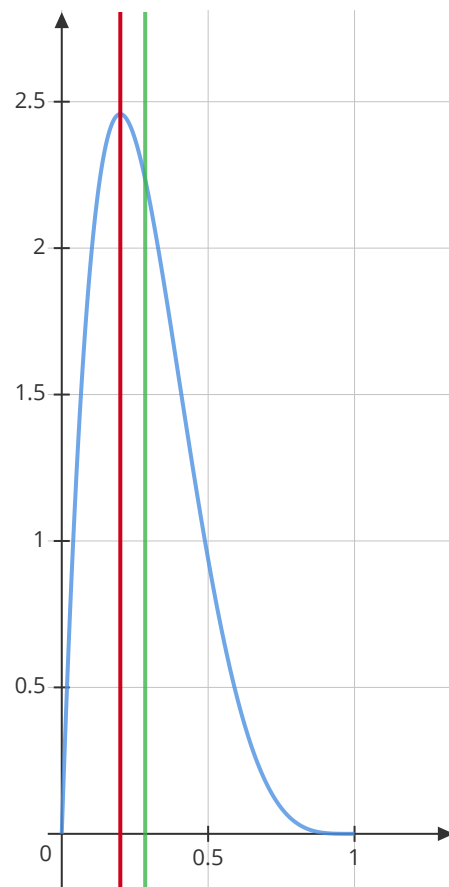
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$$\frac{d \log(f(p))}{dp} = 0$$

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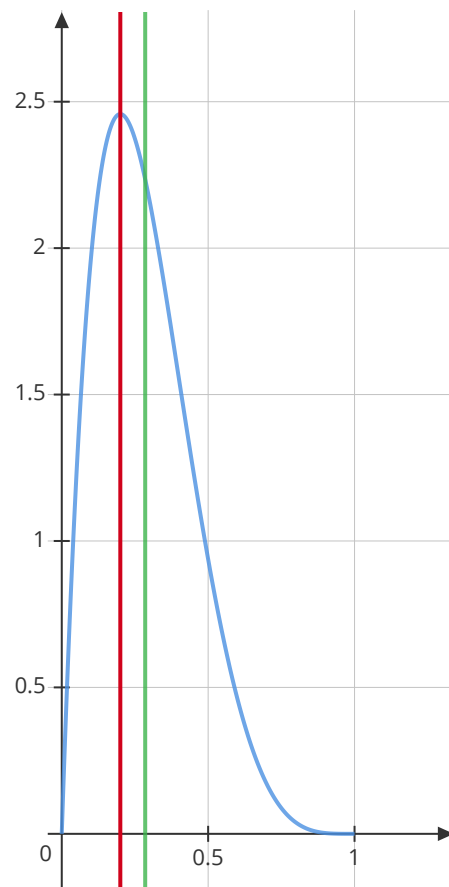
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Prior $\xrightarrow{\text{Likelihood}}$ Posterior

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$$X_i \sim Br(p)$$

$p \rightarrow$ parameter

$$p \sim \text{Beta}(\alpha, \beta)$$

$\alpha, \beta \rightarrow$ hyperparameters

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Posterior \propto

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Beta distribution is a conjugate
prior for the Bernoulli distribution

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Hard to compute $\longleftarrow P(D) = \int_{\theta} P(\theta) \cdot P(D \mid \theta)$

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Beta distribution is a conjugate
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α, β : Pseudo-observations

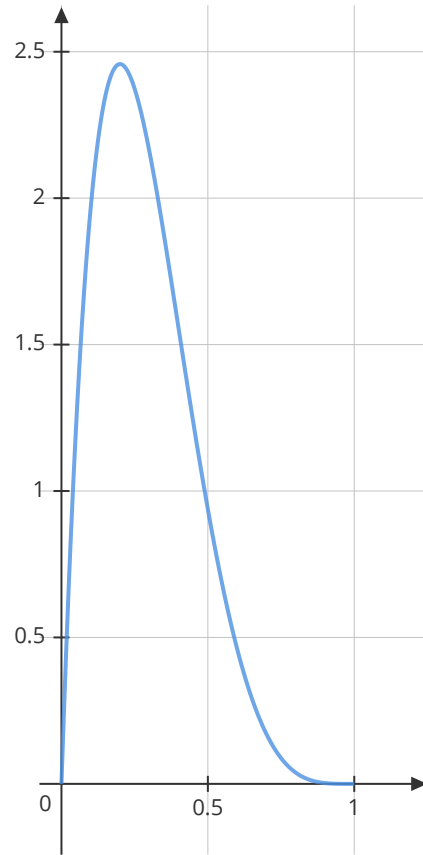
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Example-1

