

## CVaR Lab 6

- $\text{rets} \in \mathbb{R}^T$ , use each return
- observation as a scenario

$$\text{rets} = \begin{bmatrix} (r^{(1)})^T \\ \vdots \\ (r^{(T)})^T \end{bmatrix} \quad r^{(i)} \in \mathbb{R}^1, (r^{(i)})^T \in \mathbb{R}^n$$

- is this the only way to define scenarios?

→ No! but it is what we are going to do

- $\alpha$  - CVaR minimization;  $\alpha$  is confidence

$\mathcal{P}$  {

$$\begin{aligned} \min_{\gamma, x, z} \quad & \gamma + \frac{1}{(1-\alpha)T} \sum_{s=1}^T z_s \\ & z_s \geq 0 \quad \forall s=1, \dots, T \quad (C1) \\ & z_s \geq -(r^{(s)})^T x - \gamma \quad \forall s=1 \dots T \quad (C2) \\ & 1^T x = 1 \quad (C3) \\ & \mu^T x \geq R \quad (C4) \end{aligned}$$

Note :  $x \in \mathbb{R}^n, z \in \mathbb{R}^T, \gamma \in \mathbb{R}$

(1) at optimality  $\gamma = \underline{\text{VaR}_\alpha}$

(2) (1)  $\Rightarrow z_s \geq 0, z_s \geq -(r^{(s)})^T x - \text{VaR}_\alpha$

since we are minimizing  $\frac{1}{(1-\alpha)T} \sum z_s$   
in the objective, at optimality

@ least one of (C1) or (C2) is

tight for each scenario

$$\Rightarrow z_s = \max \{ 0, -(r^{(s)})^T x - \text{VaR}_\alpha \} \quad \forall s$$

i.e.  $z_g$  = the loss in excess of  $\text{VaR}_\alpha$   
@ optimality! Cool!

(3) the objective and constraints are  
all linear in  $x, z, \gamma \Rightarrow$

ok lets solve. Matlab linprog solves

$\mathcal{M}$  {  $\begin{array}{l} \min_{\tilde{x}} \quad c^T \tilde{x} \\ \text{matlab} \\ \text{doc call f} \\ \text{this} \end{array}$   $\begin{array}{l} A_{eq} \tilde{x} = b_{eq} \\ A \tilde{x} \leq b \\ lb \leq \tilde{x} \leq ub \end{array}$  Linprog

- we have to structure the inputs into  $\mathcal{M}$   
so that solving  $\mathcal{M}$  solves  $\mathcal{P}$

- lets arrange our  $x, z$ , and  $\gamma$  so that

$$\tilde{x} = \begin{bmatrix} x \\ z \\ \gamma \end{bmatrix} \in \mathbb{R}^{n+T+1}$$

lets proceed in the order given in  
the sample code

lower bounds:  $x$  is free,  $z \geq 0$ ,  $\gamma$  is free

i.e.  $-\infty \leq x_i \quad \forall i=1 \dots n$

$0 \leq z_s \quad \forall s=1 \dots T$

$-\infty \leq \gamma$

$\text{inf}(n, 1) = \begin{bmatrix} \infty \\ \vdots \\ \infty \end{bmatrix} \in \mathbb{R}^1$

i.e.  $\begin{bmatrix} -\text{inf}(n, 1) \\ 0_{T \times 1} \\ -\text{inf} \end{bmatrix} \leq \begin{bmatrix} x \\ z \\ \gamma \end{bmatrix}$

↑ this is in Matlab

upper bounds: there are none. You can set that to the empty  $[]$

Equality (C4) is the only one

$1^T x = 1 \Leftrightarrow \frac{1^T x + 0^T z + 0 \gamma}{1} = 1$

$\Leftrightarrow \begin{bmatrix} 1^T & 0^T & 0 \end{bmatrix} \begin{bmatrix} x \\ z \\ \gamma \end{bmatrix} = 1$

i.e.