p is closer to 0 than it is to 1

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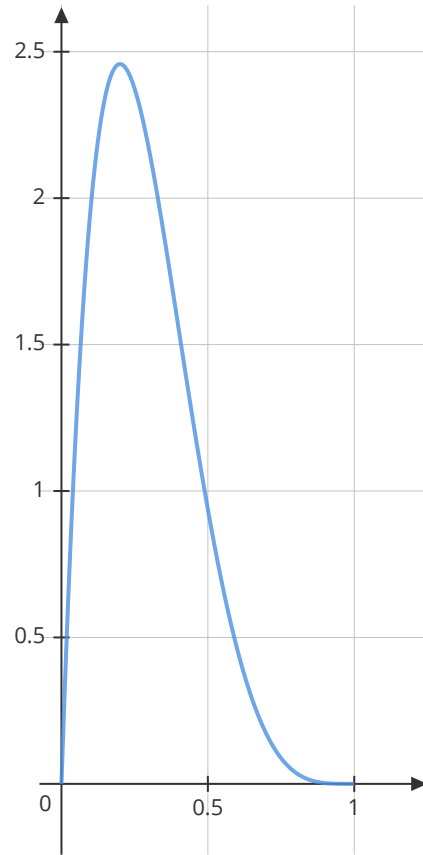
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Example-1

p is closer to 0 than it is to 1

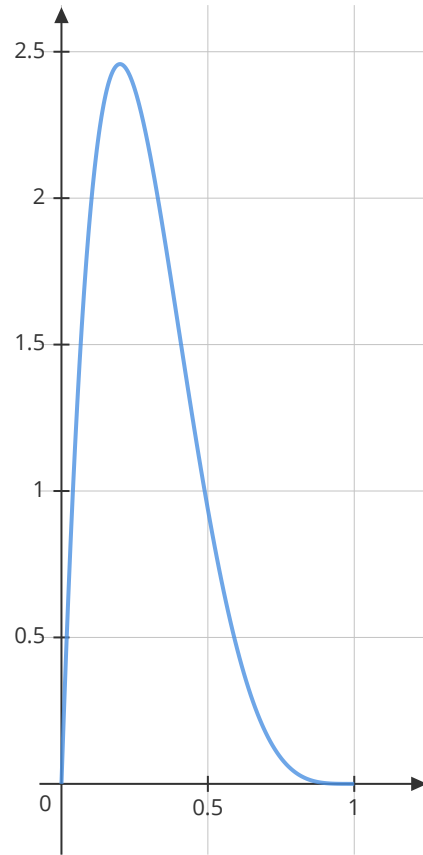
Beta(2, 5)



Example-1

p is closer to 0 than it is to 1

Beta(2, 5)



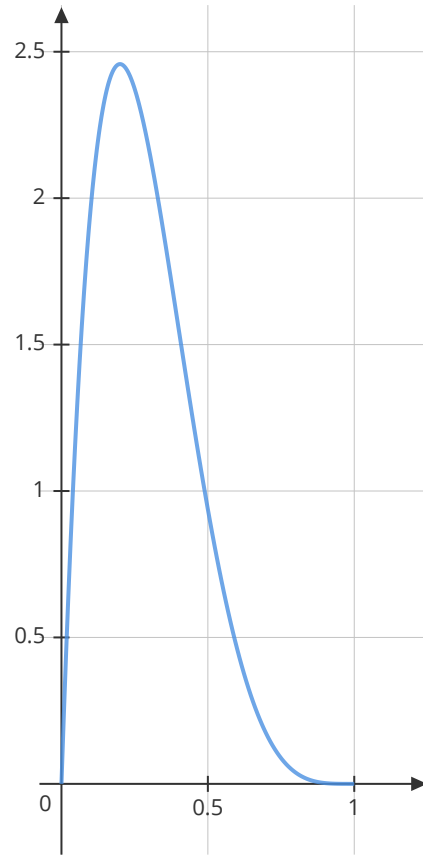
$$D = \{1, 0, 0, 0, 0, 0, 0, 0, 1\}$$

Example-1

p is closer to 0 than it is to 1

Beta(4, 12)

Beta(2, 5)

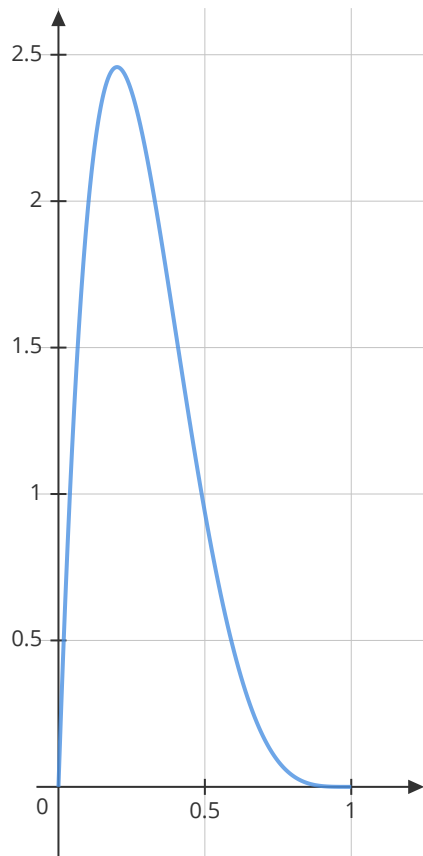


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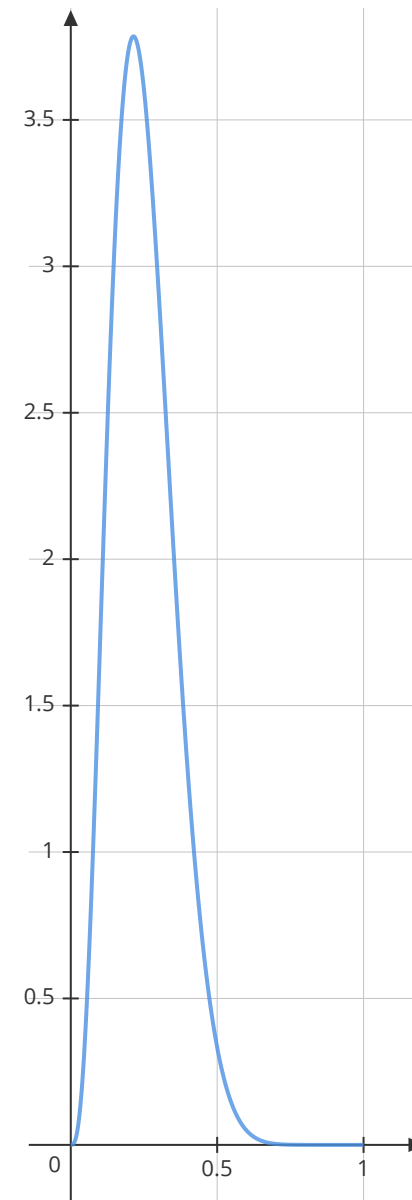
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Beta(2, 5)



Beta(4, 12)