$\underbrace{\begin{bmatrix} 1_{1 \times n} & 0_{1 \times T} & 0_{1 \times 1} \end{bmatrix}}_{A_{eq} \in \mathbb{R}^{1 \times n+T+1}} \begin{bmatrix} x \\ z \\ \gamma \end{bmatrix} = \underbrace{1}_{b_{eq}}$

Inequalities

$$z_s \geq$$

$$\mu^T x \geq R \quad (C4)$$

capital S in code

$$\forall s=1 \dots T \quad (C2)$$

$$\underbrace{A\tilde{x}} \leq \underbrace{b}_1$$

$$-(r^{(s)})^T x - z_s - \gamma \leq 0 \quad \forall s=1 \dots T$$

$$\underbrace{-\mu^T x}_{\text{set}} \leq -R$$

$$\underbrace{\begin{bmatrix} -(r^{(1)})^T x \\ -(r^{(2)})^T x \\ \vdots \\ -(r^{(T)})^T x \end{bmatrix}}_x \underbrace{\begin{bmatrix} -z_1 \\ -z_2 \\ \vdots \\ -z_s \\ \vdots \end{bmatrix}}_z \underbrace{\begin{bmatrix} -\gamma \\ -\gamma \\ \vdots \\ -\gamma \end{bmatrix}}_\gamma \leq \underbrace{\begin{bmatrix} 0_{T \times 1} \\ -R \end{bmatrix}}_{\text{vertical concat}} \underbrace{\begin{bmatrix} \vdots \\ j \end{bmatrix}}_{\text{vertical concat}}$$

$$\begin{bmatrix} -rets, & \begin{pmatrix} -1 & 0 & \dots & 0 \\ 0 & -1 & & \\ & & \ddots & \\ & & & -1 \end{pmatrix}, & \begin{bmatrix} -1 \\ -1 \\ \vdots \end{bmatrix} \end{bmatrix} \begin{bmatrix} x \\ z \\ \gamma \end{bmatrix} \leq 0_{T \times 1}$$

$T \times n$        $T \times T$        $T \times 1$

Next, do C4

$$-\mu^T x \leq -R$$

$$\Downarrow$$

$$-\mu^T x + 0^T z + 0\gamma \leq -R$$

$$\begin{matrix} \updownarrow \\ [-\mu^T + 0_{1 \times T} \quad 0_{1 \times 1}] \end{matrix} \begin{bmatrix} x \\ z \\ \gamma \end{bmatrix} \leq -R$$

$$\begin{bmatrix} -\text{rets}, \begin{pmatrix} -1 & 0 & \dots & 0 \\ 0 & -1 & & \\ & & \ddots & \\ & & & -1 \end{pmatrix}, \begin{bmatrix} -1 \\ -1 \\ \vdots \end{bmatrix} \\ \hline -\mu^T + 0_{1 \times T} \quad 0_{1 \times 1} \end{bmatrix} \begin{bmatrix} x \\ z \\ \gamma \end{bmatrix} \leq \begin{bmatrix} 0_{T \times 1} \\ -R \end{bmatrix}$$

↕

↗  
b

$$A = \begin{bmatrix} -\text{rets}, \begin{pmatrix} -1 & 0 & \dots & 0 \\ 0 & -1 & & \\ & & \ddots & \\ & & & -1 \end{pmatrix}, \begin{bmatrix} -1 \\ -1 \\ \vdots \end{bmatrix} ; \mu^T \quad 0_{1 \times T} \quad 0_{1 \times 1} \end{bmatrix}$$

objective:

$$\gamma + \frac{1}{(1-\alpha)^T} \sum_{s=1}^T z_s \quad \swarrow \quad \mathbf{1}^T \mathbf{z}$$

$$= \underline{0^T x} + \frac{1}{(1-\alpha)^T} \underline{\mathbf{1}^T \mathbf{z}} + \underline{\mathbf{1}_{1 \times 1}} \gamma$$

$$= \begin{bmatrix} 0^T & \frac{1}{(1-\alpha)^T} \mathbf{1}^T & \mathbf{1}_{1 \times 1} \end{bmatrix} \begin{bmatrix} x \\ z \\ \gamma \end{bmatrix}$$

$$= \begin{bmatrix} 0_{1 \times n} & \frac{1}{(1-\alpha)^T} & \underbrace{1}_{1 \times T} & 1_{1 \times 1} \end{bmatrix} \begin{bmatrix} x \\ z \\ y \end{bmatrix} \begin{matrix} \xrightarrow{(n+T+1) \times 1} \\ \end{matrix}$$

$\underbrace{1 \times (n+T+1)}_c$