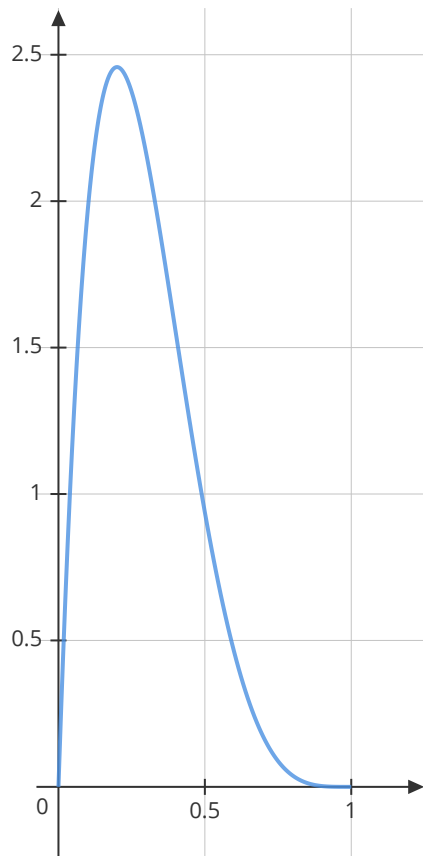


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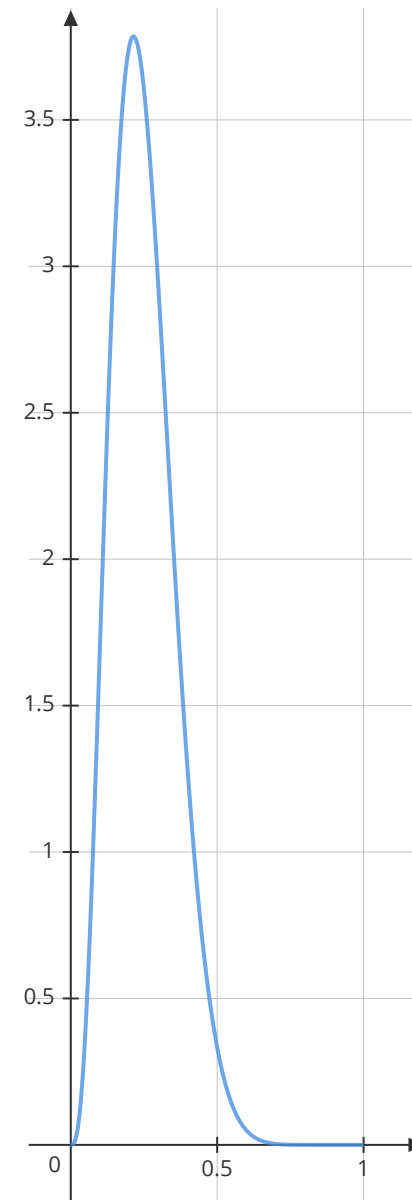
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p is closer to 0 than it is to 1

Beta(2, 5)



Beta(4, 12)



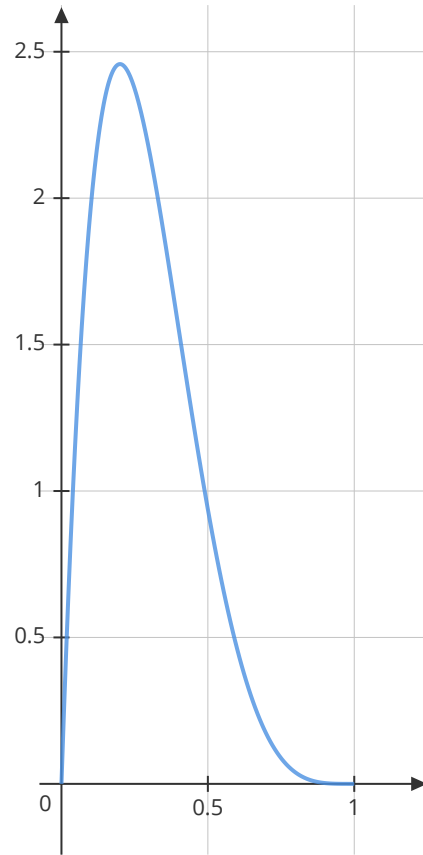
$$D_{\text{pseudo}} = \{1, 1, 0, 0, 0, 0, 0\}$$

$$D = \{1, 0, 0, 0, 0, 0, 0, 0, 1\}$$

Example-2

p is closer to 0 than it is to 1

Beta(2, 5)

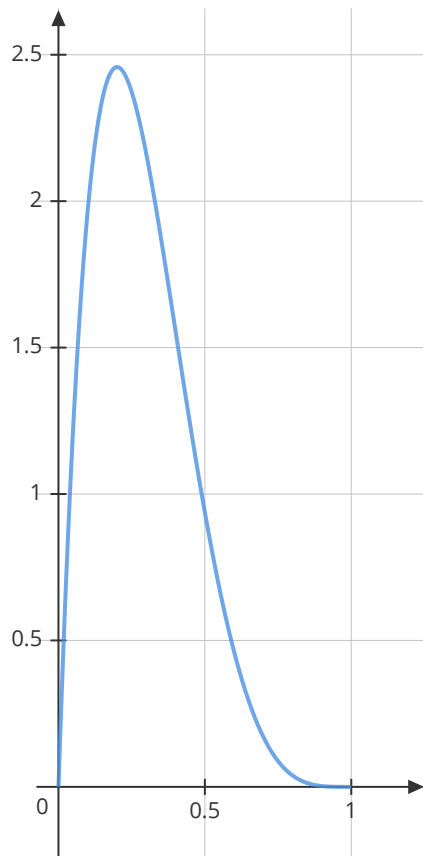


$$D = \{0, 1, 1, 1, 1, 1, 1, 1, 0\}$$

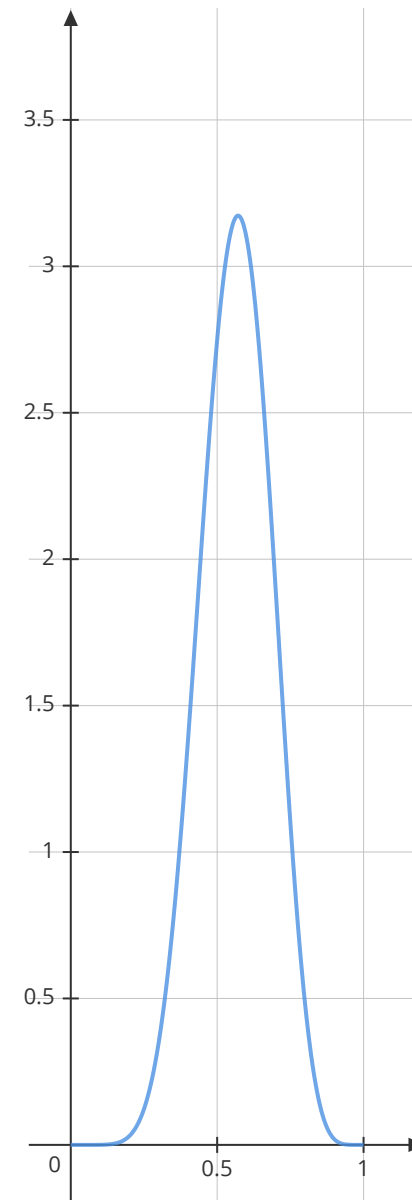
Example-2

p is closer to 0 than it is to 1

Beta(2, 5)



Beta(9, 7)



$$D_{\text{pseudo}} = \{1, 1, 0, 0, 0, 0, 0\}$$

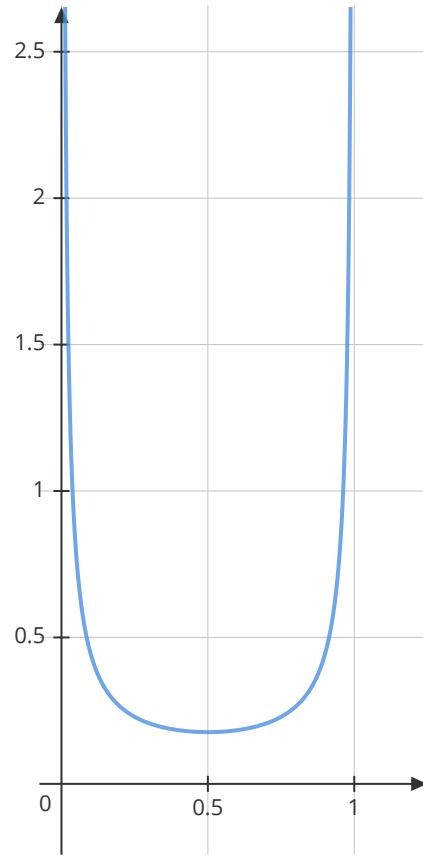
$$D = \{0, 1, 1, 1, 1, 1, 1, 1, 0\}$$

Example-3

p is extremely close to either 0 or 1

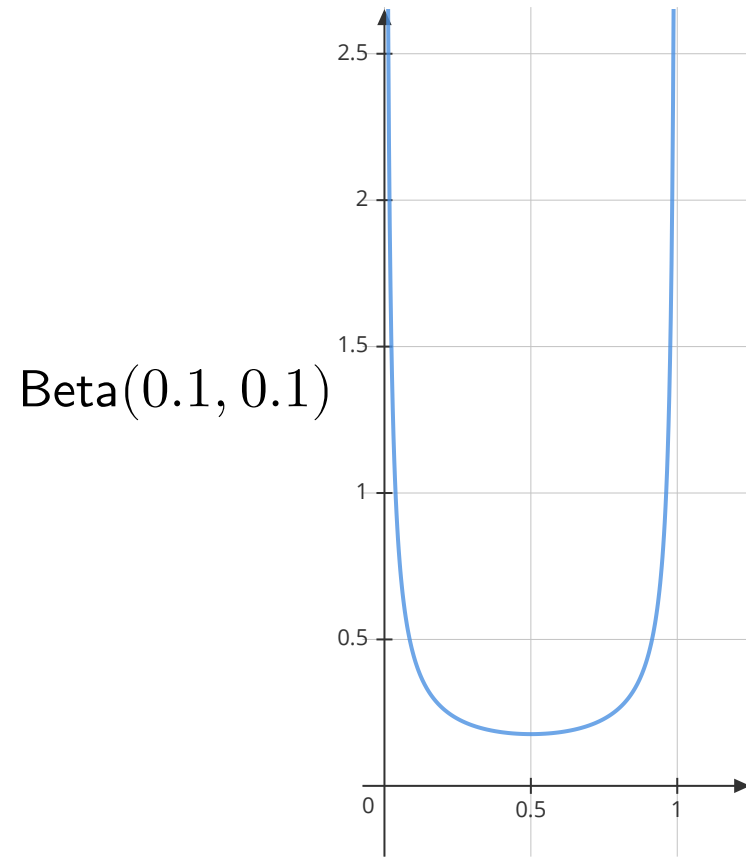
Example-3

p is extremely close to either 0 or 1



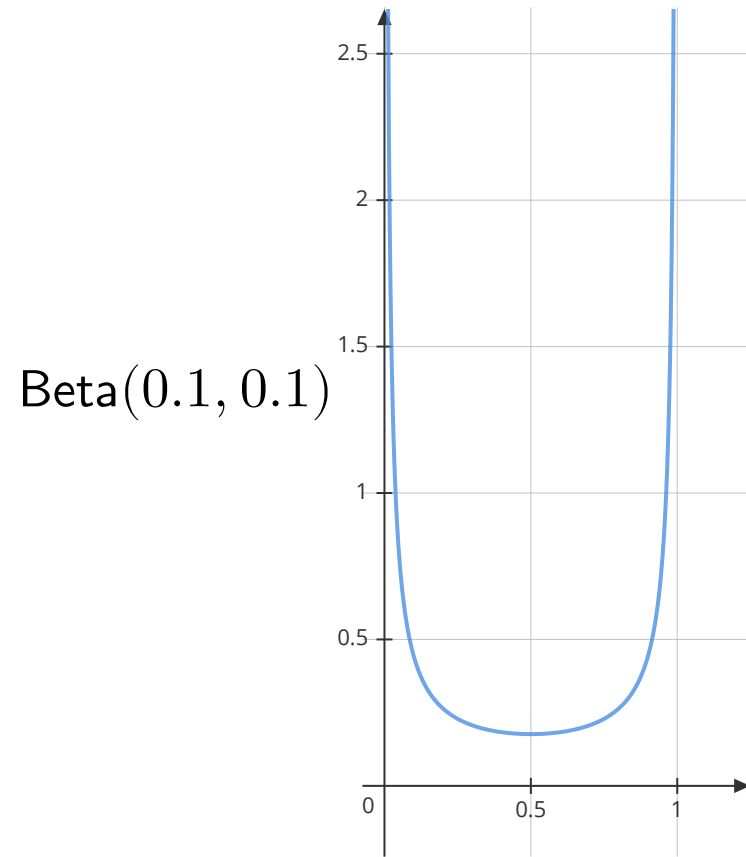
Example-3

p is extremely close to either 0 or 1



Example-3

p is extremely close to either 0 or 1



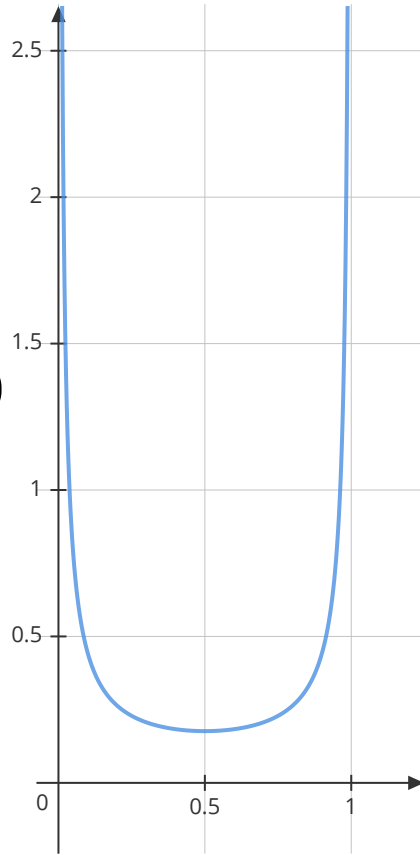
$$D = \{1, 1, 1, 1, 1, 1, 1, 1, 0\}$$

Example-3

p is extremely close to either 0 or 1

Beta(8.1, 1.1)

Beta(0.1, 0.1)

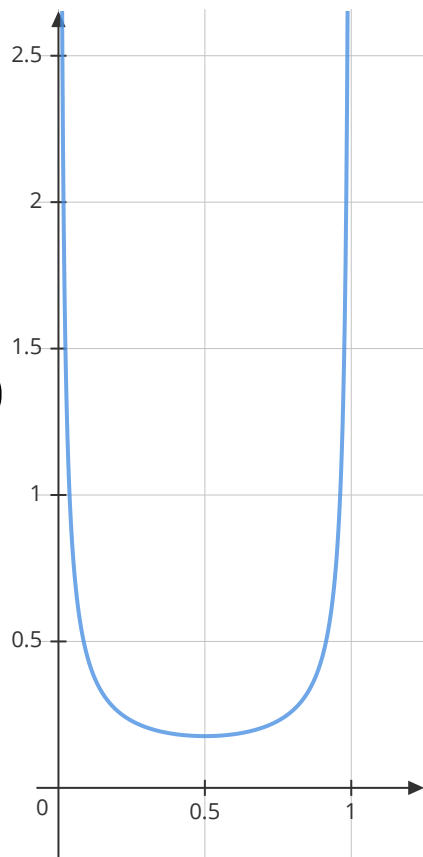


$$D = \{1, 1, 1, 1, 1, 1, 1, 1, 0\}$$

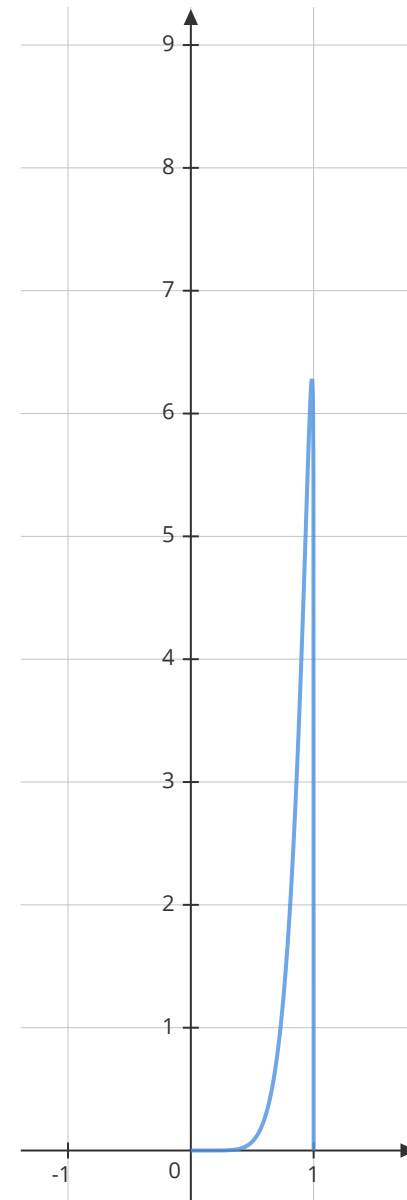
Example-3

p is extremely close to either 0 or 1

Beta(0.1, 0.1)



Beta(8.1, 1.1)



$$D = \{1, 1, 1, 1, 1, 1, 1, 1, 0\}$$

Point Estimates

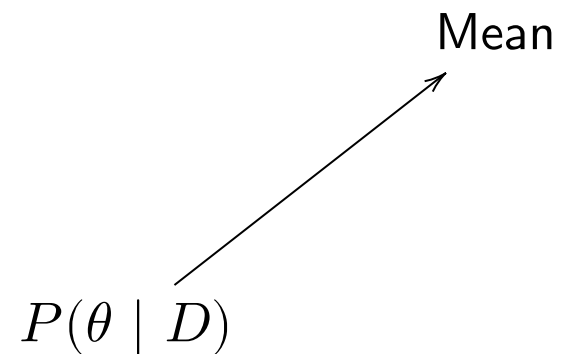
$$P(\theta \mid D)$$

Point Estimates

Posterior: $\text{Beta}(\alpha + n_h, \beta + n_t)$

$$P(\theta \mid D)$$

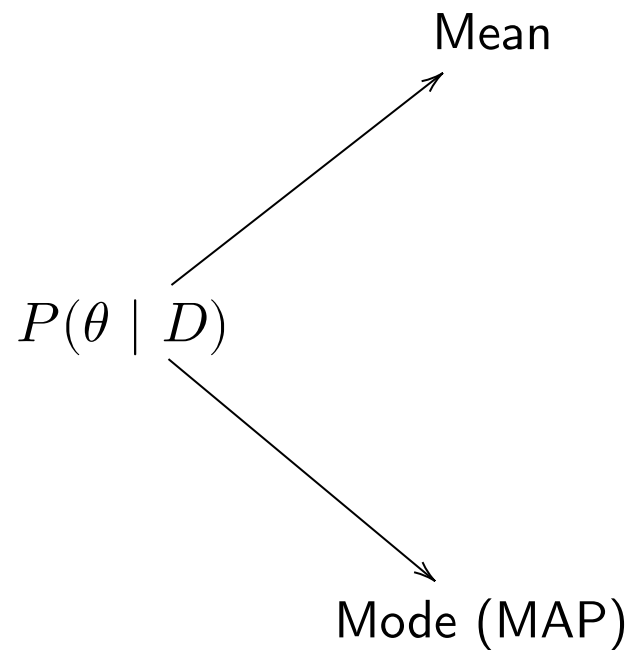
Point Estimates



Posterior: Beta($\alpha + n_h, \beta + n_t$)

$$\text{Mean} = \frac{\alpha + n_h}{\alpha + \beta + n}$$

Point Estimates



Posterior: $\text{Beta}(\alpha + n_h, \beta + n_t)$

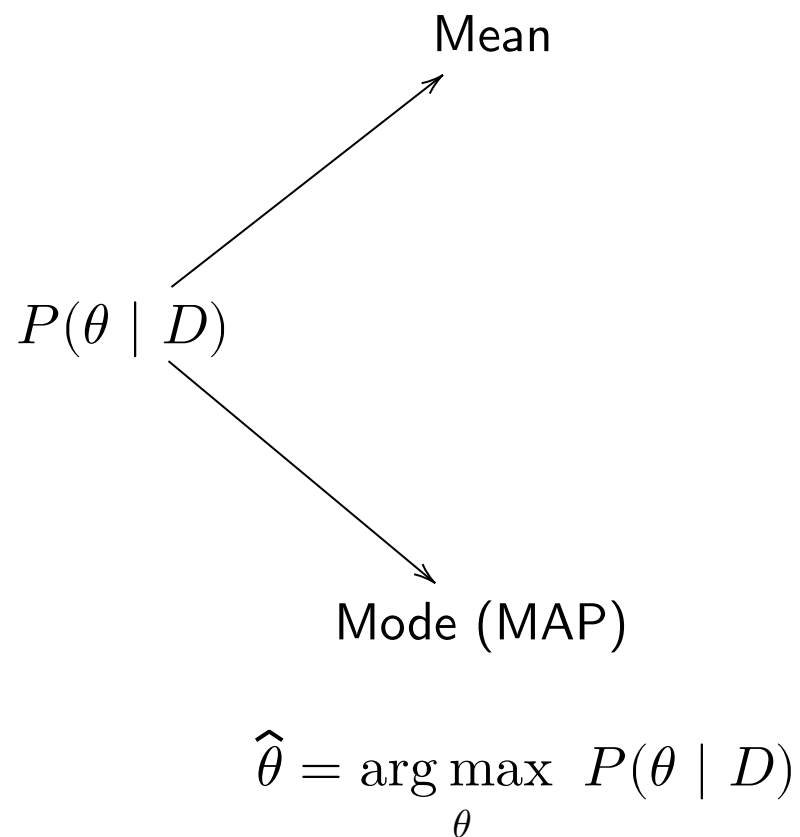
$$\text{Mean} = \frac{\alpha + n_h}{\alpha + \beta + n}$$

$$\text{Mode} = \frac{\alpha + n_h - 1}{\alpha + \beta + n - 2}$$

$$\alpha + n_h > 1$$

$$\beta + n_t > 1$$

Point Estimates



Maximum A Posteriori estimate

Posterior: Beta($\alpha + n_h, \beta + n_t$)

$$\text{Mean} = \frac{\alpha + n_h}{\alpha + \beta + n}$$

$$\text{Mode} = \frac{\alpha + n_h - 1}{\alpha + \beta + n - 2}$$

$$\alpha + n_h > 1$$

$$\beta + n_t > 1$$